

MNIST数据集

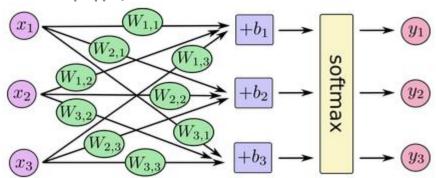
• 基础知识

• MNIST数据集 MNIST数据集相当于编程入门的Hello World



Label: 5 0 4

• Softmax回归



-1



MNIST——BP神经网络

- · BP神经网络
 - MNIST数据集
 - # 加载MNIST微据集

```
from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_sets("MNIST_data/", one_hot=True)
```

• 定义输入输出的placeholder

```
# 输入图片为28 x 28 像素 = 784, 其中None表任意值, 特别对应tensor数目 x = tf.placeholder(tf.float32, [None, 784]) # 输出为0-9的one-hot编码 y = tf.placeholder(tf.float32, [None, 10])
```

• 三层的BP神经网络

```
# 定义参数w和b
# 全连接层的两个参数w和b都是随机初始化的
# hidden Layer => w, b
W1 = tf.Variable(tf.random_normal([784, 300], stddev=0.03), name='W1')
b1 = tf.Variable(tf.random_normal([300]), name='b1')
# output Layer => w, b
W2 = tf.Variable(tf.random_normal([300, 10], stddev=0.03), name='W2')
b2 = tf.Variable(tf.random_normal([10]), name='b2')
# 构造隐层网络
# hidden Layer
hidden_out = tf.add(tf.matmul(x, W1), b1)
hidden_out = tf.nn.relu(hidden_out)
# 构造输出(预测值)
# 计算输出
y = tf.nn.softmax(tf.add(tf.matmul(hidden_out, W2), b2))
```

程序报错可以下 载数据集放在代 码的文件夹内, 不要解压



MNIST——BP神经网络

- BP神经网络
 - 损失函数:交叉熵损失函数

```
# BP神经网络部分——定义损失函数
cross_entropy = -tf.reduce_sum(y_*tf.log(y))
```

• 优化算法: 梯度下降算法

```
# BP神经网络部分---定义优化算法
```

创建优化器,确定优化目标,学习率为0.5、最小化交叉熵损失函数

optimizer = tf.train.GradientDescentOptimizer(learning_rate=

learning_rate).minimize(cross_entropy)

• 参数初始化和模型评估

```
# BP神经网络部分—定义初始化operation和推确率node
# init operator
init_op = tf.global_variables_initializer()
# 创建准确率节点,返回一个m乘1的张量,值为T/F
correct_prediction = tf.equal(tf.argmax(y, 1), tf.argmax(y_, 1))
accuracy = tf.reduce_mean(tf.cast(correct_prediction, tf.float32))
```



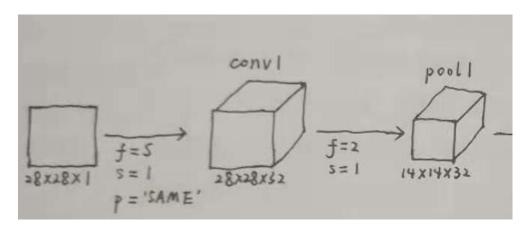
MNIST——BP神经网络

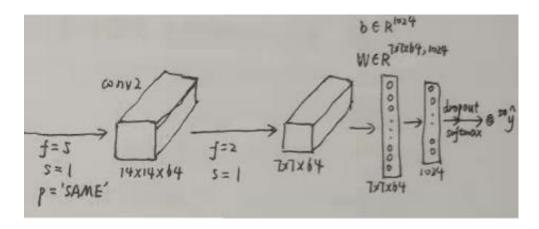
• BP神经网络——模型训练与结果

```
sess = tf.Session()
sess.run(init)
# 训练模型,循环1000次
for i in range(1000):
  batch xs, batch ys = mnist.train.next batch(100)
  sess.run(optimizer, feed dict={x: batch xs, y : batch ys})
# 创建催确等节点,返回一个m乘1的张量,值为T/F,tf.argmax(y,1)返回模型预测的类别标签
correct prediction = tf.equal(tf.argmax(y,1), tf.argmax(y_,1))
accuracy = tf.reduce mean(tf.cast(correct prediction, "float"))
print sess.run(accuracy, feed dict={x: mnist.test.images, y : mnist.test.labels})
# 任务完成, 美闭会话,
                                                                         Epoch: 1 cost = 0.586
sess.close()
                                                                         Epoch: 2 cost = 0.216
                                                                         Epoch: 3 cost = 0.158
# 开始训练
                                                                         Epoch: 4 cost = 0.126
# @@session
                                                                         Epoch: 5 cost = 0.100
with tf.Session() as sess:
                                                                         Epoch: 6 cost = 0.082
   # 变量初始化
                                                                         Epoch: 7 cost = 0.069
    sess.run(init op)
                                                                         Epoch: 8 cost = 0.058
    # 设定循环100=batch size使得total batch次可以循环结束
                                                                         Epoch: 9 cost = 0.046
    total batch = int(len(mnist.train.labels) / batch size)
                                                                         Epoch: 10 cost = 0.037
    for epoch in range(epochs):
                                                                         0.9783
        avg cost = 0
        for i in range(total batch):
            batch x, batch y = mnist.train.next batch(batch size=batch size)
            _, c = sess.run([optimizer, cross_entropy], feed_dict={x: batch_x, y: batch_y})
            avg cost += c / total batch
        print("Epoch:", (epoch + 1), "cost = ", "{:.3f}".format(avg cost))
    print(sess.run(accuracy, feed dict={x: mnist.test.images, y: mnist.test.labels}))
```



• 卷积神经网络







- 卷积神经网络
 - 定义卷积和池化函数

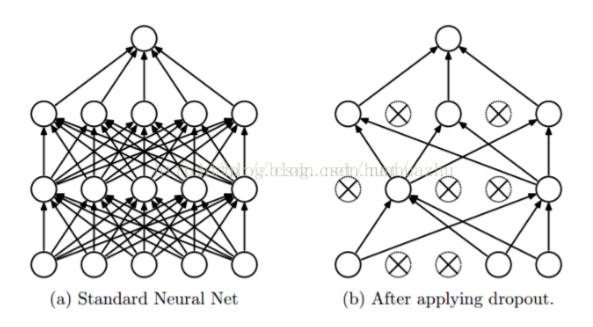
```
# 定义卷积层,宏长为1, SAME输入输出图片一样大
  def conv2d(x, W):
    return tf.nn.conv2d(x, W, strides=[1, 1, 1, 1], padding='SAME')
  # 定义池化层,2乘2的池化窗口,步长为2
  def max pool 2x2(x):
    return tf.nn.max pool(x, ksize=[1, 2, 2, 1],
                        strides=[1, 2, 2, 1], padding='SAME')
• 第一层和第二层卷积
  # 第一层券积
  # Conv1:32个filter个数,5乘5的卷积核;h conv1.shape=[-1,28,28,32]
  w conv1 = weight variable([5,5,1,32])
  b conv1 = bias variable([32])
  h_conv1 = tf.nn.relu(conv2d(X,w_conv1) + b_conv1)
  # Pool1: 最大值池化层2x2 [-1,28,28,28]->[-1,14,14,32]
  h pool1 = max pool 2x2(h conv1)
  # 第二层袋积
  # Conv2:64个filter个数,5乘5的卷积核;h_conv2.shape=[-1,14,14,64]
  w conv2 = weight variable([5,5,32,64])
  b conv2 = bias variable([64])
  h conv2 = tf.nn.relu(conv2d(h pool1,w conv2) + b conv2)
  # Pool2: 最大值池化层2x2 [-1,14,14,64]->[-1,7,7,64]
  h pool2 = max pool 2x2(h conv2)
```



• 卷积神经网络

Dropout

Dropout就是在不同的训练过程中随机扔掉一部分神经元。也就是让某个神经元的激活值以一定的概率p,让其停止工作。



但在测试及验证中:每个神经元都要参加运算,但其输出要乘以概率p。



• 卷积神经网络

Dropout

```
# dropout
# 使輸入tensor中某些元素变为0,其它投变0的元素变为原来的1/keep prob大小
# 用一个placeholder来代表一个神经元的输出在dropout中保持不变的概率
keep_prob = tf.placeholder(tf.float32) #弃权概率0.0-1.0 1.0表示不使用弃权
h fc1 drop = tf.nn_dropout(h fc1, keep prob)
# 驗房层
W fc2 = weight variable([1024, 10])
b fc2 = bias variable([10])
y conv = tf.nn.softmax(tf.matmul(h fc1 drop, W fc2) + b fc2)
sess.run(tf.initialize all variables())
# sess.run(tf.global variables initializer())
for i in range(20000):
 batch = mnist.train.next batch(50)
 if i%100 == 0:
     # 在feed dict中加入额外的参数keep prob来控制dropout比例
   train accuracy = accuracy.eval(feed dict={
       x :batch[0], y : batch[1], keep prob: 1.0})
   print ("step %d, training accuracy %g"%(i, train accuracy))
 train.run(feed dict={x : batch[0], y : batch[1], keep prob: 0.5})
print ("test accuracy %g"%accuracy.eval(feed_dict={
   x : mnist.test.images, y : mnist.test.labels, keep prob: 1.0}))
sess.close()
```



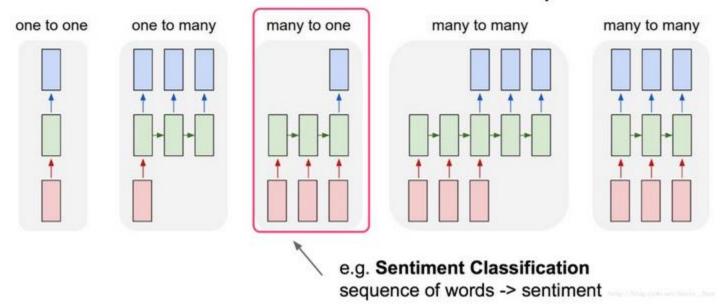
- · 卷积神经网络
 - ADAM优化器来做梯度最速下降(85行)
 train = tf.train.AdamOptimizer(1e-4).minimize(cross_entropy)
 - 模型结果

```
step 9300, training accuracy 1
step 9400, training accuracy 1
step 9500, training accuracy 1
step 9600, training accuracy 1
step 9700, training accuracy 0.98
step 9800, training accuracy 1
step 9900, training accuracy 1
step 10000, training accuracy 1
step 10100, training accuracy 0.98
```



Sequence Classification

Recurrent Neural Networks: Process Sequences



图像的分类对应上图就是个many to one的问题. 对于mnist来说 其图像的size是28*28,如果将其看成28个step,每个step的size 是28的话,刚好符合上图。



搭建LSTM

• 步骤1: 把784个点的字符信息还原成 28 * 28 的图片

```
# **步驟1: RNN 的輸入shape = (batch_size, timestep_size, input_size)
X = tf.reshape(X_input, [-1, 28, 28])
```

• 步骤2-3: 定义多层LSTM模型

```
stacked_rnn = []
for iiLyr in range(layer_num):
    # **步驟2: 定义一层 LSTM_cell, 只需要说明 hidden_size, 它会自动匹配输入的 X 的维度
    stacked_rnn.append(tf.nn.rnn_cell.LSTMCell(num_units=hidden_size, state_is_tuple=True))
# **步驟3: 週用 MultiRNNCell 来实现多层 LSTM
mlstm_cell = tf.nn.rnn_cell.MultiRNNCell(cells=stacked_rnn, state_is_tuple=True)
```

• tf.nn.rnn_cell.BscicLSTMCell

```
tf.nn.rnn_cell.BasicLSTMCell(n_hidden, forget_bias=1.0, state_is_tuple=True)
n_hidden 表示神经元个数
forget_bias LSTM忘记系数: 1.0=不会忘记信息,0.0=都忘记
state_is_tuple 输出为元祖,zero_state(batch_size,dtype)
```

• tf.nn.rnn_cell.MultiRNNCell

```
tf.nn.rnn_cell.MultiRNNCell([list RNNcell], state_is_tuple=True) [list RNNcell] RNN神经元组成的列表
```



搭建LSTM

• 步骤4: 用全零来初始化state # ** <u>运骤4: 用全零来初始</u>化state

```
init_state = mlstm_cell.zero_state(batch_size, dtype=tf.float32)
```

• 步骤5: 方法一: 按时间步展开计算

```
# **步骤5: 核时间步展开计算

outputs = list()

state = init_state

with tf.variable_scope('RNN'):
    for timestep in range(timestep_size):
        (cell_output, state) = mlstm_cell(X[:, timestep, :],state)
        outputs.append(cell_output)

h_state = outputs[-1]
```

• 方法二: tf.nn.dynamic_rnn

```
outputs, state = tf.nn.dynamic_rnn(cell,inputs,...)
cell 构建的多层RNN神经网络; inputs 输入的变量X
outputs 最后一层每个step的输出值; state 每一层RNN最后一个step的输出
```

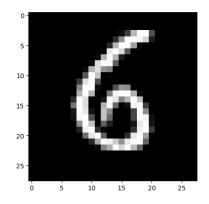


・模型输出

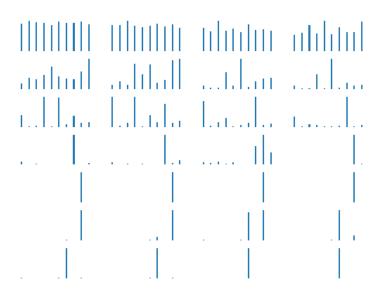
```
***模型训练和测试***
sess = tf.Session()
sess.run(tf.global variables initializer())
time0 = time.time()
for i in range(5000):
    batch size=100
    X batch, y batch = mnist.train.next batch(batch size= batch size)
    cost, acc, _ = sess.run([cross entropy, accuracy, train op], feed dict={X input: X batch,
                                 y_input: y_batch, keep_prob: 0.5, batch_size: _batch_size})
    if (i+1) % 500 == 0:
         # 分 100 个batch 迭代
         test acc = 0.0
         test cost = 0.0
               print("step {}, train cost={:.6f}, acc={:.6f}; test cost={:.6f}, acc={:.6f}; pass {}s".format(i+1, cost
               timeO = time.time()
step 500, train cost=0.010285, acc=0.970000; test cost=0.012022, acc=0.962800; pass 346.39578437805176s
step 1000, train cost=0.001810, acc=1.000000; test cost=0.009855, acc=0.969400; pass 322.5399327278137s
step 1500, train cost=0.017293, acc=0.970000; test cost=0.009581, acc=0.970900; pass 322.7249677181244s
step 2000, train cost=0.001345, acc=1.000000; test cost=0.006592, acc=0.980400; pass 323.03099966049194s
step 2500, train cost=0.000591, acc=1.000000; test cost=0.005483, acc=0.985100; pass 323.7637815475464s
step 3000, train cost=0.009209, acc=0.970000; test cost=0.004949, acc=0.984800; pass 319.5827646255493s
step 3500, train cost=0.000296, acc=1.000000; test cost=0.004581, acc=0.986700; pass 323.9109010696411s
step 4000, train cost=0.001038, acc=1.000000; test cost=0.004305, acc=0.986900; pass 345.9888160228729s
step 4500, train cost=0.002839, acc=0.980000; test cost=0.004406, acc=0.988400; pass 352.09626865386963s
step 5000, train cost=0.001505, acc=0.990000; test cost=0.004181, acc=0.986900; pass 343.2950654029846s
```



- ·LSTM可视化
 - 任找一张图片(123-126行)



• 可视化





搭建LSTM基本操作

- 基本单元
- tf.contrib.rnn.BasicRnnCell (num_units,activation)
- tf.contrib.rnn.BasicLSTMCell (num_units, forget_bias,activation,state_is_tuple=True)
- tf.contrib.rnn.GRUCell(num_units,activation)
- forget_bias:偏置; activation:激活函数。
- Dropout
- tf.contrib.rnn.DropoutWrapper (cell, keep_prob)
- 多层神经网络
- rnn_cell = tf.contrib.rnn.MultiRNNCell(cells, state_is_tuple=True)
- 运行
- outpusts,state = tf.nn.dynamic_rnn(cell=rnn_cell, inputs=embedding_input)
- 全连接层
- dense=tf.layers.dense(inputs, units=1024, activation=tf.nn.relu) #inputs二维张量
- tf.contrib.layers.dropout(dense, keep_prob) #全连接层dropout



搭建LSTM基本操作

- 基本单元
- tf.nn.rnn_cell.BasicRnnCell (num_units,activation)
- tf.nn.rnn_cell.GRUCell (num_units,activation)
- tf.nn.rnn_cell.BasicLSTMCell (num_units, forget_bias,activation,state_is_tuple=True)
- forget_bias:偏置; activation:激活函数。
- Dropout
- tf.nn.rnn_cell.DropoutWrapper(cell, keep_prob)
- 多层神经网络
- tf.nn.rnn_cell.MultiRNNCell(cells=cells)
- 一些函数
- tf.nn.relu() tf.nn.softmax tf.not_equal tf.arg_max tf.reduce_mean