view_frames Result Recorded at time: 464.802 map Broadcaster: /slam_gmapping Average rate: 20.202 Hz Most recent transform: 464.845 (-0.043 sec old) Buffer length: 4.950 sec odom Broadcaster: /odom to base Average rate: $1000\overline{0}.0\overline{0}0$ Hz Most recent transform: 0.000 (464.802 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 464.800 (0.002 sec old) Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.000$ Hz Most recent transform: 0.000 (464.802 sec old) Most recent transform: 464.800 (0.002 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec laser link livox base left wheel right_wheel