

# Utility Functions for Competing Risk

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## Model

We observe  $\mathbf{D} = (t_i, \delta_i)$ , where  $t_i$  is the occurrence time of a event,  $\delta_i$  is the event type of individual  $i$ , where  $\delta_i = 1, \dots, J$  and  $i = 1, \dots, n$ . If only one event can happen, we can use a competing risk model to model this data.

We define  $t_i$  is a realization of the random variable  $T_i$  and  $\delta_i$  is a realization of the random variable  $Z_i$ . For clarity, in this section we drop the notation  $i$ . We define  $T = \min(T|Z = 1, \dots, T|Z = J)$  and  $Z = \arg \min_{\delta} (T|Z = \delta)$ , and  $T|Z = j$  being the random variable describing

The probability of not experiencing any event before  $s$  is

$$P(T > s) = \prod_{k=1}^J P(T_k > s).$$

The density of  $j$ th event happens at time  $t$  is

$$\pi(T = t, \delta = j) = \pi(T_j = t) \prod_{k \neq j} P(T_k > t).$$

In prediction points of view, the density of  $j$ th event happens at time  $t$  given nothing happening before time  $s$  is more interesting, which is

$$\pi(T = t, \delta = j | T > s) = \frac{\pi(T_j = t) \prod_{k \neq j} P(T_k > t)}{P(T > s)}.$$

The density of observing an event at  $t$  is

$$\pi(T = t) = \sum_{j=1}^J \pi(T_j = t) \prod_{k \neq j} P(T_k > t).$$

The conditional density of observing an event at  $t$  given nothing happening before time  $s$  is

$$\pi(T = t | T > s) = \frac{\sum_{j=1}^J \pi(T_j = t) \prod_{k \neq j} P(T_k > t)}{P(T > s)} \quad (1)$$

We would also happy to know

$$P(\delta = j) = \int_0^{\infty} \pi(T_j = t) \prod_{k \neq j} P(T_k > t) dt.$$

This will correspond to the relative frequency of each events.

The conditional version is

$$P(\delta = j|T > s) = \frac{\int_s^\infty \pi(T_j = t) \prod_{k \neq j} P(T_k > t) dt}{P(T > s)}. \quad (2)$$

People are particularly interest in the probability of experiencing  $j$ th event within a time interval  $(s, s+t]$  given the whole information accumulated till the landmark time  $s$ . The probability is

$$P(T < s + t, \delta = j|T > s) = \frac{\int_s^{s+t} \pi(T = x, \delta = j) dx}{P(T > s)}. \quad (3)$$

To summerise, the conditional version is more general since we simply set  $s = 0$  to get the unconditional version. The above probability can be checked using data.

## Prediction Tasks

There are some potentially interesting questions related to prediction:

1. When will the next event (whatever event) happen given no event has happened yet?

With probability .95, we can observe a event happen before  $t$ , where  $P(T < s + t|T > s) = 0.95$ . (1)

2. What's the next event happen given no event has happened yet?

The most likely happened event is  $\delta = j$  which maximize  $P(\delta = j|T > s)$ . (2)

3. Will event  $j$  happen within  $t$  unit of time given no event has happened yet?

The probability that  $j$  will happen within  $t$  unit of time is  $P(T < s + t, \delta = j|T > s)$ . (3)

4. When will event  $j$  happen given no event has happened yet?

With probability  $P(\delta \neq j|T > s) = 1 - P(\delta = j|T > s)$ ,  $j$  will not happen. (2)

With probability  $.95 * P(\delta = j|T > s)$ , we can observe  $j$  happens before  $t$ , where  $P(T < s + t, \delta = j|T > s) = .95 * P(\delta = j|T > s)$ . (3)

## Scores

It seems question 2 - 4 are more interesting. We may focus on compute scores to check (2) and (3).

### Brier Score

We have observed  $(T_1, \delta_1), \dots, (T_n, \delta_n)$ .

We compute

$$S_B(s) = \frac{1}{n(s)} \sum_{i=1}^n \sum_{j=1}^J (P(\delta = j|T > s, \mathbf{D}) - \mathbf{1}_{\delta_i=j})^2$$

to check (2). This is Brier score.

We compute

$$S_B(s, t) = \frac{1}{n(s)} \sum_{i=1}^n \sum_{j=1}^J (P(T \leq s + t, \delta = j|T > s, \mathbf{D}) - \mathbf{1}_{T_i \leq s+t, \delta_i=j})^2$$

to check (3). This is Brier score for conditional prediction. (Blanche et al. (2015))

## Logarithmic Score

We compute

$$S_L(s) = \frac{1}{n(s)} \sum_{i=1}^n \mathbf{1}_{T_i > s} \log \pi(T = T_i, \delta = \delta_i | T > s, \mathbf{D})$$

to check (3). This is logarithmic scores or expected cross-entropy, which can check (3) indirectly. (Commenges, Liquet, and Proust-Lima (2012))

## Receiver Operating Characteristic Curve and Area Under the Curve

We predict an individual will encounter  $j$  within a time interval  $(s, s+t]$  when  $P(T < s+t, \delta = j | T > s, \mathbf{D}) > c$ ,  $\tilde{P} > c$  in short.  $\tilde{P}$  is different for each  $i$  because of the covariates.

We have the true positive counts,

$$TP_{s,t,j}(c) = \sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i = j} \mathbf{1}_{\tilde{P} > c},$$

false positive counts,

$$FP_{s,t,j}(c) = \sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i \neq j \cup T_i > s+t} \mathbf{1}_{\tilde{P} > c},$$

true negative counts,

$$TN_{s,t,j}(c) = \sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i \neq j \cup T_i > s+t} \mathbf{1}_{\tilde{P} \leq c},$$

and false negative counts

$$FN_{s,t,j}(c) = \sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i = j} \mathbf{1}_{\tilde{P} \leq c}.$$

Then the true positive rate, or sensitivity, is

$$TPR_{s,t,j}(c) = \frac{TP_{s,t}(c)}{TP_{s,t}(c) + FN_{s,t}(c)} = \frac{\sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i = j} \mathbf{1}_{\tilde{P} > c}}{\sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i = j}},$$

and the false positive rate, or specificity, is

$$FPR_{s,t,j}(c) = \frac{FP_{s,t}(c)}{FP_{s,t}(c) + TN_{s,t}(c)} = \frac{\sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i \neq j \cup T_i > s+t} \mathbf{1}_{\tilde{P} > c}}{\sum_{i=1}^n \mathbf{1}_{s < T_i \leq s+t, \delta_i \neq j \cup T_i > s+t}}.$$

Then the receiver operating characteristic curve (ROC) is defined by

$$ROC_{s,t,j}(p) = TPR_{s,t,j}(FPR_{s,t,j}^{-1}(p)),$$

and the area under the receiver operating characteristic curve (AUC) is

$$S_{AUC}(s, t) = \int_0^1 ROC_{s,t}(p) dp.$$

Using Bamber's Equivalence theorem, we can compute Wilcoxon statistic, equivalent to AUC,

$$S_{AUC}(s, t, j) = \frac{1}{K_1 K_2} \sum_{i_1=1}^{K_1} \sum_{i_2=1}^{K_2} \mathbf{1}_{\tilde{P}_{i_1} > \tilde{P}_{i_2}},$$

where  $i_1$  are those  $s < T_{i_1} < s+t, \delta_{i_1} = j$  and  $i_2$  are the compliments.

Blanche et al. (2015) considers decision about if subject  $i_1$  has higher risk than  $i_2$ . That is

$$S_{AUCb}(s, t, j) = \frac{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{\tilde{P}_{i_1} > \tilde{P}_{i_2}} \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1} = j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2} = j})}{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1} = j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2} = j})}.$$

## Cross Validation

We use cross validation to estimate those scores because we don't have future data. Leave-group-out cross-validation (LGOCV) will be involved when we have longitudinal data jointly modeled with our survival data depending on the definition of current time.

$$S_B(s, t) \approx \frac{1}{n(s)} \sum_{i=1}^n \sum_{j=1}^J (P(T \leq s + t, \delta = j | T > s, \mathbf{D}_{-I_i}) - \mathbf{1}_{T_i \leq s+t, \delta_i=j})^2$$

$$S_L(s) \approx \frac{1}{n(s)} \sum_{i=1}^n \mathbf{1}_{T_i > s} \log \pi(T = T_i, \delta = \delta_i | T > s, \mathbf{D}_{-I_i})$$

$$S_{AUC}(s, t, j) \approx \frac{1}{K_1 K_2} \sum_{i_1=1}^{K_1} \sum_{i_2=1}^{K_2} \mathbf{1}_{\tilde{P}_{i_1} | \mathbf{D}_{-i_1} > \tilde{P}_{i_2} | \mathbf{D}_{-i_2}}$$

$$S_{AUCb}(s, t, j) \approx \frac{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{\tilde{P}_{i_1} | \mathbf{D}_{-i_1} > \tilde{P}_{i_2} | \mathbf{D}_{-i_2}} \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1}=j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2}=j})}{\sum_{i_1=1}^n \sum_{i_2=1}^n \mathbf{1}_{s < T_{i_1} < s+t, \delta_{i_1}=j} (1 - \mathbf{1}_{s < T_{i_2} < s+t, \delta_{i_2}=j})}.$$

## References

- Blanche, Paul, Cécile Proust-Lima, Lucie Loubère, Claudine Berr, Jean-François Dartigues, and Hélène Jacqmin-Gadda. 2015. “Quantifying and Comparing Dynamic Predictive Accuracy of Joint Models for Longitudinal Marker and Time-to-Event in Presence of Censoring and Competing Risks.” *Biometrics* 71 (1): 102–13.
- Commenges, Daniel, Benoit Liqueur, and Cécile Proust-Lima. 2012. “Choice of Prognostic Estimators in Joint Models by Estimating Differences of Expected Conditional Kullback–Leibler Risks.” *Biometrics* 68 (2): 380–87.