

# Contents

<b>1</b>	<b>Model</b>	<b>1</b>
1.1	Problem . . . . .	1
1.2	Discretization and assumption . . . . .	2
1.3	Derivatives . . . . .	2
1.4	Monte Carlo . . . . .	3
<b>2</b>	<b>Test Results</b>	<b>3</b>
2.1	Constraints in Optimization . . . . .	5
2.1.1	$f_+$ and $f_-$ . . . . .	5
2.1.2	Average Firing Rate . . . . .	5
2.2	Stimulus Width . . . . .	5
2.2.1	The effect of $\nu$ . . . . .	5
2.2.2	The effect of $\tau$ . . . . .	5
2.3	Stimulus function shape (to be examined) . . . . .	9
2.4	Initial Conditions of Tuning curve (See Figure 1) . . . . .	9
2.5	Random choice of Saturation . . . . .	9
<b>3</b>	<b>Piecewise Constant Tuning Curves</b>	<b>9</b>
<b>4</b>	<b>About Karush–Kuhn–Tucker conditions</b>	<b>15</b>

## 1 Model

$$p(\theta) = \frac{1}{2\pi}$$

$$P(r_i|\theta) = \frac{(f_i(\theta)\tau)^{r_i}}{r_i!} e^{-f_i(\theta)\tau} \quad (1)$$

$$P(r_1, \dots, r_M|\theta) = \prod_{j=1}^M \frac{(f_j(\theta)\tau)^{r_j}}{r_j!} e^{-f_j(\theta)\tau} \quad (2)$$

where  $\theta \in (0, 2\pi)$ ,  $t$  is the tuning curve (periodic),  $s$  is the stimulus,  $\tau$  is the time for stimulus to be active. The rate function  $f$  is obtained by convolution:

$$f(\theta) = \int t(\theta - y)s(y)dy \quad (3)$$

which specifies the firing rate (number of neurons fired in unit time).

### 1.1 Problem

$$\begin{aligned} \max_{t_1(\cdot), \dots, t_M(\cdot)} I(\mathbf{r}; \theta) \\ f_- \leq f_i(\cdot) \leq f_+ \\ \int f_i(\theta)p(\theta)d\theta = \text{const} \end{aligned} \quad (4)$$

And since  $f$  is the convolution of  $t$  and  $s$ , this is equivalent to:

$$\begin{aligned} \max_{t_1(\cdot), \dots, t_M(\cdot)} I(\mathbf{r}; \theta) \\ f_- \leq t_i(\cdot) \leq f_+ \\ \int t_i(\theta)p(\theta)d\theta = \text{const} \end{aligned} \quad (5)$$

## 1.2 Discretization and assumption

$\theta = (\theta_1, \dots, \theta_M)$ ,  $f = (f_1, \dots, f_M)$ . Assume the tuning curves (also the rate curves) is **rotationally invariant**, i.e. different  $f_i$ 's have the same shape but difference in translations (rotations in  $(0, 2\pi)$ ):

$$f_i(\theta_j) = f_0(\theta_j - \theta_i) = f_{j-i} \quad (6)$$

From Rotational Invariance Assumption we get:

$$\begin{aligned} I(\mathbf{r}; \theta) &= D_{KL}(p(\mathbf{r}, \theta) \| p(\mathbf{r})p(\theta)) \\ &= \int_{\theta} \int_{\mathbf{r}} p(\mathbf{r}|\theta)p(\theta) \ln \left( \frac{p(\mathbf{r}|\theta)}{p(\mathbf{r})} \right) d\mathbf{r}d\theta \end{aligned} \quad (7)$$

$$\begin{aligned} &= \frac{1}{M} \sum_{i=1}^M D_{KL}(p(\mathbf{r}|\theta = \theta_i) \| p(\mathbf{r})) \\ &= D_{KL}(p(\mathbf{r}|\theta = 0) \| p(\mathbf{r})) \\ &= -E_{\mathbf{r}|\theta=0} \left[ \ln \left( \frac{p(\mathbf{r})}{p(\mathbf{r}|\theta=0)} \right) \right] \\ &= -E_{\mathbf{r}|\theta=0} \ln(S(\mathbf{r})) \end{aligned} \quad (8)$$

where

$$\begin{aligned} P(\mathbf{r}|\theta=0) &= \prod_{j=1}^M \frac{(f_j \tau)^{r_j}}{r_j!} e^{-(f_j \tau)} \\ S(\mathbf{r}) &= \frac{1}{M} \sum_{k=1}^M \prod_{j=1}^M \left( \frac{(\tau f_{j-k})^{r_j}}{(\tau f_j)^{r_j}} \right) = \frac{1}{M} \sum_{k=1}^M \prod_{j=1}^M f_j^{r_{j+k} - r_j} \end{aligned}$$

Therefore the discretized version of Problem:

$$\begin{aligned} &\max_{t_1, \dots, t_M} [-E_{\mathbf{r}|\theta=0} \ln(S(\mathbf{r}))] \\ &\quad f_- \leq t_i \leq f_+ \\ &\quad \sum_{i=1}^M t_i = \text{const} \end{aligned} \quad (9)$$

Here  $t_i$  denotes the value of tuning curve  $t(t_0)$  at  $\theta_i$ , not the tuning curve function as in (4), (5).

## 1.3 Derivatives

By writing  $I(\mathbf{r}; \theta) = -\sum_{\mathbf{r}} P(\mathbf{r}|\theta=0) \ln(S(\mathbf{r}))$  we get

$$\frac{\partial I}{\partial f_i} = \tau \cdot E_{\mathbf{r}|\theta=0} [(1 - r_i/f_i) \ln(S)]$$

$$\frac{\partial^2 I}{\partial f_i \partial f_j} = \tau^2 \cdot E_{\mathbf{r}|\theta=0} \left[ - (r_i/f_i - 1)(r_j/f_j - 1) \ln(S) + \frac{1}{2f_i f_j} \frac{\sum_k (r_i - r_{i+k})(r_j - r_{j+k}) \prod_l f_l^{r_{l+k}}}{\sum_k \prod_l f_l^{r_{k+l}}} + 1_{\{i=j\}} \cdot (r_i/f_i^2) \ln(S) \right]$$

And from the convolution relation

$$\frac{\partial I}{\partial t_i} = \sum_j \frac{\partial I}{\partial f_j} \frac{\partial f_j}{\partial t_i} = \sum_j \frac{\partial I}{\partial f_j} s_{j-i}$$

$$\frac{\partial^2 I}{\partial t_i \partial t_j} = \sum_k \sum_l \frac{\partial^2 I}{\partial f_k \partial f_l} s_{k-i} s_{l-j}$$

## 1.4 Monte Carlo

In computation, we approximate the above expectations by Monte Carlo:

$$\hat{I} = \frac{1}{N} \sum_{n=1}^N \ln \left( S(\mathbf{r}^{(n)}) \right)$$

$$\widehat{\partial_{f_i} I} = \tau \cdot \frac{1}{N} \sum_{n=1}^N \left[ \left( 1 - r_i^{(n)} / f_i \right) \ln(S(\mathbf{r}^{(n)})) \right]$$

$$\partial_{f_i} \widehat{\partial_{f_j} I} = \tau^2 \cdot \frac{1}{N} \sum_{t=1}^N \left[ - (r_i / f_i - 1) (r_j / f_j - 1) \ln(S(\mathbf{r})) + \frac{1}{2 f_i f_j} \sum_k (r_i - r_{i+k}) (r_j - r_{j+k}) \text{Exp}(k) + 1_{\{i=j\}} \cdot (r_i / f_i^2) \ln(S(\mathbf{r})) \right]^{(n)}$$

where  $\mathbf{r}^{(n)} = (r_1^{(n)}, \dots, r_M^{(n)})$  are sampled from independent Poisson distributions:  $r_i^{(n)} \sim \text{Poisson}(f_i)$ .

## 2 Test Results

Basic Setting for most our cases (may vary in different tests):

- Constrained Optimization Method: SLSQP (Sequential Least Squares Programming). It uses the Han–Powell quasi–Newton method with a BFGS update of the B–matrix and an L1–test function in the step–length algorithm. The optimizer uses a slightly modified version of Lawson and Hanson’s NNLS nonlinear least-squares solver. Reference: Scipy ,PyOpt
- Language in C++/Python, Package: scipy.optimize.minimize
- $M = \text{numBin} = 64$
- $s(x) = \frac{1}{\nu\tau} 1_{[0, \nu\tau]}(x)$ : rectangular stimulus function with speed  $\nu$ , time period  $\tau$ . Note: the integral of stim is always normalized to 1; however the rate function  $f$  is multiplied by  $\tau$ , see equation 1. In some cases we set  $s(x) \propto e^{-\alpha x} 1_{[0, \nu\tau]}(x)$ , also normalized.
- $\nu = 16, \tau = 1.0$
- $f_- = 0.1, f_+ = 1.0, \frac{f_+}{f_-} = 10$ .
- Average of tuning curve  $\frac{1}{M} \sum t_i = \frac{f_- + f_+}{2} = 0.55$
- Number of iterations in Monte Carlo:  $10^5$  for  $I$ ,  $10^6$  for  $\nabla I$ .
- Number of iterations in optimization around 120 (the program doesn’t end itself but the shape has generally stoped to change)
- Use  $\ln(\cdot)$  instead of  $\log_2(\cdot)$  in all information/gradient calculations.

First we vary different parameters above and did 5 experiments:

Observe the phenomenon:

- Same parameters and constraints, different initial tuning curves may ‘converge’ to different maximizers, so the maximizers may be local.
- But the tuning curves all seem to reach  $f_+, f_-$  as much as possible, i.e. ‘saturates’ to the extremes.
- Changing stim shape from rectangle to exponential does not affect the saturation effect.
- Decreasing  $\nu$  will increase the mutual information  $I$ , since we have a smaller window of convolution.

Systematically, we look at the effect of varying each test condition:

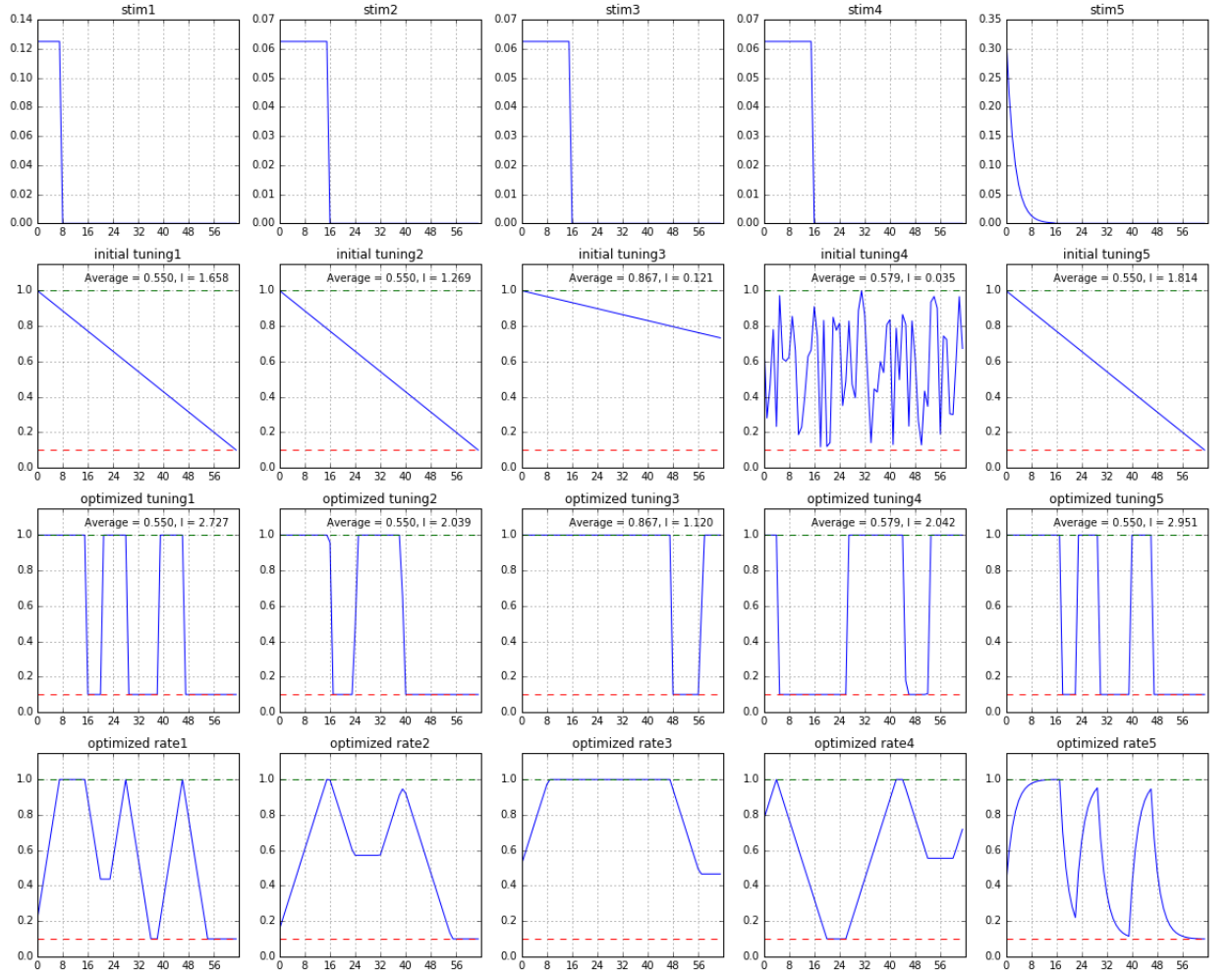


Figure 1:

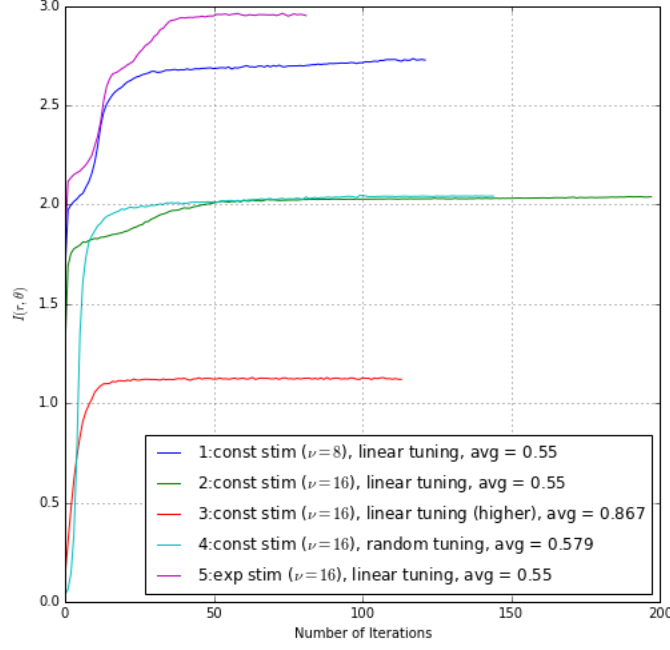


Figure 2:

## 2.1 Constraints in Optimization

### 2.1.1 $f_+$ and $f_-$

Figure 3.

Same initial tuning curve, different inequality constraints. All tends to saturates to the bounds, but surprisingly  $f_+ = 2$  gives higher information (though constraint of  $f_+ = 4$  are more loose, but it converges to a local maximum where  $I$  is lower.)

### 2.1.2 Average Firing Rate

Figure 4, Figure 5.

$\frac{f_+ + f_-}{2}$  might be the max, but not symmetric.

## 2.2 Stimulus Width

### 2.2.1 The effect of $\nu$

First we just calculated the mutual information for different  $\nu$  with the following tuning and stimulus in Figure 6, the mutual information shown in Figure 7.

Then we did optimization with different  $\nu$ : Figure 8.

### 2.2.2 The effect of $\tau$

We take  $\nu = 8$ ,  $f_- = 0.1$ ,  $f_+ = 1.0$ . Note that the stimulus  $s = \frac{1}{\nu\tau} 1_{[0, \nu\tau]}$  (integral normalized to 1), and the poisson distribution is related to  $\tau$ :  $P(\mathbf{r}|\theta = 0) = \prod_{j=1}^M \frac{(f_j\tau)^{r_j}}{r_j!} e^{-(f_j\tau)}$ .

Fix tuning0, vary  $f_+$ ,  $f_-$  with  $\nu=16$ ,  $\tau=1.0$

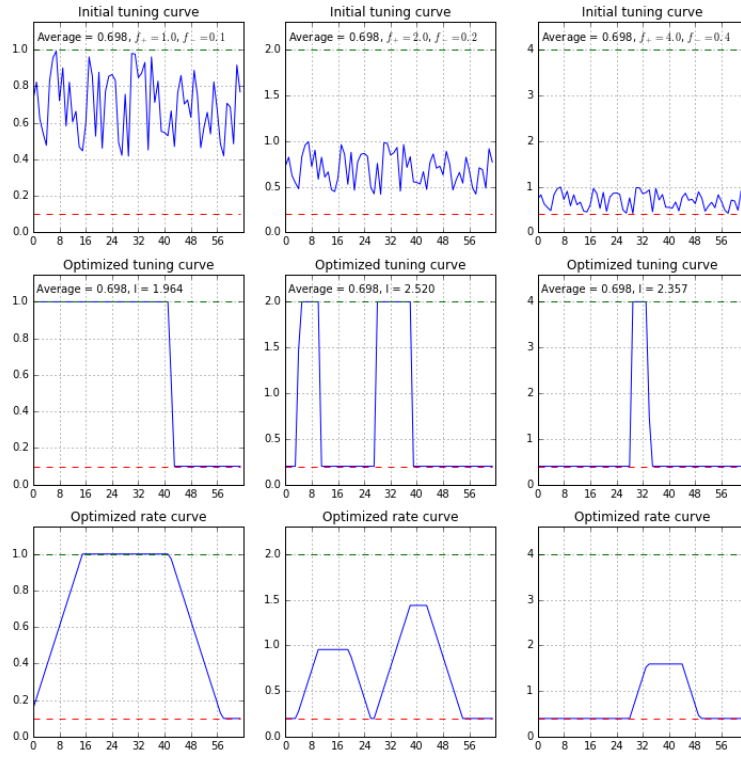


Figure 3:

Fix  $f_+$ ,  $f_-$ , vary average firing rate with  $\nu=16$ ,  $\tau=1.0$

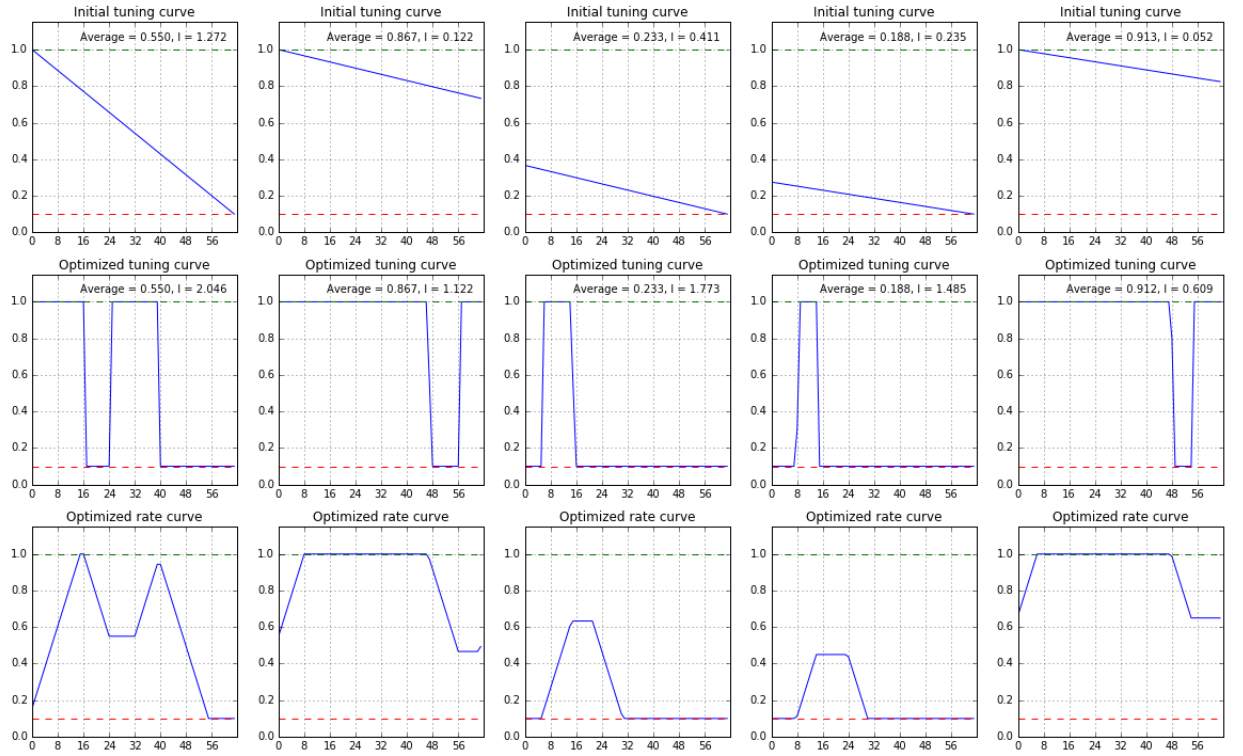


Figure 4:

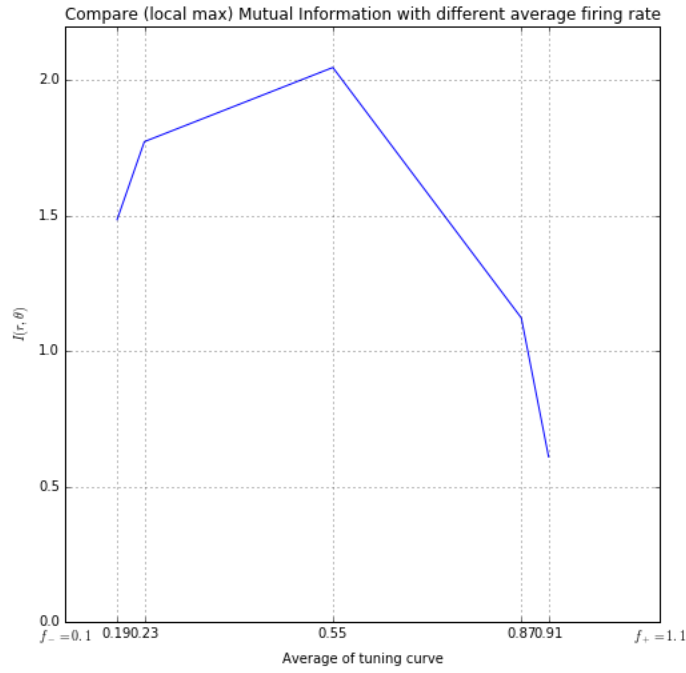


Figure 5:

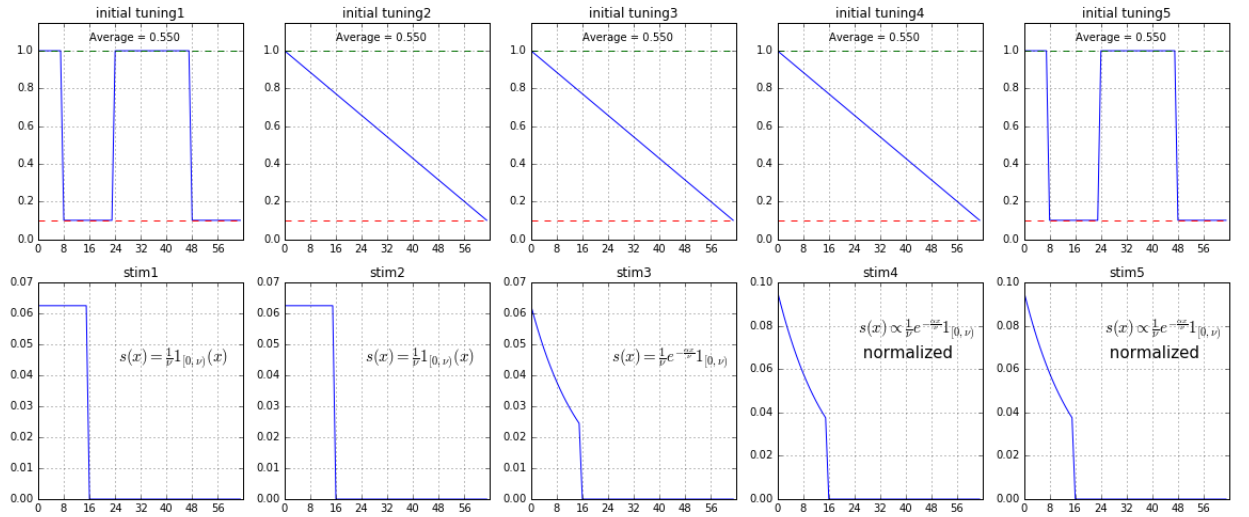


Figure 6:



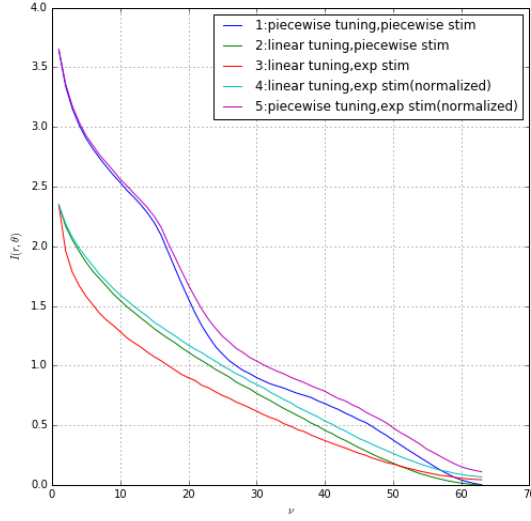


Figure 7:

What we want to investigate is the trade-off between improved evidence accumulation (larger spike count average) and worsened position certainty (larger convolution window) which is entailed by increasing  $\tau$ . We expect that there is an optimal  $\tau$  yielding the maximum mutual information.

Figure 9 shows max at  $\tau = 0.875$ , i.e.  $\nu\tau = 7$ .

More figures see 'data2-2' directory.

### 2.3 Stimulus function shape (to be examined)

### 2.4 Initial Conditions of Tuning curve (See Figure 1)

### 2.5 Random choice of Saturation

Not all curves which takes either  $f_+$  or  $f_-$  are local max. See Figure 11: randomly take different proportions of points to be  $f_+$  (other points  $f_-$ ).

## 3 Piecewise Constant Tuning Curves

For  $M = 64$ ,  $\nu = 16$ ,  $\tau = 1.0$ , average firing rate =  $\frac{f_+ + f_-}{2}$ , assume our local maximizers are of the form

$$f_+ \cdot 1_{[0, d_+)} + f_- \cdot 1_{[d_+, d_+ + d_-)} + f_+ \cdot 1_{[d_+ + d_-, \frac{M}{2} + d_-)} + f_- \cdot 1_{[\frac{M}{2} + d_-, M)}$$

i.e. two plateaus with width sum up to 32.

1. Changing  $d_+$ ,  $d_-$  we get the following diamond shape: Figure 12, optimized when  $d_+ = 8$ ,  $d_- = 16$ .
2. When  $f_+ = 16$ ,  $f_- = 1.6$  we have Figure 13. By looking at rate curves in Figure 14 (of  $f_+ = 1$ ) we can explain partially why we have larger plateaus with lower  $f_-$ ,  $f_+$ : since neurons' firing rate is too low, we need to count spikes from more neurons.
3. Not necessarily the same shape when changing  $M$ : see the diamond with  $M = 32$  in Figure 15.
4. Still need explanation why the gradient fails at  $d_+ = d_- = 16$  (knowing that it is a sharpe local minimum because of periodicity with period  $\frac{M}{2}$ , losing information).

Fix tuning0, vary  $\nu$ , with  $\tau = 1.0$

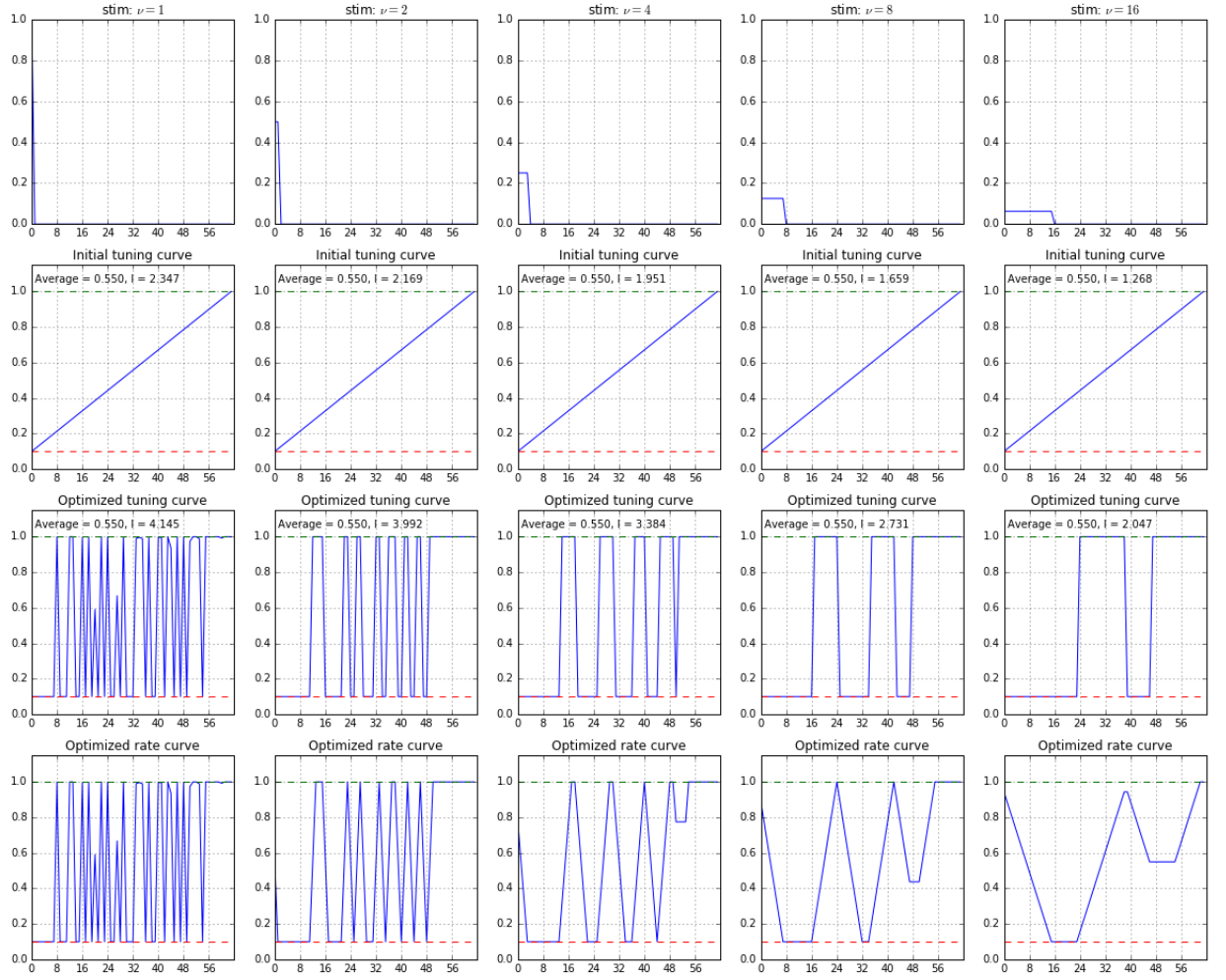


Figure 8:

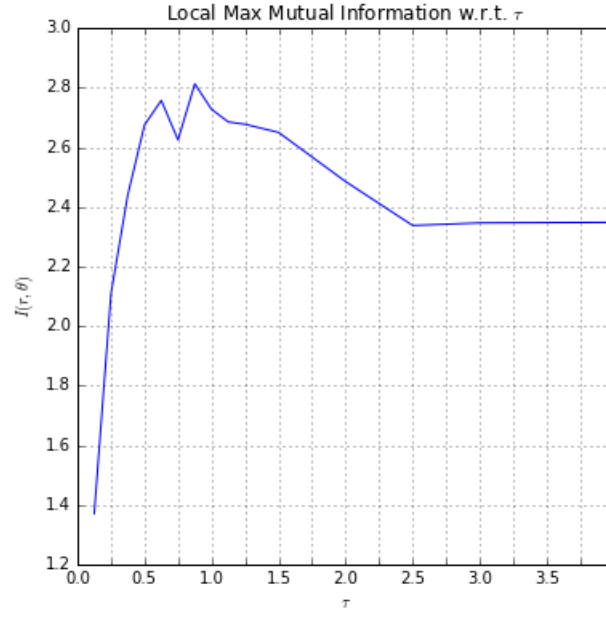


Figure 9:

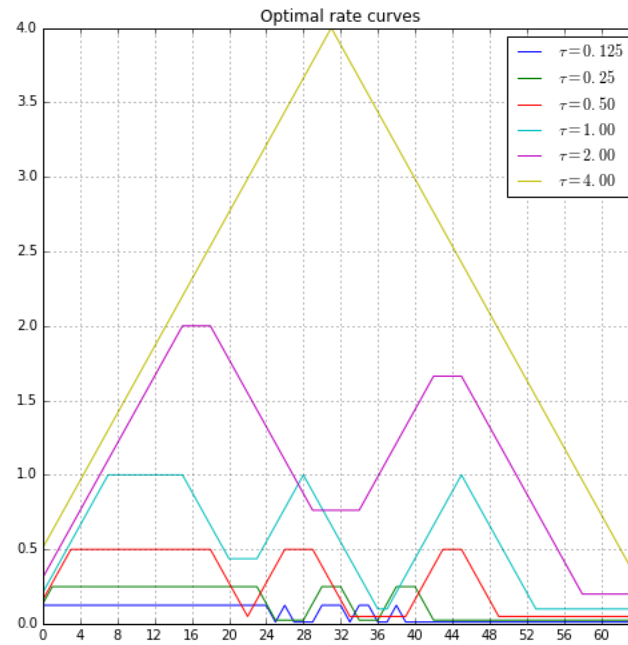


Figure 10:

Fix  $f_+$ ,  $f_-$ , vary average firing rate with  $\nu=16$ ,  $\tau=1.0$

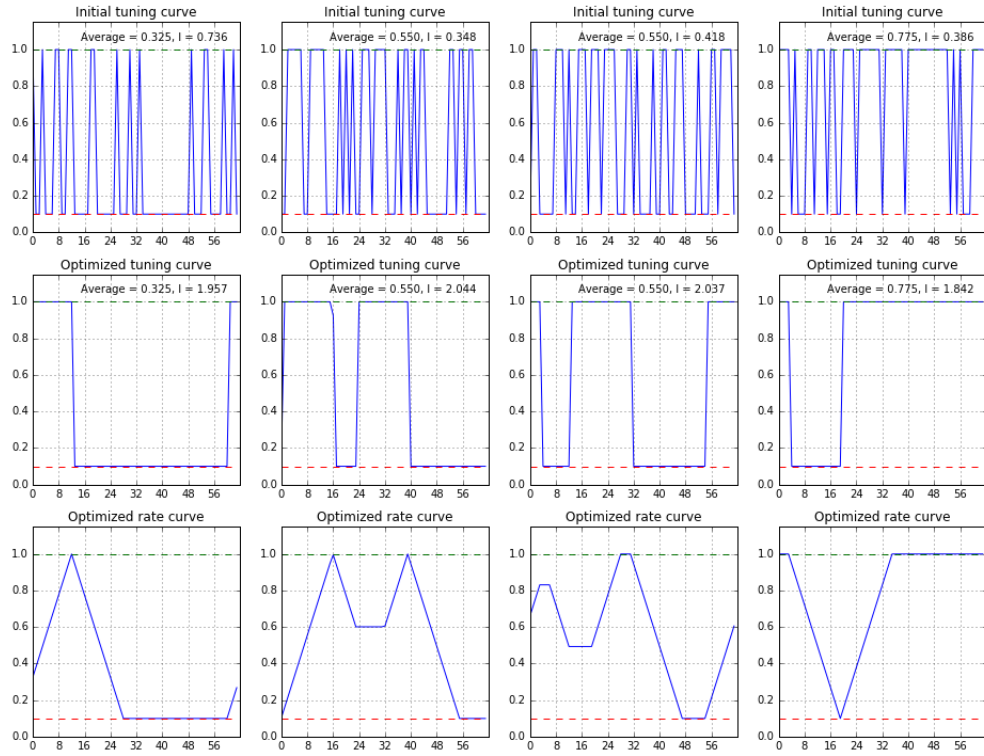


Figure 11:

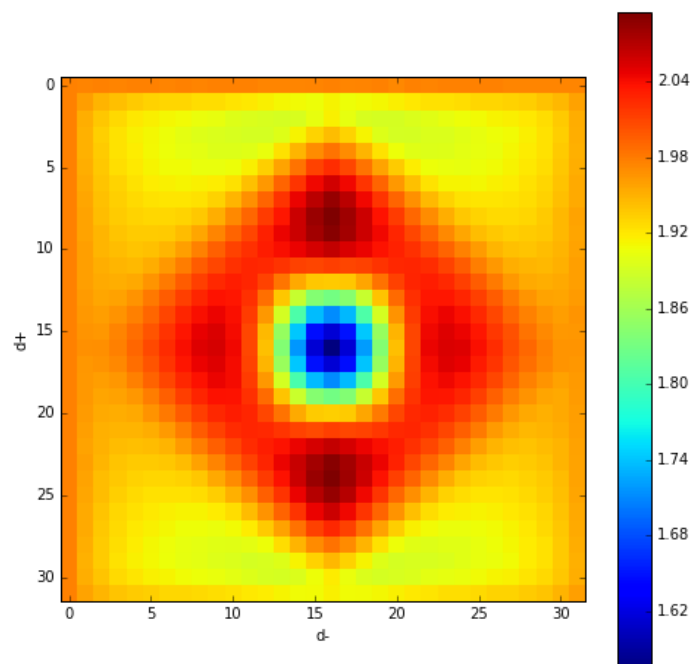


Figure 12:

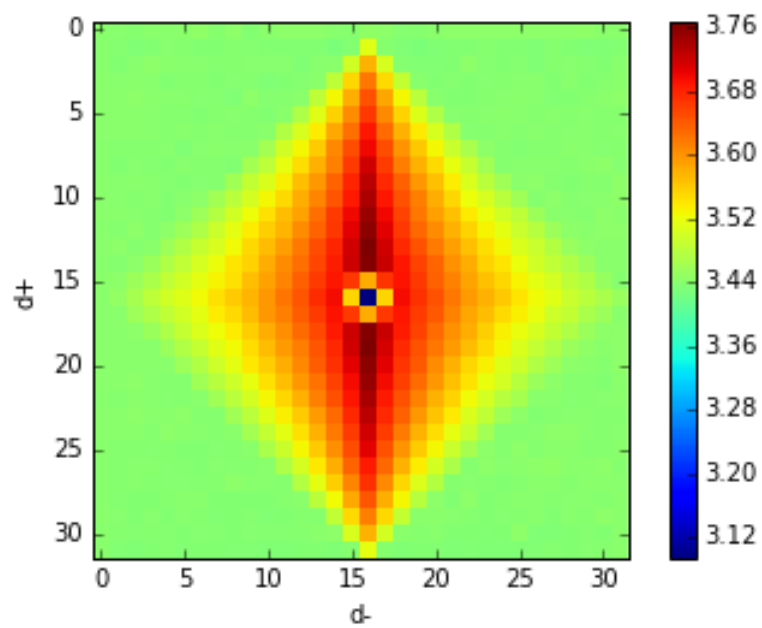


Figure 13:

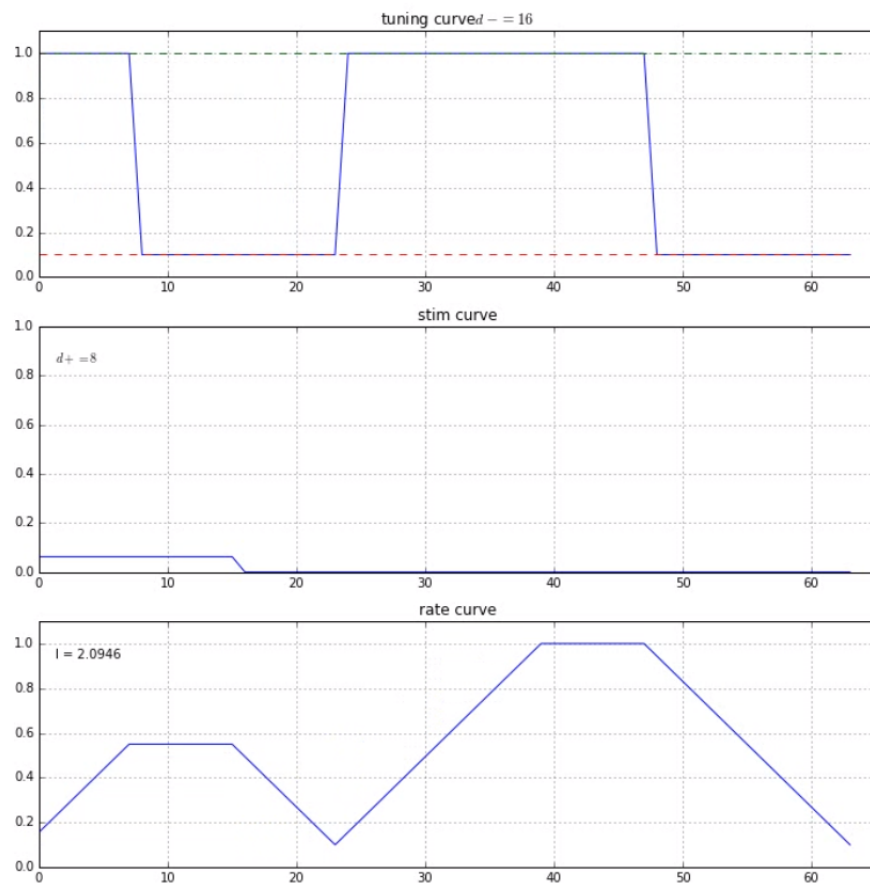


Figure 14:

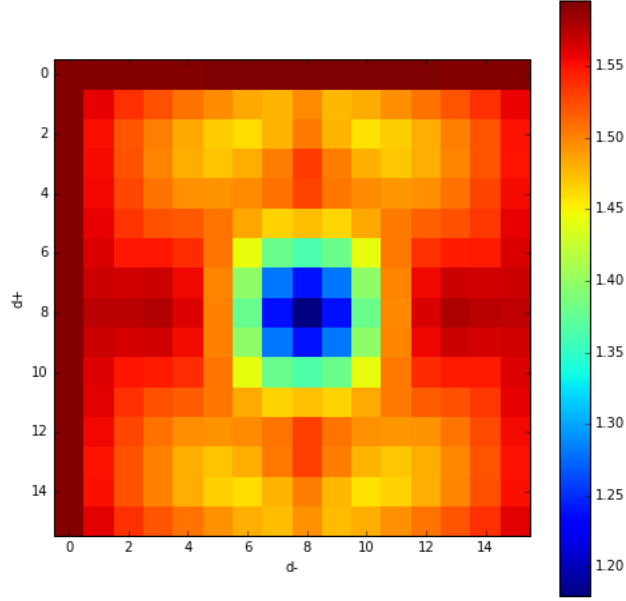


Figure 15:

## 4 About Karush–Kuhn–Tucker conditions

For convenience of reading we denote the tuning curve  $t$  as  $f$  in this section.

The Lagrangian

$$L(f; \alpha^+, \alpha^-, \mu) = I(f) + \alpha^+(f - f_+) + \alpha^-(f_- - f) + \mu\left(\frac{1}{M} \sum f - c\right)$$

where  $c$  is the average of initial tuning curve,  $f - f_+ \leq 0$ ,  $f_- - f \leq 0$ .

The constraints of the problem (9) are linear, so the KKT conditions are necessary conditions (although may not be sufficient since  $I(f)$  is not convex):

if  $f^* = (f_1^*, \dots, f_M^*)$  is a local maximizer, then there exists  $\alpha^+ = (\alpha_1^+, \dots, \alpha_M^+)$ ,  $\alpha^- = (\alpha_1^-, \dots, \alpha_M^-)$  and constant  $\mu$ , such that

1.  $\nabla_{f*} I(s) = \alpha^+(s) - \alpha^-(s) + \mu, \forall s$
2.  $f_- \leq f^* \leq f_+$
3.  $\alpha^+ \geq 0, \alpha^- \geq 0$
4.  $\alpha^+(s)(f^*(s) - f_+) = 0, \alpha^-(s)(f_- - f^*(s)) = 0$ , i.e.  $\alpha^+$  is supported on  $\{f = f_+\}$ ,  $\alpha^-$  is supported on  $\{f = f_-\}$ .

Hence we have:

- $\nabla_{f*} I(s) = \mu, \forall s$  such that  $f^*(s) \neq f_+, f^*(s) \neq f_-$
- $\nabla_{f*} I(s) = \alpha^+(s) + \mu \geq \mu, \forall s$  such that  $f^*(s) = f_+$
- $\nabla_{f*} I(s) = -\alpha^-(s) + \mu \leq \mu, \forall s$  such that  $f^*(s) = f_-$

So

$$\begin{aligned} \nabla_{f*}I(s_-) &\leq \mu \leq \nabla_{f*}I(s_+) \\ \max_{s_-} \nabla_{f*}I(s_-) &\leq \mu \leq \min_{s_+} \nabla_{f*}I(s_+) \end{aligned} \tag{10}$$

Therefore as long as  $f$  has the property that  $\max \nabla_f I(s_-) \leq \min \nabla_f I(s_+)$  (where  $s_- \in \{f = f_-\}$ ,  $s_+ \in \{f = f_+\}$ ), it is possible to find  $\mu$  such that (10) holds, and satisfies the KKT conditions.

See the animations in 'mydata2' directory which shows the gradient and  $\mu$  in experiments.