笔记整理

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1 草稿

理想流体运动的基本方程理想流体应力张量 $T_{ij} = -p\delta_{ij}$,因此动量方程($\ref{eq:condition}$)式化为:

$$\frac{\partial \overrightarrow{v}}{\partial t} + \overrightarrow{v} \cdot \nabla \overrightarrow{v} = \overrightarrow{f} - \frac{1}{\rho} \nabla \cdot p \tag{1}$$

(1)式即欧拉方程,相应的(??)化为

$$\frac{D(e + \frac{1}{2}|\overrightarrow{v}|^2)}{Dt} = \overrightarrow{f} \cdot \overrightarrow{v} - \frac{1}{\rho} \nabla \cdot (p\overrightarrow{v}) + (\dot{q} + q_R)$$
 (2)

综合连续性方程(??)式,(1),(??) 共 5 个方程,但未知数有 \overrightarrow{v} , e, p, ρ 6 个,因此需补充热力学方程才能使方程组封闭。

实际上,我们可以通过动量方程(1)式得到动能的变化率:

$$\frac{D}{Dt}(\frac{1}{2}|\overrightarrow{v}|^2) = \overrightarrow{f} \cdot \overrightarrow{v} - \frac{1}{\rho} \overrightarrow{v} \cdot \nabla p \tag{3}$$

将(2)式与(3)作差得:

$$\frac{De}{Dt} = -\frac{p}{\rho} \nabla \cdot \overrightarrow{v} + \dot{q} + q_R, \text{ by } (??)$$

$$= \frac{p}{\rho^2} \frac{D\rho}{Dt} + \dot{q} + q_R$$

$$= -p \frac{D}{Dt} \left(\frac{1}{\rho}\right) + \dot{q} + q_R$$
(4)

定义 $i = e + \frac{p}{\rho}$ 为气体的焓,则可以得到

$$\frac{Di}{Dt} = \dot{q} + q_R + \frac{1}{\rho} \frac{Dp}{Dt} \tag{5}$$

对于绝热状态下的理想常比热完全气体,我们有

$$\frac{De}{Dt} = C_V \frac{DT}{Dt}, e = C_V T$$

$$= \frac{C_V}{R} \frac{D}{Dt} \left(\frac{p}{\rho}\right), p = \rho RT$$

$$= \frac{1}{\gamma - 1} \frac{D}{Dt} \left(\frac{p}{\rho}\right), C_P - C_V = R, \frac{C_P}{C_V} = \gamma$$
(6)

将(4)式去掉产热项,与(6)式结合可以得到

$$\frac{D}{Dt} \left(\frac{p}{\rho^{\gamma}} \right) = 0 \tag{7}$$

(7)式即为对于气体补充的 ρ 和 p 的关系的热力学方程。

对于匀质不可压缩的液体,补充 $\nabla \cdot \vec{v} = 0$ 的方程,此时(??)式恒成立,动力学方程与热力学方程解耦,因此我们可以联立求解:

$$\nabla \cdot \overrightarrow{v} = 0$$

$$\frac{\partial \overrightarrow{v}}{\partial t} + \overrightarrow{v} \cdot \nabla \overrightarrow{v} = \overrightarrow{f} - \frac{1}{\rho} \nabla \cdot p$$
(8)

得到 \overrightarrow{v} , p 再代入能量方程求其他参量。

(9)

对于球坐标,基矢量随坐标变量的变化规律为[8]:

$$\frac{\partial \overrightarrow{e_r}}{\partial \theta} = \overrightarrow{e_\theta}, \quad \frac{\partial \overrightarrow{e_r}}{\partial \varphi} = \overrightarrow{e_\varphi} \sin \theta \tag{10}$$

$$\frac{\partial \overrightarrow{e_{\theta}}}{\partial \theta} = -\overrightarrow{e_r}, \ \frac{\partial \overrightarrow{e_{\theta}}}{\partial \varphi} = \overrightarrow{e_{\varphi}} \cos \theta \tag{11}$$

$$\frac{\partial \overrightarrow{e_{\varphi}}}{\partial \varphi} = -\left(\overrightarrow{e_r}\sin\theta + \overrightarrow{e_{\theta}}\cos\theta\right) \tag{12}$$

球坐标系下的梯度算子表示为:

$$\nabla = \frac{\partial}{\partial r} \overrightarrow{e_r} + \frac{1}{r} \frac{\partial}{\partial \theta} \overrightarrow{e_\theta} + \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} \overrightarrow{e_\varphi}$$
 (13)

因此球坐标系下对于矢量 $\overrightarrow{v}=v_r\overrightarrow{e_r}+v_\theta\overrightarrow{e_\theta}+v_\varphi\overrightarrow{e_\varphi}$ 的散度为:

$$\begin{split} &(\frac{\partial}{\partial r}\overrightarrow{e_r} + \frac{1}{r}\frac{\partial}{\partial \theta}\overrightarrow{e_\theta} + \frac{1}{r\sin\theta}\frac{\partial}{\partial \varphi}\overrightarrow{e_\varphi}) \cdot (v_r\overrightarrow{e_r} + v_\theta\overrightarrow{e_\theta} + v_\varphi\overrightarrow{e_\varphi}) = \\ &\frac{\partial v_r}{\partial r} + \frac{1}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{1}{r\sin\theta}\frac{\partial v_\varphi}{\partial \varphi} + \frac{v_r}{r}\frac{\partial\overrightarrow{e_r}}{\partial \theta} \cdot \overrightarrow{e_\theta} + (v_r\frac{\partial\overrightarrow{e_r}}{\partial \varphi} + v_\theta\frac{\partial\overrightarrow{e_\theta}}{\partial \varphi} + v_\varphi\frac{\partial\overrightarrow{e_\varphi}}{\partial \varphi}) \cdot \frac{\overrightarrow{e_\varphi}}{r\sin\theta} \\ &= \frac{\partial v_r}{\partial r} + \frac{1}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{1}{r\sin\theta}\frac{\partial v_\varphi}{\partial \varphi} + \frac{v_r}{r} + (v_r\sin\theta + v_\theta\cos\theta)\frac{1}{r\sin\theta} \\ &= \frac{\partial v_r}{\partial r} + \frac{1}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{1}{r\sin\theta}\frac{\partial v_\varphi}{\partial \varphi} + \frac{2v_r}{r} + \frac{v_\theta\cos\theta}{r\sin\theta} \end{split}$$

$$\nabla \cdot \overrightarrow{v} = \frac{1}{r^2} \frac{\partial (r^2 v_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial (v_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial v_\varphi}{\partial \varphi}$$
 (14)

(15)

References

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