Haoyuan Zheng

hz463

i	$lpha_i$	a_i	$ heta_i$	d_i
1	$\pi/2$	0.033	$\theta_1 + \pi/2$	0.1
2	0	0.155	$\theta_2 + \pi/2$	0
3	0	0.135	$ heta_3$	0
4	$\pi/2$	0	θ_4 + $\pi/2$	0
5	0	0	$ heta_5$	0

P1a

Discuss

P2a:

Following is the equation calculated by sympy:

Code is in the Jacobian.py

```
Matrix([[0.2175*(sin(\theta 1)*sin(\theta 2)*sin(\theta 3)
                                                                             \sin(\theta 1) \cos(\theta 2) \cos(\theta 3) \cos(\theta 4)
0.2175*(\sin(\theta 1)*\sin(\theta 2)*\cos(\theta 3)
                                                                         \sin(\theta 1) \sin(\theta 3) \cos(\theta 2) \sin(\theta 4)
0.135*\sin(\theta 1)*\sin(\theta 2)*\sin(\theta 3)
                                                                                       0.135*\sin(\theta 1)*\cos(\theta 2)*\cos(\theta 3)
0.155*sin(\theta 1)*cos(\theta 2)
                                                     0.033*\sin(\theta 1),
                                                                                     0.2175*(\sin(\theta 2)*\sin(\theta 3)*\cos(\theta 1)
cos(\theta 1)*cos(\theta 2)*cos(\theta 3))*sin(\theta 4)
                                                                                   0.2175*(-\sin(\theta 2)*\cos(\theta 1)*\cos(\theta 3)
                                                                   +
\sin(\theta 3)*\cos(\theta 1)*\cos(\theta 2))*\cos(\theta 4)
                                                                                       0.135*\sin(\theta 2)*\cos(\theta 1)*\cos(\theta 3)
0.155*sin(\theta 2)*cos(\theta 1)
                                                                                      0.135*\sin(\theta 3)*\cos(\theta 1)*\cos(\theta 2),
0.2175*(\sin(\theta 2)*\sin(\theta 3)*\cos(\theta 1)
                                                                        cos(\theta 1)*cos(\theta 2)*cos(\theta 3))*sin(\theta 4)
0.2175*(\sin(\theta 2)*\cos(\theta 1)*\cos(\theta 3)
                                                                                   \sin(\theta 3)*\cos(\theta 1)*\cos(\theta 2))*\cos(\theta 4)
0.135*\sin(\theta 2)*\cos(\theta 1)*\cos(\theta 3)
                                                                                      0.135*\sin(\theta 3)*\cos(\theta 1)*\cos(\theta 2),
                                                                        cos(\theta 1)*cos(\theta 2)*cos(\theta 3))*sin(\theta 4)
0.2175*(\sin(\theta 2)*\sin(\theta 3)*\cos(\theta 1)
                                                             +
                                                                                 \sin(\theta 3) \cos(\theta 1) \cos(\theta 2) \cos(\theta 4)
0.2175*(\sin(\theta 2)*\cos(\theta 1)*\cos(\theta 3)
[0.2175*(\sin(\theta 2)*\sin(\theta 3)*\cos(\theta 1)]
                                                                        cos(\theta 1)*cos(\theta 2)*cos(\theta 3))*cos(\theta 4)
                                                             +
0.2175*(\sin(\theta 2)*\cos(\theta 1)*\cos(\theta 3)
                                                                                    \sin(\theta 3)*\cos(\theta 1)*\cos(\theta 2))*\sin(\theta 4)
0.135*\sin(\theta 2)*\sin(\theta 3)*\cos(\theta 1)
                                                                         0.135*\cos(\theta 1)*\cos(\theta 2)*\cos(\theta 3)
                                                            +
0.155*\cos(\theta 1)*\cos(\theta 2)
                                                      0.033*\cos(\theta 1),
                                                                                      0.2175*(\sin(\theta 1)*\sin(\theta 2)*\sin(\theta 3)
\sin(\theta 1) \cos(\theta 2) \cos(\theta 3) \sin(\theta 4)
                                                                                    0.2175*(-\sin(\theta 1)*\sin(\theta 2)*\cos(\theta 3)
                                                                   +
\sin(\theta 1) \sin(\theta 3) \cos(\theta 2) \cos(\theta 4)
                                                                                        0.135*\sin(\theta 1)*\sin(\theta 2)*\cos(\theta 3)
0.155*sin(\theta 1)*sin(\theta 2)
                                                                                       0.135*\sin(\theta 1)*\sin(\theta 3)*\cos(\theta 2),
0.2175*(\sin(\theta 1)*\sin(\theta 2)*\sin(\theta 3)
                                                                        \sin(\theta 1) \cos(\theta 2) \cos(\theta 3) \sin(\theta 4)
0.2175*(\sin(\theta 1)*\sin(\theta 2)*\cos(\theta 3)
                                                                                    \sin(\theta 1) \sin(\theta 3) \cos(\theta 2) \cos(\theta 4)
0.135*\sin(\theta 1)*\sin(\theta 2)*\cos(\theta 3)
                                                                                       0.135*\sin(\theta 1)*\sin(\theta 3)*\cos(\theta 2),
0.2175*(\sin(\theta 1)*\sin(\theta 2)*\sin(\theta 3)
                                                                        \sin(\theta 1) \cos(\theta 2) \cos(\theta 3) \sin(\theta 4)
                                                                                                                                       +
                                                                     \sin(\theta 1) \sin(\theta 3) \cos(\theta 2) \cos(\theta 4)
0.2175*(\sin(\theta 1)*\sin(\theta 2)*\cos(\theta 3)
                                                                                                                                     [0,
0.2175*(\sin(\theta 2)*\sin(\theta 3) + \cos(\theta 2)*\cos(\theta 3))*\cos(\theta 4) + 0.2175*(-\sin(\theta 2)*\cos(\theta 3))
\sin(\theta 3) \cos(\theta 2) \sin(\theta 4) - 0.135 \sin(\theta 2) \sin(\theta 3) + 0.135 \cos(\theta 2) \cos(\theta 3)
                               0.2175*(-\sin(\theta 2)*\sin(\theta 3))
                                                                                       cos(\theta 2)*cos(\theta 3))*cos(\theta 4)
0.155*\cos(\theta 2),
                                                                              +
0.2175*(\sin(\theta 2)*\cos(\theta 3) - \sin(\theta 3)*\cos(\theta 2))*\sin(\theta 4) - 0.135*\sin(\theta 2)*\sin(\theta 3)
```

 $0.135*\cos(\theta 2)*\cos(\theta 3), \quad 0.2175*(-\sin(\theta 2)*\sin(\theta 3) + \cos(\theta 2)*\cos(\theta 3))*\cos(\theta 4) \\ 0.2175*(\sin(\theta 2)*\cos(\theta 3) + \sin(\theta 3)*\cos(\theta 2))*\sin(\theta 4)], [0, 0, 0, 0]])$