

# Sta 250 Optimization Homework 2

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## Problem 1. Newton-CG Method for L2-regularized Logistic Regression

Given a set of instance-label pairs  $(x_i, y_i), i = 1, \dots, n, x_i \in \mathbb{R}^d, y_i \in \{+1, -1\}$ , L2-regularized logistic regression estimates the classification model  $w$  by solving the following optimization problem:

$$\min_{w \in \mathbb{R}^d} \left\{ \frac{1}{2} \|w\|_2^2 + \sum_{i=1}^n \log(1 + \exp(-y_i w^T x_i)) \right\} := f(w),$$

The data matrix is  $X \in \mathbb{R}^{n \times d}$  is dense, where each row of  $X$  is a training sample. We test the algorithm using the “breast-cancer” dataset with  $n = 44$  and  $d = 7129$ : the training data matrix  $X$  is stored in “X\_cancer”, and the training labels  $y$  is stored in “y\_cancer” (the format is the same with hw1). Note that you are allowed to use any coding language or package in this homework.

(a) Derive the gradient and Hessian of  $f(w)$ . the objective function

$$\min_{w \in \mathbb{R}^d} \left\{ \frac{1}{2} \|w\|_2^2 + \sum_{i=1}^n \log(1 + \exp(-y_i w^T x_i)) \right\} := f(w),$$

```
#set f(w) as a function
#X[1]=y,X[-1]=x
fw<-function(w){
  1/2*sum(w^2)+sum(apply(X,1,function(X){log(1+exp(-X[1]*X[-1]*%*%w))}))
}
```

the gradient is

$$\nabla f(w) = \sum_{i=1}^n \frac{-y_i e^{-y_i w^T x_i}}{1 + e^{-y_i w^T x_i}} x_i + w$$

```
#set f'(w) as a function
fw1<-function(w){
  #calculate f'(w)
  fw=rowSums(apply(X,1,function(X){
    e=exp(-X[1]*X[-1]*%*%w)
    X[-1]*as.numeric((-X[1]*e)/(1+e))
  })))
  fw+w
}
```

the hessian matrix of  $f(w)$

$$\nabla^2 f(w) = \sum_{i=1}^n \frac{y_i^2 e^{-y_i w^T x_i}}{(1 + e^{-y_i w^T x_i})^2} x_i x_i^T + I$$

(b) We plan to apply CG to solve the linear system (compute  $\nabla^2 f(w)^{-1} \nabla f(w)$ ), where the main computation is the matrix vector product. The matrix vector product  $\nabla^2 f(w^0) v$  will need  $O(d^2)$  time if we form the  $d$  by  $d$  matrix  $\nabla^2 f(w)$  and then directly compute the matrix vector product. Explain a faster way to compute  $\nabla^2 f(w) v$  for an arbitrary vector  $v \in \mathbb{R}^d$  with  $O(nd)$  time.

Because the hessian matrix is in the form like  $\sum a_i x_i x_i^T + I$ , we can calculate the  $\nabla^2 f(w) v$  by

$$\left( \sum a_i x_i x_i^T + I \right) v = \sum a_i x_i x_i^T v + v = \sum a_i x_i (x_i^T v) + v$$

this will avoid doing the  $d$  by  $d$  matrix calculation.

- (c) Use the matrix-vector product derived in (c) to implement Conjugate Gradient method (See Algorithm 1) for solving the linear system  $(\nabla^2 f(w_0)^{-1} \nabla f(w_0))$  up to  $\|r\|/\|r_0\| \leq 10^{-3}$  (where  $r$  is the residual in the algorithm). Report how much time does the algorithm take on the breast-cancer dataset. Report  $\|\Delta x^{CG}\|_2$  where  $\Delta x^{CG}$  is the output of CG.

```
x=read.table('C:/Users/Chan/Desktop/Files/STA250/Homework 2/hw2_data/X_cancer')
y=read.table('C:/Users/Chan/Desktop/Files/STA250/Homework 2/hw2_data/y_cancer')
n=nrow(x)
d=ncol(x)
X=cbind(y,x)
```

Algorithm 1

```
CG=function(w){
  b=-fw1(w)#this is the b in the Algorithm

  output=integer(d)
  r=b-0#Ax=0
  r0=sqrt(sum(r^2))
  p=r

  while(sqrt(sum(r^2))/r0>10^(-3)){

    #use the product derived in (b)
    fw=rowSums(apply(X,1,function(X){
      e=exp(-X[1]*X[-1]%*%w)
      t(X[-1])*as.numeric(X[-1]%*%p)*as.numeric((X[1]^2*e)/(1+e)^2)
    })))
    Ap=fw+p#Ap_k in the Algorithm

    a=as.numeric(t(r)%*%r/(t(p)%*%Ap))
    output=output+a*p
    r2=r-a*Ap
    b=as.numeric(t(r2)%*%r2/t(r)%*%r)
    p=r2+b*p
    r=r2
  }
  output
}
```

Report how much time does the algorithm take on the dataset.

```
system.time(CG(numeric(d)))
```

```
##      user  system elapsed
##    0.97    0.00    0.97
```

the iteration times

```
CG2=function(w){
  b=fw1(w)#this is the b in the Algorithm

  output=integer(d)
  r=b-0#Ax=0
  r0=sqrt(sum(r^2))
  p=r
  i=0#count for iteration
```

```

while(sqrt(sum(r^2))/r0>10^(-3)){
  i=i+1
  #use the product derived in (b)
  fw=rowSums(apply(X,1,function(X){
    e=exp(-X[1]*X[-1]%%w)
    t(X[-1])*as.numeric(X[-1]%%p)*as.numeric((X[1]^2*e)/(1+e)^2)
  }))
  Ap=fw+p#Ap_k in the Algorithm

  a=as.numeric(t(r)%%r/(t(p)%%Ap))
  output=output+a*p
  r2=r-a*Ap
  b=as.numeric(t(r2)%%r2/t(r)%%r)
  p=r2+b*p
  r=r2
}
i#change the output to the iteration times
}
CG2(numeric(d))

```

```
## [1] 12
```

Report  $\|\Delta x^{CG}\|_2$  where  $\Delta x^{CG}$  is the output of CG.

```
norm(CG(numeric(d)),"2")
```

```
## [1] 0.177959
```

(d) Implement the Newton-CG algorithm (See Algorithm 2). Initial from  $w^0 = 0$  and run 20 iterations. What is the objective function value  $f(w^{20})$ ? Plot the iteration vs error figure: x-axis is  $k=1, \dots, 18$  and y-axis is corresponding error  $\log(f(w^k) - f(w^*))$ . In practice it is impossible to get the exact optimal solution  $w^*$ , so instead we assume  $f(w^*) = f(w^{20})$  when we plot the figure.

```

#set the iteration times
k=20
#initial w
w=matrix(0, d, 1)
#To record w
wlist=matrix(0,d,(k+1))
wlist[,1]=w

for(j in 1:k){
  D=CG(w)
  alpha=1
  while(fw(w+alpha*D)>fw(w)+0.01*alpha*t(D)%%fw1(w)){
    alpha=alpha/2
  }
  w=w+alpha*D#the new w
  wlist[,j+1]=w#record w
}

flist=vector(mode='numeric',k+1)
for (j in 1:(k+1)) {
  flist[j]=fw(wlist[,j])}

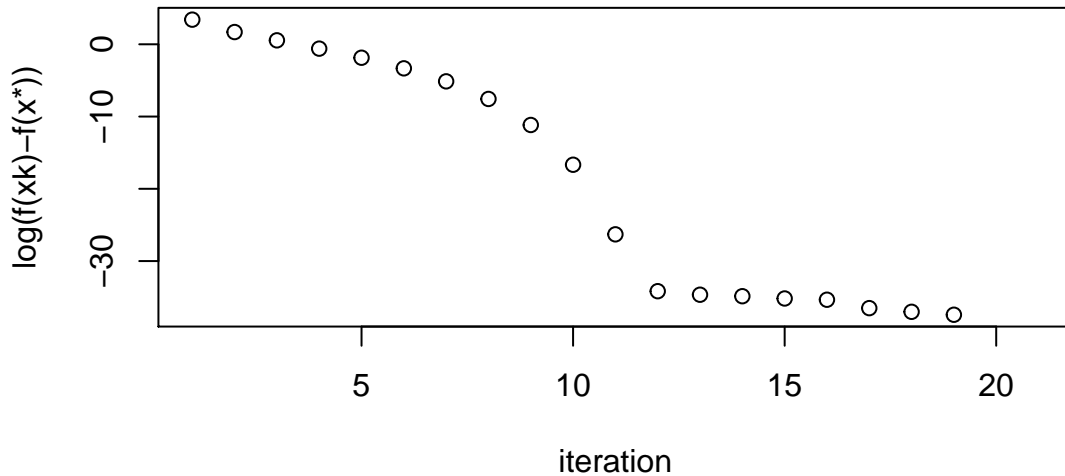
min(flist)

```

```
## [1] 0.2158171
```

```
plot(log(flist-min(flist)),xlab = "iteration",ylab = "log(f(xk)-f(x*))",main = "Newton method for L2-reg
```

## Newton method for L2-regularized logistic regression



### Problem 2. Nonnegative Matrix Factorization

Given an input matrix  $X \in \mathbb{R}^{m \times n}$ , we try to factorize it into  $X \approx WH^T$  by solving

$$(NMF) \min_{W \in \mathbb{R}^{m \times k}, H \in \mathbb{R}^{n \times k}} \frac{1}{2} \|A - WH^T\|_F^2 + \frac{\lambda}{2} \|W\|_F^2 + \frac{\lambda}{2} \|H\|_F^2$$

$$s.t. W_{ij} \geq 0, H_{ij} \geq 0 \forall i, j$$

We will use the cbcl dataset in “cbcl.txt”. In this data,  $m=361, n=2,429$ , and we set  $k=49$ .

- Apply a block-coordinate descent algorithm to solve NMF. At each iteration, we first fix  $W$  and update  $H$ , and then fix  $H$  and update  $W$ . For each subproblem, update  $W$  (or  $H$ ) using projected gradient descent with 3 steps (see Algorithm 3). Use random initialization for  $W, H$ . Run the algorithm for 50 iterations and plot the objective value vs time curve. Report the final objective function value you get.

First we need to derive the gradient

$$\nabla_W f(W, H) = (WH^T - A)H + \lambda W$$

$$\nabla_H f(W, H) = (WH^T - A)^T W + \lambda H$$

```
fW=function(W,H){
  (W%*%t(H)-A)%*%H+lambda*W
}

fH=function(W,H){
  t((W%*%t(H)-A))%*%W+lambda*H
}
```

```

#objective function
f=function(W,H){
  norm(as.matrix(A-W%*%t(H)),"F")^2/2+lambda/2*norm(W,"F")^2+lambda/2*norm(H,"F")^2
}

```

```

A=read.table('C:/Users/Chan/Desktop/Files/STA250/Homework 2/hw2_data/cbcl.txt')
A=as.matrix(A)
m=nrow(A)
n=ncol(A)
k=49

```

```

#initial W and H randomly
set.seed(100)
W=matrix(runif(m*k,0,.1),m, k)
H=matrix(runif(n*k,0,.1),n, k)

```

```

#set eta
eta=0.0001
#set lambda
lambda=1
flist=f(W,H)

```

```

for(i in 1:50){
  for(j in 1:3){
    W=W-eta*fW(W,H)#the new w
    W[W<0]=0
  }
  for(j in 1:3){
    H=H-eta*fH(W,H)#the new w
    H[H<0]=0
  }
  flist=cbind(flist,f(W,H))
}

```

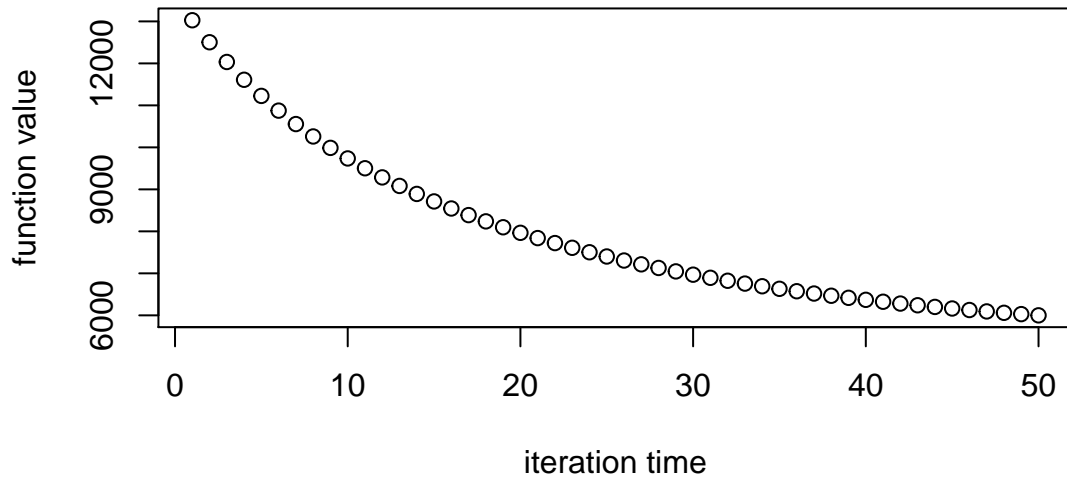
function value vs time curve and the final objective function value

```

plot(as.vector(flist[-1]),xlab = "iteration time",ylab = "function value",
     main = "objective function value vs time curve")

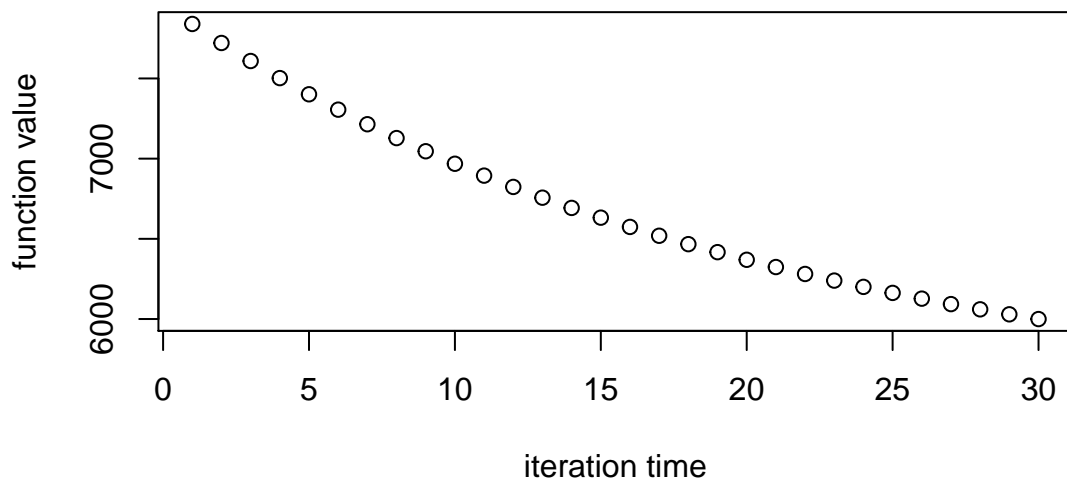
```

### objective function value vs time curve



```
plot(as.vector(flist[-(1:21)]),xlab = "iteration time",ylab = "function value",
     main = "objective function value vs time curve with last 30 times")
```

### objective function value vs time curve with last 30 times



```
f(W,H)
```

```
## [1] 5999.648
```

- (b) Now try block coordinate descent by defining each column of  $W, H$  as a block. So there are totally  $2k$  blocks (See Algorithm 4). For updating  $w_i$  (for some  $1 \leq i \leq k$ ), we want to minimize the function with respect to  $w_i$ . Derive the corresponding subproblem and show the close form solution of  $w_i$ . Similarly run 50 iterations, report the final objective function value, and plot the objective function value vs time curve. Compare the two methods and discuss your findings.

Fix  $H$  and the remain column of  $W$ , the subproblem is that

$$\min_{w_i} \frac{1}{2} \|A^* - w_i h_i^T\|_F^2 + \frac{\lambda}{2} \|w_i\|_F^2$$

where

$$A^* = A - \sum_{k \neq i} w_k h_k$$

First we need to derive the gradient

$$\nabla_{w_i} f(W, H) = (w_i h_i^T - A^*) h_i + \lambda w_i$$

set the gradient to zero, and we get

$$w_i = \frac{A^* h_i}{h_i^T h_i + \lambda}$$

we also need to projection to let  $w_i \geq 0$

$$\nabla_{h_i} f(W, H) = (W H^T - A)^T w_i + \lambda h_i$$

similarly

$$h_i = \frac{A^{*T} w_i}{w_i^T w_i + \lambda}$$

```
#initial W and H randomly, seed is set so they are the same as (a)
set.seed(100)
W=matrix(runif(m*k,0,.1), m, k)
H=matrix(runif(n*k,0,.1), n, k)

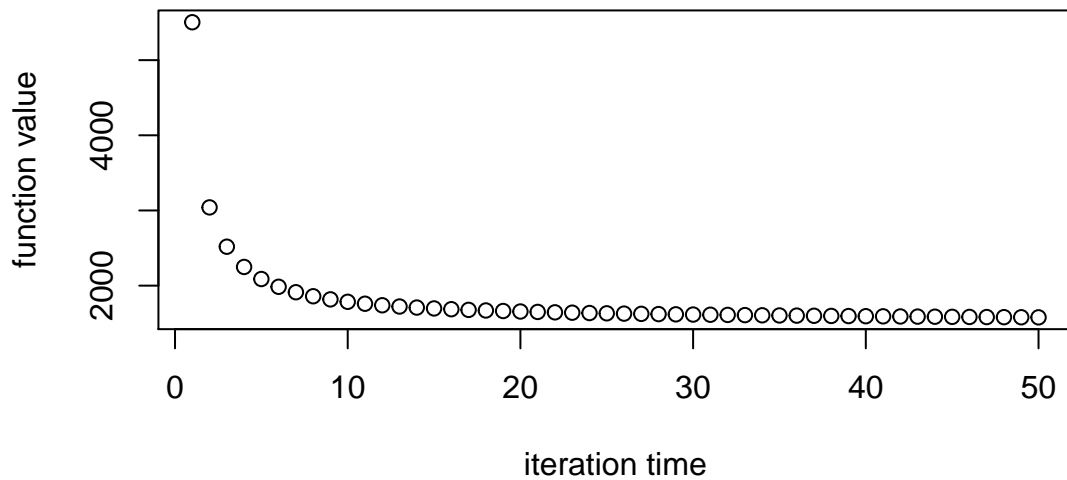
#set eta
eta=0.0001
#set lambda
lambda=1
flist=f(W,H)

for(i in 1:50){
  for(j in 1:k){
    A2=A-W%*%t(H)+W[,j]%*%t(H[,j])
    W[,j]=A2%*%H[,j]/as.numeric(t(H[,j])%*%H[,j]+lambda) #the new wj
    W[W<0]=0
  }
  for(j in 1:k){
    A2=A-W%*%t(H)+W[,j]%*%t(H[,j])
    H[,j]=t(A2)%*%W[,j]/as.numeric(t(W[,j])%*%W[,j]+lambda) #the new w
    H[H<0]=0
  }
  flist=cbind(flist,f(W,H))
}
```

function value vs time curve and the final objective function value

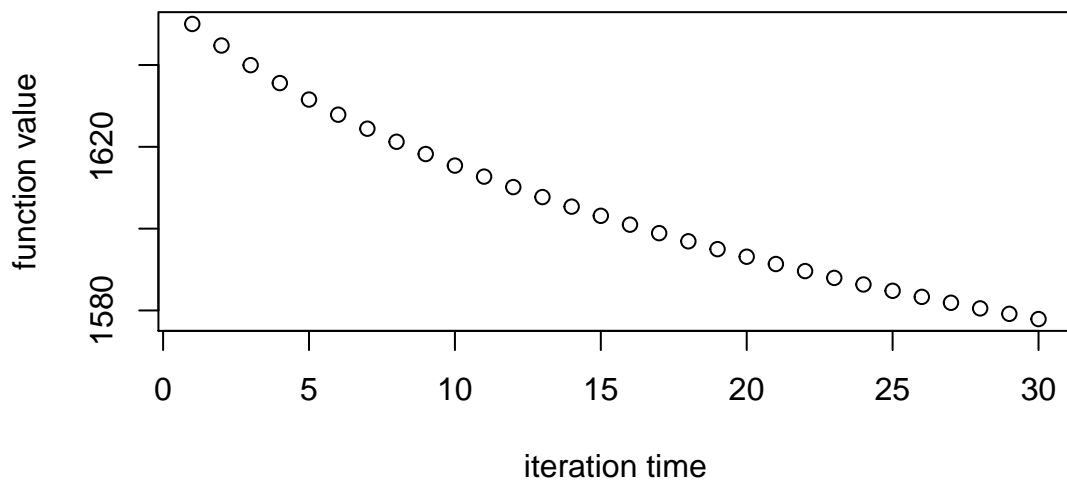
```
plot(as.vector(flist[-1]),xlab = "iteration time",ylab = "function value",
     main = "objective function value vs time curve")
```

### objective function value vs time curve



```
plot(as.vector(flist[-(1:21)]),xlab = "iteration time",ylab = "function value",  
     main = "objective function value vs time curve with last 30 times")
```

### objective function value vs time curve with last 30 times



```
f(W,H)
```

```
## [1] 1577.892
```