



Cluster-based Segmentation

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- Clustering Analysis
- Image Segmentation with Clustering

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Cluster-based Segmentation

基于聚类的图像分割

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CVBIOUC

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Clustering is **unsupervised classification**: no predefined classes.

Cluster: a collection of data objects

- Similar to one another within the same cluster
- Dissimilar to the objects in other clusters



Image Segmentation with Clustering

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Idea:

Cluster similar pixel features together.

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How to segment images by clustering?





Image Segmentation with Clustering

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Image \implies Feature space

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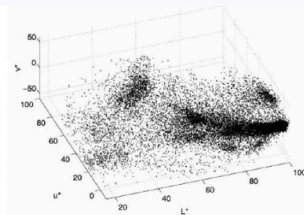


Image Segmentation with Clustering

Cluster-based Segmentation

Image \Rightarrow Feature space

Feature space: $(R, G, B), (R, G, B, X, Y), (L, U, V) \dots$



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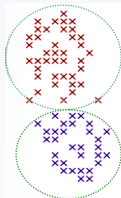
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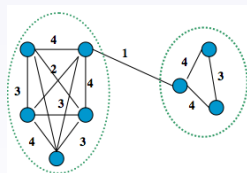
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■ Vector Clustering



Each point has a vector.

■ Graph Clustering



Each vertex is connected to others by edges.

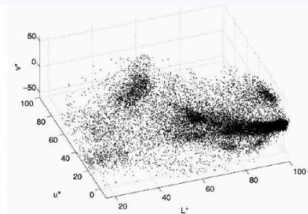


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Techniques:

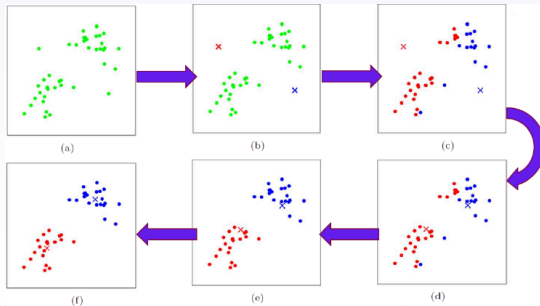
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K-means

Idea:

- 1 Randomly initialize the K cluster centers.
- 2 For each point, find the closest cluster centers. Put the point into the cluster.
- 3 Change the cluster centers.



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Algorithm:

- 1 Choose randomly K-means m_1, \dots, m_k .
- 2 For each vector x_i compute $D(x_i, m_k(ic)), k = 1, \dots, K$ and assign x_i to the cluster C_j with nearest mean.
- 3 Update the means to get $m_1(ic), \dots, m_K(ic)$.

$$m_i^{(t+1)} = \frac{1}{|S_i^{(t)}|} \sum_{x_j \in S_i^{(t)}} x_j$$

- 4 Repeat steps 2 and 3 until $C_k(ic) = C_k(ic + 1)$ for all k.



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Pros:

- Simple and fast
- Converges to a local minimum of the error function

Cons:

- Sensitive to initialization
- Need to pick K



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Algorithm:

- 1 Take one center c_1 , chosen uniformly at random from X .
- 2 Take a new center c_i , choosing $x \in X$ with probability
$$\frac{D(x)^2}{\sum_{x \in X} D(x)^2}$$
- 3 Repeat Step 1, until we have taken k centers altogether.

$D(x)$ denote the shortest distance from a data point to the closest center.



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Mean Shift¹

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An advanced and versatile technique for clustering-based segmentation.

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Idea:

- Find the **clustering center**.



¹D. Comaniciu and P. Meer, “Mean Shift: A Robust Approach toward Feature Space Analysis”, PAMI, 2002.



What and How?

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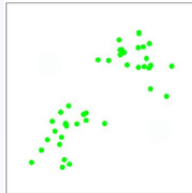
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Center is maximum points of probability density function and gradient direction.



Mean Shift Vector

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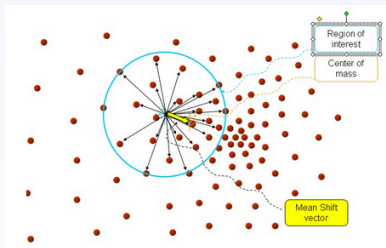
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$$M_h = \frac{1}{K} \sum_{x_i \in S_k} (x_i - x)$$



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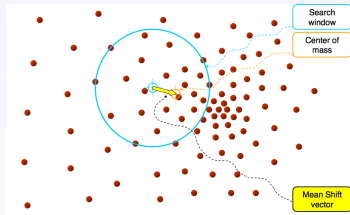
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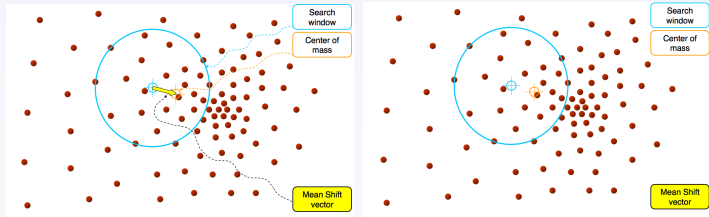
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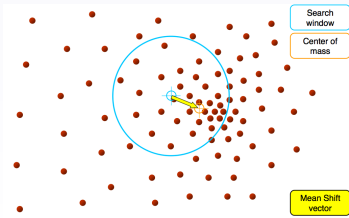
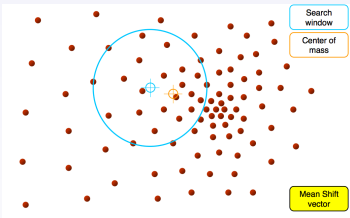
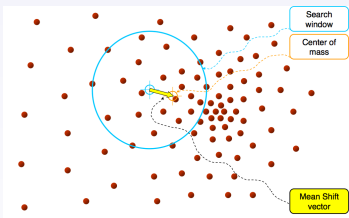
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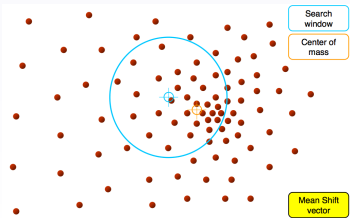
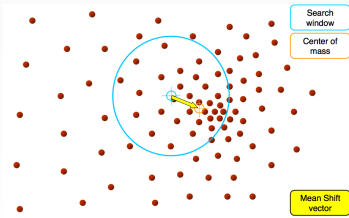
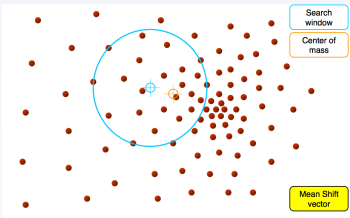
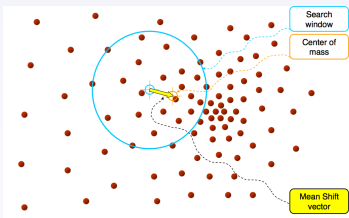
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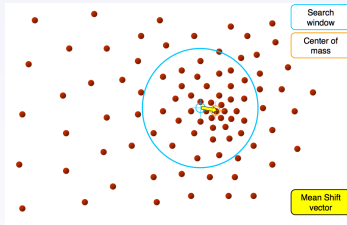
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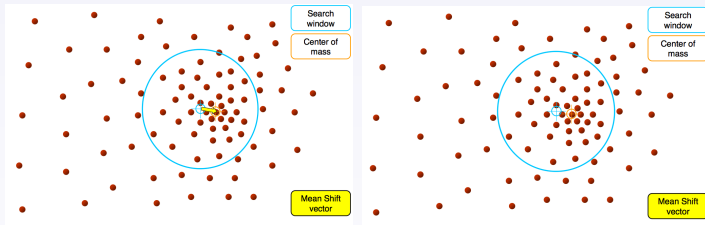
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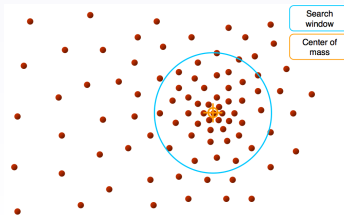
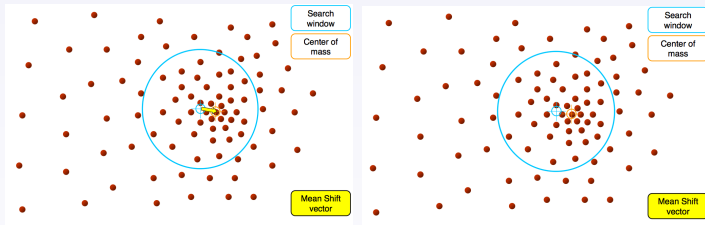
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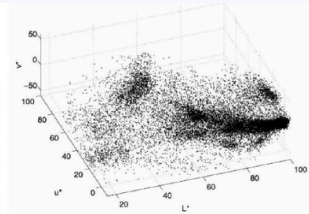
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Density Estimation

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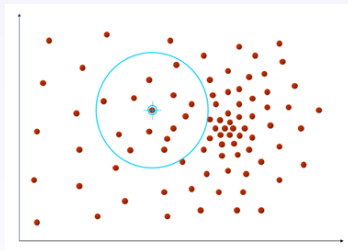
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$$P = \frac{N_k}{N}$$

$$f(x) = \frac{P}{S} = \frac{N_k}{NS}$$



Kernel density estimation (Parzen windows)

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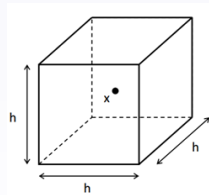
Kernel density estimation:

Let (x_1, x_2, \dots, x_n) be an independent and identically distributed sample drawn from some distribution with an unknown density $f(x)$. Its kernel density estimator is

$$\hat{f}(x)_{h,k} = \frac{1}{Nh^d} \sum_{n=1}^N k\left(\frac{x_n - x}{h}\right)$$

Kernel function:

$$k(u) = \begin{cases} 1 & |u_i| \leq \frac{1}{2}, i = 1, \dots, D \\ 0 & \text{otherwise} \end{cases}$$





Kernel density estimation

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$$\hat{f}_{h,K}(x) = \frac{1}{Nh^d} \sum_{n=1}^N k\left(\left\|\frac{x - x_n}{h}\right\|^2\right)$$

Density gradient:

$$\hat{\nabla} f_{h,K}(x) = \frac{2}{Nh^{d+2}} \sum_{n=1}^N (x_n - x) \left[-k' \left(\left\| \frac{x - x_n}{h} \right\|^2 \right) \right]$$

$$g(x) = -k'(x)$$



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$$\begin{aligned}\hat{\nabla} f_{h,K}(x) &= \frac{2}{Nh^{d+2}} \sum_{n=1}^N (x_n - x) \left[g\left(\left\|\frac{x - x_n}{h}\right\|^2\right) \right] \\ &= \underbrace{\frac{2}{h^2}}_C \underbrace{\left[\frac{1}{Nh^d} \sum_{n=1}^N g\left(\left\|\frac{x_n - x}{h}\right\|^2\right) \right]}_{f_{h,G}(x)} \underbrace{\left[\frac{\sum_{n=1}^N x_n g\left(\left\|\frac{x_n - x}{h}\right\|^2\right)}{\sum_{n=1}^N g\left(\left\|\frac{x_n - x}{h}\right\|^2\right)} - x \right]}_{m_{h,G}(x)}\end{aligned}$$



Kernel density estimation

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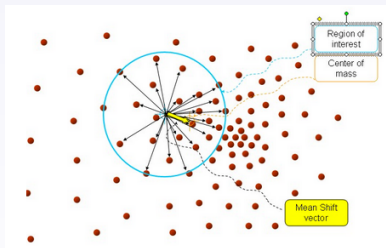
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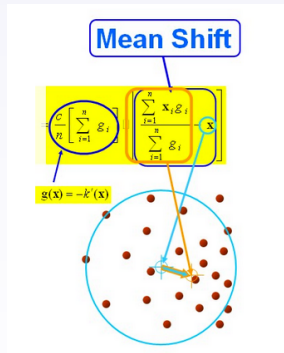
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$$m_{h,G}(x) = \frac{\sum_{n=1}^N x_n g(\|\frac{x_n - x}{h}\|^2)}{\sum_{n=1}^N g(\|\frac{x_n - x}{h}\|^2)} - x$$

$$m_{h,G}(x) = 0$$





Kernel density estimation

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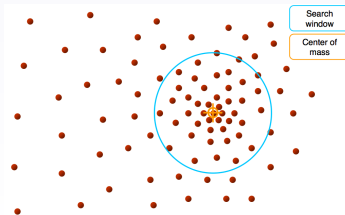
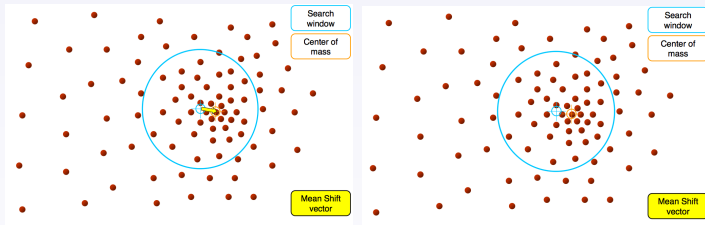
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Clustering center:

$$y_{i,k+1} = \frac{\sum_{n=1}^N x_n g(\|\frac{x_n - x}{h}\|^2)}{\sum_{n=1}^N g(\|\frac{x_n - x}{h}\|^2)}$$



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Algorithm:

- 1 Find features(color, gradients, texture, etc).
- 2 Initialize windows at individual pixel locations.
- 3 Compute $y_{i,k+1}$ until convergence, $y_{i,k} = y_{i,k+1}$.
- 4 Assign $z_i = (x_i, y_{i,k})$.



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Thanks!