

# Sequence Models and Attention

CS280

Spring 2025

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# Next few lectures

- Today: Transformers / Attention
- Next: Vision Transformers, DINO
- Next Week: Diffusion Models

# What is Attention

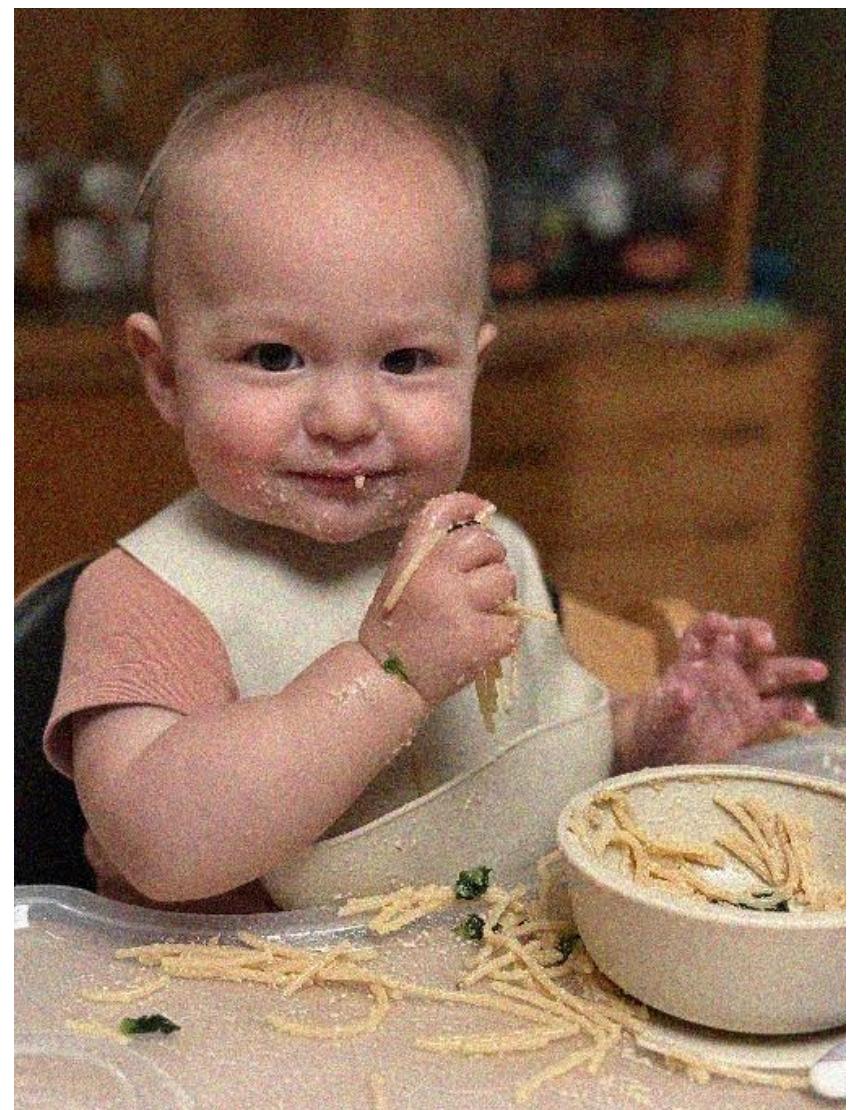
A Computer Vision perspective

# Computer Vision History on filtering

- Gaussian Filter
- Anisotropic Diffusion
- Bilateral Filter
- Non-Local Means

# How to filter an image?

Gaussian filter



How to do edge  
preserving filter?

# Physical analog: Heat diffusion



Heat Equation

$$\frac{\partial u}{\partial t} = c \Delta u = \operatorname{div}(c \nabla u)$$

Moving from higher to lower concentration of signal  $u$

# Physical analog: Heat diffusion



Heat Equation

$$\frac{\partial u}{\partial t} = c \Delta u = \operatorname{div}(c \nabla u)$$

Moving from higher to lower concentration of signal  $u$

Solution is exactly convolution with a gaussian kernel!

# Useful intuition for later...



Heat Equation

$$\frac{\partial u}{\partial t} = c \Delta u = \operatorname{div}(c \nabla u)$$

SDE formulation (how each particle moves):

$$dx(t) = cdW(t)$$

# How to do edge preserving filter?

How do we keep the two soups separate?

Why does gaussian filter  
destroy the edges?



# Anisotropic Diffusion Perona & Malik 1990

- Idea: Look to see if there is a wall, modulate diffusion across the edge!
- Anisotropic Diffusion:
  - Treats the edges in the image like this wall

$$\frac{\partial u}{\partial t} = \operatorname{div}(c(|\nabla u|)\nabla u)$$

- Makes the diffusion process, edge dependent
- → **Data dependent filtering**



# Anisotropic Diffusion Results

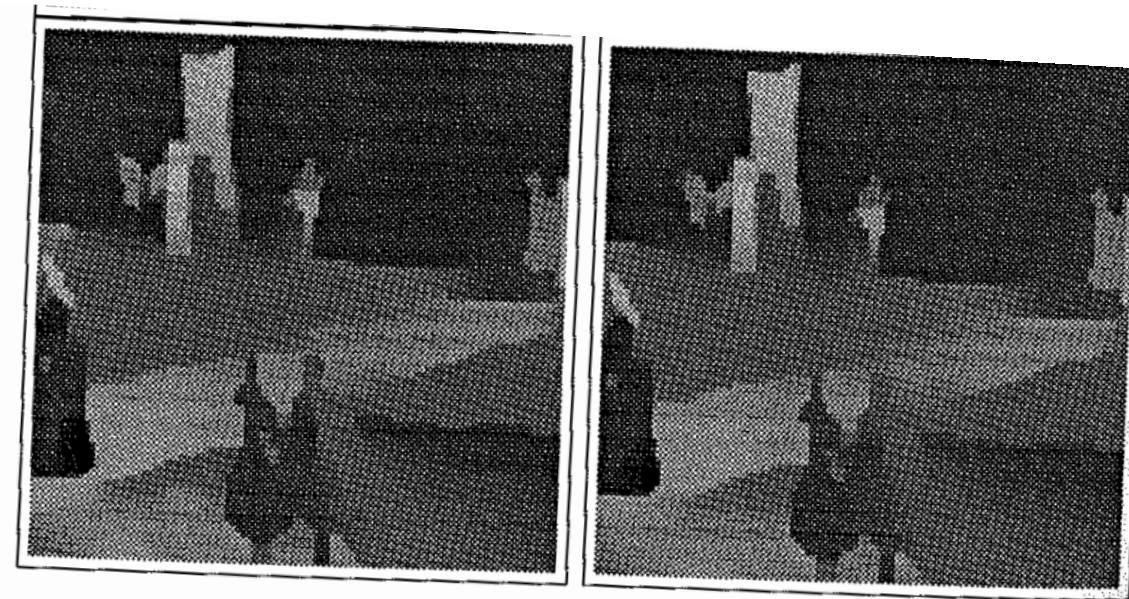
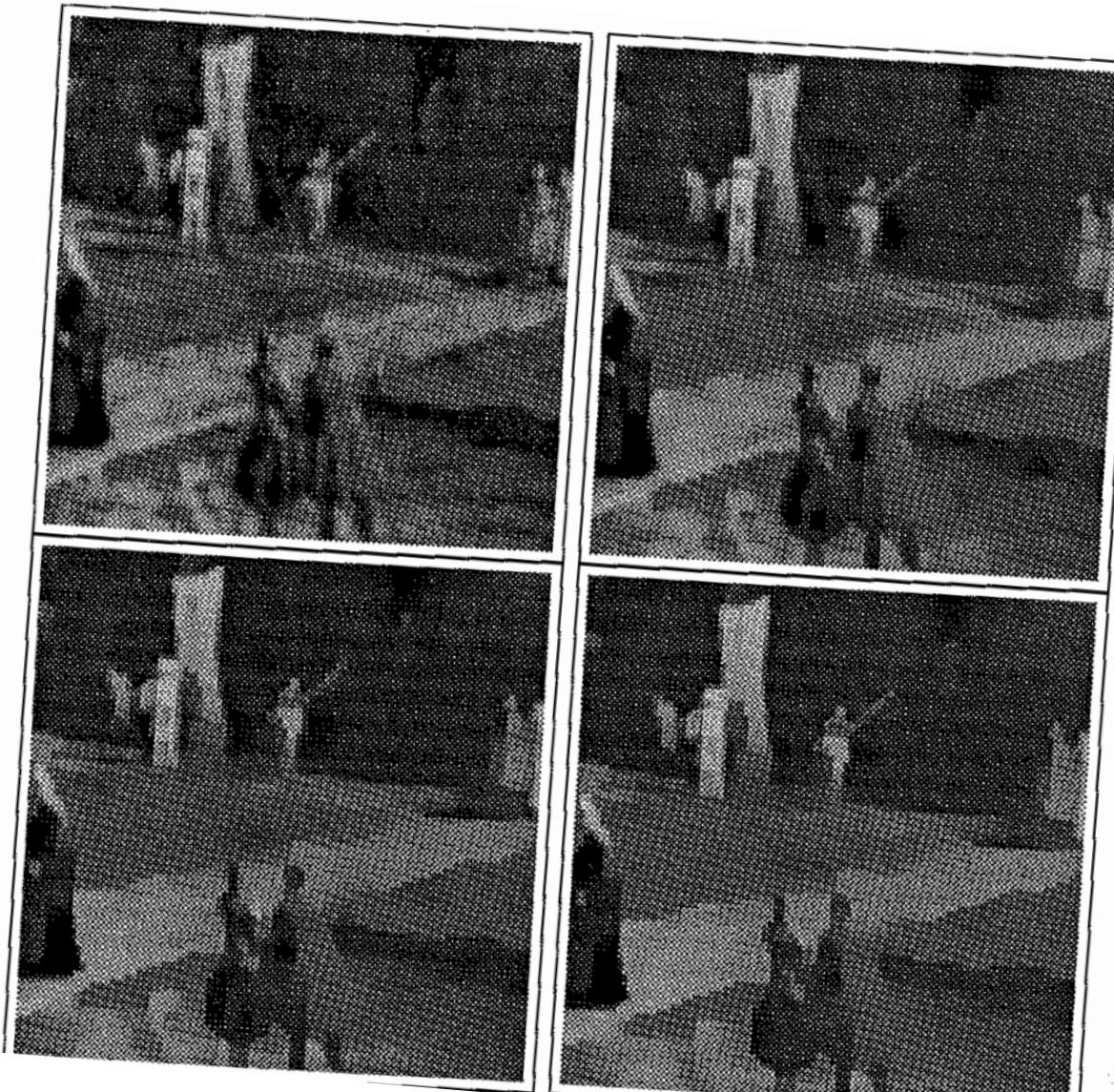


Figure 3.7. Sequence of images produced by anisotropic diffusion. The code presented in figure 3.5 was run on the image at the top-left corner for 10, 20, 30, 60, 100 iterations. The original image has pixel values between 0 (black) and 255 (white) and had a size of  $100 \times 100$  pixels. The coefficient  $K$  was set equal to  $K = 10$ .

Aurich and Weule 1995  
Tomasi and Manduchi 1998...

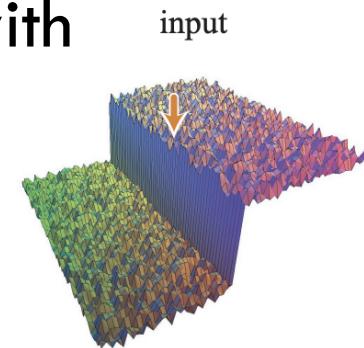
# Bilateral Filter



Photo from wikipedia

# Bilateral Filter

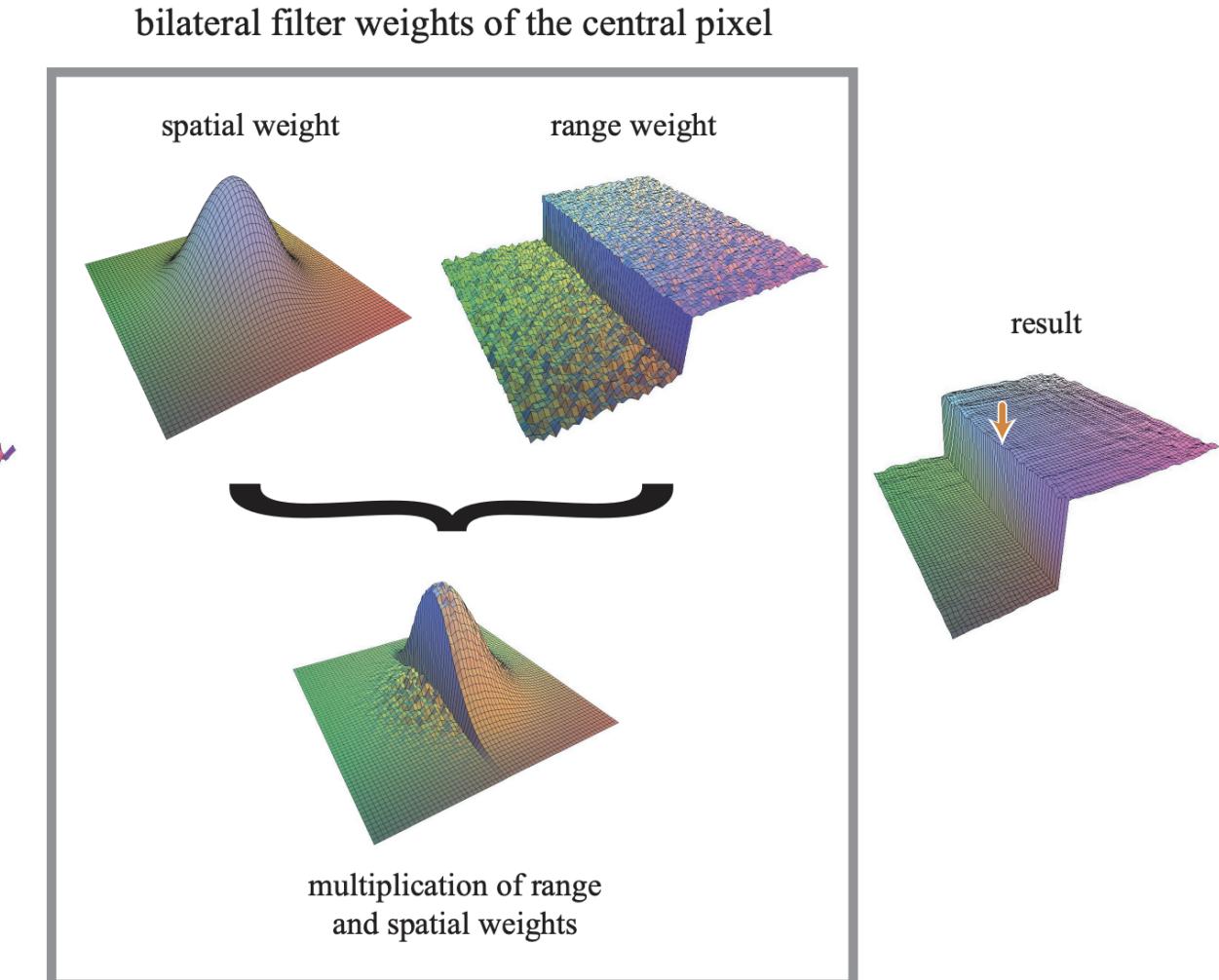
- Inspired by Anisotropic Diffusion
- Weight gaussian kernel with pixel similarity
- Again data-dependent
- This is core idea of ROPE



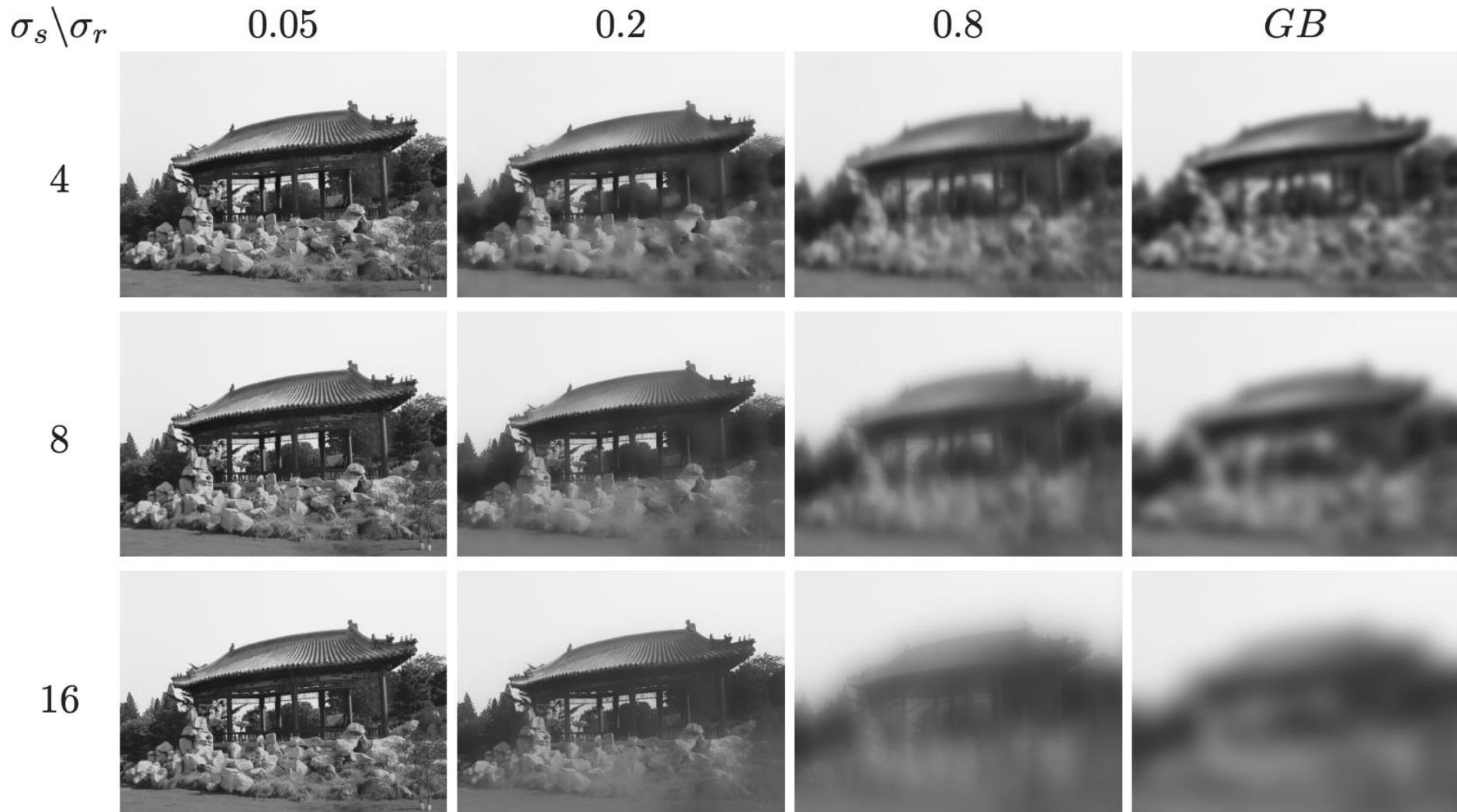
$$BF[I]_p = \frac{1}{W_p} \sum_{q \in S} G_{\sigma_s}(\|p - q\|) G_{\sigma_r}(I_p - I_q) I_q$$

Distance Similarity

Pixel Similarity



# Bilateral Filter Results



16

4

8

$\sigma_s \backslash \sigma_r$

0.05

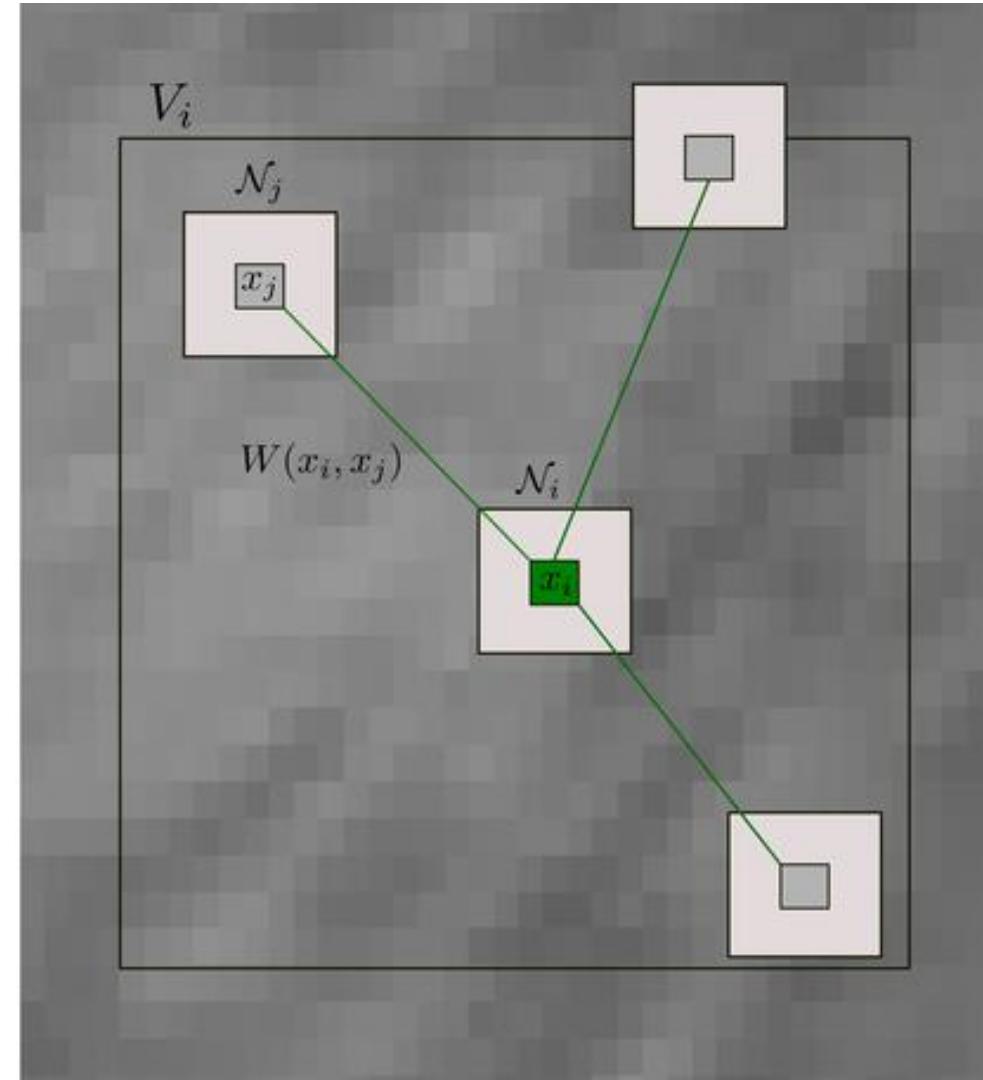
0.2

0.8

*GB*

# Non-local means Buades, Coll, and Morel 2005

- Idea of a filter is to denoise by averaging similar pixels
- Why look at near by pixels only? The similar pixels **can be anywhere!**
- Idea: filter by average of similar patches, **from everywhere in the image!**
- Data-driven weights (similarity) with large field of view.



# Non-local means

$$NL[v](i) = \sum_{j \in I} w(i, j)v(j),$$



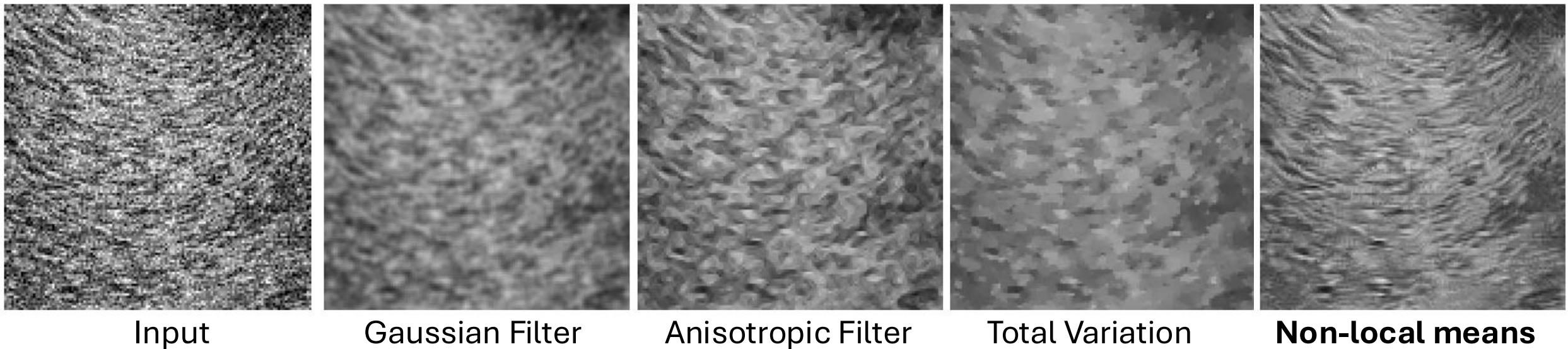
Weight is normalized affinity to all other pixels:

$$w(i, j) = \frac{1}{z_i} e^{-\|v_i - v_j\|^2 / \sigma^2} \quad z_i = \sum_j e^{-\|v_i - v_j\|^2 / \sigma^2}$$

Softmax! In vectorized form, this is:

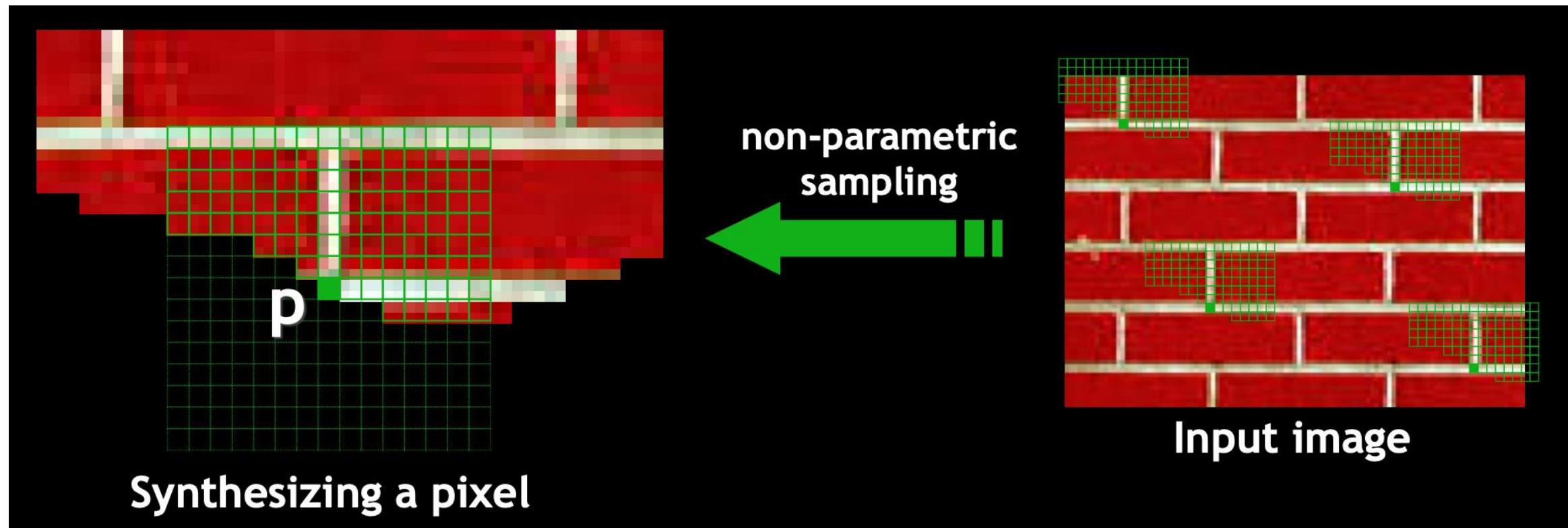
$$NL = \text{softmax}(\text{dist}(v_i, v_j))V$$

# Results



# Aside Efros and Leung 1999

- Inspired non-local means



# Two key ideas

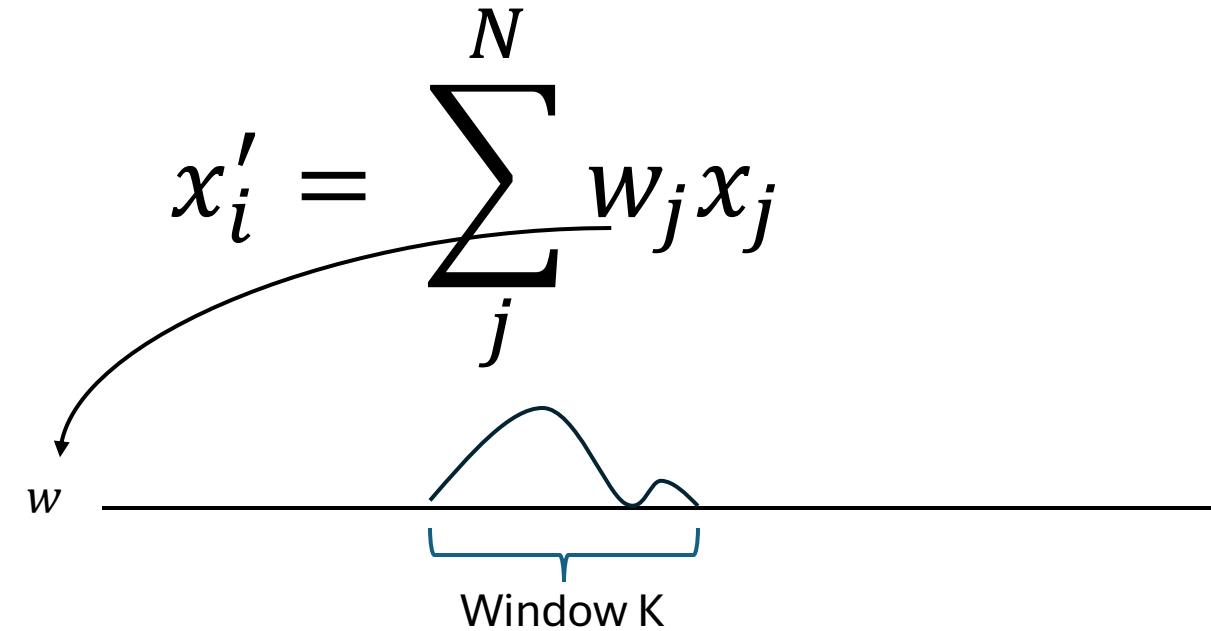
In contrast to ordinary convolution by a fixed kernel

1. **Data-driven kernel** → Weights conditioned on the data point
2. **Full field of view** → non-local connections

These are the key difference between convnets and transformers

**Convolution:**

$$x' = Wx + b$$



**Attention:**

$$\text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$

$$x'_i = \sum_j^N w_j(x_i, x_j)x_j$$

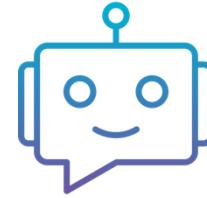
# Transformer Architecture

Excellent slides from Jiabin Huang (UMD) for the rest

<https://www.youtube.com/watch?v=rcWMRA9E5RI>



Please explain  
transformers like I am five



Sure! Let's break down what a transformer is in a way that's easy to understand.

Imagine you have a big book, and you want to summarize each chapter. A traditional way to do this might be to read each chapter from start to finish and write down the important points. But what if you could read the whole chapter at once and instantly understand which parts are important? That's kind of what a transformer does!

#### Key Parts of a Transformer

1. **Input Representation:** The text is turned into a form that the transformer can understand, usually a list of numbers.
2. **Attention Mechanism:** This is like a spotlight that shines on different parts of the text, helping the transformer focus on the important bits. The cool thing is, it can shine on multiple parts at once, not just one word at a time.
3. **Layers:** The transformer has several layers, and each layer helps it understand the text better. Think of these layers as levels in a video game, where each level makes you a bit stronger and better at the game.

#### How It Works

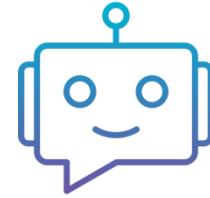
1. **Reading the Text:** When you give a transformer a sentence, it first converts each word into a number.
2. **Understanding Relationships:** The transformer then uses the attention mechanism to figure out how words in the sentence relate to each other. For example, in the sentence "The cat sat on the mat," it understands that "cat" and "sat" are related.
3. **Processing Layers:** The sentence goes through multiple layers, with each layer making the understanding of the sentence a bit clearer.
4. **Output:** Finally, the transformer gives its output. This could be a translation of the sentence into another language, a summary, or even the next word in a text you're writing.

#### Why It's Cool

Transformers are powerful because they can handle long sentences and understand context really well.

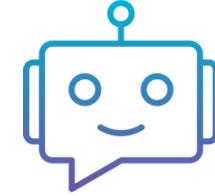
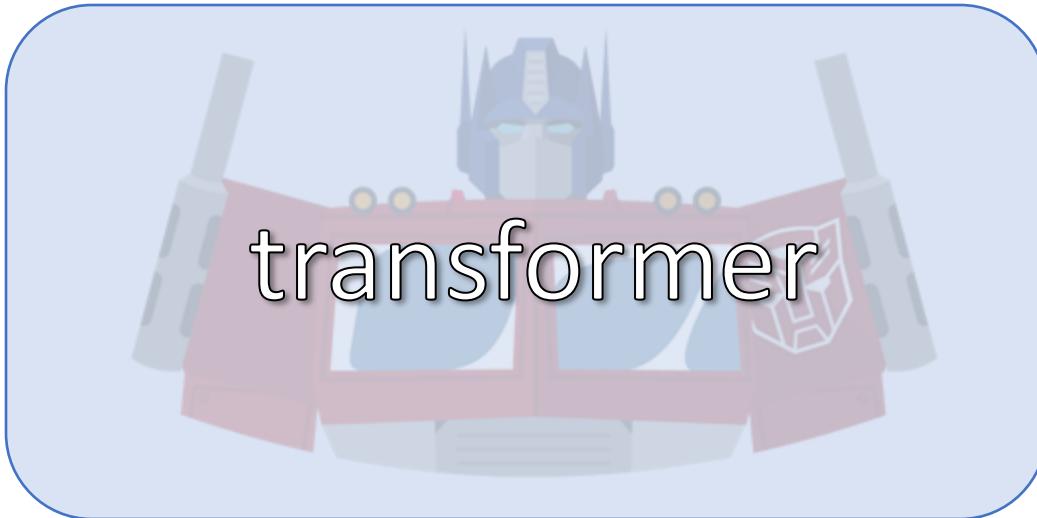


Beautiful, snowy Tokyo city is bustling. The camera moves through the bustling city street, following several people enjoying the beautiful snowy weather and shopping at nearby stalls. Gorgeous sakura petals are flying through the wind along with snowflakes.





Which street was this photo taken on?



The photo was taken on Bourbon Street, which is located in the French Quarter of New Orleans, Louisiana.



**What?**



**How?**



**Why?**



# Sequence-to-Sequence model



# Sequence-to-Sequence model



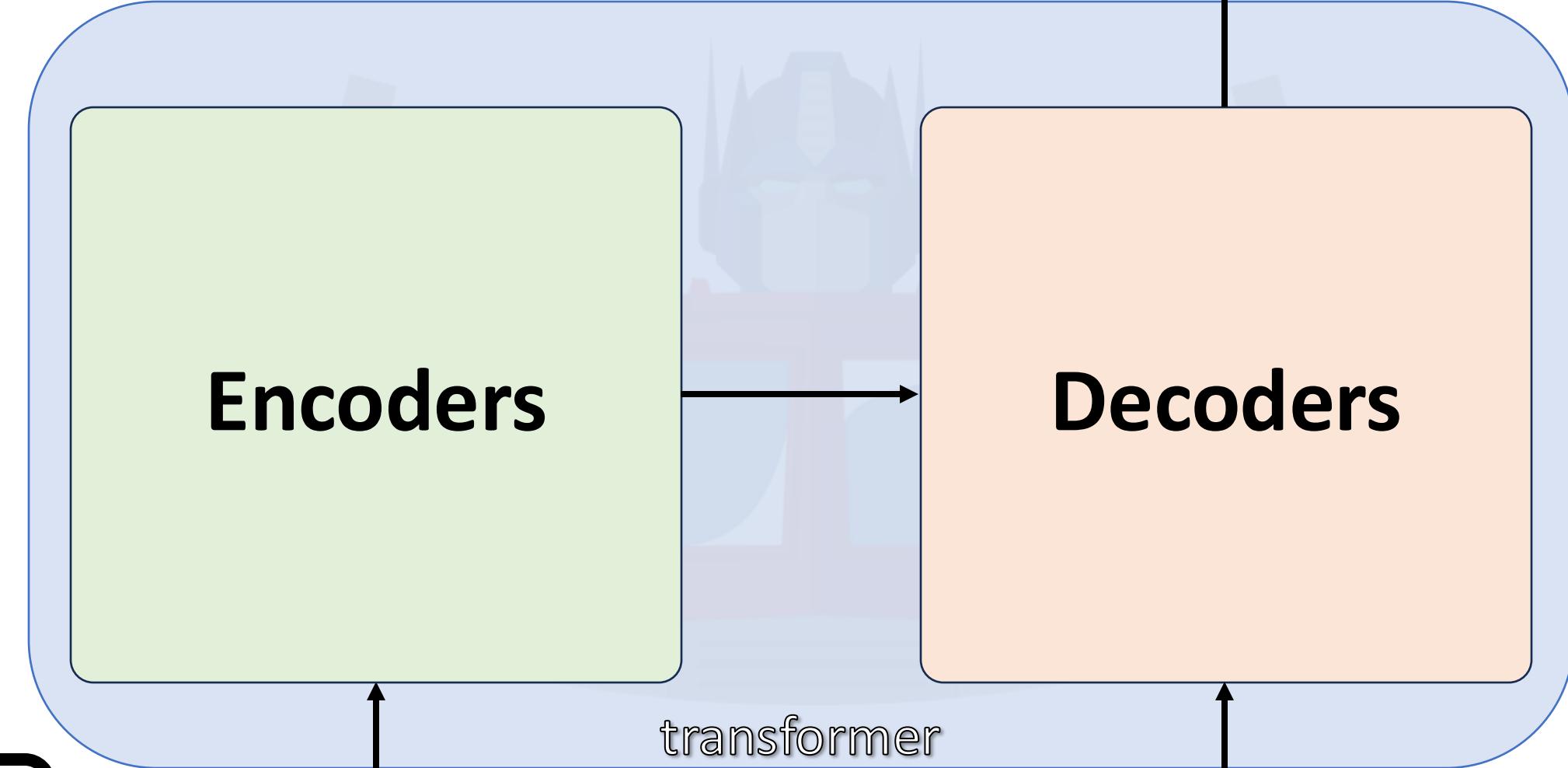
# Sequence-to-Sequence model



# Sequence-to-Sequence model



# Sequence-to-Sequence model



En

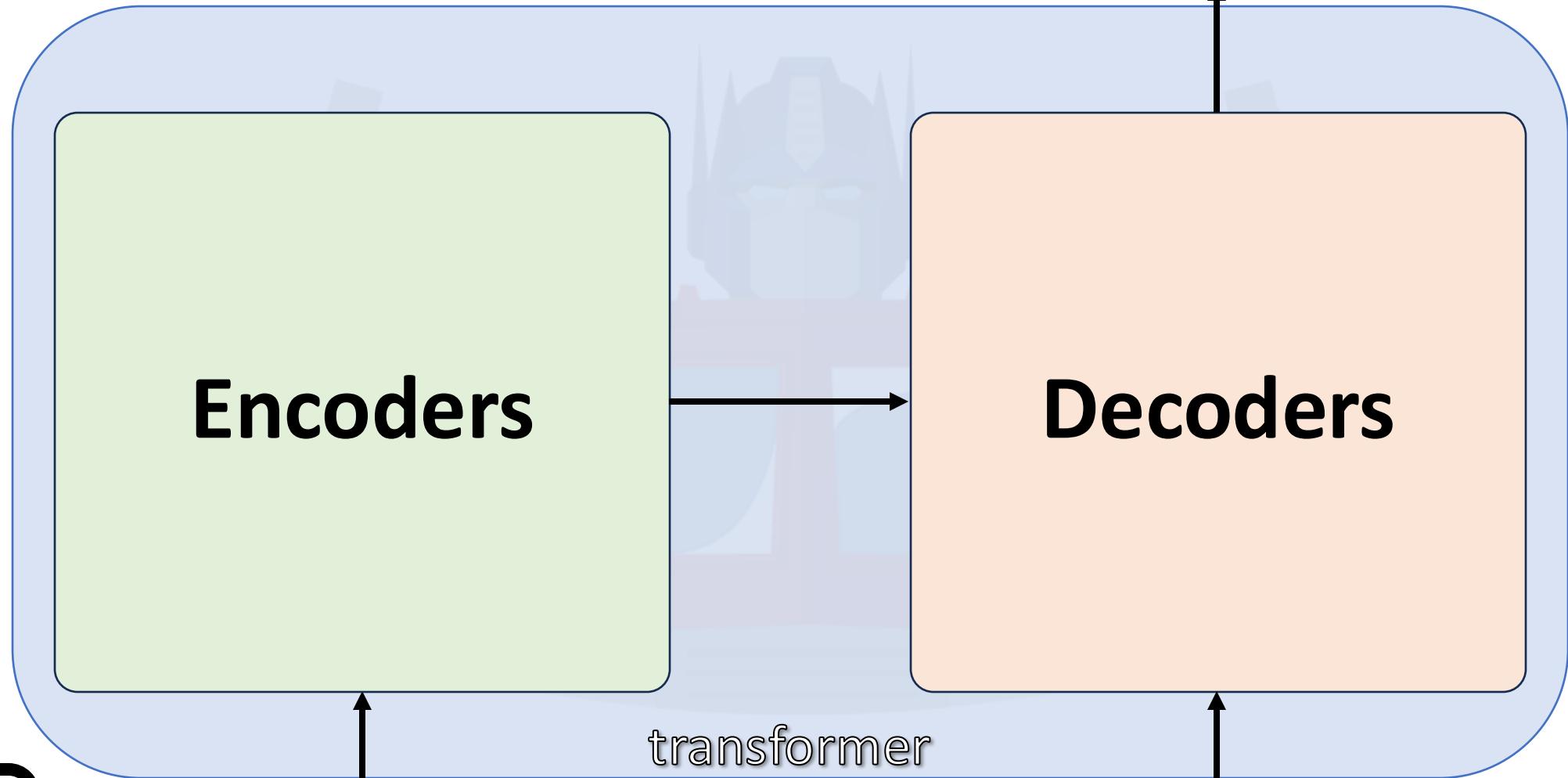
How are you?

transformer

<start>

你 好 吃 飽 嗎 ... ? <end>

ZH

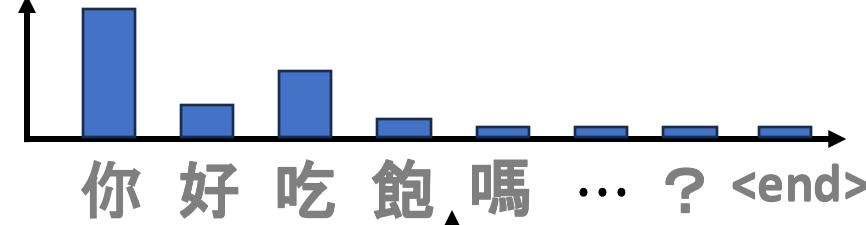


En

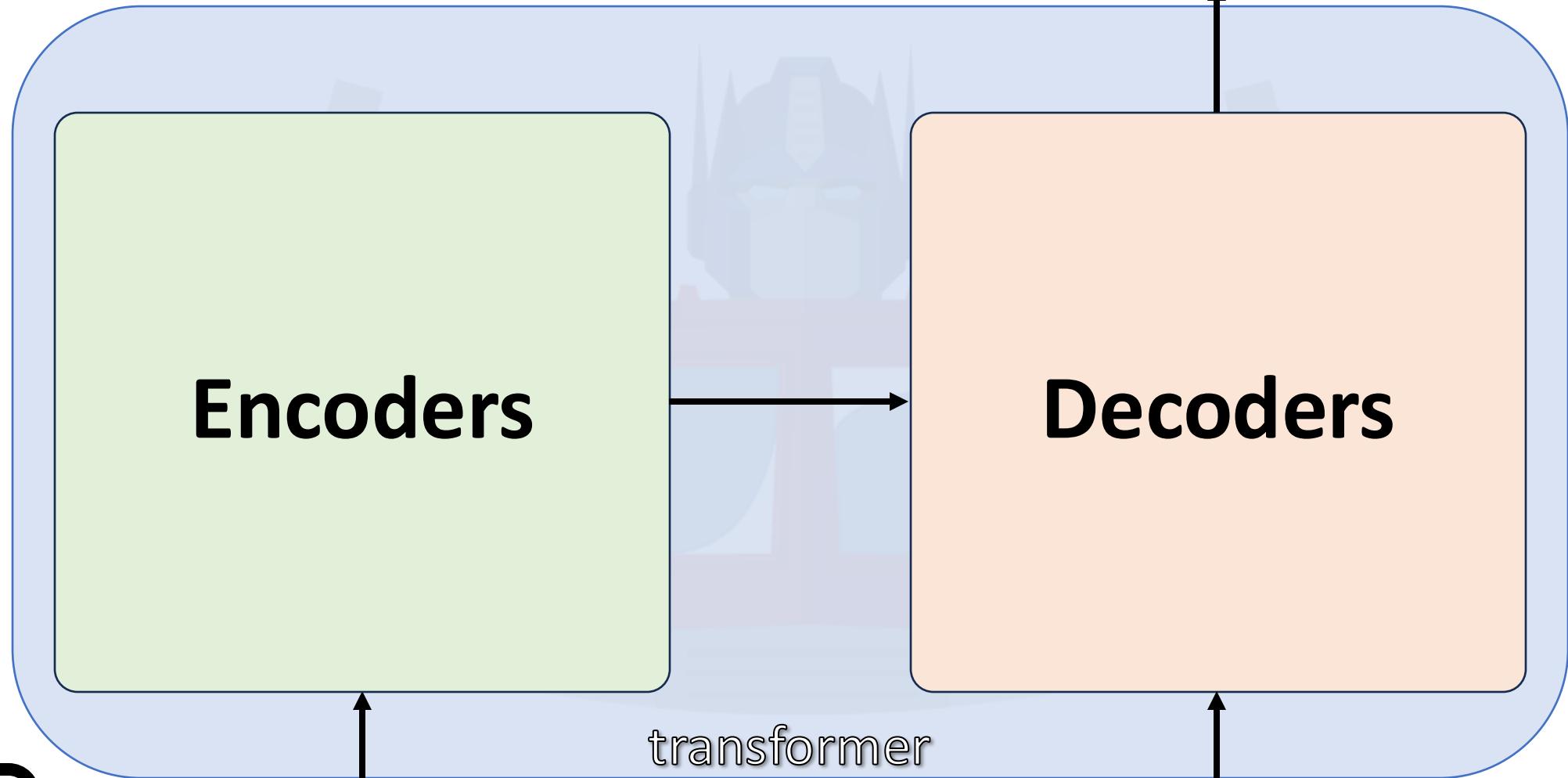
How are you?

transformer

<start> 你



ZH



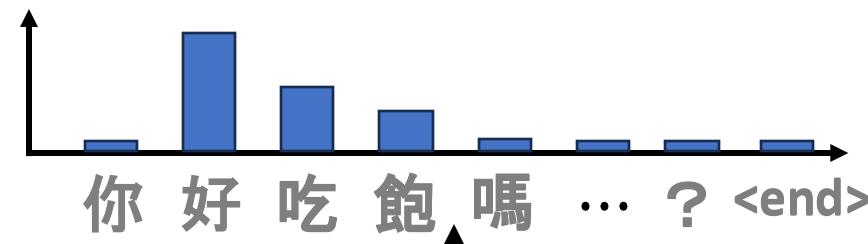
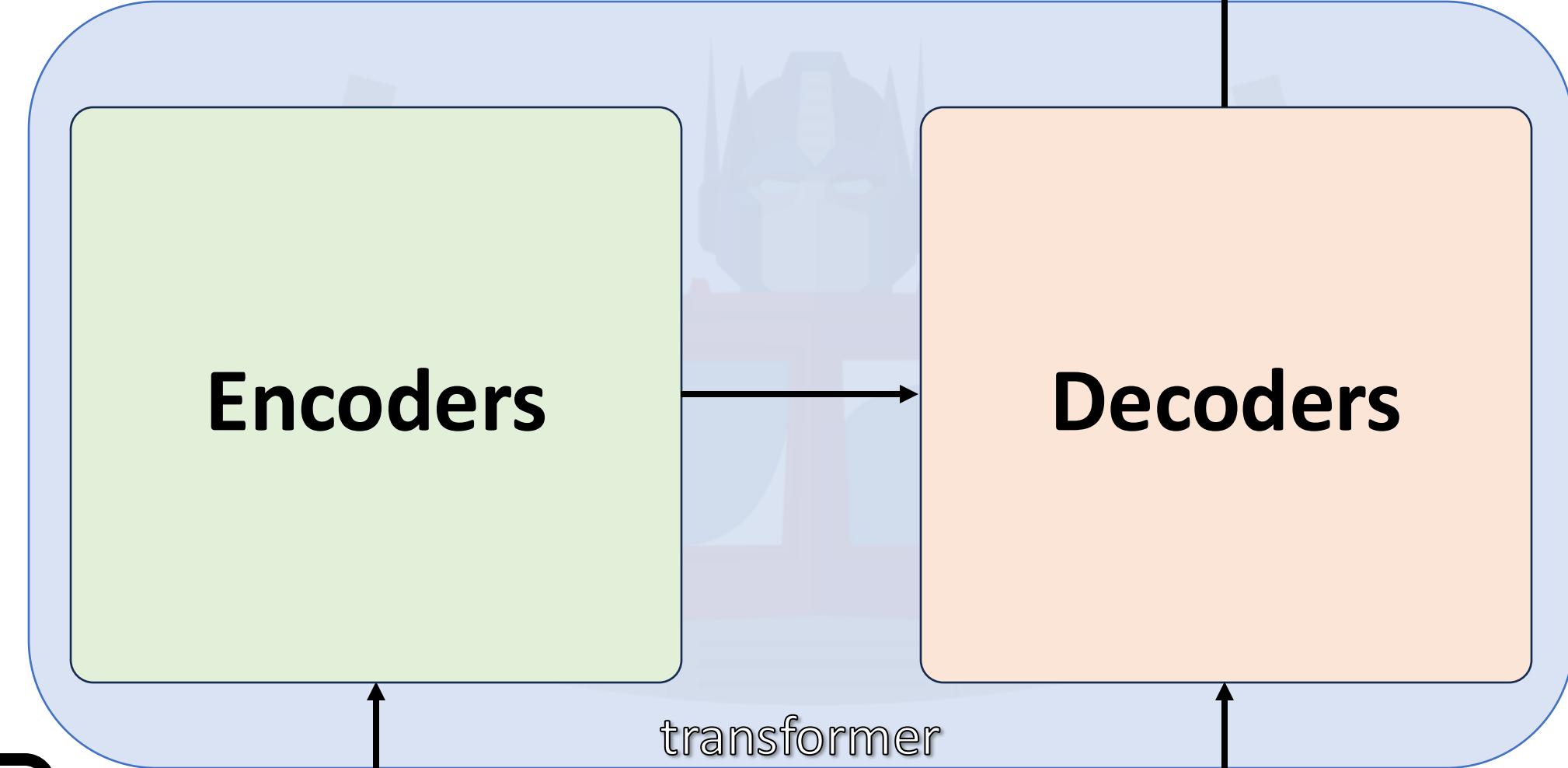
En

How are you?

transformer

<start> 你

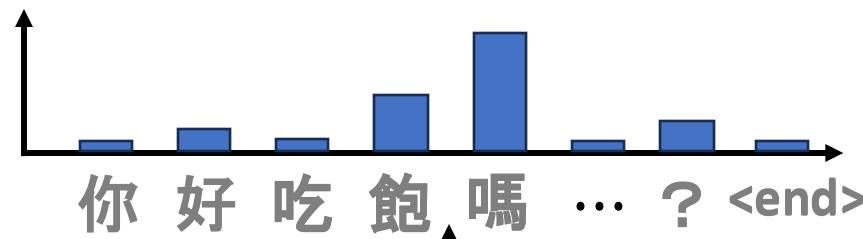
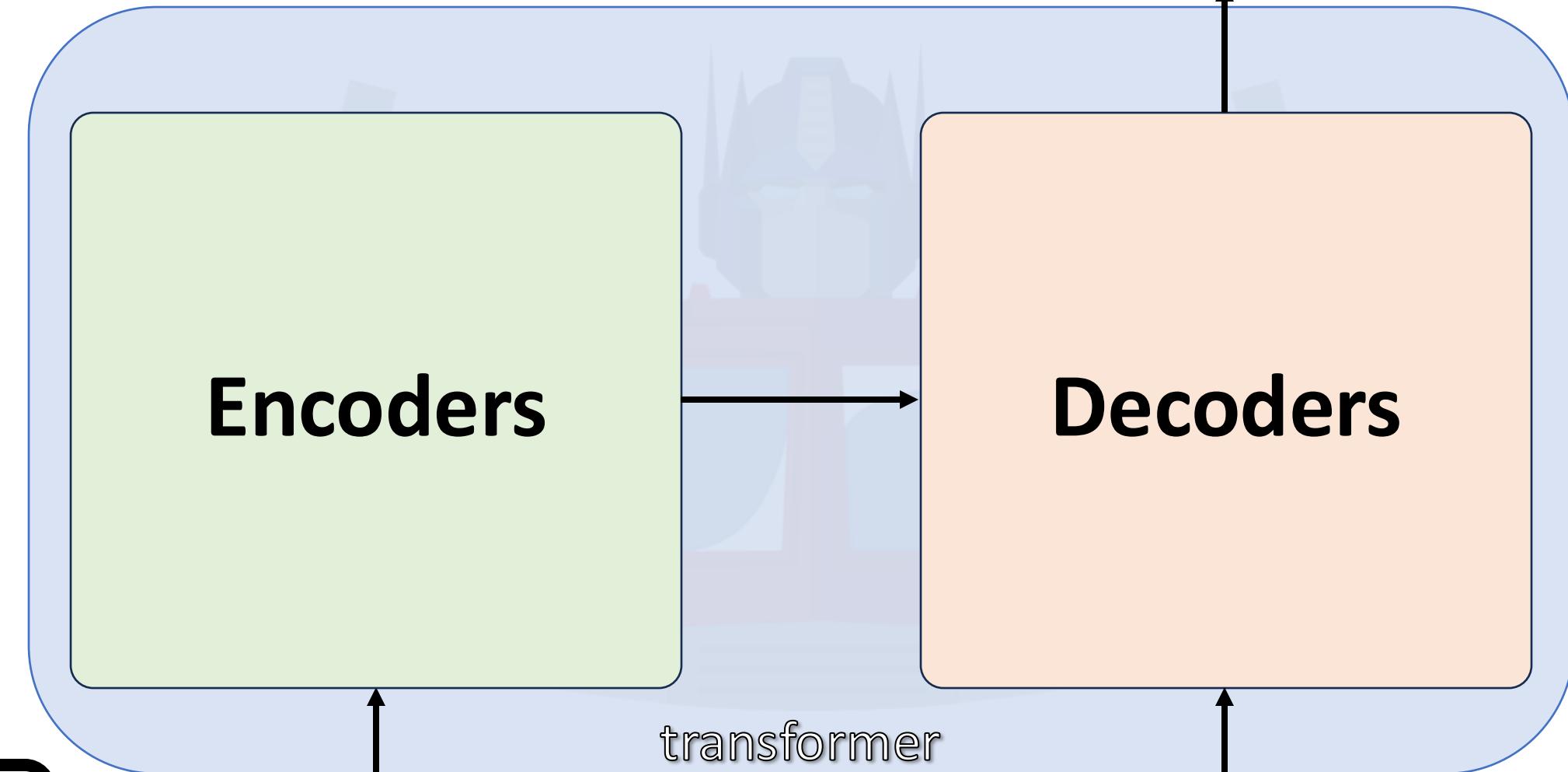
ZH



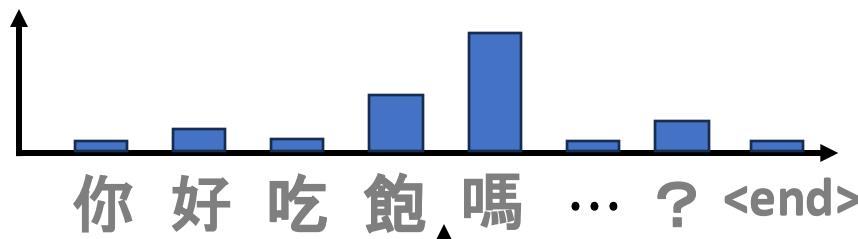
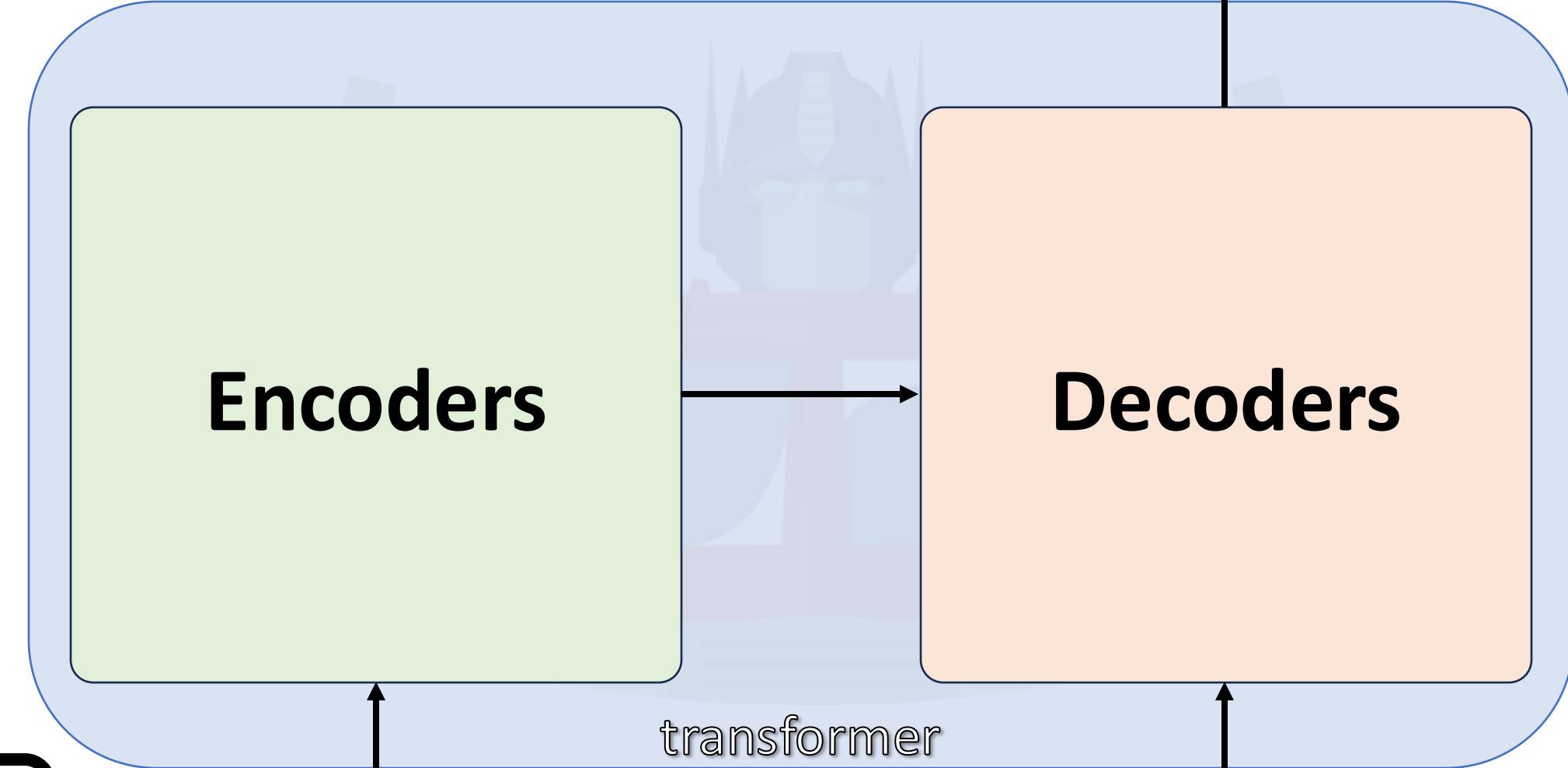
En

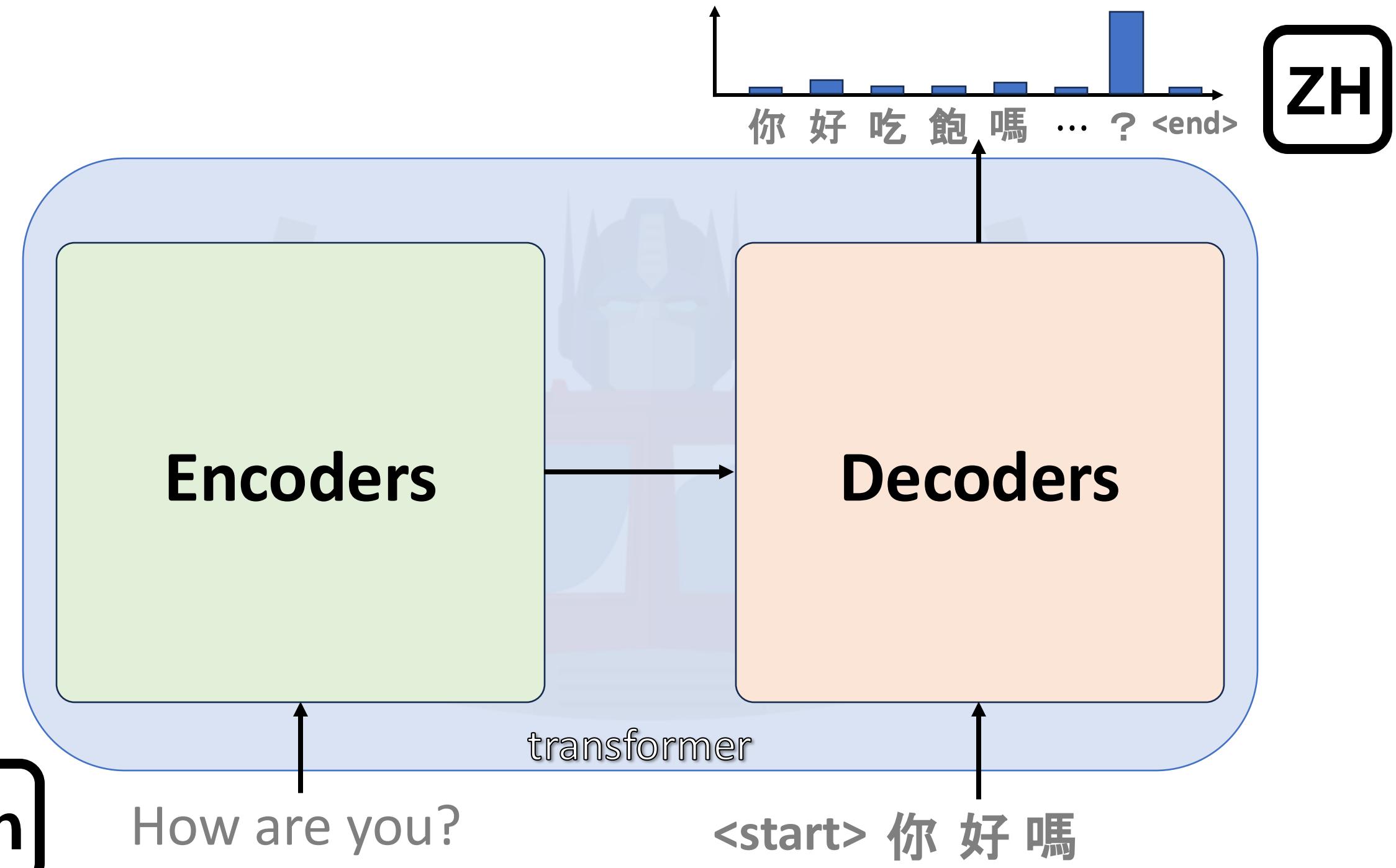
How are you?

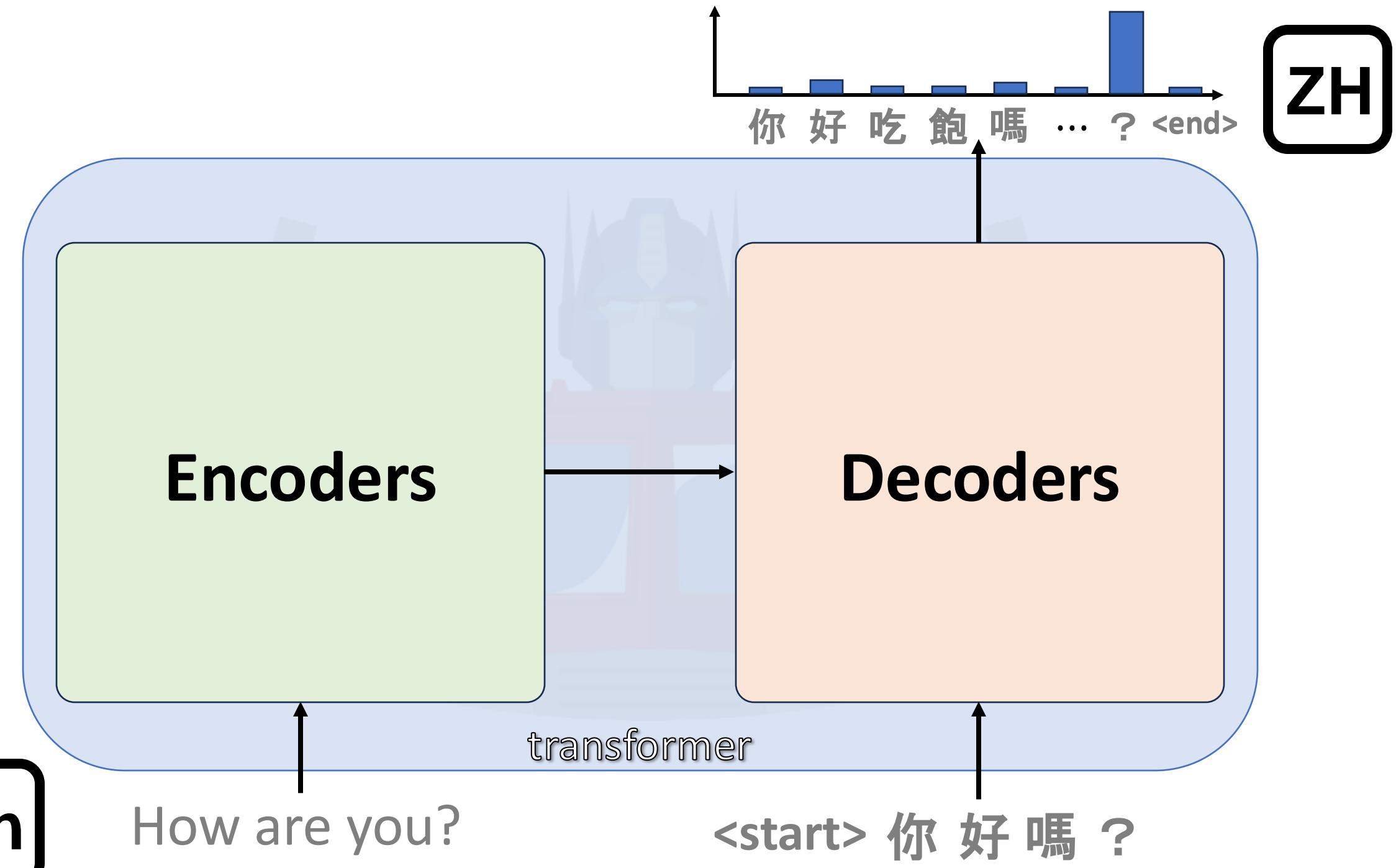
<start> 你好

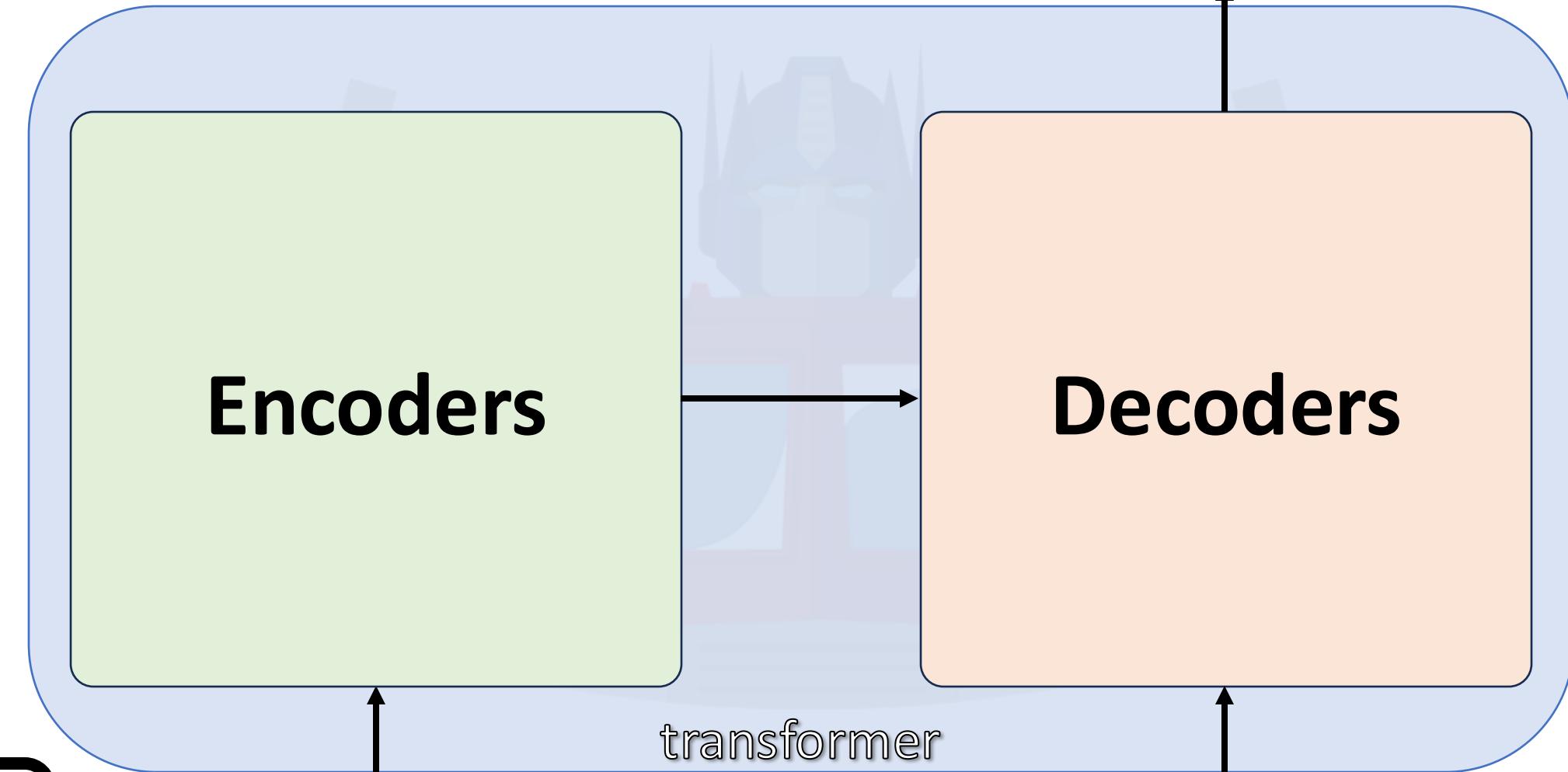


ZH









**En**

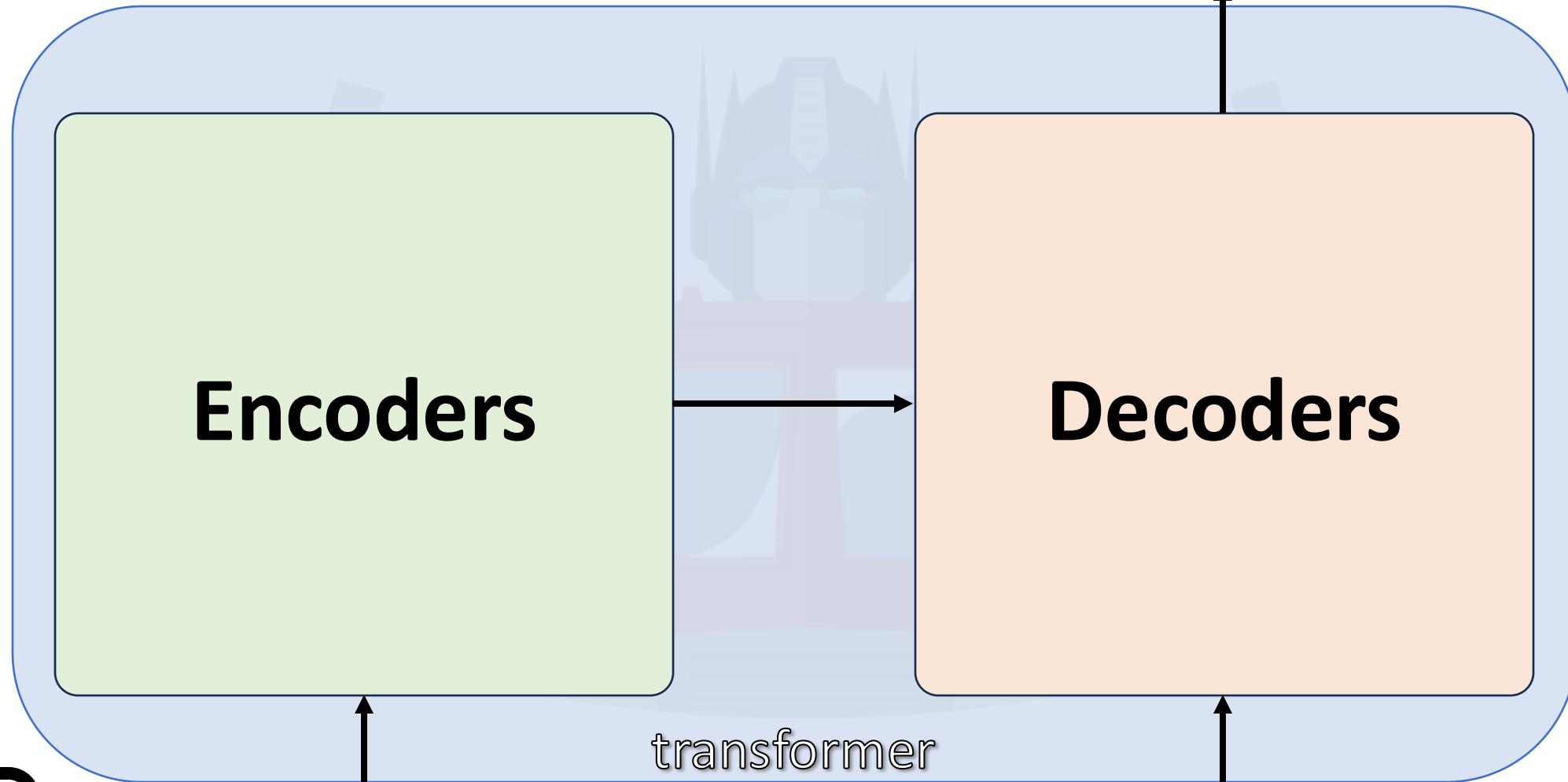
How are you?

transformer

<start> 你 好 嗎 ?

ZH

AuTo-regressive



En

How are you?

<start> 你 好 嗎 ? <end>

# Encoders



How are you?

# Tokenization

Many words map to one token, but some don't: **indivisible.**

8607	4339	2472	311	832	4037	11	719	1063	1541	956	25	3687	23936	13
------	------	------	-----	-----	------	----	-----	------	------	-----	----	------	-------	----



**One-hot encoding**

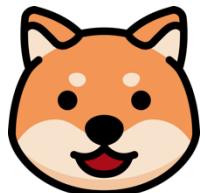
# tokens

	cat	dog	bear	cow	indiv
1	1	0	0	0	0
0	0	1	0	0	0
0	0	0	1	0	0
0	0	0	0	1	0
⋮	⋮	⋮	⋮	⋮	⋮
0	0	0	0	0	0

Value 1 at  
3687<sup>th</sup>  
entry

# TOKEN EMBEDDING

## One-hot encoding



cat

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

dog

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

bear

$$\begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

cow

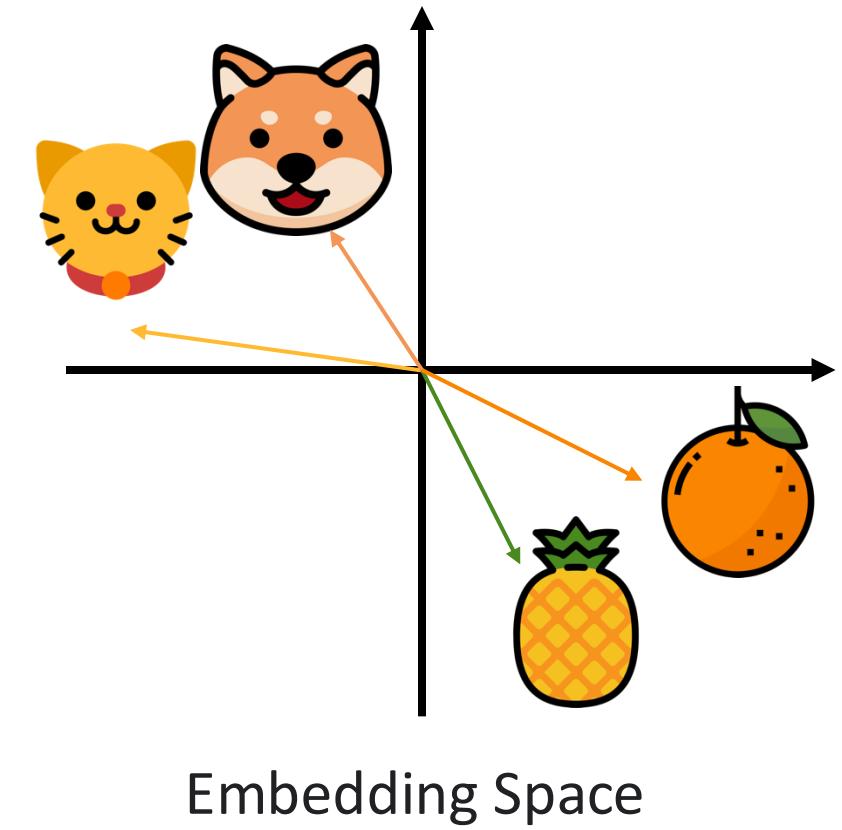
$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

indiv

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Value 1 at  
3687<sup>th</sup>  
entry

# TOKEN EMBEDDING



cat

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

dog

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

bear

$$\begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

cow

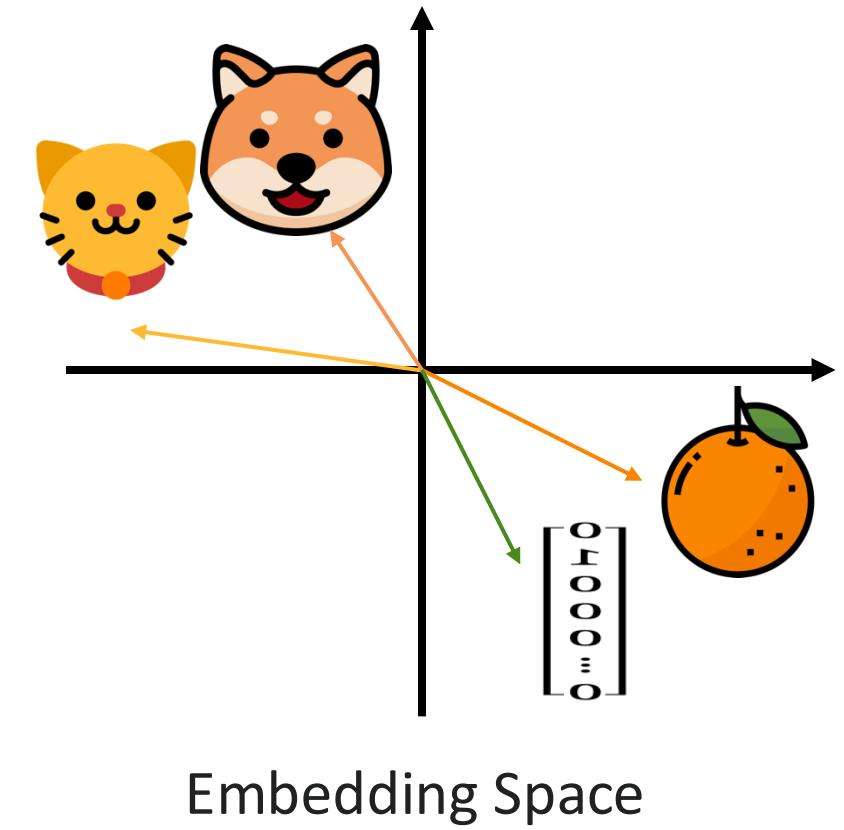
$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

indiv

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Value 1 at  
3687<sup>th</sup>  
entry

# TOKEN EMBEDDING



$$\text{Embedded token} = \text{# tokens} \times \text{Embedding Matrix}$$

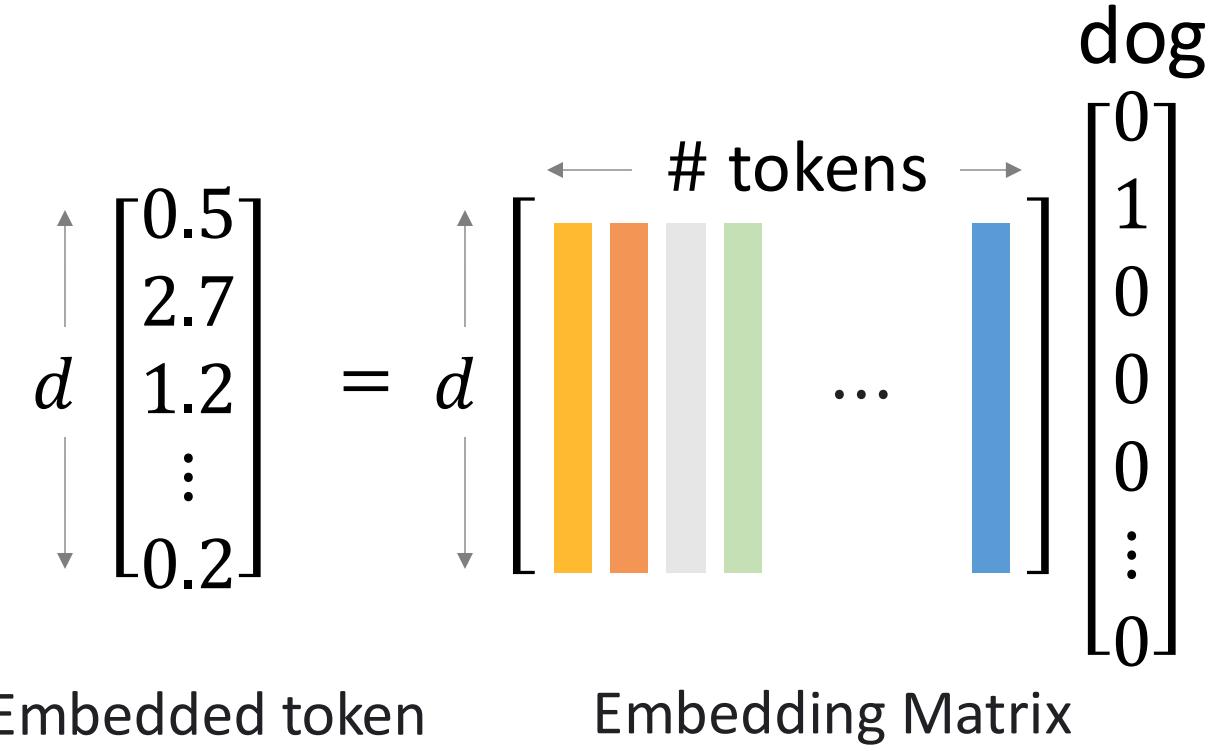
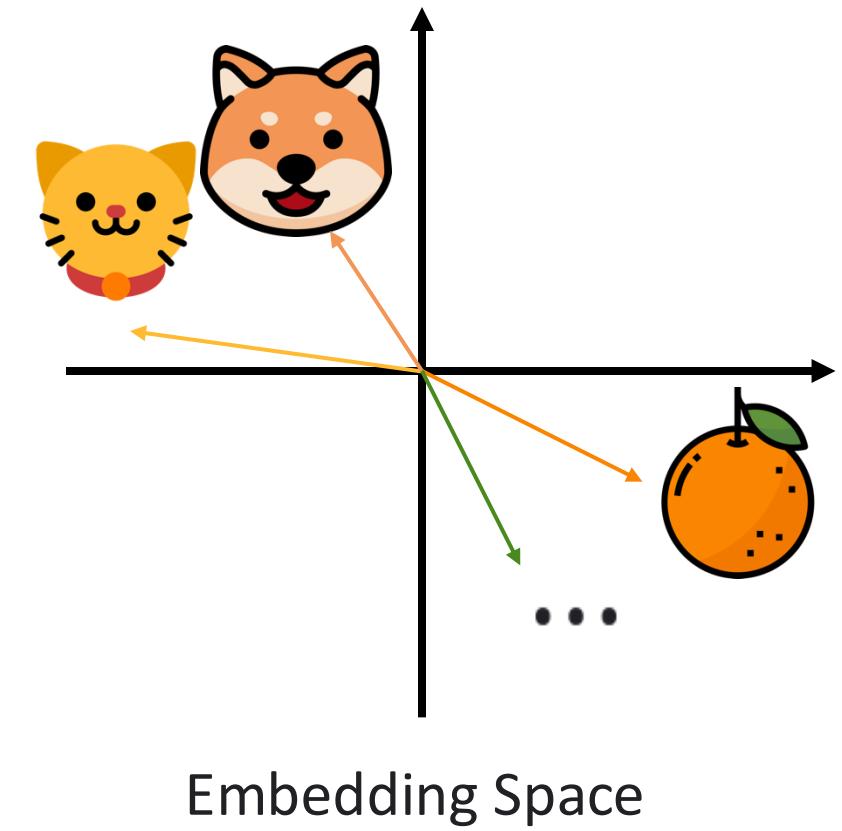
The diagram illustrates the relationship between an embedded token and an embedding matrix. On the left, a vertical vector of dimension  $d$  is labeled "Embedded token". In the center, an equals sign is followed by a multiplication operation. The first factor is a vertical vector of dimension  $d$ , with values 0.5, 2.7, 1.2, and 0.2. The second factor is a large bold letter  $W_E$ , representing the "Embedding Matrix". The third factor is a vertical vector of dimension  $d$  with values 0, 1, 0, 0, 0, and 0, labeled "dog". Above the central multiplication, an arrow points from the label "# tokens" to the bold letter  $W_E$ .

Embedded token

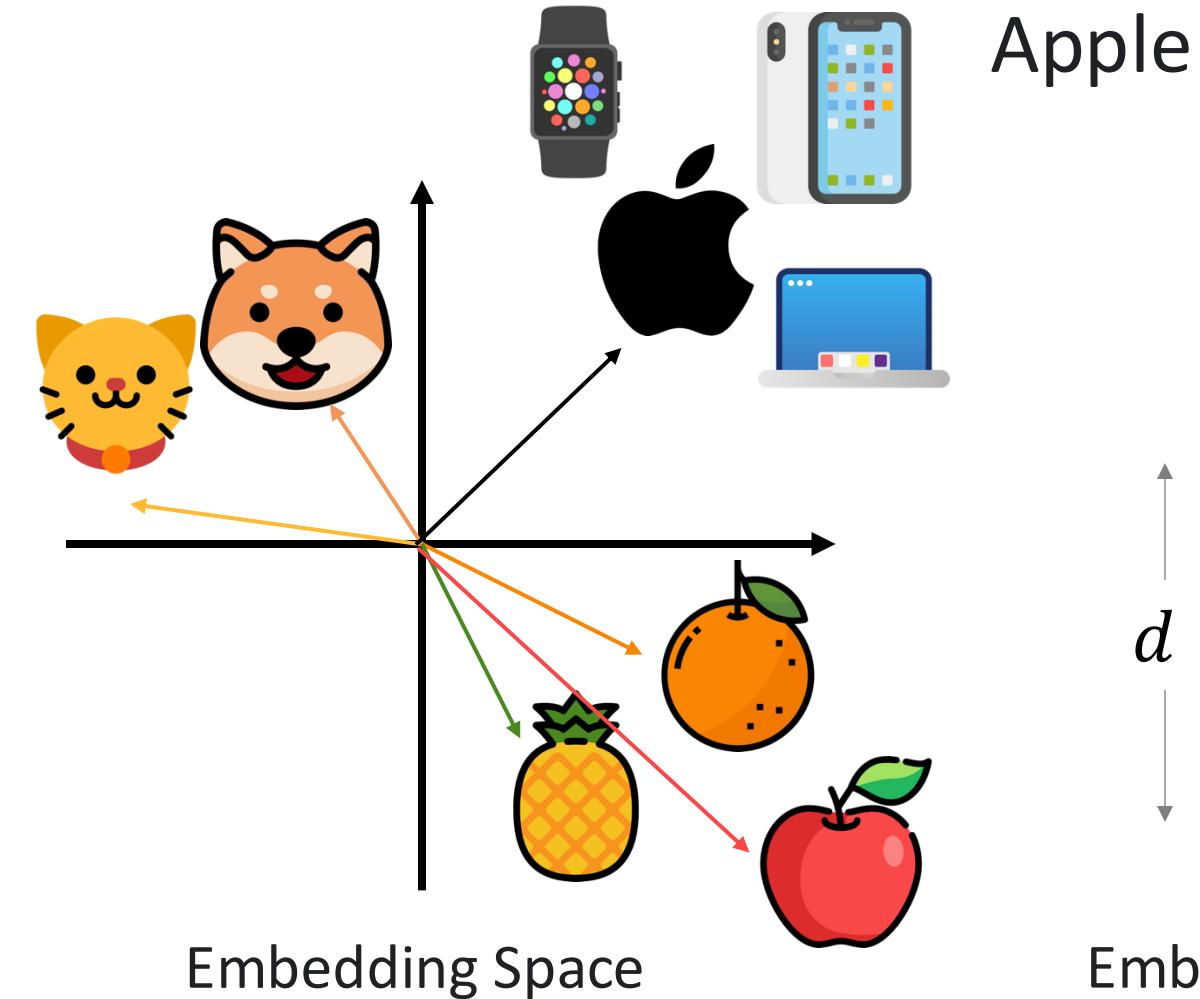
# tokens

Embedding Matrix

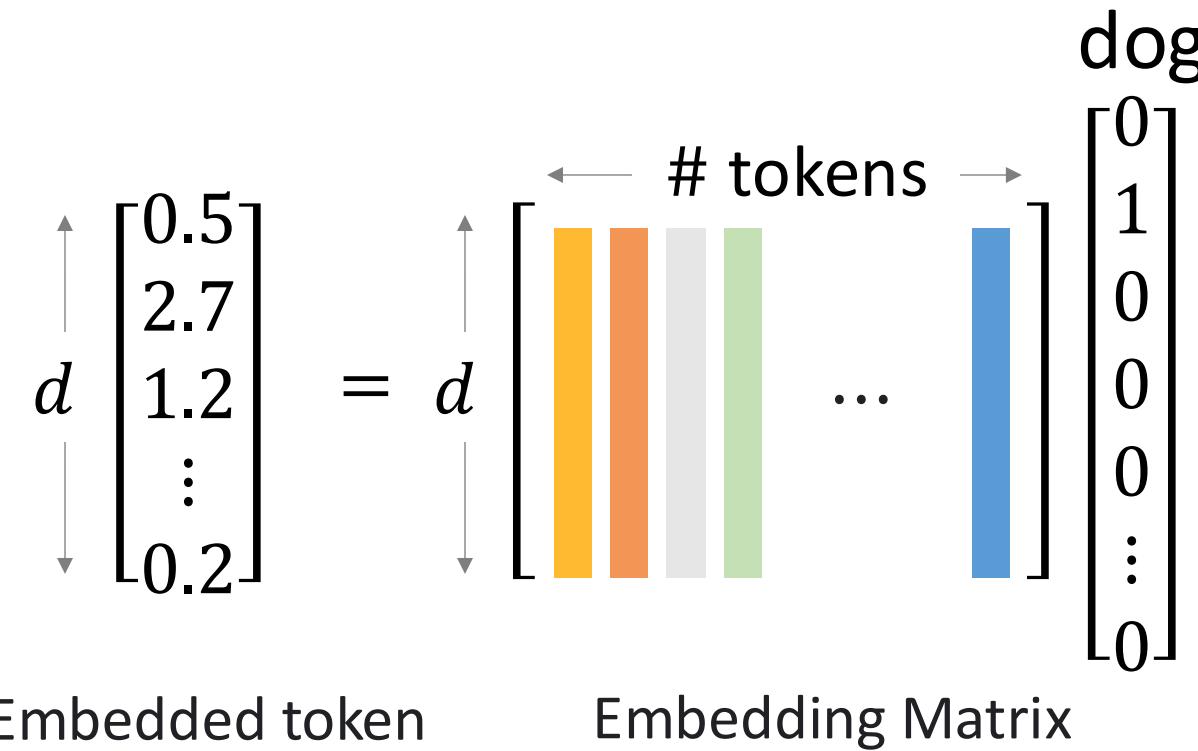
# TOKEN EMBEDDING



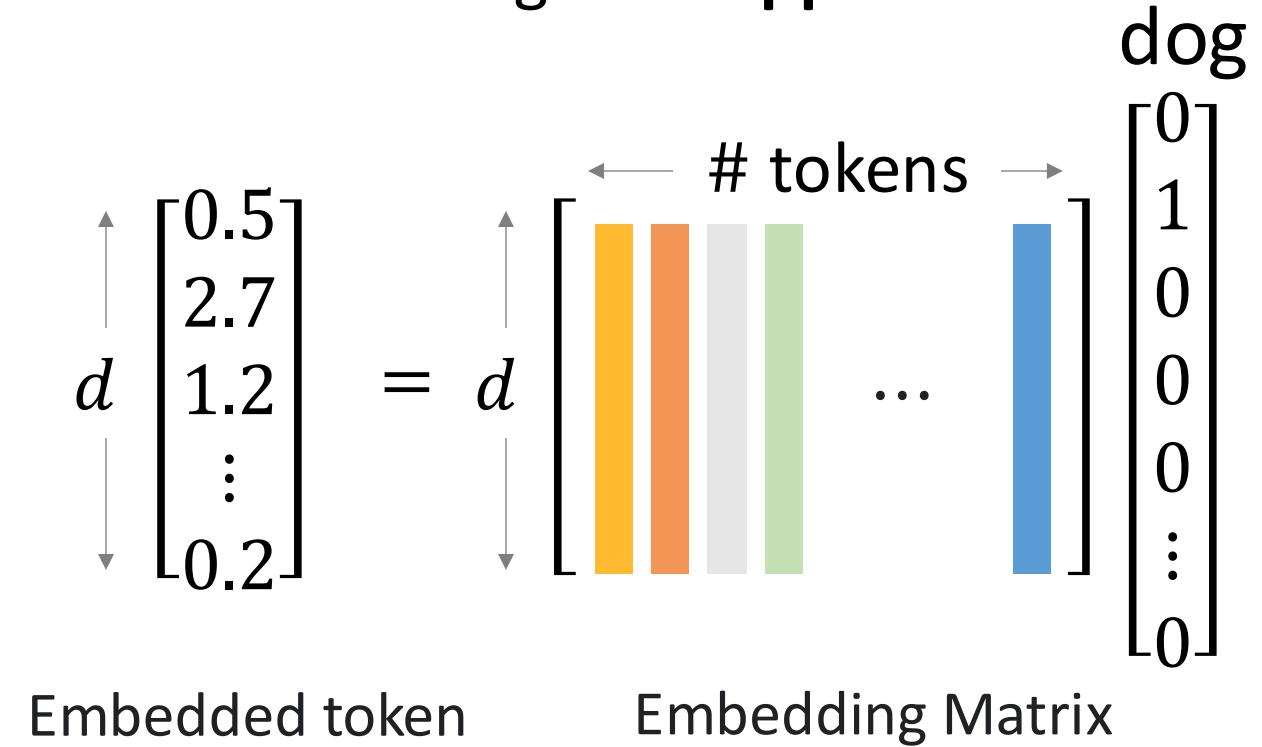
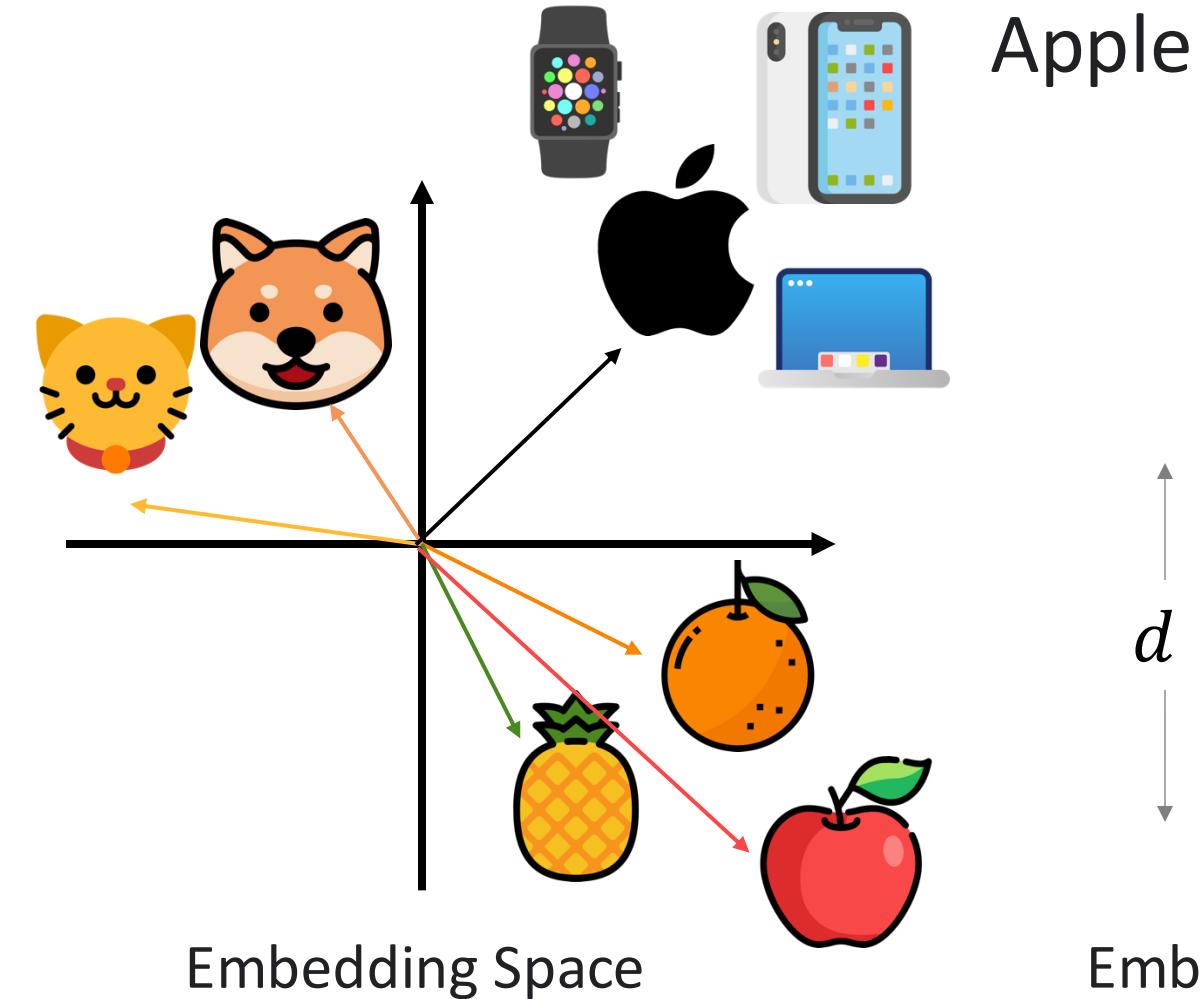
# TOKEN EMBEDDING

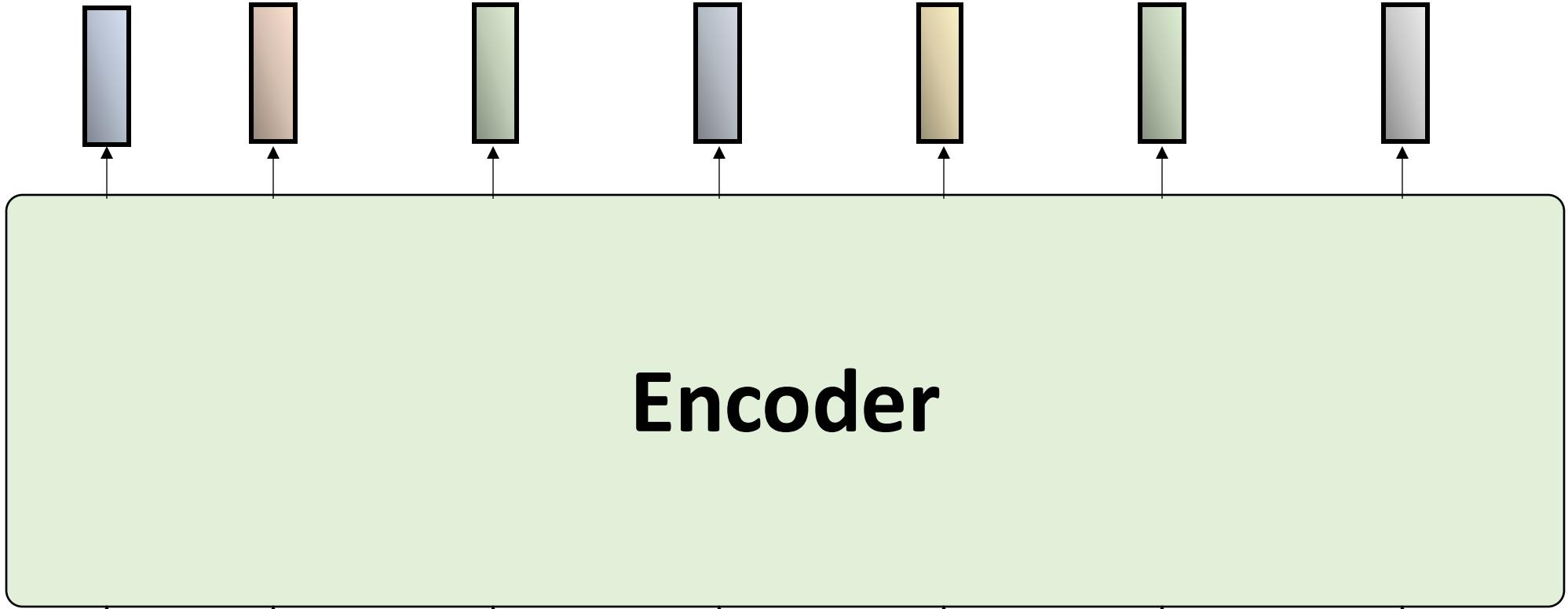


Apple



## TOKEN EMBEDDING

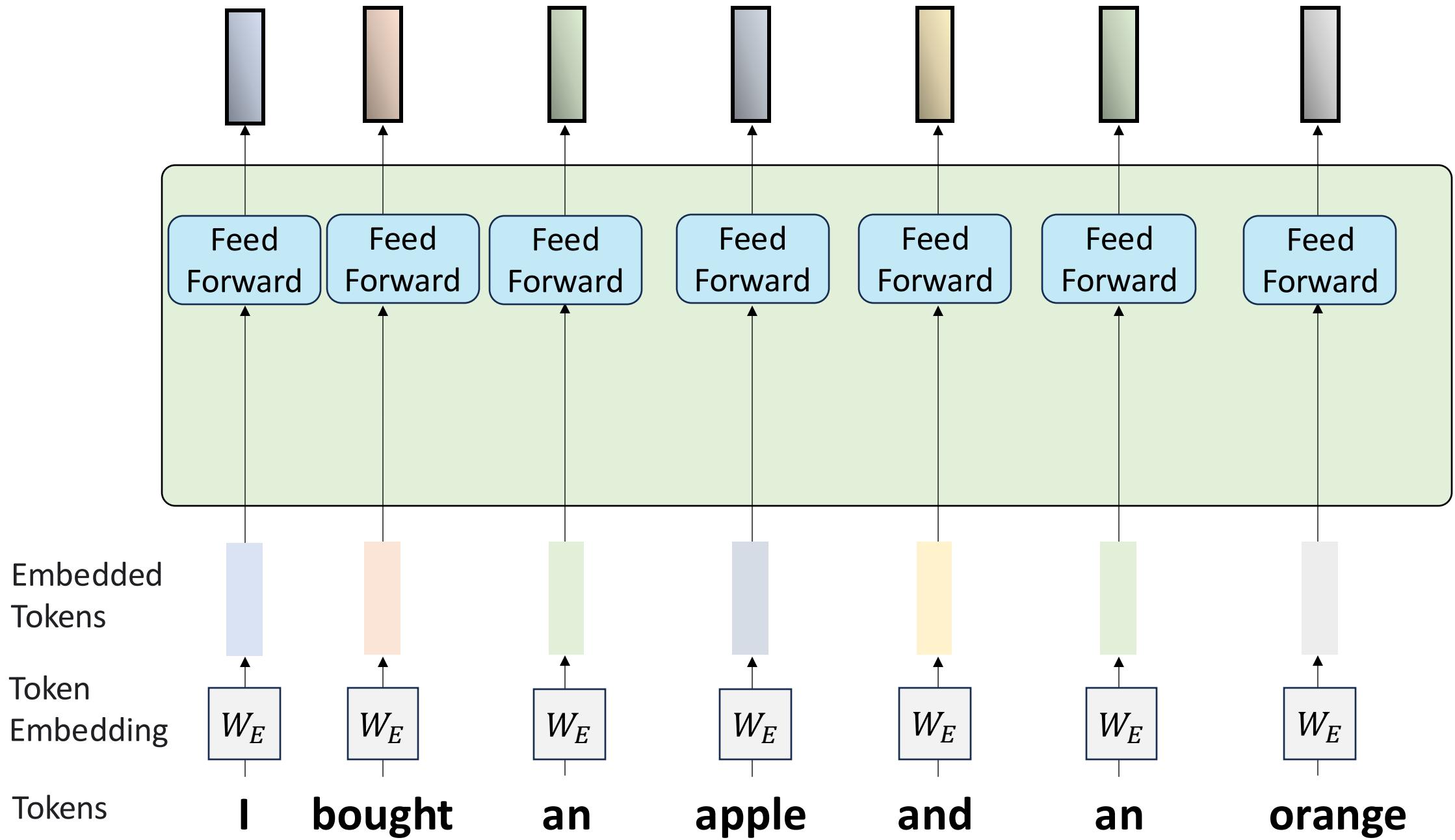


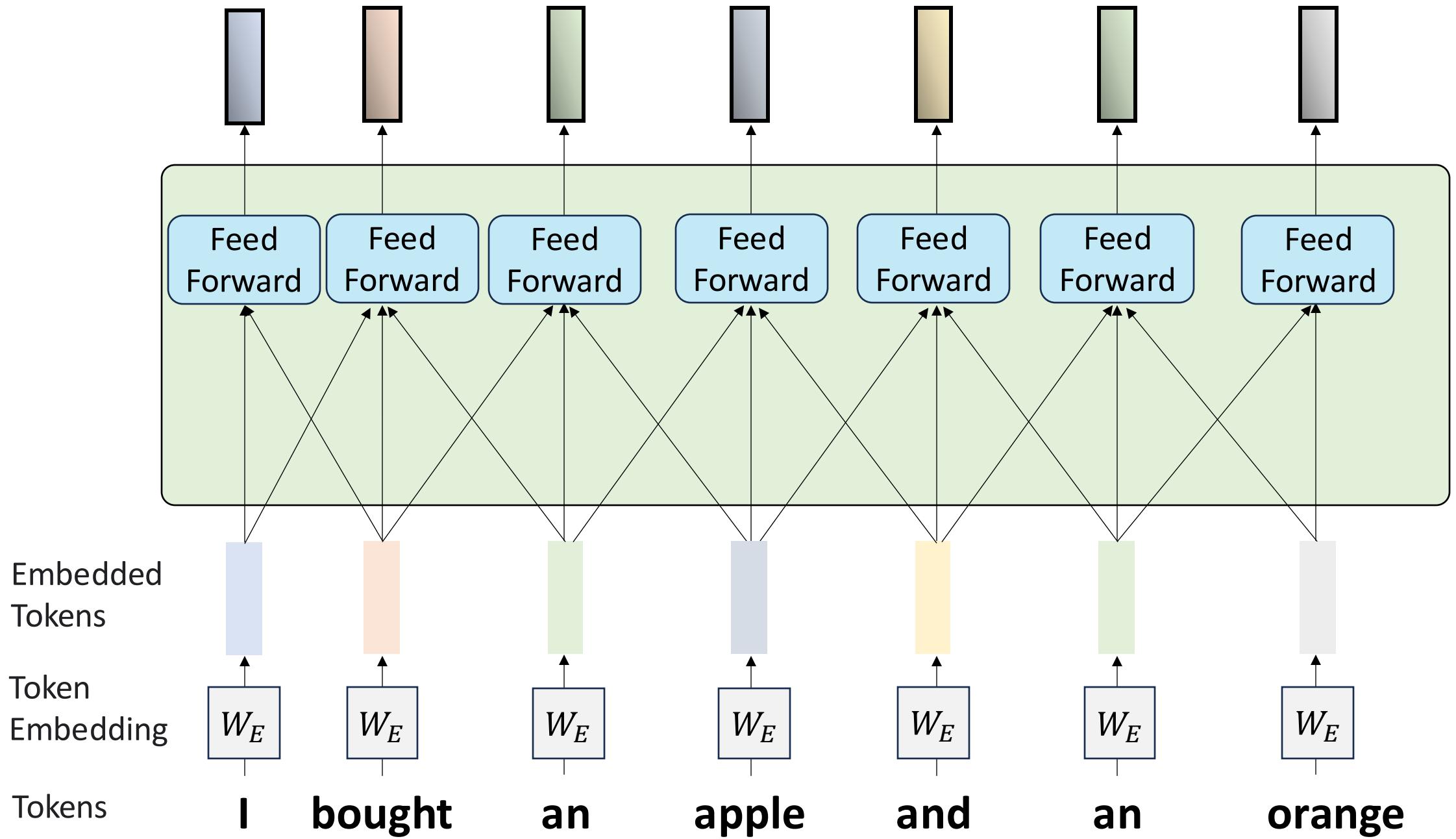


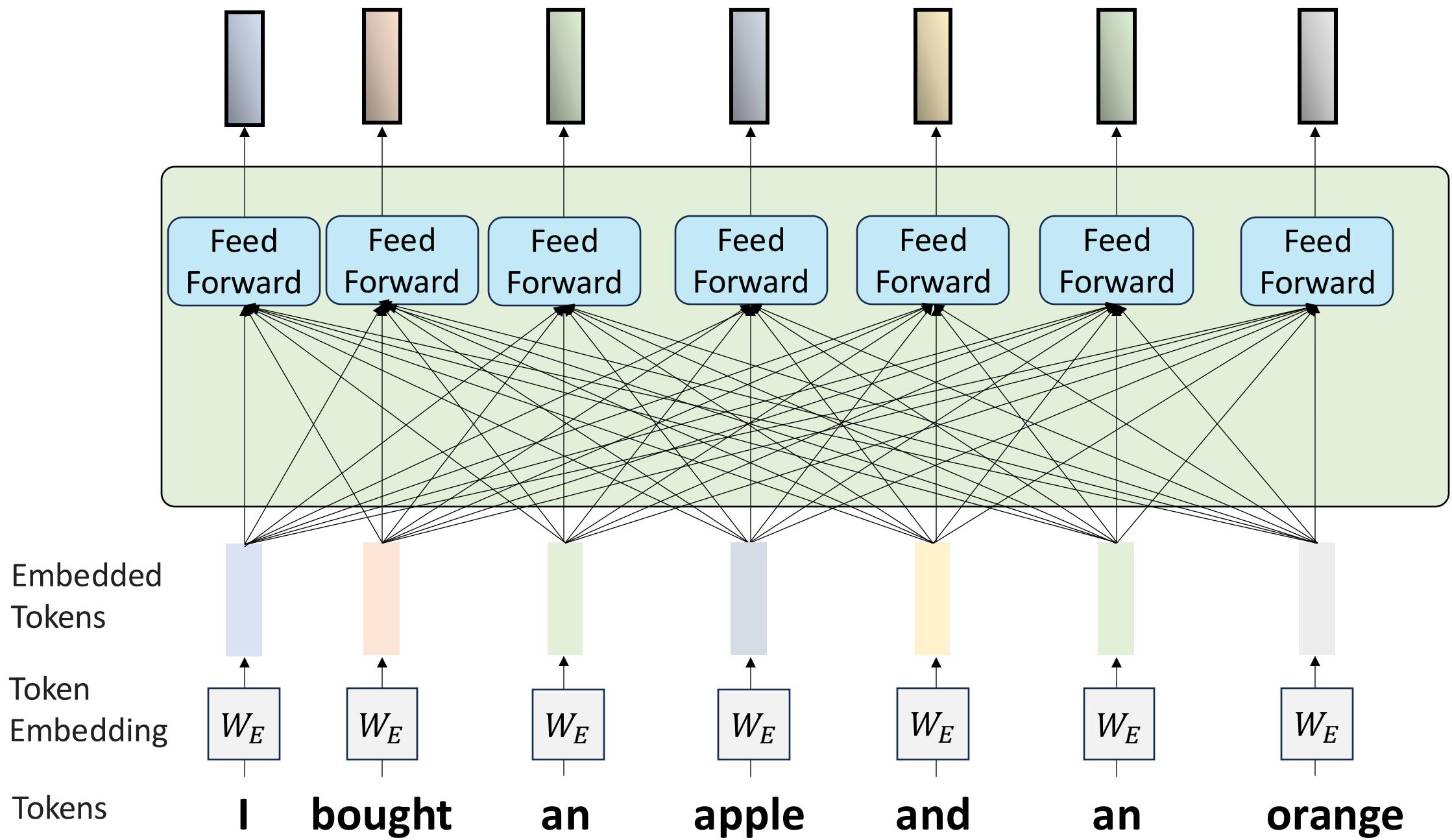
Embedded  
Tokens

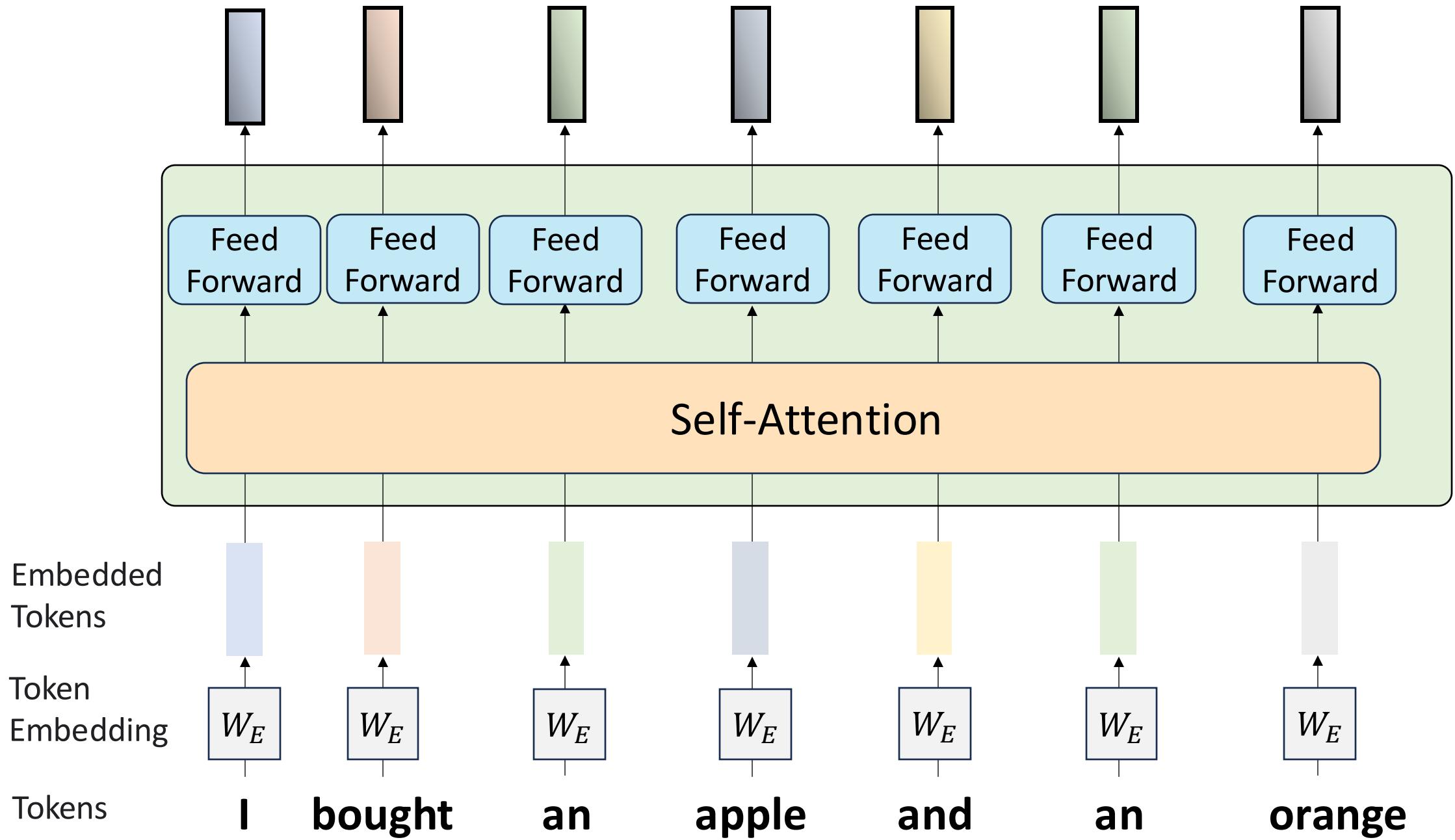
Token  
Embedding

Tokens      I    bought    an    apple    and    an    orange

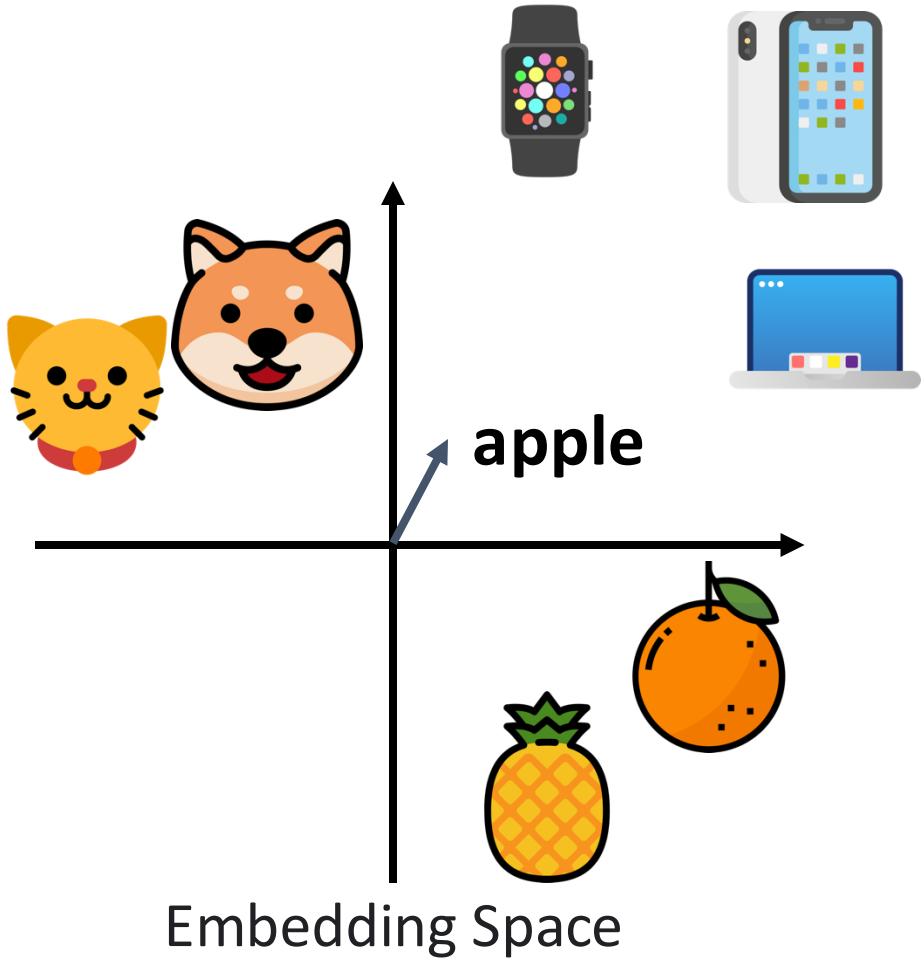








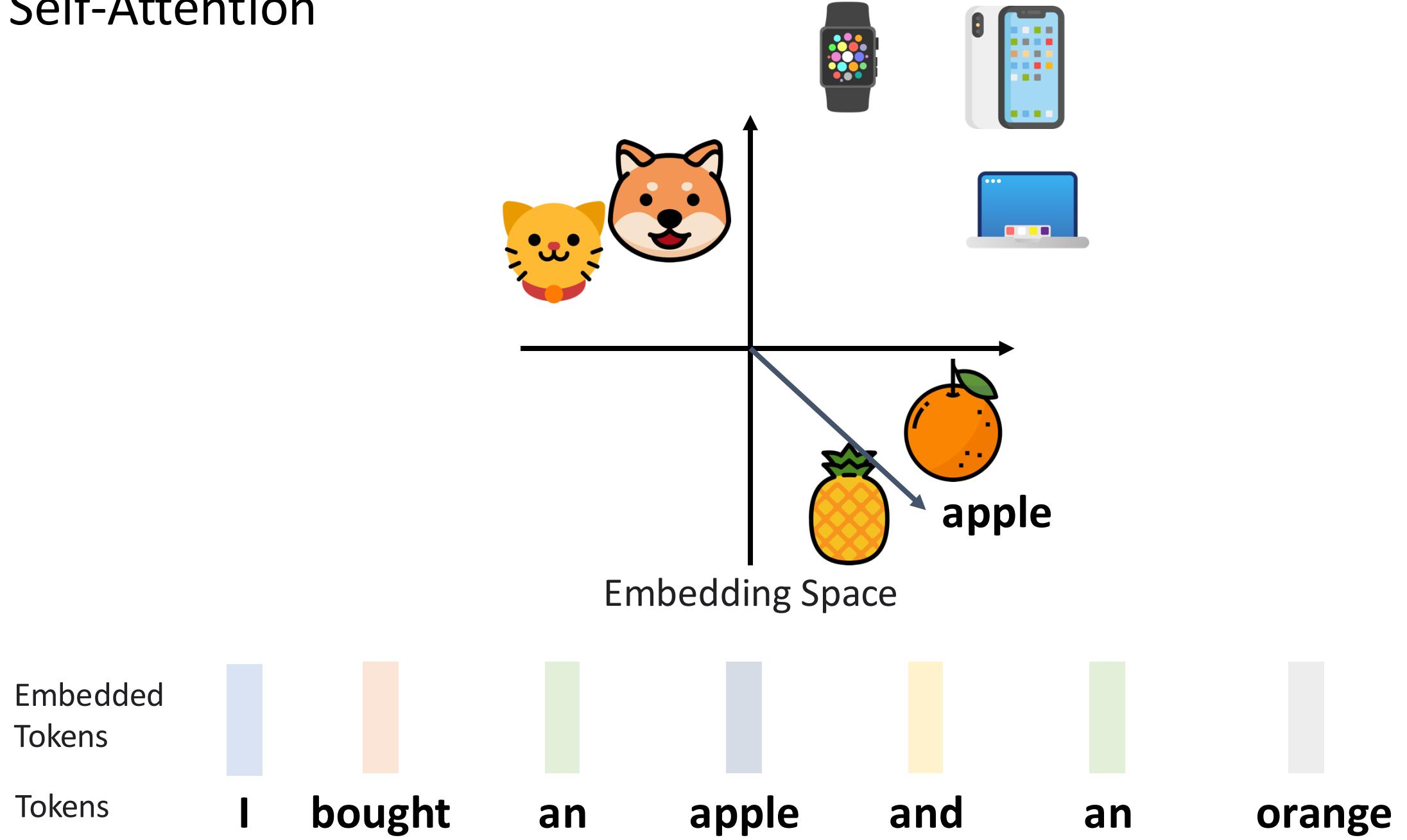
# Self-Attention



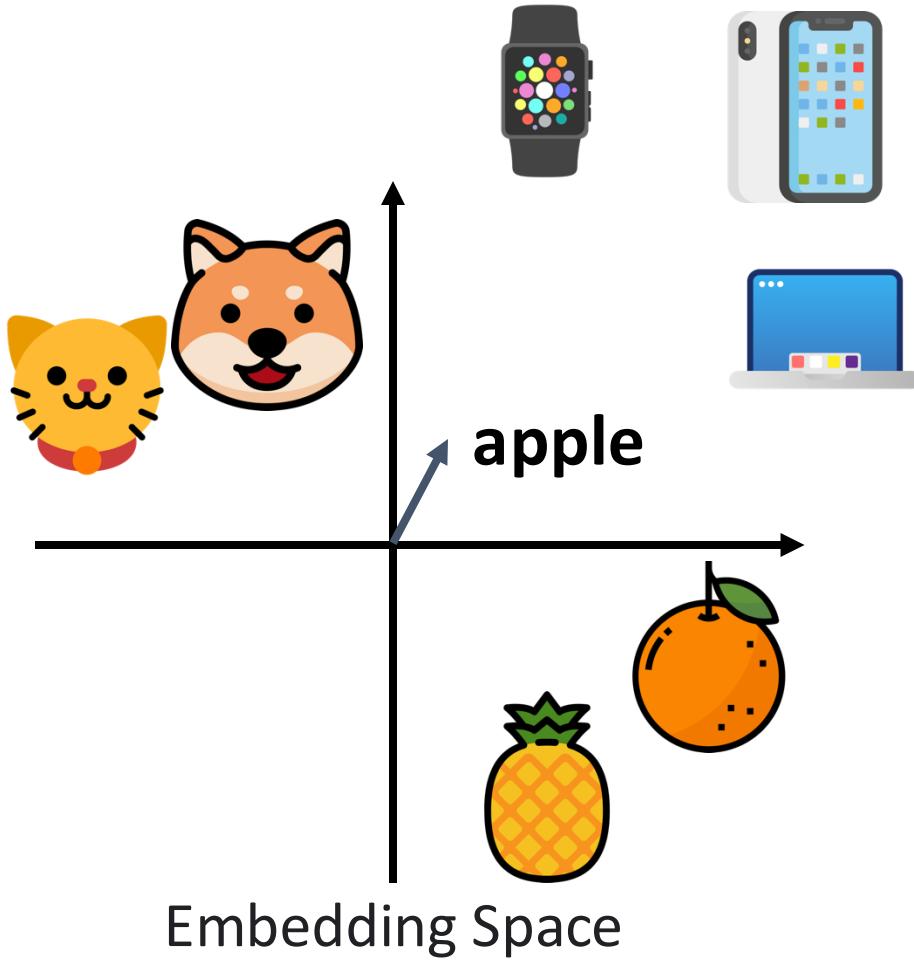
Embedded  
Tokens

Tokens      I      bought      an      apple      and      an      orange

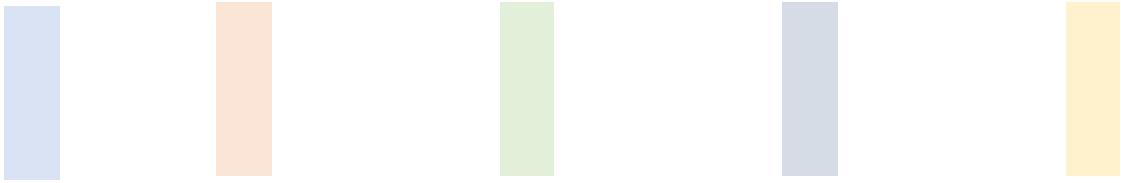
# Self-Attention



# Self-Attention



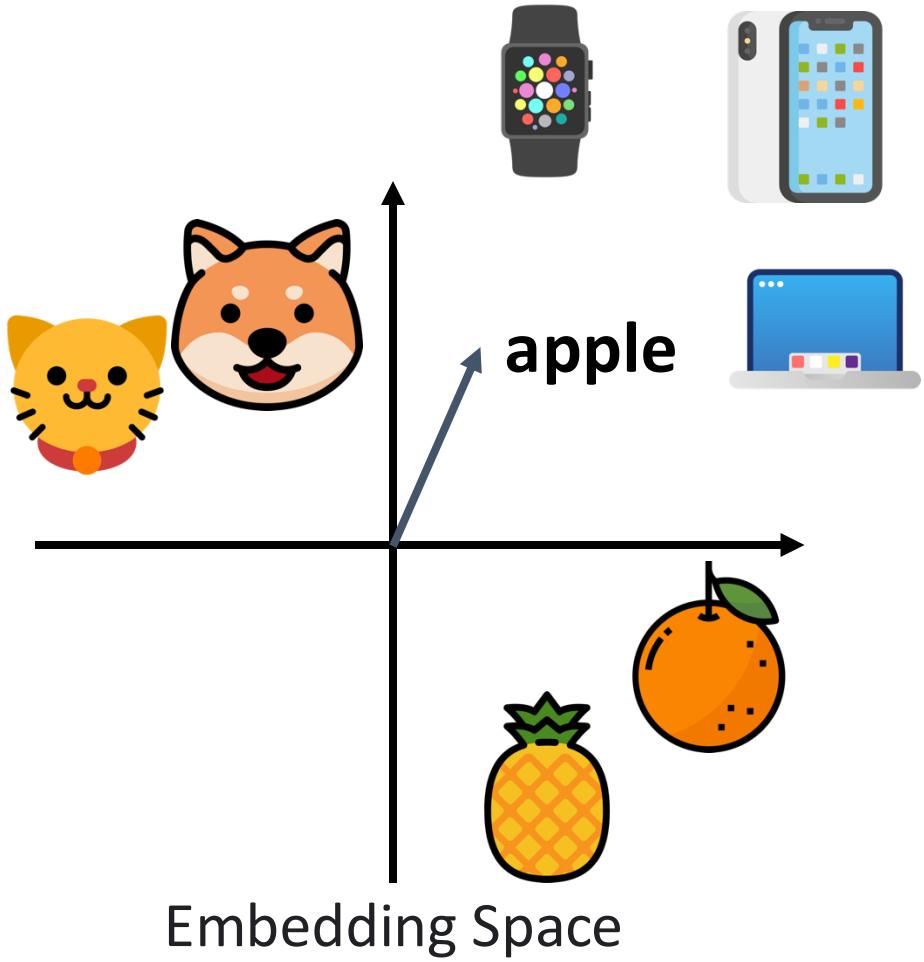
Embedded  
Tokens



Tokens

I    bought    an    apple    watch

# Self-Attention



Embedded  
Tokens

Tokens



I



bought



an

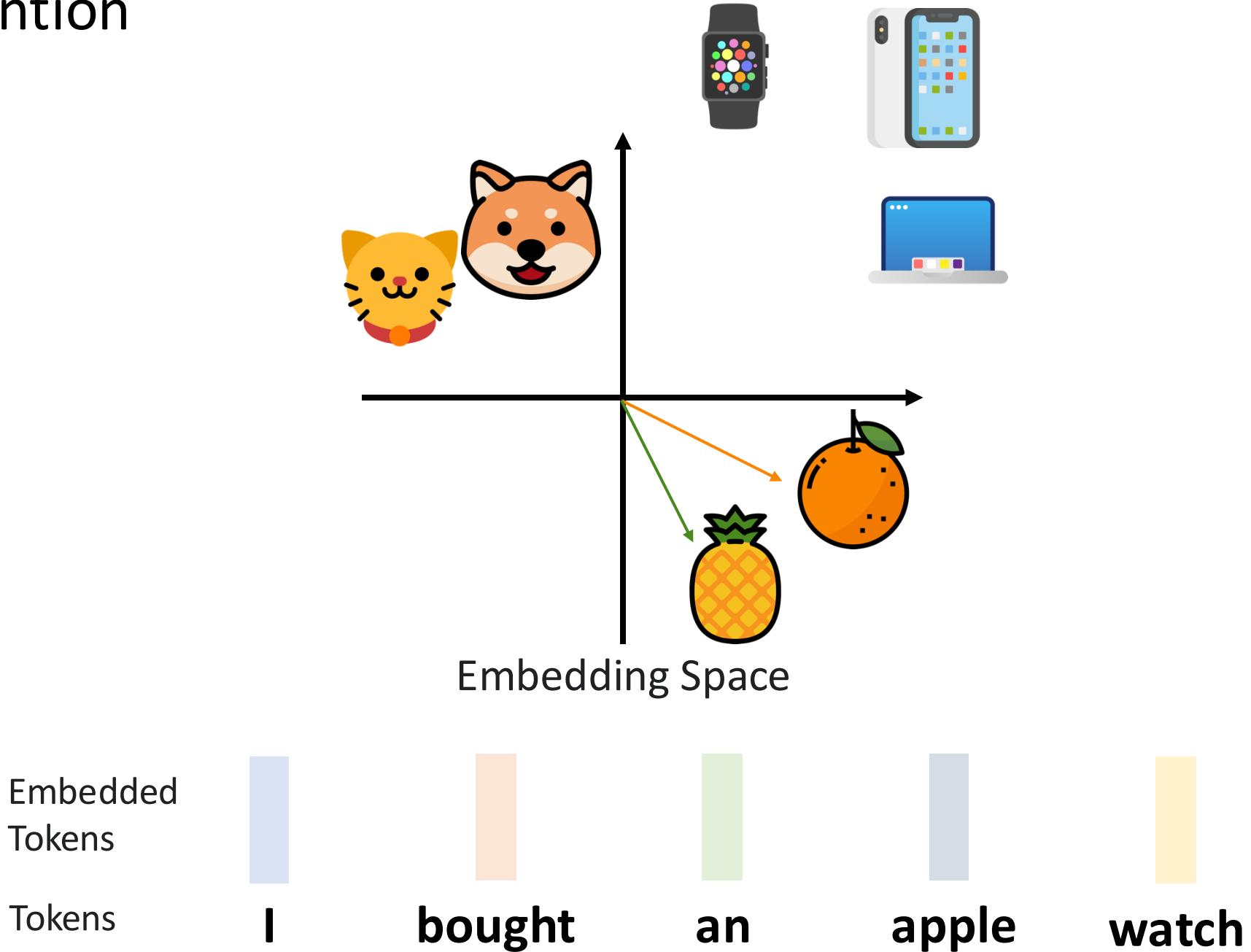


apple

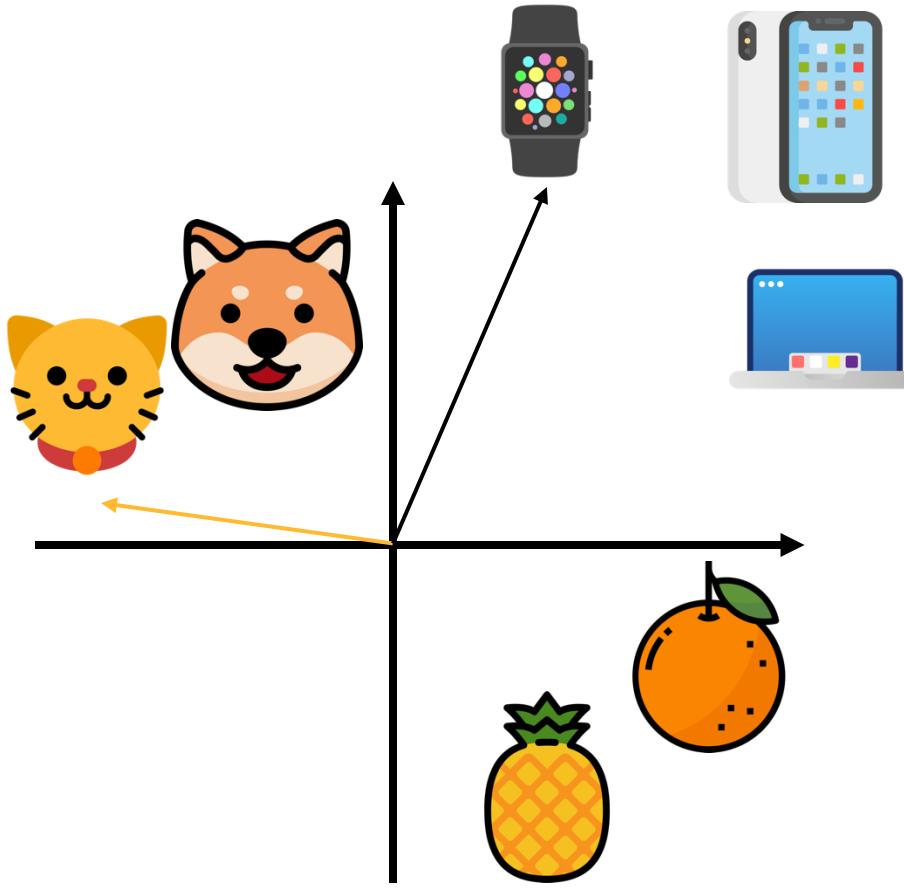


watch

# Self-Attention



# Self-Attention



Embedded  
Tokens

Tokens

I

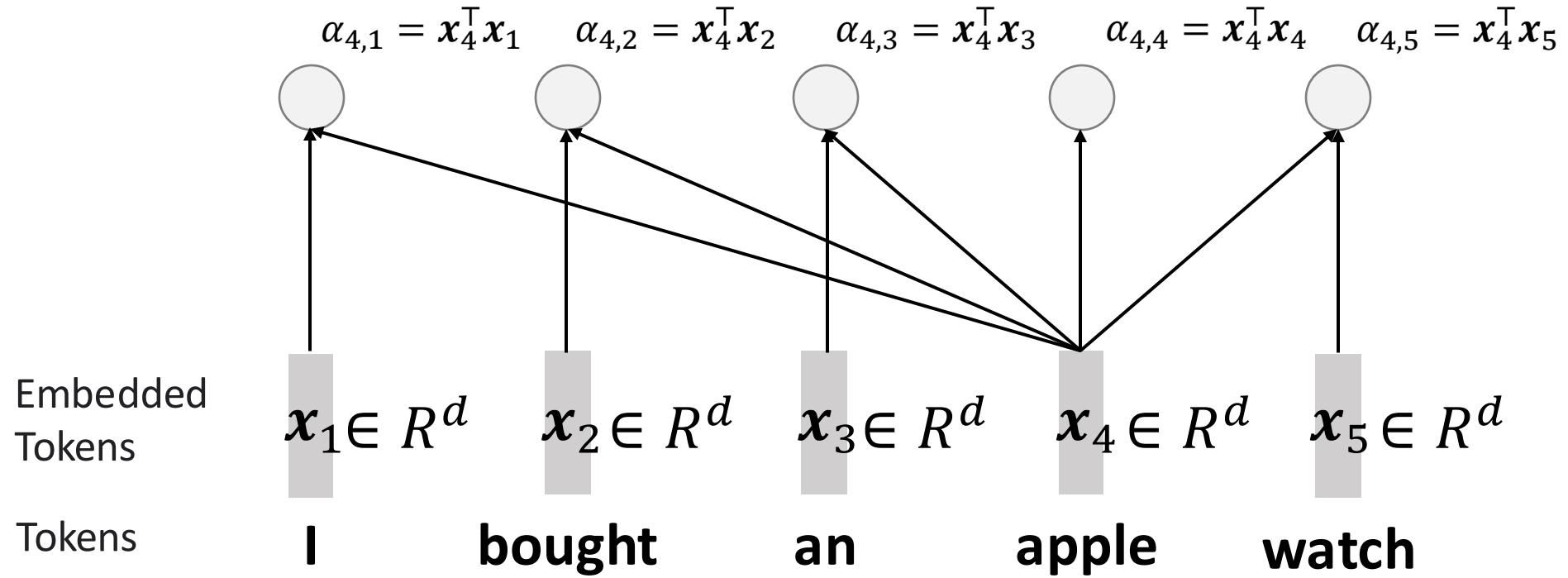
bought

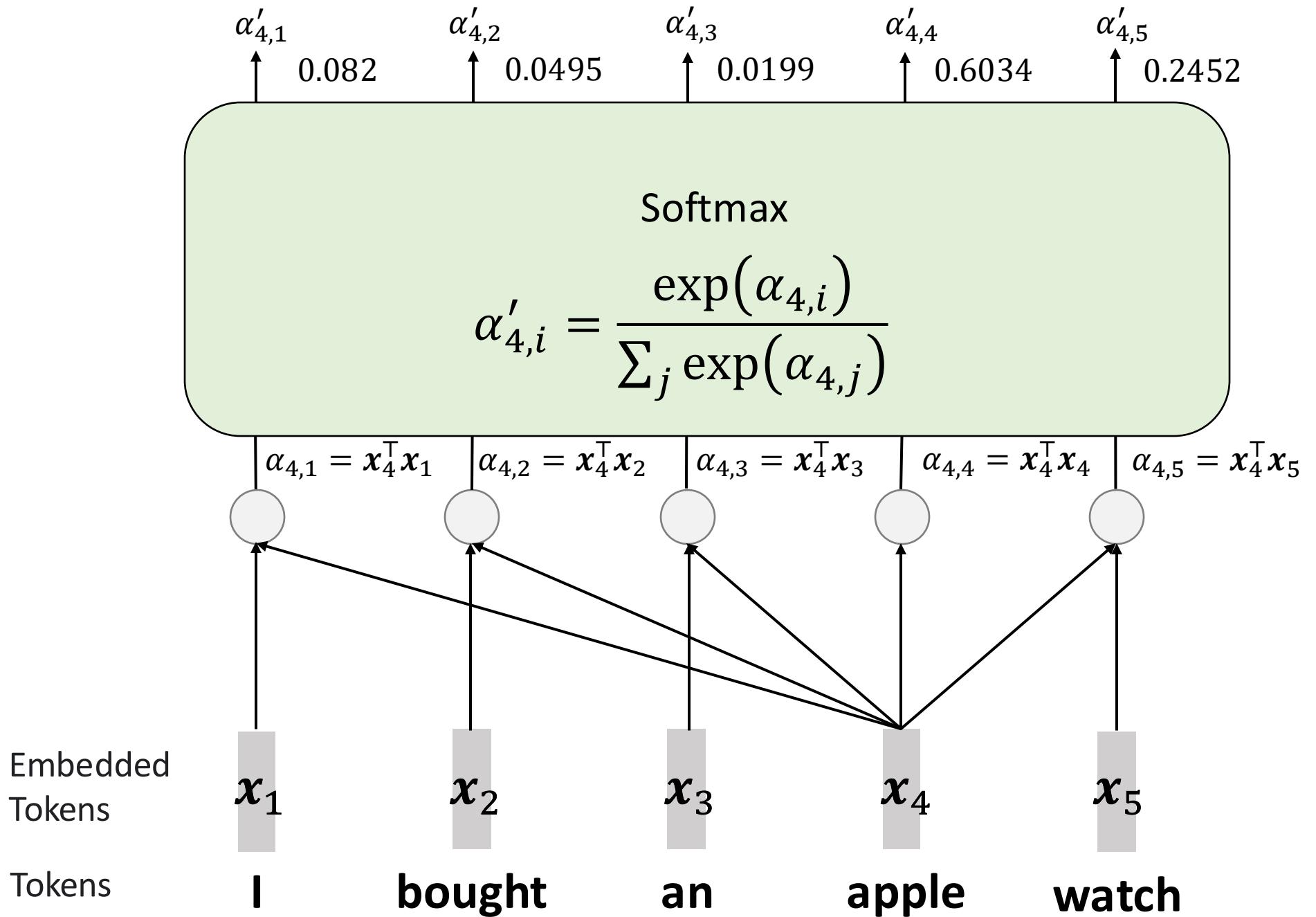
an

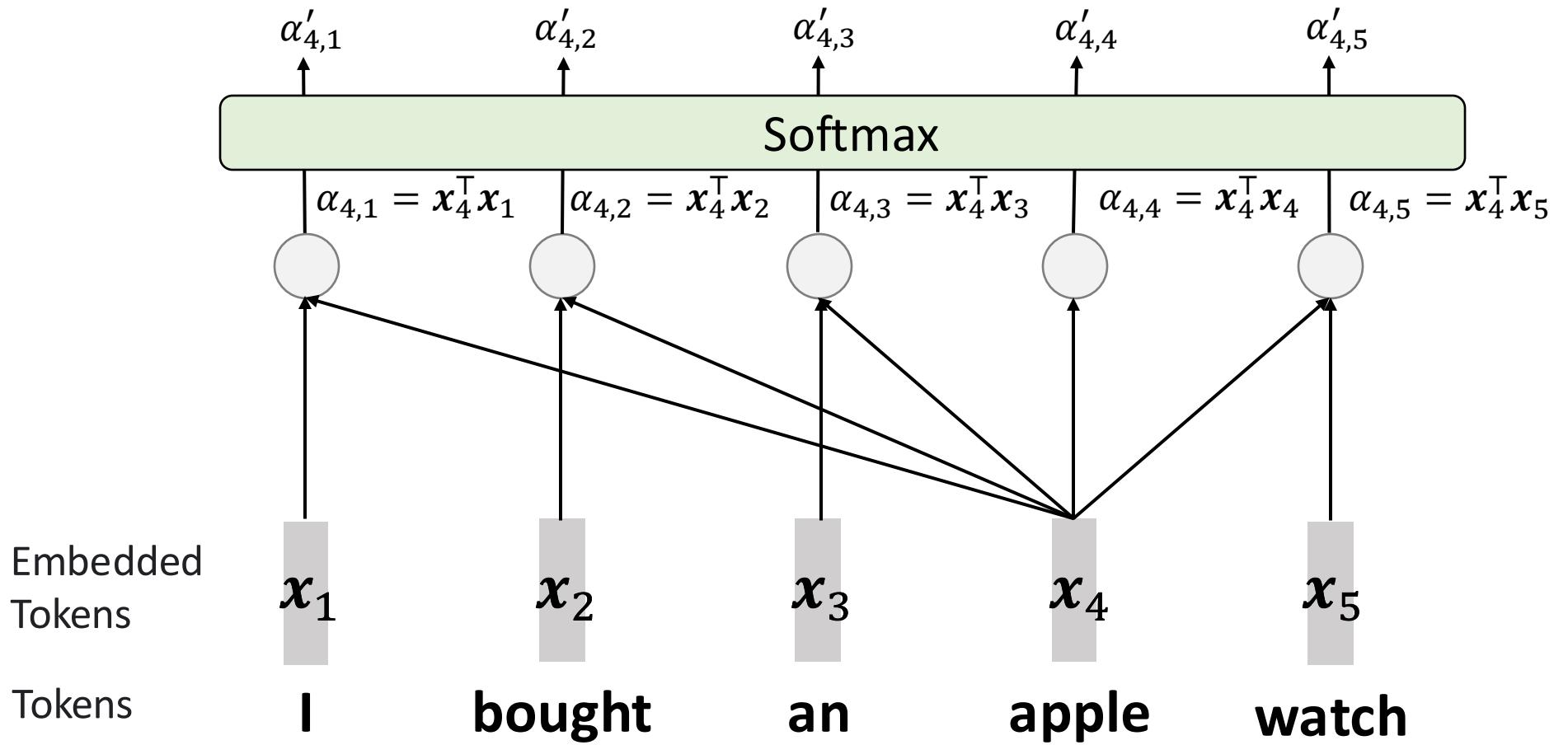
apple

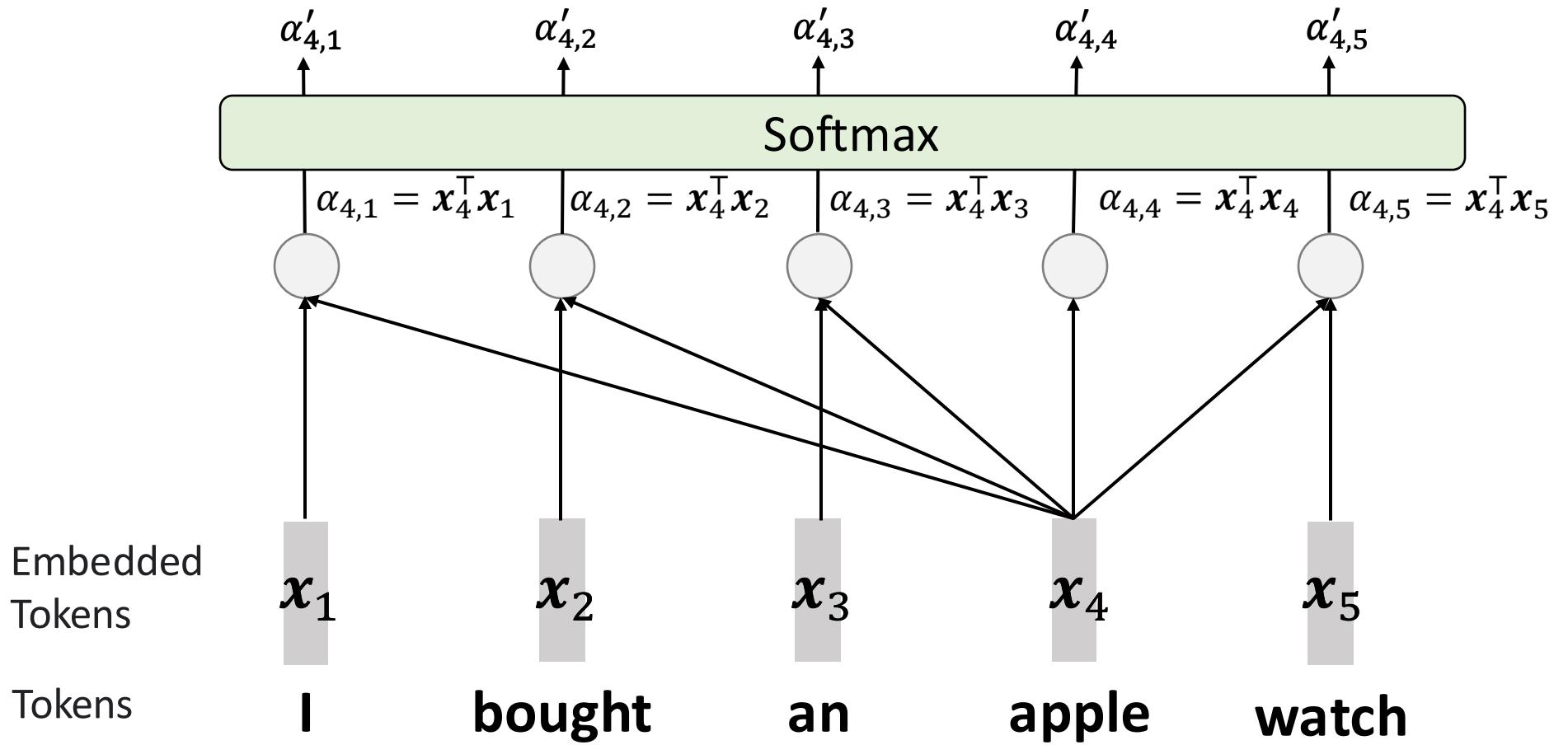
watch

# Self-Attention

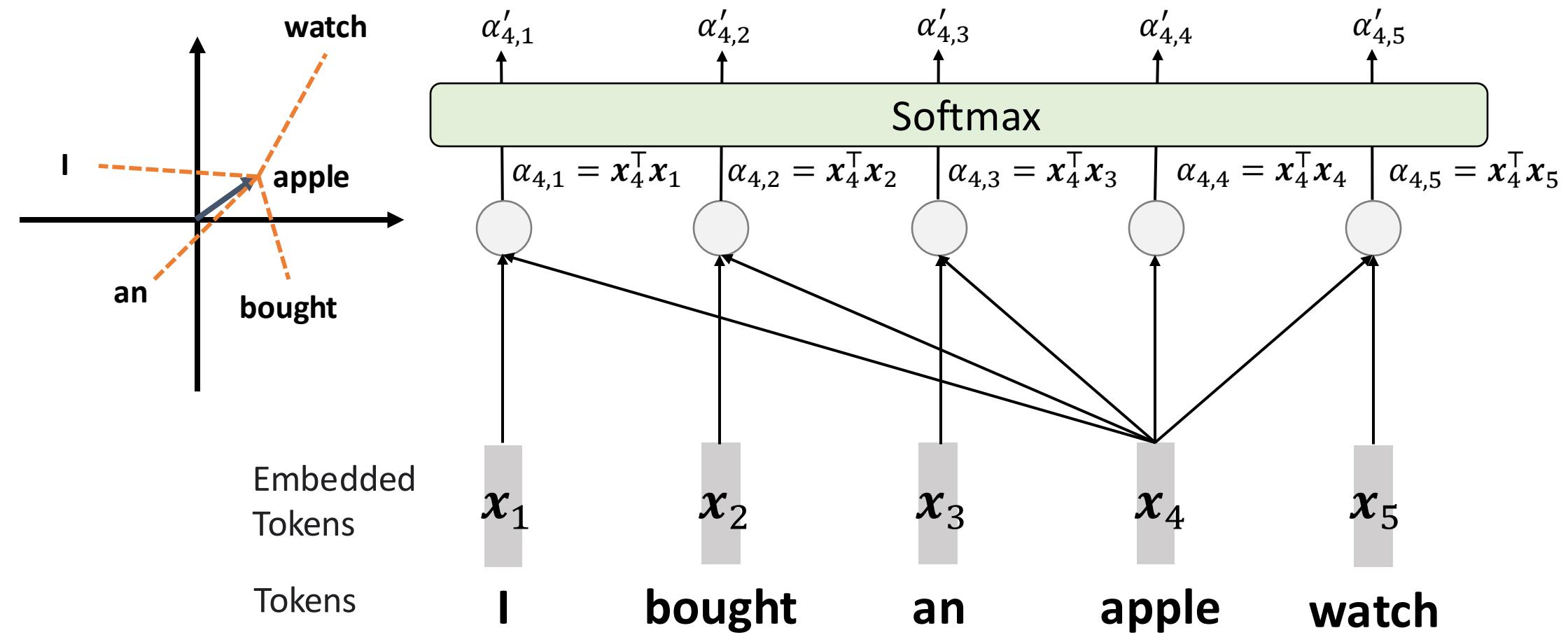




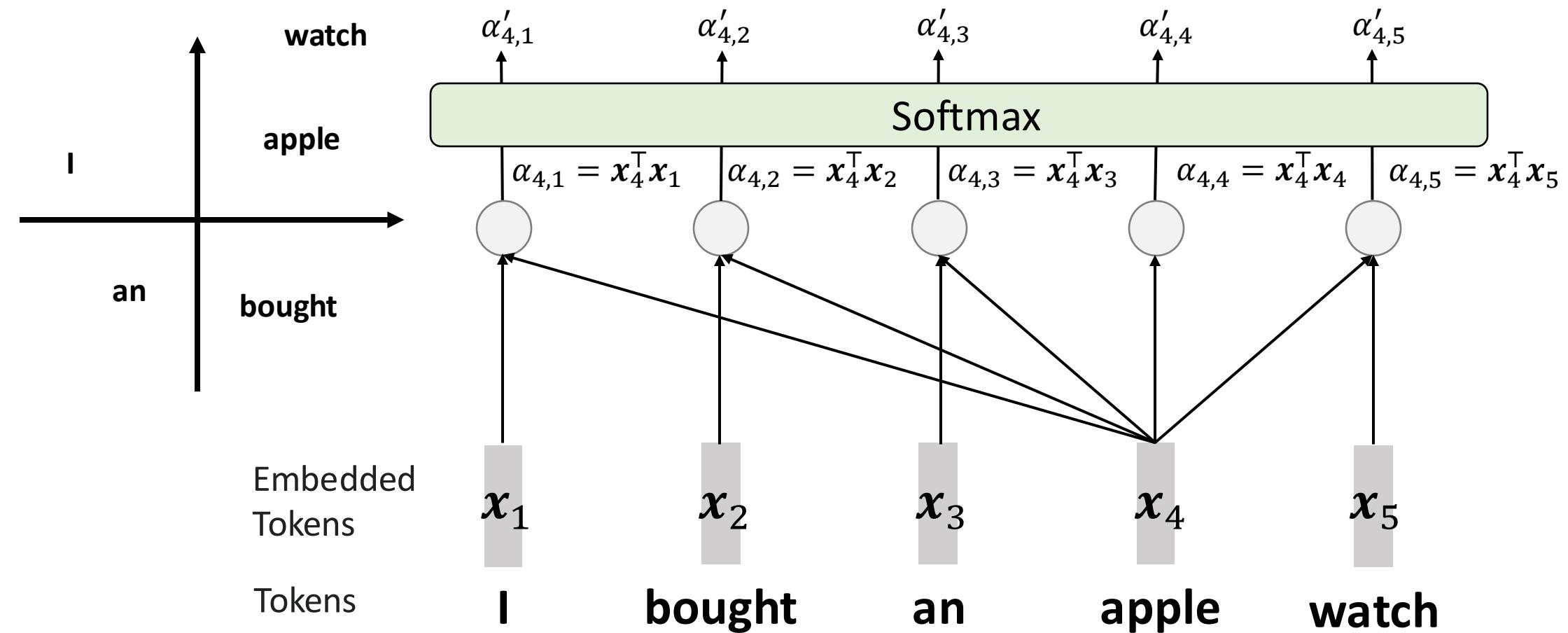




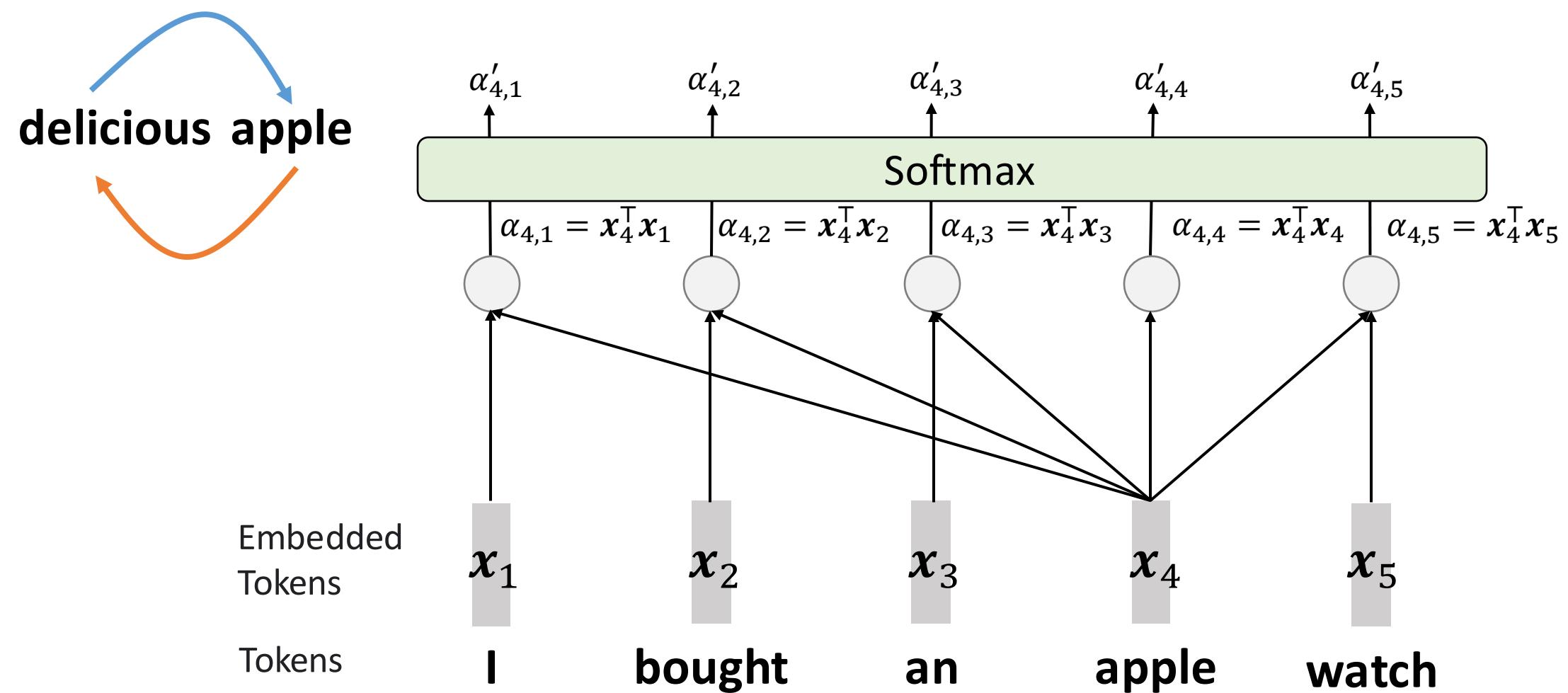
$$\text{Updated feature } \boldsymbol{x}'_4 = \alpha'_{4,1} \boldsymbol{x}_1 + \alpha'_{4,2} \boldsymbol{x}_2 + \alpha'_{4,3} \boldsymbol{x}_3 + \alpha'_{4,4} \boldsymbol{x}_4 + \alpha'_{4,5} \boldsymbol{x}_5$$

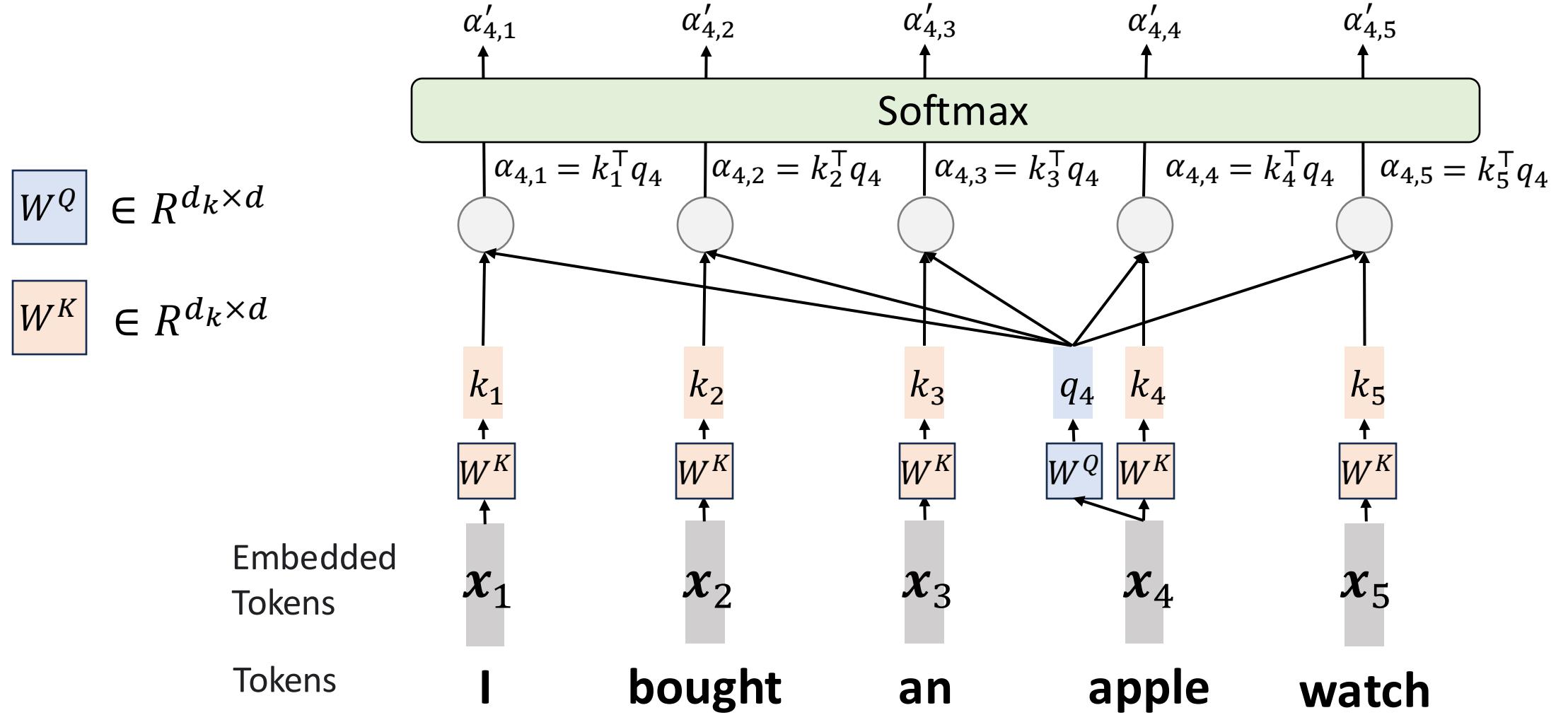


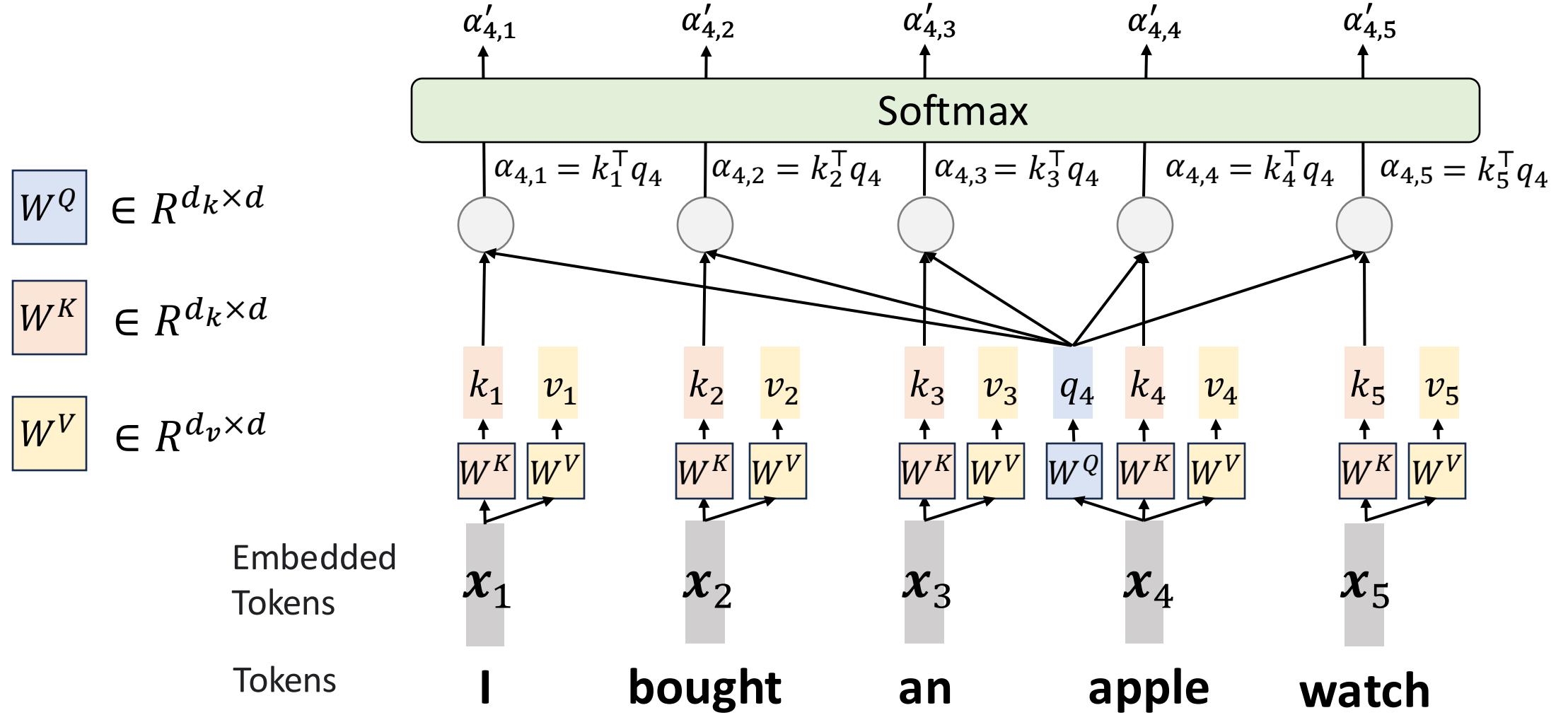
$$\text{Updated feature } \boldsymbol{x}'_4 = \alpha'_{4,1} \boldsymbol{x}_1 + \alpha'_{4,2} \boldsymbol{x}_2 + \alpha'_{4,3} \boldsymbol{x}_3 + \alpha'_{4,4} \boldsymbol{x}_4 + \alpha'_{4,5} \boldsymbol{x}_5$$



$$\text{Updated feature } \boldsymbol{x}'_4 = \alpha'_{4,1} \boldsymbol{x}_1 + \alpha'_{4,2} \boldsymbol{x}_2 + \alpha'_{4,3} \boldsymbol{x}_3 + \alpha'_{4,4} \boldsymbol{x}_4 + \alpha'_{4,5} \boldsymbol{x}_5$$

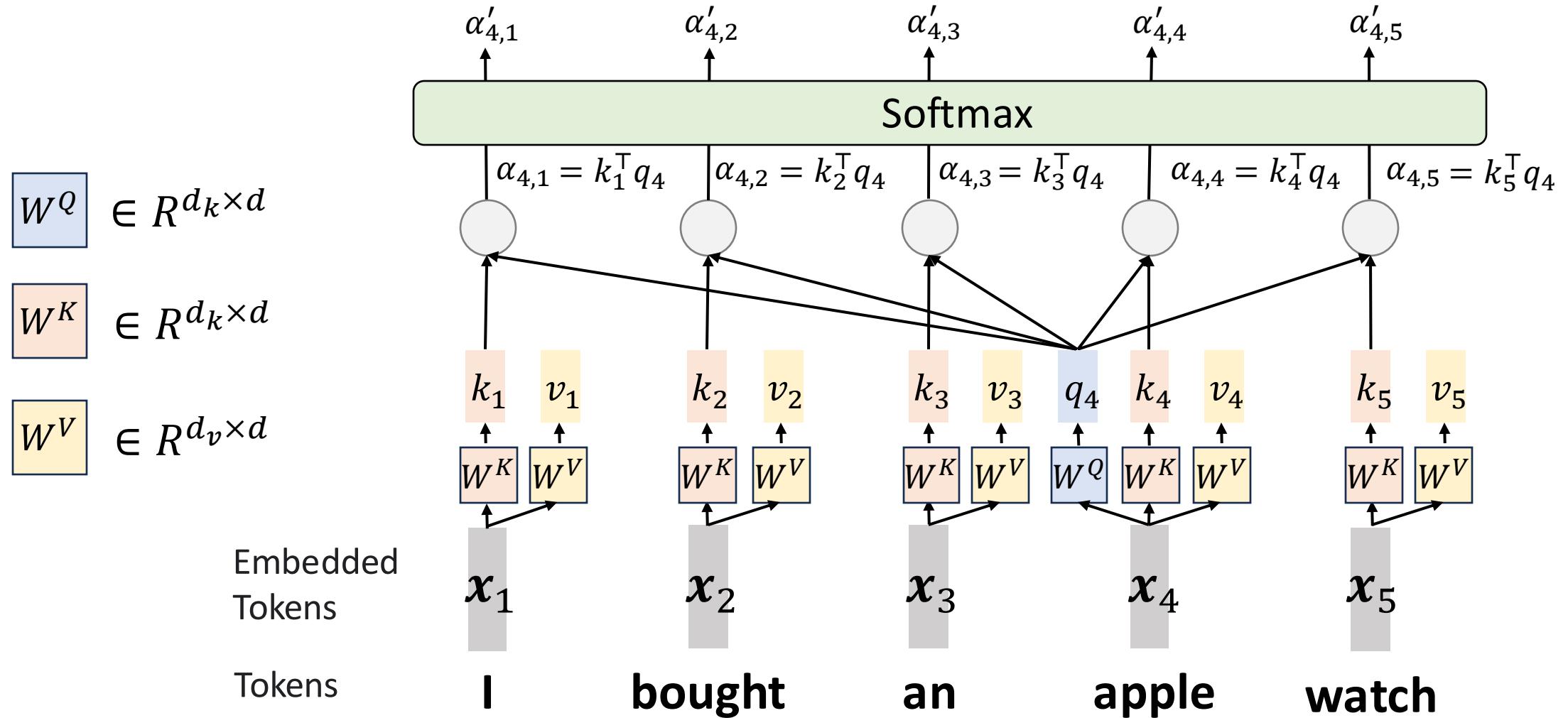






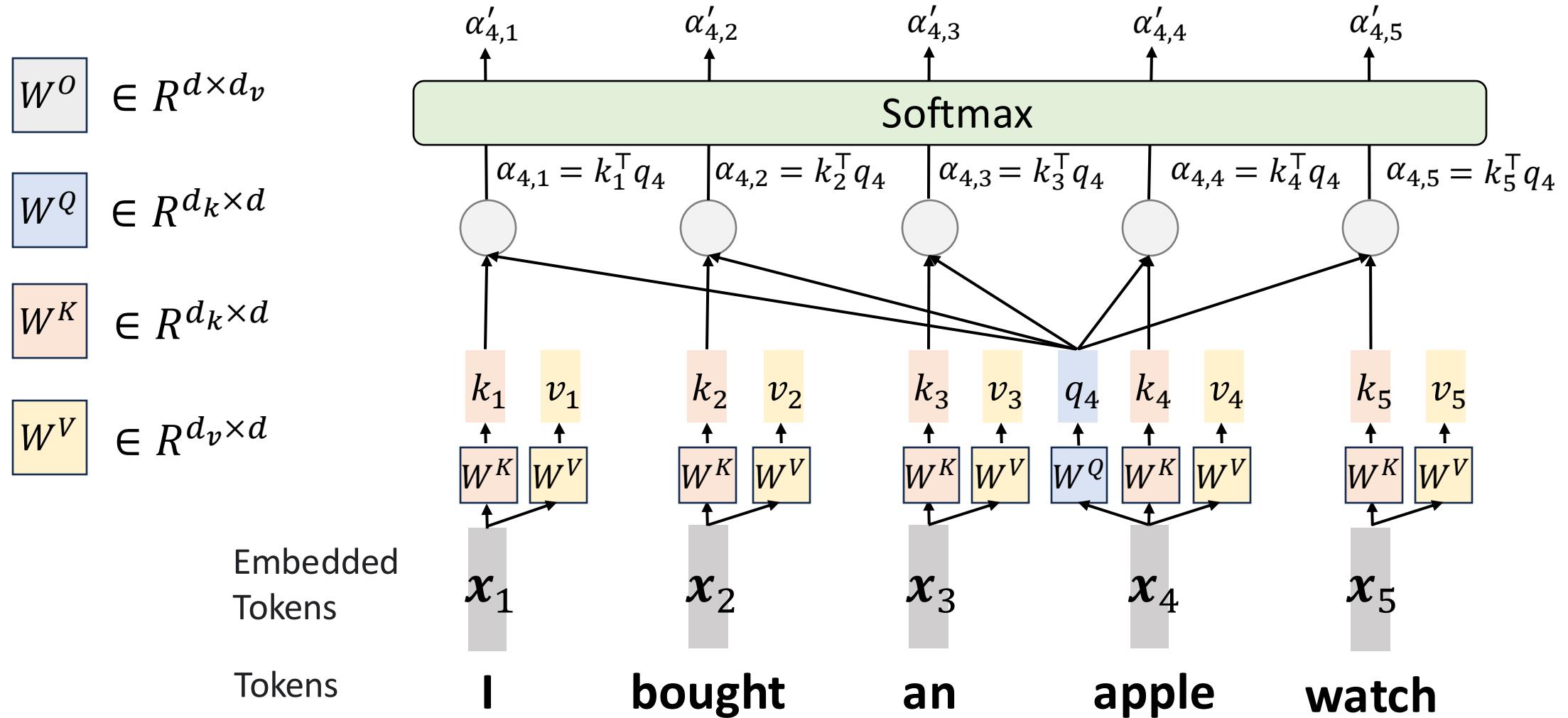
Updated feature

$$\boldsymbol{x}'_4 = \alpha'_{4,1} v_1 + \alpha'_{4,2} v_2 + \alpha'_{4,3} v_3 + \alpha'_{4,4} v_4 + \alpha'_{4,5} v_5$$



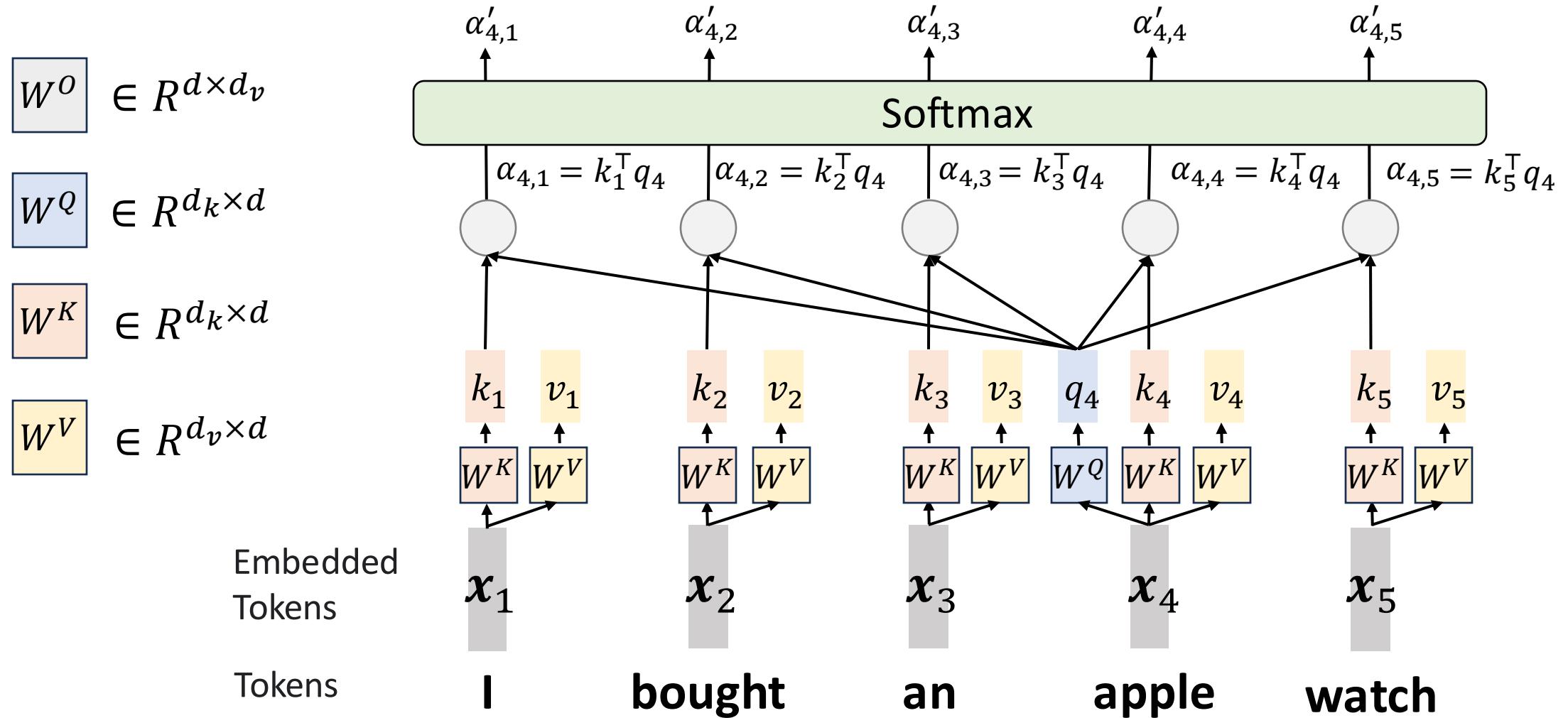
Updated feature  $\mathbf{x}'_4 = \boxed{W^O} (\alpha'_{4,1} v_1 + \alpha'_{4,2} v_2 + \alpha'_{4,3} v_3 + \alpha'_{4,4} v_4 + \alpha'_{4,5} v_5 )$

$$= \sum_i \alpha'_{4,i} \boxed{W^O} \boxed{W^V} \mathbf{x}_i$$



$$\text{Updated feature } \mathbf{x}'_4 = W^O (\alpha'_{4,1} v_1 + \alpha'_{4,2} v_2 + \alpha'_{4,3} v_3 + \alpha'_{4,4} v_4 + \alpha'_{4,5} v_5)$$

$$= \sum_i \alpha'_{4,i} (W^O W^V) \mathbf{x}_i$$



$$W^O \in R^{d \times d_v}$$

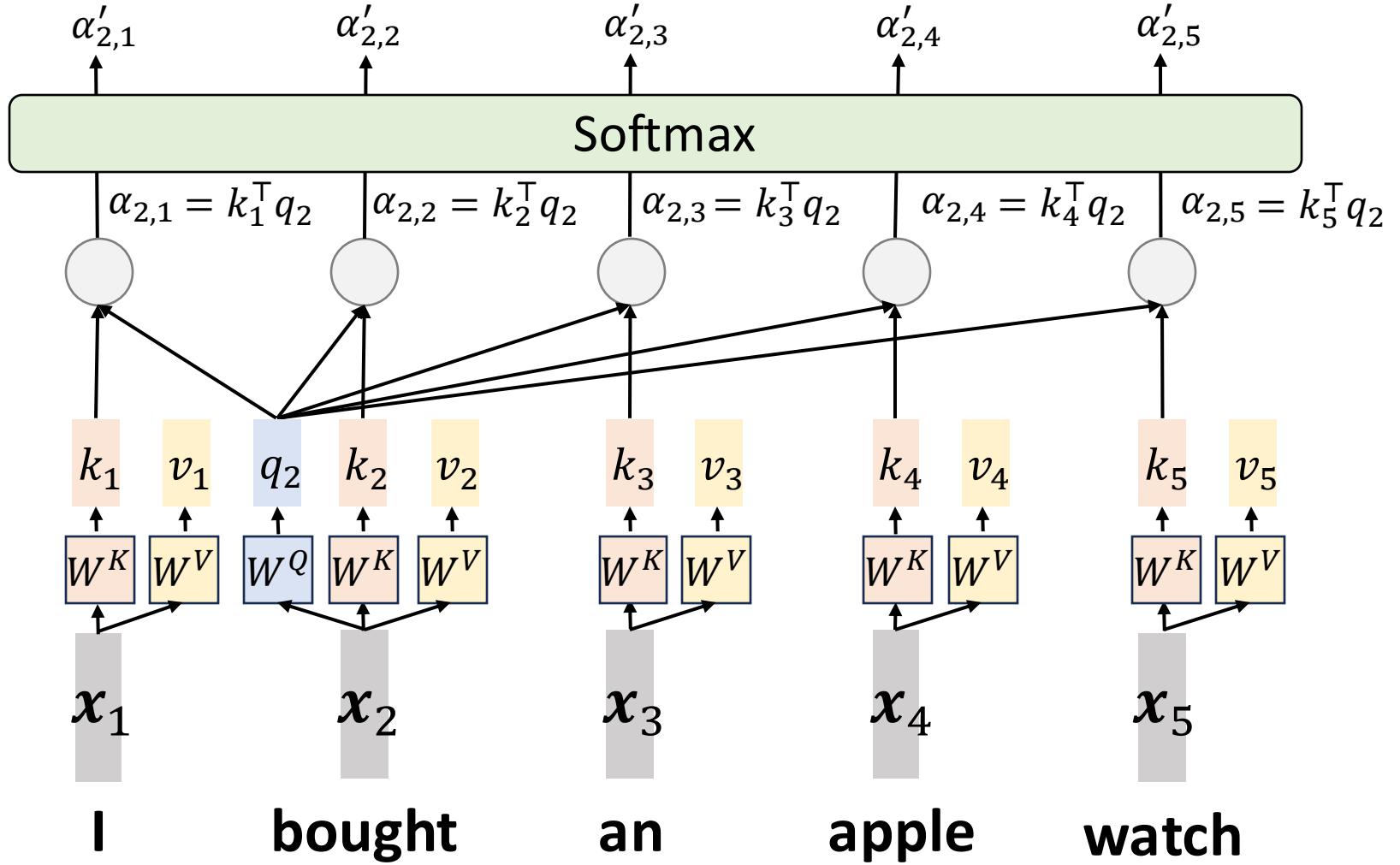
$$W^Q \in R^{d_k \times d}$$

$$W^K \in R^{d_k \times d}$$

$$W^V \in R^{d_v \times d}$$

Embedded  
Tokens

Tokens



$$W^O \in R^{d \times d_v}$$

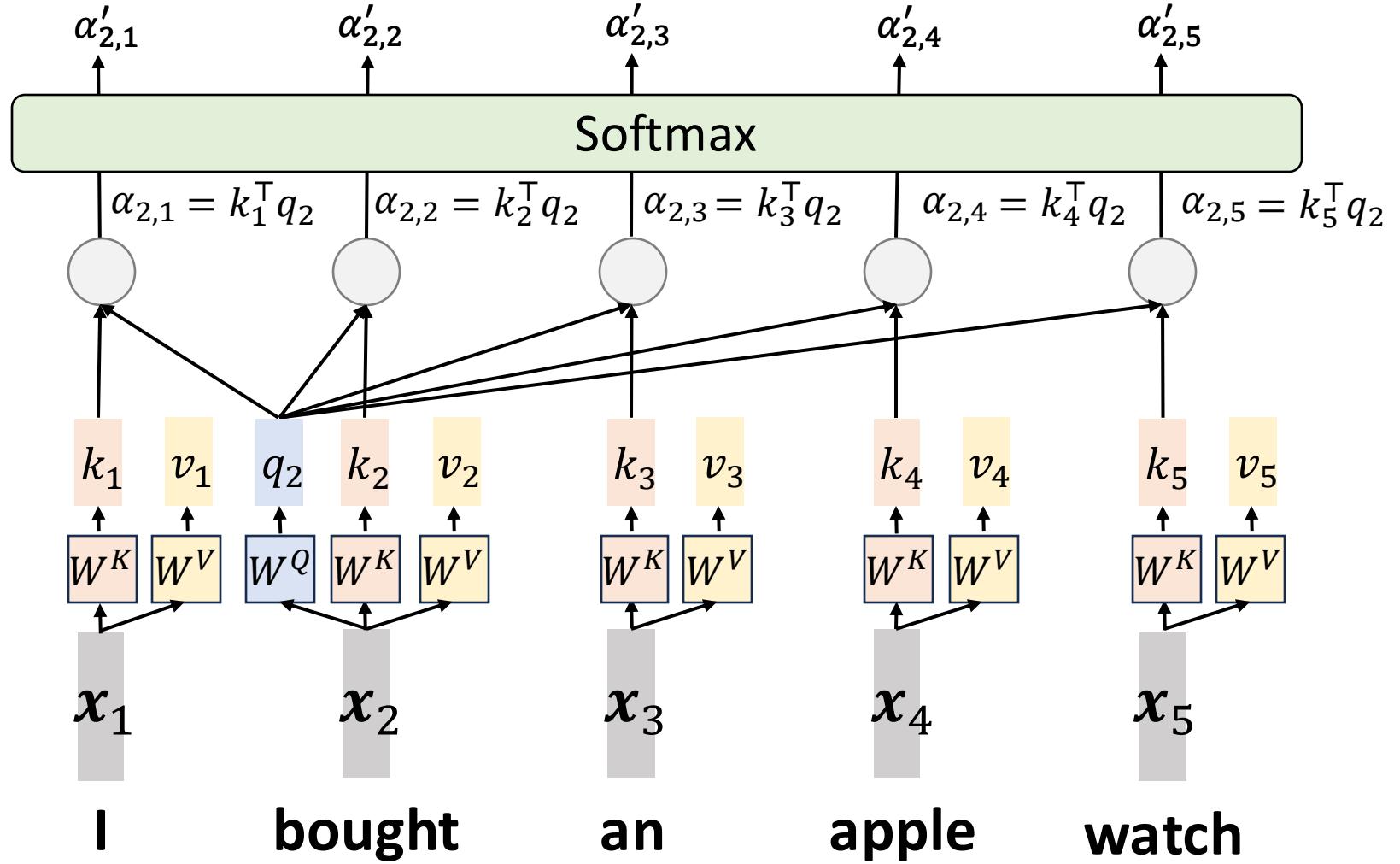
$$W^Q \in R^{d_k \times d}$$

$$W^K \in R^{d_k \times d}$$

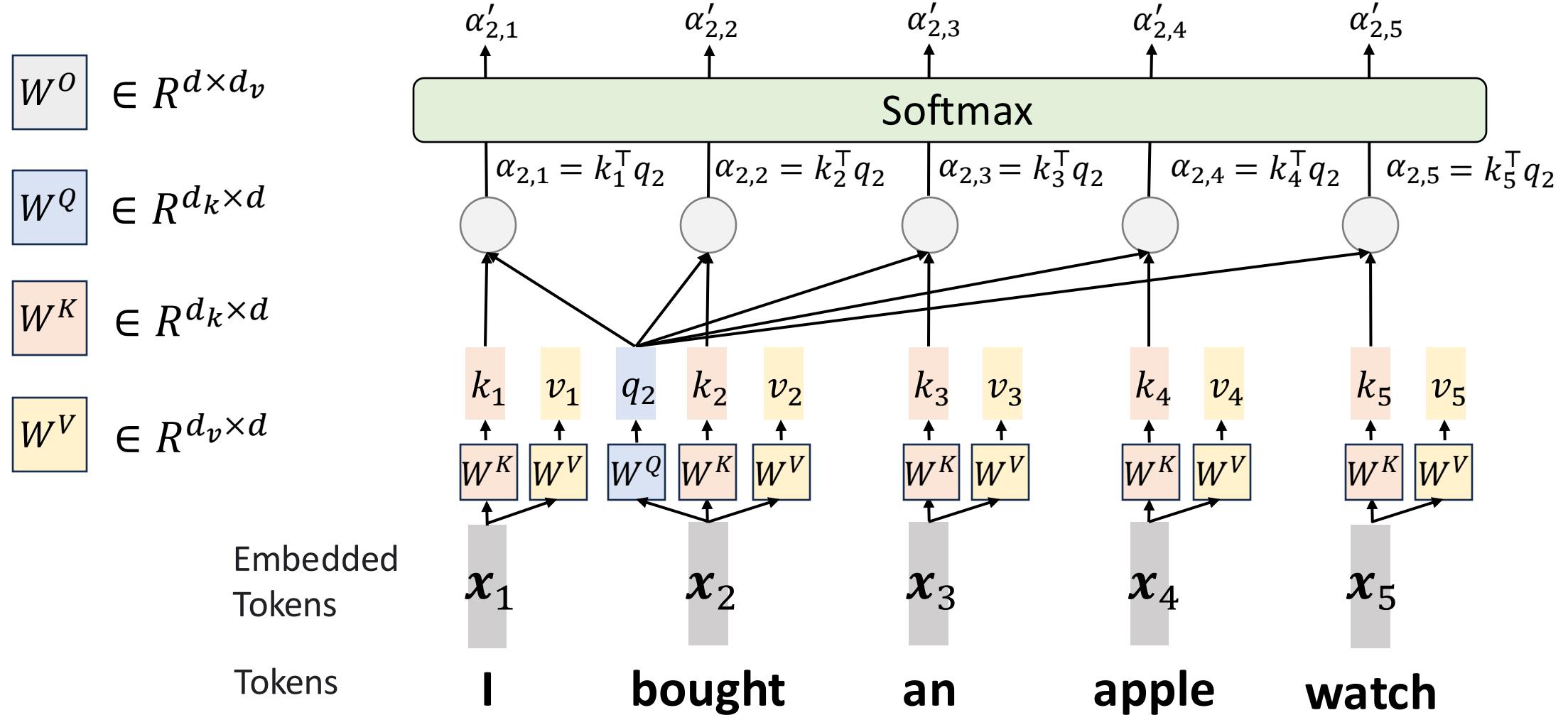
$$W^V \in R^{d_v \times d}$$

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Tokens

Tokens



$$\text{Updated feature } \mathbf{x}'_2 = W^O (\alpha'_{2,1} v_1 + \alpha'_{2,2} v_2 + \alpha'_{2,3} v_3 + \alpha'_{2,4} v_4 + \alpha'_{2,5} v_5)$$



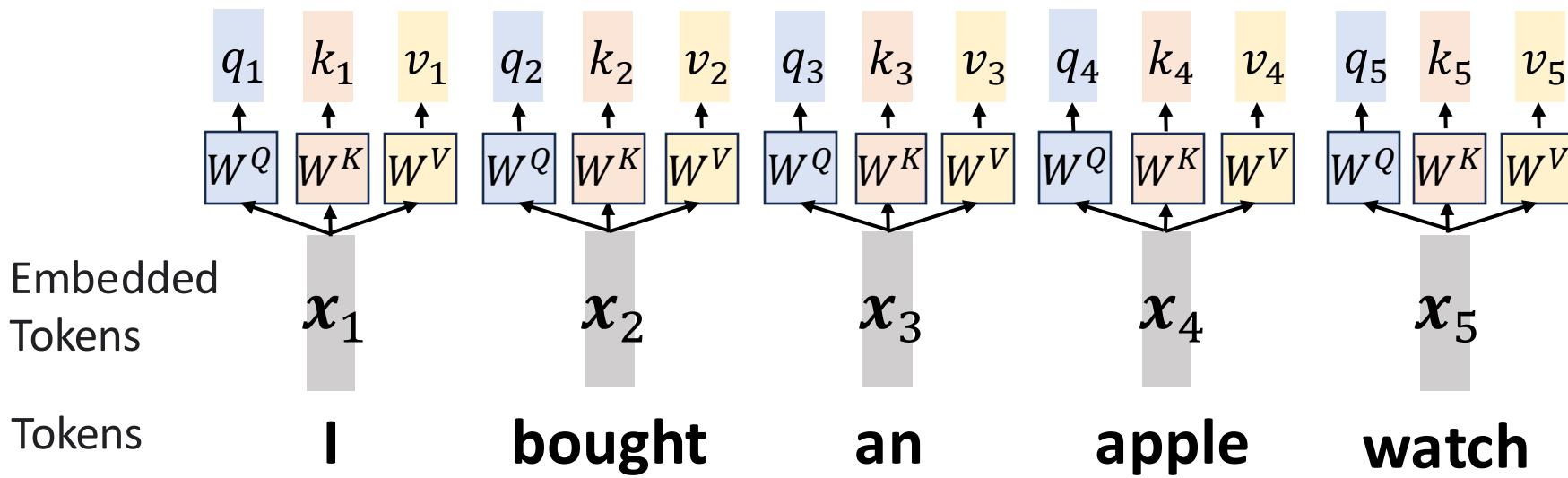
$$\alpha_{1,1} = k_1^\top q_1$$

$$\alpha_{1,2} = k_2^\top q_1$$

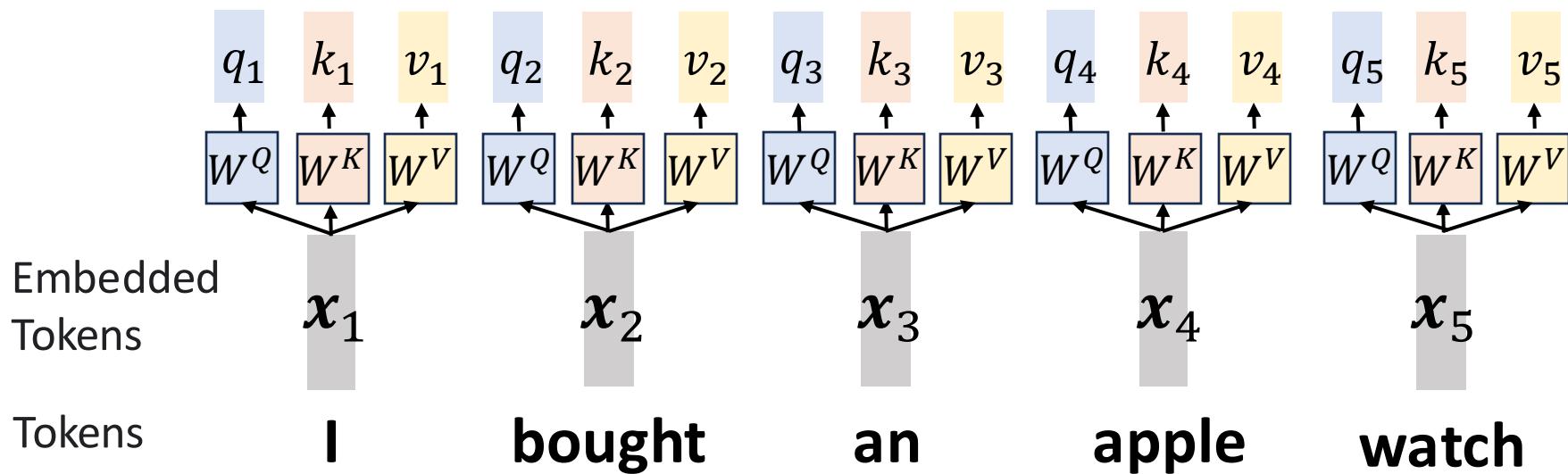
$$\alpha_{1,3} = k_3^\top q_1$$

$$\alpha_{1,4} = k_4^\top q_1$$

$$\alpha_{1,5} = k_5^\top q_1$$



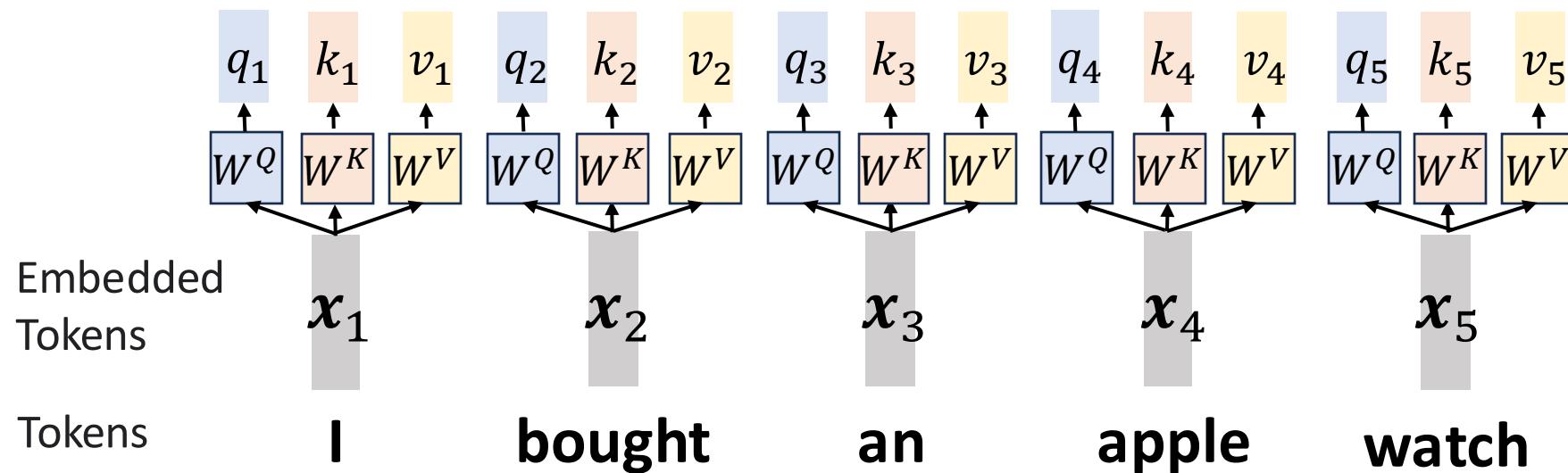
$$\begin{matrix} \alpha_{1,1} & \alpha_{2,1} & \alpha_{3,1} & \alpha_{4,1} & \alpha_{5,1} \\ \alpha_{1,2} & \alpha_{2,2} & \alpha_{3,2} & \alpha_{4,2} & \alpha_{5,2} \\ \alpha_{1,3} & \alpha_{2,3} & \alpha_{3,3} & \alpha_{4,3} & \alpha_{5,3} \\ \alpha_{1,4} & \alpha_{2,4} & \alpha_{3,4} & \alpha_{4,4} & \alpha_{5,4} \\ \alpha_{1,5} & \alpha_{2,5} & \alpha_{3,5} & \alpha_{4,5} & \alpha_{5,5} \end{matrix} = \left[ \begin{array}{c} k_1^\top \\ k_2^\top \\ k_3^\top \\ k_4^\top \\ k_5^\top \end{array} \right] \quad q_1 \quad q_2 \quad q_3 \quad q_4 \quad q_5$$



$$\frac{1}{\sqrt{d_k}} \times \begin{bmatrix} \alpha_{1,1} & \alpha_{2,1} & \alpha_{3,1} & \alpha_{4,1} & \alpha_{5,1} \\ \alpha_{1,2} & \alpha_{2,2} & \alpha_{3,2} & \alpha_{4,2} & \alpha_{5,2} \\ \alpha_{1,3} & \alpha_{2,3} & \alpha_{3,3} & \alpha_{4,3} & \alpha_{5,3} \\ \alpha_{1,4} & \alpha_{2,4} & \alpha_{3,4} & \alpha_{4,4} & \alpha_{5,4} \\ \alpha_{1,5} & \alpha_{2,5} & \alpha_{3,5} & \alpha_{4,5} & \alpha_{5,5} \end{bmatrix} = \begin{bmatrix} k_1^\top \\ k_2^\top \\ k_3^\top \\ k_4^\top \\ k_5^\top \end{bmatrix} \begin{bmatrix} q_1 & q_2 & q_3 & q_4 & q_5 \end{bmatrix}$$

Softmax

$$\rightarrow \begin{bmatrix} \alpha'_{1,1} & \alpha'_{2,1} & \alpha'_{3,1} & \alpha'_{4,1} & \alpha'_{5,1} \\ \alpha'_{1,2} & \alpha'_{2,2} & \alpha'_{3,2} & \alpha'_{4,2} & \alpha'_{5,2} \\ \alpha'_{1,3} & \alpha'_{2,3} & \alpha'_{3,3} & \alpha'_{4,3} & \alpha'_{5,3} \\ \alpha'_{1,4} & \alpha'_{2,4} & \alpha'_{3,4} & \alpha'_{4,4} & \alpha'_{5,4} \\ \alpha'_{1,5} & \alpha'_{2,5} & \alpha'_{3,5} & \alpha'_{4,5} & \alpha'_{5,5} \end{bmatrix}$$



$$\frac{1}{\sqrt{d_k}} \times \begin{bmatrix} \alpha_{1,1} & \alpha_{2,1} & \alpha_{3,1} & \alpha_{4,1} & \alpha_{5,1} \\ \alpha_{1,2} & \alpha_{2,2} & \alpha_{3,2} & \alpha_{4,2} & \alpha_{5,2} \\ \alpha_{1,3} & \alpha_{2,3} & \alpha_{3,3} & \alpha_{4,3} & \alpha_{5,3} \\ \alpha_{1,4} & \alpha_{2,4} & \alpha_{3,4} & \alpha_{4,4} & \alpha_{5,4} \\ \alpha_{1,5} & \alpha_{2,5} & \alpha_{3,5} & \alpha_{4,5} & \alpha_{5,5} \end{bmatrix} = \begin{bmatrix} k_1^\top \\ k_2^\top \\ k_3^\top \\ k_4^\top \\ k_5^\top \end{bmatrix} \begin{bmatrix} q_1 & q_2 & q_3 & q_4 & q_5 \end{bmatrix}$$

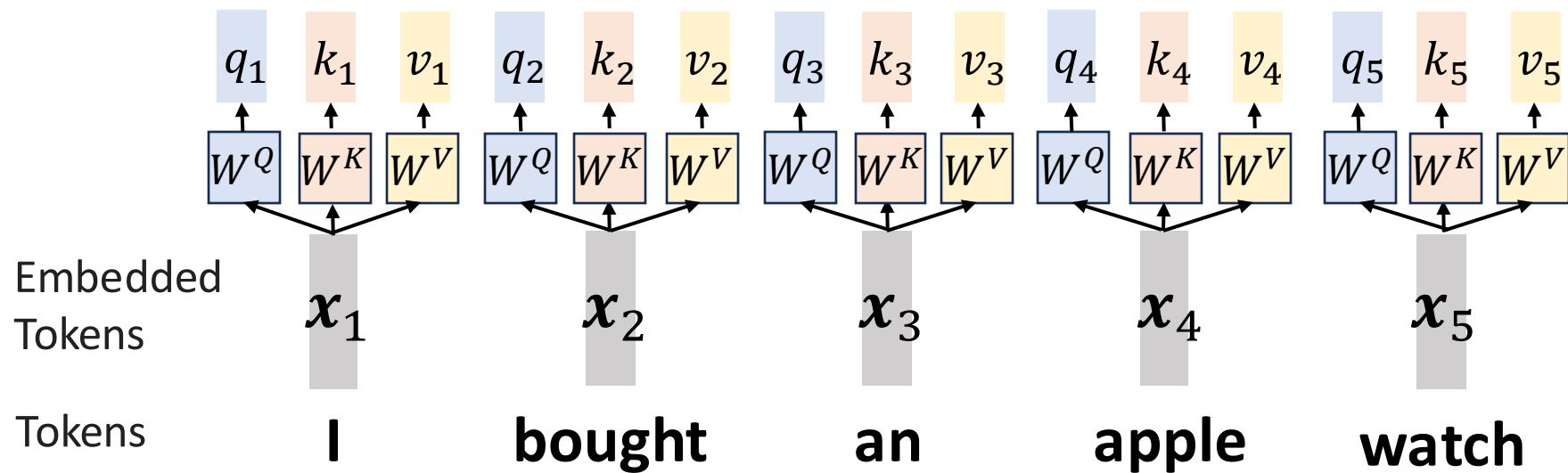
Softmax

$$\begin{bmatrix} \alpha'_{1,1} & \alpha'_{2,1} & \alpha'_{3,1} & \alpha'_{4,1} & \alpha'_{5,1} \\ \alpha'_{1,2} & \alpha'_{2,2} & \alpha'_{3,2} & \alpha'_{4,2} & \alpha'_{5,2} \\ \alpha'_{1,3} & \alpha'_{2,3} & \alpha'_{3,3} & \alpha'_{4,3} & \alpha'_{5,3} \\ \alpha'_{1,4} & \alpha'_{2,4} & \alpha'_{3,4} & \alpha'_{4,4} & \alpha'_{5,4} \\ \alpha'_{1,5} & \alpha'_{2,5} & \alpha'_{3,5} & \alpha'_{4,5} & \alpha'_{5,5} \end{bmatrix}$$

$$k = [k^1, k^2, \dots, k^{d_k}]^\top \quad E[k^i] = E[q^i] = 0$$

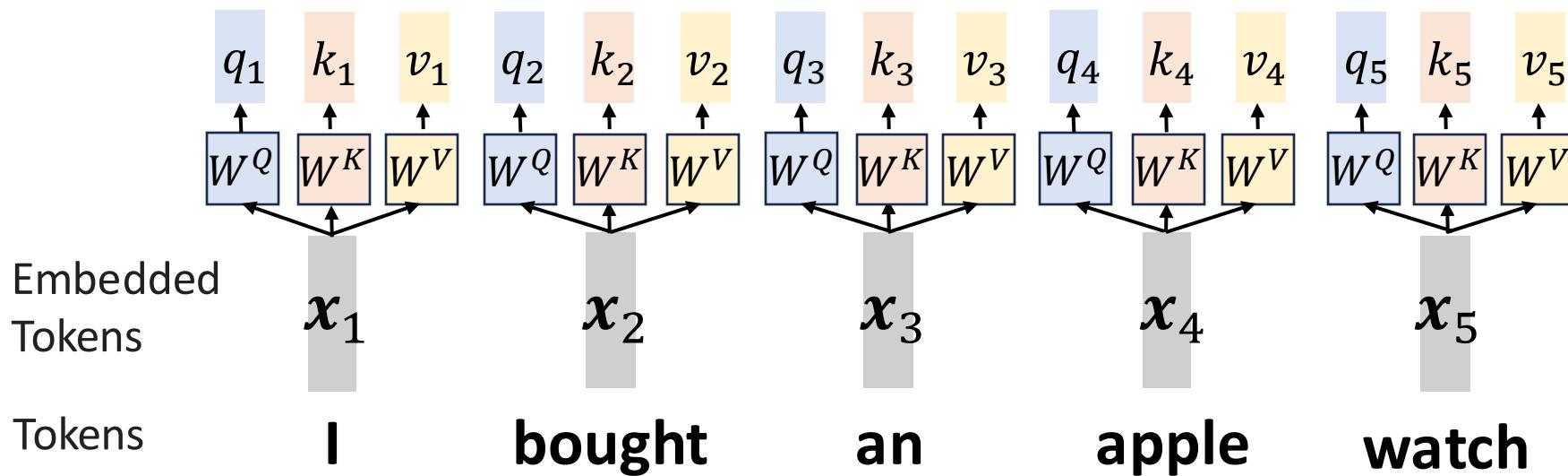
$$q = [q^1, q^2, \dots, q^{d_k}]^\top \quad \text{Var}[k^i] = \text{Var}[q^i] = 1$$

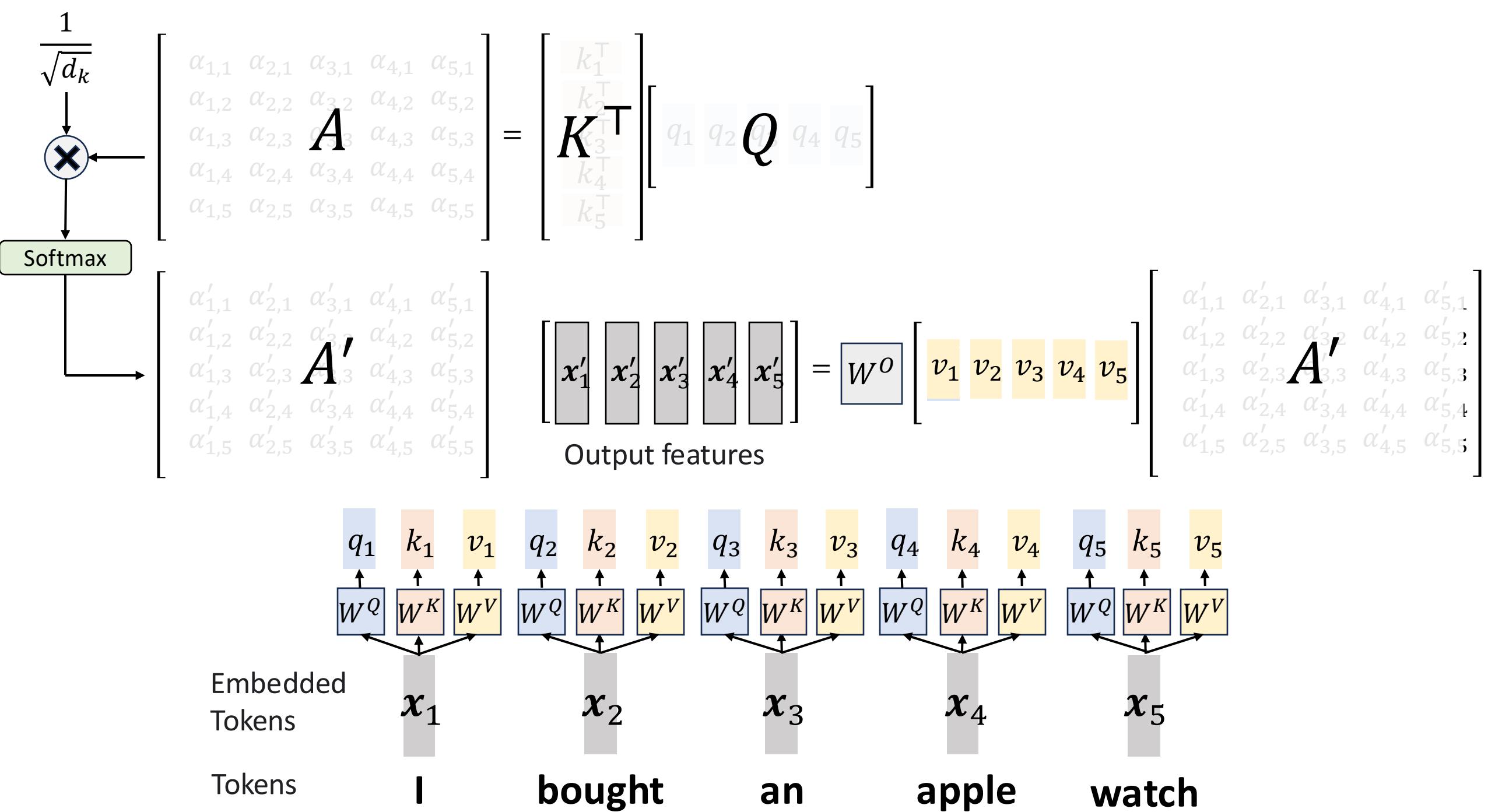
$$k^\top q = \sum_{i=1}^{d_k} k^i q^i \quad \text{Var}[k^\top q] = d_k$$

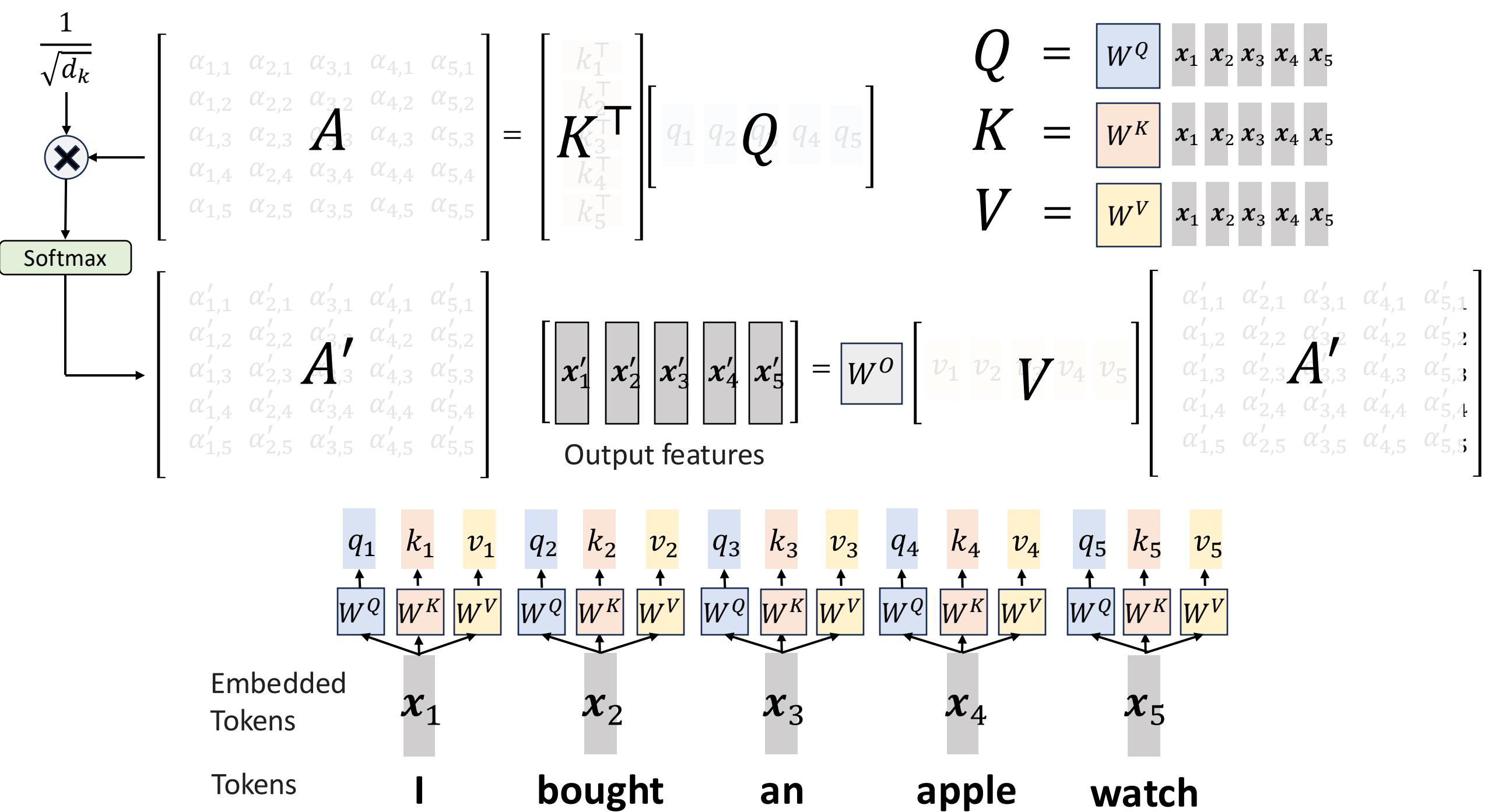


$$\frac{1}{\sqrt{d_k}} \times \text{Softmax} \left[ \begin{bmatrix} \alpha_{1,1} & \alpha_{2,1} & \alpha_{3,1} & \alpha_{4,1} & \alpha_{5,1} \\ \alpha_{1,2} & \alpha_{2,2} & \alpha_{3,2} & \alpha_{4,2} & \alpha_{5,2} \\ \alpha_{1,3} & \alpha_{2,3} & \alpha_{3,3} & \alpha_{4,3} & \alpha_{5,3} \\ \alpha_{1,4} & \alpha_{2,4} & \alpha_{3,4} & \alpha_{4,4} & \alpha_{5,4} \\ \alpha_{1,5} & \alpha_{2,5} & \alpha_{3,5} & \alpha_{4,5} & \alpha_{5,5} \end{bmatrix} \mathbf{A} \right] = \begin{bmatrix} k_1^\top \\ k_2^\top \\ k_3^\top \\ k_4^\top \\ k_5^\top \end{bmatrix} \mathbf{K}^\top \begin{bmatrix} q_1 & q_2 & \mathbf{Q} & q_4 & q_5 \end{bmatrix}$$

$$\left[ \begin{bmatrix} \alpha'_{1,1} & \alpha'_{2,1} & \alpha'_{3,1} & \alpha'_{4,1} & \alpha'_{5,1} \\ \alpha'_{1,2} & \alpha'_{2,2} & \alpha'_{3,2} & \alpha'_{4,2} & \alpha'_{5,2} \\ \alpha'_{1,3} & \alpha'_{2,3} & \alpha'_{3,3} & \alpha'_{4,3} & \alpha'_{5,3} \\ \alpha'_{1,4} & \alpha'_{2,4} & \alpha'_{3,4} & \alpha'_{4,4} & \alpha'_{5,4} \\ \alpha'_{1,5} & \alpha'_{2,5} & \alpha'_{3,5} & \alpha'_{4,5} & \alpha'_{5,5} \end{bmatrix} \mathbf{A}' \right]$$





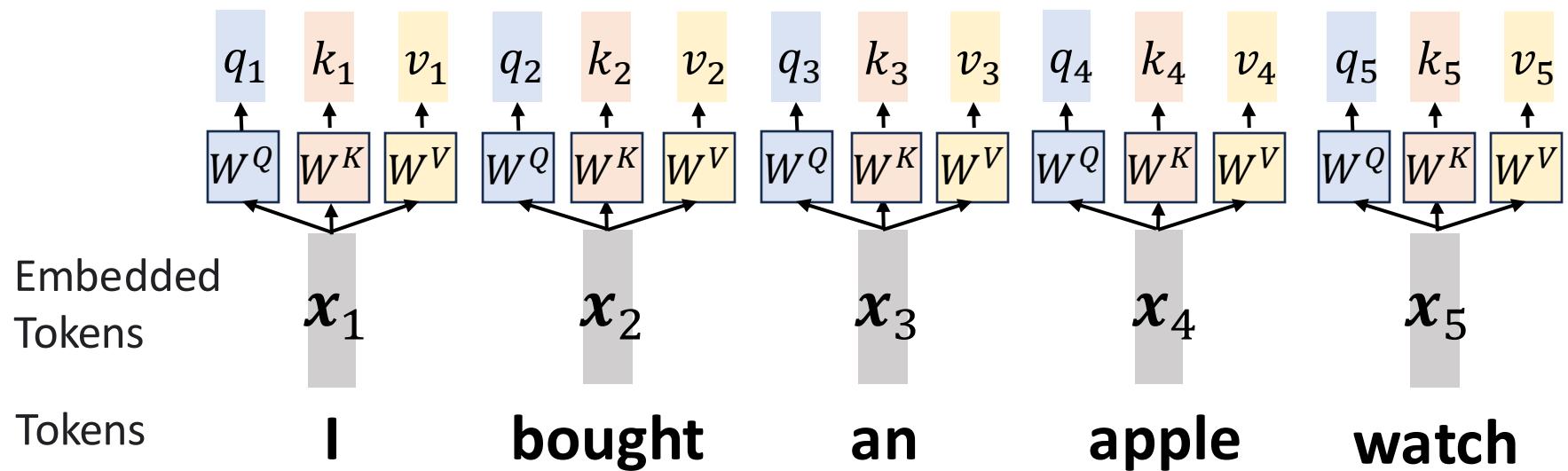




## Single-head attention

$$\text{Attention}(Q, K, V) = V \text{ softmax} \left( \frac{K^\top Q}{\sqrt{d_k}} \right)$$

$$Q = \boxed{W^Q} \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$
$$K = \boxed{W^K} \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$
$$V = \boxed{W^V} \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$



## Single-head attention

$$\text{Attention}(Q, K, V) = V \text{ softmax} \left( \frac{K^\top Q}{\sqrt{d_k}} \right)$$

$$\begin{aligned} Q &= \boxed{W^Q} \quad \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix} \\ K &= \boxed{W^K} \quad \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix} \\ V &= \boxed{W^V} \quad \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix} \end{aligned}$$

$$\boxed{W_0^Q} \quad \boxed{W_0^K} \quad \boxed{W_0^V}$$

$$\boxed{W_1^Q} \quad \boxed{W_1^K} \quad \boxed{W_1^V}$$

...

$$\boxed{W_{h-1}^Q} \quad \boxed{W_{h-1}^K} \quad \boxed{W_{h-1}^V}$$

$$\boxed{W_i^Q} \in R^{d_k \times d}$$

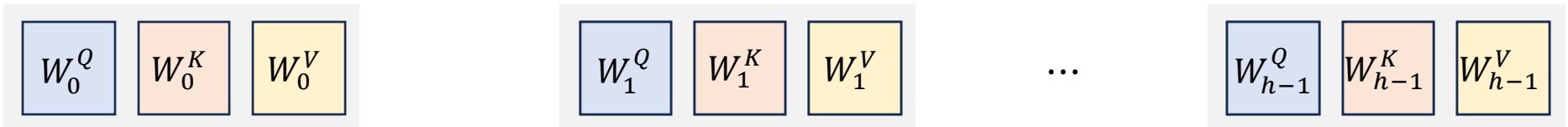
$$\boxed{W_i^K} \in R^{d_k \times d}$$

$$\boxed{W_i^V} \in R^{d_v \times d}$$

## Single-head attention

$$\text{Attention}(Q, K, V) = V \text{ softmax} \left( \frac{K^\top Q}{\sqrt{d_k}} \right)$$

$$Q = \begin{matrix} W^Q & x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$
$$K = \begin{matrix} W^K & x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$
$$V = \begin{matrix} W^V & x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$



$$W_i^Q \in R^{d_k \times d}$$

$$\begin{matrix} W_0^Q & Q \\ \hline \end{matrix} \quad \begin{matrix} W_0^K & K \\ \hline \end{matrix} \quad \begin{matrix} W_0^V & V \\ \hline \end{matrix}$$

$$W_i^K \in R^{d_k \times d}$$

$$W_i^V \in R^{d_v \times d}$$

$$\text{Head}_0 \in R^{d_v \times n}$$

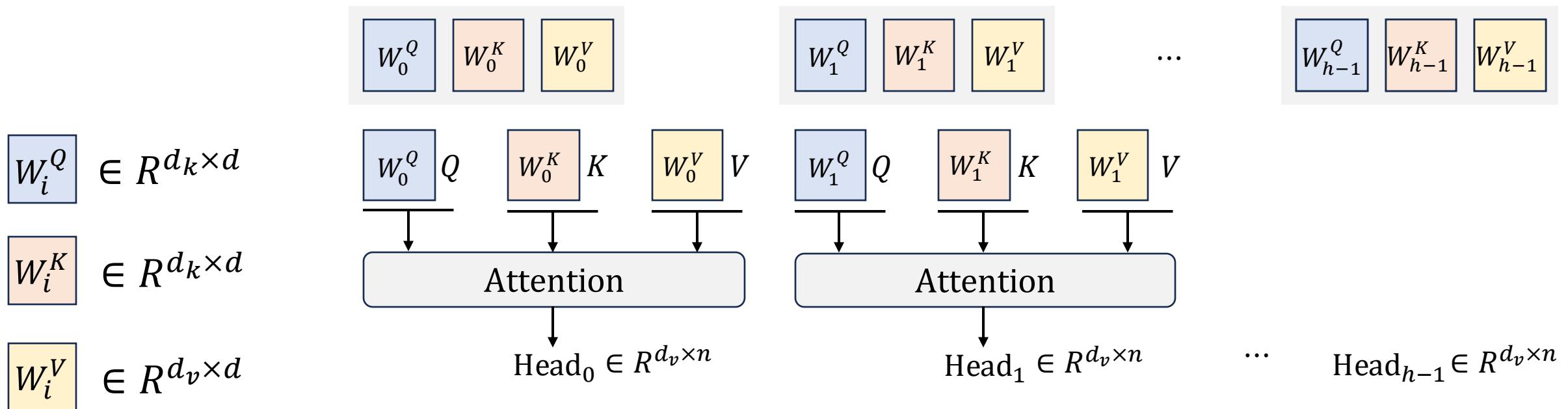
## Single-head attention

$$\text{Attention}(Q, K, V) = V \text{ softmax} \left( \frac{K^\top Q}{\sqrt{d_k}} \right)$$

$$Q = \begin{matrix} W^Q & x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$

$$K = \begin{matrix} W^K & x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$

$$V = \begin{matrix} W^V & x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix}$$



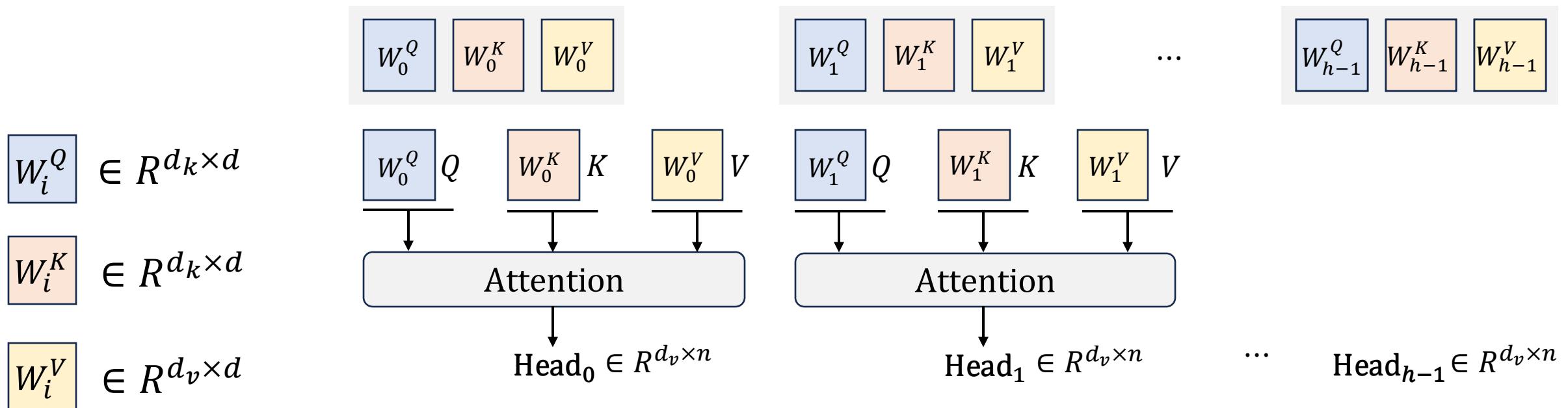
## Single-head attention

$$\text{Attention}(Q, K, V) = V \text{ softmax} \left( \frac{K^\top Q}{\sqrt{d_k}} \right)$$

$$Q = \begin{matrix} W^Q \\ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{matrix}$$

$$K = \begin{matrix} W^K \\ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{matrix}$$

$$V = \begin{matrix} W^V \\ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{matrix}$$

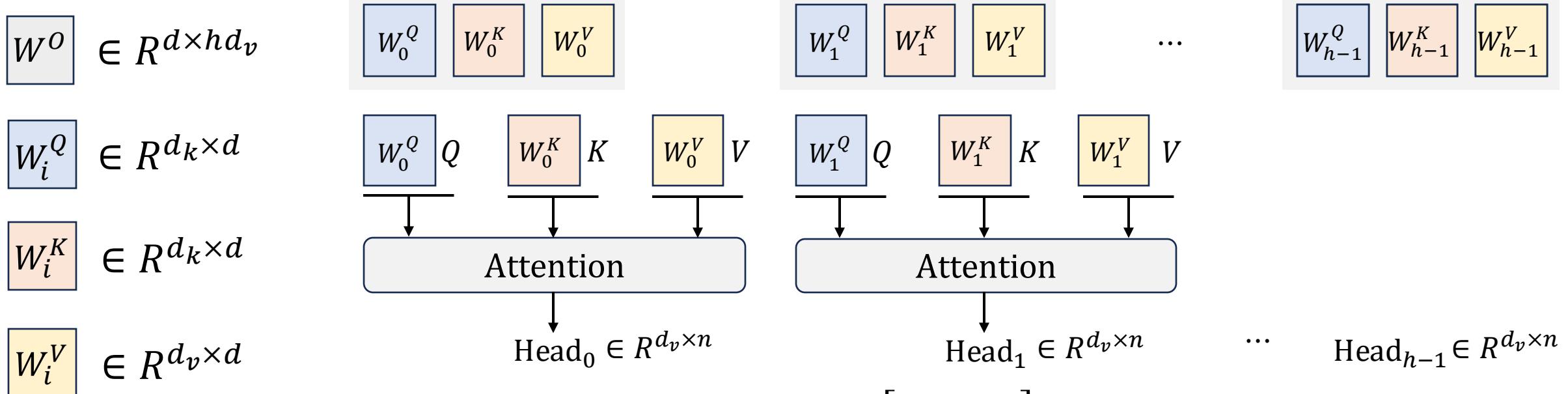


## Single-head attention

$$\text{Attention}(Q, K, V) = V \text{ softmax} \left( \frac{K^T Q}{\sqrt{d_k}} \right)$$

## Multi-head attention

$$\begin{aligned} Q &= \begin{matrix} W^Q \\ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{matrix} \\ K &= \begin{matrix} W^K \\ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{matrix} \\ V &= \begin{matrix} W^V \\ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \end{matrix} \end{aligned}$$

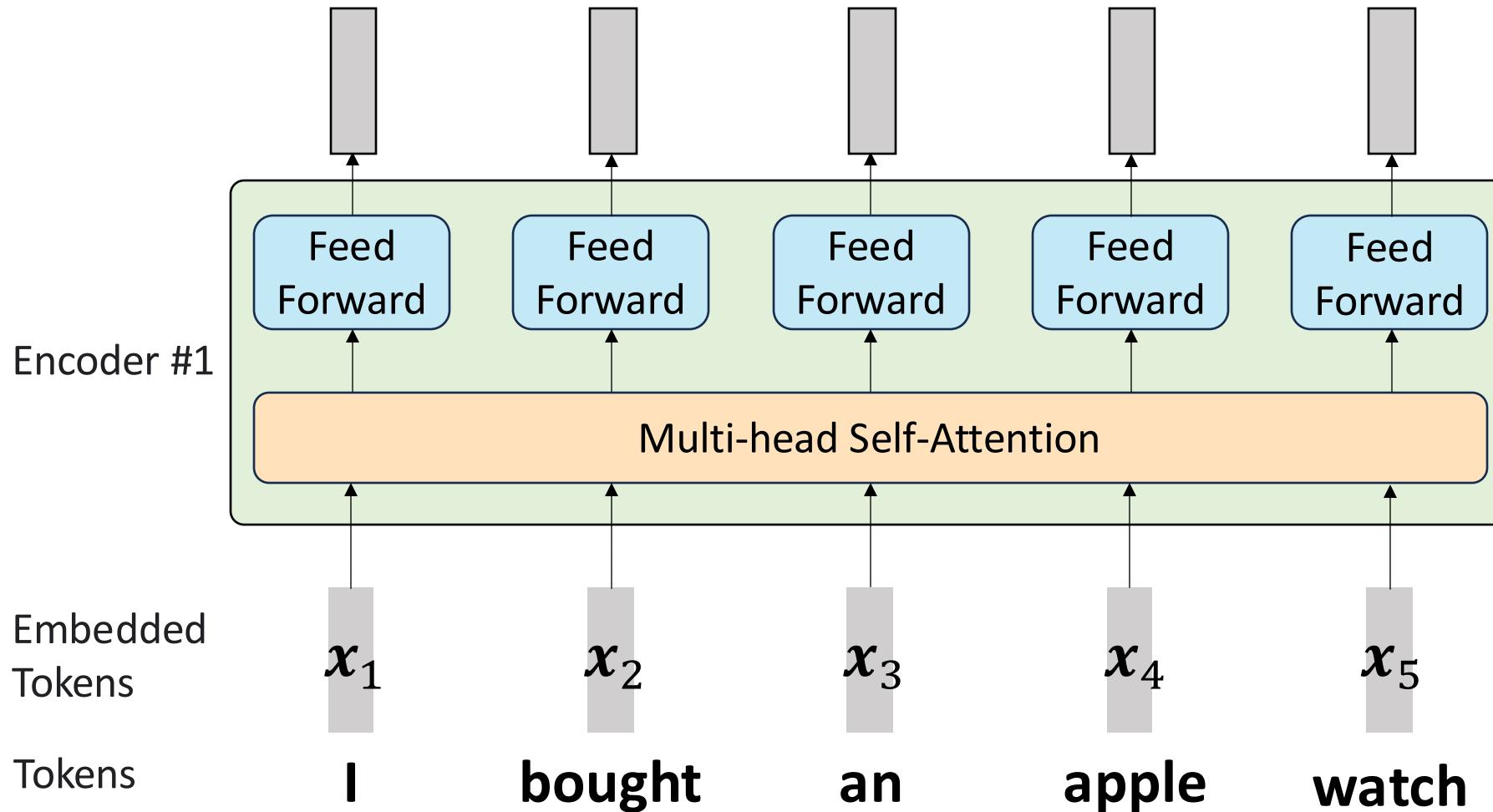


$$\text{MultiHeadedAttention}(Q, K, V) =$$

$$W^O \begin{bmatrix} \text{Head}_0 \\ \text{Head}_1 \\ \vdots \\ \text{Head}_{h-1} \end{bmatrix}$$

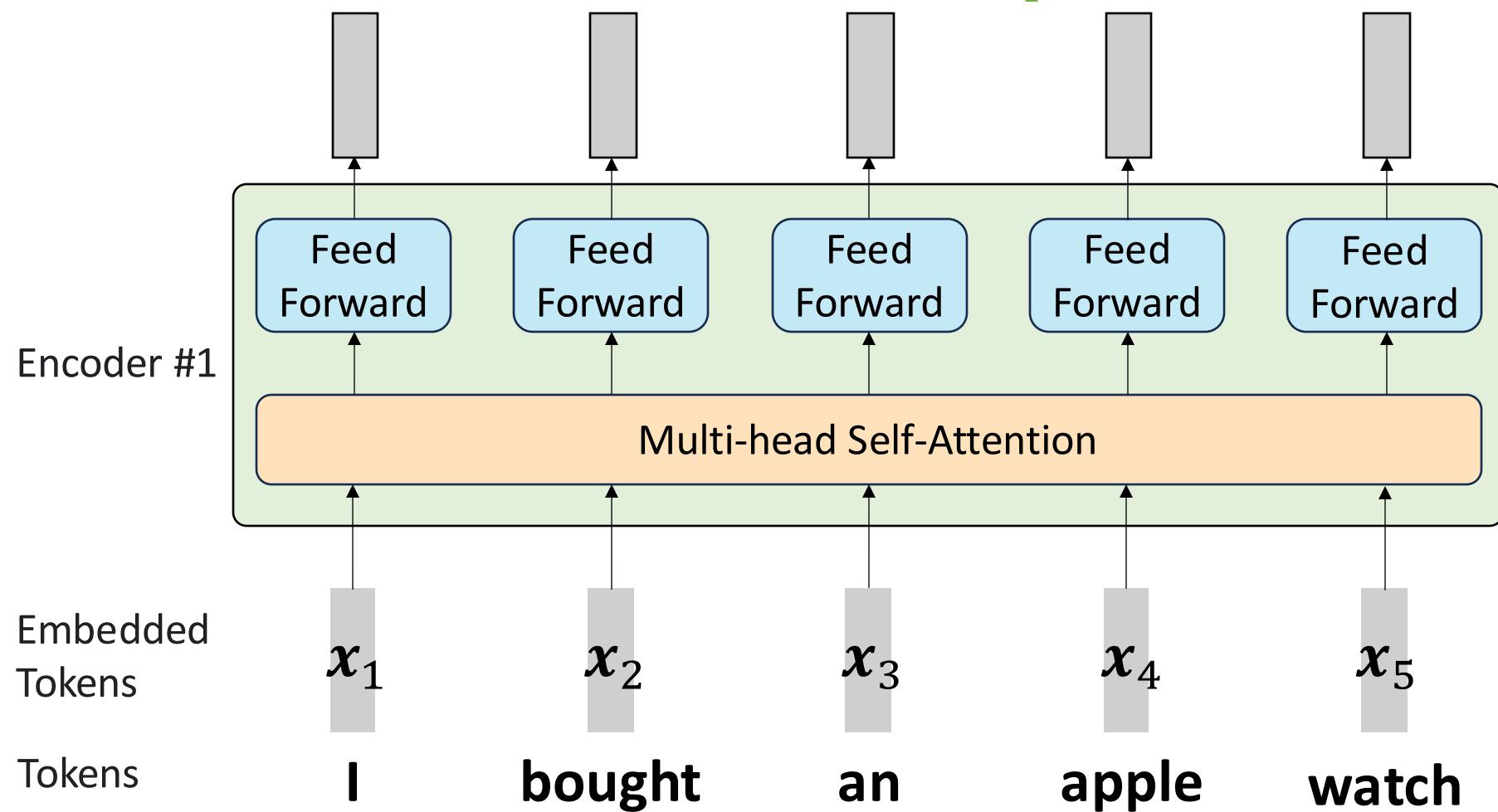
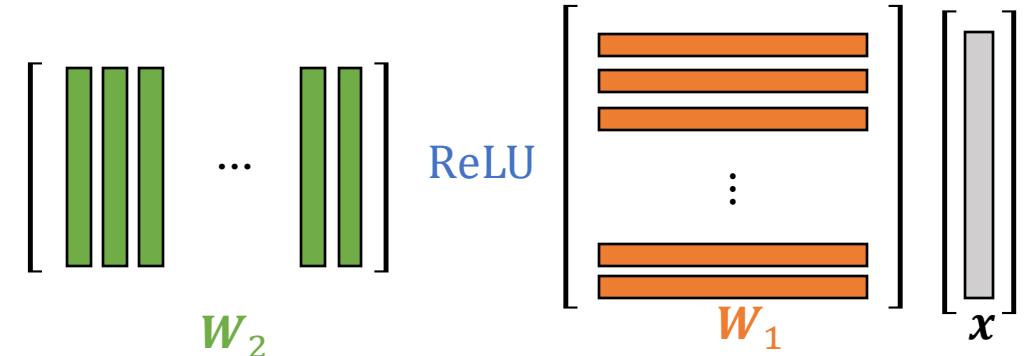
# Feed Forward Network (FFN)

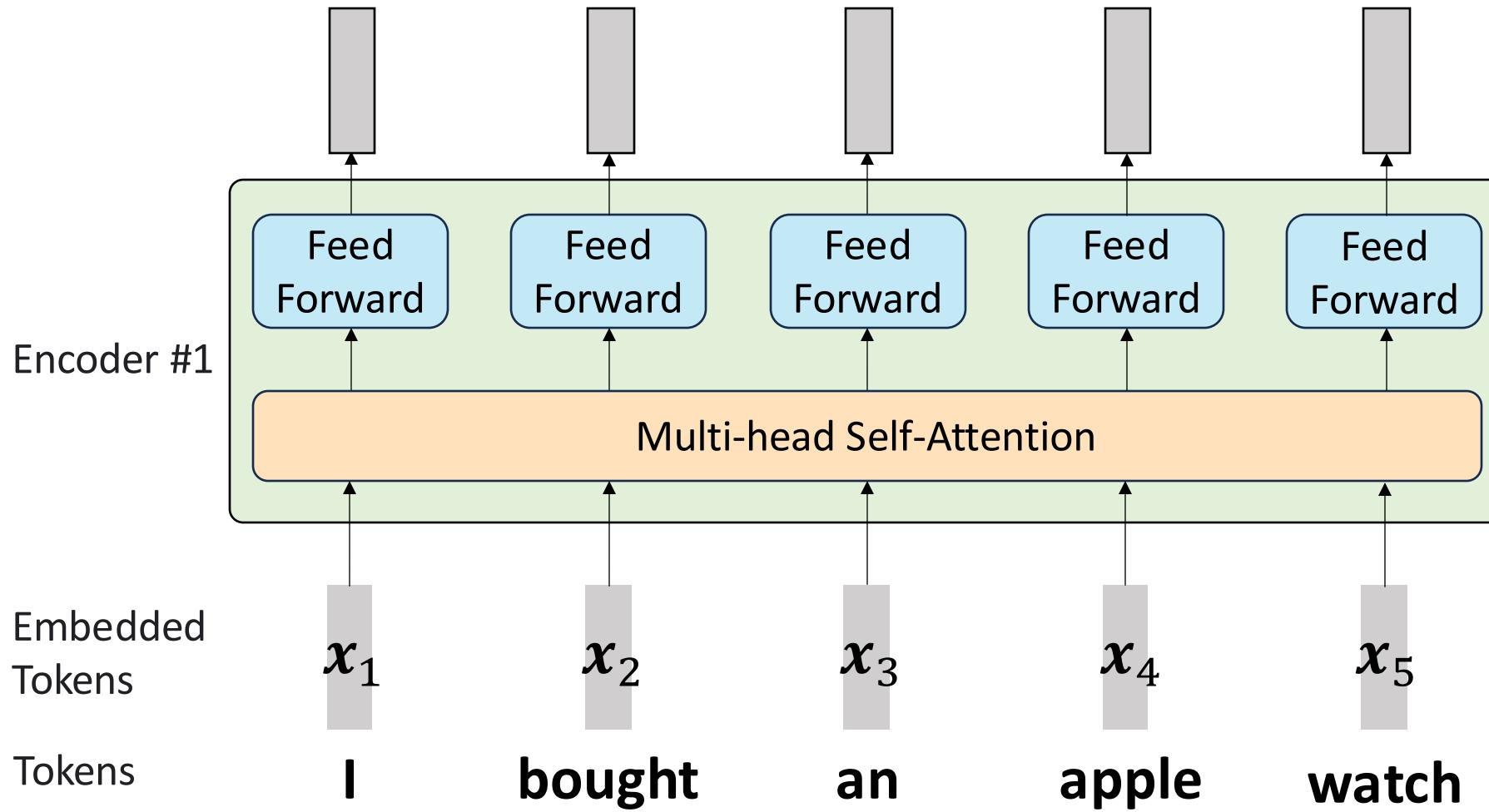
$$FFN(x) = \mathbf{W}_2 \text{ReLU}(\mathbf{W}_1 x + \mathbf{b}_1) + \mathbf{b}_2$$

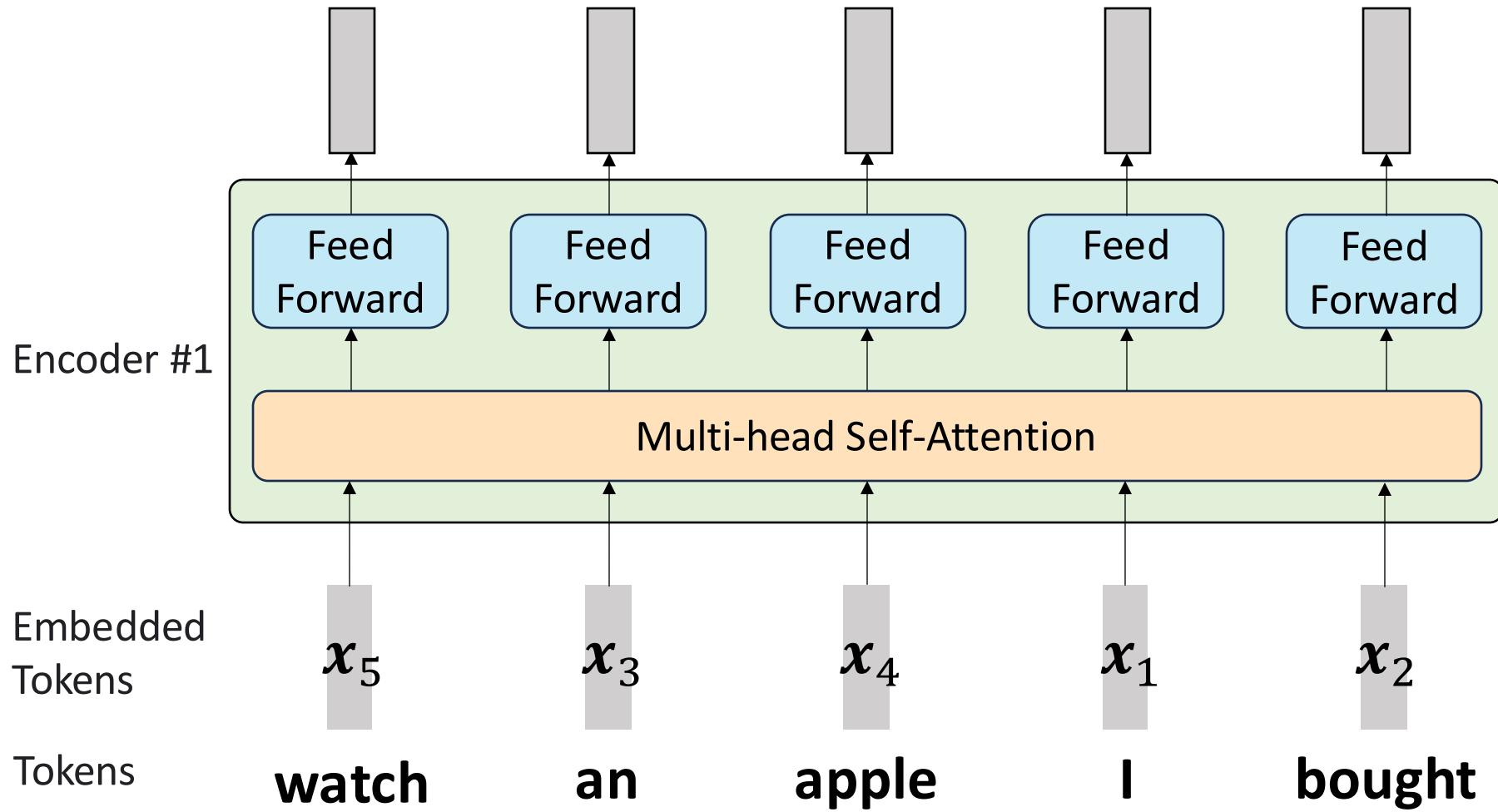


## Feed Forward Network (FFN)

$$FFN(x) = W_2 \text{ReLU}(W_1 x + b_1) + b_2$$

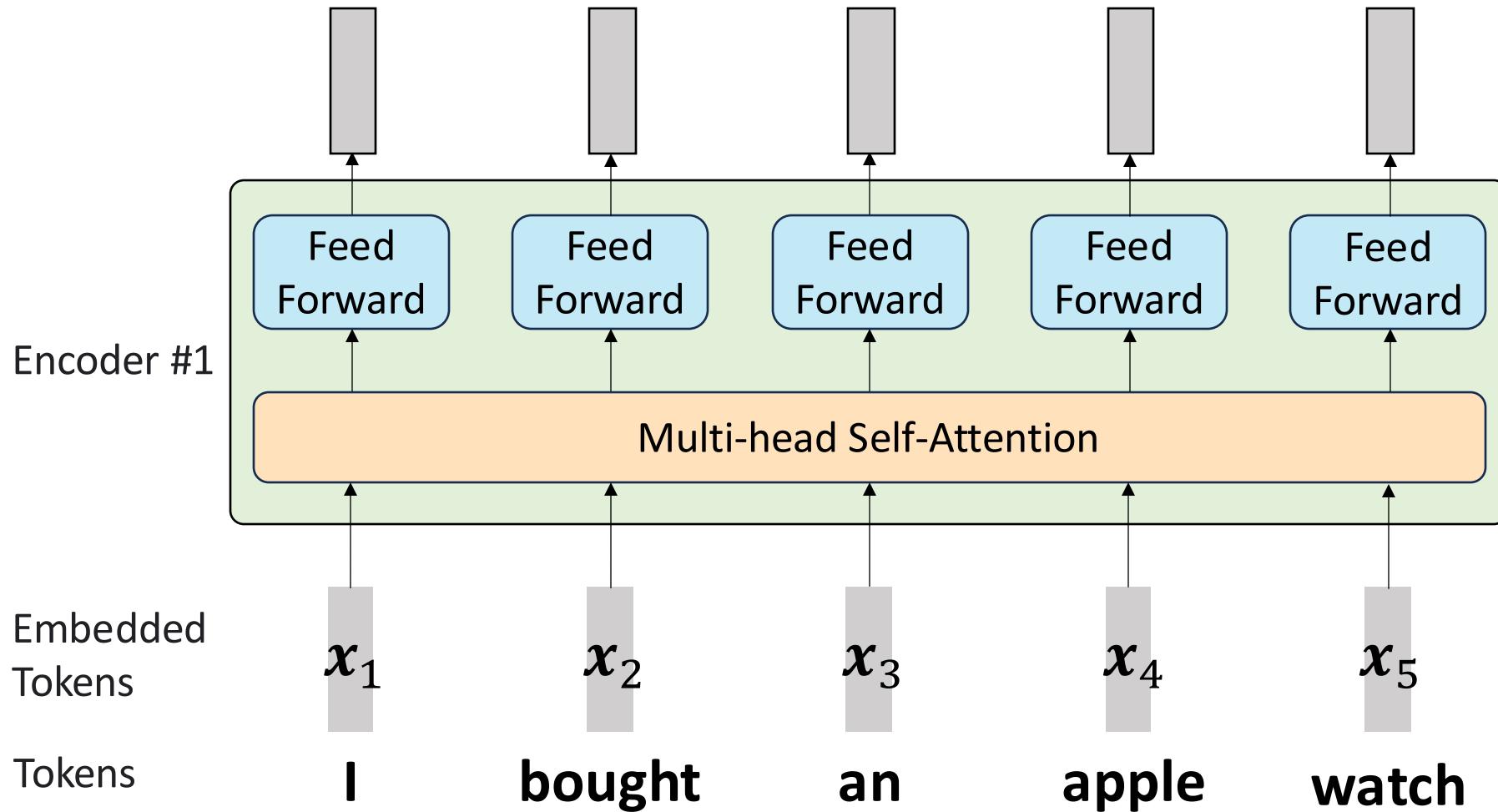






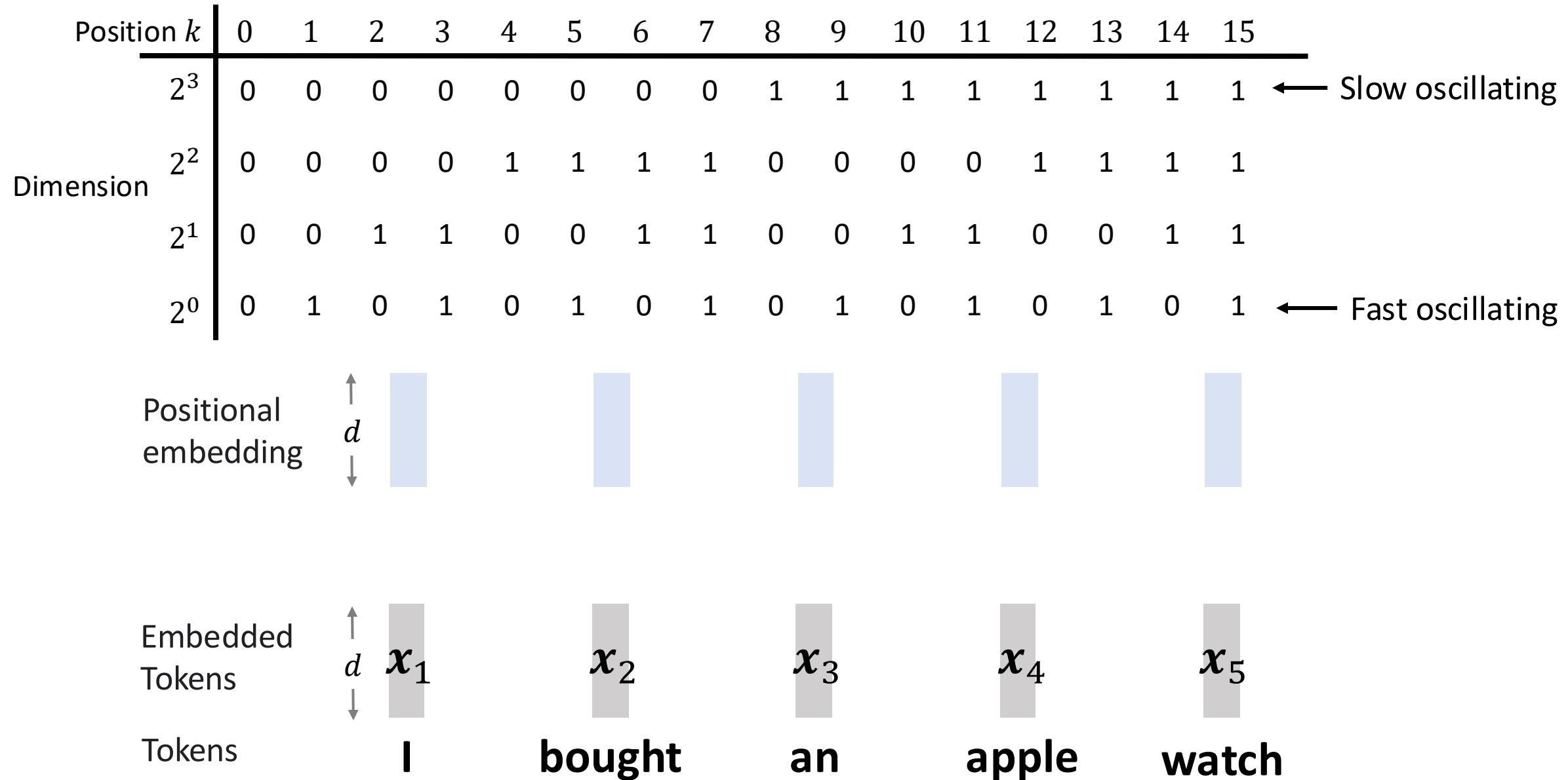


# Positional encoding





# Positional encoding





# Positional encoding

Position  $k$

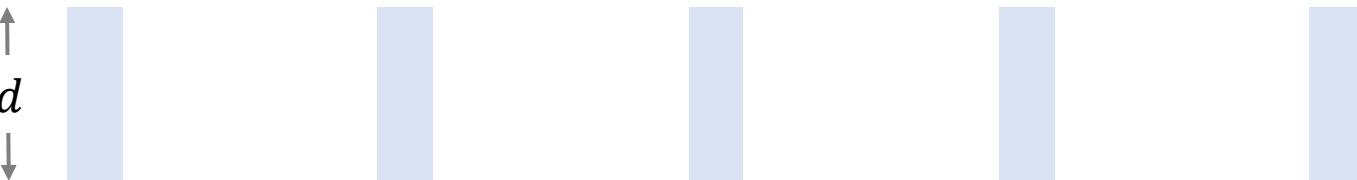
Angular frequency

$$w_i = N^{-2i/d}$$

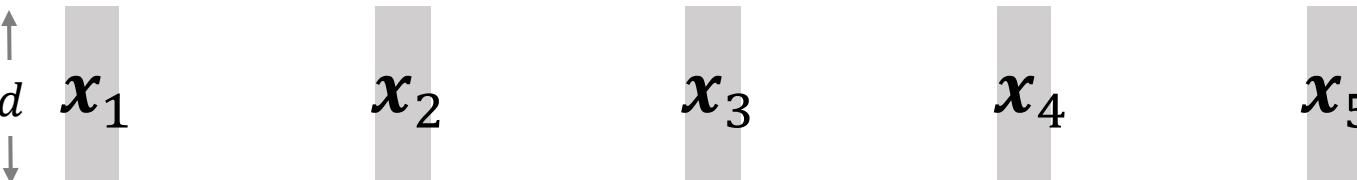
$$N = 100,000$$

$$\begin{bmatrix} \sin(w_0 k) \\ \cos(w_0 k) \\ \sin(w_1 k) \\ \cos(w_1 k) \\ \vdots \\ \vdots \\ \sin\left(w_{\frac{d}{2}-1} k\right) \\ \cos\left(w_{\frac{d}{2}-1} k\right) \end{bmatrix} \quad \begin{array}{l} \text{Fast oscillating} \\ \text{Slow oscillating} \end{array}$$

Positional  
embedding



Embedded  
Tokens



Tokens

I      bought      an      apple      watch



# Positional encoding

Position  $k$

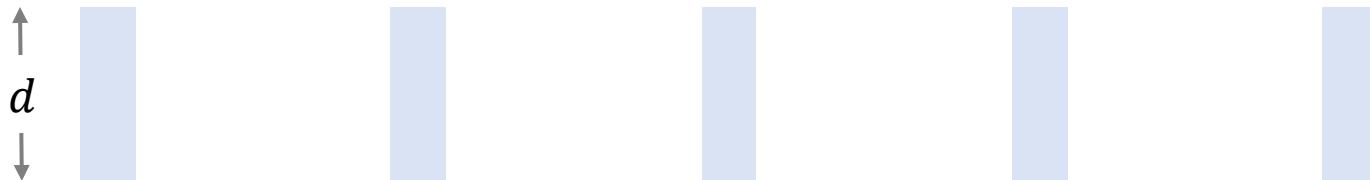
Angular frequency

$$w_i = N^{-2i/d}$$

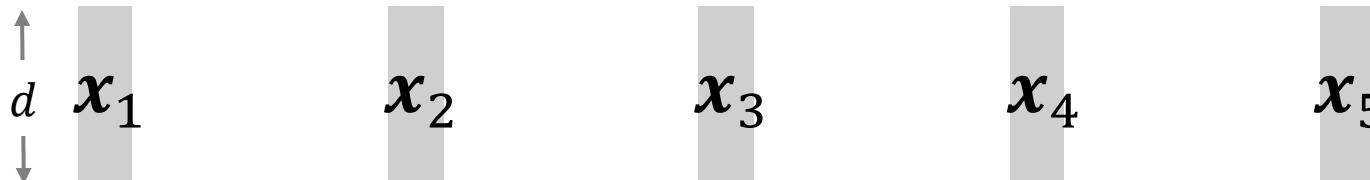
$$N = 100,000$$

$$\begin{bmatrix} \sin(w_0 k) \\ \cos(w_0 k) \\ \sin(w_1 k) \\ \cos(w_1 k) \\ \vdots \\ \vdots \\ \sin\left(w_{\frac{d}{2}-1} k\right) \\ \cos\left(w_{\frac{d}{2}-1} k\right) \end{bmatrix}$$

Positional  
embedding



Embedded  
Tokens



Tokens

I            bought            an            apple            watch



Normalized Range

Unique identifier, unlimited length

Relative positions as linear transform

$$\begin{bmatrix} \sin(w_i(k + \Delta k)) \\ \cos(w_i(k + \Delta k)) \end{bmatrix} = \begin{bmatrix} \sin(w_i k) \cos(w_i \Delta k) + \cos(w_i k) \sin(w_i \Delta k) \\ \cos(w_i k) \cos(w_i \Delta k) - \sin(w_i k) \sin(w_i \Delta k) \end{bmatrix}$$



# Positional encoding

Position  $k$

Angular frequency

$$w_i = N^{-2i/d}$$

$$N = 100,000$$

$$\begin{bmatrix} \sin(w_0 k) \\ \cos(w_0 k) \\ \sin(w_1 k) \\ \cos(w_1 k) \\ \vdots \\ \vdots \\ \sin\left(w_{\frac{d}{2}-1} k\right) \\ \cos\left(w_{\frac{d}{2}-1} k\right) \end{bmatrix}$$

Positional  
embedding

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ P_1 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ P_2 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ P_3 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ P_4 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ P_5 \end{array}$$

$$P_{k+\Delta k} = M P_k$$

Embedded  
Tokens

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ x_1 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ x_2 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ x_3 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ x_4 \end{array}$$

$$\begin{array}{c} \uparrow \\ d \\ \downarrow \\ x_5 \end{array}$$

Tokens

I bought an apple watch

bought

an

apple

watch



**Normalized Range**



**Unique identifier, unlimited length**

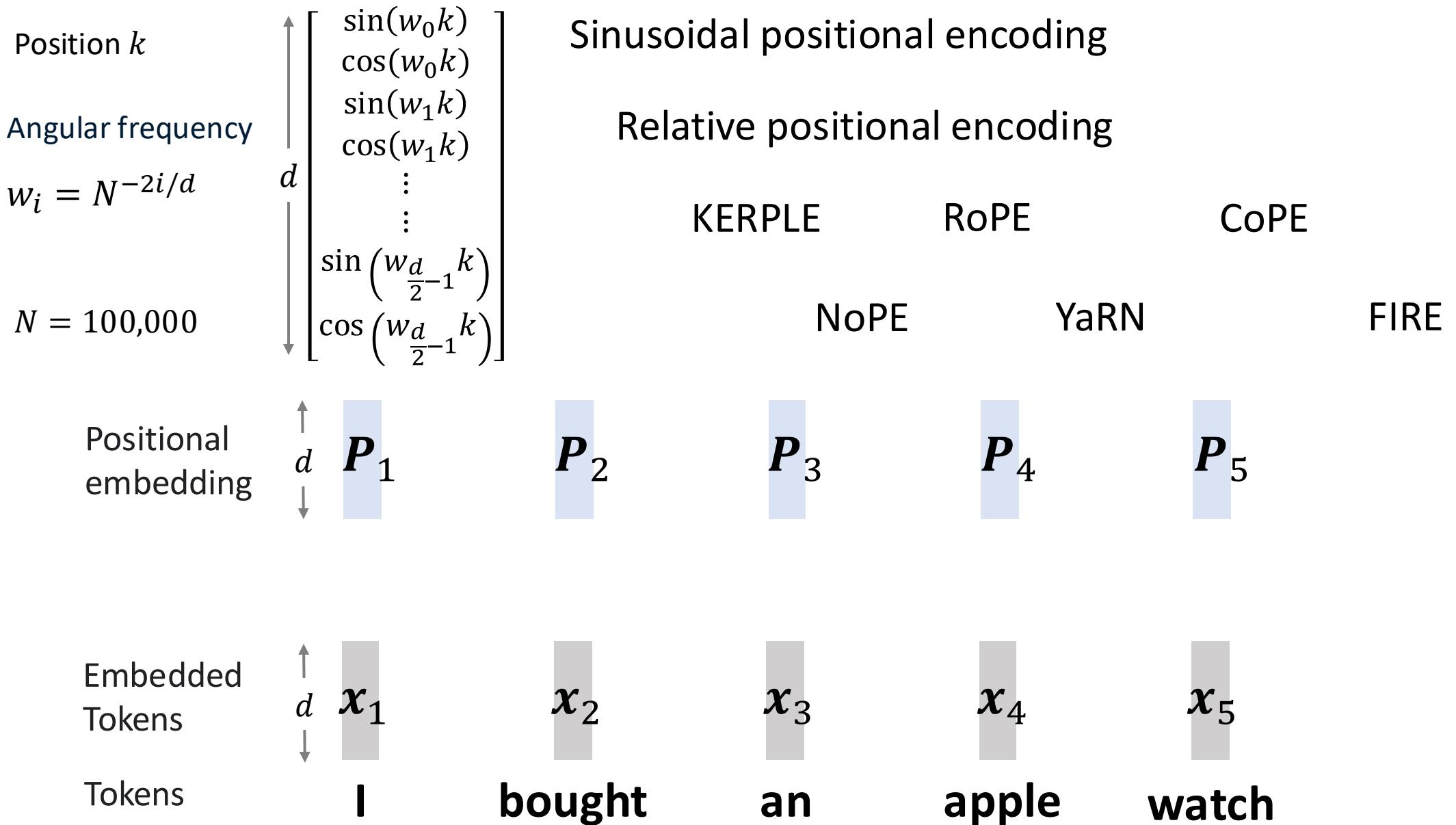


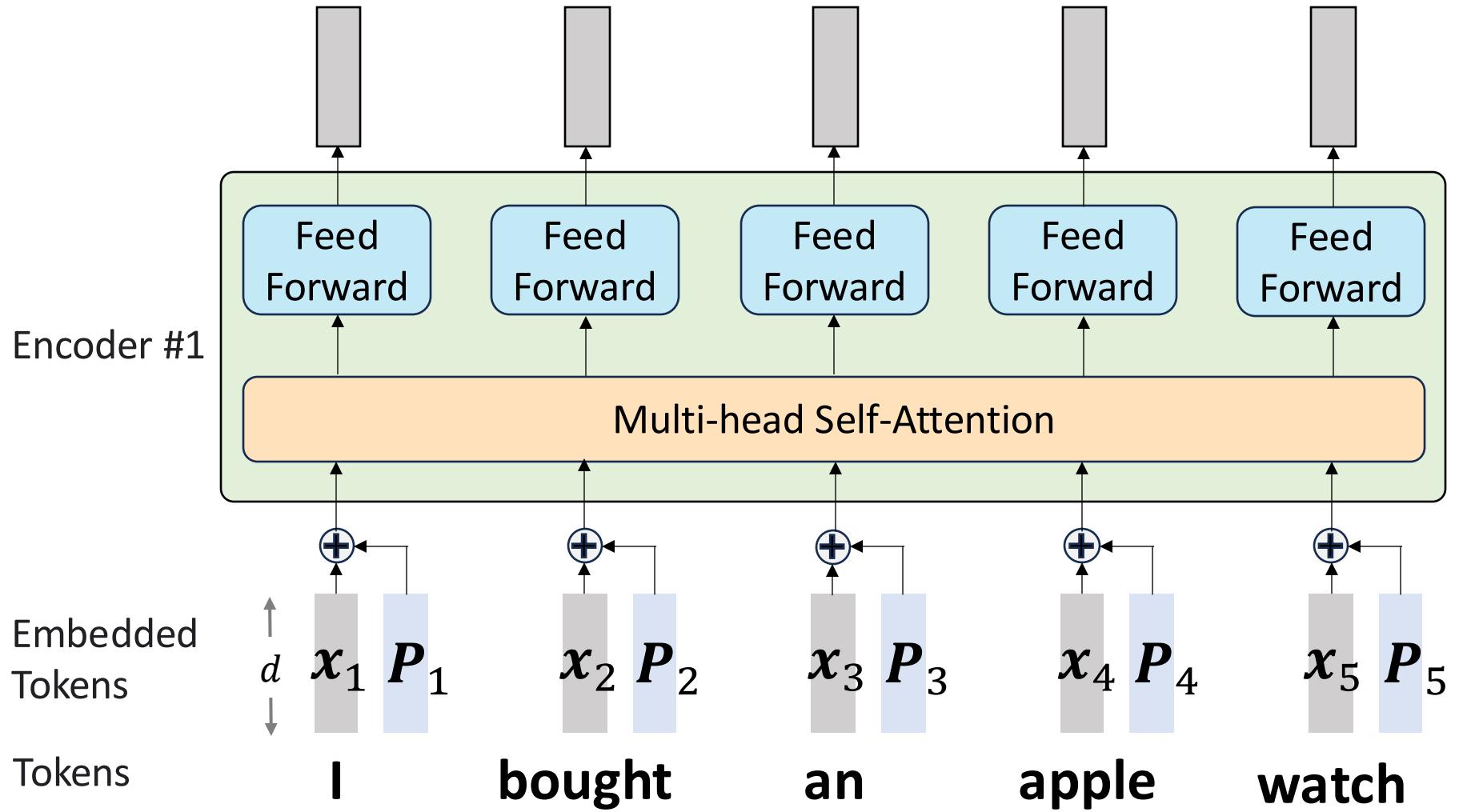
**Relative positions as linear transform**

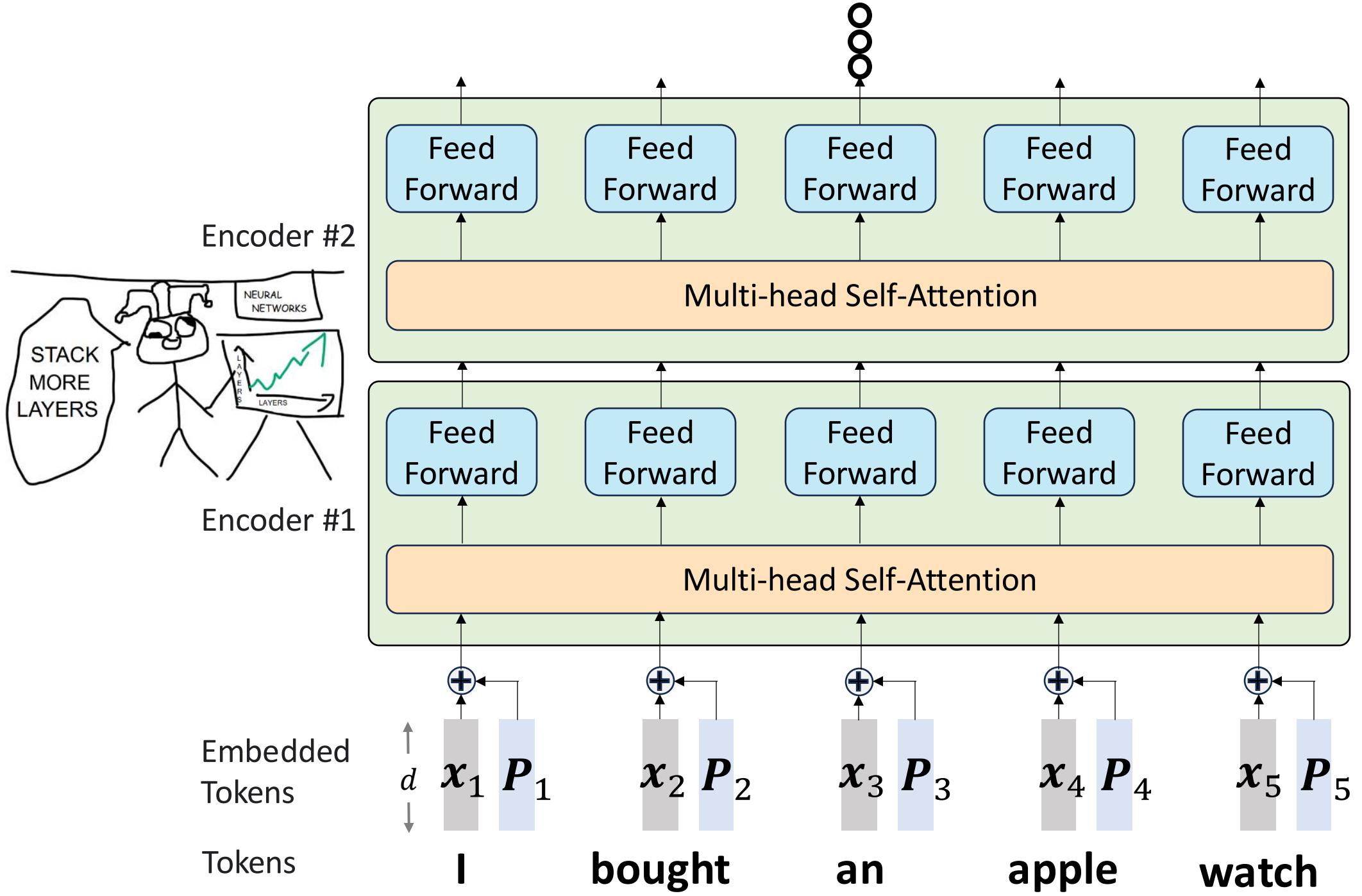
$$\begin{aligned} \begin{bmatrix} \sin(w_i(k + \Delta k)) \\ \cos(w_i(k + \Delta k)) \end{bmatrix} &= \begin{bmatrix} \sin(w_i k) \cos(w_i \Delta k) + \cos(w_i k) \sin(w_i \Delta k) \\ \cos(w_i k) \cos(w_i \Delta k) - \sin(w_i k) \sin(w_i \Delta k) \end{bmatrix} \\ &= \begin{bmatrix} \cos(w_i \Delta k) & \sin(w_i \Delta k) \\ -\sin(w_i \Delta k) & \cos(w_i \Delta k) \end{bmatrix} \begin{bmatrix} \sin(w_i k) \\ \cos(w_i k) \end{bmatrix} \end{aligned}$$

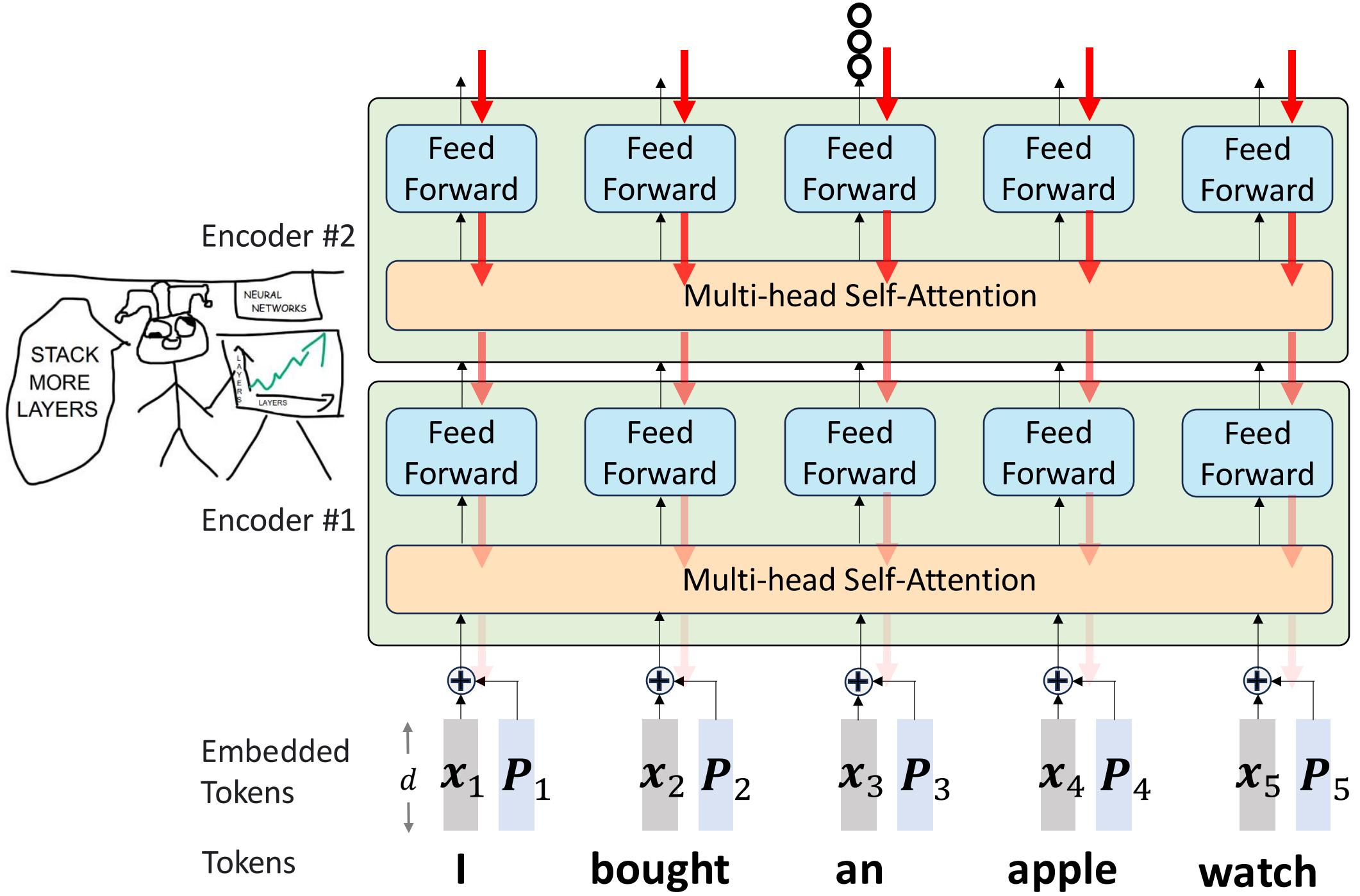


# Positional encoding



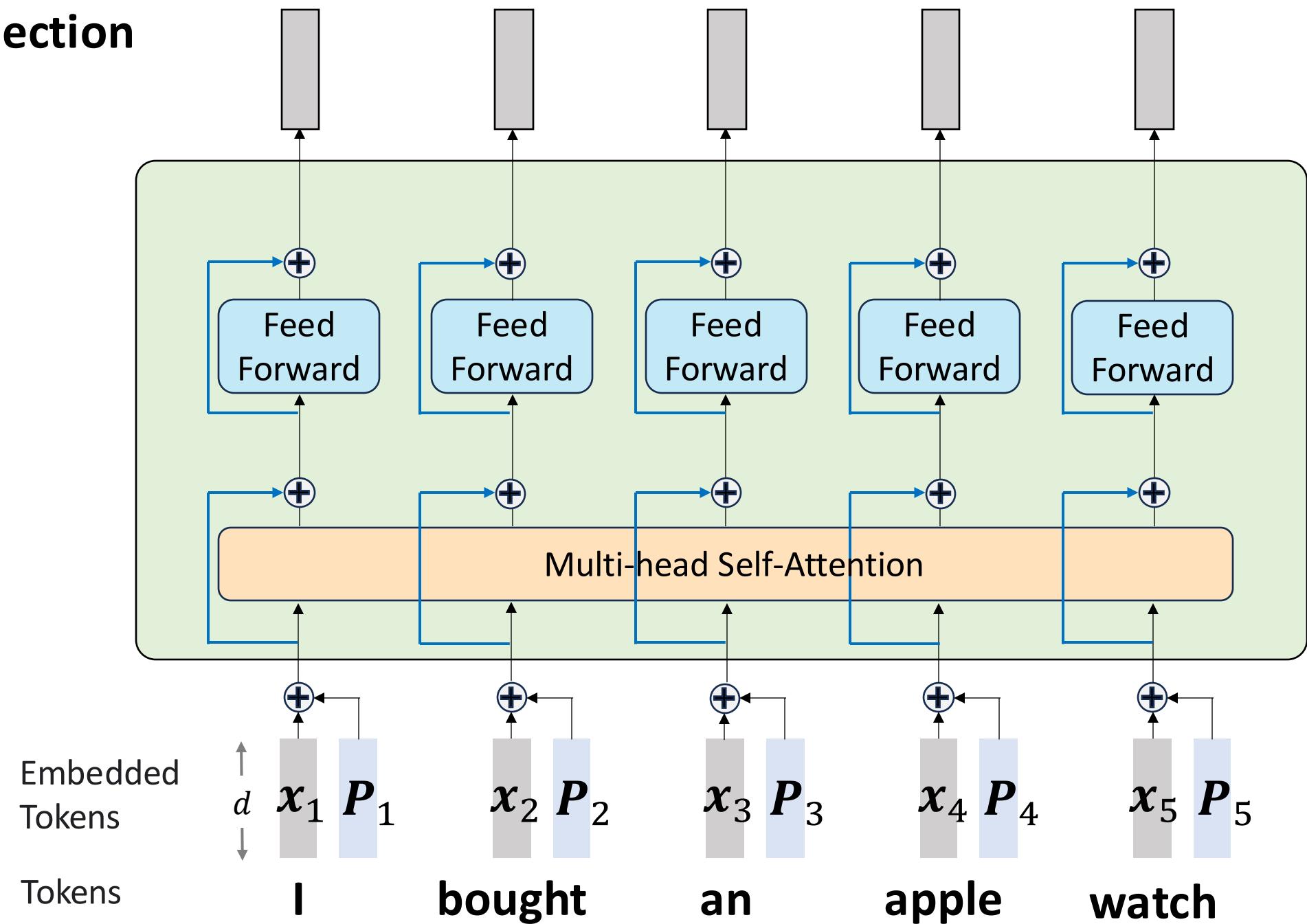






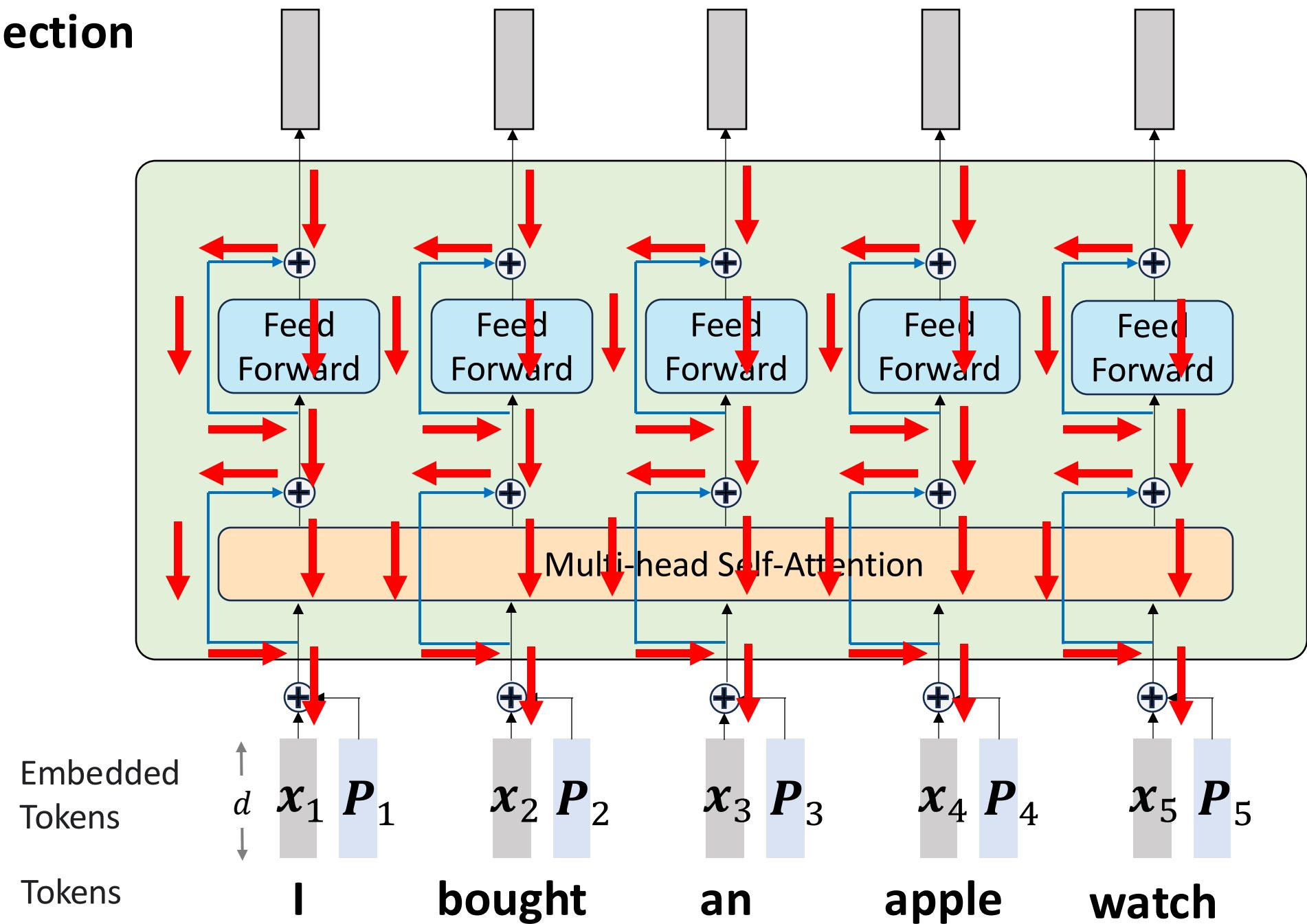


# Residual connection





# Residual connection

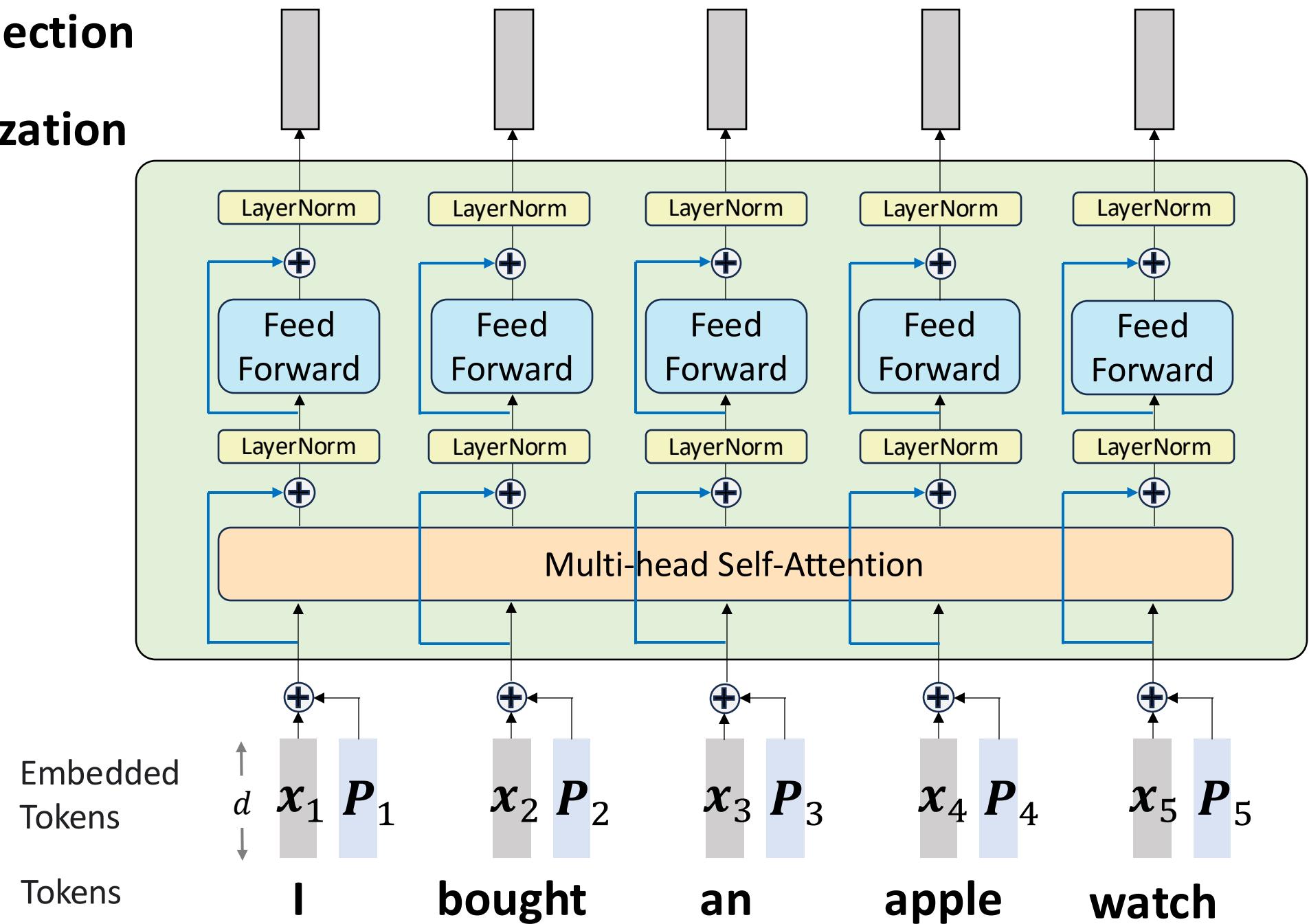




## Residual connection



## Layer normalization





## Residual connection



## Layer normalization

$\text{LayerNorm}(x) =$

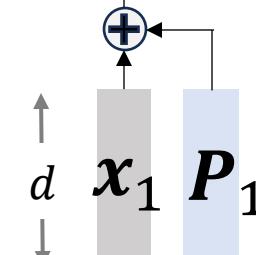
$$\gamma \left( \frac{x - \text{mean}(x)}{\sqrt{\text{Variance}(x) + \epsilon}} \right) + \beta$$

$\gamma, \beta \in R$

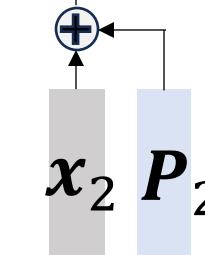
Learnable parameters

Embedded  
Tokens

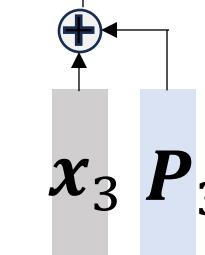
Tokens



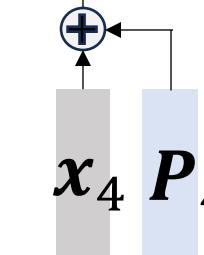
I



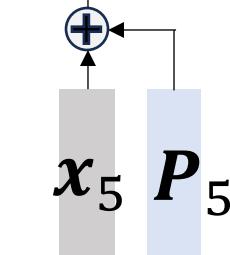
bought



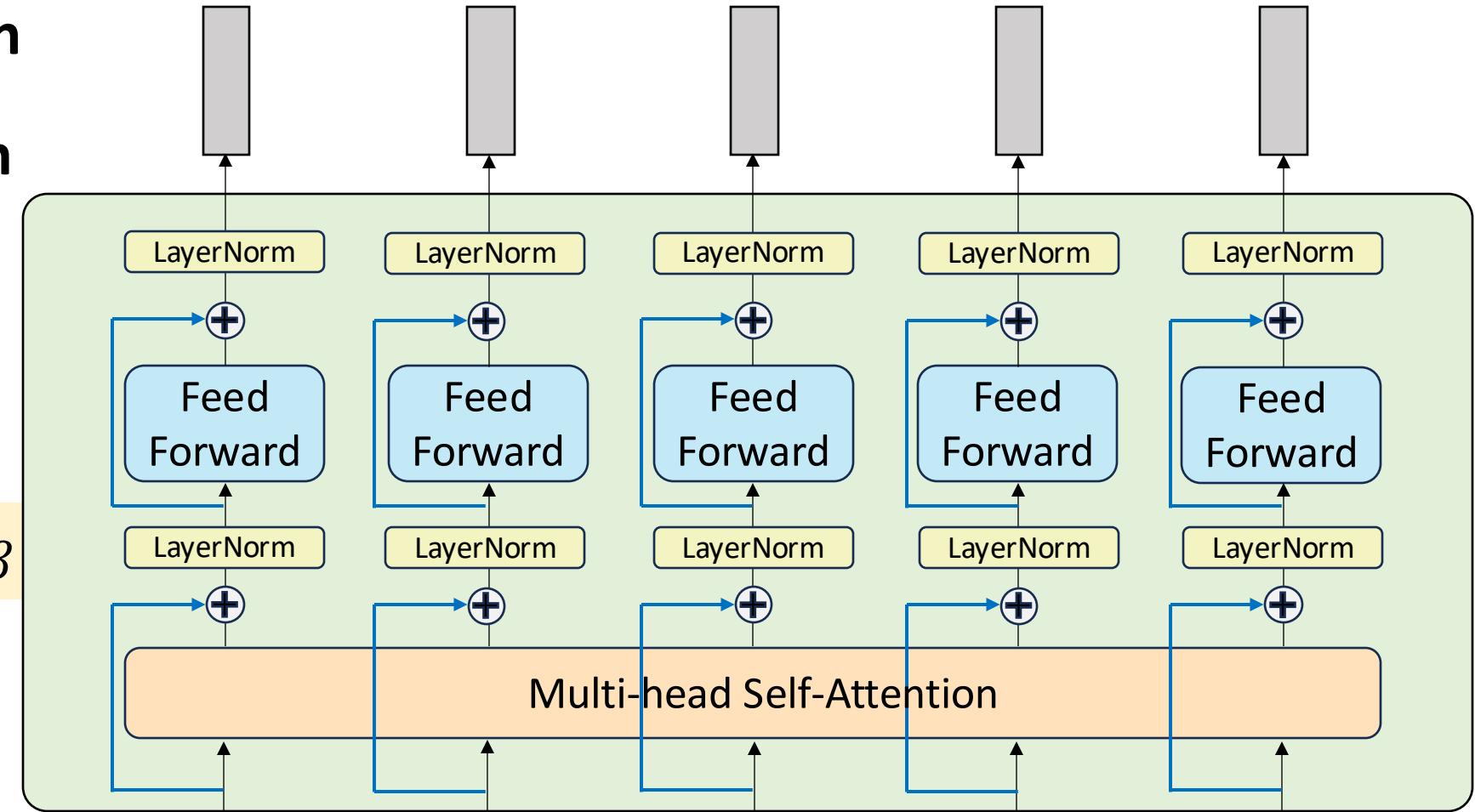
an



apple



watch





## Residual connection



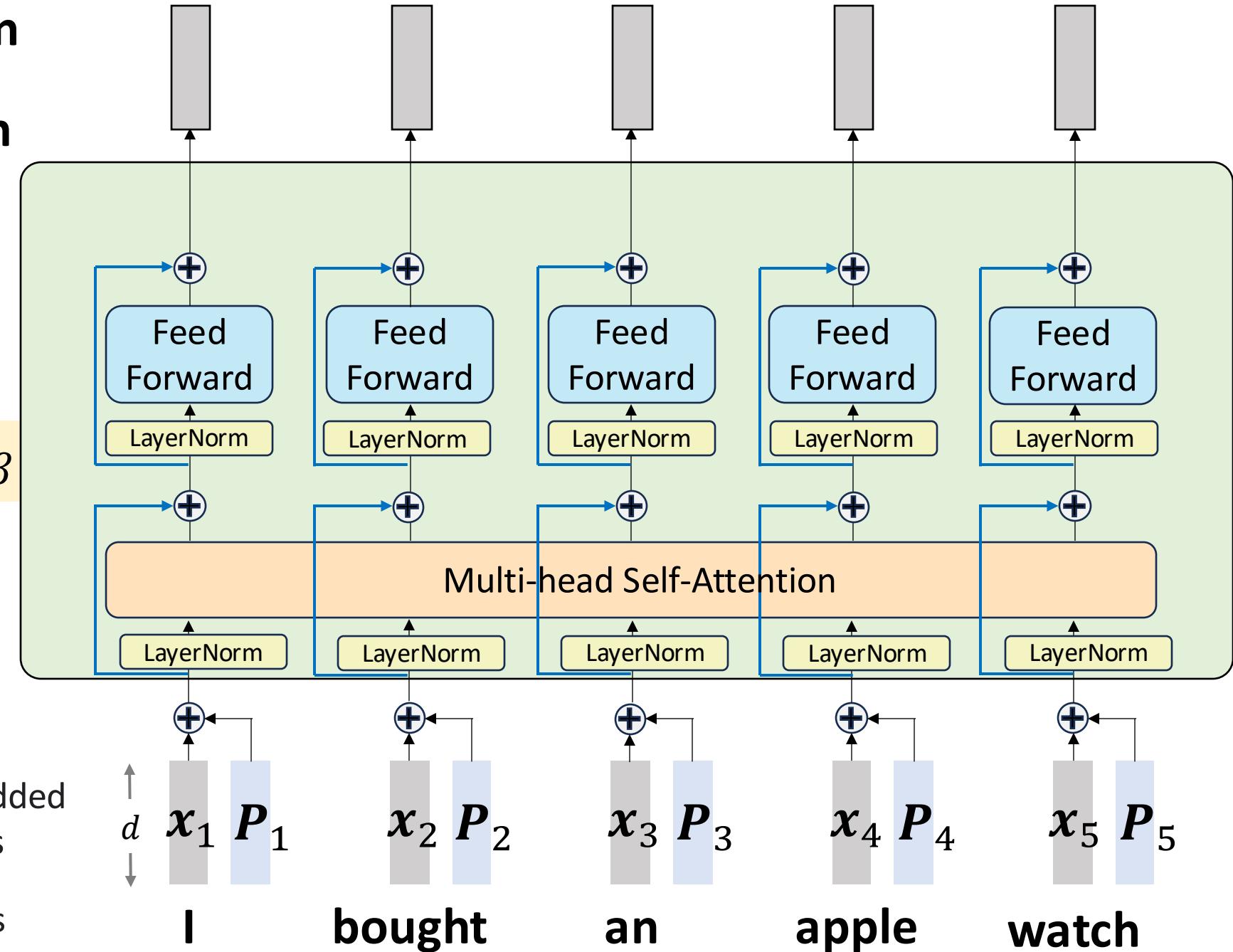
# Layer normalization

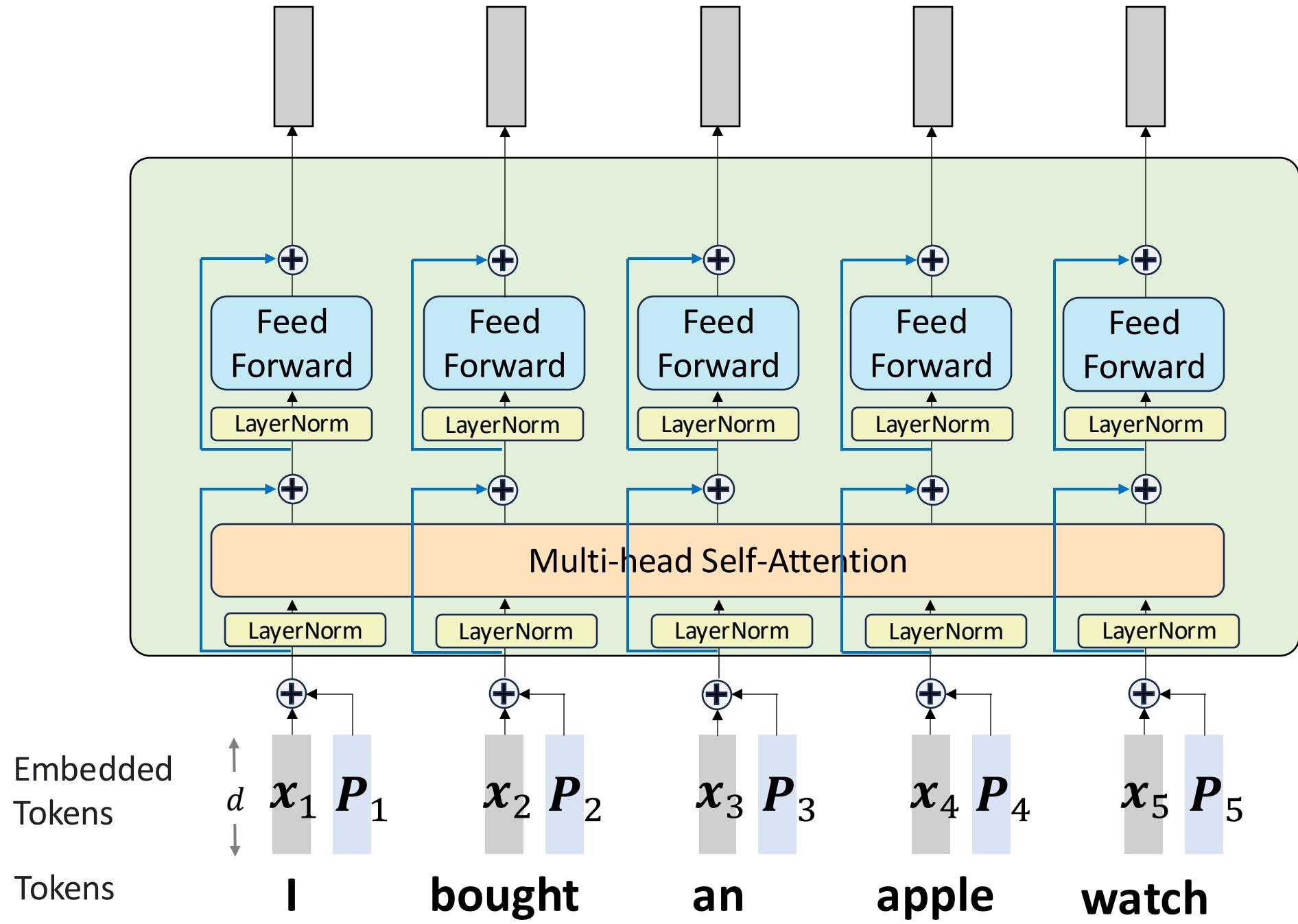
LayerNorm( $x$ ) =

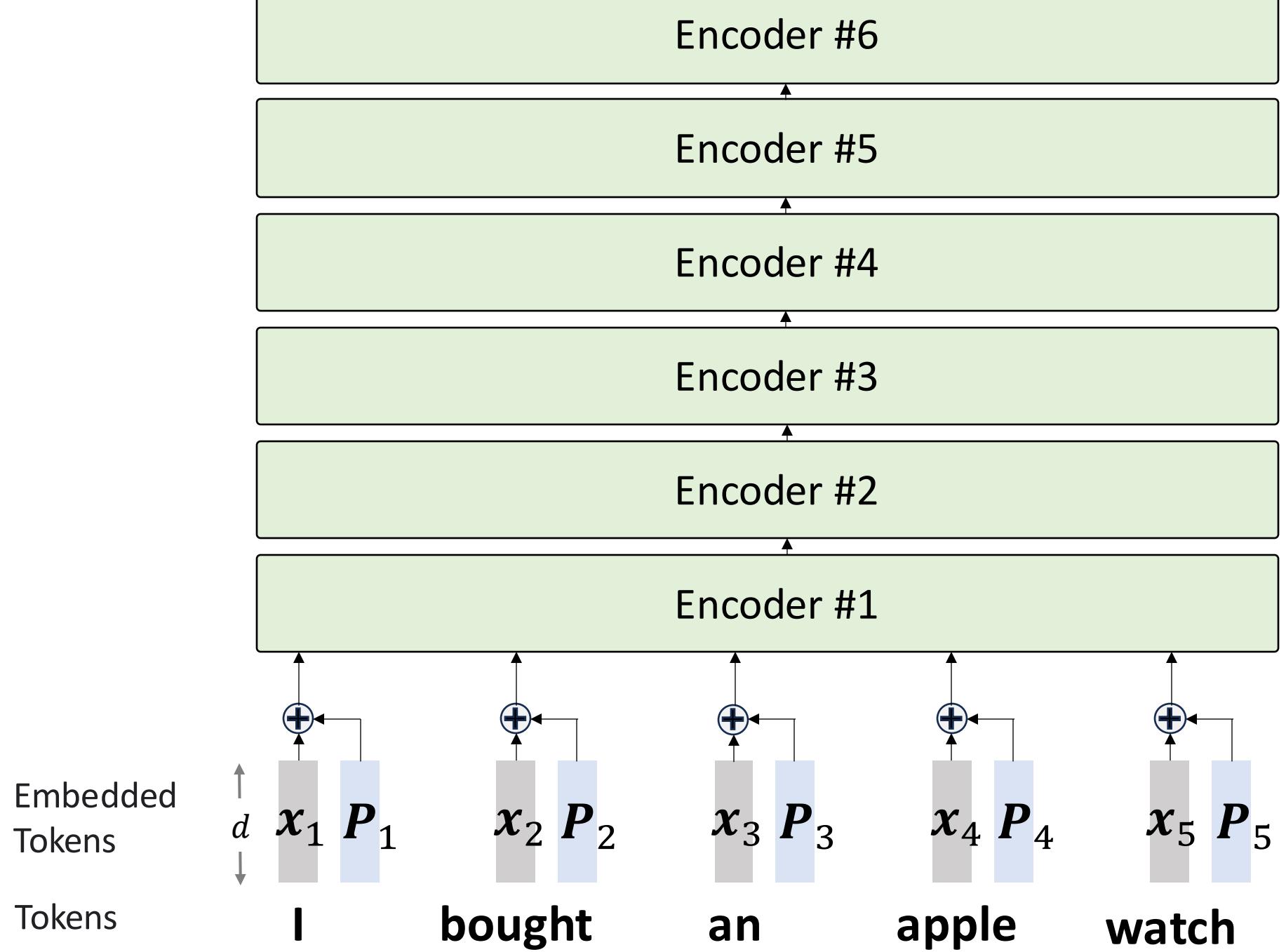
$$\gamma \left( \frac{x - \text{mean}(x)}{\sqrt{\text{Variance}(x) + \epsilon}} \right) + \beta$$

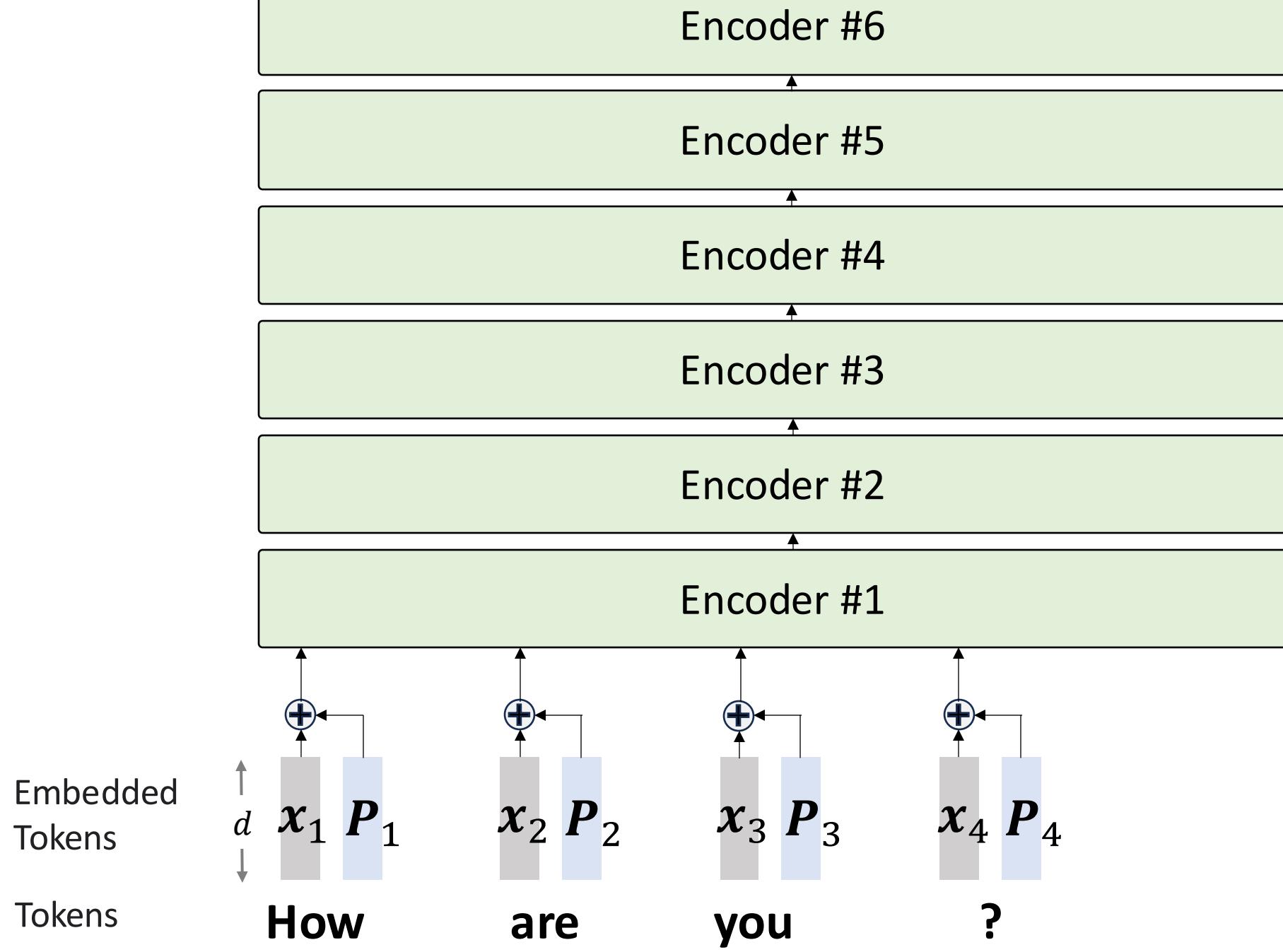
$$\gamma, \beta \in R$$

## Learnable parameters





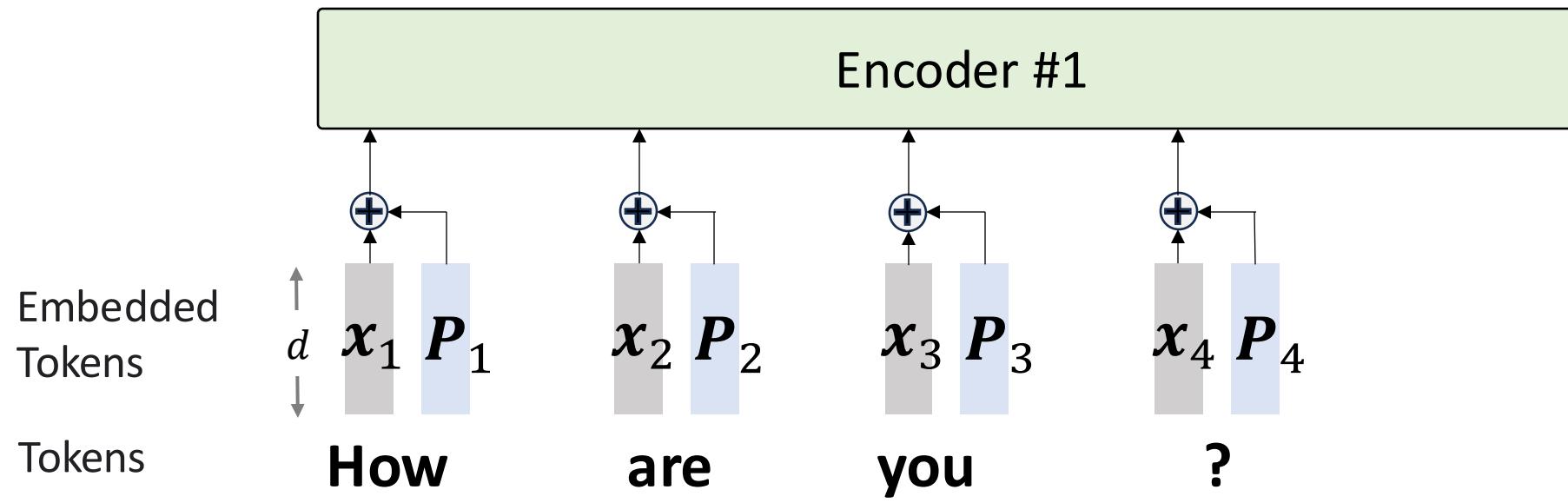


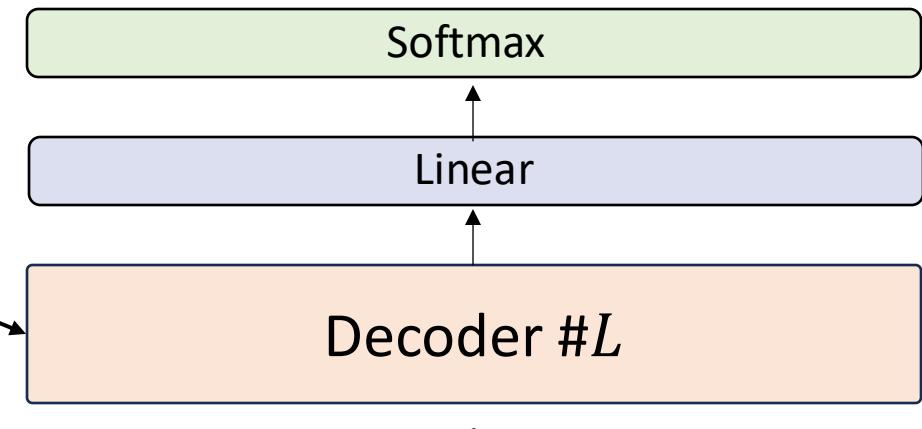
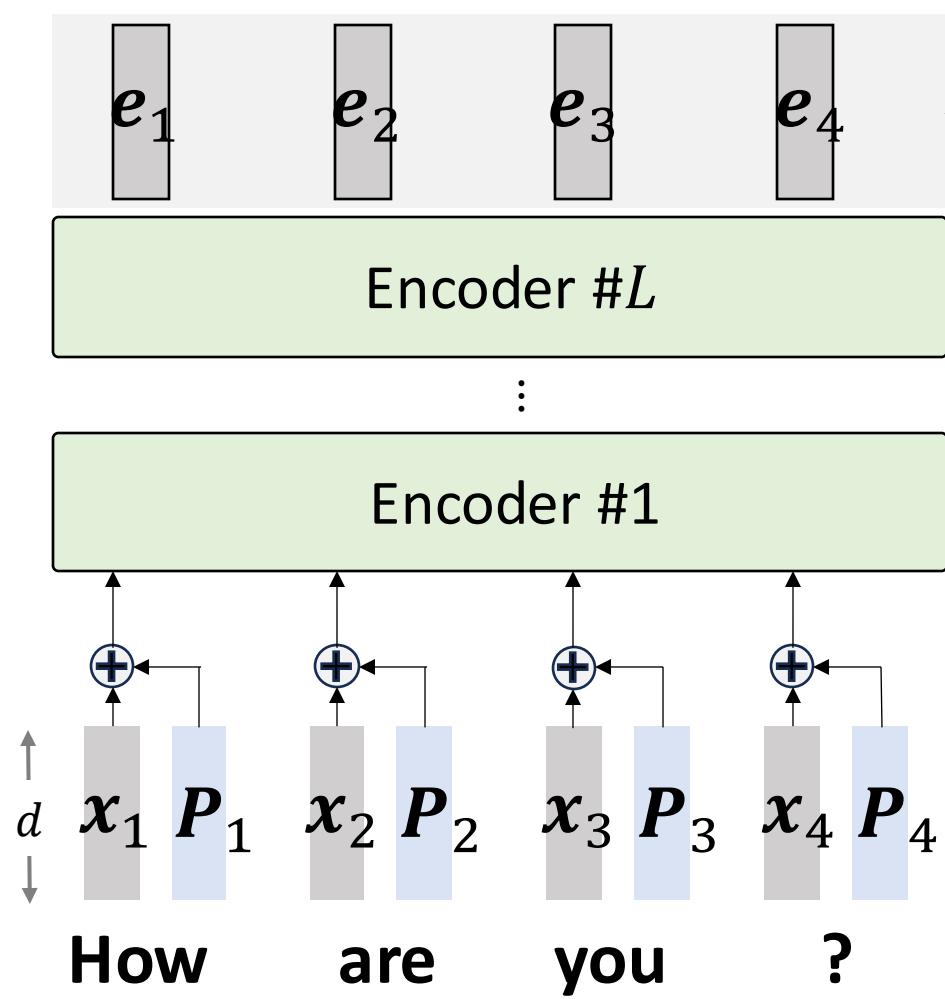
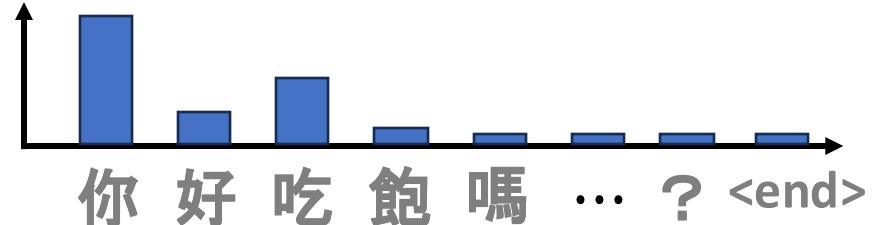


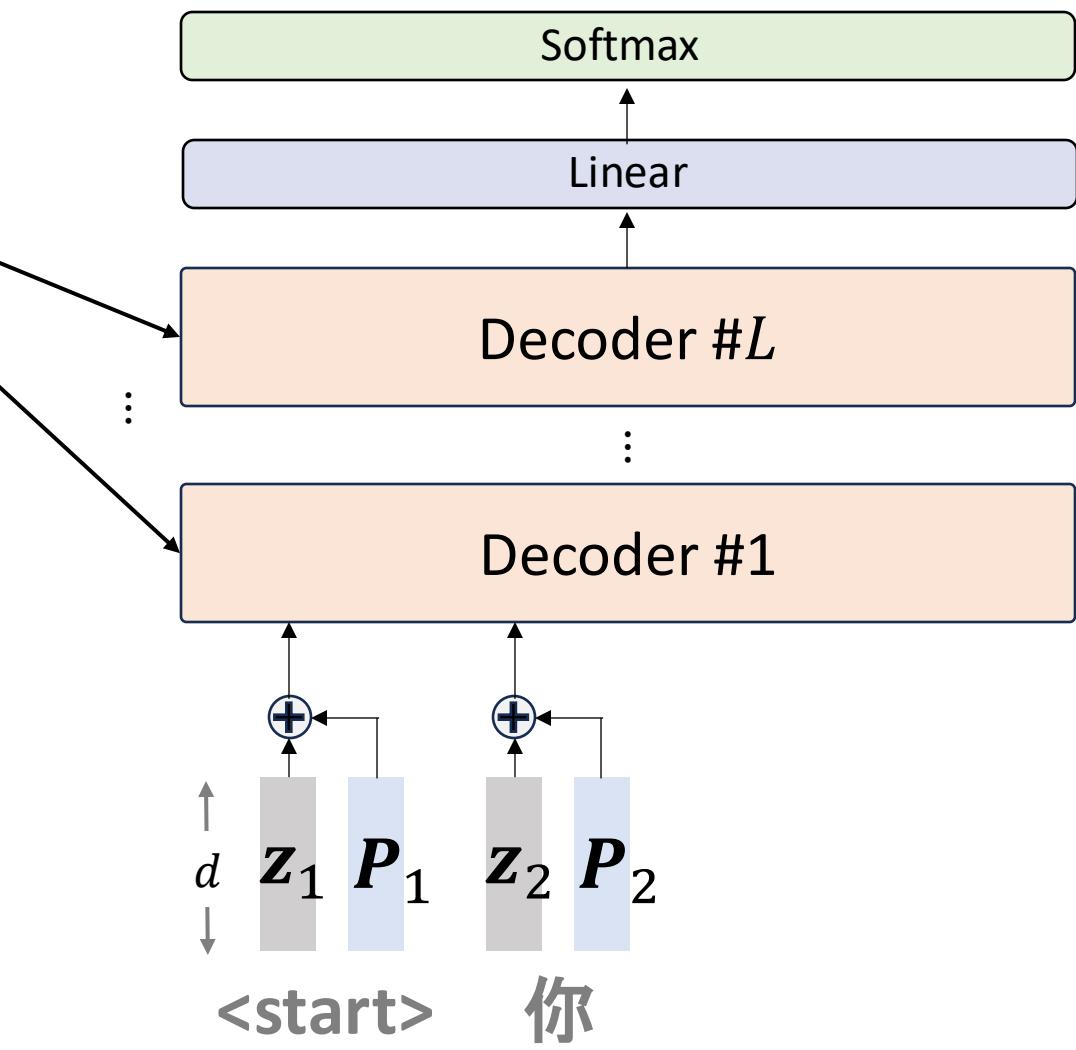
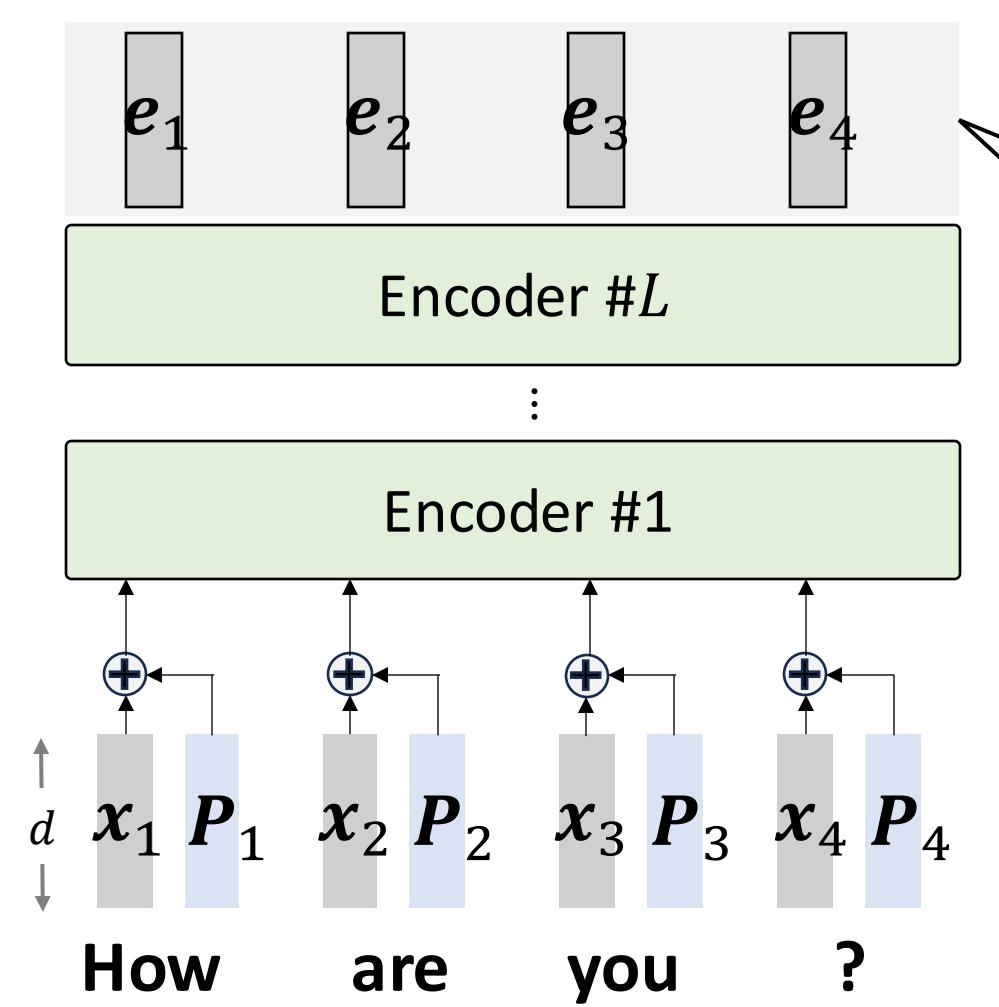
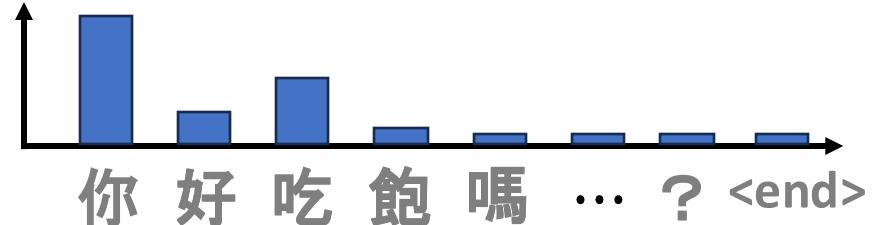
## Encoder #6

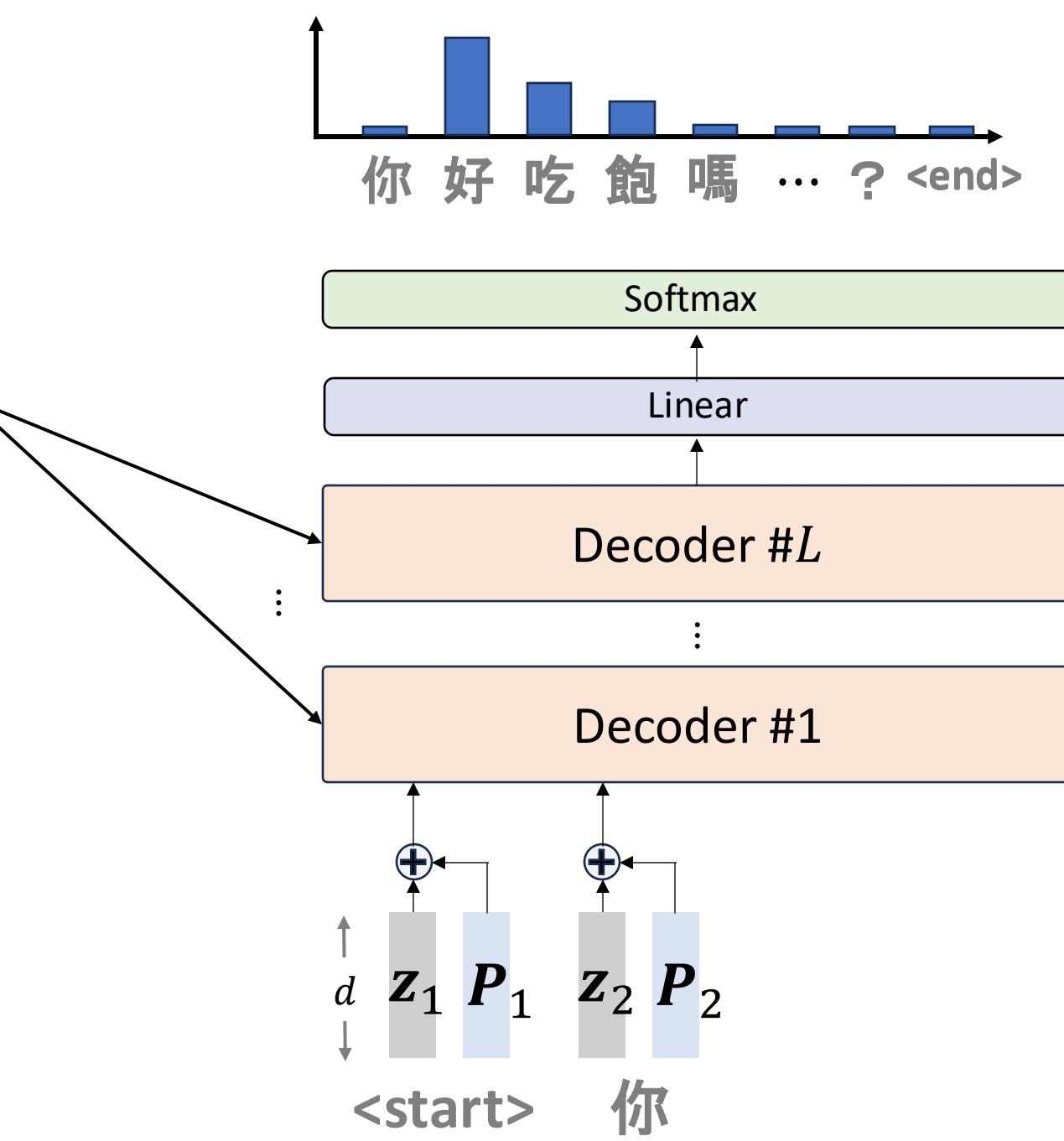
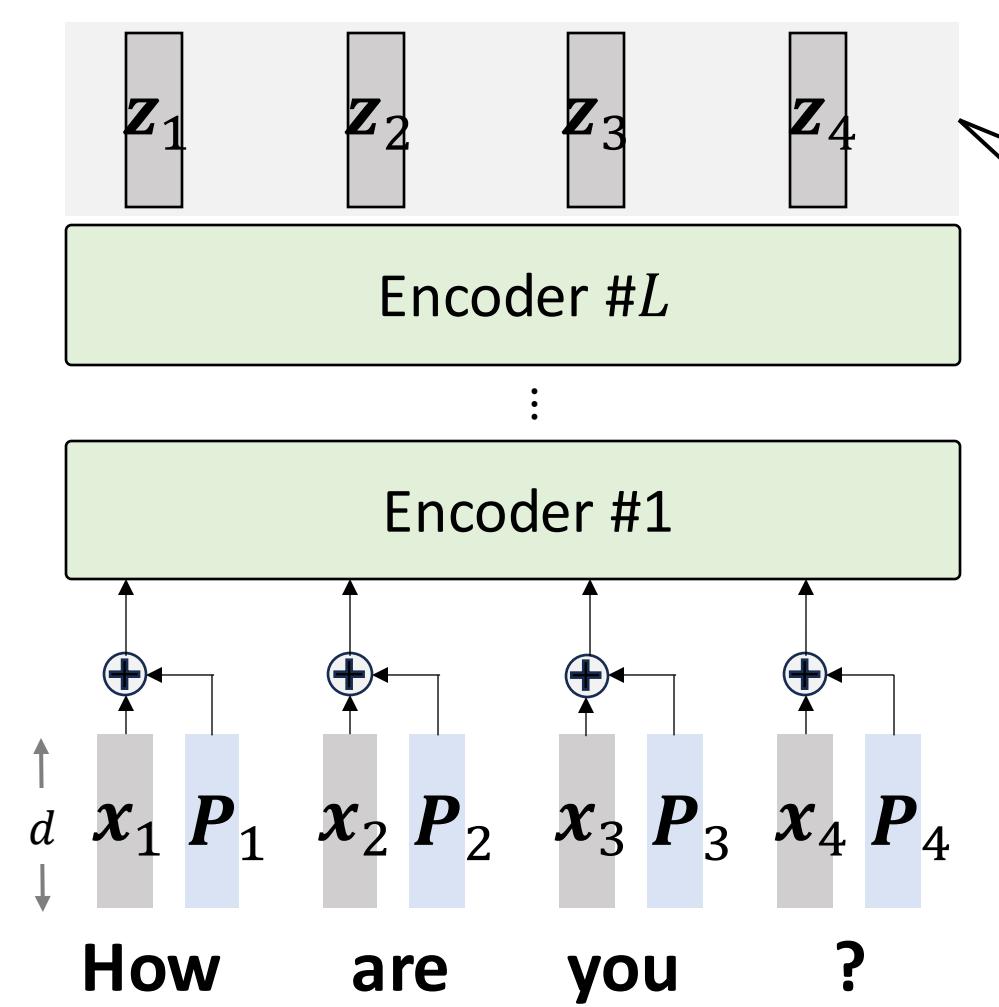
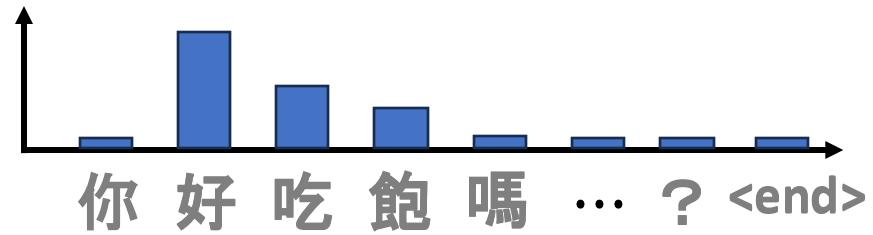
:

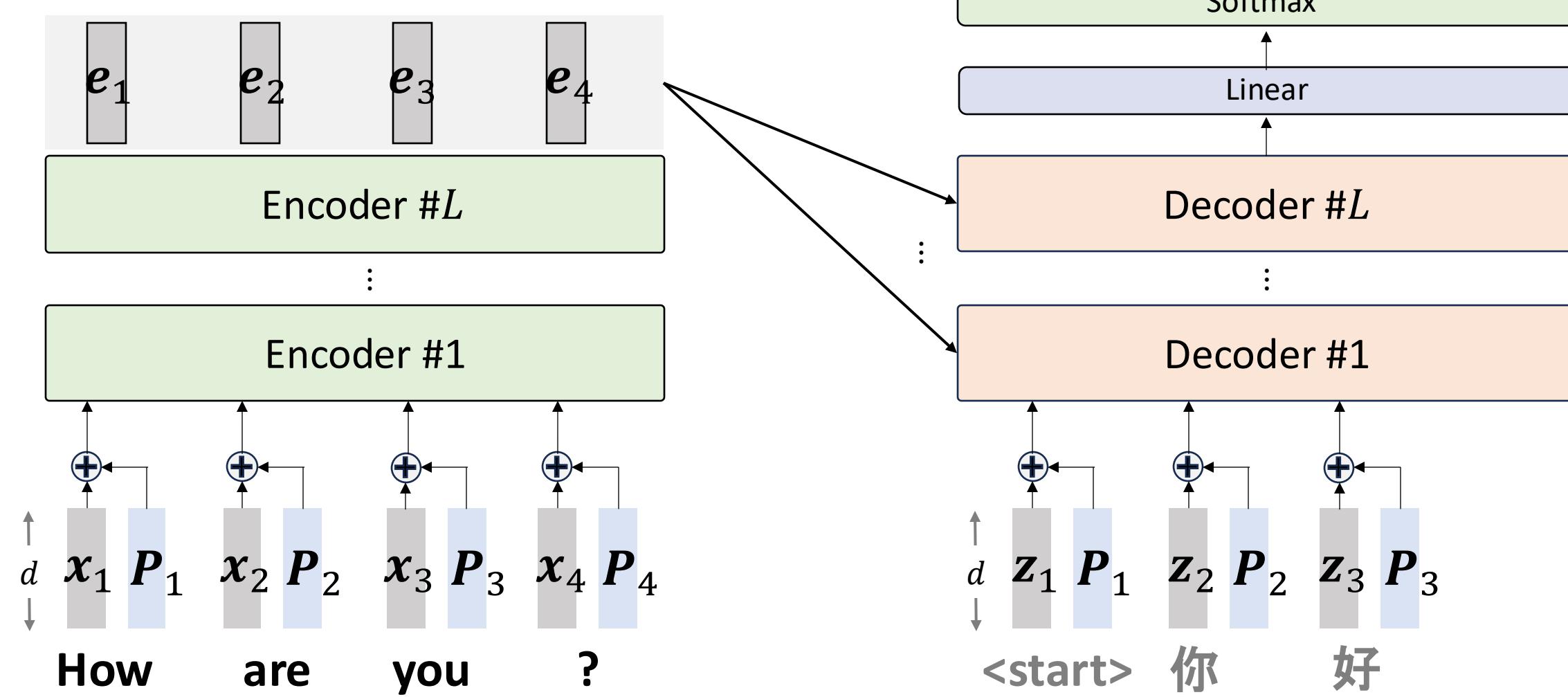
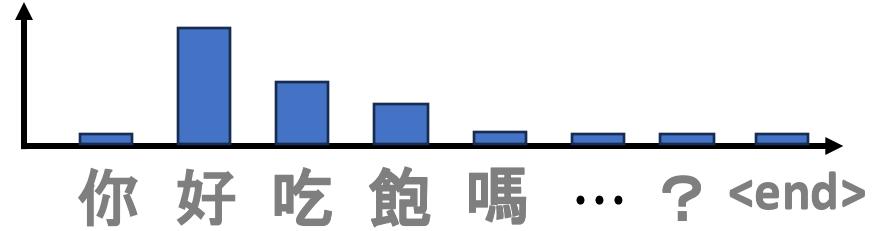
## Encoder #1

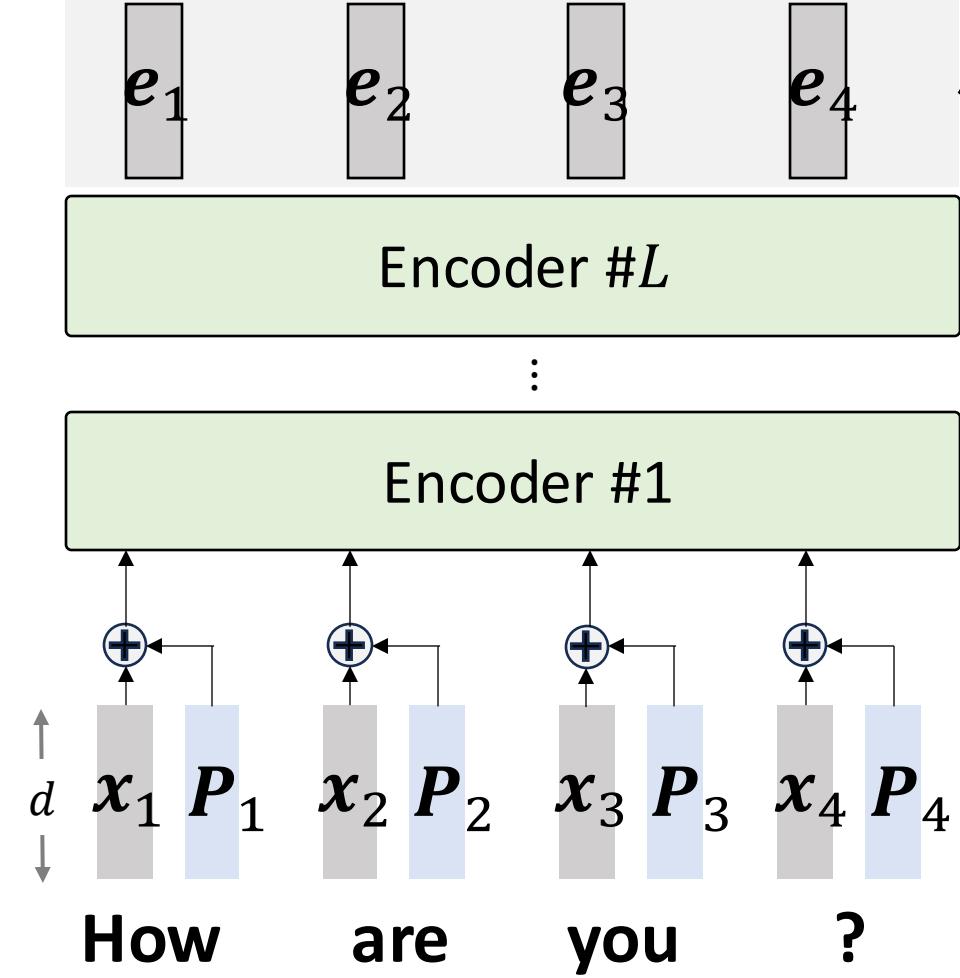
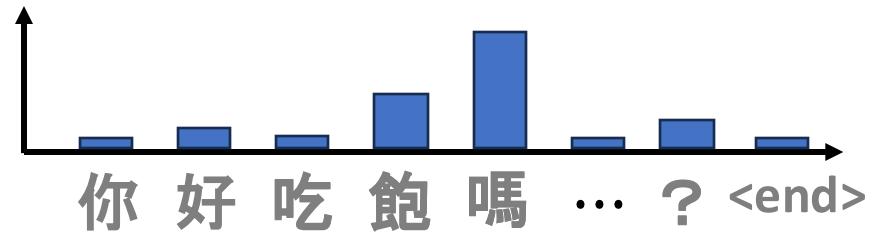


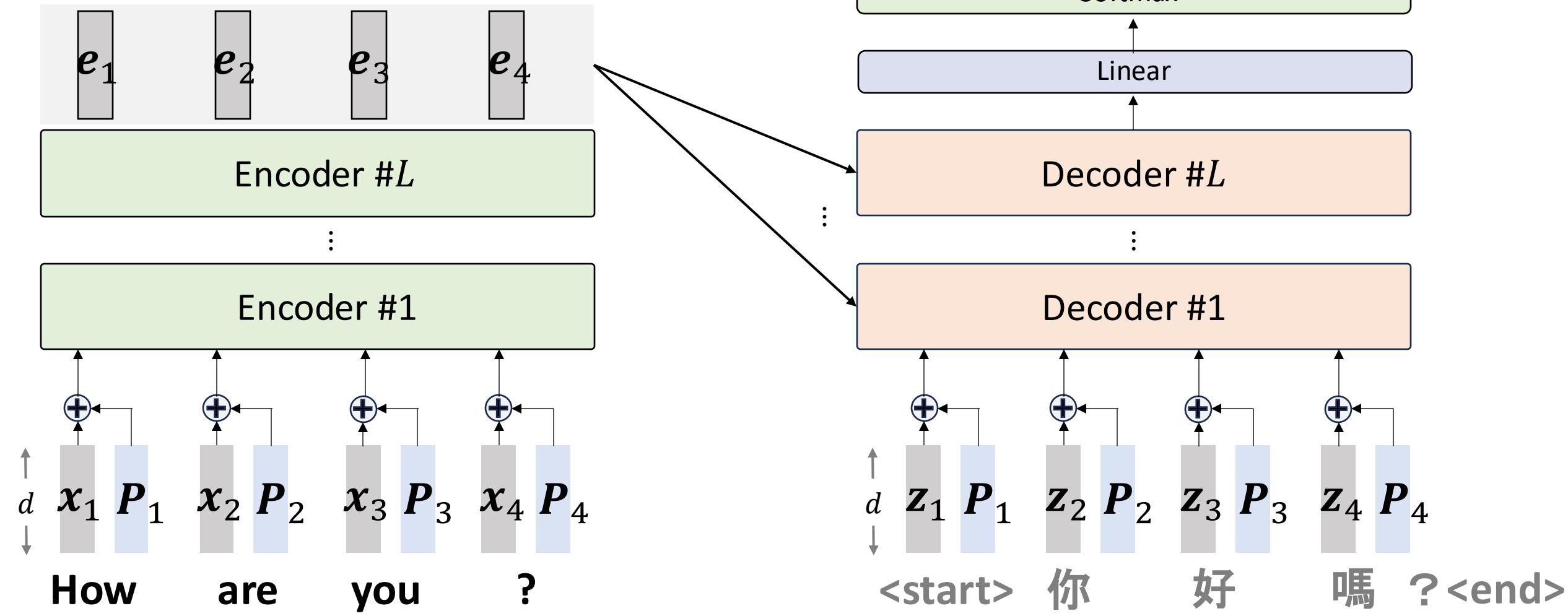
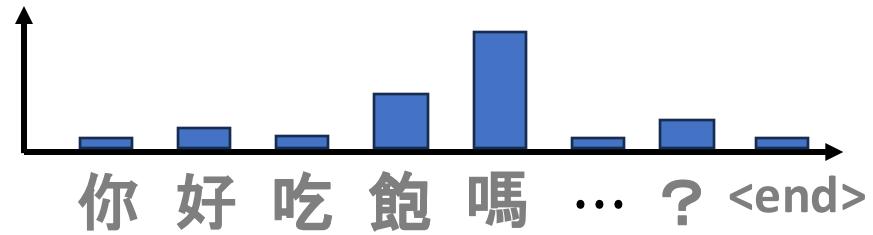


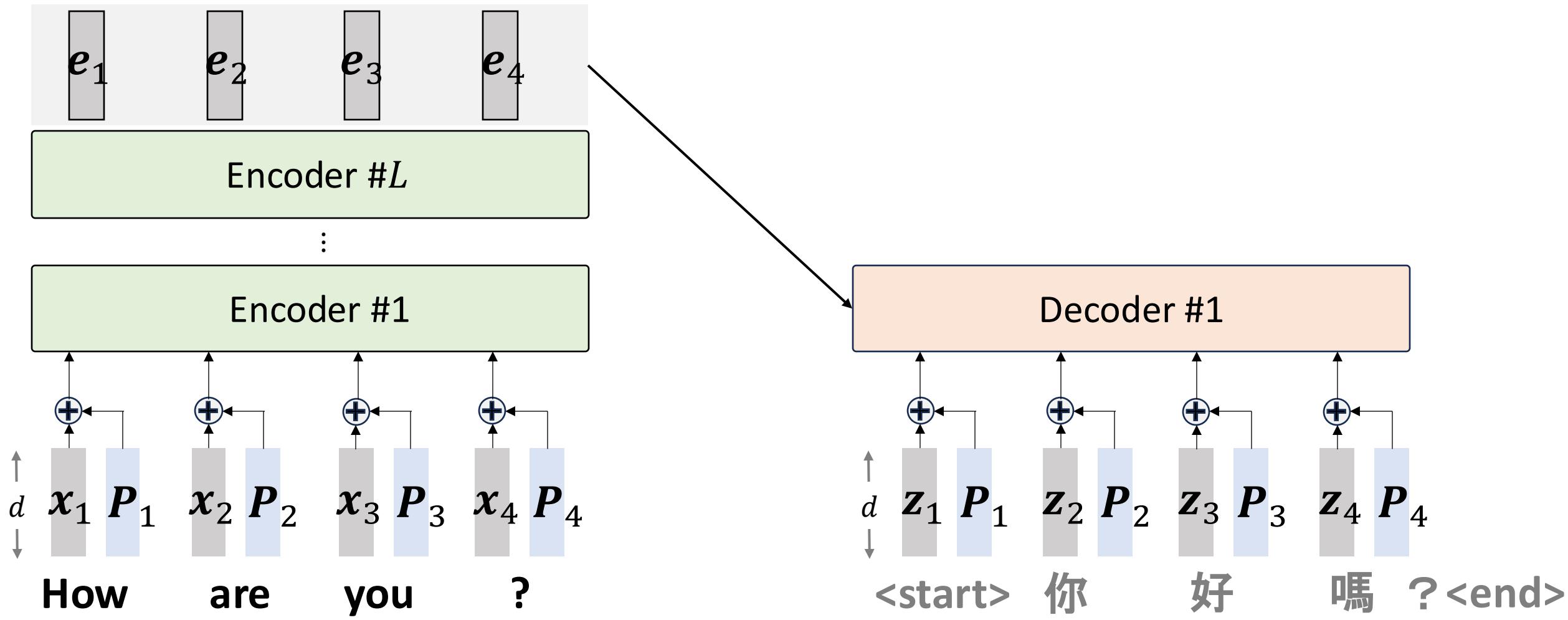


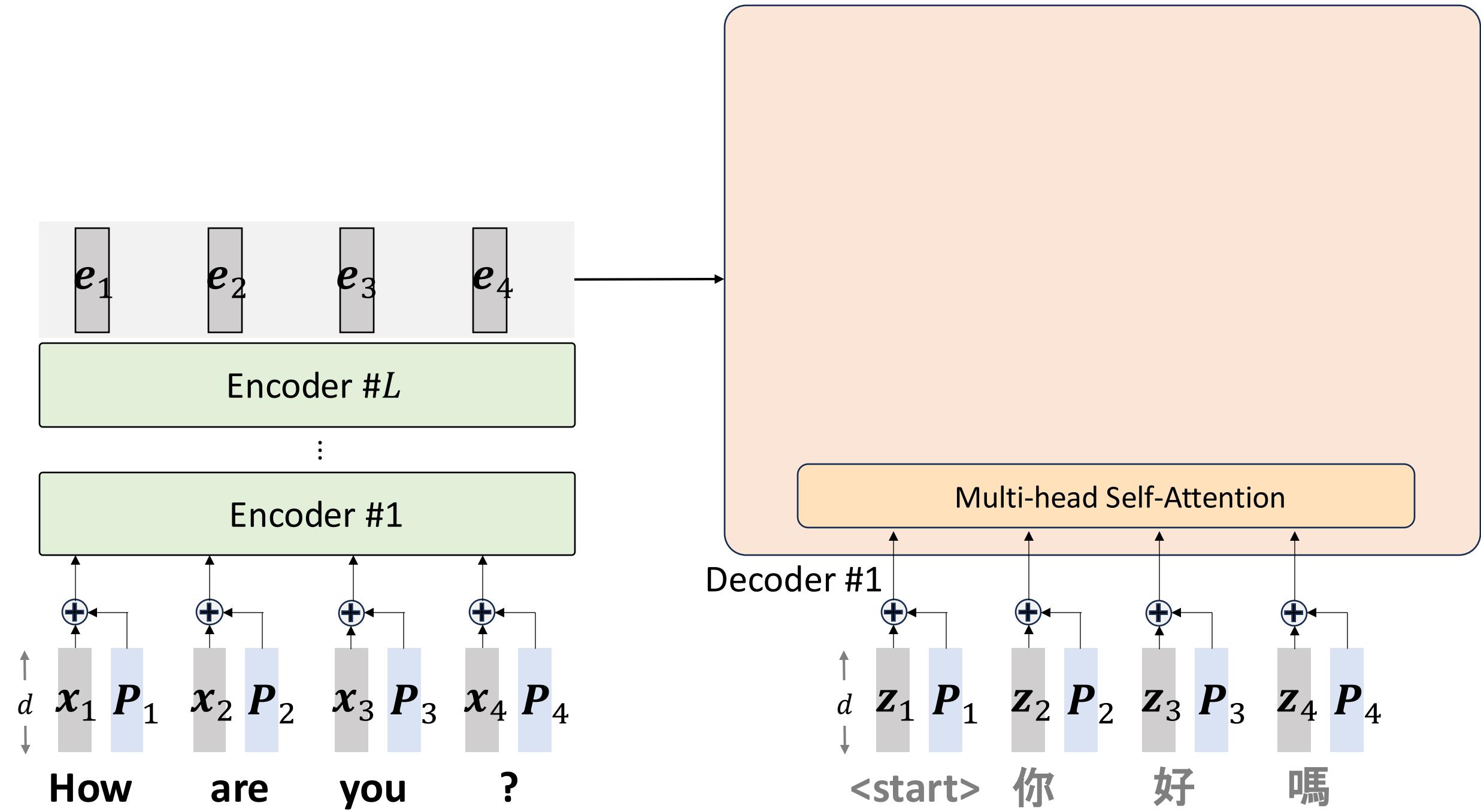


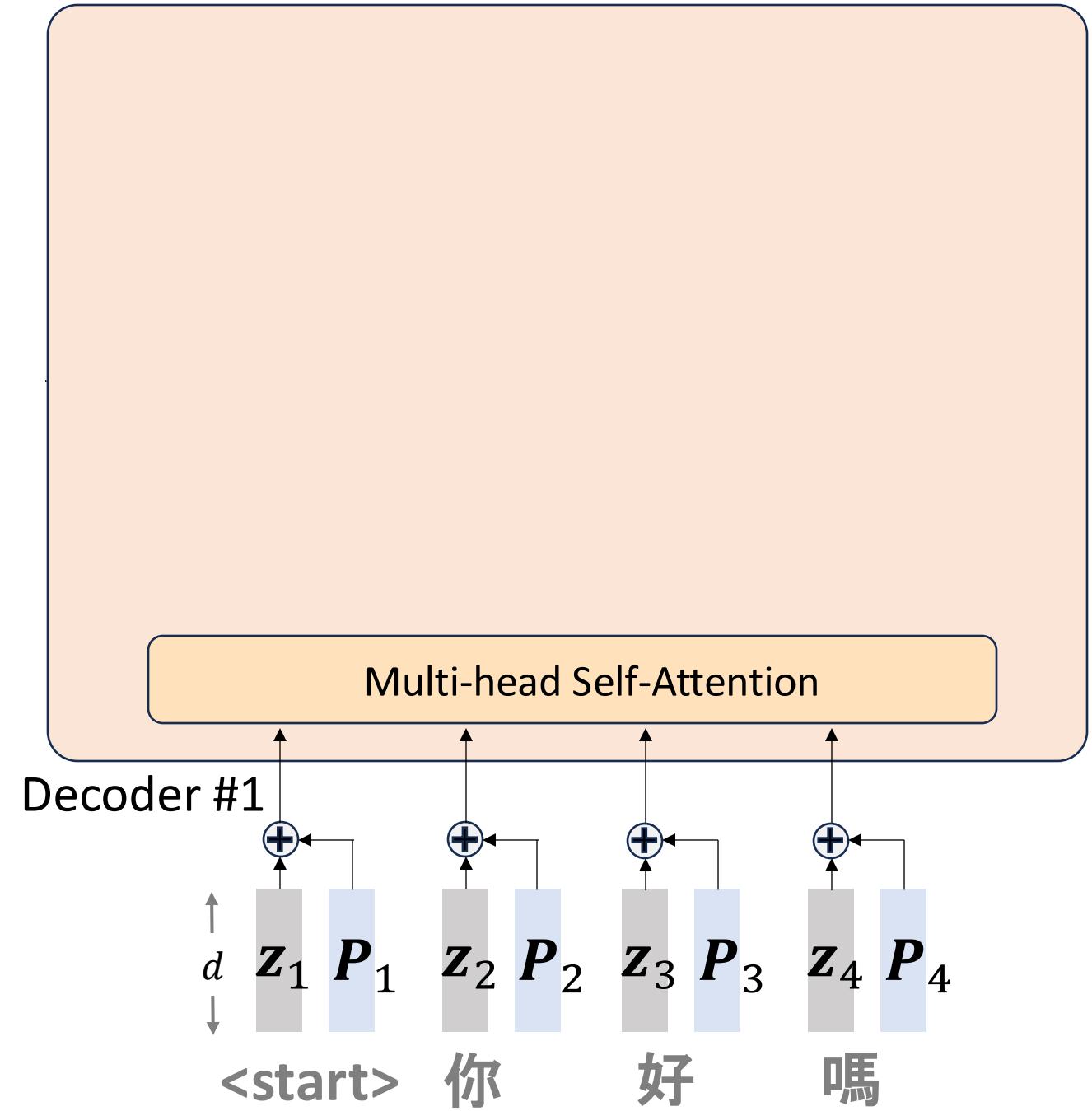
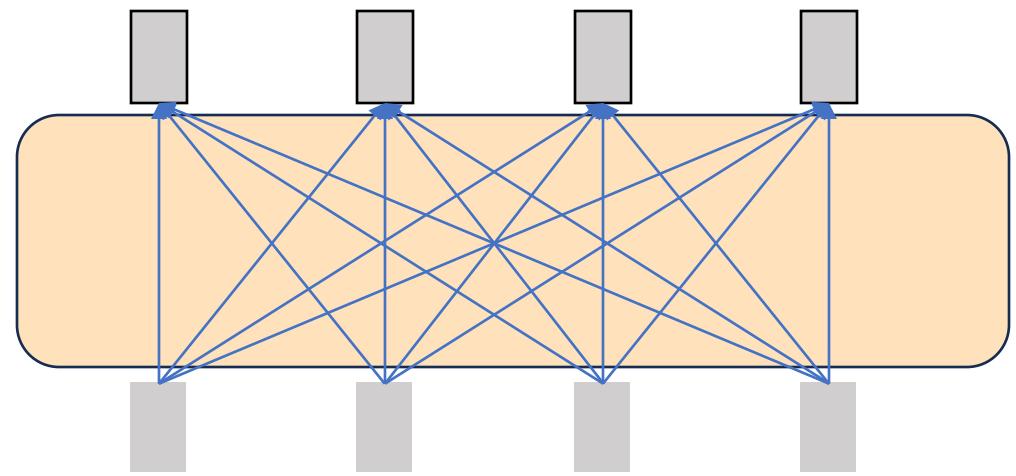


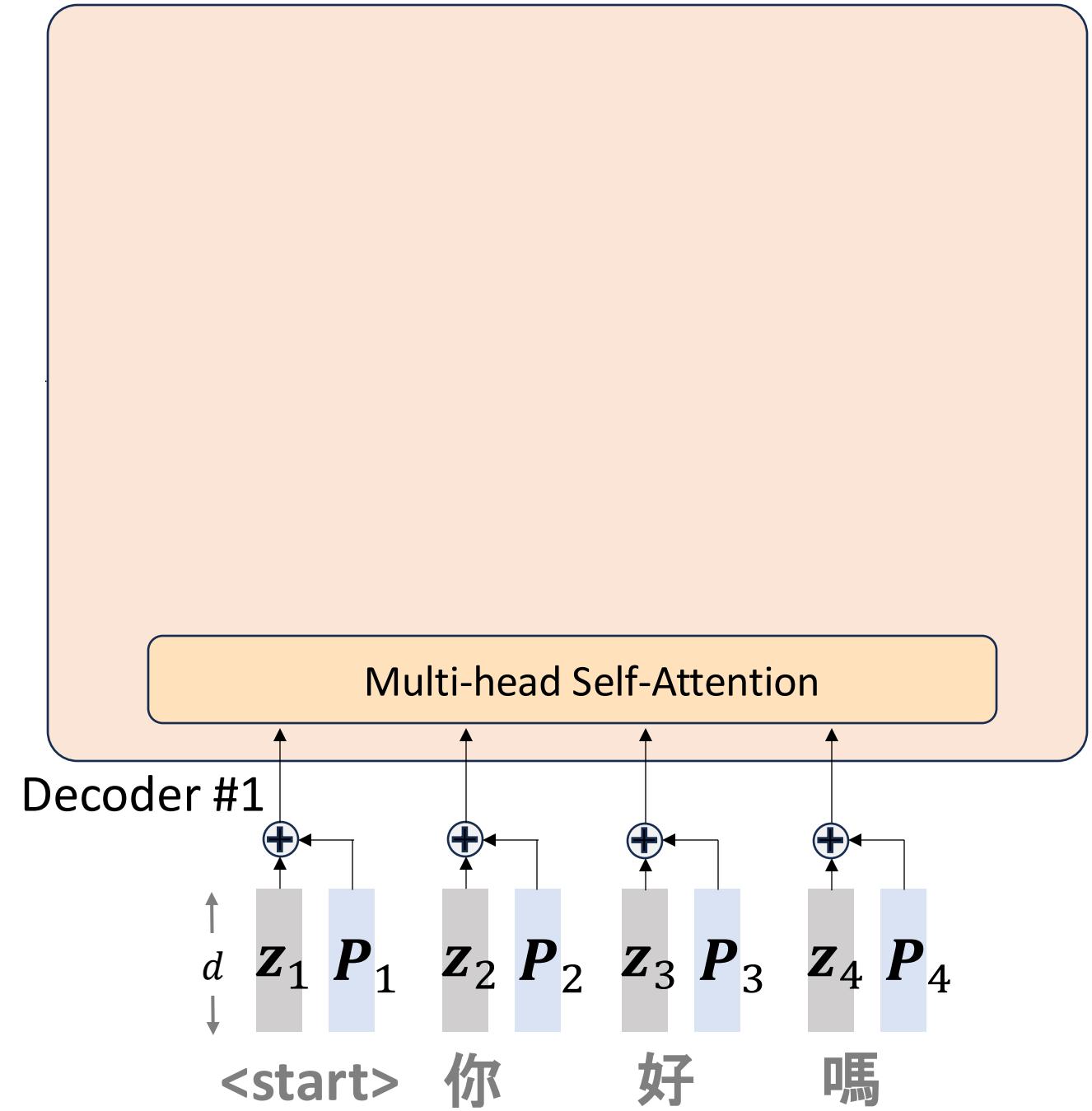
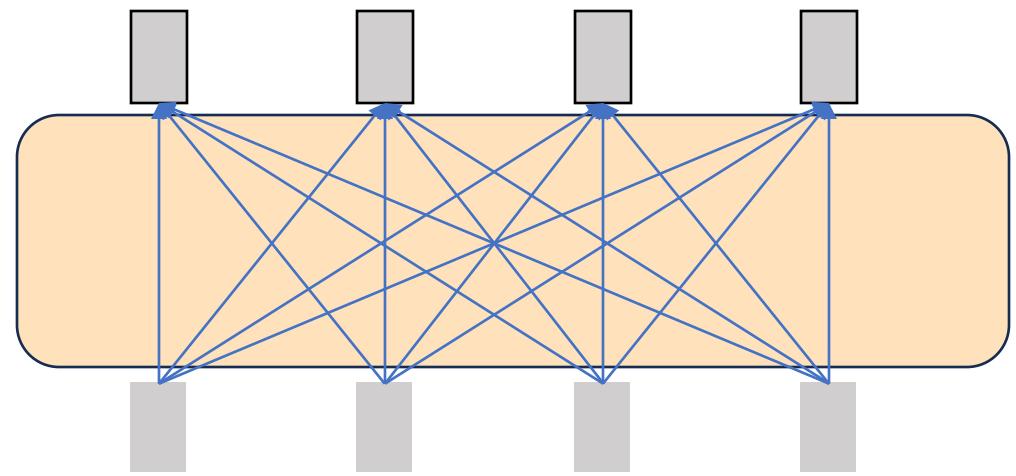


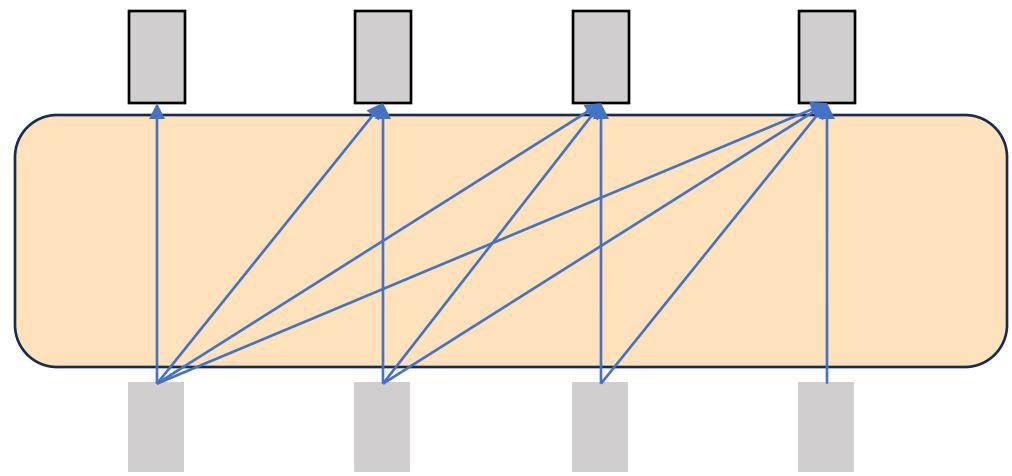










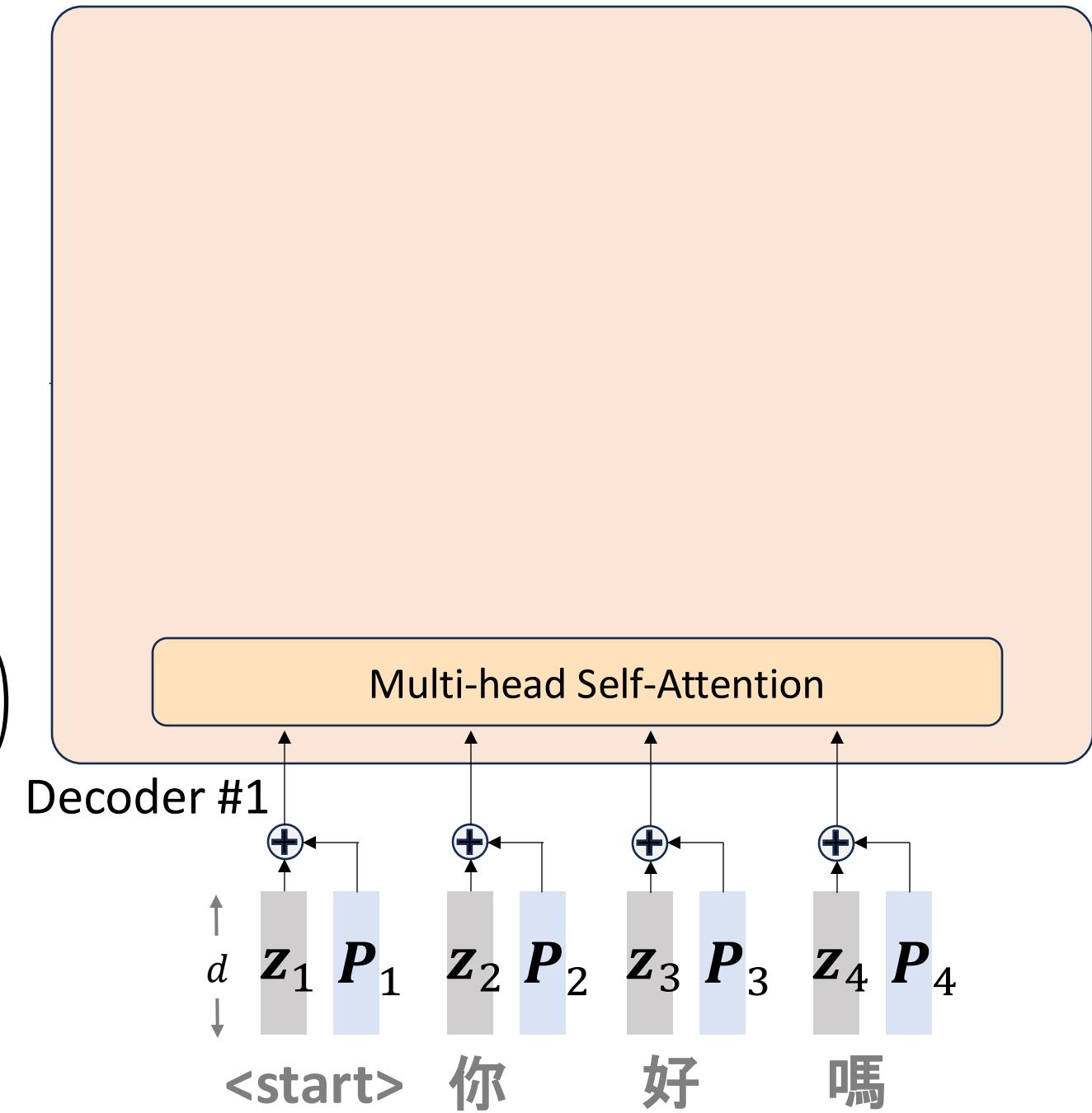


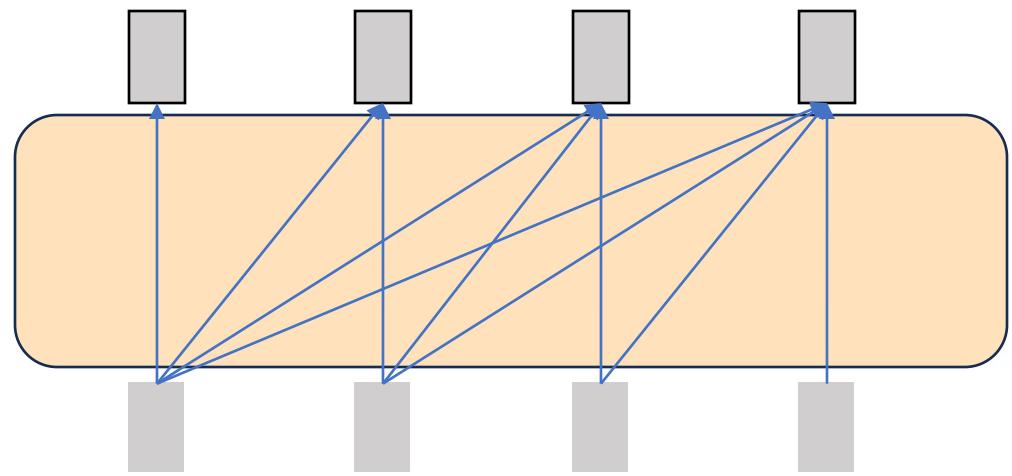
$$\text{Attention}(Q, K, V) = V \operatorname{softmax}\left(\frac{K^T Q}{\sqrt{d_k}}\right)$$

$$\text{MaskedAttention}(Q, K, V) = V \operatorname{softmax}\left(\frac{K^T Q}{\sqrt{d_k}} + M\right)$$

0	0	0	0	0
$-\infty$	0	0	0	0
$-\infty$	$-\infty$	0	0	0
$-\infty$	$-\infty$	$-\infty$	0	0
$-\infty$	$-\infty$	$-\infty$	$-\infty$	0

$M =$



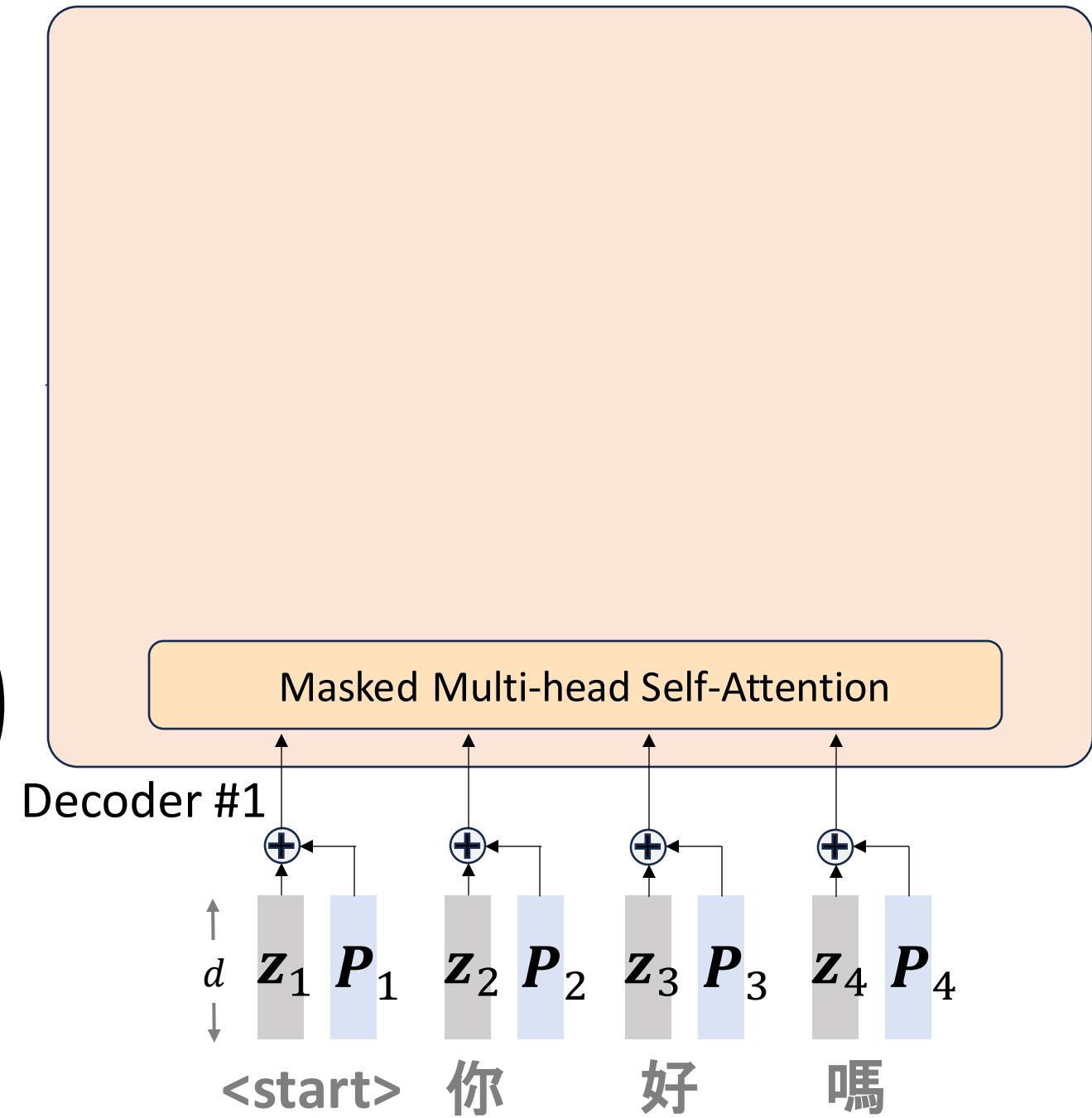


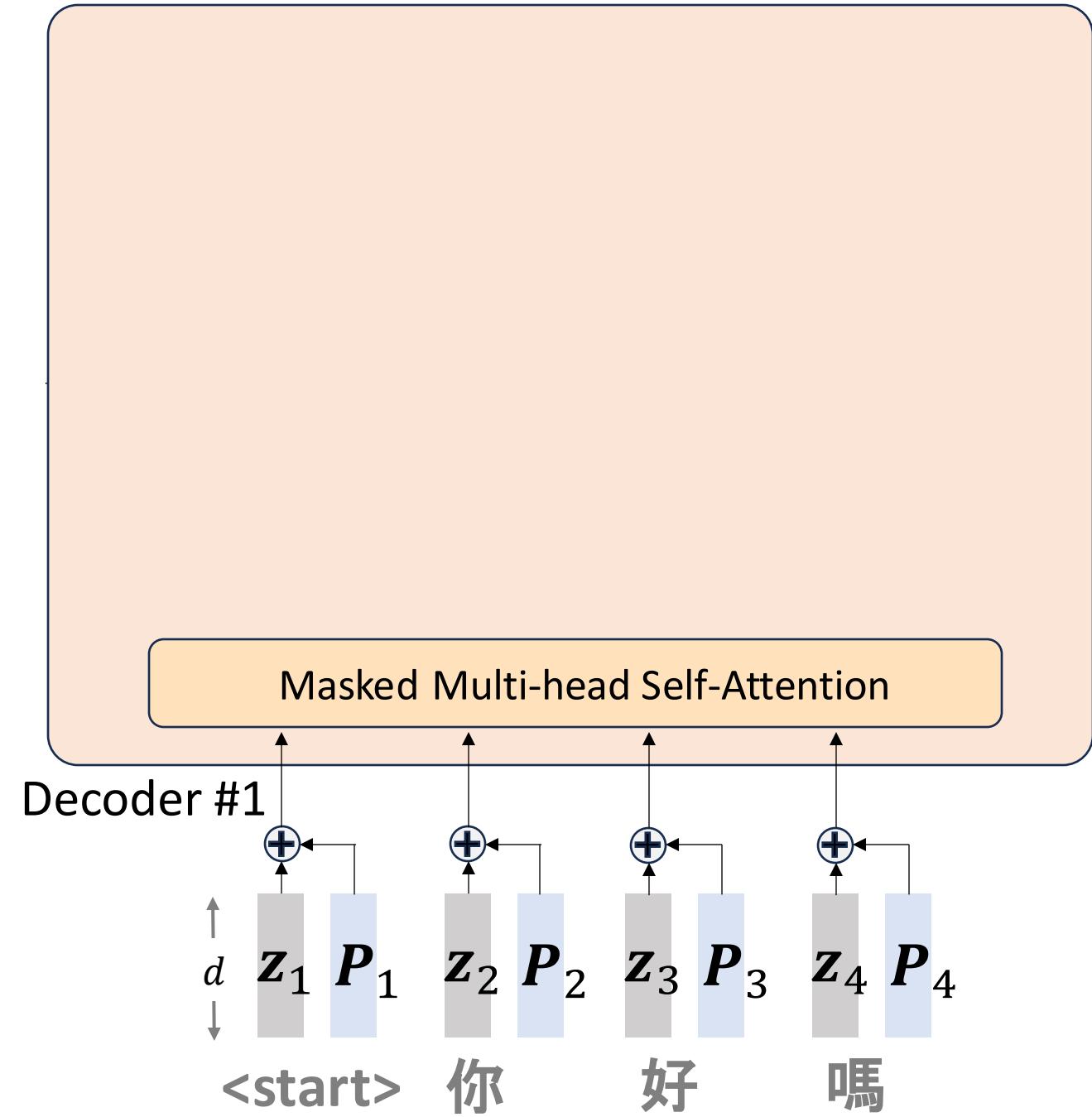
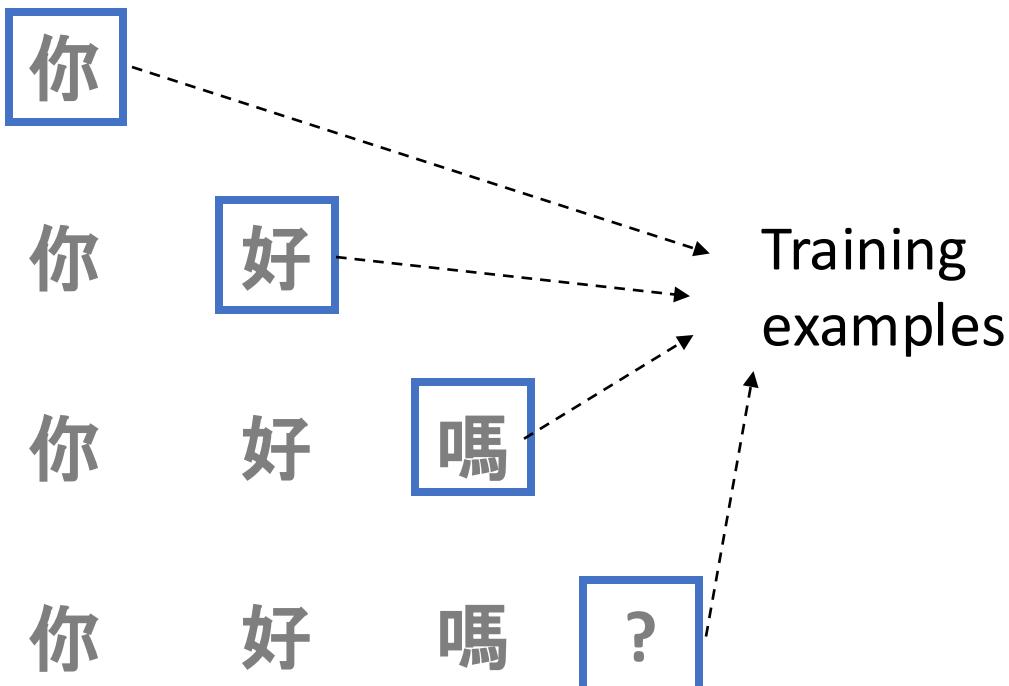
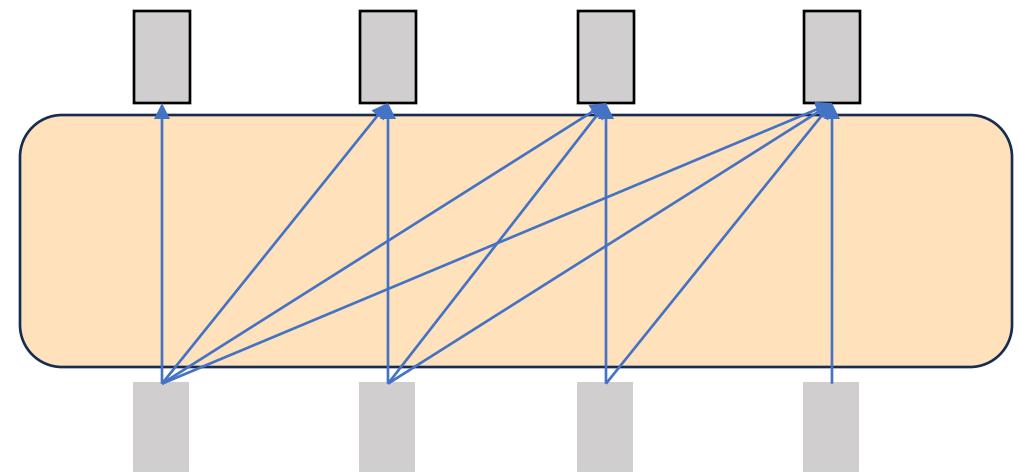
$$\text{Attention}(Q, K, V) = V \operatorname{softmax}\left(\frac{K^T Q}{\sqrt{d_k}}\right)$$

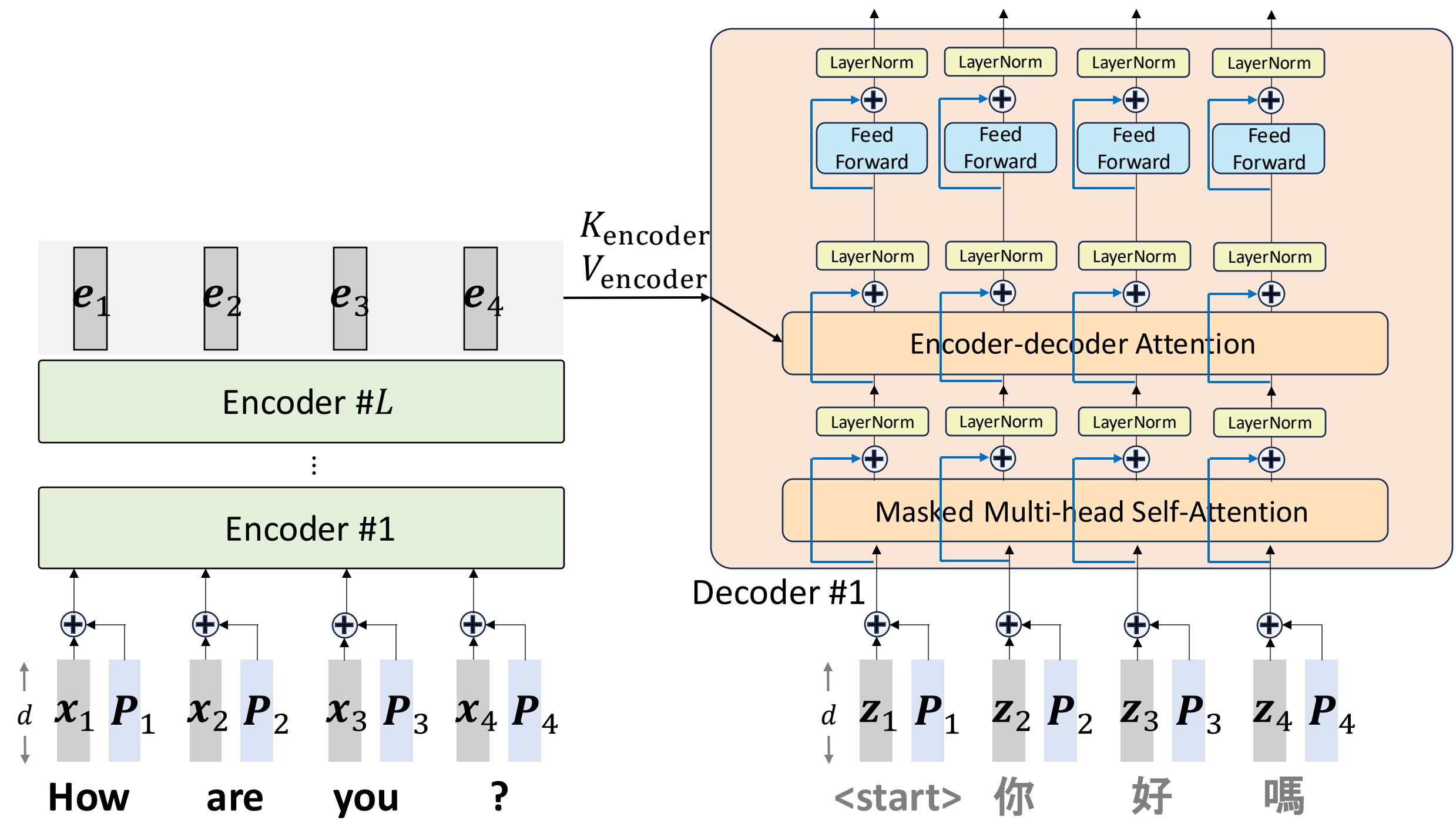
$$\text{MaskedAttention}(Q, K, V) = V \operatorname{softmax}\left(\frac{K^T Q}{\sqrt{d_k}} + M\right)$$

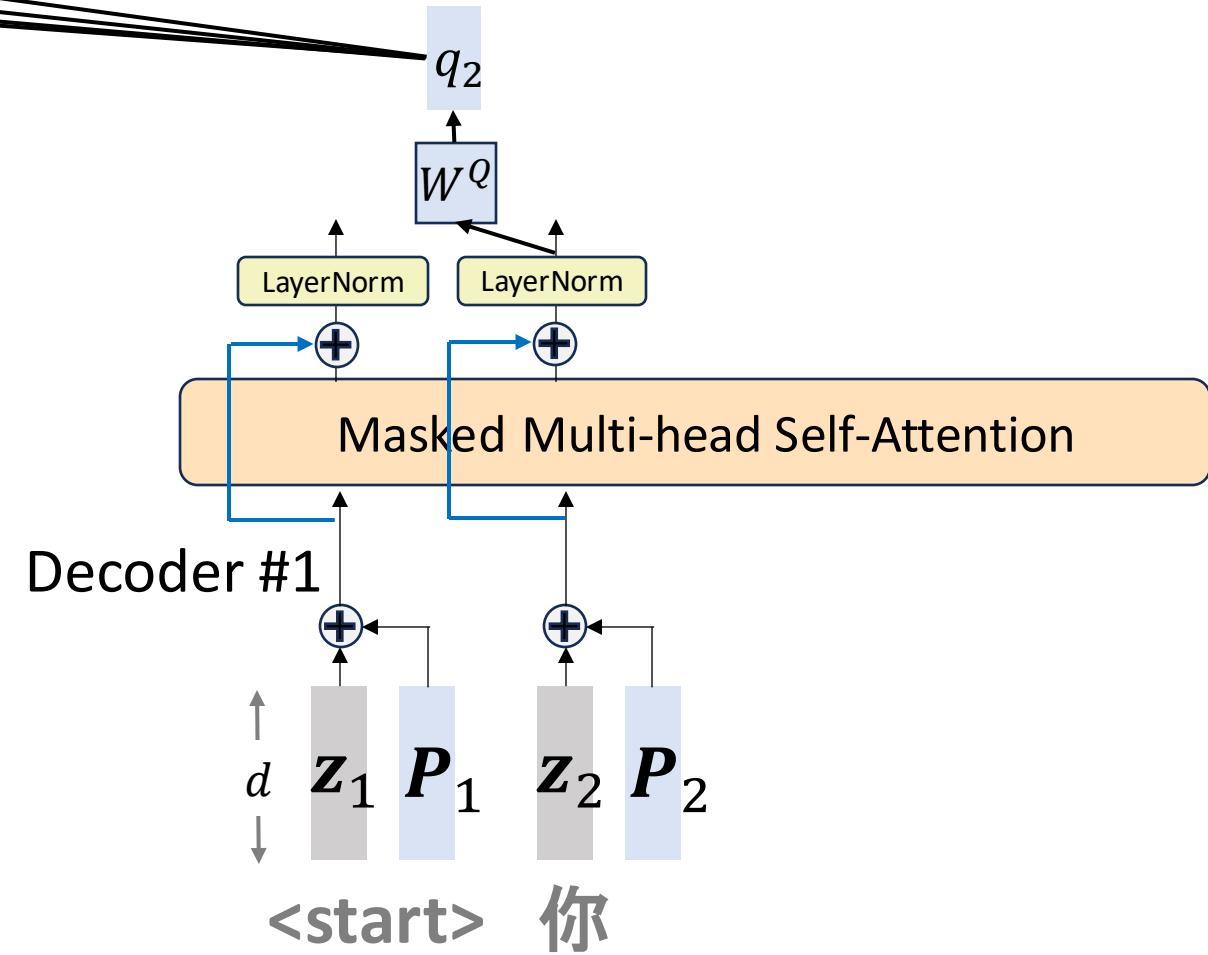
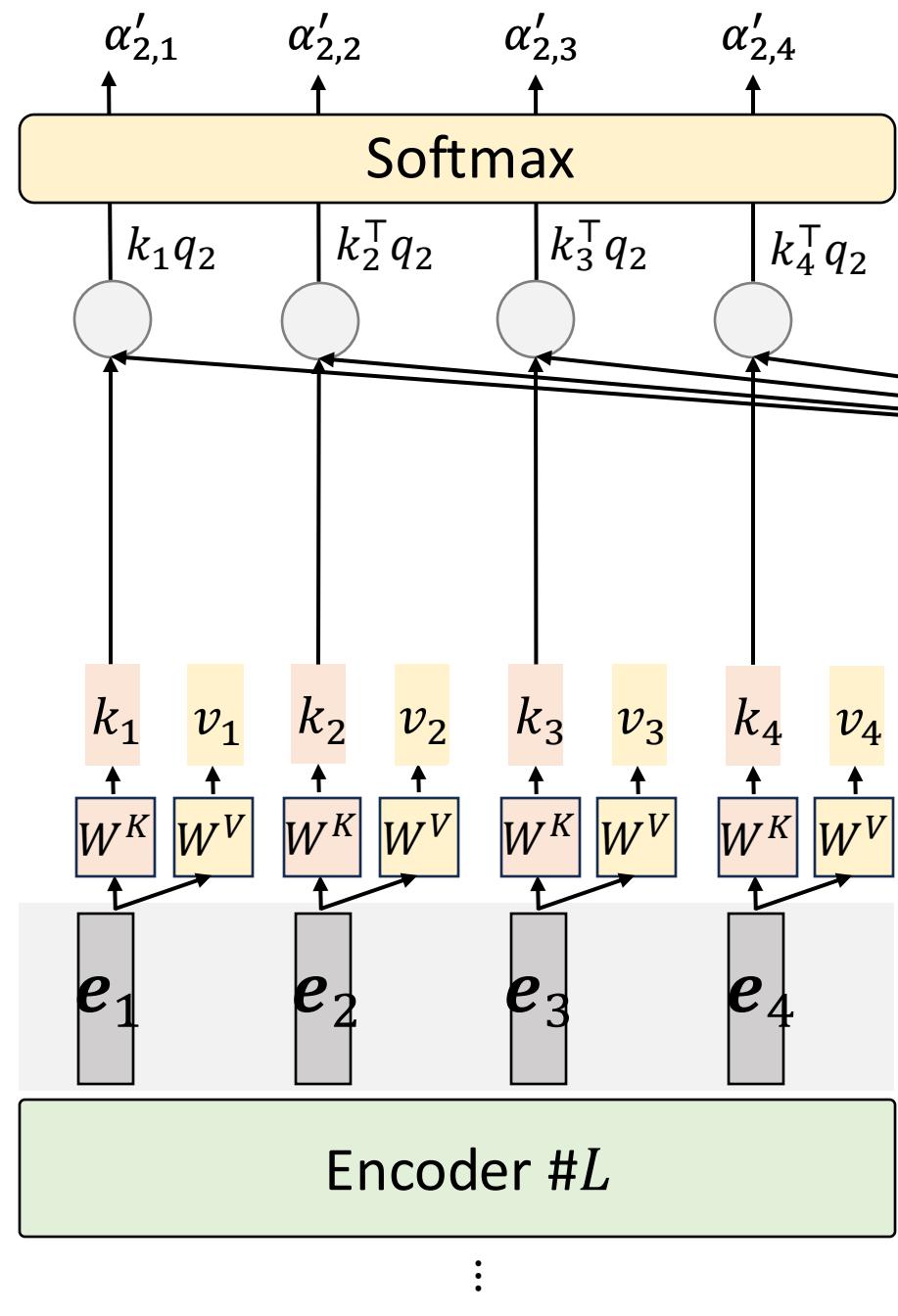
0	0	0	0	0
$-\infty$	0	0	0	0
$-\infty$	$-\infty$	0	0	0
$-\infty$	$-\infty$	$-\infty$	0	0
$-\infty$	$-\infty$	$-\infty$	$-\infty$	0

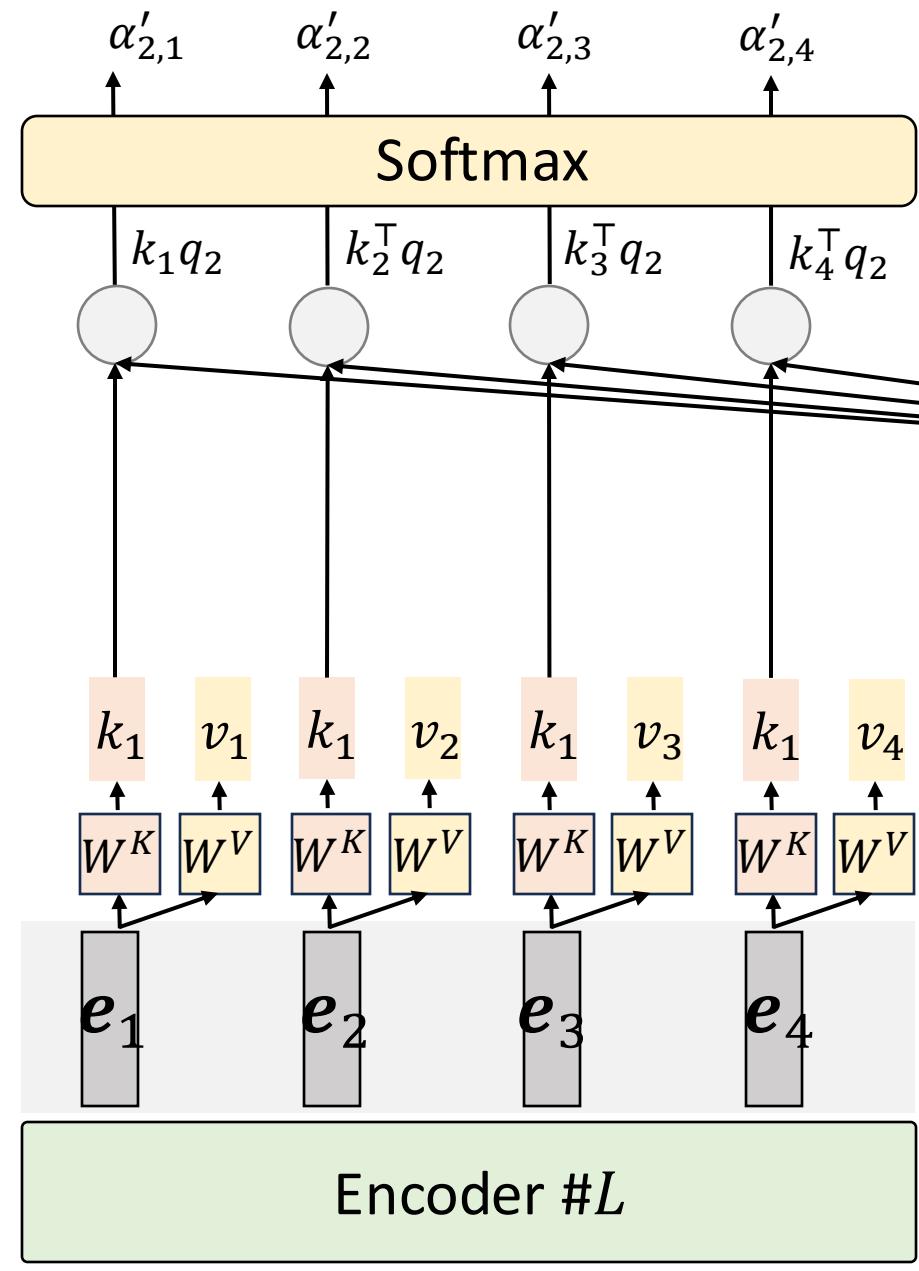
$M =$





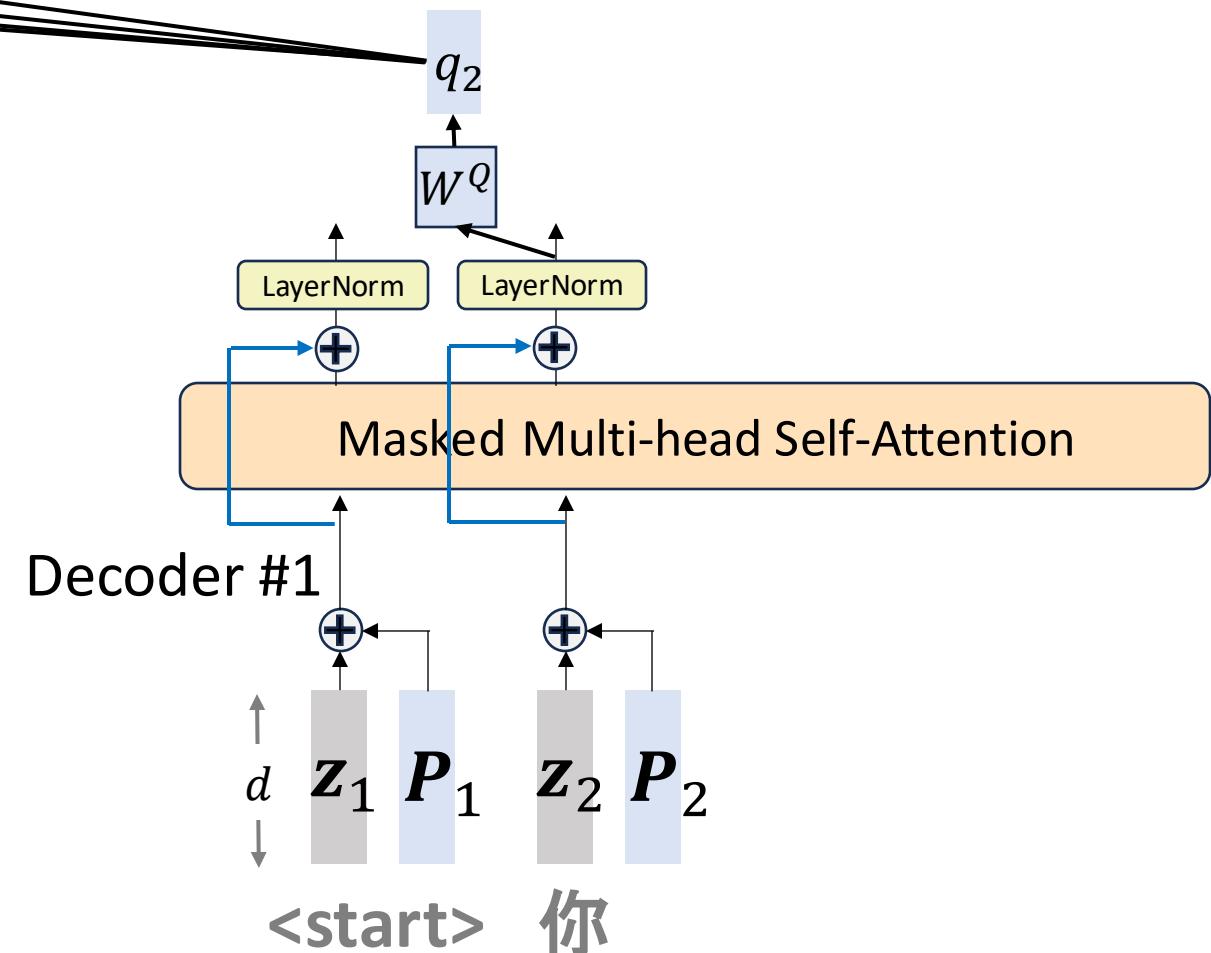




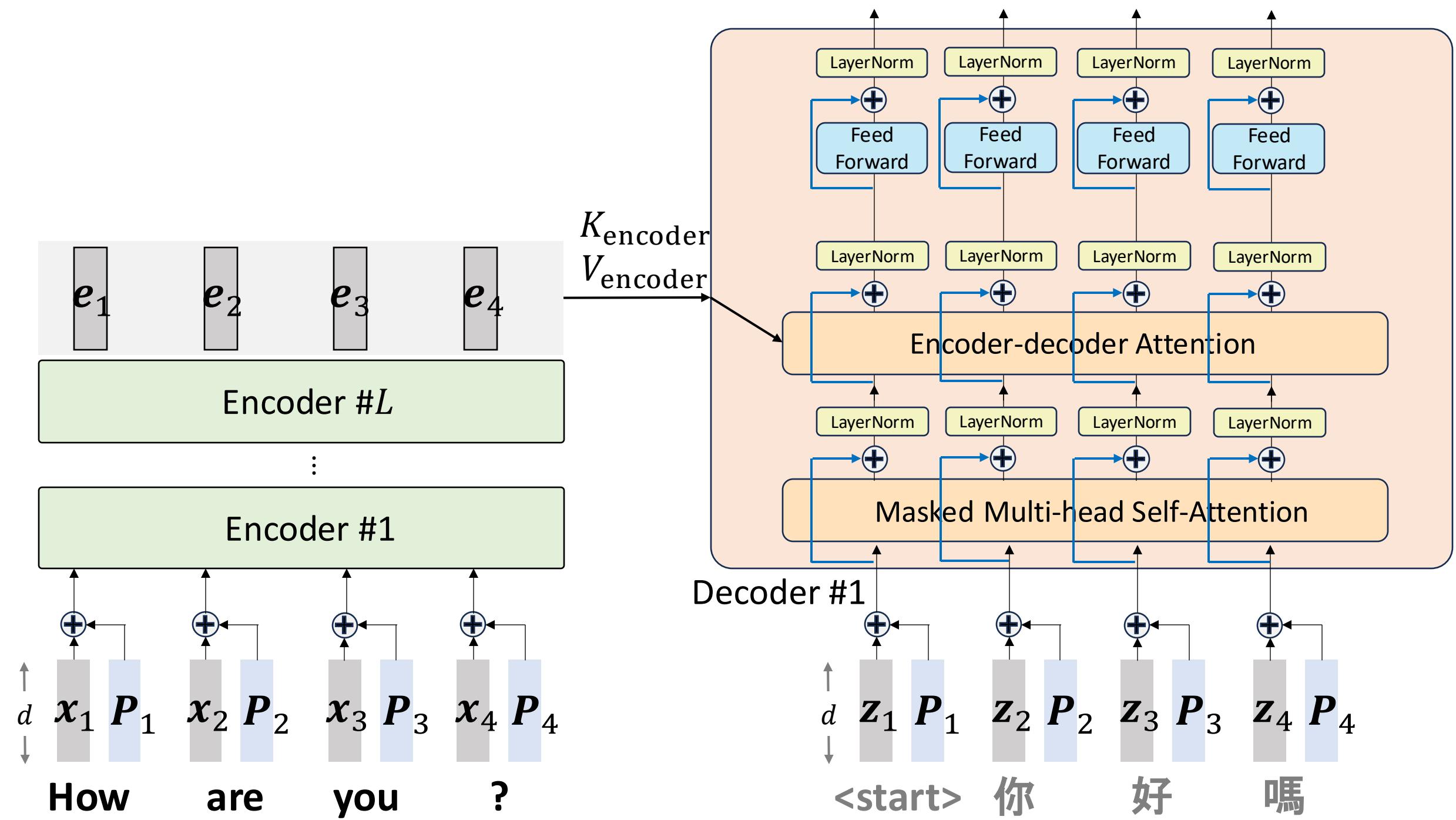


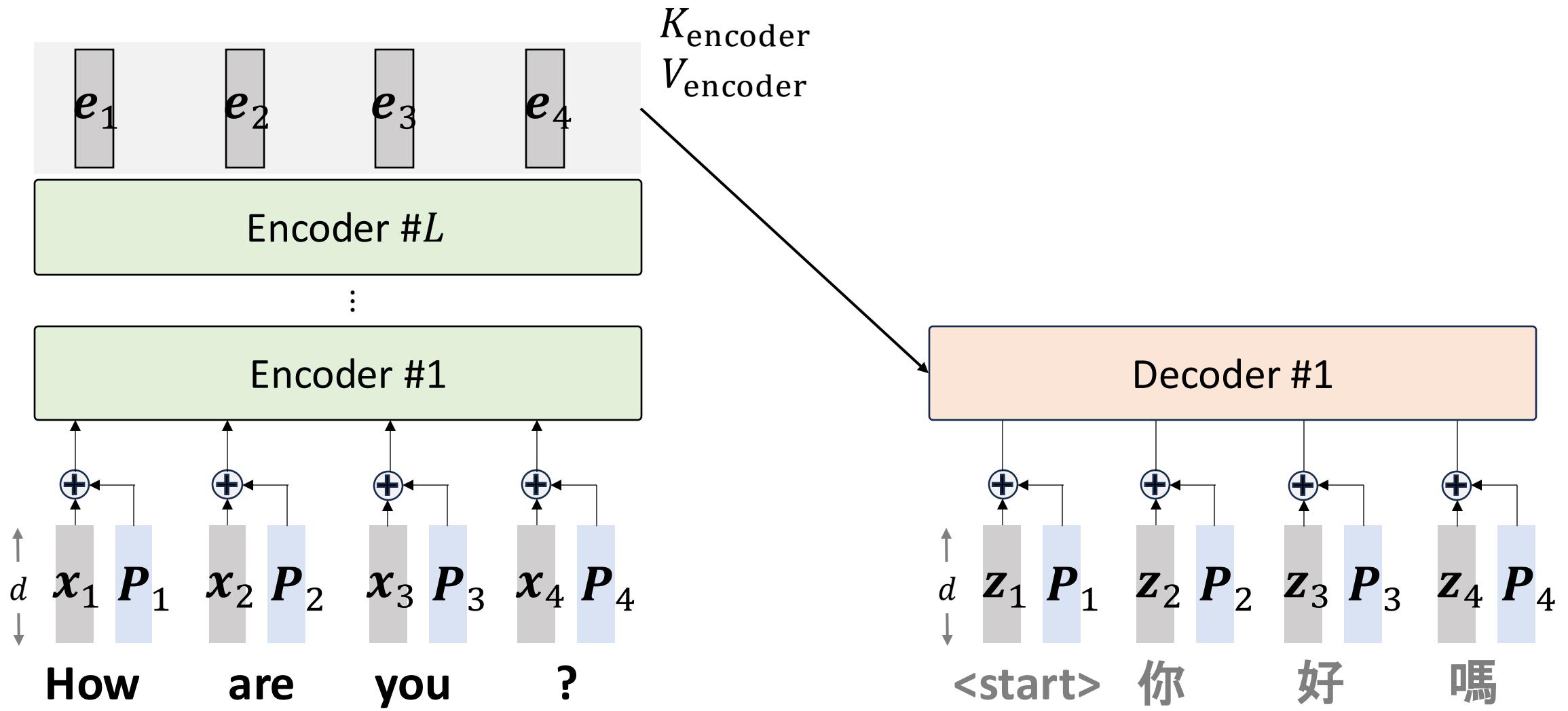
$$\mathbf{z}'_2 = W^O (\alpha'_{2,1} v_1 + \alpha'_{2,2} v_2 + \alpha'_{2,3} v_3 + \alpha'_{2,4} v_4)$$

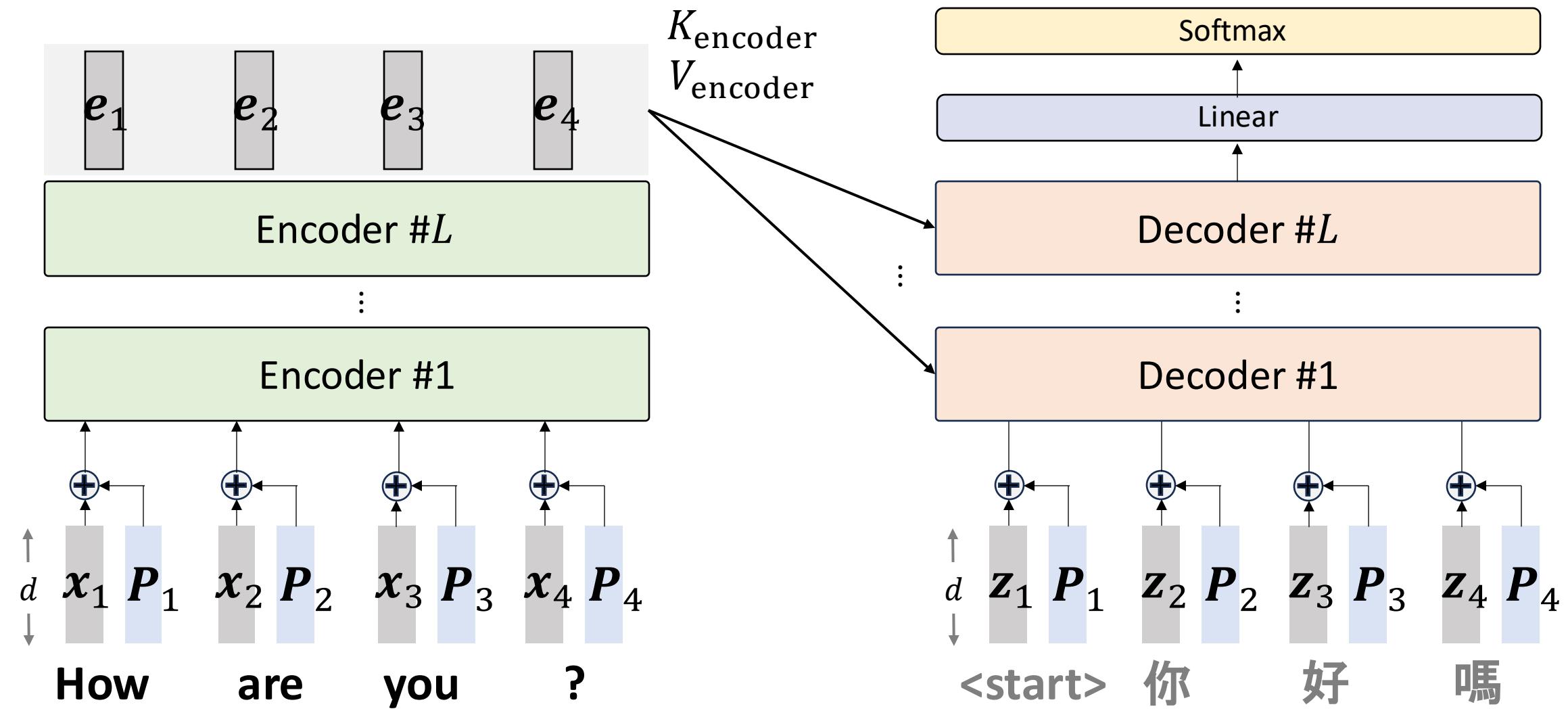
Cross-attention  
Encoder-decoder attention



(ignore the scaling  $1/\sqrt{d_k}$  here for simplicity)







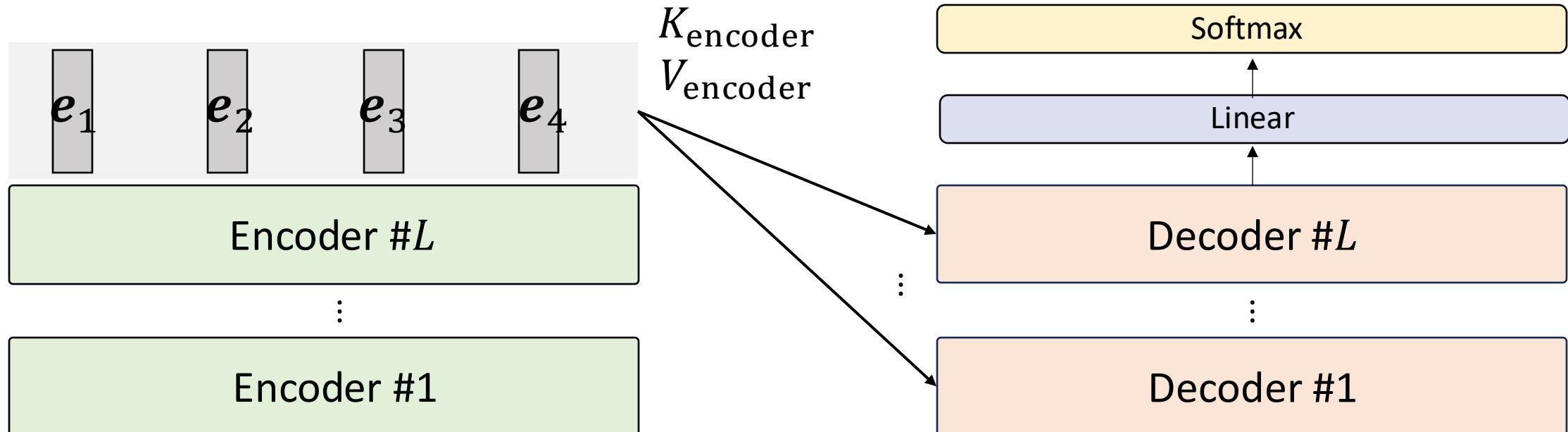
# Encoder-Decoder Transformer

## Examples:

Attention is all you need, T5, BART.

## Good for:

Machine translation, summarization, QA  
(when input/target are sufficiently different)



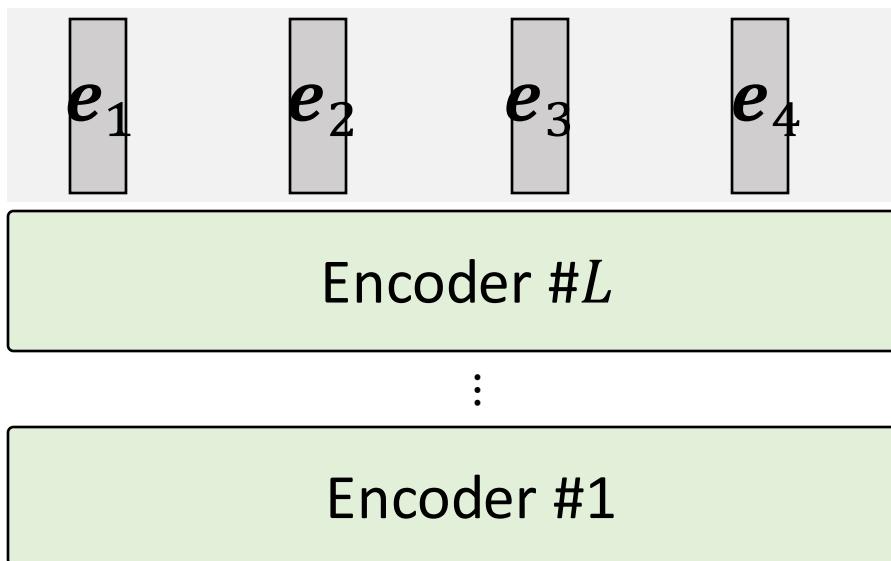
# Encoder-Decoder Transformer

## Examples:

Attention is all you need, T5, BART.

## Good for:

Machine translation, summarization, QA  
(when input/target are sufficiently different)



# Encoder-only Transformer



## Examples:

BERT, RoBERTa, DeBERTa, X-BERT

## Good for:

Classification, sequence tagging, sentiment analysis

(Understand text, but not generate them)

$e_1$

Encoder # $L$

:

Encoder #1

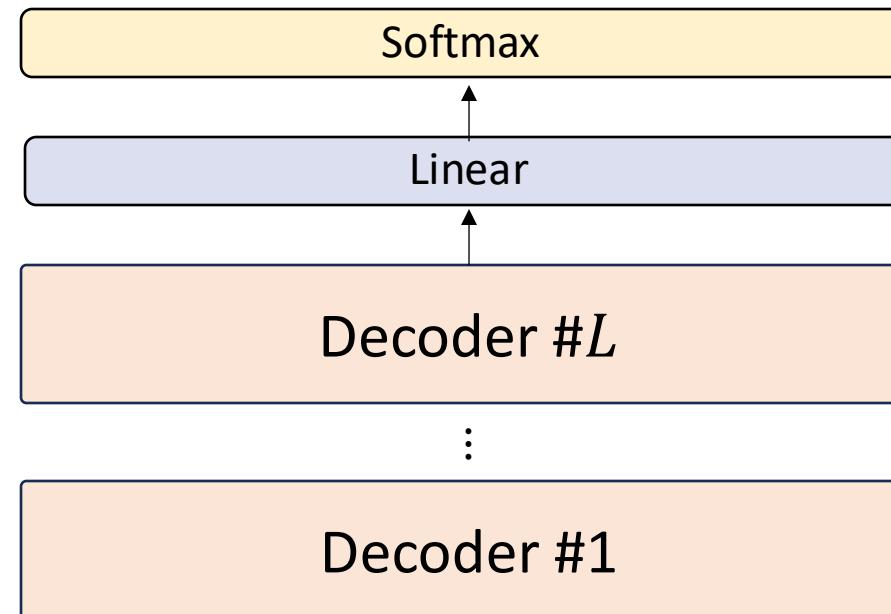
# Decoder-only Transformer

**Examples:**

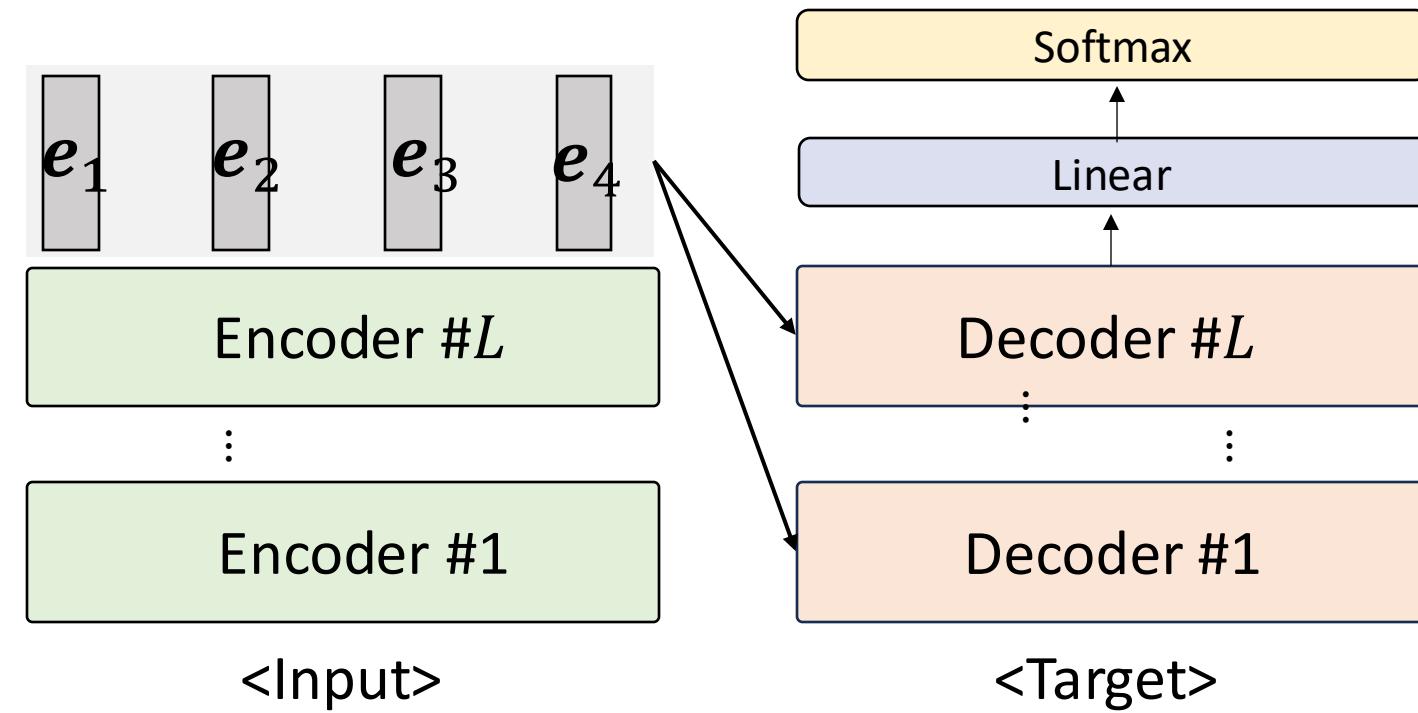
GPT-X (OpenAI), PaLM (Google), LLaMA (Meta)  
BLOOM (BigScience)

**Good for:**

Text generation, multi-round conversation

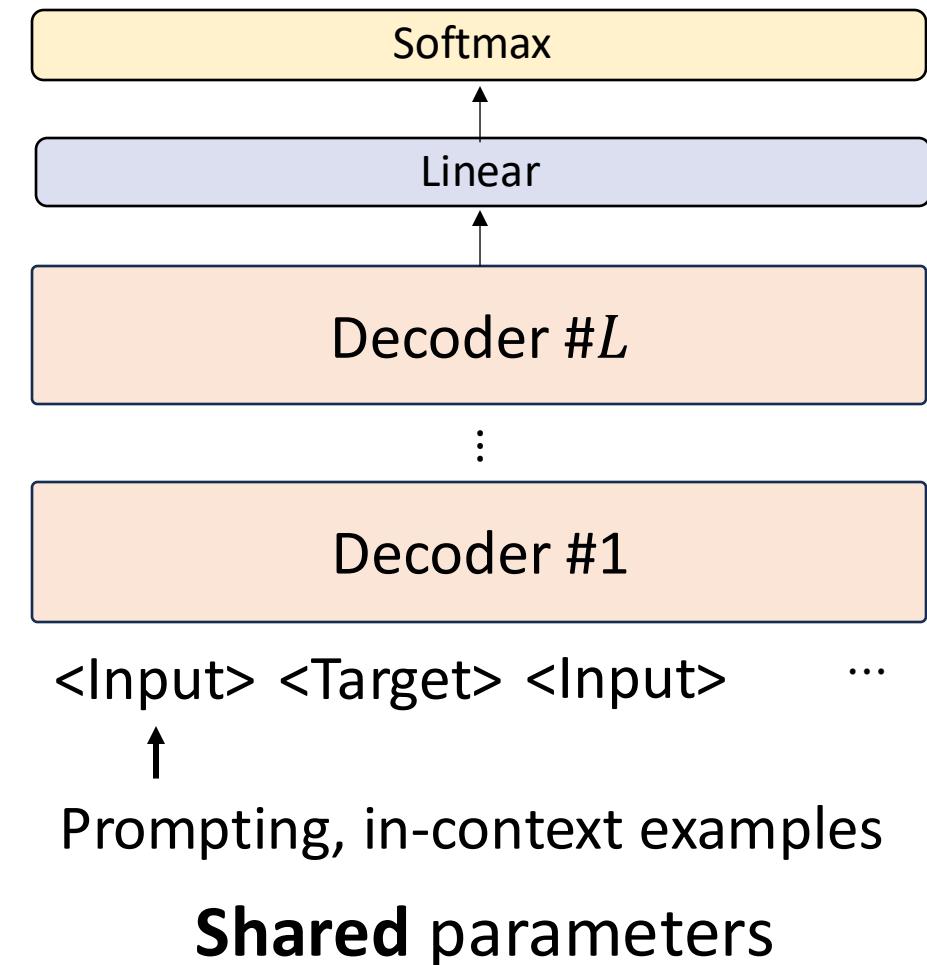


## Encoder-Decoder Transformer



Different parameters for **encoder/decoder**

## Decoder-only Transformer



Shared parameters

# Encoder-Decoder

