# Utility Functions for Competing Risk

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## Generation Model

Assume we will observe  $(T, \delta)$ , where T is the occurance time,  $\delta$  is the event type,  $\delta = 1, \dots J$  and

$$T = min(T_1, \ldots, T_J).$$

We describe  $T_{\delta}$  using pdf  $\pi(T_{\delta} = t)$ , then its cdf  $P(T_{\delta} < t)$ , survival function  $P(T_{\delta} > t)$  and hazard function  $h(T_{\delta} = t) = \frac{\pi(T_{\delta} = t)}{P(T_{\delta} > t)}$  are defined. We assume the underlining processes  $T_{\delta}$  are independent.

The probability of not experiencing any event before s is

$$P(T > s) = \prod_{k=1}^{J} P(T_k > s).$$

The density of jth event happens at time t is

$$\pi(T=t, \delta=j) = \pi(T_j=t) \prod_{k \neq j} P(T_k > t).$$

In prediction points of view, the density of jth event happens at time t given nothing happening before time s is more interesting, which is

$$\pi(T = t, \delta = j | T > s) = \frac{\pi(T_j = t) \prod_{k \neq j} P(T_k > t)}{P(T > s)}.$$

The density of observing an event at t is

$$\pi(T=t) = \sum_{j=1}^{J} \pi(T_j=t) \prod_{k \neq j} P(T_k > t).$$

The conditional density of observing an event at t given nothing happening before time s is

$$\pi(T = t|T > s) = \frac{\sum_{j=1}^{J} \pi(T_j = t) \prod_{k \neq j} P(T_k > t)}{P(T > s)}$$
(1)

We would also happy to know

$$P(\delta = j) = \int_0^\infty \pi(T_j = t) \prod_{k \neq j} P(T_k > t) dt.$$

This will correspond to the relative frequency of each events.

The conditional version is

$$P(\delta = j|T > s) = \frac{\int_s^\infty \pi(T_j = t) \prod_{k \neq j} P(T_k > t) dt}{P(T > s)}.$$
 (2)

People are particularly interest in the probability of experiencing jth event within a time interval (s,s+t] given the whole information accumulated till the landmark time s. The probability is

$$P(T < s + t, \delta = j | T > s) = \frac{\int_s^{s+t} \pi(T = x, \delta = j) dx}{P(T > s)}.$$
 (3)

To summerise, the conditional version is more general since we simply set s = 0 to get the unconditional version. The above probability can be checked using data.

## Fitted Model

Now we have our fitted model,

$$\pi(T_i|\mathbf{D}),$$

where D represents observed data. Thus all the above quantity can be derived.

We want to check how good is the model.

# **Prediction Tasks**

There are some potentially interesting questions related to prediction:

1. When will the next event (whatever event) happen given no event has happened yet?

With probability .95, we can observe a event happen before t, where P(T < s + t | T > s) = 0.95. (1)

2. What's the next event happen given no event has happened yet?

The most likely happened event is  $\delta = j$  which maximize  $P(\delta = j | T > s)$ . (2)

3. Will event j happen within t unit of time given no event has happened yet?

The probability that j will happen within t unit of time is  $P(T < s + t, \delta = j | T > s)$ . (3)

4. When will event j happen given no event has happened yet?

With probability  $P(\delta \neq j | T > s) = 1 - P(\delta = j | T > s)$ , j will not happen. (2)

With probability  $.95 * P(\delta = j | T > s)$ , we can observe j happens before t, where  $P(T < s + t, \delta = j | T > s) = .95 * P(\delta = j | T > s)$ . (3)

## Scores

It seems question 2 - 4 are more interesting. We may focus on compute scores to check (2) and (3).

#### **Brier Score**

We have observed  $(T_1, \delta_1), \ldots (T_n, \delta_n)$ .

We compute

$$S_B(s) = \frac{1}{n(s)} \sum_{i=1}^n \sum_{j=1}^J (P(\delta = \delta_i | T > s, \mathbf{D}) - \mathbf{1}_{\delta_i = j})^2$$

to check (2). This is Brier score.

We compute

$$S_B(s,t) = \frac{1}{n(s)} \sum_{i=1}^{n} \sum_{j=1}^{J} (P(T_i \le s + t, \delta = \delta_i | T > s, \mathbf{D}) - \mathbf{1}_{T_i \le s + t, \delta_i = j})^2$$

to check (3). This is anther Brier score. (Blanche et al. (2015))

### Logarithmic Score

We compute

$$S_L(s) = \frac{1}{n(s)} \sum_{i=1}^{n} \mathbf{1}_{T_i > s} \log \pi(T = T_i, \delta = \delta_i | T > s, \mathbf{D})$$

to check (3). This is logarithmic scores or expected cross-entropy, which can check (3) indirectly. (Commenges, Liquet, and Proust-Lima (2012))

# Receiver Operating Characteristic Curve and Area Under the Curve

We predict an individual will encounter j within a time interval (s, s+t] when  $P(T < s+t, \delta = j | T > s, \mathbf{D}) > c$ ,  $\tilde{P} > c$  in short.  $\tilde{P}$  is different for each i because of the covariates.

We have the true positive counts,

$$TP_{s,t}(c) = \sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i = j} \mathbf{1}_{\tilde{P} > c},$$

false positive counts,

$$FP_{s,t}(c) = \sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i \ne j \cup T_i > s+t} \mathbf{1}_{\tilde{P} > c},$$

true negative counts,

$$TN_{s,t}(c) = \sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i \ne j \cup T_i > s+t} \mathbf{1}_{\tilde{P} \le c},$$

and false negative counts

$$FN_{s,t}(c) = \sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i = j} \mathbf{1}_{\tilde{P} \le c}.$$

Then the true positive rate, or sensitivity, is

$$TPR_{s,t}(c) = \frac{TP_{s,t}(c)}{TP_{s,t}(c) + FN_{s,t}(c)} = \frac{\sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i = j} \mathbf{1}_{\tilde{P} > c}}{\sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i = j}},$$

and the false positive rate, or specificity, is

$$FPR_{s,t}(c) = \frac{FP_{s,t}(c)}{FP_{s,t}(c) + TN_{s,t}(c)} = \frac{\sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i \ne j \cup T_i > s+t} \mathbf{1}_{\tilde{P} > c}}{\sum_{i=1}^{n} \mathbf{1}_{s < T_i \le s+t, \delta_i \ne j \cup T_i > s+t}}$$

Then the receiver operating characteristic curve (ROC) is defined by

$$ROC_{s,t}(p) = TPR_{s,t}(FPR_{s,t}^{-1}(p)),$$

and the area under the receiver operating characteristic curve (AUC) is

$$S_{AUC}(s,t) = \int_0^1 ROC_{s,t}(p)dp.$$

Using Bamber's Equivalence theorem, we can compute Wilcoxon statistic, equivalent to AUC,

$$S_{AUC}(s,t) = \frac{1}{K_1 K_2} \sum_{i_1=1}^{K_1} \sum_{i_2=1}^{K_2} \mathbf{1}_{\tilde{P}_{i_1} > \tilde{P}_{i_2}},$$

where  $i_1$  are those  $s < T_{i_1} < s + t, \delta_{i_1} = j$  and  $i_2$  are the compliments.

Blanche et al. (2015) considers decision about if subject  $i_1$  has higher risk than  $i_2$ . That is

$$S_{AUCb}(s,t) = \frac{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{\tilde{P}_{i_1} > \tilde{P}_{i_2}} \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1}=j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2}=j})}{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1}=j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2}=j})}.$$

## Cross Validation

We use cross validation to estimate those scores because we don't have future data. Leave-group-out cross-validation (LGOCV) will be involved when we have longitudinal data jointly modeled with our survival data depending on the definition of current time.

$$S_B(s,t) \approx \frac{1}{n(s)} \sum_{i=1}^n \sum_{j=1}^J (P(T_i \le s+t, \delta = \delta_i | T > s, \mathbf{D}_{-I_i}) - \mathbf{1}_{T_i \le s+t, \delta_i = j})^2$$

$$S_L(s) \approx \frac{1}{n(s)} \sum_{i=1}^n \mathbf{1}_{T_i > s} \log \pi (T = T_i, \delta = \delta_i | T > s, \mathbf{D}_{-I_i})$$

$$S_{AUC}(s,t) = \frac{1}{K_1 K_2} \sum_{i_1=1}^{K_1} \sum_{i_2=1}^{K_2} \mathbf{1}_{\tilde{P}_{i_1} | \mathbf{D}_{-i_1} > \tilde{P}_{i_2} | \mathbf{D}_{-i_2}}$$

$$S_{AUCb}(s,t) = \frac{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{\tilde{P}_{i_1} | \mathbf{D}_{-i_1} > \tilde{P}_{i_2} | \mathbf{D}_{-i_2}} \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1} = j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2} = j})}{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1} = j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2} = j})}.$$

# References

Blanche, Paul, Cécile Proust-Lima, Lucie Loubère, Claudine Berr, Jean-François Dartigues, and Hélène Jacqmin-Gadda. 2015. "Quantifying and Comparing Dynamic Predictive Accuracy of Joint Models for Longitudinal Marker and Time-to-Event in Presence of Censoring and Competing Risks." *Biometrics* 71 (1): 102–13.

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