

# Defintions and notations

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## 0.1 Limit

Let  $f(x)$  be a function defined on an interval that contains  $x = a$ , except possibly at  $x = a$ , then we say that

$$\lim_{x \rightarrow a} f(x) = L$$

if for every  $\epsilon > 0$  there is some number  $\delta > 0$  such that

$$|f(x) - L| < \epsilon \text{ whenever } 0 < |x - a| < \delta$$

## 0.2 Gradient

Given  $f(x_1, x_n)$  on  $\mathbf{R}^n$

$$\nabla f(a_1, \dots, a_n) = (\frac{\partial}{\partial x_1}(a_1, \dots, a_n), \dots, \frac{\partial}{\partial x_n}(a_1, \dots, a_n))$$

## 0.3 Directional derivative

**Homework notation**

$$f'(x; u) = \lim_{h \rightarrow 0} \frac{f(x + hu) - f(x)}{h}$$

**Wikipedias notation** note that it's  $f$  on a vector  $\vec{x}$  having its derivative calculated on direction  $\vec{v}$ , essentially gradient on direction  $\vec{v}$ .

$$\nabla_v f(\vec{x}) = \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\vec{v}) - f(\vec{x})}{h}$$

## 0.4 Vector norm

A norm is a function that assigns a stricly positive length or size to each vector in a vector space (except the zero vector which is assigned a length of 0).

**Absolute value norm** is a norm on the one-dimensional vector spaces formed by real or complex numbers.

$$\|x\| = |x|$$

**Euclidean norm** on a Euclidean space  $\mathbf{R}^n$  is such

$$\|\vec{x}\|_2 = \sqrt{x_1^2 + \dots + x_n^2}$$

**Manhattan or taxicab norm**

$$\|\vec{x}\|_1 = \sum_{i=1}^n |x_i|$$

**$p$ -norm**

$$\|\vec{x}\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{\frac{1}{p}}$$

Note that when  $p = 1$ , we get Manhattan norm, and when  $p = 2$ , we get Euclidean norm.

When  $p = \infty$

$$\|\vec{x}\|_\infty = \max_i |x_i|$$

## 0.5 argmax

Points of the domain of some function at which the function values are maximized.

Given an arbitrary set  $X$ , a totally ordered set  $Y$  and a function  $f : X \rightarrow Y$ , the arg max over some subset  $S$  of  $X$  is defined by

$$\arg \max_{x \in S \subseteq X} f(x) = \{x \mid x \in S \wedge \forall y \in S : f(y) \leq f(x)\}$$

## 0.6 Random variable

A random variable  $X : \Omega \rightarrow E$  is a measurable function from a set of possible outcomes  $\Omega$  to a measurable space  $E$ . Often times  $E = \mathbb{R}$

The probability that  $X$  takes on a value in a measurable set  $S \subseteq E$  is written as

$$Pr(X \in S) = P(\omega \in \Omega \mid X(\omega) \in S)$$

**Intuition:** mapping outcomes of a random process to numbers, like this definition of  $X$

$$X = \begin{cases} 0, & \text{if heads} \\ 1, & \text{if tails} \end{cases}$$

Instead of a traditional algebraic variable that can be solved for one value, a random variable can have different values (each with a probability) under different conditions.

## 0.7 Law of large numbers

$X_1, X_2, \dots$  is an infinite sequence of independent and identically distributed (iid) random variables with expected value  $E(X_1) = E(X_2) = \dots = \mu$ , and

$$\bar{X}_n = \frac{1}{n}(X_1 + \dots + X_n) *$$

**The weak law** states that for any positive number  $\epsilon$

$$\lim_{n \rightarrow \infty} Pr(|\bar{X}_n - \mu| > \epsilon) = 0$$

**The strong law** states that

$$Pr(\lim_{n \rightarrow \infty} \bar{X}_n = \mu) = 1$$

**Intuition:** law of large numbers is a theorem that describes the average of the results obtained from a large number of trials should be close to the expected value, and will tend to become closer as more trials are performed.

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\*What does the sum of random variables mean? Seems that each  $X_i$  here means 'sampled' values following the distribution defined by the random variable, like, the outcome of an experiment