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1 A Model Problem

Consider a simplified version of the continuous limit case. Assume θ is on the circle $[0, 1)$ with uniform distribution $p(\theta) = 1$. X, Y are conditionally independent of θ :

$$p(x, y|\theta) = p(x|\theta)p(y|\theta).$$

Also, assume that X, Y comes from the same population and satisfy translation invariance:

$$p(x|\theta) = f(x - \theta), p(y|\theta) = f(y - \theta)$$

and f satisfies the constraint:

$$\int_0^1 f(\theta) d\theta = 1.$$

Then the mutual information of (X, Y) and Θ is:

$$\begin{aligned} I(X, Y; \Theta) &= D_{KL}(p(x, y, \theta) \| p(x, y)p(\theta)) \\ &= \int_0^1 dx \int_0^1 dy f(x)f(y) \ln \left(\frac{f(x)f(y)}{\int_0^1 d\theta f(x-\theta)f(y-\theta)} \right) \end{aligned} \quad (1)$$

where we have applied the periodicity of f on $[0, 1)$.

1.1 The auto-correlation function

Define

$$A(u) := \int_0^1 d\theta f(\theta)f(u + \theta)$$

Properties of $A(\cdot)$ on circle $[0, 1)$:

- $A(u) = A(-u)$ since $\int_0^1 d\theta f(\theta) f(u + \theta) = \int_0^1 d\theta' f(\theta' - u) f(\theta')$;
- $A(u) = A(1 - u)$, i.e. $A(u)$ is symmetric w.r.t. $u = \frac{1}{2}$;
- $A(x - y) = \int_0^1 d\theta f(\theta) f(x - y + \theta) = \int_0^1 d\theta f(x - \theta) f(y - \theta)$;
- If $\bar{f} = 1$ then $\int A = 1$, $f_- \leq A \leq f_+$;
- A is continuous if f only has a finite number of discontinuities.

Thus the expression for mutual information can be simplified as:

$$\begin{aligned}
I(X, Y; \Theta) &= -2H[f] - \int dx \int dy f(x) f(y) \ln(A(x - y)) \\
&= -2H[f] - \int d\theta \int dx \int dy f(x - \theta) f(y - \theta) \ln(A(x - y)) \\
&= -2H[f] + H[A]
\end{aligned} \tag{2}$$

where H is the continuous entropy: $H[f] = -\int_0^1 f(x) \ln f(x) dx$.

1.2 Gradient

$$\nabla_f I(x) = 2 \left(\ln f(x) - \int_0^1 dy f(y) \ln(A(y - x)) \right) \tag{3}$$

Detailed computation in the Appendix A.1.

2 Preturbation Method

Let $\delta(x)$ be a smooth, 1-Lipschitz function which satisfies $\delta(0) = \delta(1) = 0$. When ϵ is small enough, $x \mapsto x + \epsilon\delta(x)$ is a one-to-one mapping. Also, we require that $\int_0^1 f(x + \epsilon\delta(x)) = 1$, which implies

$$\int_0^1 f(x) \delta'(x) = 0. \tag{4}$$

Assume f is **piecewise** C^1 on the circle $[0, 1)$.

Proposition 1. *If f is piecewise C^1 , for any $\delta(x) \in C^\infty(0, 1)$,*

$$\int \delta'(\eta) f(\eta) d\eta = - \left[\int \delta(\eta) f'_c(\eta) + \sum_{i \in D} \Delta_i f \cdot \delta(x_i) \right] \tag{5}$$

i.e. the distributional derivative of f is

$$f'(x) = f'_c(x) + \sum_{i \in D} \Delta_i f \cdot \delta_{x_i}(x) \tag{6}$$

where $f'_c(x)$ is the point-wise derivative of f (zero at discontinuities), D is the set of discontinuities of f , $\Delta_i f := f(x_i^+) - f(x_i^-)$, where $x_i \in D$.

Proof. Assume f is discontinuous only at $a \in (0, 1)$:

$$\begin{aligned}
\int_0^1 \delta'(\eta) f(\eta) d\eta &= \int_0^a \delta'(\eta) f(\eta) d\eta + \int_a^1 \delta'(\eta) f(\eta) d\eta \\
&= \delta(a) f(a^-) - \delta(0) f(0) - \int_0^a \delta(\eta) f'(\eta) d\eta + \delta(1) f(1) - \delta(a) f(a^+) - \int_a^1 \delta(\eta) f'(\eta) d\eta \\
&= - \left[\int_0^1 \delta(\eta) f'(\eta) d\eta + (f(a^+) - f(a^-)) \delta(a) \right]
\end{aligned}$$

Similarly, when we have more than one discontinuities $x_i \in D$,

$$\int_0^1 \delta'(\eta) f(\eta) d\eta = - \left[\int \delta(\eta) f'_c(\eta) d\eta + \sum_{i \in D} \Delta_i f \cdot \delta(x_i) \right]$$

□

2.1 Computation of $\nabla_\delta I[f]$

By writting $I[f(x + \epsilon\delta(x))] - I[f]$, we obtain

$$\begin{aligned} \nabla_\delta I[f] &= 2 \left[f'_c(x) (\log f_c(x) + 1) - f'_c(x) \int dy f(y) \log A(y-x) - f(x) \int dy f(y) \frac{\int_0^1 d\theta f'(x-\theta) f(y-\theta)}{\int_0^1 d\theta f(x-\theta) f(y-\theta)} \right] \\ &\quad + 2 \sum_{i \in D} \left[\Delta_i (f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right] \delta_{x_i}(x) \end{aligned} \quad (7)$$

Notice that $A(y-x) = \int_0^1 d\theta f(x-\theta) f(y-\theta)$ is continuous, and the intergral $\int_0^1 d\theta f'(x-\theta) f(y-\theta)$ is well-defined even though f' may enclude dirac delta terms. The detailed computations are in the Appendix A.2.

Proposition 2.

$$\int \nabla_\delta I[f](x) dx = 0$$

Proof. From integration by parts,

$$\begin{aligned} \int dx f(x) \int dy f(y) \frac{\int_0^1 d\theta f'(x-\theta) f(y-\theta)}{\int_0^1 d\theta f(x-\theta) f(y-\theta)} &= \int f(y) dy \int f(x) \frac{\partial}{\partial x} \log(A(y-x)) dx \\ &= - \int f(y) dy \int f'(x) \log(A(y-x)) dx \\ &= - \int f(y) dy \int f'_c(x) \log(A(y-x)) dx - \sum_{i \in D} \Delta_i f \int f(y) \log(A(y-x_i)) dy \end{aligned}$$

Thus

$$\int dx f(x) \int dy f(y) \frac{\int_0^1 d\theta f'(x-\theta) f(y-\theta)}{\int_0^1 d\theta f(x-\theta) f(y-\theta)} + \int f(y) dy \int f'_c(x) \log(A(y-x)) dx + \sum_{i \in D} \Delta_i f \int f(y) \log(A(y-x_i)) dy = 0,$$

$$\int \nabla_\delta I[f](x) dx = \int dx \left(f'_c(x) (\log f_c(x) + 1) + \sum_{i \in D} \Delta_i (f \log f) \delta_{x_i}(x) \right) = \int (f \log f)'(x) dx = 0.$$

□

3 KKT conditions

$$\nabla_f I(x) = \mu + \alpha_+(x) - \alpha_-(x) \quad (8)$$

$$\nabla_\delta I(x) = \nu \left[f'_c(x) + \sum_{i \in D} \Delta_i f \cdot \delta_{x_i}(x) \right] \quad (9)$$

where the 2nd one comes from minimizing $I[f(x+\epsilon\delta(x))]$ w.r.t δ , where $\int f(x) \delta'(x) dx = - \int \delta(x) dx (f'_c(x) + \sum_{i \in D} \Delta_i f \delta_{x_i}(x)) = 0$.

Proposition 3. *If $f(x)$ is continuous at x , then $\nabla_f I(x)$, $\alpha_+(x)$, $\alpha_-(x)$ are continuous at x .*

Proof. Directly observe from $\nabla_f I(x) = 2(\log f(x) - \int dy f(y) \log A(y-x))$ and $\nabla_f I(x) = \mu + \alpha_+(x) - \alpha_-(x)$. Note that $\alpha_+(x)$ and $\alpha_-(x)$ cannot be nonzero at the same time. \square

Take (distributional) derivative of the first condition with respect to x :

$$\begin{aligned} 2 \left(\log f(x) - \int_0^1 dy f(y) \log(A(y-x)) \right) &= \mu + \alpha_+(x) - \alpha_-(x) \\ \frac{f'_c(x)}{f_c(x)} + \sum_{i \in D} \Delta_i(\log f) \delta_{x_i}(x) - \int_0^1 dy f(y) \frac{\int_0^1 f'(x-\theta) f(y-\theta) d\theta}{\int_0^1 f(x-\theta) f(y-\theta) d\theta} &= \frac{\alpha'_+(x)}{2} - \frac{\alpha'_-(x)}{2} + \frac{\sum_{i \in D} (\Delta_i \alpha_+ - \Delta_i \alpha_-) \delta_{x_i}(x)}{2} \\ \frac{f'(x)}{f(x)} - \int_0^1 dy f(y) \frac{\int_0^1 f'(x-\theta) f(y-\theta) d\theta}{\int_0^1 f(x-\theta) f(y-\theta) d\theta} &= \frac{\alpha'_+(x)}{2} - \frac{\alpha'_-(x)}{2} \text{ for } x \notin D \end{aligned} \quad (10)$$

$$\Delta_i(\log f) = \frac{\Delta_i \alpha_+}{2} - \frac{\Delta_i \alpha_-}{2} \text{ for } x_i \in D \quad (11)$$

Proposition 4. *If $f(x)$ is C^1 on $[0, 1)$ and does not reach the upper/lower bounds (f_+, f_-) , then $f(x)$ is constant.*

Proof. Assume $\frac{f'(x)}{f(x)}$ is not constant, set $x = \arg \max \frac{f'(x)}{f(x)}$. Then there exists an interval where $\frac{f'(x-\theta)}{f(x-\theta)} < \frac{f'(x)}{f(x)}$. Averaging $f'(x-\theta)$ by $f(y-\theta)$,

$$\begin{aligned} \int_0^1 f'(x-\theta) f(y-\theta) d\theta &< \int_0^1 \frac{f'(x)}{f(x)} f(x-\theta) f(y-\theta) d\theta \\ \frac{\int_0^1 f'(x-\theta) f(y-\theta) d\theta}{\int_0^1 f(x-\theta) f(y-\theta) d\theta} &< \frac{f'(x)}{f(x)} \\ \int_0^1 dy f(y) \frac{\int_0^1 f'(x-\theta) f(y-\theta) d\theta}{\int_0^1 f(x-\theta) f(y-\theta) d\theta} &< \frac{f'(x)}{f(x)} \end{aligned}$$

Also, since f does not take f_+ or f_- , $\alpha_+(x) = \alpha_-(x) = 0$ for all x . From equation (10),

$$\frac{f'(x)}{f(x)} = \int_0^1 dy f(y) \frac{\int_0^1 f'(x-\theta) f(y-\theta) d\theta}{\int_0^1 f(x-\theta) f(y-\theta) d\theta}$$

which contradicts the inequality above. Therefore $\frac{f'(x)}{f(x)}$ is constant, $\log f(x) = kx + c$, $f(x) = ce^{kx}$. However since f is continuous and periodic on $[0, 1)$, $k = 0$, $f(x)$ is constant. From $\int_0^1 f(y) dy = 1$, $f(x) \equiv 1$. \square

Proposition 5. *If $f(x)$ has a jump discontinuity at x , then either one of $f(x^+)$ and $f(x^-)$ must take f_+ or f_- . That is, every jump of f takes the function value either to or from the upper/lower bounds.*

Proof. Assume that at $x_i \in D$, neither $f(x_i^+)$ nor $f(x_i^-)$ reach the bounds. Then $\alpha_+(x_i^+) = \alpha_+(x_i^-) = \alpha_-(x_i^+) = \alpha_-(x_i^-) = 0$, which contradicts the equation (11):

$$\frac{\Delta_i \alpha_+}{2} - \frac{\Delta_i \alpha_-}{2} = \log f(x_i^+) - \log f(x_i^-) \neq 0$$

\square

4 Piecewise constant functions

We focus on piecewise constant f which only takes f_+ and f_- .

Notice that for given f_- , f_+ and $\int f(x)dx = 1$, the proportion of f taking f_+ and f_- are fixed. Then $H[f] = -\int f(x) \log f(x)dx$ is fixed. Since $I[f] = -2H[f] + H[A]$, it only suffices to study the auto-correlation function $A(x) = \int f(\theta)f(x+\theta)d\theta$. First, we look at when $f(\cdot)$ and $f(\cdot+x)$ both reach f_+ or f_- :

Proposition 6. *Denote:*

$$\begin{aligned} d_+(x) &:= |\{y : f(y) = f(y+x) = f_+\}| \\ d_-(x) &:= |\{y : f(y) = f(y+x) = f_-\}| \end{aligned}$$

Then $d_+(x) - d_-(x) = d_+(0) - d_-(0) \triangleq d$.

Proof. Denote

$$\begin{aligned} l_+(x) &= |\{y : f(y) = f_+, f(y+x) = f_-\}| \\ l_-(x) &= |\{y : f(y) = f_-, f(y+x) = f_+\}| \end{aligned}$$

Then

$$\begin{aligned} d_+(0) - l_+(x) &= |\{y : f(y) = f_+\}| - |\{y : f(y) = f_+, f(y+x) = f_-\}| = |\{y : f(y) = f_+, f(y+x) = f_+\}| = d_+(x) \\ d_-(0) - l_-(x) &= |\{y : f(y) = f_-\}| - |\{y : f(y) = f_-, f(y+x) = f_+\}| = |\{y : f(y) = f_-, f(y+x) = f_-\}| = d_-(x) \end{aligned}$$

Since $f(x+\cdot)$ is a translation of f , $l_+(x) = l_-(x)$. Thus $d_+(x) - d_-(x) = d_+(0) - d_-(0)$. \square

Denote $d := d_-(0) - d_+(0)$,

$$\begin{aligned} d_+(0) + d_-(0) &= 1 \\ d_+(0)f_+ + d_-(0)f_- &= \int f dx = \bar{f} \end{aligned}$$

We get

$$d_+(0) = \frac{\bar{f} - f_-}{f_+ - f_-} = \frac{1 - f_-}{f_+ - f_-} \quad (12)$$

$$d_-(0) = \frac{f_+ - \bar{f}}{f_+ - f_-} = \frac{f_+ - 1}{f_+ - f_-} \quad (13)$$

$$d = \frac{f_+ + f_- - 2\bar{f}}{f_+ - f_-} = \frac{f_+ + f_- - 2}{f_+ - f_-} \quad (14)$$

Then

$$\begin{aligned} A(x) &= \int f(\theta)f(x+\theta)d\theta \\ &= f_+^2 d_+(x) + f_-^2 d_-(x) + f_+ f_- (1 - d_+(x) - d_-(x)) \\ &= f_+^2 d_+(x) + f_-^2 (d_+(x) + d) + f_+ f_- (1 - d_+(x) - d_+(x) - d) \\ &= (f_+ - f_-)^2 d_+(x) - f_- (f_+ - f_-) d + f_+ f_- \end{aligned} \quad (15)$$

$$\begin{aligned} &= (f_+ - f_-)^2 d_+(x) - f_- (f_+ + f_- - 2\bar{f}) + f_+ f_- \\ &= (f_+ - f_-)^2 d_+(x) + f_- (2\bar{f} - f_-) \end{aligned} \quad (16)$$

$$= (f_+ - f_-)^2 d_-(x) + f_+ (2\bar{f} - f_+) \quad (17)$$

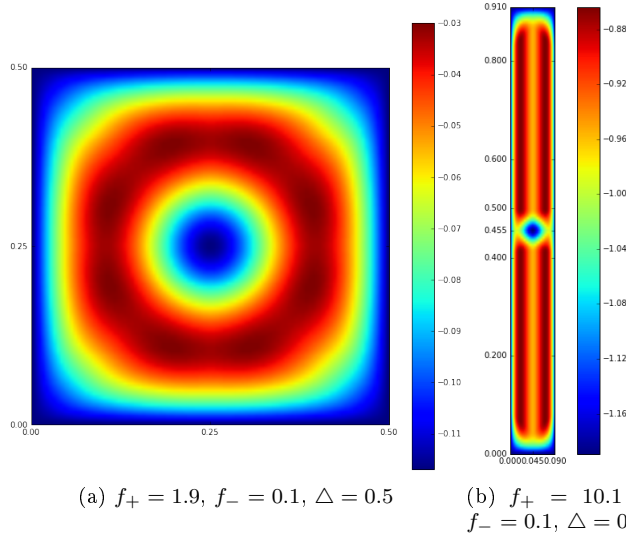


Figure 1: Mutual information I with fixed f_+, f_- and varying (t, d)

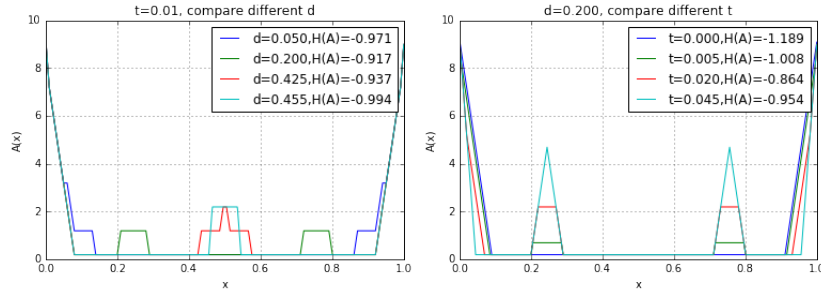


Figure 2: The shapes of $A(x)$ and $H[A]$ with varying (t, d)

4.1 Two peaks

We first focus on the case when f only has two peaks. Fix the proportion of $f = f_+$ to be $\Delta = \frac{1-f_-}{f_+-f_-}$. Express f as:

$$f = f_+ 1_{[0,t]} + f_- 1_{[t,t+d]} + f_+ 1_{[t+d,t+d+\Delta]} + f_- 1_{[1-\Delta-d,1]} \quad (18)$$

where $0 \leq t \leq \Delta, 0 \leq d \leq 1 - \Delta$.

The magnitude of mutual information w.r.t. (t, d) generally follows a diamond shape. In figure 2, we plot different shapes of $A(x)$ with varying (t, d) .

One **principle observation** is that large $H[A]$ favors those curves f , such that for all $x \in (0, 1)$, the number of overlapping peaks of $f(\cdot)$ and $f(x + \cdot)$ is at most one. (When $x = 0$, f and $f(x + \cdot)$ totally overlaps and there are two peaks).

In this case, $A(x) = \int f(x + \theta) f(\theta) d\theta$ puts more mass on smaller values of A , i.e. the values of A is more distributed around f_- . This phenomena might be roughly explained by the following change of variable:

$$-\int_0^1 A(x) \log(A(x)) dx = -\int_B^H \log(A) \ell(A) dA$$

where ℓ is the lebesgue measure: $\ell(A) = \lambda(\{x : A(x) < A\})$. Because $\log x$ is a concave function and $\int_B^H \ell(A) dA = \int_0^1 A(x) dx = 1$, putting more mass $\ell(A)$ on smaller values of A decreases $\int \log(A) \ell(A) dA$, thus increases the entropy.

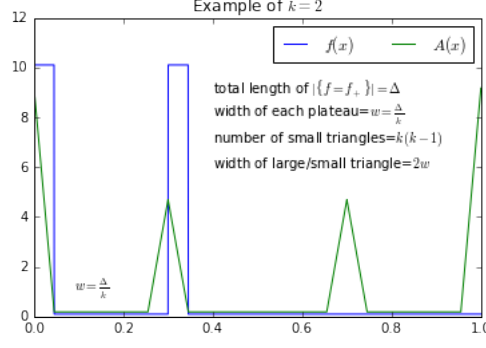


Figure 3: Illustration of a function with k peaks

4.2 Multiple peaks

We still consider $f_+ \gg f_-$, $|\{f = f_+\}| = \Delta = \frac{1-f_-}{f_+-f_-}$. Also, assume $\{f = f_+\}$ is splitted into k peaks with equal width $w = \frac{\Delta}{k}$.

Based on our observation from the 2-peaks case, we first focus on those function f such that for all $x \in (0, 1)$, the number of overlapping peaks of $f(x + \cdot)$ and $f(\cdot)$ is at most one.

Since $A(x)$ is a piecewise linear function, the width and heights of each linear part can be calculated:

$$\begin{aligned} w &:= \frac{\Delta}{k} \\ H &:= A(0) = f_+^2 \Delta + f_-^2 (1 - \Delta) \\ B &:= 2f_+ f_- \Delta + f_-^2 (1 - 2\Delta) \\ h(k) &:= f_+^2 \frac{\Delta}{k} + 2(k-1)f_+ f_- \frac{\Delta}{k} + f_-^2 \left(1 - (2k-1) \frac{\Delta}{k}\right) \end{aligned}$$

In this case, $H[A]$ can be expressed as

$$\begin{aligned} H[A] &= - \int_0^1 A(x) \log(A(x)) dx \\ &= 2Int(H, B, w) + 2 \binom{k}{2} \cdot 2Int(h(k), B, w) + \left(-B \log B \left(1 - 2w - 2 \cdot 2 \binom{k}{2} w\right) \right) \\ &= 2Int(H, B, w) + 2k(k-1) Int(h(k), B, w) + (-B \log B (1 - 2w - 2k(k-1)w)) \end{aligned} \quad (19)$$

An illustration of this setting is shown in Figure 3. Here $Int(h, b, w)$ stands for the integral of $-A(x) \log A(x)$ on each interval where $A(x)$ is linear, with upper height h , lower height b and width w :

$$Int(h, b, w) := - \int_0^w \left(h - \frac{h-b}{w}x\right) \log\left(h - \frac{h-b}{w}x\right) dx = \frac{w}{4(h-b)} [h^2 - b^2 - 2(h^2 \log h - b^2 \log b)] \quad (20)$$

We first evaluate equation (19) numerically for different k 's. We observe that:

1. $H(A)$ increases as k is increasing, suggesting that large $H[A]$ favors the splitting of $f(x)$ into more peaks.
2. k cannot increase to infinity since $k(k-1)2\frac{\Delta}{k} + 2\frac{\Delta}{k} \leq 1$.

We finally tried to do **randomly** split f into widths $\{\alpha_i\}_{i=1,\dots,k}$, $\{\beta_i\}_{i=1,\dots,k}$, with $\sum_{i=1}^k \alpha_i = \Delta$, $\sum_{i=1}^k \beta_i = 1 - \Delta$, such that $f = f_+$ on intervals $\left[\sum_{j=1}^{i-1} (\alpha_j + \beta_j), \sum_{j=1}^{i-1} (\alpha_j + \beta_j) + \alpha_i\right)$, and $f = f_-$ on intervals $\left[\sum_{j=1}^{i-1} (\alpha_j + \beta_j) + \alpha_i, \sum_{j=1}^i (\alpha_j + \beta_j)\right)$. For each k , we took the maximum of $H[A]$ from 1000 samples of α_i and β_i 's, drawn from Multinomial distributions.

Figure 4 shows the numerical results. As k increases, $H[A]$ increases and approaches a fixed value, and as shown in Figure 4b, 4c, the function f which produces highest $H[A]$ seems to vary more and more 'wildly' between f_- and f_+ . $A(x)$ approaches a near-constant function, taking $H = f_+^2 \Delta + f_-^2 (1 - \Delta)$ at 0, and fastly decreases to 1.

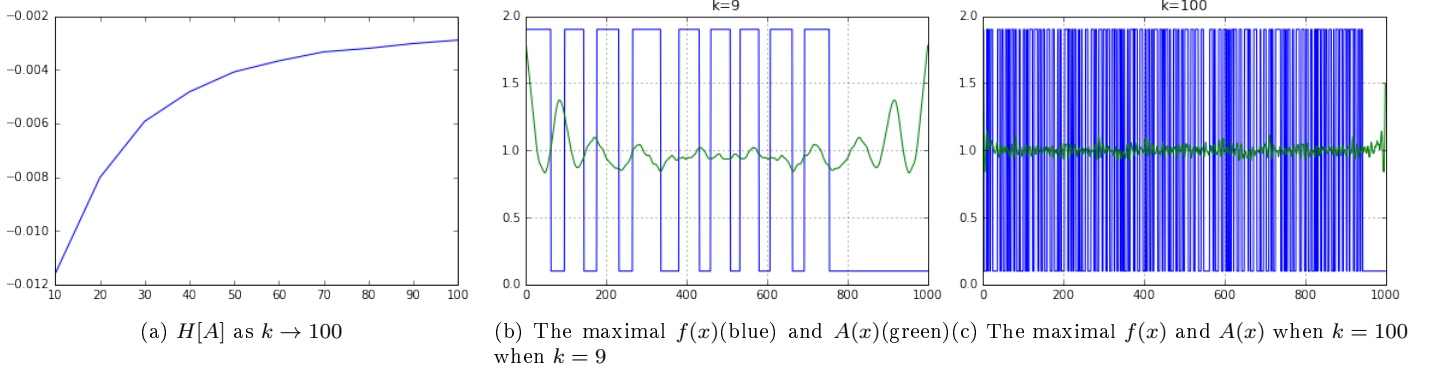


Figure 4: Random experiments of a function with k peaks

5 Maximum of the mutual information

5.1 Maximum of the negative entropy

Lemma 7. Assume $f(x)$ is piece-wise C^1 . Under the given constraints $f_- \leq f \leq f_+$ and $\int_0^1 f(x)dx = 1$, $-H[f]$ is maximized when f only takes f_- and f_+ a.e.

Proof. We combined the KKT conditions for both $\nabla_f H$ and $\nabla_\delta H$ in the Section of perturbation method. Let $G[f] = -H[f]$ be the objective function we want to maximize. It can be derived from $G[f+h] - G[f]$ that

$$\nabla_f (G[f])(x) = \ln f(x) + 1.$$

For a local maximizer f of G , there exists functions $\alpha_+(x) \geq 0$, $\alpha_-(x) \geq 0$ and a constant μ , such that for all x where $f(x)$ (thus also $\nabla_f G(x)$) is continuous, the following KKT conditions hold:

$$\nabla_f I(x) = \alpha_+(x) - \alpha_-(x) + \mu$$

and $\alpha_+(x)(f(x) - f_+) = 0$, $\alpha_-(x)(f_- - f(x)) = 0$. From $\nabla_f G(x) = \ln f(x) + 1$, $f(x)$ is constant when $f(x) \neq f_+$ or f_- , since $\alpha_+ = \alpha_- = 0$ implies $\ln f(x) + 1 = \mu$. Hence $f(x)$ is a piece-wise constant function which takes at most 3 values:

$$f(x) = \begin{cases} f_+ \\ f_- \\ e^{\mu-1} \end{cases} \quad \text{if } f \neq f_+ \text{ or } f_-$$

Next we show that the third option is impossible using perturbation method. It is shown in the Appendix A.2 that

$$\nabla_\delta (G[f])(x) = 1_{\{x \notin D\}} (f \log f)'_c(x) + \sum_{x_i \in D} \Delta_i (f \log f) \delta_{x_i}(x)$$

where D is the set of discontinuities of f , $(f \log f)'_c(x)$ is the point-wise derivative of f . From maximizing the function G with respect to δ , there exists $\nu \in \mathbb{R}$ such that the KKT condition holds:

$$\nabla_\delta (G[f])(x) = \nu \left(f'_c(x) + \sum_{x_i \in D} \Delta_i f \delta_{x_i}(x) \right)$$

where the right-hand-side comes from the constraint $\int f(x) \delta'(x) dx = - \int \delta(x) dx (f'_c(x) + \sum_{x_i \in D} \Delta_i f \delta_{x_i}(x)) = 0$. Now since f is piecewise constant, for all $x \notin D$, $f'_c(x) = 0$ and $(f \log f)'_c(x) = 0$. Thus

$$\begin{aligned} \sum_{x_i \in D} \Delta_i (f \log f) \delta_{x_i}(x) &= \nu \sum_{x_i \in D} \Delta_i f \delta_{x_i}(x) \\ \frac{\Delta_i (f \log f)}{\Delta_i f} &= \nu, \forall x_i \in D \end{aligned}$$

Suppose that there exists \tilde{f} such that $f_+ < \tilde{f} < f_-$ and that $\{f = \tilde{f}\}$ has positive measure. Then at discontinuities, f either jumps between f_+ and f_- , or between f_+ (or f_-) and \tilde{f} . There are 3 options for $\frac{\Delta_i(f \log f)}{\Delta_i f}$, which are equal to a constant ν :

$$\frac{f_+ \log(f_+) - f_- \log(f_-)}{f_+ - f_-} = \frac{f_+ \log(f_+) - \tilde{f} \log(\tilde{f})}{f_+ - \tilde{f}} = \frac{\tilde{f} \log(\tilde{f}) - f_- \log(f_-)}{\tilde{f} - f_-} = \nu.$$

However, this contradicts the convexity of the function $y = t \log t$. Therefore it is impossible to have $f_+ < \tilde{f} < f_-$ with positive measure, and $f = f_+$ or f_- a.e. \square

5.2 Upper bound of the entropy of auto-correlation

Lemma 8. *Given $\int_0^1 f(x)dx = 1$, there is an upper bound for $I[f]$ such that*

$$I[f] \leq -2H[f]$$

Proof. It suffices to show $H(A) \leq 0$. Since $A(x)$ satisfies $\int_0^1 A(x)dx$ and $A \geq 0$, the entropy of a density function is maximized by uniform distribution on $[0,1]$:

First, the K-L divergence $D_{KL}(f||g) \geq 0$ for any two distributions f, g . Let U be the uniform distribution on $[0,1]$, then

$$\begin{aligned} D_{KL}(A||U) &= \int_0^1 A(x) \log \frac{A(x)}{U(x)} dx \\ &= \int_0^1 A(x) \log \frac{A(x)}{1} dx \\ &= -H[A] \\ &\geq 0 \end{aligned}$$

Therefore $H[A] \leq 0$, $I[f] = -2H[f] + H[A] \leq -2H[f]$. \square

As shown in the proof the above lemma, this maximum reachable only when A is the uniform distribution on $[0,1]$. Ideally, this happens when $f(x)$ are i.i.d. random variables with $P(f = f_+) = \Delta$, $P(f = f_-) = 1 - \Delta$, where $\Delta = \frac{1-f_-}{f_+-f_-}$:

$$\begin{aligned} A(x) &= \int f(\theta) f(x + \theta) d\theta \\ &= E[f(\theta) f(x + \theta)] \\ &= E[f(\theta)] E[f(x + \theta)] \\ &= (\Delta f_+ + (1 - \Delta) f_-)^2 \\ &= 1 \end{aligned}$$

Questions remained:

- Integral well-defined?

Note that this auto-correlation function $A(x)$ may not be continuous, which is different from the property stated in Section 1, since here f does not satisfy the condition that it has only a finite number of discontinuities.

5.3 Main Theorem

The conclusion above can be generalized to our Poissonian model:

Theorem 9. $I[f] = -E_N \left[\int_0^1 \prod_{i=1}^n \frac{f(s_i - \theta)}{f(s_i)} d\theta \right] \leq -\bar{f} H[h]$, where h is a piece-wise constant function only taking two values $\left\{ \frac{f_-}{\bar{f}}, \frac{f_+}{\bar{f}} \right\}$ on $[0,1]$ with $\int_0^1 h(x)dx = 1$. For such an h , $H[h]$ has fixed value: $H[h] = -\left(\frac{f_+}{\bar{f}} \ln \left(\frac{f_+}{\bar{f}} \right) \Delta + \frac{f_-}{\bar{f}} \ln \left(\frac{f_-}{\bar{f}} \right) (1 - \Delta) \right)$, where $\Delta = \frac{\bar{f} - f_-}{f_+ - f_-}$.

Proof. Let $\tilde{f} = \frac{f}{\bar{f}}$, then $\frac{f_-}{\bar{f}} \leq \tilde{f} \leq \frac{f_+}{\bar{f}}$,

$$\begin{aligned}
I[f] &= -E_N \left[\int_0^1 \prod_{i=1}^n \frac{f(s_i - \theta)}{f(s_i)} d\theta \right] \\
&= \sum_{n=0}^{\infty} \frac{1}{n!} \int_0^1 \cdots \int_0^1 \prod_{i=1}^n ds_i f(s_i) e^{-\int_0^1 f(s) ds} \ln \left(\frac{\prod_{i=1}^n f(s_i)}{\int_0^1 \prod_{i=1}^n f(s_i - \theta) d\theta} \right) \\
&= \sum_n \frac{1}{n!} e^{-\bar{f}} (\bar{f})^n \int_0^1 \cdots \int_0^1 \prod_{i=1}^n ds_i \tilde{f}(s_i) \ln \left(\frac{\prod_{i=1}^n \tilde{f}(s_i)}{\int_0^1 \prod_{i=1}^n \tilde{f}(s_i - \theta) d\theta} \right) \\
&= \sum_n \frac{1}{n!} e^{-\bar{f}} (\bar{f})^n \left[\int_0^1 \cdots \int_0^1 \prod_{i=1}^n ds_i \tilde{f}(s_i) \ln \left(\prod_{i=1}^n \tilde{f}(s_i) \right) - \int_0^1 \cdots \int_0^1 \prod_{i=1}^n ds_i \tilde{f}(s_i) \ln (A(s_1, \dots, s_n)) \right] \\
&\leq \sum_n \frac{1}{n!} e^{-\bar{f}} (\bar{f})^n \int_0^1 \cdots \int_0^1 \prod_{i=1}^n ds_i \tilde{f}(s_i) \ln \left(\prod_{i=1}^n \tilde{f}(s_i) \right) \\
&= \sum_n \frac{1}{n!} e^{-\bar{f}} (\bar{f})^n (-nH[\tilde{f}]) \\
&= (-H[\tilde{f}]) \sum_{n=1}^{\infty} \frac{1}{(n-1)!} e^{-\bar{f}} (\bar{f})^n \\
&= -\bar{f} H[\tilde{f}] \\
&\leq -\bar{f} H[h]
\end{aligned} \tag{21}$$

Where the last step is followed from Lemma 7. □

Note that the maximum is attained when $A(s_1, \dots, s_n)$ is constant (equal to one) for all n .

A Appendix: Computation of the gradients

A.1 Computation of $\nabla_f I$

First we show the following two conclusions:

$$\nabla_f|_t (H[f]) = -(\ln f(t) + 1) \tag{22}$$

$$\nabla_f|_t (A[f](u)) = f(t+u) + f(t-u) \tag{23}$$

where the 2nd one can be derived from

$$\begin{aligned}
&\int_0^1 d\theta (f(u+\theta) + h(u+\theta)) (f(\theta) + h(\theta)) \\
&= A(u) + \int d\theta f(u+\theta) h(\theta) + \int d\theta f(\theta) h(u+\theta) + O(h^2) \\
&= A(u) + \int d\theta f(u+\theta) h(\theta) + \int d\theta' f(\theta' - u) h(\theta') + O(h^2).
\end{aligned}$$

Now since $I = -2H(f) + H(A)$, using (22)(23), we obtain

$$\begin{aligned}
\nabla_f I(t) &= -2\nabla_f|_t (H[f]) + \int_0^1 du (-\ln A(u) + 1) \nabla_f|_t A(u) \\
&= 2(\ln f(t) + 1) - \int_0^1 du (\ln A(u) + 1) (f(t+u) + f(t-u)) \\
&= 2(\ln f(t) + 1) - \int_0^1 f(t+u) \ln A(u) du - \int_0^1 f(t-u) \ln A(u) du - 2 \\
&= 2 \left(\ln f(t) - \int_0^1 f(y) \ln A(y-t) dy \right)
\end{aligned}$$

*Note that previously we derived $\nabla_f I(t) = 2 \left(\ln f(t) - H[f] - \int_0^1 f(y) \ln A(y-t) dy \right)$ from the expression of I : $\int_0^1 dx \int_0^1 dy f(x) f(y)$ before simplification. Since the simplification involves plugging in the constraint $\int f(x) dx = 1$, which also produces some derivative, the expression of $\nabla_f I$ is differed by a constant. Either including the constant $H[f]$ or not does not affect our conclusions since it can be absorbed into μ in the KKT condition.

A.2 Computation of $\nabla_\delta I$

To compute $\nabla_\delta I[f]$, first we compute $\nabla_\delta (\int f \log f)$: applying change of variable $\eta = x + \epsilon \delta(x)$, $d\eta = (1 + \epsilon \delta'(x)) dx$,

$$\begin{aligned}
dx &= \frac{1}{1 + \epsilon \delta'(x)} d\eta = (1 - \epsilon \delta'(x) + O(\epsilon^2)) d\eta = (1 - \epsilon \delta'(\eta) + O(\epsilon^2)) d\eta \\
-H[f(x + \epsilon \delta(x))] &= \int dx f(x + \epsilon \delta(x)) \log(f(x + \epsilon \delta(x))) \\
&= \int d\eta (1 - \epsilon \delta'(\eta) + O(\epsilon^2)) f(\eta) \log(f(\eta)) \\
&= -H[f] + \epsilon \left[\int \delta(\eta) (f \log f)'_c(\eta) d\eta + \sum_{i \in D} \Delta_i (f \log f) \delta(x_i) \right] + O(\epsilon^2)
\end{aligned}$$

Similarly, define $F(x, y) = f(x) f(y) \ln \left(\int_0^1 d\theta f(x - \theta) f(y - \theta) \right)$, then

$$\begin{aligned}
&\int dx \int dy F(x + \epsilon \delta(x), y + \epsilon \delta(y)) \\
&= \int d\eta \int d\gamma F(\eta, \gamma) - 2\epsilon \int \left(\int d\gamma F(\eta, \gamma) \right) \delta'(\eta) d\eta + O(\epsilon^2) \\
&= \int d\eta \int d\gamma F(\eta, \gamma) + 2\epsilon \left[\int \left(\int d\gamma \frac{\partial F_c(\eta, \gamma)}{\partial \eta} \right) \delta(\eta) d\eta + \sum_{i \in D} \Delta_i \left(\int d\gamma F(\eta, \gamma) \right) \delta_{x_i}(\eta) \right] + O(\epsilon^2) \\
&= \int d\eta \int d\gamma F(\eta, \gamma) + O(\epsilon^2) + 2\epsilon \int \delta(\eta) d\eta \int d\gamma f'_c(\eta) f(\gamma) \ln(A(\gamma - \eta)) \\
&\quad + 2\epsilon \left[\int \delta(\eta) d\eta \int d\gamma f(\gamma) f(\eta) \frac{\int_0^1 d\theta f'(\eta - \theta) f(\gamma - \theta)}{A(\gamma - \eta)} + \sum_{i \in D} \Delta_i \left(f(\eta) \int d\gamma f(\gamma) \ln(A(\gamma - \eta)) \right) \delta_{x_i}(\eta) \right]
\end{aligned}$$

Thus

$$\begin{aligned}
\nabla_\delta (-H[f]) &= (f \log f)'_c(x) + \sum_{i \in D} \Delta_i (f \log f) \delta_{x_i}(x) \\
\nabla_\delta \left(\int dx \int dy F(x, y) \right) &= 2 \left[f'_c(x) \int dy f(y) \log(A(y - x)) + f(x) \int dy f(y) \frac{\int_0^1 d\theta f'(x - \theta) f(y - \theta)}{\int_0^1 d\theta f(x - \theta) f(y - \theta)} \right] \\
&\quad + 2 \sum_{i \in D} \Delta_i f \cdot \left(\int dy f(y) \log A(y - x_i) \right) \cdot \delta_{x_i}(x)
\end{aligned} \tag{24}$$

Therefore from $I[f] = -2H(f) - \int dx \int dy F(x, y)$ we obtain

$$\begin{aligned} \nabla_\delta I[f] &= 2 \left[f'_c(x) (\log f(x) + 1) - f'_c(x) \int dy f(y) \log A(y-x) - f(x) \int dy f(y) \frac{\int_0^1 d\theta f'(x-\theta) f(y-\theta)}{\int_0^1 d\theta f(x-\theta) f(y-\theta)} \right] \\ &\quad + 2 \sum_{i \in D} \left[\Delta_i (f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right] \delta_{x_i}(x) \end{aligned}$$

A.3 Other conclusions

*The following conclusions are derived from 'integration by parts' below, which we were not sure about their correctness (and they contradict the numerical simulations):

$$\begin{aligned} \int_0^1 f'(x-\theta) f(y-\theta) d\theta &= \int_0^1 \left(f'_c(x-\theta) + \sum_{i \in D} \Delta_i f \delta_{x_i}(x-\theta) \right) f(y-\theta) d\theta \\ &= - \int_0^1 f_c(x-\theta) f'(y-\theta) d\theta + \sum_{i \in D} \Delta_i f \cdot f(y-x+x_i) \\ &= - \int_0^1 f(x-\theta) f(y-\theta) d\theta + \sum_{i \in D} \Delta_i f \cdot f(y-x+x_i) \end{aligned}$$

$$\begin{aligned} \int dy f(y) \frac{\int_0^1 d\theta f'(x-\theta) f(y-\theta)}{\int_0^1 d\theta f(x-\theta) f(y-\theta)} &= - \int dy f(y) \frac{\int_0^1 d\theta f(x-\theta) f'(y-\theta)}{A(y-x)} + \sum_{i \in D} \Delta_i f \cdot \int \frac{f(y) f(y-x+x_i)}{A(y-x)} dy \\ &= - \int dy f(y) \frac{\partial \log A(y-x)}{\partial y} + \sum_{i \in D} \Delta_i f \cdot \int \frac{f(y) f(y-x+x_i)}{A(y-x)} dy \\ &= \int dy f'(y) \log A(y-x) + \sum_{i \in D} \Delta_i f \cdot \int \frac{f(y) f(y-x+x_i)}{A(y-x)} dy \end{aligned}$$

$$\begin{aligned} \nabla_\delta I[f] &= 2 \left[f'_c(x) (\log f_c(x) + 1) - \int dy (f'_c(x) f(y) + f(x) f'(y)) \log A(y-x) - f(x) \sum_{i \in D} \Delta_i f \int \frac{f(y) f(y-x+x_i)}{A(y-x)} dy \right] \\ &\quad + 2 \sum_{i \in D} \left(\Delta_i (f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right) \cdot \delta_{x_i}(x) \end{aligned} \tag{25}$$

*Especially, if f is piece-wise constant, since its point-wise derivative $f'_c(x) = 0$,

$$\begin{aligned} \nabla_\delta I[f] &= -2f(x) \int dy f'(y) \log A(y-x) - 2f(x) \sum_{i \in D} \Delta_i f \cdot \int \frac{f(y) f(y-x+x_i)}{A(y-x)} dy \\ &\quad + 2 \sum_{i \in D} \left(\Delta_i (f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right) \cdot \delta_{x_i}(x) \\ &= -2f(x) \sum_{i \in D} \Delta_i f \left(\log A(x_i-x) + \int \frac{f(y) f(y-x+x_i)}{A(y-x)} dy \right) \\ &\quad + 2 \sum_{i \in D} \left(\Delta_i (f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right) \cdot \delta_{x_i}(x) \end{aligned}$$

By plugging in equation (10) into $\nabla_\delta I$ in (25) and (9), we get

$$\begin{aligned}
\nabla_\delta I[f] &= 2 \left[f'_c(x)(\log f_c(x) + 1) - f'_c(x) \int dy f(y) \log A(y-x) - f(x) \int dy f(y) \frac{\int_0^1 d\theta f'(x-\theta)f(y-\theta)}{\int_0^1 d\theta f(x-\theta)f(y-\theta)} \right] \\
&\quad + 2 \sum_{i \in D} \left(\Delta_i(f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right) \cdot \delta_{x_i}(x) \\
&= 2f'(x)(\log f(x) + 1) - 2f'(x) \int dy f(y) \log A(y-x) - 2f(x) \left(\frac{f'(x)}{f(x)} - \frac{\alpha'_+(x)}{2} + \frac{\alpha'_-(x)}{2} \right) \\
&\quad + 2 \left(\Delta_i(f \log f) - \Delta_i f \cdot \int dy f(y) \log A(y-x_i) \right) \cdot \delta_{x_i}(x) \\
&= \nu \left[f'(x) + \sum_{i \in D} \Delta_i f \cdot \delta_{x_i}(x) \right]
\end{aligned}$$

$$f'(x) \log f(x) = f'(x) \left(\int dy f(y) \log A(y-x) + \frac{\nu}{2} \right) - f(x) (\alpha'_+(x) - \alpha'_-(x)) \text{ for } x \notin D \quad (26)$$

$$\frac{\Delta_i(f \log f)}{\Delta_i f} = \int dy f(y) \log A(y-x_i) + \frac{\nu}{2} \text{ for } x_i \in D \quad (27)$$

Proposition 10. $\alpha_+(x), \alpha_-(x), \nabla_f I(x)$ are piecewise constant functions.

Proof. From equation (8) we only need to show $\alpha_+(x)$ is piecewise const.

If $f(x) < f_+$, $\alpha_+(x) = 0$.

If $f(x) = f_+$, $\alpha_+(x) \geq 0$, $\alpha_-(x) = 0$. There exists an interval \mathcal{I} around x such that $f = f_+$ on \mathcal{I} . Thus on interval \mathcal{I} , $f'(x) = 0$, by equation (26),

$$\begin{aligned}
f(x) (\alpha'_+(x) - \alpha'_-(x)) &= 0 \\
\alpha'_+(x) &= 0
\end{aligned}$$

Thus $\alpha_+(x)$ is constant on interval \mathcal{I} around x , which gives us the conclusion that α_+ is piecewise const. \square

Therefore, f **cannot vary continuously between f_+ and f_-** , otherwise ∇f is continuous but α_+ or α_- is discontinuous.

We can also further simplify equation (10) as

$$\frac{f'(x)}{f(x)} = \int_0^1 dy f(y) \frac{\int_0^1 f'(x-\theta)f(y-\theta)d\theta}{\int_0^1 f(x-\theta)f(y-\theta)d\theta} \text{ for } x \notin D \quad (28)$$

Proposition 11. If $f(x)$ has a jump discontinuity at x_0 , then there exists an open interval (β_1, β_2) such that $\beta_1 < x_0 < \beta_2$ and $f(x)$ is constant on both (β_1, x_0) and (x_0, β_2) .

Proof. Suppose there's no such interval on the left of x_0 . Then there exists a sequence $x_k \rightarrow x_0^-$ such that $f'(x_k) \neq 0$. Applying equations (26), (27),

$$\begin{aligned}
\log f(x_0^-) &= \int dy f(y) \log A(y-x_0) + \frac{\nu}{2} \\
\frac{\Delta_{x_0}(f \log f)}{\Delta_{x_0} f} &= \int dy f(y) \log A(y-x_0) + \frac{\nu}{2}
\end{aligned}$$

Therefore

$$\log f(x_0^-) = \frac{\Delta_{x_0}(f \log f)}{\Delta_{x_0} f} = \frac{f(x_0^+) \log f(x_0^+) - f(x_0^-) \log f(x_0^-)}{f(x_0^+) - f(x_0^-)}$$

which implies $f(x_0^+) = f(x_0^-)$. This contradicts with the discontinuity at x_0 . Similarly, there's an interval to the right of x_0 such that f is constant. \square