

Homework 2

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Keywords: *Newton method, projected gradient***Problem 1. Newton-CG Method for L2-regularized Logistic Regression**

Given a set of instance-label pairs $(\mathbf{x}_i, y_i), i = 1, \dots, n, \mathbf{x}_i \in \mathbb{R}^d, y_i \in \{+1, -1\}$, L2-regularized logistic regression estimates the classification model \mathbf{w} by solving the following optimization problem:

$$\min_{\mathbf{w} \in \mathbb{R}^d} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 + \sum_{i=1}^n \log(1 + \exp(-y_i \mathbf{w}^T \mathbf{x}_i)) \right\} := f(\mathbf{w}), \quad (1)$$

The data matrix is $X \in \mathbb{R}^{n \times d}$ is dense, where each row of X is a training sample. We test the algorithm using the “breast-cancer” dataset with $n = 44$ and $d = 7129$: the training data matrix X is stored in “X_cancer”, and the training labels \mathbf{y} is stored in “y_cancer” (the format is the same with hw1). Note that you are allowed to use any coding language or package in this homework.

- (a) (5 pt) Derive the gradient and Hessian of $f(\mathbf{w})$.
- (b) (15 pt) We plan to apply CG to solve the linear system (compute $\nabla^2 f(\mathbf{w})^{-1} \nabla f(\mathbf{w})$), where the main computation is the matrix vector product. The matrix vector product of $\nabla^2 f(\mathbf{w}^0) \mathbf{v}$ will need $O(d^2)$ time if we form the d by d matrix $\nabla^2 f(\mathbf{w})$ and then directly compute the matrix vector product. Explain a faster way to compute $\nabla^2 f(\mathbf{w}) \mathbf{v}$ for an arbitrary vector $\mathbf{v} \in \mathbb{R}^d$ with $O(nd)$ time.
- (c) (15 pt) Use the matrix-vector product derived in (c) to implement Conjugate Gradient method (see Algorithm 1) for solving the linear system $(\nabla^2 f(\mathbf{w}^0)^{-1} \nabla f(\mathbf{w}^0))$ up to $\|\mathbf{r}\|/\|\mathbf{r}_0\| \leq 10^{-3}$ (where \mathbf{r} is the residual in the algorithm). Report how much time does the algorithm take on the breast-cancer dataset. Report $\|\Delta \mathbf{x}^{\text{CG}}\|_2$ where $\Delta \mathbf{x}^{\text{CG}}$ is the output of CG.
- (d) (15 pt) Implement the Newton-CG algorithm (see Algorithm 2). Initial from $\mathbf{w}^0 = \mathbf{0}$ and run 20 iterations. What is the objective function value $f(\mathbf{w}^{20})$? Plot the iteration vs error figure: x -axis is $k = 1, \dots, 18$ and y -axis is the corresponding error $\log(f(\mathbf{w}^k) - f(\mathbf{w}^*))$. In practice it is impossible to get the exact optimal solution \mathbf{w}^* , so instead we assume $f(\mathbf{w}^*) = f(\mathbf{w}^{20})$ when we plot the figure.

Problem 2. Nonnegative Matrix Factorization

Given an input matrix $X \in \mathbb{R}^{m \times n}$, we try to factorize it into $X \approx WH^T$ by solving

$$\begin{aligned} (\text{NMF}) \quad & \min_{W \in \mathbb{R}^{m \times k}, H \in \mathbb{R}^{n \times k}} \frac{1}{2} \|A - WH^T\|_F^2 + \frac{\lambda}{2} \|W\|_F^2 + \frac{\lambda}{2} \|H\|_F^2, \\ & \text{s.t. } W_{ij} \geq 0, H_{ij} \geq 0 \quad \forall i, j \end{aligned}$$

We will use the cbcl dataset in “cbcl.txt”. In this data, $m = 361$, $n = 2,429$, and we set $k = 49$.

- (a) (20 pt) Apply a block-coordinate descent algorithm to solve NMF. At each iteration, we first fix W and update H , and then fix H and update W . For each subproblem, update W (or H) using projected gradient descent with 3 steps (see Algorithm 3). Use random initialization for W, H . Run the algorithm for 50 iterations and plot the objective function value vs time curve. Report the final objective function value you get.
- (b) (30 pt) Now try block coordinate descent by defining each column of W, H as a block. So there are totally $2k$ blocks (see Algorithm 4). For updating w_i (for some $1 \leq i \leq k$), we want to minimize the function with respect to w_i . Derive the corresponding subproblem and show the close form solution of w_i . Similarly run 50 iterations, report the final objective function value, and plot the objective function value vs time curve. Compare the two methods and discuss your findings.

Algorithm 1 Conjugate Gradient to Solve $A\mathbf{x} = \mathbf{b}$

- Input: A and \mathbf{b}
- $\mathbf{x}_0 = \mathbf{0}$
- $\mathbf{r}_0 = \mathbf{b} - A\mathbf{x}_0$
- $\mathbf{p}_0 = \mathbf{r}_0$
- $k = 0$
- For $k = 0, 1, \dots$
 1. $\alpha_k = \frac{\mathbf{r}_k^T \mathbf{r}_k}{\mathbf{p}_k^T A \mathbf{p}_k}$
 2. $\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{p}_k$
 3. $\mathbf{r}_{k+1} = \mathbf{r}_k - \alpha_k A \mathbf{p}_k$
 4. If $\frac{\|\mathbf{r}_{k+1}\|}{\|\mathbf{r}_0\|} \leq 10^{-3}$, exit the for loop
 5. $\beta_k = \frac{\mathbf{r}_{k+1}^T \mathbf{r}_{k+1}}{\mathbf{r}_k^T \mathbf{r}_k}$
 6. $\mathbf{p}_{k+1} = \mathbf{r}_{k+1} + \beta_k \mathbf{p}_k$

Algorithm 2 Newton method for L2-regularized logistic regression

- Input: $\{\mathbf{x}_i, y_i\}_{i=1}^n$, regularization parameter λ , initial $\mathbf{w}^0 = \mathbf{0}$.
- For iter = 1, 2, ..., 10
 1. Solving $\nabla^2 f(\mathbf{w}) \mathbf{d} = -\nabla f(\mathbf{w})$ by Algorithm 1 to get \mathbf{d} .
 2. Find the maximum step size $\alpha = \max\{1, 2^{-1}, 2^{-2}, \dots\}$ such that $\alpha \mathbf{d}$ satisfies the following line search condition:
$$f(\mathbf{w} + \alpha \mathbf{d}) < f(\mathbf{w}) + 0.01 \alpha \mathbf{d}^T \nabla f(\mathbf{w}).$$
 3. $\mathbf{w} \leftarrow \mathbf{w} + \alpha \mathbf{d}$.

Algorithm 3 Alternating minimization + Projected gradient descent for NMF

- Input: A, λ
- For $k = 0, 1, \dots$
 1. Fix W and update H : solving the following subproblem with 3 projected gradient steps:

$$\min_H \frac{1}{2} \|A - WH^T\|_F^2 + \frac{\lambda}{2} \|H\|_F^2 \quad \text{s.t.} \quad H_{ij} \geq 0, \forall i, j$$

2. Fix H and update W : solving the following subproblem with 3 projected gradient steps:

$$\min_W \frac{1}{2} \|A - WH^T\|_F^2 + \frac{\lambda}{2} \|W\|_F^2 \quad \text{s.t.} \quad W_{ij} \geq 0, \forall i, j$$

Algorithm 4 Block-coordinate descent for NMF—update one column at a time.

- Input: A , λ , initial values for W, H
 - For $t = 0, 1, \dots$
 1. For $i = 1, \dots, k$
Update w_i (i -th column of W)
 2. For $i = 1, \dots, k$
Update h_i (i -th column of H)
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