view_frames Result Recorded at time: 1543336876.005 Broadcaster: /robot_state_publisher_ur10 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 10000.000 Hz Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec WorldPerceptionNeuron Broadcaster: /perception_neuron_tf_broadcaster_node 1543336455006063258 Broadcaster: /camera_base_link Broadcaster: /robot_state_publisher_ur10 Average rate: 933.037 Hz Average rate: 12.000 Hz Average rate: 390000.000 Hz Most recent transform: 1543336876.004 (0.000 sec old) / Most recent transform: 1543336875.913 (0.091 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.647 sec Buffer length: 0.500 sec Buffer length: 0.000 sec shoulder_link Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258\ Broadcaster: /perception_neuron_tf_broadcaster node_1543336455006063258\ Broadcaster: /perception_neuron_tf_broadcaster node_1543336455006063258\ Broadcaster: /robot_state_publisher_ur10 Average rate: 390000.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Average rate: 12.000 Hz Most recent transform: 1543336875.913 (0.091 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.500 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec RightUpLeg LeftUpLeg upper_arm_link Broadcaster: /robot_state_publisher_ur10 Average rate: 390000.000 Hz Average rate: 12.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Most recent transform: 1543336875.913 (0.091 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.500 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec forearm_link Broadcaster: /robot_state_publisher_ur10 Average rate: 390000.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Average rate: 12.000 Hz Most recent transform: 1543336875.913 (0.091 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.500 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec wrist_1_link RightFoot LeftFoot Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /robot_state_publisher_ur10 Average rate: 12.000 Hz Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 1543336875.913 (0.091 sec old) Buffer length: 0.500 sec Buffer length: 0.000 sec wrist_2_link Broadcaster: /robot_state_publisher_ur10 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 |Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 \ Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 12.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 1543336875.913 (0.091 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.500 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec wrist_3_link Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 | Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /robot_state_publisher_ur10 Average rate: 10000.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec ee_link Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 390000.000 Hz Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec RightForeArm LeftForeArm /Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 390000.000 Hz Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec RightHand /Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 \ Broadcaster_node_1543336455006063258 \ Broadcaster_node_15433 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258\ Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec RightInHandIndex RightInHandRing RightInHandPinky LeftHandThumb1 LeftInHandPinky RightHandThumb1 LeftInHandMiddle Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 | Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec RightHandThumb2 RightHandPinky1 RightHandIndex1 RightHandMiddle1 LeftHandThumb2 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster: /perception_neuron_tf_broadcaster | perception_neuron_tf_broadcaster Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec RightHandIndex2 RightHandMiddle2 RightHandPinky2 RightHandRing2 LeftHandThumb3 LeftHandIndex2 RightHandThumb3 LeftHandMiddle2 LeftHandRing2 LeftHandPinky2 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster_node_1543336455006063258 Broadcaster_node_15433364550060606060 Broadcaster_node_1543336 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster: /perception_neuron_tf_broadcaster_node_1543336455006063258 Broadcaster_node_1543336455006063258 Broadcaster_node_15433364550060606060606060606060606060606 Average rate: 390000.000 Hz Most recent transform: 0.000 (1543336876.005 sec old) Buffer length: 0.000 sec RightHandIndex3 RightHandMiddle3 RightHandPinky3 LeftHandIndex3 LeftHandMiddle3 LeftHandPinky3 RightHandRing3 LeftHandRing3