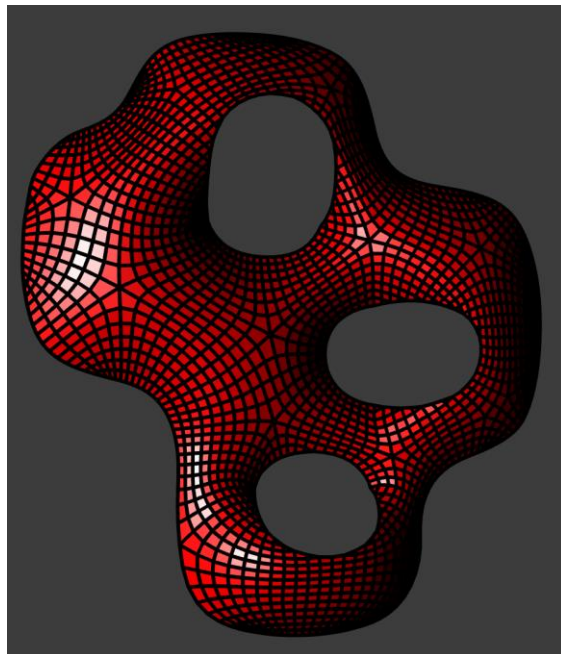
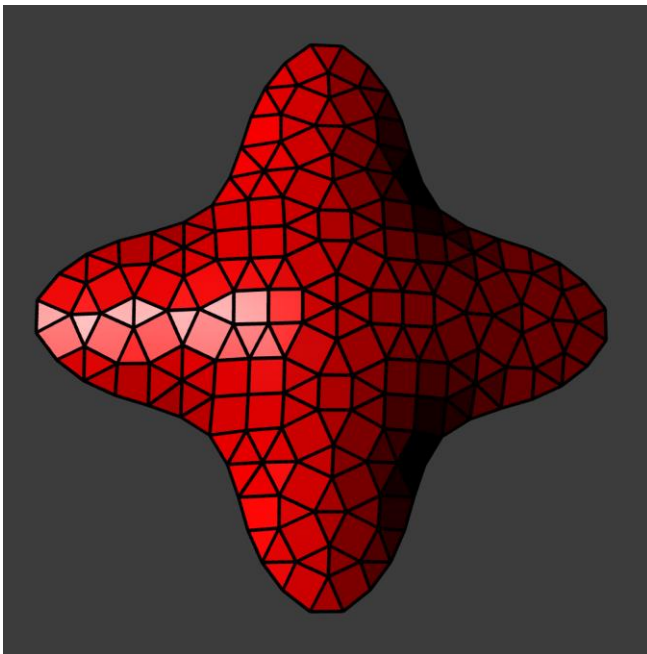
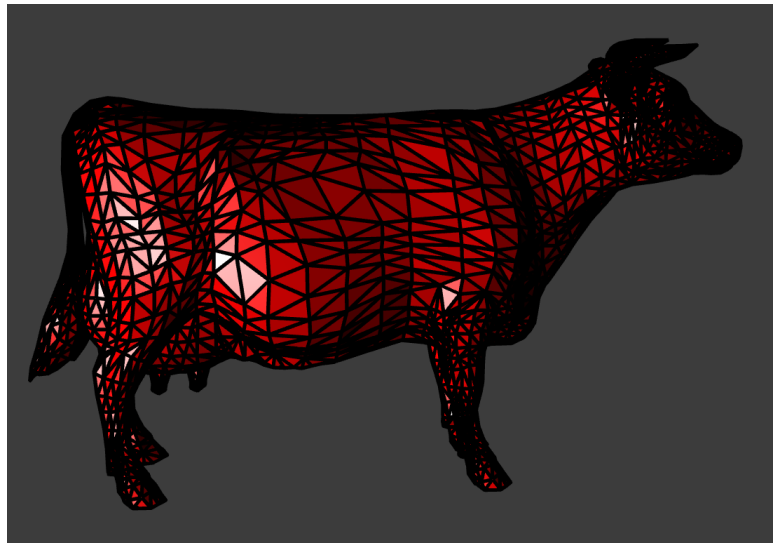
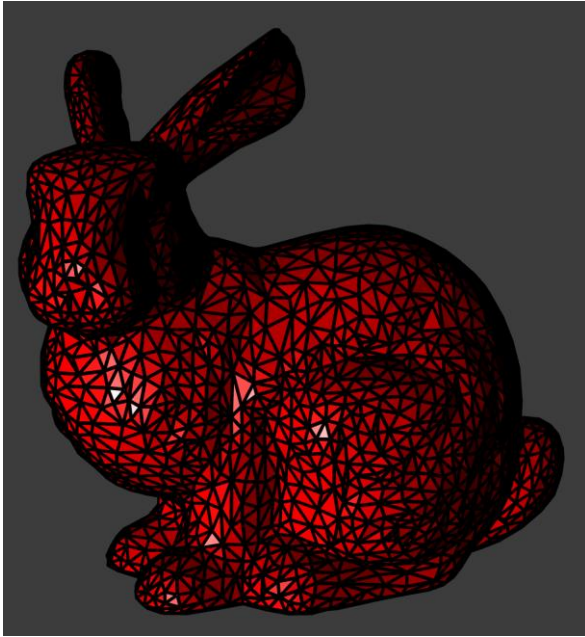


Project 4 – Discrete Curvatures

Total is 9 points and 1.5 bonus points. Your tasks are as follows:

1. [4 points] Render your half-edge meshes (loaded from .obj files) done in the previous project as *flat-faced* meshes with visible edges in OpenFrameworks. The reference is the mesh visualization as in MeshMan (<http://www.holmes3d.net/graphics/meshman/>). Show your renderings for **bunny.obj**, **cow.obj**, **lilium.obj**, and **roof.obj**. They should look like (you can pick a different color):



**Hints:** you can try your own approaches, but the best way is probably to create a “polygon-soup” as a **ofMesh**, which means every face (not necessarily triangle) has its own vertices (so if it is a quad, it has its 4 vertices). Each face’s vertices are assigned *the same normal* (the face’s normal) so they are guaranteed to be rendered in a “flat-faced” manner. Render the created ofMesh using your Blinn-Phong shaders as done in project 1 should work.

For each face, create its vertices using **ofMesh’s addVertex()** function. For every vertex, also add its normal by calling **addNormal()**. However, since **ofMesh** supports triangles only, for non-triangle faces, you do need to triangulate a face into multiple triangles and call ofMesh’s **addTriangle()** to create the triangles (as vertex indices).

To render the visible edges, this is not easy with OpenFrameworks because the ofMesh’s **drawWireFrame()** function doesn’t have depth tests. The best way is probably to create thin “cylinder” ofMeshs for each of the edges and render them separately. A function to create a cylinder ofMesh from point a to b with radius is provided for you to use (Cylinder.cpp / Cylinder.h). To avoid z-fighting between rendering the mesh itself and the edge cylinder meshes, add the following codes before rendering the mesh:

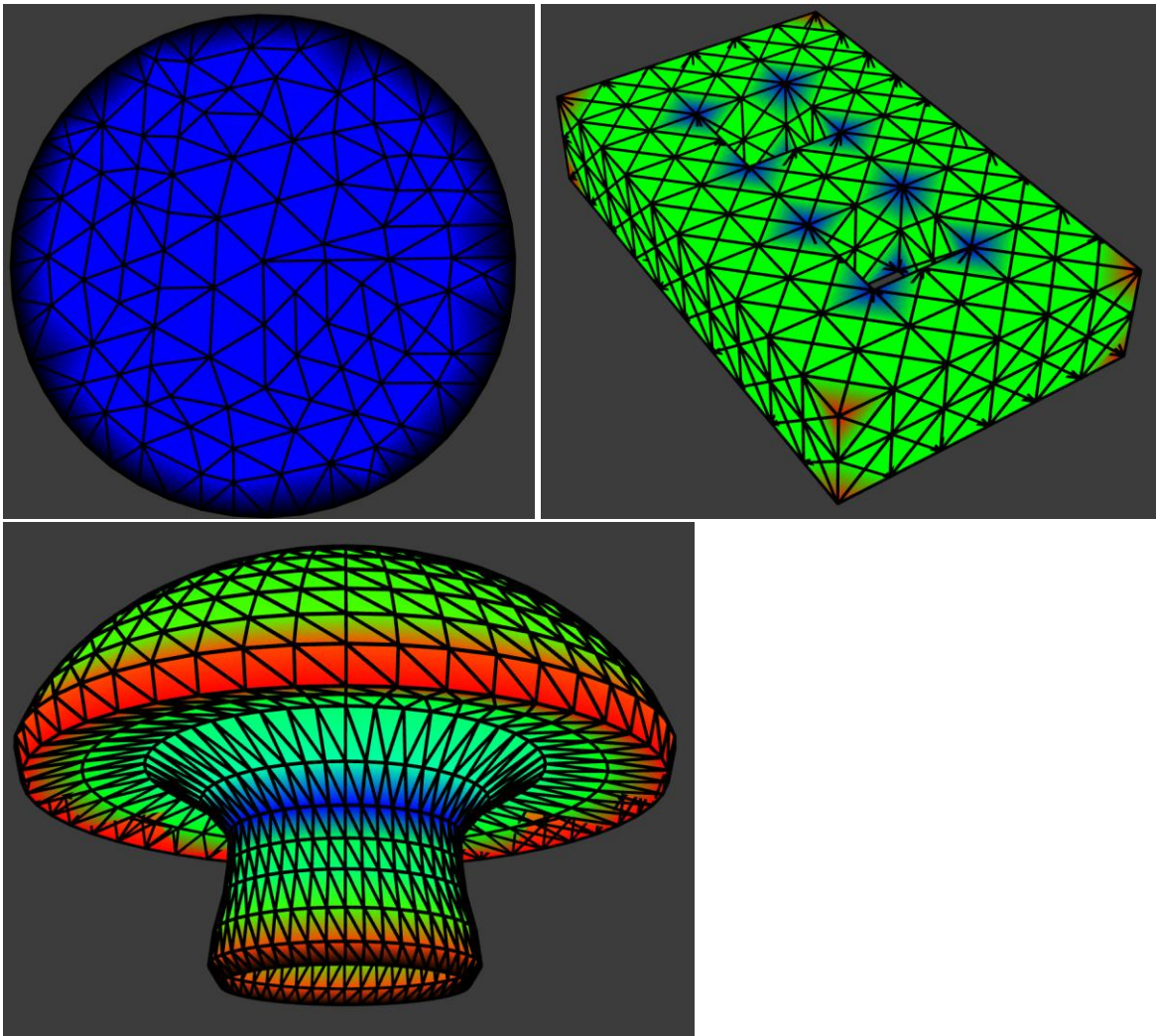
```
glEnable(GL_POLYGON_OFFSET_FILL);  
glPolygonOffset(1.0f, 0.7f);
```

Be sure to disable **GL\_POLYGON\_OFFSET\_FILL** after rendering the mesh. Consider using a different shader (e.g., just draw every fragment as black) for rendering the cylinder meshes.

[Grading: 3 points for rendering the flat-shaded meshes, 1 point for rendering the edges.]

2. [5 points] Calculate two kinds of per-vertex discrete curvature measures and color the vertices using their curvature values.

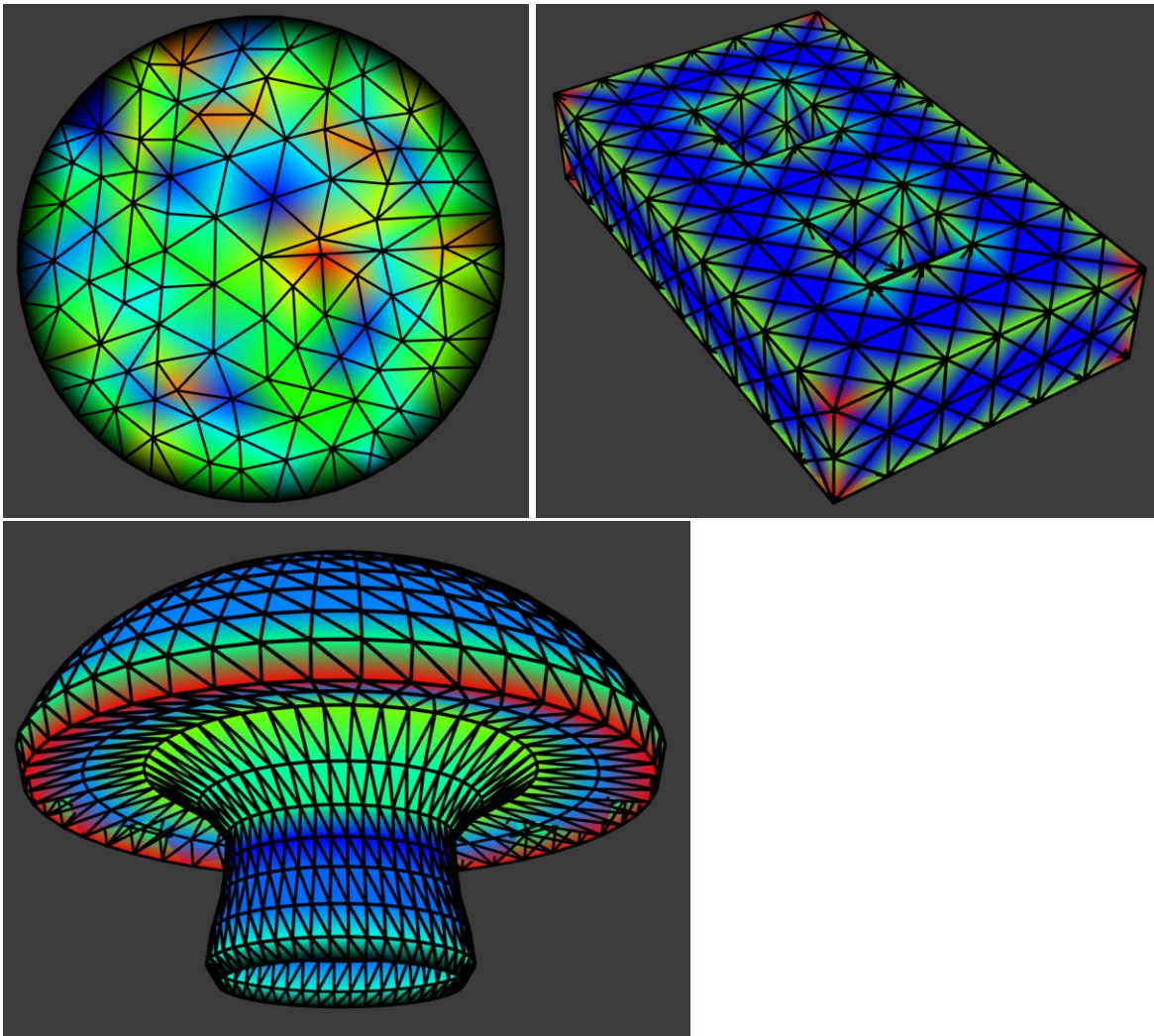
a) Calculate the **angle defects** (in radians) of every vertices (i.e., they are used as proxies for per-vertex *discrete Gaussian Curvatures*). Skip boundary vertices. Consider round values very close to 0 to 0 (e.g., “**if abs(value)<1e-5, value = 0;**”). Then, calculate a color for every vertex according to their angle defects. To do so, find the min and max values of all the angle defects, and map every angle defect value to a color from blue (min) to green (middle) to red (max). Show your results for **double\_torus.obj**, **mushroom.obj**, and **disk.obj**. The results should look like:



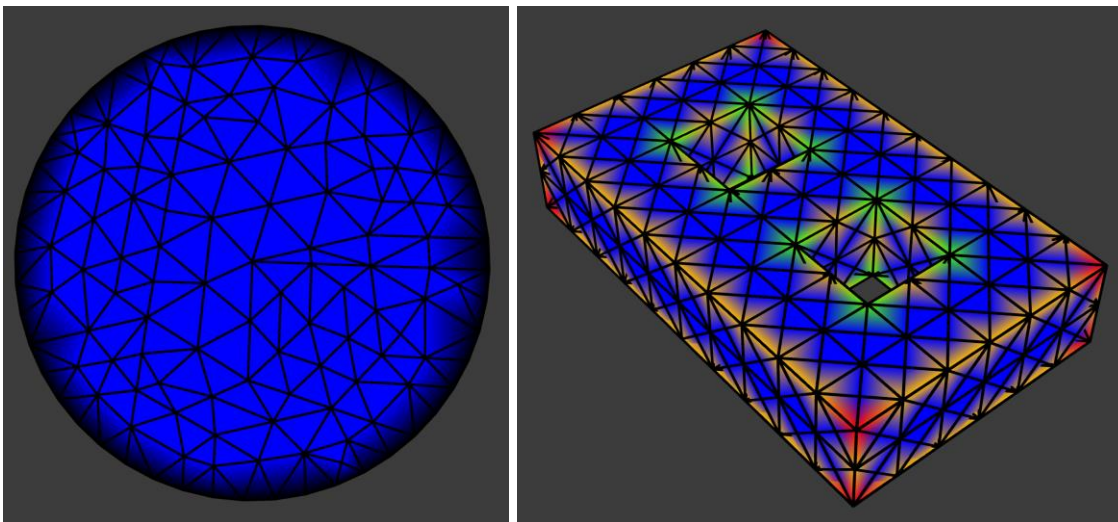
**Q1:** For each result, **point to regions with positive and negative Gaussian curvatures, respectively** (and some explanations will be great) in your video. Be careful for the disk.obj!

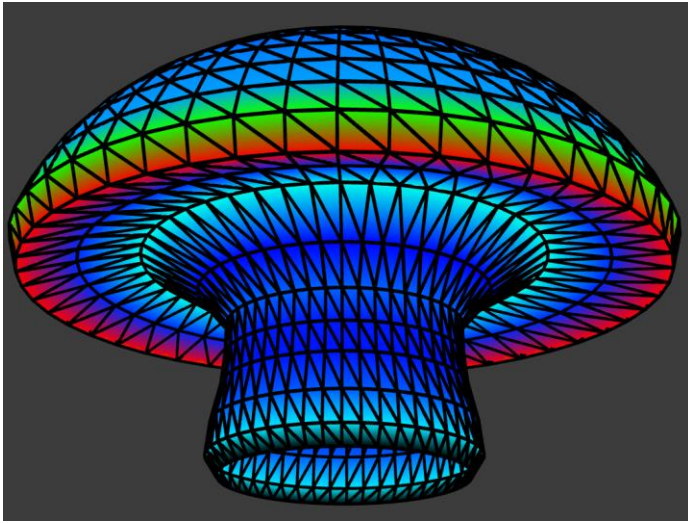
b) Calculate the **Laplacian vectors** of every vertices (i.e., they are used as proxies for per-vertex *discrete Mean Curvatures*). Skip boundary vertices. **Use uniform-weight 1-ring neighborhood scheme.** The per-vertex mean curvatures are approximated as the lengths of these Laplacian vectors. Consider round values very close to 0 to 0 (e.g., “**if abs(value)<1e-5, value = 0;**”). Then, calculate a color for every vertex according to their mean curvatures. To do so, find the min and max values of all the mean curvatures, and map every mean curvature value to a color from blue (min) to green (middle) to red (max). Show your results for double\_torus.obj, mushroom.obj, and disk.obj. The results should look like:





(c) Now, use **cotangent-weight Laplacian vector scheme** and calculate the per-vertex mean curvatures again. The results should look like:





**Q2:** why the mean curvature values calculated by the two Laplacian schemes are very different for disk.obj? which one is more correct?

[Grading: 2 points for doing (a) correctly. 1 points each for doing (b) and (c) correctly each. 0.5 points each for answering Q1 and Q2 correctly each.]

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Deliver your results as a video and your source codes.

0.5 bonus point for making a good video (clear and not overly long).

**[Challenge]** 1.0 bonus point for suggesting and implementing an even more efficient way to render the edges. (The current scheme involves creating a lot of “cylinder” meshes and becomes quite slow for big meshes. I don’t like it but I couldn’t find better ways to do so.)