

COMPUTER ORGANIZATION AND DESIGN

The Hardware/Software Interface

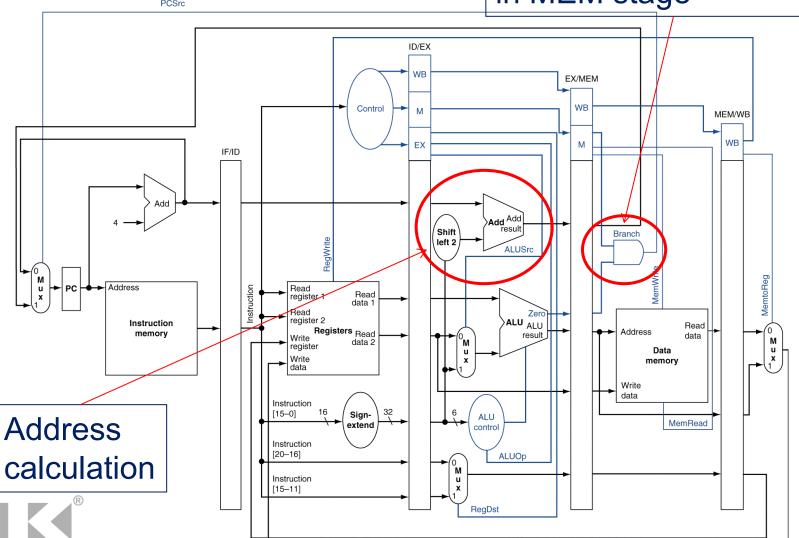
Topic 9

Control Hazards

Branch Hazards

Current implementation

Determination for branch in MEM stage



Control Hazards

- Branch determines flow of control
 - Fetching next instruction depends on branch outcome
 - Pipeline can't always fetch correct instruction (Branch Hazard) because
 - When Branch instruction is still in the ID stage, target instruction is needed in the IF stage



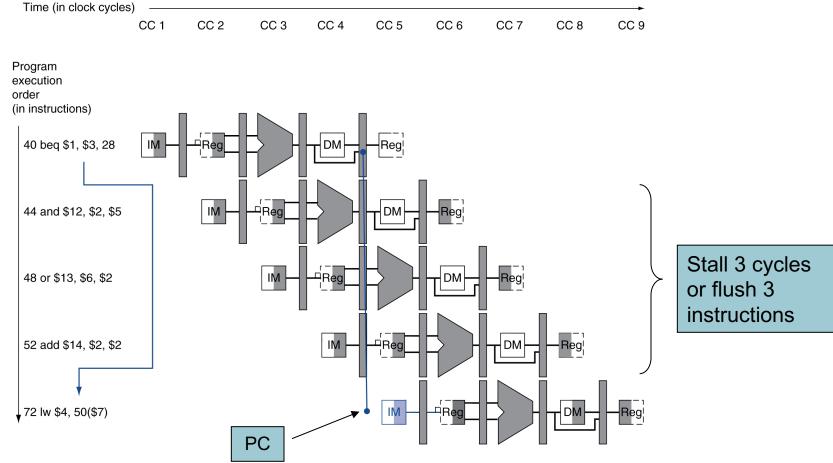
Branch Hazard Resolutions

- Stall on branch
- Always assume branch not taken or taken
- Branch prediction
- Delayed Branch



Branch Hazards

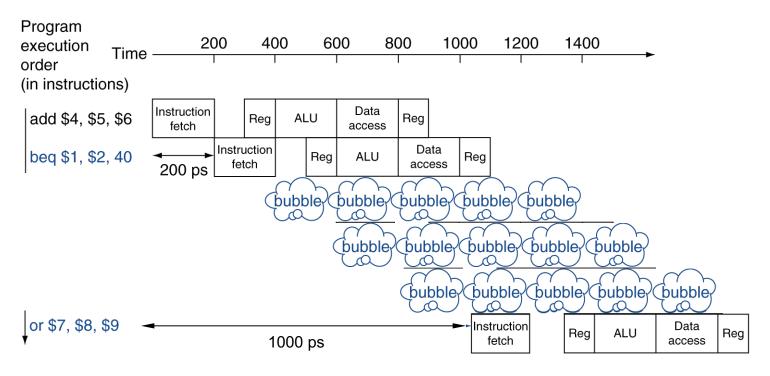
- If branch outcome determined in MEM
 - Stall branch or take penalty of wrong branch





Stall on Branch

 Wait until branch outcome determined before fetching next instruction





Branch Hazard Resolutions

- Stall on branch
- Always assume branch not taken or taken
- Branch prediction
- Delayed Branch



Assume Branch Not Taken

- If we are right, lucky us!
- If we are wrong, penalty will be to flush some (up to 3) instructions
- Penalty may be reduced
 - By making earlier decision on branch or not
 - Need to compare registers and compute target early in the pipeline

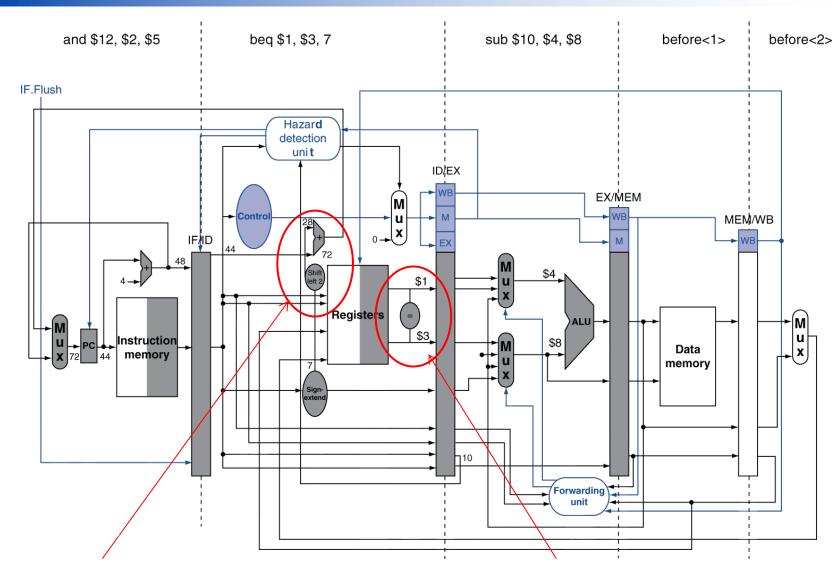


Reducing Branch Penalty

- Move hardware for determining PC to *ID stage* including
 - Target address calculation
 - Register comparator
- For branch not taken, correct assumption, no penalty
- For taken branch, penalty reduced
 - 1 instruction to be flushed



Example: Branch Taken



Address calculation

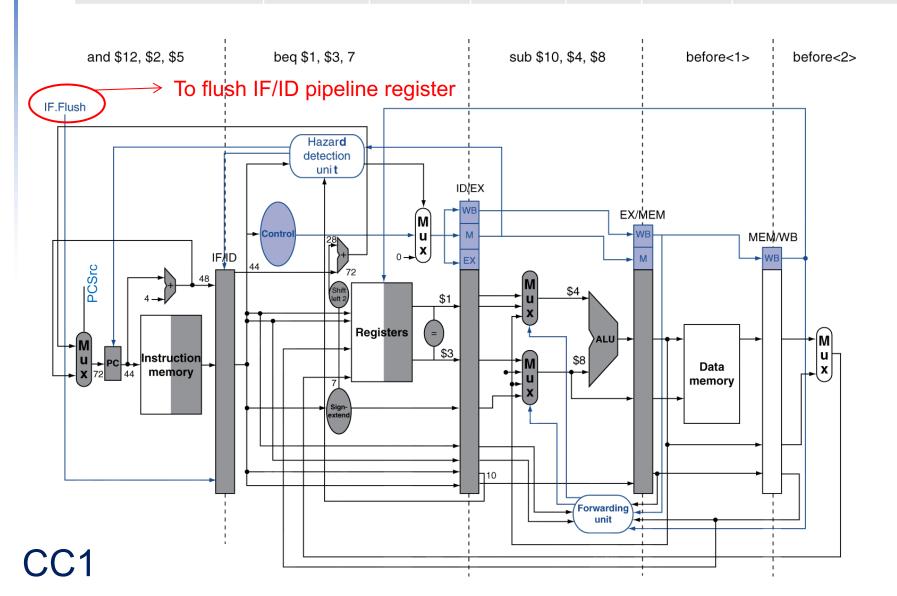
Register comparison

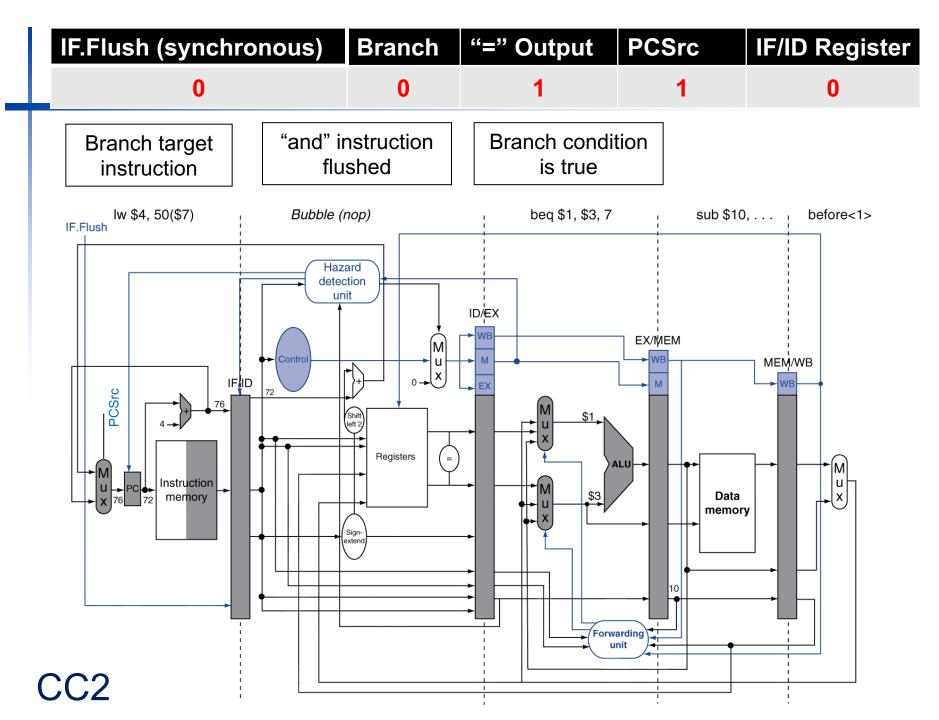
Flush an Instruction

- Flush: To discard the wrong instruction in pipeline, equivalent to neutralize all operations
 - Clear IF/ID pipeline register, by a new control signal IF.Flush
 - Flushes the instruction in IF stage



IF.Flush (synchronous)	Branch	"=" Output	PCSrc	PCin		IF/ID Register
1	1	1	0	72	44	beq & PC+4



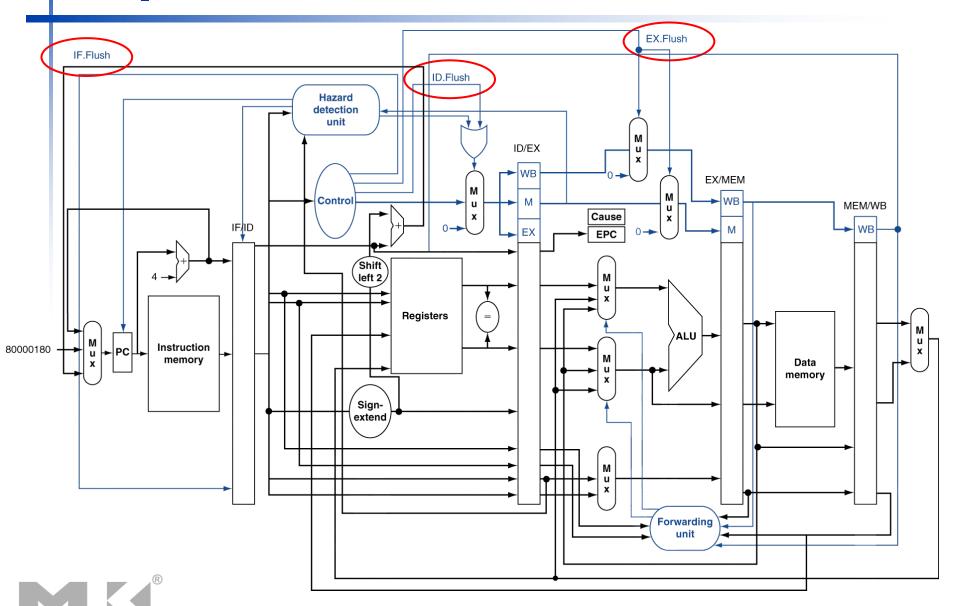


Flush Multiple Instructions

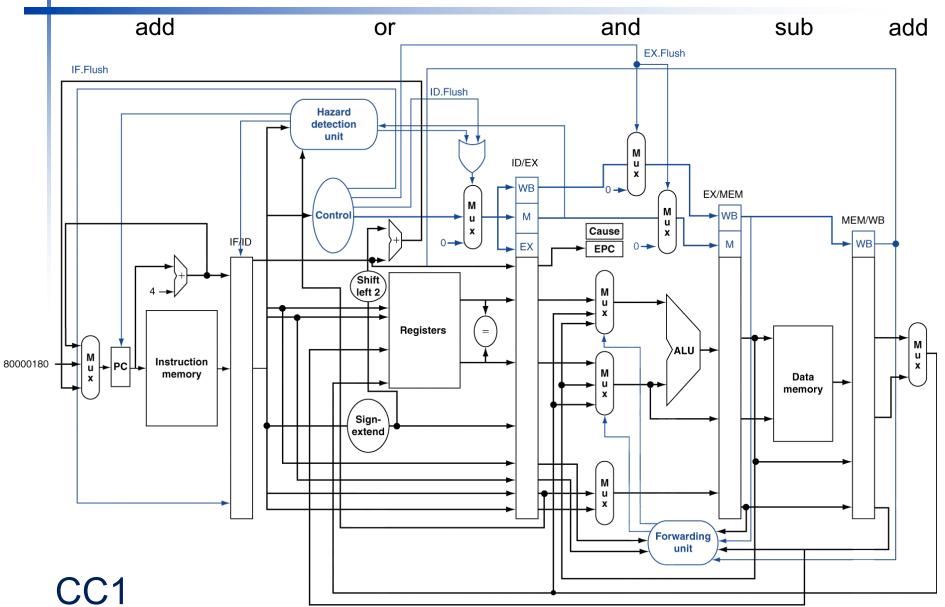
- What's in IF stage is previous 1 instruction, how to flush previous 2 or 3 instructions in ID and EX stages?
 - Send 0 control signals through the pipeline
 - Flushes the instruction in ID stage
 - Flushes instructions in following stage

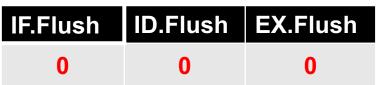


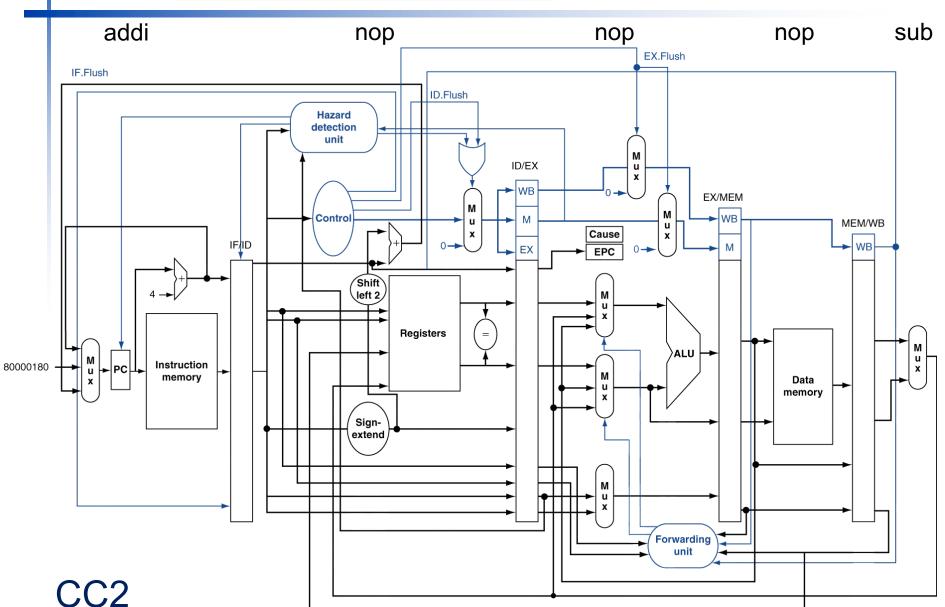
Pipeline with Extra Controls



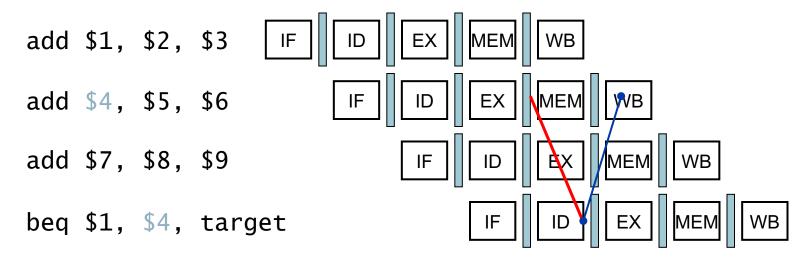








- Changing datapath structure causes more possible data hazards
- If a register for comparison is a destination of 2nd preceding ALU instruction



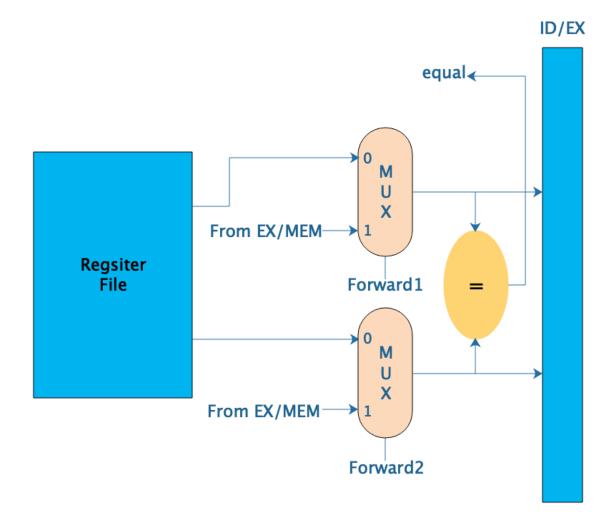
- Can resolve using new forwarding paths
- Is \$1 a data hazard?



Forwarding Paths

 Forwarding paths are created between stage pipeline register and comparator inputs

Conditions to determine Forward1 and Forward2?





If a comparison register is a destination of *immediately* preceding ALU instruction or 2nd preceding load instruction



Need 1 stall cycle even with forwarding



- If a comparison register is a destination of immediately preceding load instruction
 - Need 2 stall cycles



Branch Hazard Resolutions

- Stall on branch
- Always assume branch not taken or taken
- Branch prediction (instead of assumption)
- Delayed Branch



Branch Prediction

- Static prediction
 - Based on typical branch behavior
 - Example: loop and if-statement branches
 - Could predict backward branches taken
 - Could predict forward branches not taken
- Dynamic prediction
 - Hardware measures actual branch behavior
 - e.g., record recent history of each branch
 - Assume future behavior will continue the trend
 - If wrong, take penalty, and update history



Dynamic Branch Prediction

- Dynamic prediction is better
 - Branch prediction buffer (aka branch history table)
 - Indexed by recent branch instruction addresses
 - Stores outcome (taken/not taken)
 - To execute a branch
 - Check table, expect the same outcome
 - Start fetching from fall-through (next) or target address
 - If wrong, flush pipeline and flip prediction in the buffer
- In deeper pipelines (more stages), branch penalty is more significant



1-Bit Dynamic Predictor

- Assume branch taken
- Inner loop branches mis-predicted twice in every outer loop iteration

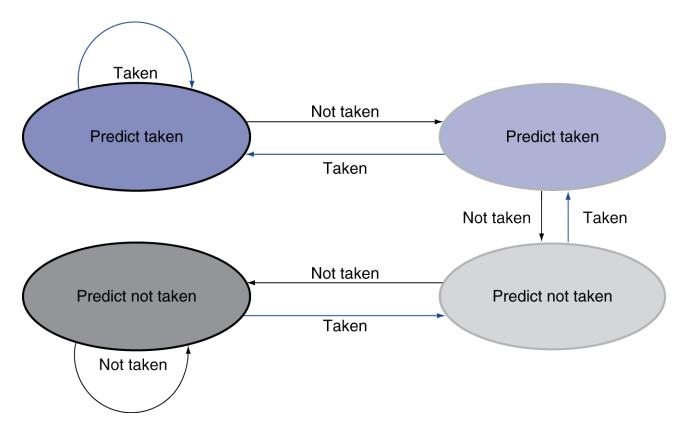
```
outer: ...
inner: ...
beq ..., ..., inner
...
beq ..., outer
```

- Mis-predict as taken on last iteration of inner loop
- Then mis-predict as not taken on first iteration of inner loop next time around



2-Bit Dynamic Predictor

 Only change prediction on two successive mispredictions





2-Bit Dynamic Predictor

- Assume initial state of strong branch taken
- Inner loop branches mis-predicted once in every outer loop iteration

```
outer: ...
inner: ...
beq ..., ..., inner
...
beq ..., ..., outer
```

Mis-predict as taken on last iteration of inner loop



Branch Hazard Resolutions

- Stall on branch
- Always assume branch not taken or taken
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Delayed Branch

- Always delay the branch
 - With one instruction, NOP or usually a real instruction, for 5 stage pipeline
 - Maybe more delays for deeper pipeline
- Requires carefully designed compiler



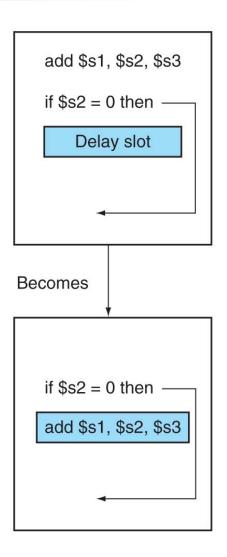
Delayed Branch

- Always execute the instruction immediately following branch
 - Called Branch delay slot
 - Further reduce branch penalty
- One branch delay slot becomes insufficient
 - When pipeline gets deeper or multiple instructions per clock cycle
 - Dynamic branch prediction is better choice



Example for Delayed Branch

- Will remove the 1 clock cycle penalty
- Will work only if instructions can be found to fill the delay slot





Overall Structure

