

W10 - Molecular dynamics as a Markov process

Physical models of living systems, Nelson chp 8

"stochastic simulations, applications to biomolecular networks", Gante

"Modeling of stochastically gating of ion channels" G.D. Smith

Ion channel /
RNA production/regulation
(birth/death master equation)

"How molecules change with time"

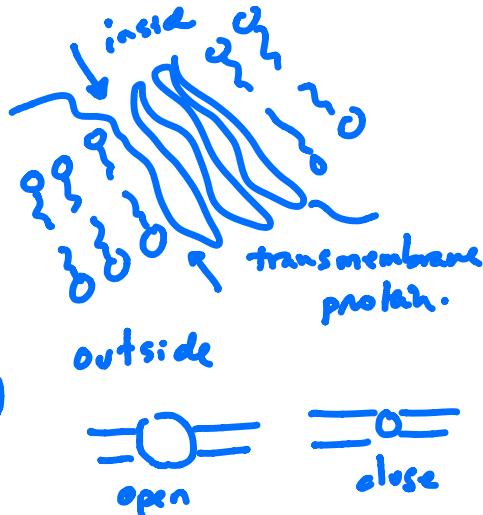
"How molecule concentrations change with time"

Stochastic gating of a single ion channel

gated channels:

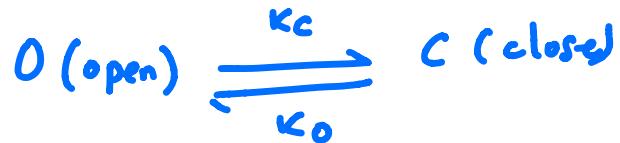
can be gated by:

- Ions: $\text{Ca}^{2+}, \text{Na}^+, \text{K}^+$
- Voltage
- Light (channelrhodopsin)



Measure the dynamics of a single ion channel

using a Markov process with 2 states



k_c, k_o are reaction constants of the process,
that of course, we are going to interpret
as probabilities.

① a discrete time Markov process

$$P(c, t \rightarrow O, t + \Delta t) = k_o \cdot \Delta t$$

$$\Delta t \downarrow P(O, t \rightarrow c, t + \Delta t) = k_c \cdot \Delta t$$

② a continuous time Markov process

$$P(O|t), P(c|t)$$

Discrete-time Markov process

s_i = state of ion at time $i \cdot \Delta t$

$$s_0 \rightarrow s_1 \rightarrow \dots \quad s_i \rightarrow s_{i+1} \rightarrow \dots$$

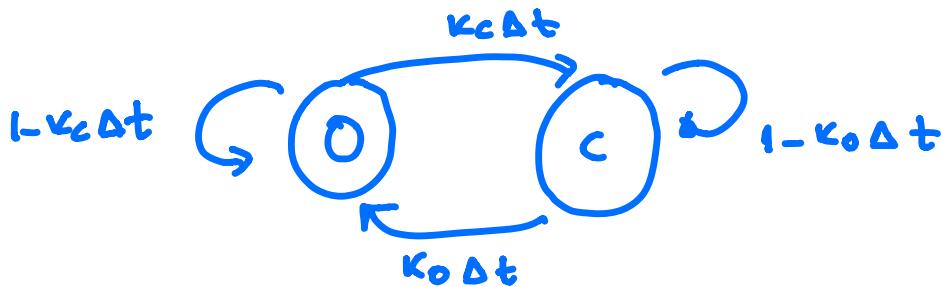
$t(s_0 \rightarrow s_1)$ $t(s_i \rightarrow s_{i+1})$

$$t(c \rightarrow o) = P(o, t + \Delta t | c, t) = k_o \cdot \Delta t$$

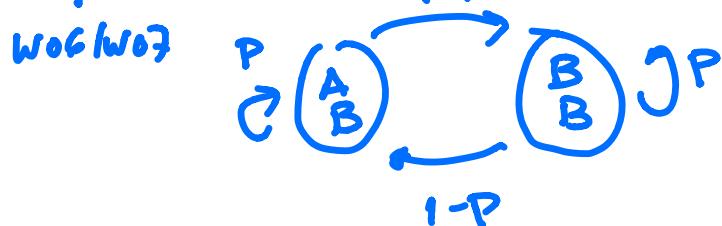
$$t(o \rightarrow c) = P(c, t + \Delta t | o, t) = k_c \cdot \Delta t$$

$$t(c \rightarrow c) = P(c, t + \Delta t | c, t) = 1 - k_o \cdot \Delta t$$

$$t(o \rightarrow o) = P(o, t + \Delta t | o, t) = 1 - k_c \cdot \Delta t$$



Compared to:



The HMM probabilities are dependent on $\underline{\Delta t}$

$$P(s_i = o | s_{i-1} = o) = 1 - \Delta t \cdot k_c$$

$$P(A|AB) = p$$

The transition probability matrix

$P(0|t)$ =: prob that at t , channel is 0

$P(c|t)$ =: " " " ", channel is C

$$P(0|t) + P(c|t) = 1$$

Master eqs:

$$P(0|t+\Delta t) = (1 - \kappa_c \Delta t) P(0|t)$$

$$\kappa_o \cdot \Delta t P(c|t)$$

$$P(c|t+\Delta t) = (1 - \kappa_o \Delta t) P(c|t)$$

$$\kappa_c \Delta t P(0|t)$$

Matricial representation

$$\begin{bmatrix} P(0|t+\Delta t) \\ P(c|t+\Delta t) \end{bmatrix} = \begin{bmatrix} 1 - \kappa_c \Delta t & \kappa_o \Delta t \\ \kappa_c \Delta t & 1 - \kappa_o \Delta t \end{bmatrix} \begin{bmatrix} P(0|t) \\ P(c|t) \end{bmatrix}$$

$$T_{\Delta t} = \begin{bmatrix} 1 - \kappa_c \Delta t & \kappa_o \Delta t \\ \kappa_c \Delta t & 1 - \kappa_o \Delta t \end{bmatrix}$$

$$\begin{bmatrix} P(o|t+\Delta t) \\ P(c|t+\Delta t) \end{bmatrix} = T_{\Delta t} \begin{bmatrix} P(o|t) \\ P(c|t) \end{bmatrix}$$

" " "

$$\vec{P}(t+\Delta t) \quad \vec{P}(t)$$

$$\vec{P}(t+\Delta t) = \bar{T} \vec{P}(t)$$

Then for $t+2\Delta t$

$$\begin{aligned} \vec{P}(t+2\Delta t) &= \bar{T} \vec{P}(t+\Delta t) \\ &= \bar{T}^2 \vec{P}(t) \end{aligned}$$

in general

$\vec{P}(t+n\Delta t) = \bar{T}^n \vec{P}(t)$

The Chapman-Kolmogorov equation.

[A general result for any continuous-time Markov process]

The deterministic solution

$$\Delta t \rightarrow 0$$

$$P(C|t+\Delta t) = \kappa_c \Delta t P(O|t) \\ (1 - \kappa_o \Delta t) P(C|t)$$

$$P(O|t+\Delta t) = \kappa_o \Delta t P(C|t) \\ (1 - \kappa_c \Delta t) P(O|t)$$

$$P(C|t+\Delta t) - P(C|t) = \kappa_c \Delta t P(O|t) - \kappa_o \Delta t P(C|t)$$

$$P(O|t+\Delta t) - P(O|t) = \kappa_o \Delta t P(C|t) - \kappa_c \Delta t P(O|t)$$

$$\frac{P(C|t+\Delta t) - P(C|t)}{\Delta t} = \kappa_c - (\kappa_c + \kappa_o) P(C|t)$$

$$\frac{P(O|t+\Delta t) - P(O|t)}{\Delta t} = \kappa_o - (\kappa_c + \kappa_o) P(O|t)$$

at $\Delta t \rightarrow 0$

$$\left. \begin{aligned} \frac{dP(c|t)}{dt} &= k_c - (k_c + k_o) P(c|t) \\ \frac{dP(o|t)}{dt} &= k_o - (k_c + k_o) P(o|t) \end{aligned} \right\}$$

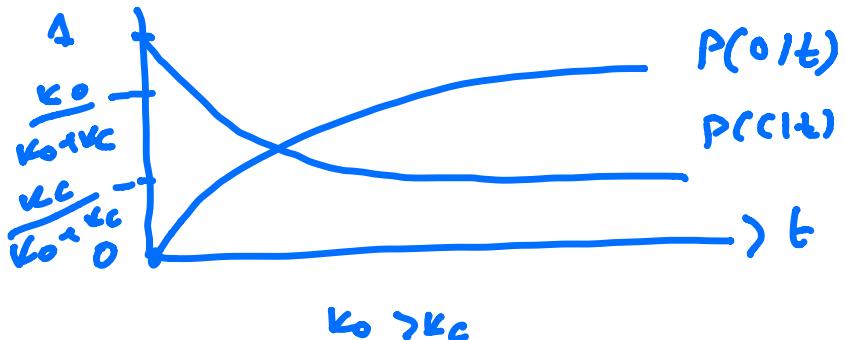
differential eqs.

can be solved:

$$P(c|t) = \frac{k_c}{k_o + k_c} + \left(P(c|0) - \frac{k_c}{k_c + k_o} \right) e^{-(k_c + k_o)t}$$

$$P(o|t) = \frac{k_o}{k_o + k_c} + \left(P(o|0) - \frac{k_o}{k_c + k_o} \right) e^{-(k_c + k_o)t}$$

$P(c|0) = 1$



This is a general result

$$\text{for } P(t + \Delta t) = T P(t)$$

$$\frac{P(t + \Delta t) - P(t)}{\Delta t} = \frac{T - I}{\Delta t} P(t)$$

Introduce $Q = \frac{T - I}{\Delta t} = \begin{bmatrix} -\kappa_c & \kappa_0 \\ \kappa_c & -\kappa_0 \end{bmatrix}$

Q : rate matrix = changes per unit time.

$$\frac{d\bar{P}}{dt} = Q \bar{P}(t)$$

general solution

$$\bar{P}(t) = e^{tQ} \bar{P}(0)$$

Note $e^{tQ} \neq \begin{bmatrix} e^{-t\kappa_c} & e^{t\kappa_0} \\ e^{t\kappa_c} & e^{-t\kappa_0} \end{bmatrix}$

$$e^{tQ} = I + tQ + \frac{t^2}{2!} Q^2 + \frac{t^3}{3!} Q^3 + \dots$$

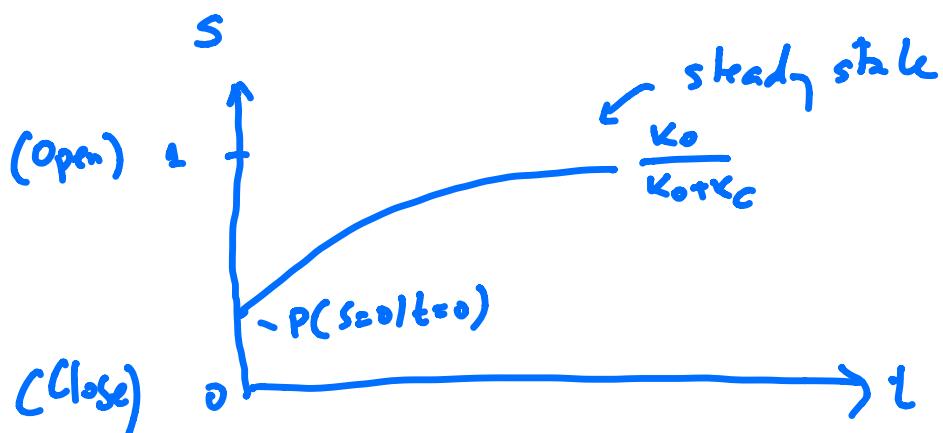
Expectations over many channels

$$S = \begin{cases} 1 & \text{if channel open} \\ 0 & \text{if channel close} \end{cases}$$

$$\begin{aligned}\langle S(t) \rangle &= 1 \cdot P(S=0|t) \\ &\quad + 0 \cdot P(S=c|t) \\ &= P(S=0|t) \\ &= \frac{k_o}{k_o+k_c} + \left(P(S=0|t=0) - \frac{k_o}{k_o+k_c} \right) e^{-(k_o+k_c)t}\end{aligned}$$

Steady state solution

$$\left\{ \begin{array}{l} \langle S(t) \rangle \rightarrow \frac{k_o}{k_o+k_c} \\ t \rightarrow \infty \end{array} \right.$$



Stochastic Simulation : MC algorith.

Δt

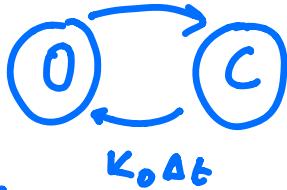
look at one channel as it $O \rightleftharpoons C$ $k_c \Delta t$

+ if channel is at $S=0$

draw $r \in U[0,1]$

if $r < k_c \Delta t \rightarrow S_{i+1} = C$

else stay 0 : $S_{i+1} = 0$



+ if channel is at $S=C$

draw $r \in U[0,1]$

if $r < k_o \Delta t \rightarrow S_{i+1} = 0$ (change)

else stay C $S_{i+1} = C$

→ class code

compare

stochastic simulation
for 1 channel

average deterministic solution

Dwell times

Dwell time = $\langle \tau \rangle$ =: expected time for a channel
to remain open before it
(0)
changes to close (C)

.....



A channel is open at t , making that
stays open at $t + \tau$

$$P(0, t+\tau | 0, t) = P(0, t+\tau | 0, t+\tau - \Delta t)$$

$$P(0, t+\tau - \Delta t | 0, t+\tau - 2\Delta t)$$

$$\vdots \\ P(0, t+\Delta t | 0, t)$$

if $\tau = m \cdot \Delta t$

$$= (1 - k_c \Delta t)^m = \left(1 - k_c \frac{\tau}{m}\right)^m$$

$$\lim_{m \rightarrow \infty} = e^{-k_c \tau}$$

Then the prob of a dwell time τ requires to add the instantaneous probability of changing from $0 \rightarrow c = k_c$

$$\text{then } P_0(\tau) = k_c e^{-k_c \tau}$$

And the expected dwell time

$$\langle \tau \rangle_0 = \frac{1}{k_c} \quad 0$$

similarly

