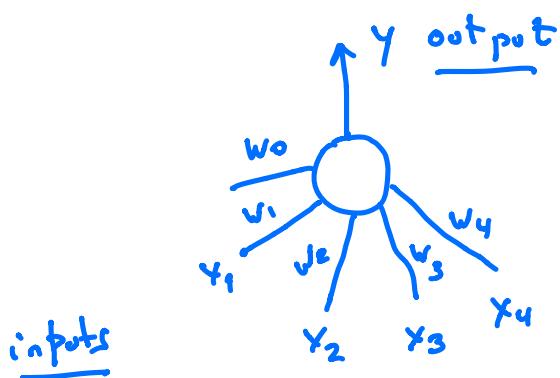


W08 - Neural Networks . Learning as Inference

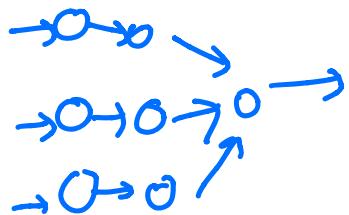
Mackay's lectures 15, 1C. Chapters 39, 41, 42.

Feedforward Networks

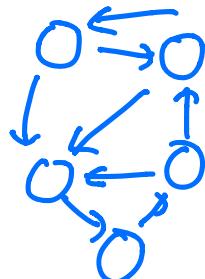
A single neuron



Feedforward network



Feedback network



Elements of the network

• inputs x_1, \dots, x_I

• output $y = \underbrace{\text{activity}}$ $\gamma > \text{threshold, neuron fires}$

• weights (parameters) w_0, w_1, \dots, w_I

This is not a probabilistic process

Given the inputs, how does the neuron produce y ?

i) neuron adds all weights

$$a = w_0 + \sum_{i=1}^I w_i x_i = \text{activation}$$

\uparrow
bias

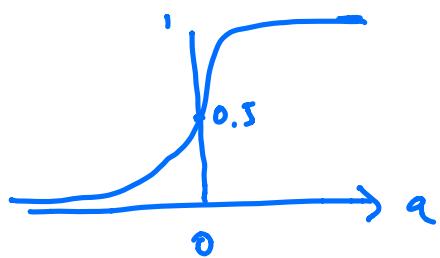
ii) the activity of the neuron y is a function
of the activation a : $\underline{\gamma(a)}$

$\gamma(a)$ is generally a "threshold" function

Several commonly used forms for the activity $\gamma(a)$

are:

The linear logistic function

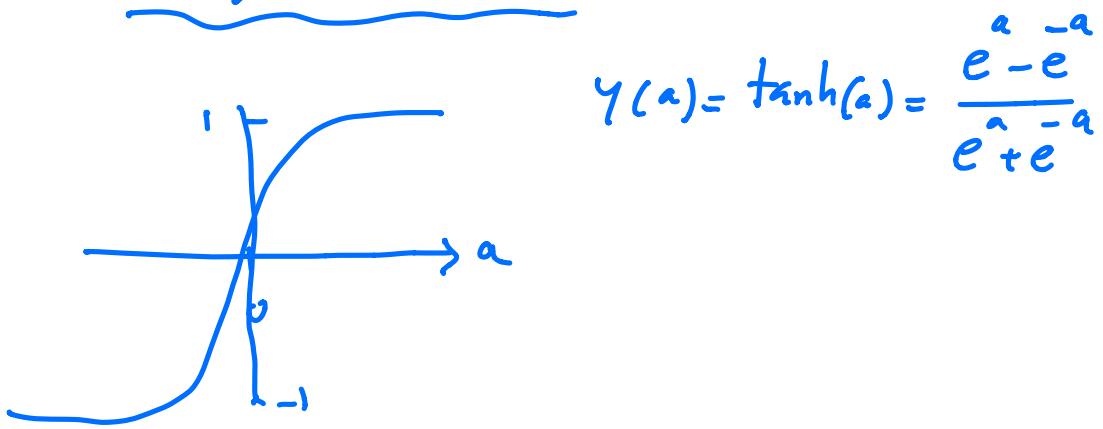


$$\gamma(a) = \frac{1}{1+e^{-a}} = \frac{1}{1+e^{-\bar{w}\bar{x}}}$$

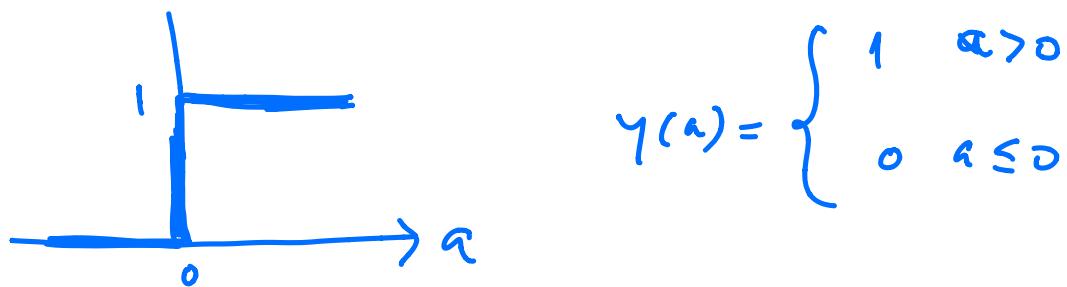
$$\bar{w}\bar{x} = \sum_i w_i x_i + w_0$$

$$= \sum_{i=0}^I w_i x_i \quad x_0 = 1$$

. the sigmoidal function



. The step function



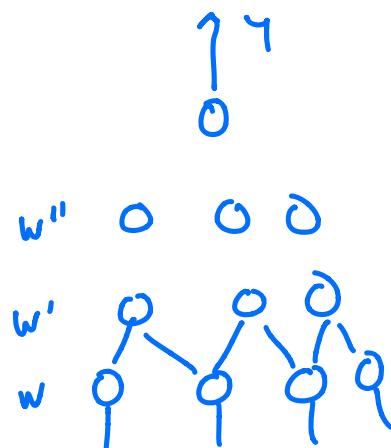
Recap Neural Network

i) architecture

w_i

ii) activity $a = \sum_{i=0}^I w_i x_i$
 $= \bar{w} \bar{x}$

iii) the activity rule $y(a) = \frac{1}{1+e^{-a}} = \frac{1}{1+e^{-\bar{w}\bar{x}}}$



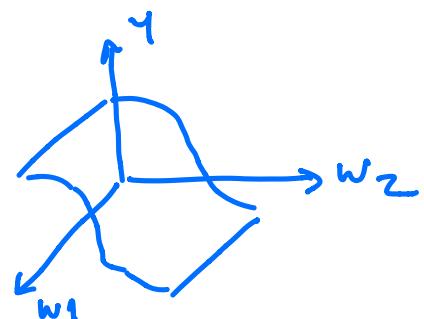
the activity $y(a)$ can be interpreted as:

The probability according to the neuron (weights)
that the inputs (\bar{x}) deserves a response

$y \approx 1$ response

$y = 0$ no response

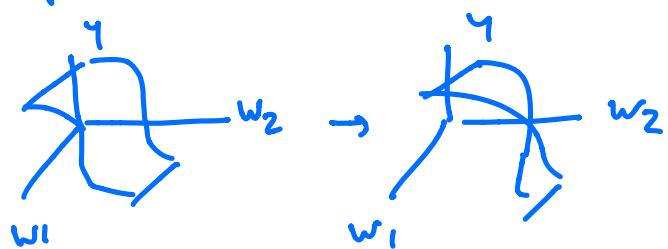
The Space of Weights



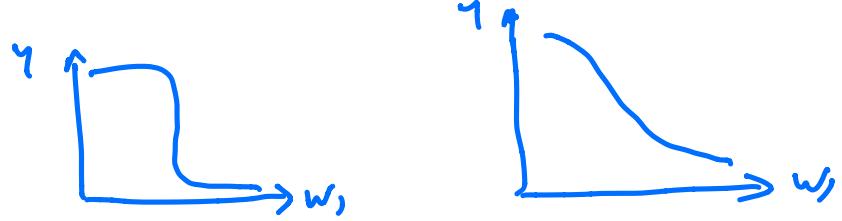
+ change in bias w_0 ,



+ change in w_1 / w_2 (a twist)



+ scale of weight



Contour plots



What can a single neuron learn?

to be a classifier!

Idea of supervised learning is:

given a number of examples of

input vectors $\bar{x}^{(1)} \dots \bar{x}^{(N)}$

and their outputs $t^{(1)} \dots t^{(N)}$

make the network learn their relationship.

Find the values of the weights so that $y^{(n)} \approx t^{(n)}$

"learning" ~ "finding parameters"

Classification problem

$A \rightarrow t=1$

w?

$y(A|w) \geq 1$

$O \rightarrow t=0$

w?

$y(O|w) \leq 0$

$$\text{error} = \left\{ \frac{y^{(1)} - t^{(1)}}{w}, \dots, \frac{y^{(N)} - t^{(N)}}{w} \right\}$$

Learning = adjust w's so that error is small.

The Error Function

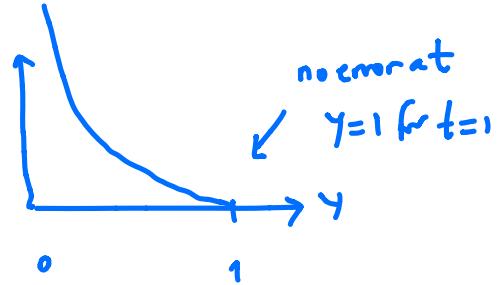
inputs: $\{\bar{x}^{(n)}, t^{(n)}\}_{n=1}^N, \{x_i^{(n)}\}_{i=0}^I$

outputs $y^{(n)}(\bar{x}^{(n)}, \bar{w}) = \frac{1}{1 + e^{-\bar{w}\bar{x}^{(n)}}}$

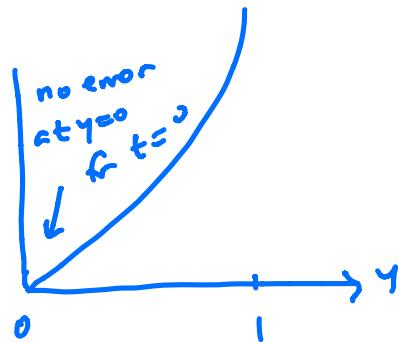
Introduce the error function

$$G(w) = -\sum_{n=1}^N \left[t^{(n)} \cdot \log y^{(n)} + (1-t^{(n)}) \log (1-y^{(n)}) \right]$$

why? $t^{(n)}=1 : -\log y^{(n)}$



$$t^{(n)}=0 : -\log(1-y^{(n)})$$



$$G(w) = - \sum_{n=1}^N \left[t^{(n)} \log y^{(n)}(\bar{w}, \bar{x}) + (1-t^{(n)}) \log (1-y^{(n)}(\bar{w}, \bar{x})) \right]$$

Back propagation

want to minimize error $G(w)$

$$G(\bar{w}) > 0 \quad \text{if} \quad G(w) = 0 \Leftrightarrow y^{(n)} = t^{(n)}$$

let's take the derivative of $G(\bar{w})$

$$\begin{aligned} \frac{\delta G(\bar{w})}{\delta w_j} &= - \sum_n \left[\frac{t^{(n)}}{y^{(n)}} - \frac{1-t^{(n)}}{1-y^{(n)}} \right] \cdot \frac{\delta y^{(n)}}{\delta w_i} \\ &= - \sum_n \frac{t^{(n)}(1-y^{(n)}) - y^{(n)}(1-t^{(n)})}{y^{(n)}(1-y^{(n)})} \frac{\delta y^{(n)}}{\delta w_i} \\ &= - \sum_n \frac{t^{(n)} - y^{(n)}}{y^{(n)}(1-y^{(n)})} \cdot \frac{\delta y^{(n)}}{\delta w_i} \end{aligned}$$

$$y^{(n)}(\bar{w}, \bar{x}) = \frac{1}{1 + e^{-\bar{w} \bar{x}^{(n)}}}$$

$$\frac{\delta y^{(n)}}{\delta w_i} = (-1) \left(1 + e^{-\bar{w} \bar{x}^{(n)}} \right)^{-2} \cdot \frac{\delta}{\delta w_i} \begin{bmatrix} -\bar{w} \bar{x}^{(n)} \\ e \end{bmatrix}$$

$$\begin{aligned} &= \frac{-1}{\left[1 + e^{-\bar{w} \bar{x}^{(n)}} \right]^2} \cdot (-w_i) \quad \bar{e} \\ &= x_i^{(n)} \cdot \frac{-\bar{w} \bar{x}^{(n)}}{\left(1 + e^{-\bar{w} \bar{x}^{(n)}} \right)^2} = x_i^{(n)} y^{(n)} (1 - y^{(n)}) \end{aligned}$$

$$\frac{\delta h(w)}{\delta w_j} = - \sum_n (t^{(n)} - y^{(n)}) x_j^{(n)} = - \sum_n e^{(n)} x_j^{(n)}$$

$$\left(\frac{\delta h}{\delta w_1}, \dots, \frac{\delta h}{\delta w_I} \right) = \boxed{\bar{g} = - \sum_n e^{(n)} \bar{x}^{(n)}}$$

gradient vector

Back propagation

Update weights by a quantity η in the opposite direction to the gradient

$$\begin{aligned}\bar{w}^{(\text{old})} \\ \bar{w}^{(\text{new})} &= \bar{w}^{(\text{old})} + \eta \sum_n e^{(n)} \bar{x}^{(n)} \\ &= \bar{w}^{(\text{old})} + \eta \sum_n (t^{(n)} - \hat{y}^{(n)}(\bar{w}^{(\text{old})}, \bar{x})) \bar{x}^{(n)}\end{aligned}$$

η = learning rate, a free parameter

Different ways to update the weight

- batch gradient descent learning
- on-line gradient descent learning

batch learning

all weights are updated by looking at all data points at the time

$$\cdot \bar{w}^{(0)}$$

$$\cdot \bar{w}^{(1)} = \bar{w}^{(0)} + \eta \sum_n (t^{(n)} - y_o^{(n)}) \bar{x}^{(n)}$$

$$y_o^{(n)} = y^{(n)}(\bar{w}^{(0)}, \bar{x}^{(n)})$$

On-line learning

Change all the weights by looking at one data point at the time

$$\cdot \bar{w}^{(0)}$$

• take $m \in M$

$$\bar{w}^{(1)} = \bar{w}^{(0)} + \eta \left[t^{(m)} - y^{(m)}(\bar{w}^{(0)}, \bar{x}^{(m)}) \right] \bar{x}^{(m)}$$

How well does the batch learning algorithm do?

Apples/ oranges

2 inputs x_1 - skin color

w_0

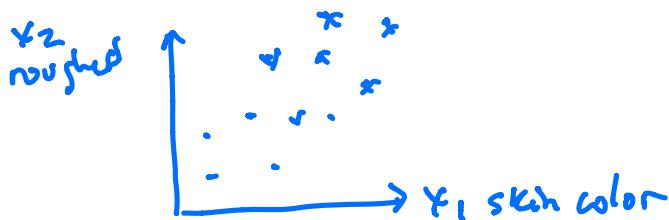
x_2 - surface roughness

w_1

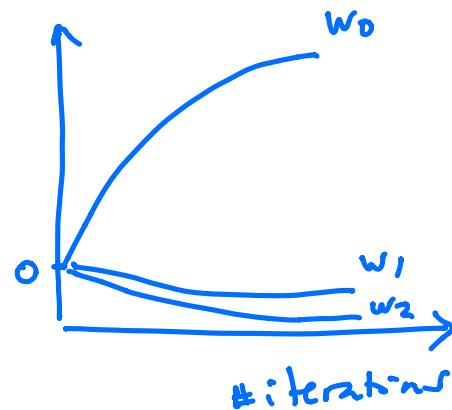
w_2

$$Y(\bar{w}, \bar{x}) = \frac{1}{1 + e^{-(w_0 + w_1 x_1 + w_2 x_2)}}$$

$N=10$ data points



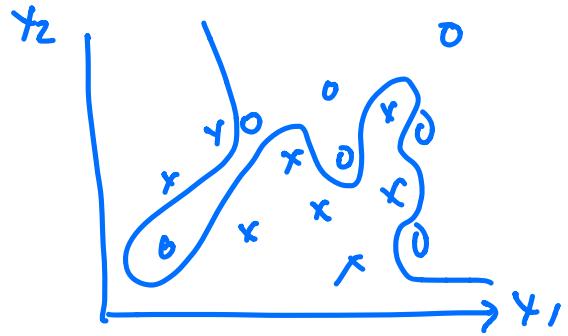
$$\eta = 0.01 \quad w_0^{(0)} = w_1^{(0)} = w_2^{(0)} = 0$$



→ class code

Regularization

To avoid overfitting



$h(w)$

$$M(\bar{w}) = h(\bar{w}, \bar{x}) + \alpha R(\bar{w})$$

$$R(\bar{w}) = \frac{1}{2} \sum_i w_i^2$$

$$\frac{\delta M}{\delta \bar{w}_i} = \frac{\delta h}{\delta w_i} + \frac{\delta R}{\delta w_i} = \frac{\delta h}{\delta w_i} + \alpha w_i$$

$$\boxed{\bar{w}^{new} = \bar{w}^{old} (1 - \eta \alpha) + \eta \sum_n (t^n - y_i^{(n)}) \bar{x}^{(n)}}$$