TREE-LIKE GRAPHINGS OF COUNTABLE BOREL EQUIVALENCE RELATIONS

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ABSTRACT. We present a streamlined exposition of a construction presented recently by R. Chen, A. Poulin, R. Tao, and A. Tserunyan, where it is proven that every locally-finite Borel graph with each component a quasi-tree induces a canonical treeable equivalence relation. Write some more details...

0. Introduction

The purpose of this note is to provide a streamlined proof of a particular case of a construction presented in [CPTT23], in order to better understand the general formalism developed therein. We attempt to make this note self-contained, but nevertheless urge the reader to refer to the original paper for more detailed discussions and some generalizations of the results we have selected to include here.

0.1. Treeings of equivalence relations. A countable Borel equivalence relation (CBER) on a standard Borel space X is a Borel equivalence relation $E \subseteq X^2$ with each class countable. We are interested in special types of graphings on a CBER $E \subseteq X^2$, i.e. a Borel graph $G \subseteq X^2$ whose connectedness relation is precisely E. For instance, a graphing of E such that each component is a tree is called a treeing of E, and the CBERs that admit treeings are said to be treeable. The main results of [CPTT23] provide new sufficient criteria for treeability of certain classes of CBERs, and in particular, they prove the following

Theorem A ([CPTT23, Theorem 1.1]). If a CBER admits a locally-finite graphing whose components are quasi-trees, then it is treeable.

Recall that metric spaces X and Y are *quasi-isometric* if they are isometric up to a bounded multiplicative and additive error, and X is a *quasi-tree* if it is quasi-isometric to a simplicial tree; see [Gro93] and [DK18].

- 0.2. Outline of the proof. Roughly speaking, the existence of a quasi-isometry $G|C \to T_C$ to a simplicial tree T_C for each component $C \subseteq X$ induces a collection $\mathcal{H}(C)$ of 'cuts' (subsets $H \subseteq C$ with finite boundary such that both H and $C \setminus H$ are connected), which are 'tree-like' in the sense that
 - 1. $\mathcal{H}(C)$ is finitely-separating: each pair $x,y\in C$ is separated by finitely-many $H\in\mathcal{H}(C)$, and
 - 2. $\mathcal{H}(C)$ is dense towards ends: each end in G|C has a neighborhood basis in $\mathcal{H}(C)$.

By Condition (1), these cuts have the structure of a profinite pocset with non-trivial points isolated, which in turn provide exactly the data to construct a 'median graph' whose vertices are 'ultrafilters' thereof. Condition (2) then ensures that this graph has finite 'hyperplanes', which allows us to apply a Borel 'cyclecutting' algorithm and obtain a canonical spanning tree. Each step above can be done in a uniform way to each component $C \subseteq G$, giving us the desired treeing of the CBER.

Quasi-tree
$$\xrightarrow{1}$$
 Dense family of cuts $\xrightarrow{2.1+2.2}$ of cuts $\xrightarrow{\text{Pocset w/}}$ non-triv. pts. $\xrightarrow{3.1+3.2}$ $\xrightarrow{\text{Median graph}}$ w/ finite hyperplanes $\xrightarrow{4}$ Canonical spanning tree

Write some more stuff to tie things together...

Remark. We follow [CPTT23, Convention 2.7], where for a family $\mathcal{H} \subseteq 2^X$ of subsets of a fixed set X, we write $\mathcal{H}^* := \mathcal{H} \setminus \{\emptyset, X\}$ for the *non-trivial* elements of \mathcal{H} .

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¹As in [CPTT23], we call them *orientations* instead, to avoid confusion with the more standard notion; see Definition 3.1.

1. Graphs with Dense Families of Cuts

1.1. **Ends of graphs.** Let (X, G) be a connected locally-finite graph, which, in the context of Theorem A, will stand for a single component of the locally-finite graphing of a CBER.

Definition 1.1. For a subset $A \subseteq X$, we let $\partial_{\mathsf{iv}}A := A \cap \operatorname{Ball}_1(\neg A)$ be its inner vertex boundary, $\partial_{\mathsf{ov}}A := \partial_{\mathsf{iv}}(\neg A)$ be its outer vertex boundary, and let $\partial_{\mathsf{ie}}A := G \cap (\partial_{\mathsf{ov}}A \times \partial_{\mathsf{iv}}A)$ and $\partial_{\mathsf{oe}}A := \partial_{\mathsf{ie}}(\neg A)$ respectively be its inner and outer edge boundaries. Let $\partial_{\mathsf{v}}A := \partial_{\mathsf{iv}}A \cup \partial_{\mathsf{ov}}A$ be the (total) vertex boundary of A.

Let $\mathcal{H}_{\partial<\infty}(X)\subseteq 2^X$ be the Boolean algebra of all $A\subseteq X$ with finite vertex boundary, called *cuts* in X.

Definition 1.2. The end compactification of (X,G) is the Stone space \widehat{X} of $\mathcal{H}_{\partial<\infty}(X)$, whose non-principal ultrafilters are the ends of (X,G).

We identify $X \hookrightarrow \widehat{X}$ via principal ultrafilter map $x \mapsto p_x$, so $\widehat{X} \setminus X$ is the set of ends of G. By definition, \widehat{X} admits a basis of clopen sets of the form $\widehat{A} := \{p \in \widehat{X} : A \in p\}$ for each $A \in \mathcal{H}_{\partial < \infty}(X)$.

Definition 1.3. A family $\mathcal{H} \subseteq \mathcal{H}_{\partial < \infty}(X)$ of cuts is *dense towards ends* of (X,G) if \mathcal{H} contains a neighborhood basis for every end in $\widehat{X} \setminus X$.

In other words, \mathcal{H} is dense towards ends if for every $p \in \widehat{X} \setminus X$ and every (clopen) neighborhood $\widehat{A} \ni p$, where $A \in \mathcal{H}_{\partial < \infty}(X)$, there is some $H \in \mathcal{H}$ with $p \in \widehat{H} \subseteq \widehat{A}$; it is useful to note that $\widehat{H} \subseteq \widehat{A}$ iff $H \subseteq A$.

1.2. **Dense cuts induced by quasi-trees.** If X is a quasi-tree – and thus does not have arbitrary long cycles – we expect that there is some finite bound $R < \infty$ such that the ends in $\widehat{X} \setminus X$ are 'limits' of cuts $\mathcal{H}_{\operatorname{diam}(\partial) \leq R}(X) \subseteq \mathcal{H}_{\partial < \infty}(X)$ with boundary diameter bounded by R. We show that this is indeed the case, in the sense that $\mathcal{H}_{\operatorname{diam}(\partial) \leq R}(X)$ is dense towards ends of (X, G).

Lemma 1.4. Let $f:(X,G) \to (Y,T)$ be a coarse-equivalence between connected graphs. For a fixed $H \in \mathcal{H}_{\partial < \infty}(Y)$, diam $(\partial_{\nu}f^{-1}(H))$ is uniformly bounded in terms of diam $(\partial_{\nu}H)$.

Proof. Since f is bornologous, let $S < \infty$ be such that xGx' implies $d(f(x), f(x')) \leq S$, so that for any $(x, x') \in \partial_{\mathsf{ie}} f^{-1}(H)$, there is a path of length $\leq S$ between $f(x) \notin H$ and $f(x') \in H$. Thus both $d(f(x), \partial_{\mathsf{v}} H)$ and $d(f(x'), \partial_{\mathsf{v}} H)$ are bounded by S, so $f(\partial_{\mathsf{v}} f^{-1}(H)) \subseteq \operatorname{Ball}_S(\partial_{\mathsf{v}} H)$ and hence

$$\operatorname{diam}(f(\partial_{\mathsf{v}}f^{-1}(H))) \le \operatorname{diam}(\partial_{\mathsf{v}}H) + 2S.$$

That f is a coarse-equivalence gives us a uniform bound of diam $(\partial_{\mathsf{v}} f^{-1}(H))$ in terms of diam $(\partial_{\mathsf{v}} H)$.

In particular, if diam($\partial_{\nu}H$) is itself also uniformly bounded, then so is diam($\partial_{\nu}f^{-1}(H)$).

Proposition 1.5. The class of connected locally-finite graphs in which $\mathcal{H}_{\operatorname{diam}(\partial) \leq R}$ is dense towards ends for some $R < \infty$ is invariant under coarse equivalence.

Proof. Let (X,G), (Y,T) be connected locally-finite graphs, $f:X\to Y$ be a coarse equivalence with quasi-inverse $g:Y\to X$, and suppose $\mathcal{H}_{\operatorname{diam}(\partial)\leq S}(Y)$ is dense towards ends for some $S<\infty$. By Lemma 1.4, pick some $R<\infty$ so that for any $H\in\mathcal{H}_{\operatorname{diam}(\partial)\leq S}(Y)$, we have $f^{-1}(H)\in\mathcal{H}_{\operatorname{diam}(\partial)\leq R}(X)$.

Fix an end $U \in \widehat{X} \setminus X$ with $U \in \widehat{A}$ for some $A \in \mathcal{H}_{\partial < \infty}(X)$. We need to find some $B \in \mathcal{H}_{\partial < \infty}(Y)$ such that $\widehat{f}(U) \in \widehat{B}$ and $f^{-1}(B) \subseteq A$, for then $\widehat{f}(U) \in \widehat{H}$ for some $B \supseteq H \in \mathcal{H}_{\operatorname{diam}(\partial) < S}(Y)$, and hence we have

$$U \in \widehat{f^{-1}(H)} \subseteq \widehat{f^{-1}(B)} \subseteq \widehat{A}$$

with $f^{-1}(H) \in \mathcal{H}_{\operatorname{diam}(\partial) \leq R}(X)$. For convenience, let $D < \infty$ be the uniform distance $d(1_X, g \circ f)$.

To this end, note that $\widehat{f}(U) \in \widehat{B}$ iff $U \in \widehat{f^{-1}(B)}$. Since $U \in \widehat{A}$, the latter can occur if $|A \triangle f^{-1}(B)| < \infty$, and so we need to find such a $B \in \mathcal{H}_{\partial < \infty}(Y)$ with the additional property that $f^{-1}(B) \subseteq A$.

Attempt 1. Set
$$B := g^{-1}(A) \in \mathcal{H}_{\partial < \infty}(Y)$$
. Then $f^{-1}(B) \subseteq \operatorname{Ball}_D(A)$ since if $(g \circ f)(x) \in A$, then $d(x,A) \leq d(x,(g \circ f)(x)) \leq d(1_X,g \circ f) = D$.

By local-finiteness of G, we see that $A \triangle f^{-1}(B) = A \setminus f^{-1}(B)$ is finite, as desired.

However, it is *not* the case that $f^{-1}(B) \subseteq A$. To remedy this, we 'shrink' A by D to A' so that $\operatorname{Ball}_D(A') \subseteq A$, and take $B := g^{-1}(A')$ instead. Indeed, $A' := \neg \operatorname{Ball}_D(\neg A) \subseteq A$ works, since $f^{-1}(B) \subseteq \operatorname{Ball}_D(A')$ as before, so $A' \triangle f^{-1}(B) = A' \setminus f^{-1}(B)$ is finite. Also, $A \triangle A'$ is finite since $x \in A \triangle A'$ iff $x \in A$ and $d(x, \neg A) \leq D$, so $A \triangle f^{-1}(B)$ is finite too. It remains to show that $\operatorname{Ball}_D(A') \subseteq A$, for then $f^{-1}(B) \subseteq A$ as desired.

Indeed, if $y \in \operatorname{Ball}_D(A')$, then by the (reverse) triangle-inequality we have $d(y, \neg A) \ge d(x, \neg A) - d(x, y)$ for all $x \in A'$. But $d(x, \neg A) > D$, strictly, so $d(y, \neg A) > D - D = 0$, and hence $y \in A$.

Corollary 1.6. If (X,G) is a locally-finite quasi-tree, then $\mathcal{H}_{\operatorname{diam}(\partial) \leq R}(X)$ is dense towards ends for some $R < \infty$.

Proof. Observe that $\mathcal{H}_{\operatorname{diam}(\partial) \leq 2}(T)$ is dense towards ends for any tree T, and invoke Proposition 1.5.

2. Pocsets of Dense Families of Cuts

2.1. Pocsets of cuts. The family $\mathcal{H}_{\text{diam }\partial \leq R}(X)$ of cuts have the structure of a 'profinite pocset', which we first study abstractly. We then deduce some properties of the pocset induced by a *dense* family of cuts.

Definition 2.1. A pocset $(\mathcal{H}, \leq, \neg, 0)$ is a poset (\mathcal{H}, \leq) equipped with an order-reversing involution $\neg : \mathcal{H} \to \mathcal{H}$ and a least element $0 \neq \neg 0$ such that 0 is the only lower-bound of $H, \neg H$ for every $H \in \mathcal{H}$. We call the elements in \mathcal{H} half-spaces.

A profinite pocset is a pocset \mathcal{H} equipped with a compact topology making \neg continuous and is totally order-disconnected, in the sense that if $H \not\leq K$, then there is a clopen upward-closed $U \subseteq \mathcal{H}$ with $H \in U \not\ni K$.

Remark 2.2. Such a topology is automatically Hausdorff and zero-dimensional.

We are primarily interested in subpossets of $(2^X, \subseteq, \neg, \varnothing)$, which is profinite if equipped with the product topology of the discrete space 2. Indeed, 2^X admits a base of *cylinder sets* – which are finite intersections of sets of the form $\pi_x^{-1}(i)$ where $x \in X$, $i \in \{0,1\}$, and $\pi_x : 2^X \to 2$ is the projection – making \neg continuous since cylinders are clopen. Show that it is totally order-disconnected.

The following proposition gives a sufficient criteria for subpossets of 2^X to be profinite. We also show in this case that every non-trivial element $H \in \mathcal{H}^*$ is isolated, which will important in Section 3.1.

Proposition 2.3. Let X be a set and $\mathcal{H} \subseteq 2^X$ be a subposset. If \mathcal{H} is finitely-separating, then $\mathcal{H} \subseteq 2^X$ is closed and every non-trivial element is isolated.

Proof. It suffices to show that the limit points of \mathcal{H} are trivial, so let $A \in 2^X \setminus \{\emptyset, X\}$. Fix $x \in A \not\supseteq y$. Since \mathcal{H} is finitely-separating, there are finitely-many $H \in \mathcal{H}$ with $x \in H \not\supseteq y$, and for each such $H \in \mathcal{H} \setminus \{A\}$, we have either some $x_H \in A \setminus H$ or $y_H \in H \setminus A$. Let $U \subseteq 2^X$ be the family of all subsets $B \subseteq X$ containing x and each x_H but not y or any y_H .

This is the desired neighborhood isolating $A \in U$. Indeed, it is (cl)open since it is the *finite* intersection of cylinders prescribed by the x_H 's and y_H 's, and it is disjoint from $\mathcal{H} \setminus \{A\}$ by construction.

Example 2.4. For a connected graph² (X,G), a subposset $\mathcal{H} \subseteq 2^X$ is finitely-separating if each $x \in X$ is on the boundary of finitely-many half-spaces. Indeed, any $H \in \mathcal{H}$ separating $x, y \in X$ separates some edge on any fixed path between x and y, and there are only finitely-many such H for each edge.

In particular, the subposest $\mathcal{H}_{\text{diam}(\partial) \leq R}(X)$ for any fixed $R < \infty$ (see Section 1.2) is finitely-separating.

2.2. Finiteness conditions on \mathcal{H} induced by dense cuts. Let (X, G) be a connected locally-finite graph and consider a family $\mathcal{H} \subseteq \mathcal{H}_{\partial < \infty}$ of cuts that are dense towards ends of G. TODO

3. The Dual Median Graph with Finite Hyperplanes

3.1. The dual median graph of a pocset. Let \mathcal{H} be a profinite subpocset with every non-trivial element isolated; for instance, if \mathcal{H} is finitely-separating, and in particular the cuts $\mathcal{H}_{\operatorname{diam}(\partial) \leq R}(X)$ for some locally-finite connected graph (X, G). We present a classical construction in geometric group theory (see [Dun79], [Rol98], [Sag95], and [NR03] for applications) of a 'tree-like' graph associated to such a pocset.

Definition 3.1. An orientation on \mathcal{H} is an upward-closed subset $U \subseteq \mathcal{H}$ containing exactly one of $H, \neg H$ for each $H \in \mathcal{H}$. We let $\mathcal{U}(\mathcal{H})$ denote the set of all orientations on \mathcal{H} and let $\mathcal{U}^{\circ}(\mathcal{H})$ denote the clopen ones.

²If (X,G) is locally-finite, then this condition is necessary, since then each $x \in X$ is separated from each of its finitely-many neighbors by finitely-many $H \in \mathcal{H}$.

Intuitively, an orientation is a 'maximally consistent' choice of half-spaces³.

Example 3.2. Each $x \in X$ induces its principal orientation $\widehat{x} := \{H \in \mathcal{H} : x \in H\} = \mathcal{H} \cap \pi_x^{-1}(1)$ — which is clearly clopen in \mathcal{H} — and gives us a canonical map $X \to \mathcal{U}^{\circ}(\mathcal{H})$. However, this map is not necessarily injective, and we call a fiber $[x]_{\mathcal{H}} := \{y \in X : \widehat{x} = \widehat{y}\}$ thereof an \mathcal{H} -block.

The goal of this section is to canonically construct a graph whose vertices are clopen orientations on \mathcal{H} .

Definition 3.3. A median graph is a connected graph (X,G) such that for any $x,y,z\in X$, the intersection

$$[x,y] \cap [y,z] \cap [x,z]$$

is a singleton, whose element $\langle x, y, z \rangle$ is called the *median* of x, y, z. Thus we have a ternary median operation $\langle \cdot, \cdot, \cdot \rangle : X^3 \to X$, and a *median homomorphism* $f : (X, G) \to (Y, H)$ is a map preserving said operation.

Some basic properties of median graphs are given in Section 4.2. For more comprehensive references and their general theory, see [Rol98] and [Bow22].

Proposition 3.4. Let \mathcal{H} be a profinite posset with every non-trivial element isolated. Then the graph $\mathcal{M}(\mathcal{H})$, whose vertices are clopen orientations $\mathcal{U}^{\circ}(\mathcal{H})$ and whose edges are pairs $\{U,V\}$ with $V=U \triangle \{H, \neg H\}$ for some \subseteq -minimal $H \in \mathcal{H}^*$, is a median graph with path metric $d(U,V) = |U \triangle V|/2$ and medians

$$\begin{split} \langle U, V, W \rangle &\coloneqq \{ H \in \mathcal{H} : H \text{ belongs to at least two of } U, V, W \} \\ &= (U \cap V) \cup (V \cap W) \cup (U \cap W). \end{split}$$

Proof. First, $V := U \triangle \{H, \neg H\}$ as above is clopen since $H, \neg H \in \mathcal{H}^*$ are isolated (whence $\{H\}, \{\neg H\}$ are clopen), and it is an orientation by \subseteq -minimality of H. That $\mathcal{M}(\mathcal{H})$ is connected follows from the following claim by noting that $U \triangle V \not\supseteq \varnothing, X$ is clopen, so it is a compact set of isolated points, whence finite.

Claim ([Sag95, Theorem 3.3]). There is a path between U, V iff $U \triangle V$ is finite, in which case

$$d(U, V) = |U \triangle V|/2 = |U \setminus V| = |V \setminus U|.$$

Proof. If $(U_i)_{i < n}$ is a path from $U =: U_0$ to $V =: U_{n-1}$, then, letting $\{H_i, \neg H_i\} := U_i \triangle U_{i-1}$ for all $1 \le i < n$ gives us a sequence $(H_i)_{i < n}$ inducing this path, whence $U \triangle V$ consists of $\{H_i\}_{i < n}$ and their complements. Thus $U \triangle V = 2n = 2d(U, V)$, as desired.

Conversely, if $U \triangle V = \{H_1, \ldots, H_n\} \sqcup \{K_1, \ldots, K_m\}$ with $U \setminus V = \{H_i\}$ and $V \setminus U = \{K_j\}$, then $\neg H_i \in V \setminus U$ and $\neg K_j \in U \setminus V$ for all i < n and j < m, so n = m and $V = U \cup \{\neg H_i\} \setminus \{H_i\}$. We claim that there is a permutation $\sigma \in S_n$ such that $(H_{\sigma(i)})$ induces a path from $U : U_0$, which is the desired path from U to V. Choose a minimal $H \in \{H_i\}$, which is also minimal in U: if $K \subseteq H$ for some $K \in U$, then $\neg H \subseteq \neg K$, and hence $\neg K \in V$, so $K = H_i \subseteq H$ for some i, forcing i and i set i and i so on i and so on i gives us the desired path with i and i so i and i so i and i and i so i and i and i so i and i

Finally, we show that $\mathcal{M}(\mathcal{H})$ is a median graph. Fix $U, V, W \in \mathcal{U}^{\circ}(\mathcal{H})$, and note that for any $M \in \mathcal{U}^{\circ}(\mathcal{H})$, we have by the triangle inequality that $M \in [U, V]$ iff $(U \setminus M) \cup (M \setminus V) \subseteq U \setminus V$, which clearly occurs iff $U \cap V \subseteq M \subseteq U \cup V$. Thus, a vertex M lies in the triple intersection $[U, V] \cap [V, W] \cap [U, W]$ iff

$$(U \cap V) \cup (V \cap W) \cup (U \cap W) \subseteq M \subseteq (U \cup V) \cap (V \cup W) \cap (U \cup W).$$

Note that the two sides coincide, so $M = \langle U, V, W \rangle$ — which is clopen if U, V, W are — is as claimed.

Given such a pocset \mathcal{H} , the graph $\mathcal{M}(\mathcal{H})$ constructed above is called the $dual^4$ median graph of \mathcal{H} . An important special case of this construction is when \mathcal{H} is nested, in which case $\mathcal{M}(\mathcal{H})$ is a tree:

^aIn the sense that $U_i = U_{i-1} \triangle \{H_i, \neg H_i\}$ and $H_i \in U_i$ for each $1 \le i < n$; see [Tse20, Definition 2.20].

³This can be formalized by letting \sim be the equivalence relation on $\mathcal H$ given by $H \sim \neg H$. Letting $\partial: \mathcal H \to \mathcal H/\sim$ denote the quotient map, orientations $U \subseteq \mathcal H$ then correspond precisely to sections $\varphi: \mathcal H/\sim \to \mathcal H$ of ∂ such that $\varphi(\partial H) \not\subseteq \neg \varphi(\partial K)$ for every $H, K \in \mathcal H$; the latter condition rules out 'orientations' of the form $\leftarrow \mid \to \cdot$.

⁴The name is justified by a Stone-type duality between median graphs with median homomorphisms and profinite pocsets whose non-trivial points are isolated with continuous maps, where from a median graph one can construct a canonical pocset of 'convex' half-spaces (see [CPTT23, Section 2.D] for details).

Definition 3.5. Let $\mathcal{H} \subseteq 2^X$ be a posset. Two half-spaces $H, K \in \mathcal{H}$ are nested if $\neg^i H \cap \neg^j K = \emptyset$ for some $i, j \in \{0, 1\}$, where $\neg^0 H := H$ and $\neg^1 H := \neg H$. We say that \mathcal{H} is nested if every pair $H, K \in \mathcal{H}$ is nested.

Proposition 3.6. If $(H_i)_{i < n}$ induces a path in $\mathcal{M}(\mathcal{H})$ with no backtracking, then (H_i) is strictly increasing.

Proof. Let $(U_i)_{i < n}$ be the induced path. By definition, we have $U_{i+1} = U_{i-1} \cup \{ \neg H_i, \neg H_{i-1} \} \setminus \{ H_i, H_{i-1} \}$, so $H_i \neq \neg H_{i-1}$, lest $U_{i+1} = U_{i-1}$. Thus, since $H_i \in U_i = U_{i-1} \cup \{\neg H_{i-1}\} \setminus \{H_{i-1}\}$, we see that $H_i \in U_{i-1}$. Clearly $H_i \neq H_{i-1}$. It suffices to remove the three cases when $\neg H_i \subseteq H_{i-1}$, $H_{i-1} \subseteq \neg H_i$, and $H_i \subseteq H_{i-1}$, since then nestedness of \mathcal{H} gives us $H_{i-1} \subsetneq H_i$, as desired.

Indeed, if $\neg H_i \subseteq H_{i-1}$, then $H_{i-1} \in U_{i+1}$ by upward-closure of $U_{i+1} \ni \neg H_i$. But since $H_{i-1} \neq \neg H_i$, we have by definition of U_{i+1} that $H_{i-1} \in U_i$, a contradiction. The other cases are similar.

Corollary 3.7. If \mathcal{H} is a nested profinite pocset with non-trivial elements isolated, then $\mathcal{M}(\mathcal{H})$ is a tree.

Nonetheless, in the general non-nested case, there is a sufficient criteria for the existence of a canonical spanning tree of $\mathcal{M}(\mathcal{H})$, which we now explore.

3.2. Finiteness conditions on $\mathcal{M}(\mathcal{H})$ induced by ???

4. Median Graphs, Convex Half-spaces, and Canonical Spanning Trees

Throughout this section, let (X,G) be a median graph, which, in the context of Theorem A, is the dual median graph of the pocset $\mathcal{H}_{\operatorname{diam}(\partial) \leq R}$ given by the quasi-isometry.

The presence of the median operation gives rise to a canonical finitely-separating pocset of convex (and co-convex) half-spaces $\mathcal{H}_{\text{cvx}}(X) \subseteq 2^X$ with a very rigid structure. To study them, we need to first understand the geometry of *projections* therein.

4.1. Projections in median graphs. For vertices $x, y, z \in X$, we write x-y-z for $y \in [x,z]$. By the triangle inequality, we have for all $w, x, y, z \in X$ that

$$(w-x-y \text{ and } w-y-z) \Leftrightarrow (w-x-z \text{ and } x-y-z),$$

and both sides occur iff there is a geodesic from w to x to y to z, which we write as w-x-y-z.

Lemma 4.1. For any $\emptyset \neq A \subseteq X$ and $x \in X$, there is a unique point in $\operatorname{cvx}(A)$ between x and every point in A, called the projection of x towards A, denoted $\operatorname{proj}_A(x)$.

Moreover, we have $\bigcap_{a \in A} [x, a] = [x, \operatorname{proj}_A(x)]$, and for any y in this set, we have $\operatorname{proj}_A(y) = \operatorname{proj}_A(x)$.

Proof. To show existence, pick any $a_0 \in A$. Given $a_n \in \text{cvx}(A)$, if there exists $a \in A$ with $a_n \notin [x, a]$, set $a_{n+1} := \langle x, a, a_n \rangle \in \text{cvx}(A)$. Then $a_0 - a_1 - \cdots - a_n - x$ for all n, so this sequence terminates in at most $d(a_0, x)$ steps at a point in cvx(A) between x and every point in A. For uniqueness, if there exist two such points $a, b \in \text{cvx}(A)$, then x-a-b and x-b-a, forcing a = b.

Finally, if x-y—proj_A(x) and $a \in A$, then x—proj_A(x)—a and hence x-y—a. Conversely, let x-y—afor all $a \in A$. Since $[y, a] \subseteq [x, a]$ for all a, we see that

$$\operatorname{proj}_A(y) \in \operatorname{cvx}(A) \cap \bigcap_{a \in A} [y, a] \subseteq \operatorname{cvx}(A) \cap \bigcap_{a \in A} [x, a]$$

hence x-y—proj_A(x) as desired.

Remark 4.2. It follows from the proof above that for any median homomorphism $f:(X,G)\to (Y,H)$, we have $f(\operatorname{proj}_A(x)) = \operatorname{proj}_{f(A)}(f(x))$ for any $\emptyset \neq A \subseteq X$ and $x \in X$. Indeed, we have

$$\operatorname{proj}_{A}(x) = \langle x, a_{m}, \dots, \langle x, a_{2}, \langle x, a_{1}, a_{0} \rangle \rangle \dots \rangle$$

for some $m \leq d(a_0, x)$ and $a_0, \ldots, a_m \in A$, and this is preserved by f.

For $A := \{a, b\}$, we have $\operatorname{proj}_A(x) = \langle a, b, x \rangle$, and hence $\operatorname{cvx}(A) = \operatorname{proj}_A(X) = \langle a, b, X \rangle = [a, b]$.

Lemma 4.3. For each $x, y \in X$, cone_x(y) is convex, and if xGy, then cone_x $(y) \sqcup \text{cone}_y(x) = X$.

Proof. Fix $a, b \in \text{cone}_x(y)$ and a-c-b. It suffices to show that $x-y-\langle a,c,x\rangle$, for then x-y-c since we have $x - \langle a, c, x \rangle - c$. Indeed, it follows from the following observations.

• $x-y-\langle a,b,x\rangle$, since $\langle a,b,x\rangle=\operatorname{proj}_{\{a,b\}}(x)$ and so $[x,\langle a,b,x\rangle]=[x,a]\cap [x,b]\ni y$ by Lemma 4.1.

• $x-\langle a,b,x\rangle-\langle a,c,x\rangle$, which follows from $\langle a,b,x\rangle-\langle a,c,x\rangle-a$, since $x-\langle a,b,x\rangle-a$ by definition. Indeed, we have $\langle a,c,x\rangle$ is in both [a,x] and $[a,c]\subseteq [a,b]$, and since $\operatorname{proj}_{\{b,x\}}(a)=\langle a,b,x\rangle$, we have again by Lemma 4.1 that $[\langle a,b,x\rangle,a]=[a,x]\cap [a,b]\ni \langle a,c,x\rangle$.

Finally, take $z \in X$ and consider $w := \langle x, y, z \rangle \subseteq [x, y]$. Either w = x or w = y (but not both), giving us the desired partition.

In particular, this shows that if xGy, then $\operatorname{cone}_x(y) \in \mathcal{H}^*_{\operatorname{cvx}}(X)$. The convexity of cones also shows, in the situation of Lemma 4.1, that $\operatorname{proj}_A = \operatorname{proj}_{\operatorname{cvx}(A)}$, i.e., $\operatorname{proj}_A(x)$ is also between x and every point in $\operatorname{cvx}(A)$. Indeed, note that $\operatorname{cone}_x(\operatorname{proj}_A(x))$ is convex and contains A, so it contains $\operatorname{cvx}(A)$ too.

Lemma 4.4. $\operatorname{proj}_A : X \twoheadrightarrow \operatorname{cvx}(A)$ is a median homomorphism with $\operatorname{proj}_A \circ \operatorname{cvx} = \operatorname{cvx} \circ \operatorname{proj}_A$.

Proof. The second claim follows from the first since, by Remark 4.2, we have

$$f(\operatorname{cvx}(B)) = f(\operatorname{proj}_B(X)) = \operatorname{proj}_{f(B)}(f(X)) = \operatorname{cvx}(f(B))$$

for all median homomorphisms $f: X \to Y$ and $B \subseteq X$, so it in particular applies to $f := \operatorname{proj}_A$.

To this end, let $x-y-z \in X$ and set $w \coloneqq \langle \operatorname{proj}_A(x), \operatorname{proj}_A(y), \operatorname{proj}_A(z) \rangle \in \operatorname{cvx}(A)$. It suffices to show that y-w-a for all $a \in A$, for then $w = \operatorname{proj}_A(y)$ and hence $\operatorname{proj}_A(x) - \operatorname{proj}_A(y) - \operatorname{proj}_A(z)$. But we have $y-\operatorname{proj}_A(y)-a$ already, so it further suffices to show that $y-w-\operatorname{proj}_A(y)$. For this, we note that

$$x$$
— $\operatorname{proj}_A(x)$ — $\operatorname{proj}_A(y)$ and $\operatorname{proj}_A(x)$ — w — $\operatorname{proj}_A(y)$,

so $x-w-\operatorname{proj}_A(y)$, and similarly $z-w-\operatorname{proj}_A(y)$. Thus, it follows that

$$w \in [\operatorname{proj}_A(y), x] \cap [\operatorname{proj}_A(y), z] = [\operatorname{proj}_A(y), \operatorname{proj}_{\{x,z\}}(\operatorname{proj}_A(y))] \qquad \text{Lemma 4.1}$$
$$= [\operatorname{proj}_A(y), \operatorname{proj}_{[x,z]}(\operatorname{proj}_A(y))]$$
$$\subseteq [\operatorname{proj}_A(y), y], \qquad \text{Lemma 4.1}$$

where the second equality follows from $\operatorname{cvx}(\{x,z\}) = [x,z]$, and hence $\operatorname{proj}_{\{x,z\}} = \operatorname{proj}_{[x,z]}$.

4.2. Convex half-spaces of median graphs. We now use projections to explore the geometry of convex half-spaces in median graphs. In particular, they are very rigid:

Proposition 4.5. Each edge $(x,y) \in G$ is on a unique hyperplane, namely the inward boundary of $\operatorname{cone}_x(y)$, and conversely, each half-space $H \in \mathcal{H}^*_{\operatorname{CVX}}(X)$ is $\operatorname{cone}_x(y)$ for every $(x,y) \in \partial_{\operatorname{ie}}H$.

Thus, hyperplanes are equivalence classes of edges. Furthermore, this equivalence relation is generated by parallel sides of squares (i.e., 4-cycles).

Proof. We have $\operatorname{cone}_x(y) \in \mathcal{H}^*_{\operatorname{cvx}}(X)$ by the above lemma, and clearly $(x,y) \in \partial_{\operatorname{ie}} \operatorname{cone}_x(y)$. Conversely, take $H \in \mathcal{H}^*_{\operatorname{cvx}}(X)$ and any $(x,y) \in \partial_{\operatorname{ie}}H$. Then $H = \operatorname{cone}_x(y)$, for if $z \in H \cap \neg \operatorname{cone}_x(y)$, then $z \in \operatorname{cone}_y(x)$, and hence $x \in [y,z] \subseteq H$ by convexity of H, a contradiction; if $z \in \operatorname{cone}_x(y) \cap \neg H$, then $[x,z] \subseteq \neg H$ by convexity of $\neg H$, and hence $y \notin H$, a contradiction.

Finally, parallel edges of a strip of squares generate the same hyperplane since, for a given square, each vertex is between its neighbors and hence any hyperplane containing an edge contains its opposite edge. On the other hand, let $(a,b), (c,d) \in \partial_{ie}H$ for some $H \in \mathcal{H}^*_{cvx}(X)$. Note that $\partial_{ov}H = \operatorname{proj}_{\neg H}(H)$ is convex since H is, and $\operatorname{proj}_{\neg H}$ preserves convex sets by Proposition 4.4, so any geodesic between $a, c \in \partial_{ov}H$ lies in $\partial_{ov}H$. Matching this geodesic via $\partial_{ie}H : \partial_{ov}H \to \partial_{iv}H$ gives us a geodesic between b,d in $\partial_{iv}H$, which together with the matching forms the desired strip of squares.

Corollary 4.6. Two half-spaces $H, K \in \mathcal{H}^*_{\text{cvx}}(X)$ are non-nested iff there is an embedding $\{0,1\}^2 \hookrightarrow X$ of the Hamming cube into the four corners $\neg^i H \cap \neg^j K$.

In particular, if $H, K \in \mathcal{H}^*_{cvx}(X)$ are non-nested, then $\partial_{\nu} H \cap \partial_{\nu} K \neq \varnothing$.

Proof. Let H, K be non-nested and take $x_1 \in H \cap K$ and $x_2 \in H \cap \neg K$. Since H is connected, any geodesic between x_1, x_2 crosses an edge $(x_1', x_2') \in \partial_{oe} K$ in H. Similarly, there is an edge $(y_1', y_2') \in \partial_{oe} K$ in $\neg H$, so we may slide both edges along $\partial_{oe} K$ to obtain the desired square (see Proposition 4.5).

Conversely, the half-spaces cutting the square are clearly non-nested.

Lemma 4.7 (Helly). Any finite intersection of pairwise-intersecting non-empty convex sets is non-empty.

Proof. For pairwise-intersecting convex sets H_1, H_2, H_3 , pick any $x \in H_1 \cap H_2$, $y \in H_1 \cap H_3$ and $z \in H_2 \cap H_3$; their median $\langle x, y, z \rangle$ then lies in $H_1 \cap H_2 \cap H_3$.

Suppose that it holds for some $n \geq 3$ and let $H_1, \ldots, H_{n+1} \subseteq X$ pairwise-intersect. Then $\{H_i \cap H_{n+1}\}_{i \leq n}$ is a family of n pairwise-intersecting convex sets, so $\bigcap_{i < n+1} H_i = \bigcap_{i < n} (H_i \cap H_{n+1})$ is non-empty.

Lastly, we have some useful finiteness conditions on convex half-spaces; the former implies that $\mathcal{H}_{\text{cvx}}(X)$ is finitely-separating, and the latter allows us to replace finite sets with their convex hulls.

Lemma 4.8. Any two disjoint convex sets $\emptyset \neq A, B \subseteq X$ can be separated by a half-space $A \subseteq H \subseteq \neg B$, and furthermore we have in this case that $d(A, B) = |\{H \in \mathcal{H}_{cvx}(X) : A \subseteq H \subseteq \neg B\}|$.

Proof. Pick a geodesic $A \ni x_0Gx_1G\cdots Gx_n \in B$, where n := d(A, B). Then $H := \operatorname{cone}_{x_1}(x_0)$, which is a half-space by Lemma 4.3, separates A, B since $x_0 = \operatorname{proj}_A(x_n)$, and thus we have $A \subseteq \operatorname{cone}_{x_n}(x_0) \subseteq \operatorname{cone}_{x_1}(x_0)$ and $B \subseteq \operatorname{cone}_{x_0}(x_n) \subseteq \operatorname{cone}_{x_0}(x_1)$.

Moreover, each such half-space $A \subseteq H \subseteq \neg B$ satisfies $x_i \in H \not\ni x_{i+1}$ for a unique i < n, and conversely each pair (x_i, x_{i+1}) has a unique half-space separating them, so we have the desired bijection.

Lemma 4.9. Every interval [x,y] is finite. More generally, if $A \subseteq X$ is finite, then so is cvx(A).

Proof. The singletons $\{x\}$ and $\{y\}$ are convex, so there are finitely-many half-spaces $H \subseteq [x,y]$. But each $z \in [x,y]$ is determined uniquely by those half-spaces containing it, so [x,y] is finite.

Let $A := \{x_0, \dots, x_n\}$. Since $\operatorname{cvx}(A) = \operatorname{proj}_A(X)$, we have by Remark 4.2 that points in $\operatorname{cvx}(A)$ are of the form $\langle x, x_n, \dots, \langle x, x_2, \langle x, x_1, x_0 \rangle \rangle \rangle$, which is finite by induction using that intervals are finite.

4.3. Canonical spanning trees. We now present the Borel cycle-cutting algorithm that can be preformed canonically on any countable median graph with finite hyperplanes. We do so by colouring the half-spaces $\mathcal{H}^*_{\text{cvx}}(X)$ into certain nested half-spaces $\mathcal{H}_n \subseteq \mathcal{H}_{\text{cvx}}(X)$, from which we inductively build a spanning forest by leveraging a tree structure on the \mathcal{H}_n -blocks X/\mathcal{H}_n . This tree is constructed as follows.

Lemma 4.10. For any subpocset $\mathcal{H} \subseteq \mathcal{H}_{cvx}(X)$, the principal orientations map $X \to \mathcal{U}^{\circ}(\mathcal{H})$ is surjective.

Proof. Let $U \in \mathcal{U}^{\circ}(\mathcal{H})$. Since $U \subseteq \mathcal{H}$ is clopen, there is a finite set $A \subseteq X$ — which we may assume to be convex by Corollary 4.9 — such that for all $H \in \mathcal{H}$, we have $H \in U$ iff there is $K \in U$ with $H \cap A = K \cap A$. Note that $K \cap A \neq \emptyset$ for every $K \in U$, since otherwise $\emptyset \in U$. Furthermore, $H \cap K \neq \emptyset$ for every $H, K \in U$, since otherwise we have $H \subseteq \neg K$, and so $\neg K \in U$. By Lemma 4.7, we have $(H \cap A) \cap (K \cap A) = H \cap K \cap A \neq \emptyset$, and applying it again furnishes some $X \in \bigcap_{H \in U} H \cap A$ in X; note that the latter intersection is finite. Thus $U \subseteq \widehat{x}$, so $U = \widehat{x}$ since both are orientations.

This lemma is crucial, in that it induces an isomorphism $X/\mathcal{H} \cong \mathcal{M}(\mathcal{H})$. Here, \mathcal{H} is finitely-separating by Example 2.4 and Proposition 4.5, and so $\mathcal{U}^{\circ}(\mathcal{H})$ is the vertices of the median graph $\mathcal{M}(\mathcal{H})$ by Propositions 2.3 and 3.4. The fibers of $X \to \mathcal{U}^{\circ}(\mathcal{H})$ are the \mathcal{H} -blocks by definition, so we have the desired bijection. Explicitly, two \mathcal{H} -blocks $([x]_{\mathcal{H}}, [y]_{\mathcal{H}})$ are said to be G-adjacent if $(\widehat{x}, \widehat{y}) \in \mathcal{M}(\mathcal{H})$.

Proposition 4.11. Every countable median graph with finite hyperplanes admits a canonical spanning tree.

Proof. Let (X,G) be a countable median graph with finite hyperplanes. By Corollary 4.6, if two half-spaces $H,K\in\mathcal{H}^*_{\mathrm{cvx}}(X)$ are non-nested, then $\partial_{\mathsf{v}}H\cap\partial_{\mathsf{v}}K\neq\varnothing$, so looking at the intersection graph of the boundaries furnishes a countable colouring $\mathcal{H}^*_{\mathrm{cvx}}(X)=\bigsqcup_{n\in\mathbb{N}}\mathcal{H}^*_n$ such that each $H,\neg H$ receive the same color and that each $\mathcal{H}_n\coloneqq\mathcal{H}^*_n\cup\{\varnothing,X\}$ is a nested subposest. For each $n\in\mathbb{N}$, let $\mathcal{K}_n\coloneqq\bigcup_{m>n}\mathcal{H}_m$.

We shall inductively construct an increasing chain of subforests $T_n \subseteq G$ such that the components of T_n are exactly the \mathcal{K}_n -blocks. Then, the increasing union $T := \bigcup_n T_n$ is a spanning tree, since each $(x,y) \in G$ lies in a \mathcal{K}_n -block for sufficiently large n (namely, the n such that $\operatorname{cone}_x(y) \in \mathcal{H}_{n-1}^*$, since $\operatorname{cone}_x(y)$ and its complement are the only half-spaces separating x and y by Proposition 4.5).

Since each pair of distinct points is separated by a half-space, the $\mathcal{K}_0 = \mathcal{H}_{cvx}(X)$ -blocks are singletons, so put $T_0 := \emptyset$. Suppose that a forest T_n is constructed as required. Note that each \mathcal{K}_{n+1} -block $Y \in X/\mathcal{K}_{n+1}$ is not separated by any half-spaces in \mathcal{H}_m for m > n, but is separated (by Proposition 4.5) by \mathcal{H}_n into the \mathcal{K}_n -blocks contained in Y, and those correspond precisely to the \mathcal{H}_n -blocks in Y/\mathcal{H}_n . For each G-adjacent pair $A, B \in Y/\mathcal{H}_n$, which is separated by a unique half-space $H \in \mathcal{H}_n$ by Lemma 4.8, we may pick an edge from the finite hyperplane $\partial_{ie}H$. Since each Y/\mathcal{H}_n is a tree by Corollary 3.7, and a single edge is picked

between every pair of G-adjacent blocks therein, the graph T_{n+1} obtained from T_n by adding all such edges is a forest whose components are exactly the \mathcal{K}_{n+1} -blocks.

Corollary 4.12. If a CBER admits a graphing whose components are median graphs, then it has a subtreeing.

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