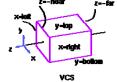


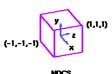
Derivation of the Orthographic Projection Matrix

Another coordinate system transformation

 Scale 2x2x2 cube to the rectangular cuboid and flip z then translate appropriately

left: x = l right: x = rbottom: y = b top: y = tnear: z = -n far: z = -f





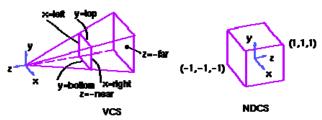
$$\mathbf{M}_O = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2}{\ell-b} & 0 & 0 \\ 0 & 0 & -\frac{2}{f-n} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -\frac{r+l}{2} \\ 0 & 1 & 0 & -\frac{\ell+b}{2} \\ 0 & 0 & 1 & +\frac{f+n}{2} \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{\ell-b} & 0 & -\frac{\ell+b}{\ell-b} \\ 0 & 0 & \frac{2}{n-f} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Translation

Scaling

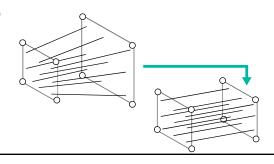
(note negation to flip z axis)

Derivation of the Perspective Transformation Matrix



Maps any line through the origin (eye) to a line parallel to the z axis

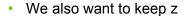
- Without moving the point on the line at z = -n
- Leaves points on the
 z = -f plane, while
 "squishing" them in x and y



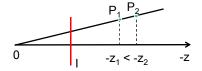
Derivation of the Perspective Transformation Matrix

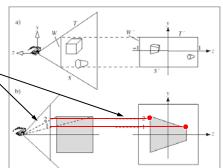
This transformation warps the view volume and the objects in it

 Eye becomes a point at infinity, and the projection rays become parallel lines (i.e., orthographic projection)



- Pseudodepth





The Perspective Transformation Matrix

$$\mathbf{M}_{P} \begin{bmatrix} P_{x} \\ P_{y} \\ P_{z} \\ 1 \end{bmatrix} = \begin{bmatrix} nP_{x} \\ nP_{y} \\ P_{z}(n+f) + nf \\ -P_{z} \end{bmatrix} \quad \begin{array}{c} \text{homogenize} \\ \text{homogenize} \\ \vdots \\ \text{(h=-P_{z})} \end{array} \quad \begin{bmatrix} -\frac{P_{x}n}{P_{z}} \\ -\frac{P_{y}n}{P_{z}} \\ -n - f - \frac{nf}{P_{z}} \end{bmatrix} = \begin{bmatrix} P'_{x} \\ P'_{y} \\ P'_{z} \\ 1 \end{bmatrix}$$

homogenize
$$\begin{array}{ccc}
 & -\frac{P_z}{P_z} \\
 & -\frac{P_y n}{P_z} \\
 & +(h=-P_z)
\end{array} = \begin{bmatrix}
 & P_x \\
 & -\frac{P_y n}{P_z} \\
 & -n-f-\frac{nf}{P_z}
\end{bmatrix} = \begin{bmatrix}
 & P_x \\
 & P_y \\
 & P_z \\
 & -n-f-\frac{nf}{P_z}
\end{bmatrix}$$

Therefore:

$$\mathbf{M}_{P} = \begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n+f & nf \\ 0 & 0 & -1 & 0 \end{bmatrix}$$
 Note: $P'_{z} = \begin{cases} -n, & \text{when } P_{z} = -n \\ -f, & \text{when } P_{z} = -f \end{cases}$

Note:
$$P_z' = \begin{cases} -n, & \text{when } P_z = -n \\ -f, & \text{when } P_z = -f \end{cases}$$

The Projection Matrix

As defined by OpenGL

$$\begin{split} \mathbf{M_{proj}} &= \mathbf{M_OM_P} \\ &= \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{n-f} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n+f & nf \\ 0 & 0 & -1 & 0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{bmatrix} \end{split}$$

Nonlinearity of Perspective Transformation

Tracks:

$$z = -inf$$
, $+inf$

Left track: x = -1, y = -1

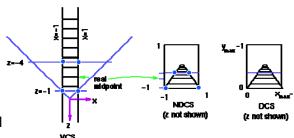
Right track: x = 1, y = -1

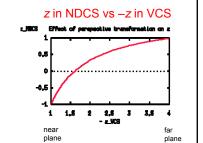
View volume:

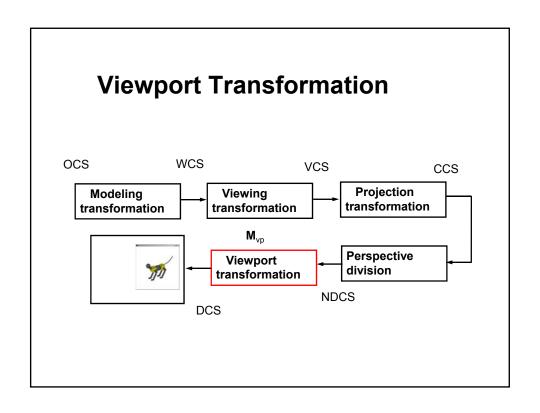
Left =
$$-1$$
, Right = 1

Bottom = -1, Top = 1

Near = 1, Far = 4



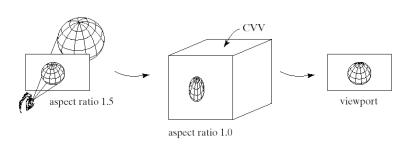


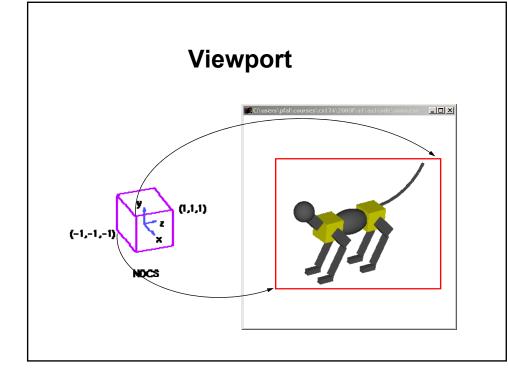


Why Viewports?

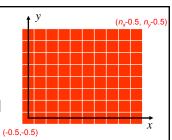
Undo the distortion of the projection transformation

Map to pixel coordinates on screen





Viewport Matrix

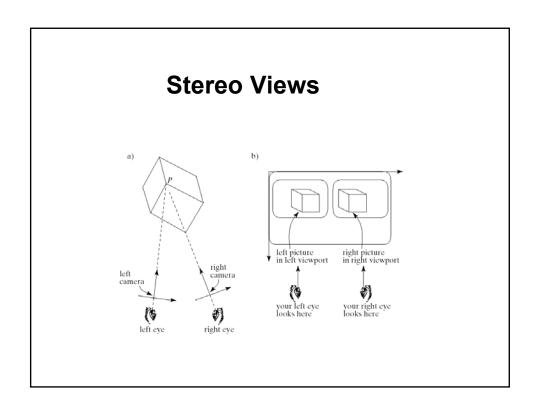


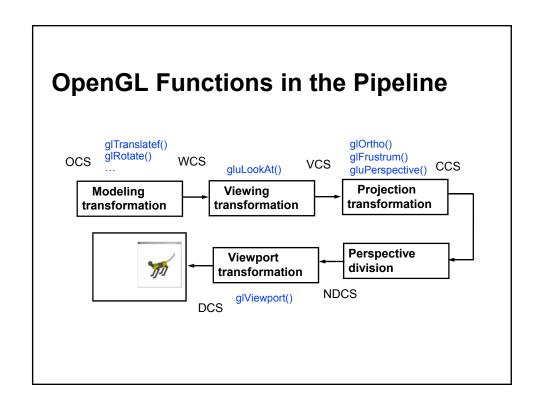
- Canonical image plane: [-1.0, -1.0] x [1.0, 1.0]
- Leave z coordinates unchanged

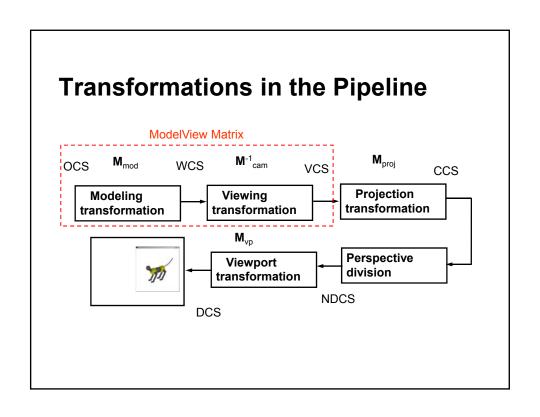
• Transform x,y coordinates to a rectangular viewport of size n_x x n_y pixels assume square pixels of size 1.0x1.0, from (0,0) at lower left; thus, viewport is [-0.5, n_x -0.5] x [-0.5, n_y -0.5]

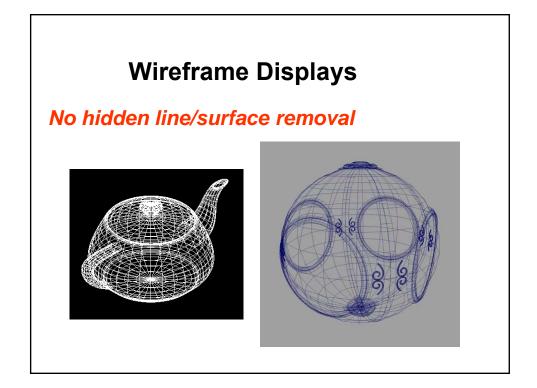
$$\mathbf{M}_{\mathit{VP}} = \begin{bmatrix} 1 & 0 & 0 & \frac{n_{\mathrm{sc}}-1}{2} \\ 0 & 1 & 0 & \frac{n_{\mathrm{y}}-1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{n_{\mathrm{sc}}}{2} & 0 & 0 & 0 \\ 0 & \frac{n_{\mathrm{y}}}{2} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{n_{\mathrm{sc}}}{2} & 0 & 0 & \frac{n_{\mathrm{yc}}-1}{2} \\ 0 & \frac{n_{\mathrm{y}}}{2} & 0 & \frac{n_{\mathrm{yc}}-1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$
Translation
Scaling

What would change if *y* were increasing downward?









A Wireframe Rendering Algorithm

Compute \mathbf{M}_{mod}

Compute M⁻¹cam

Compute $\mathbf{M}_{\text{modelview}} = \mathbf{M}^{-1}_{\text{cam}} \mathbf{M}_{\text{mod}}$

Compute M_O

Compute \mathbf{M}_{P} // disregard \mathbf{M}_{P} here and below for orthographic-only case

Compute $\mathbf{M}_{proj} = \mathbf{M}_{O} \mathbf{M}_{P}$

Compute M_{vp}

Compute $\mathbf{M} = \mathbf{M}_{\text{vp}} \mathbf{M}_{\text{proj}} \mathbf{M}_{\text{modelview}}$

for each line segment i between points Pi and Qi do

 $P = MP_i$; $Q = MQ_i$

 $drawline(P_x/w_P,\,P_y/w_P,\quad Q_x/w_Q,\,Q_y/w_Q) \qquad \textit{//}\ w_P,\,w_Q \ are \ 4^{th} \ coords \ of \ P,\,Q$

end for

More Complex Wireframe Displays

No hidden line/surface removal

