Assignment 3

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Part 1: Grab Cut

1. Input image

In step 1, I read images by batch. Next, I show the program as an example.

```
clear;
close all;
clc;
img path = 'E:\GrabCut\grabcut 1\gc\PASCAL\' ;
result path = 'E:\GrabCut\grabcut 1\gc\PASCAL SALENCY 0.3\';
picstr = dir(strcat(img path, '*.jpg'));
m = length(picstr);
th=0.3;
ifm > 0
      for i = 1:m
          img name = picstr(i).name;
          if img name(1) == '.'
          continue;
          filename1=strcat(img path,img name);
          img = imread(filename1);
          [l,w]=size(img);
          param = default signature param(w);
          salency image = signatureSal( img,param);
          salency = imresize(salency image , [ size(img,1)
          size(img,2) ]);
          salencyoutput=im2bw(salency,th);
          imwrite(salencyoutput, strcat(result path, img name));
       end
end
```

2. Use image signature

In this process, I adjust threshold to transform saliency map for different binary images. As we all know, the image is saved in x. Then I can call functions of 'signatureSal', the result is the saliency map. The saliency map is obtained by image signature and the matlab code of "signatureSal". The code is as follow:

```
param = default_signature_param;
salency_image = signatureSal( img,param);
salency = imresize(salency_image , [ size(img,1) size(img,2) ] );
salencyoutput=im2bw(salency,th);
imwrite(salencyoutput,strcat(result path,img name));
```

3. Draw the rectangle

I input saliency map image from step 2. The rectangle is used to locate the most probable position of object and initialize mask in grab cut. I use threshold to transform saliency map to binary image and draw a rectangle according to the binary image with different size of rectangle.



4. Implement grab cut

I input image (m \times n \times 3 matrix) from step 1 and the rectangle from step 3. The codes in C is showing:

```
#include <iostream>
#include <cv.hpp>
#include <opencv2/highgui/highgui.hpp>
#include <opencv2/core/core.hpp>
#include<string>
#include<contrib/contrib.hpp>

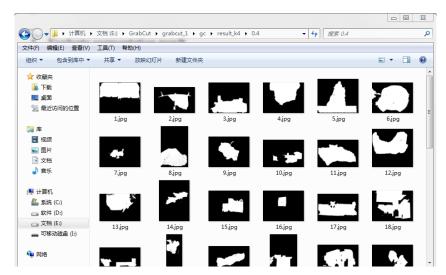
using namespace std;
using namespace cv;

int main()
{
   for(int threshold=2;threshold<9;threshold++)</pre>
```

```
{
   Directory dir1, dir2;
   char threch[1];
   itoa(threshold, threch, 10);
   string threst=threch;
   string path1="E:/class/computer vision/assignment3/PASCAL";
   string path2="E:/class/computer
   vision/assignment3/signmap0."+threst;
   string exten="*.jpg";
   string extenout=".jpg";
   string filenames3;
   bool addPath1 = true;
   string output="E:/output/0."+threst+"/";
   char numch[1];
   vector<string> filenames1 = dir1.GetListFiles(path1, exten,
   addPath1);
   vector<string> filenames2 = dir2.GetListFiles(path2, exten,
   addPath1);
   for(int n=0;n<filenames1.size();n++)</pre>
      itoa(n+1, numch, 10);
      filenames3=output+numch+extenout;
      Mat mOriginImg=imread(filenames1[n],1);
      Mat mSaMap=imread(filenames2[n],0);
      const int nRow=mOriginImg.rows;
      const int nCol=mOriginImg.cols;
      //~~~~~~~//
      int i=0, j=0, c=0;
      int nRowMin=0, nRowMax=0, nColMin=0, nColMax=0;
      for(i=0;i<nRow;i++)</pre>
         for(j=0;j<nCol;j++)</pre>
             if (mSaMap.at < uchar > (i, j) == 255)
                nColMin=j;
                nColMax=j;
                nRowMin=i;
```

```
nRowMax=i;
           c=1;
           break;
   }
   if(c==1)
       break;
for(c=0,j=0;j<nColMin;j++)</pre>
   for(i=nRowMin;i<nRow;i++)</pre>
       if (mSaMap.at<uchar>(i,j) == 255)
           nRowMax=i;
          nColMin=j;
          c=1;
          break;
   if(c==1)
       break;
for(c=0,i=nRow-1;i>nRowMax;i--)
   for(j=nColMin;j<nCol;j++)</pre>
       if(mSaMap.at<uchar>(i,j)==255)
           nRowMax=i;
           if(j>nColMax)
              nColMax=j;
           c=1;
           break;
       }
   if(c==1)
       break;
for(c=0,j=nCol-1;j>nColMax;j--)
   for(i=nRowMin;i<nRowMax;i++)</pre>
       if (mSaMap.at < uchar > (i, j) == 255)
```

```
{
          nColMax=j;
          c=1;
          break;
   if(c==1)
      break;
}
Mat mDrawRec=mOriginImg.clone();
Point2f pRecLeftUp,pRecRightDown;
pRecLeftUp=cvPoint(nColMin,nRowMin);
pRecRightDown=cvPoint(nColMax,nRowMax);
rectangle(mDrawRec, pRecLeftUp, pRecRightDown, Scalar(0, 255,
0), 2);
//~~~~~Implement grab cut~~~~~~~//
Rect rect(pRecLeftUp,pRecRightDown);
Mat OutMask(mOriginImg.size(), CV 8UC1);
Mat BgdModel, FgdModel;
int nIteration=3;
Mat mask;
Mat obj;
bool isInitialized=false;
for(i=0; i<nIteration; i++)</pre>
      if(!isInitialized)
      {
             grabCut(mOriginImg, OutMask, rect, BgdModel,
             FgdModel, 1, GC INIT WITH RECT);
             isInitialized=true;
      }
      else
      {
             grabCut(mOriginImg, OutMask, rect, BgdModel,
             FgdModel, 1);
      }
compare(OutMask, GC PR FGD, mask, CMP EQ);
mOriginImg.copyTo(obj, mask);
```



5. Evaluate segmentation result

I input segmentation result and groundtruth from dataset. Adjust threshold to obtain different segmentation results and draw a bar graph to evaluate grab cut.

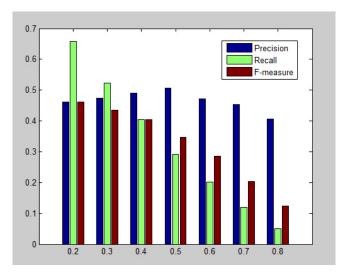


Figure PRF bar graph k=3

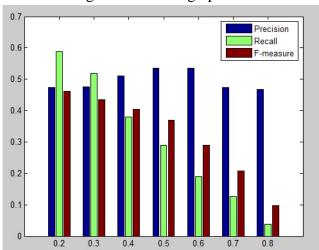


Figure PRF bar graph k=4

Part 2: Meanshift

1. Input all images by batch processing

I input the image by beach, and show the codes:

```
clear all;
clc;
close all;

picstr=dir('E:\meanshift\BSDS500\data\images\train\*.jpg');
[m,n]=size(picstr);
for i=1:m
   if picstr(i).name(1)=='.'
      continue;
   end
```

```
filename=strcat('E:\meanshift\BSDS500\data\images\train\',picstr(i).n
ame);
end
```

where , the purpose of the program is to skip the hidden files. It is asking for help Ruchen Wang.

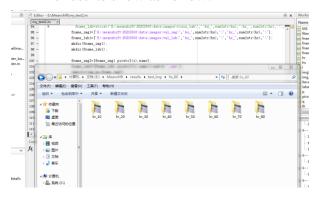
2. Segment via mean shift

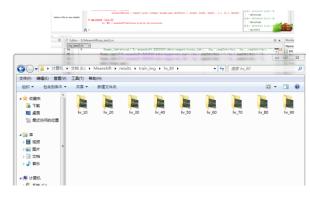
I download the source code from the website and adjust the parameters (hs, hr) from 10 to 80. Every result is saved as different folders named by relative parameter.

```
for hs=10:5:40
   for hr=10:10:90
      for i=1:m
          if picstr(350).name(1) == '.'
          continue;
          end
          filename=strcat('E:\meanshift\BSDS500\data\images\train\',p
          icstr(350).name);
          x=imread(filename);
          th=0.1;
          iteration=5;
          [y, MS] = meanShiftPixCluster(x,hs,hr,th,iteration);
          img ms=uint8(y);
          fname img=strcat('E:\meanshift\BSDS500\data\images\train im
          g','\','hs ',num2str(hs),'\','hr ',num2str(hr),'\');
          fname lab=strcat('E:\meanshift\BSDS500\data\images\train la
          b','\','hs ',num2str(hs),'\','hr ',num2str(hr),'\');
          fname img1=['E:\meanshift\BSDS500\data\images\train img\','
          hs_', num2str(hs),'\','hr_', num2str(hr),'\'];
          fname lab1=['E:\meanshift\BSDS500\data\images\train lab\','
          hs ', num2str(hs),'\','hr ', num2str(hr),'\'];
          mkdir(fname img);
          mkdir(fname lab);
```

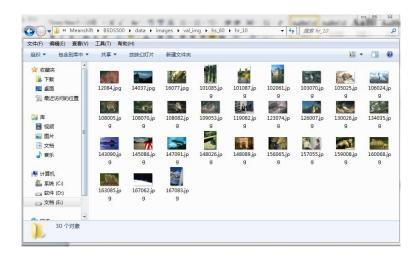
```
fname img1=strcat(fname img,picstr(350).name);
          fname lab1=strcat(fname lab,picstr(350).name(1:end-4),'.mat
          imwrite(img ms,fname img1);
          imgInf = processSuperpixelImage(y);
          label result = double(imgInf.segimage);
          fid lab=fopen(fname lab1,'wt');
          fwrite(fid lab, label result);
          fclose(fid lab);
       end
   end
end
where "[y, MS] = meanShiftPixCluster(x,hs,hr,th,iteration);
       img ms=uint8(y);" is meanshift's main function.
Where "imgInf = processSuperpixelImage(y);
       label result = double(imgInf.segimage);
       fid lab=fopen(fname lab1,'wt');" is making labels.
At first, I writed the code "for i=1:m
                           if picstr(350).name(1) == '.'
                           continue;
                           end
                           for hs=10:5:40
                               for hr=10:10:90"
                                    .....
                               end
                            end
                        end
```

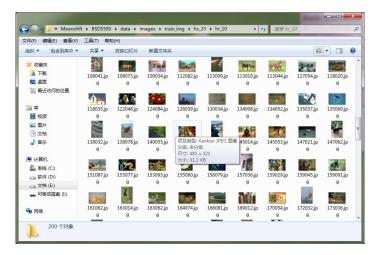
The results show as follow:



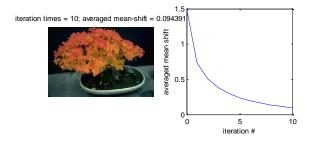


Each folder is saved one map. So modify the program, the results is showing:





The part processing image is showing:



3. Evaluate segmentation result with groundtruth

Input the label matrixes ($m \times n$ matrix) from step 2, the groundtruth matrixes ($m \times n$ matrix) from dataset.

```
clear;
clc;
benchPath = 'E:\meanshift\BSDS500\data\groundTruth\train\';
testPath = 'E:\Meanshift\BSDS500\data\images\train lab\hs 10';
testList = dir(testPath);
numX = 0;
for i = 1:length(testList)
   if testList(i).name(1) == '.'
      continue;
   end
      numX = numX+1;
      x(1,numX) = str2double(testList(i).name);
      averageBoundaryError = 0;
      averageRI = 0;
      averageVOI = 0;
      averageGCE = 0;
       imageCount = 0;
       testImgPath = [testPath '\' testList(i).name];
      testImgList = dir(testImgPath);
       for j = 1:length(testImgList)
          if testImgList(j).name(1) == '.'
             continue;
          end
          benchImgName = [benchPath testImgList(j).name];
          testImgName = [testImgPath '\' testImgList(j).name];
          load(benchImgName);
          load(testImgName);
          imageCount = imageCount + 1;
          imageLabelCell=groundTruth;
          sampleLabels = label result;
           % Comparison script
          totalBoundaryError = 0;
          sumRI = 0;
          sumVOI = 0;
          sumGCE = 0;
          [imageX, imageY] = size(sampleLabels);
          [benchX, benchY] = size(imageLabelCell{1}.Segmentation);
          for benchIndex=1:length(imageLabelCell)
             benchLabels = imageLabelCell{benchIndex}.Segmentation;
```

```
totalBoundaryError = totalBoundaryError +
             compare image boundary error (double (benchLabels),
             double(sampleLabels));
             [curRI, curGCE, curVOI] =
             compare segmentations(sampleLabels, benchLabels);
             sumRI = sumRI + curRI;
             sumVOI = sumVOI + curVOI;
             sumGCE = sumGCE + curGCE;
          end
          % update the averages... note that sumRI /
          length(imageLabelCell) is
          % equivalent to the PRI.
          averageBoundaryError = averageBoundaryError +
          totalBoundaryError / length(imageLabelCell);
          averageRI = averageRI + sumRI / length(imageLabelCell);
          averageVOI = averageVOI + sumVOI / length(imageLabelCell);
          averageGCE = averageGCE + sumGCE / length(imageLabelCell);
      end
      arrayRI(numX,1) = averageRI/imageCount;
      arrayVOI(numX,1) = averageVOI/imageCount;
      arrayGCE(numX,1) = averageGCE/imageCount;
      arrayBE(numX,1) = averageBoundaryError/imageCount;
end
xNum = 0;
for i =1:length(x)
   if x(1,i) \sim =100;
      xNum = xNum+1;
      xFinal(1,xNum) = x(1,i);
      arrayRIFinal(xNum,1) = arrayRI(i,1);
      arrayVOIFinal(xNum,1) = arrayVOI(i,1);
      arrayGCEFinal(xNum,1) = arrayGCE(i,1);
      arrayBEFinal(xNum,1) = arrayBE(i,1);
   else
      xFinal(1, length(x)) = x(1,i);
      arrayRIFinal(length(x),1) = arrayRI(i,1);
      arrayVOIFinal(length(x),1) = arrayVOI(i,1);
      arrayGCEFinal(length(x),1) = arrayGCE(i,1);
      arrayBEFinal(length(x),1) = arrayBE(i,1);
   end
end
subplot(221);plot(xFinal,arrayBEFinal,'r'),title('BDE'),xlabel('hs'),
```

```
ylabel('BDE');
subplot(222);plot(xFinal,arrayRIFinal,'k'),title('PRI'),xlabel('hs'),
ylabel('PRI');
subplot(223);plot(xFinal,arrayVOIFinal,'b'),title('VOI'),xlabel('hs'),
ylabel('VOI');
subplot(224);plot(xFinal,arrayBEFinal,'y'),title('GCE'),xlabel('hs'),
ylabel('GCE');
```

The result is showing: Th=0.1 iterate=5 hr=40

