Robot Trajectory with the Synthesized Controller for Trial 46 from t = 20 to t = 506.5 Trajectory Sensor Estimated Location for Obstacle 1 6.0 Sensor Estimated Location for Obstacle 2 Obstacle Location 1 5.5 Obstacle Location 2 5.0 4.5 4.0 3.5 3.0 2.5

5.0

5.5

3.0

3.5

4.0

4.5

2.5