

03

Image Dehazing

Haze/Fog Weather



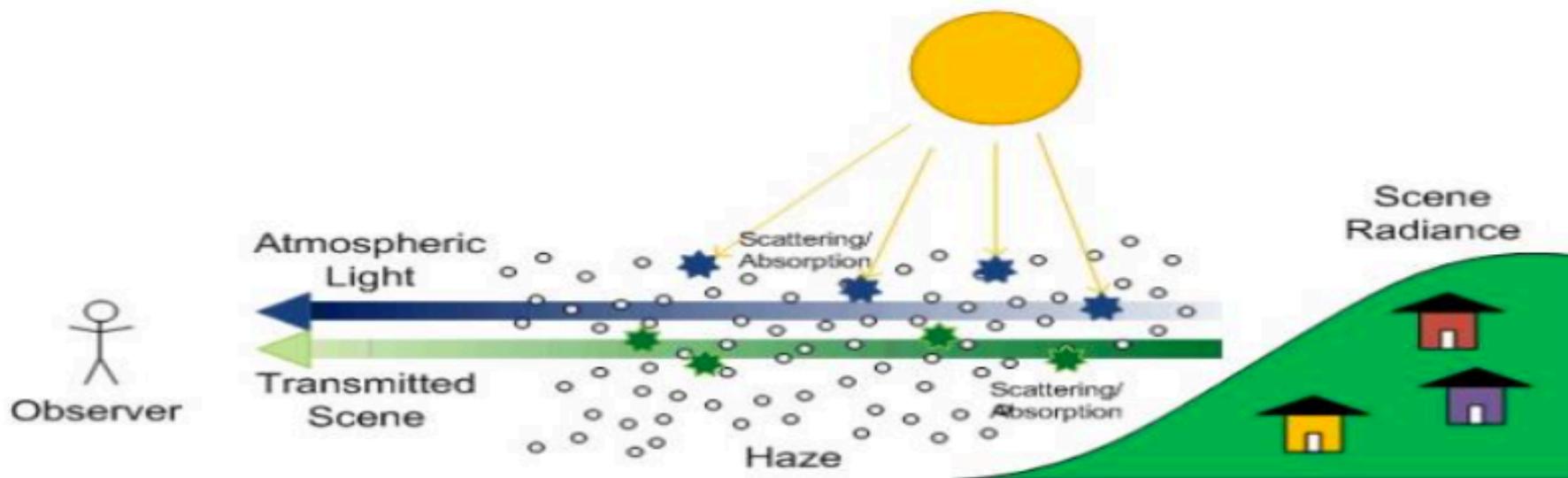
Haze

- **What is haze?**

- The characteristics of atmosphere degradation
- As distance between an object and the observer increases, atmosphere color replaces the color of the object.
- Physical interactions of light with particles can be classified mainly as **scattering** and **absorption**.

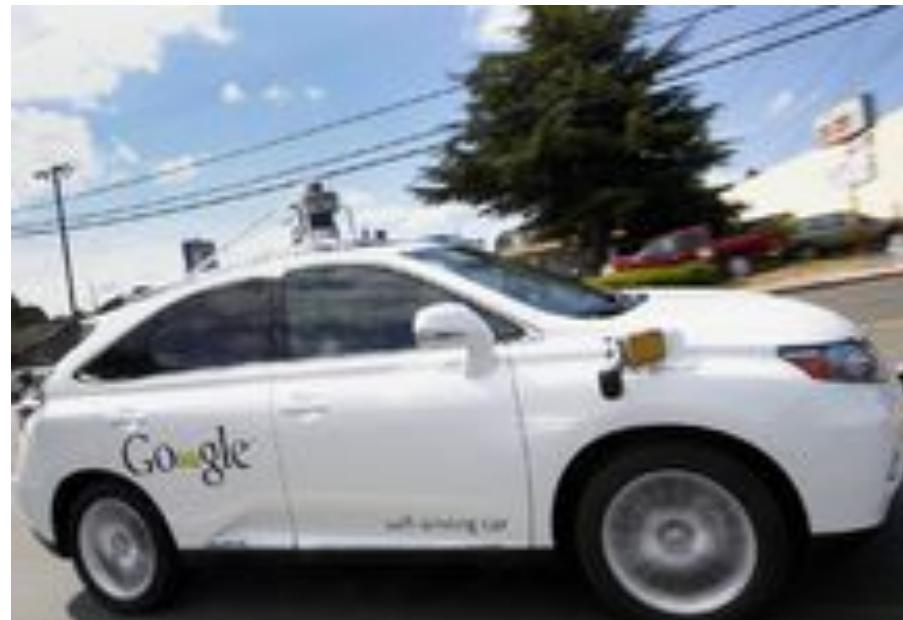
Haze

- What is haze?
 - Physical interactions of light with particles can be classified mainly as scattering and absorption.



Application of Dehazing

- Removing this degradation is useful in many applications:
 - Autonomous vehicle navigation



Application of Dehazing

- Removing this degradation is useful in many applications:
 - Video surveillance systems



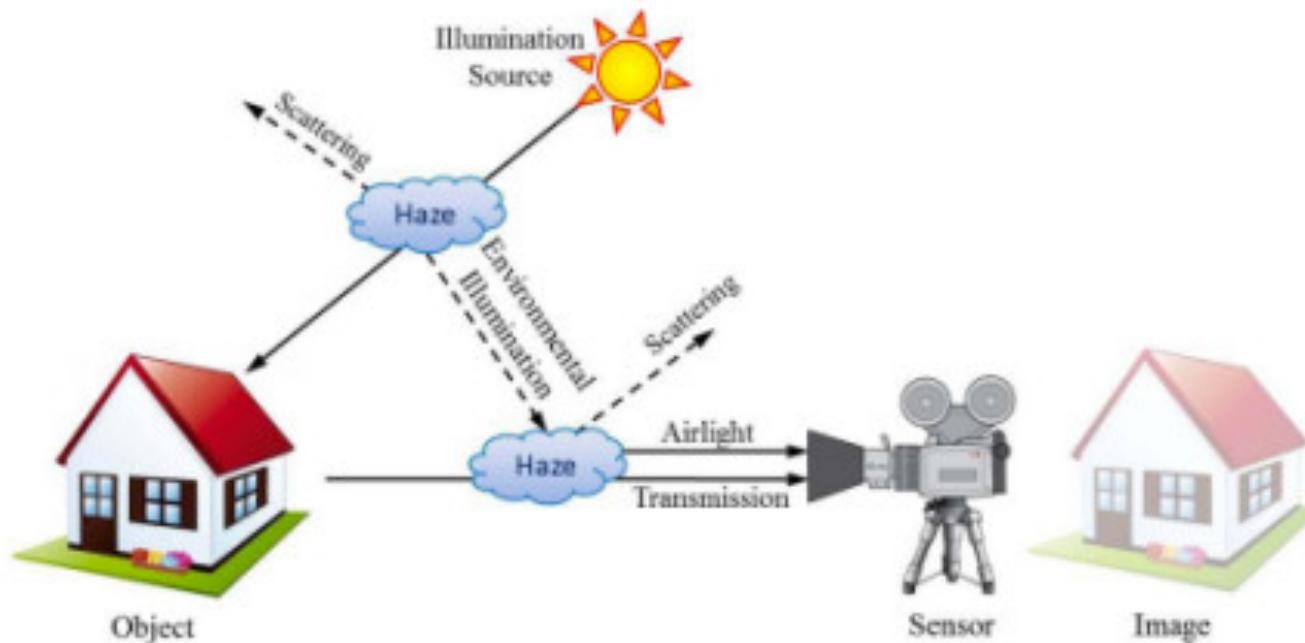
Application of Dehazing

- Removing this degradation is useful in many applications:
 - Aerial remote sensed images



How to dehaze

- Atmospheric scattering model



$$I(x) = J(x)t(x) + A(1 - t(x))$$

How to dehaze

● Atmospheric scattering model

$$I(x) = J(x)t(x) + A(1 - t(x))$$

$$t(x) = e^{-\beta d(x)}$$

$I(x)$ ——— Haze image

$J(x)$ ——— Clear scene

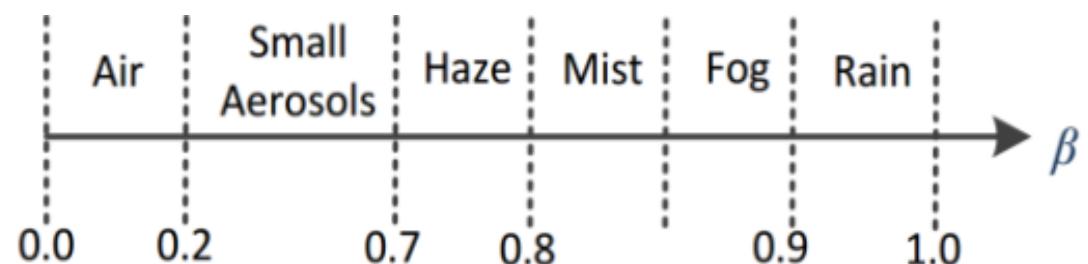
$t(x)$ ——— Medium transmission

A ——— The global atmospheric light(Airlight)

x ——— Index pixels in the observed haze image

$d(x)$ ——— Depth map

β ——— Scattering coefficient of the atmosphere



How to dehaze

- Atmospheric scattering model

$$I(x) = J(x)t(x) + A(1 - t(x))$$

$$\rightarrow J(x) = \frac{I(x) - A(1 - t(x))}{t(x)}$$

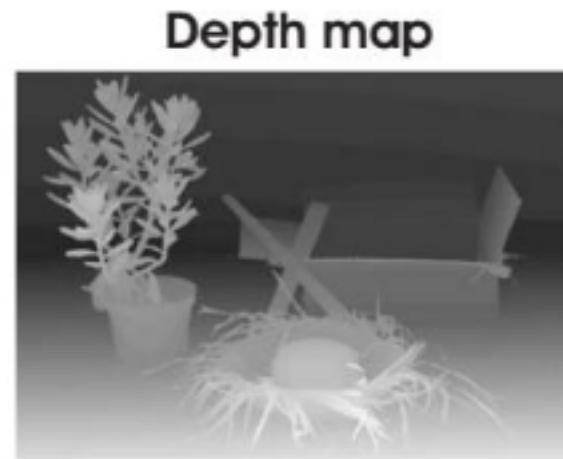
$$\rightarrow J(x) = \frac{I(x) - A + At(x)}{t(x)}$$

$$\rightarrow J(x) = \frac{I(x) - A}{t(x)} + A$$

Haze dataset

- **D-Hazy:**

- The dataset that contains 1400+ pairs of images with ground truth reference images and hazy images of the same scene.



Haze dataset

- D-Hazy:

- The dataset is built on the Middelbury[1] and NYU[2] Depth datasets that provide images of various scenes and their correspond depth maps.



[1] <http://vision.middlebury.edu/stereo/data/scenes2014/>

[2] http://cs.nyu.edu/~silberman/datasets/nyu_depth_v2.html vision@ouc

Haze dataset

- D-Hazy:

- $t(x) = e^{-\beta d(x)}$
- The transmission map is estimated based on equation using the depth d and the medium attenuation coefficient β .
- $\beta=1$
- $A=[1,1,1]$



Dehaze Methods

- Single Image Haze Removal Using Dark Channel Prior
K. He, J. Sun, and X. Tang
CVPR2009
- DehazeNet: An End-to-End System for Single Image Haze Removal
B. Cai, X. Xu, K. Jia, C. Qing, and D. Tao
IEEE Trans Image Process 2016

Single Image Haze Removal Using Dark Channel Prior

- **Dark channel prior**

- It is a kind of statistics of the haze-free outdoor images.
- It is based on a key observation —most local patches in haze-free outdoor images contain some pixels which have very low intensities in at least one color channel.



Dark Channel

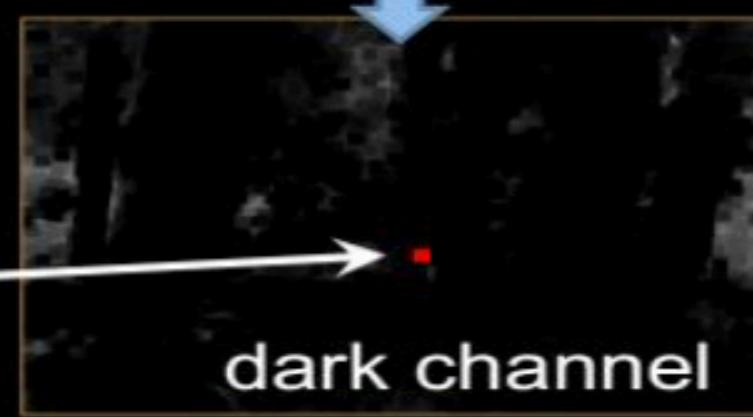
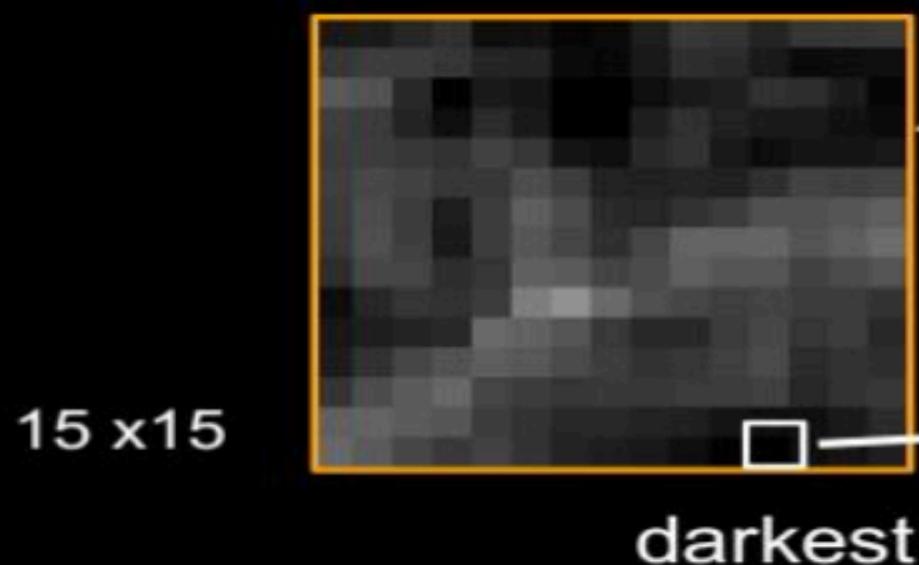
- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$



$\min(r, g, b)$

Dark Channel

- min (rgb, local patch)
 - min (r, g, b)
 - min (local patch) = min filter



*This slide is from Kaiming He's talking slides in CVPR'09.

Dark Channel

- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$
 - $\min(\text{local patch}) = \min \text{filter}$

$$J^{dark}(x) = \min_{y \in \Omega(x)} (\min_{c \in \{r, g, b\}} J^c(y))$$

- J^c : color channel of J
- J^{dark} : dark channel of J



dark channel

Dark Channel

- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$
 - $\min(\text{local patch}) = \text{min filter}$

$$J^{dark} = \min_{\Omega} (\min_c J^c)$$

- J^c : color channel of J
- J^{dark} : dark channel of J



● Dark channel prior

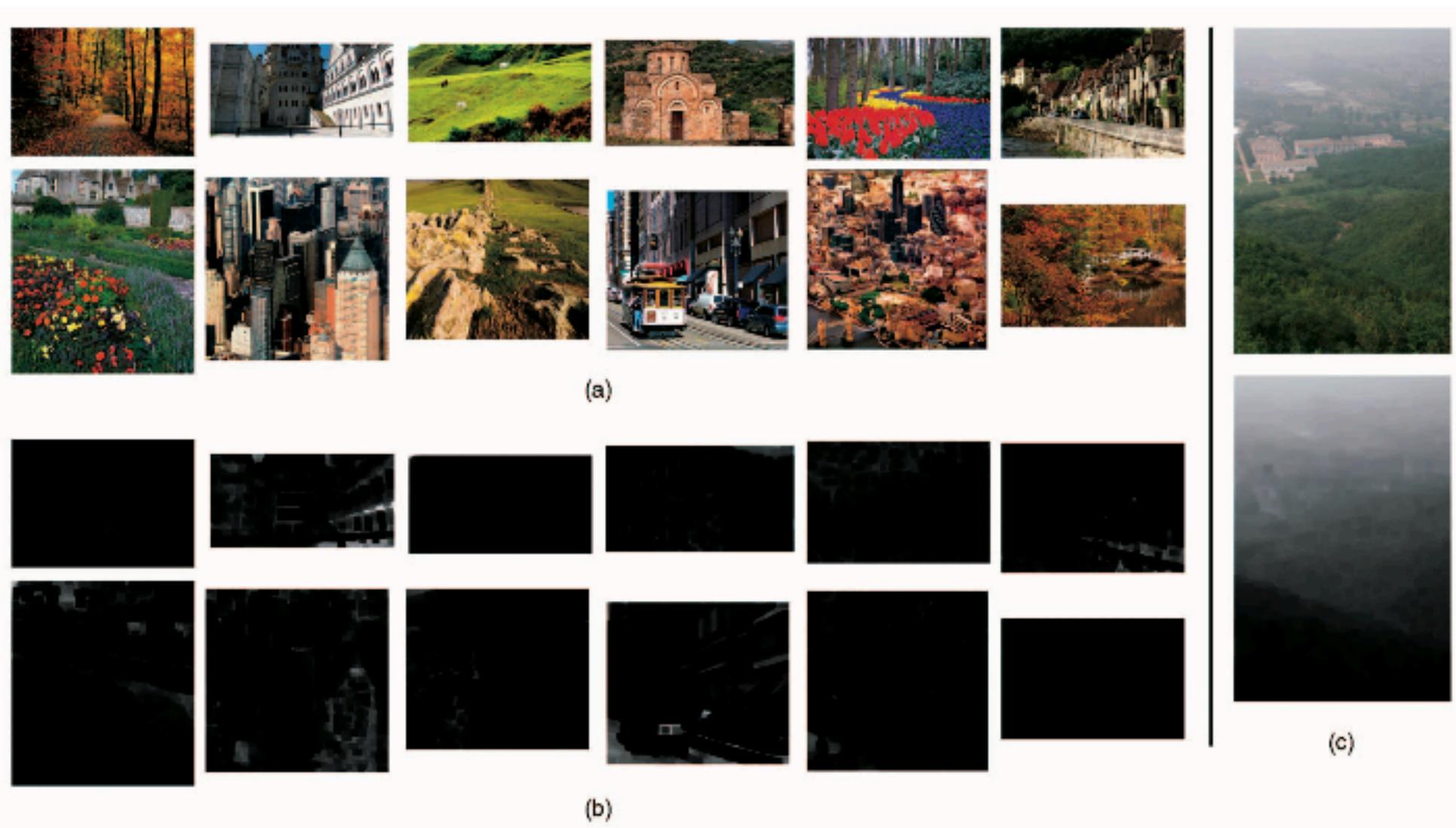


Fig. 4. (a) Example images in our haze-free image database. (b) The corresponding dark channels. (c) A hazy image and its dark channel.

Single Image Haze Removal Using Dark Channel Prior

- Dark channel prior

- Image size: 500×500, patch size: 15×15
- 75% dark channel values = 0
- 86% dark channel values <16
- 90% dark channel values <25

$$\longrightarrow J^{dark} \longrightarrow 0$$

- So: $\min_{\Omega} \left(\min_c (J^c) \right) \longrightarrow 0$

Single Image Haze Removal Using Dark Channel Prior

- Transmission Estimation

$$I(x) = J(x)t(x) + A(1 - t(x))$$

$$\rightarrow \min_{y \in \Omega(x)} (I^c(y)) = \tilde{t}(x) \min_{y \in \Omega(x)} (J^c(y)) + (1 - \tilde{t}(x))A^c$$

$$\rightarrow \min_{y \in \Omega(x)} \left(\frac{I^c(y)}{A^c} \right) = \tilde{t}(x) \min_{y \in \Omega(x)} \left(\frac{J^c(y)}{A^c} \right) + (1 - \tilde{t}(x))$$

$$\min_{y \in \Omega(x)} \left(\frac{I^c(y)}{A^c} \right) = \tilde{t}(x) \min_{y \in \Omega(x)} \left(\min \left(\frac{J^c(y)}{A^c} \right) \right) + (1 - \tilde{t}(x))$$

● Dark channel prior

$$\min_{y \in \Omega(x)} \left(\frac{I^c(y)}{A^c} \right) = \tilde{t}(x) \boxed{\min_{y \in \Omega(x)} \left(\min_c \left(\frac{J^c(y)}{A^c} \right) \right)} + (1 - \tilde{t}(x))$$

$$J^{dark}(x) = \min_{y \in \Omega(x)} \left(\min_c (J^c(y)) \right) = 0, \text{ and, } A^c > 0$$

$$\boxed{\min_{y \in \Omega(x)} \left(\min_c \left(\frac{J^c(y)}{A^c} \right) \right)} = 0$$

$$\min_{y \in \Omega(x)} \left(\min_c \left(\frac{I^c(y)}{A^c} \right) \right) = 1 - \tilde{t}(x)$$

$$\tilde{t}(x) = 1 - \omega \min_{y \in \Omega(x)} \left(\min_c \left(\frac{J^c(y)}{A^c} \right) \right)$$

Single Image Haze Removal Using Dark Channel Prior

- He shows that the transmission can be estimated by calculating:

$$\tilde{t}(x) = 1 - \omega \min_{y \in \Omega(x)} \left(\min_c \left(\frac{J^c(y)}{A^c} \right) \right)$$

$$\omega=0.95$$

Single Image Haze Removal Using Dark Channel Prior

- Atmospheric Light (A) Estimation:

- Airlight is estimated by picking up the pixels of the image corresponding to the 0.1% brightest pixels in the dark channel.
- And then choosing the pixels with maximum intensity



Single Image Haze Removal Using Dark Channel Prior

$$I(x) = J(x)t(x) + A(1 - t(x))$$

$$\rightarrow J(x) = \frac{I(x) - A(1 - t(x))}{t(x)}$$

$$\rightarrow J(x) = \frac{I(x) - A + At(x)}{t(x)}$$

$$\rightarrow J(x) = \frac{I(x) - A}{t(x)} + A \quad \rightarrow \quad J(x) = \frac{I(x) - A}{\max(t(x), t_0)} + A$$

Single Image Haze Removal Using Dark Channel Prior

$$J(x) = \frac{I(x) - A}{\max(t(x), t_0)} + A \quad \rightarrow \quad t_0 = 0.1$$



Single Image Haze Removal Using Dark Channel Prior

- Airlight and transmission are sufficient to invert the model and recover the original radiance of the scene

$$J(x) = \frac{I(x) - A}{\max(t(x), t_0)} + A$$

Single Image Haze Removal Using Dark Channel Prior

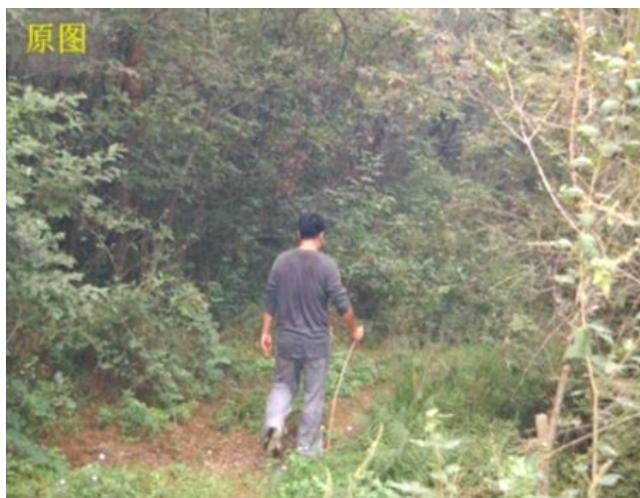


Single Image Haze Removal Using Dark Channel Prior

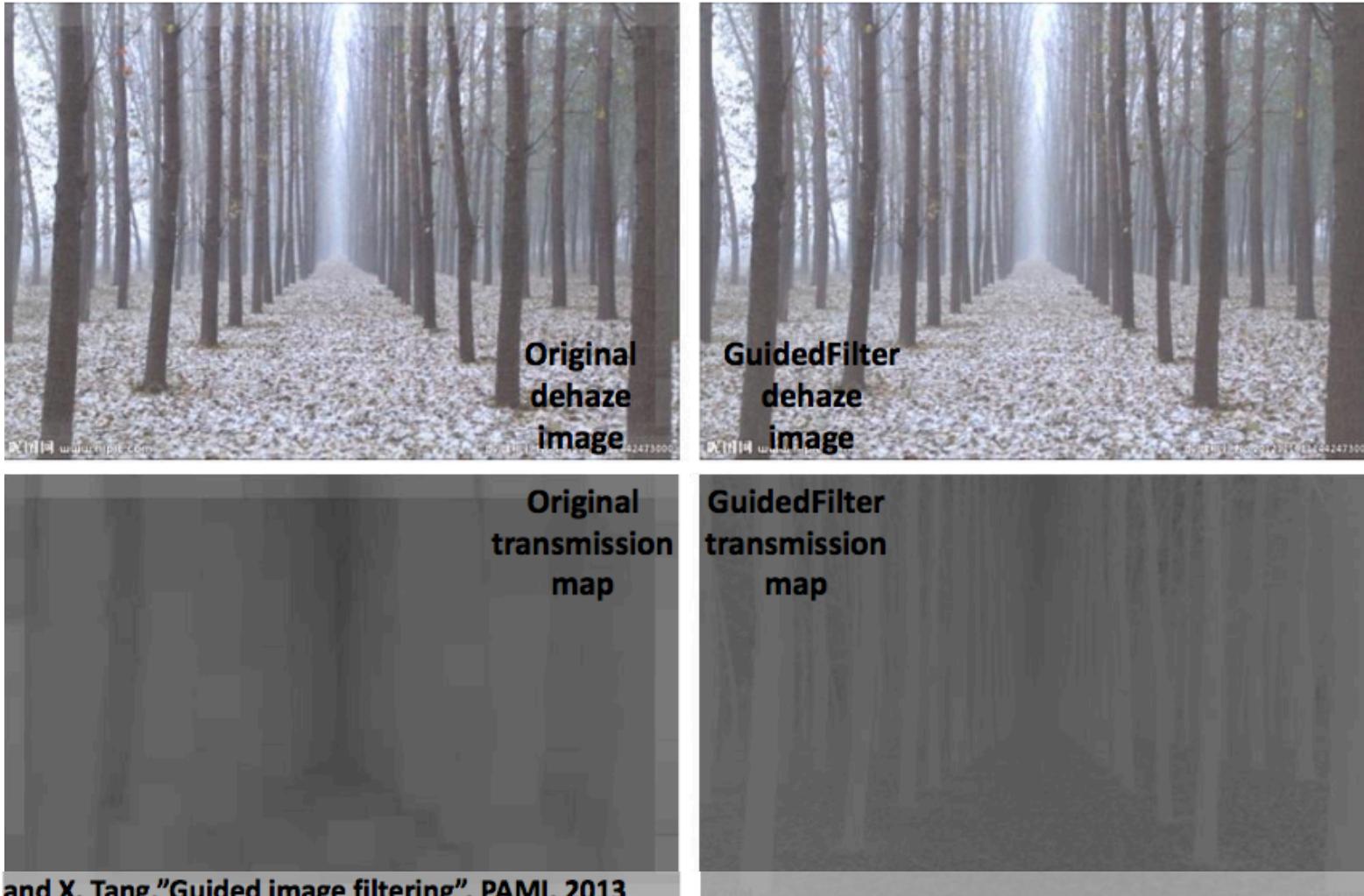
haze



dehaze



Single Image Haze Removal Using Dark Channel Prior



Single Image Haze Removal Using Dark Channel Prior

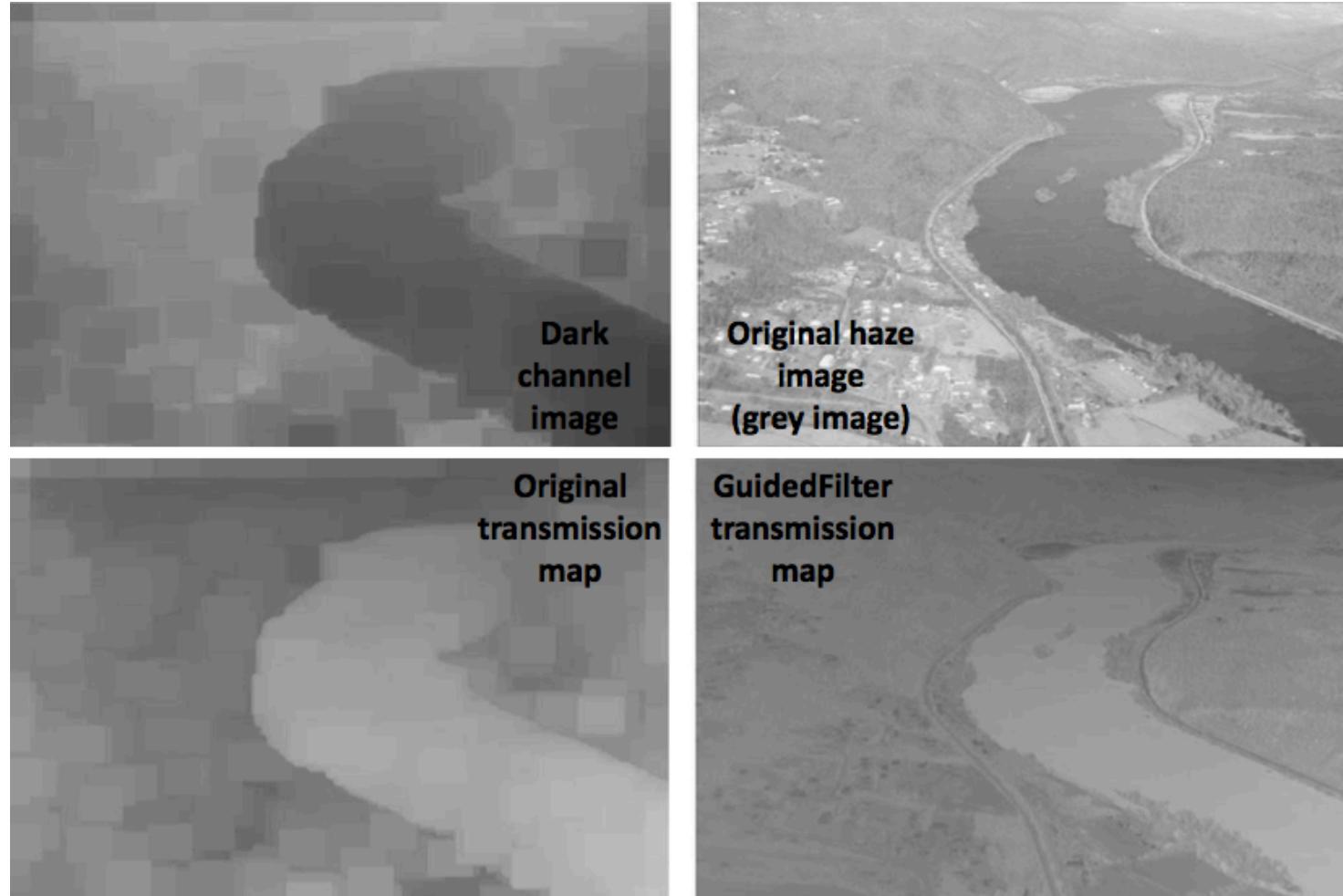


haze



dehaze

Single Image Haze Removal Using Dark Channel Prior



Single Image Haze Removal Using Dark Channel Prior

- **Limitation**

It is known what are the consequences of a bad estimate for the transmission



Haze is not completely removed, or it is removed where there is no haze (overboost contrast)

Single Image Haze Removal Using Dark Channel Prior

● Limitation

When the scene objects are similar to the atmospheric light and no shadow is cast on them, the dark channel prior is invalid.

The method will underestimate the transmission for these objects, such an the white marble in Figure.



Figure 13. Failure case. Left: input image. Middle: our result. Right: our transmission map. The transmission of the marble is underestimated.

DehazeNet: An End-to-End System for Single Image Haze Removal

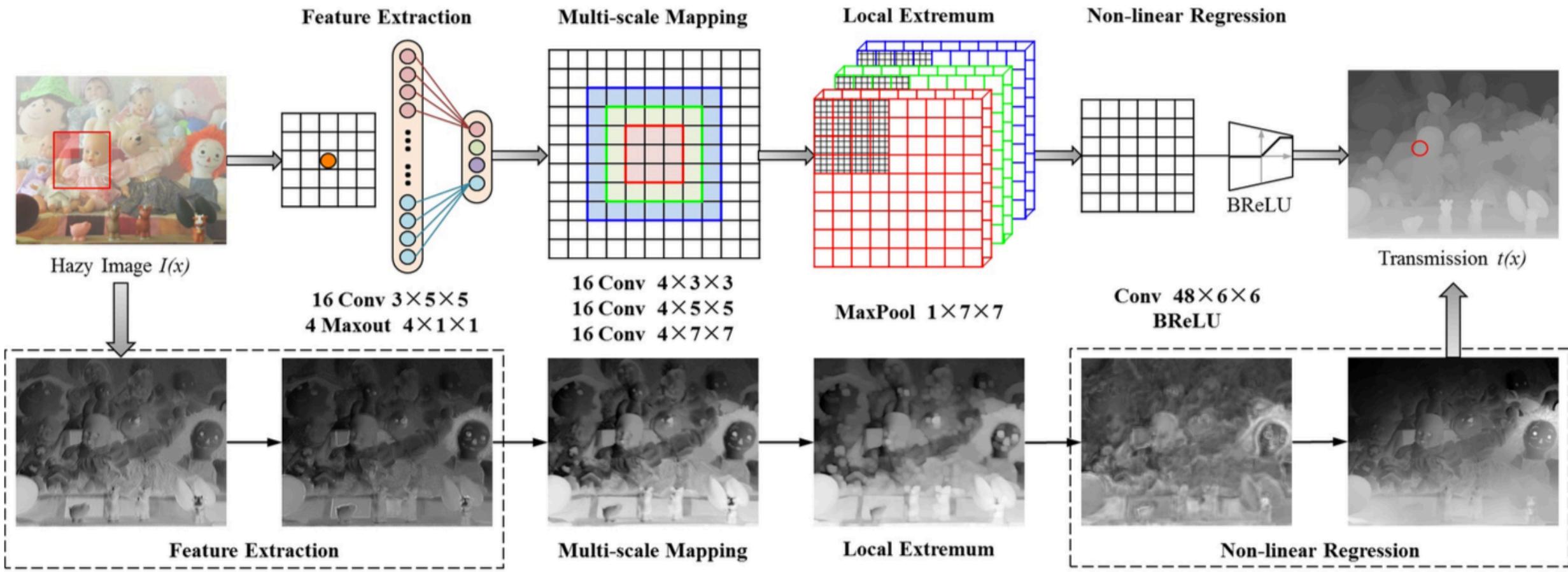
Estimation of a global atmospheric light

Recover an accurate medium transmission map

DehazeNet, a trainable CNN based end-to-end system for
medium transmission estimation

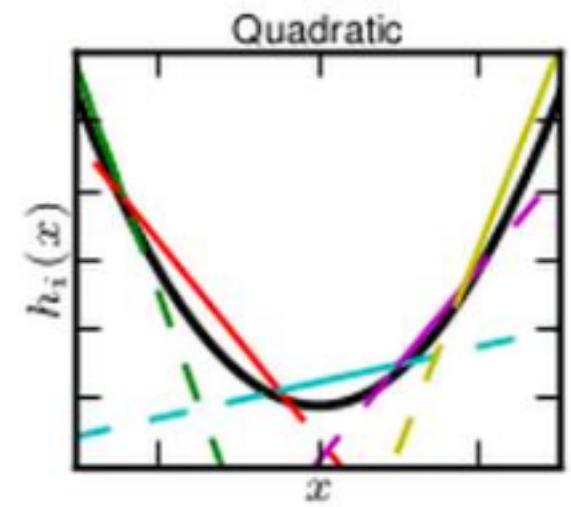
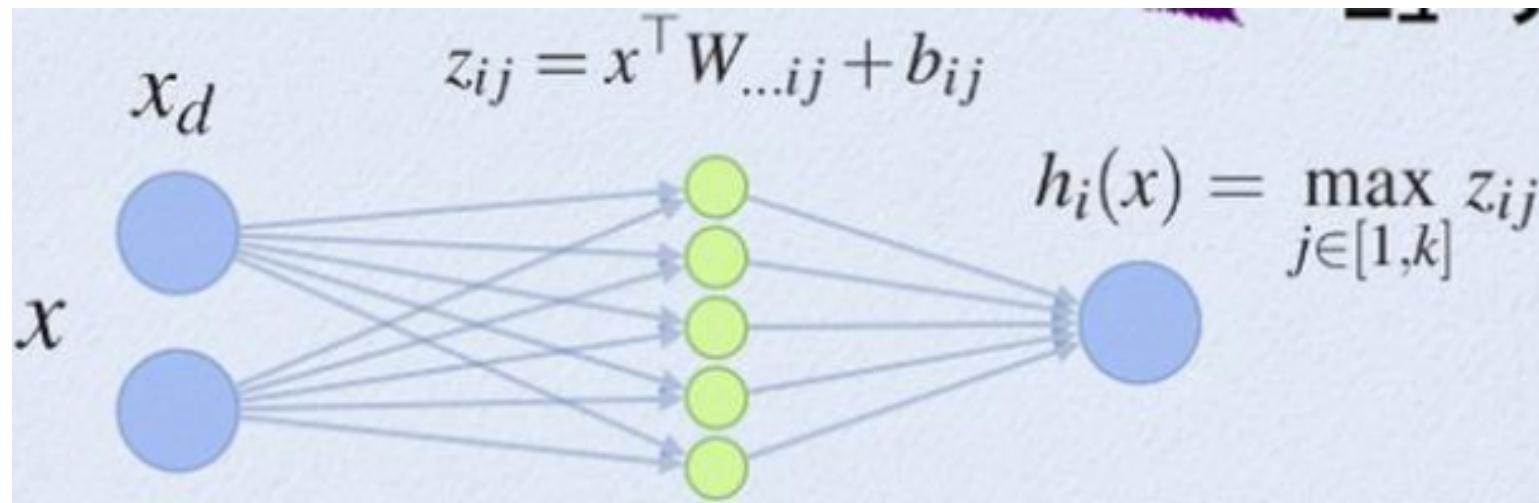
DehazeNet: An End-to-End System for Single Image Haze Removal

- Learn and estimate the mapping relations between haze image patches and their medium transmissions.
- Propose a novel nonlinear activation function in Net, called Bilateral Rectified Linear Unit(BReLU).
- Establish connections between components of DehazeNet and priors used in existing dehazing methods.

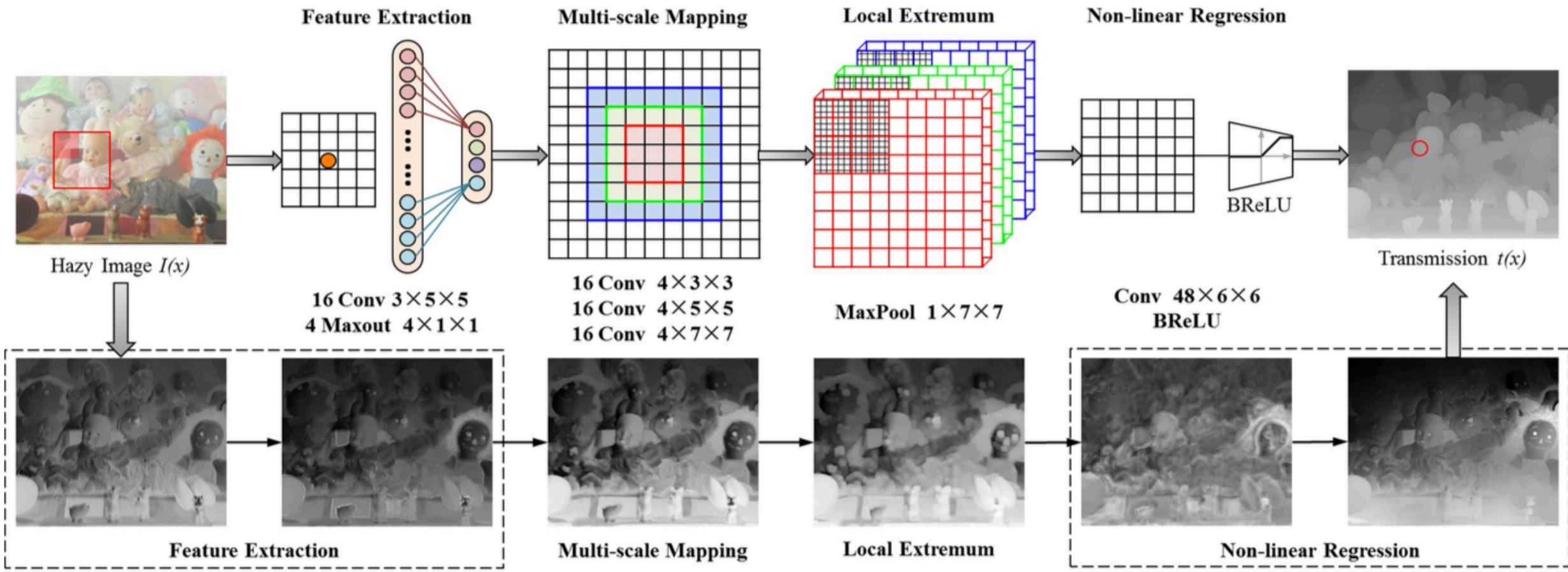


- DehazeNet conceptually consists of four sequential operations (feature extraction, multi-scale mapping, local extremum and non-linear regression) which is constructed 3 convolution layers, a max-pooling, a Maxout unit and a BReLU activation function.

DehazeNet: An End-to-End System for Single Image Haze Removal



$$h_i(x) = \max_{j \in [1, k]} z_{ij} \quad z_{ij} = x^T W_{\dots ij} + b_{ij}, \text{ and } W \in R^{d*m*k}$$



- DehazeNet conceptually consists of four sequential operations (feature extraction, multi-scale mapping, local extremum and non-linear regression) which is constructed 3 convolution layers, a max-pooling, a Maxout unit and a BReLU activation function.

DehazeNet: An End-to-End System for Single Image Haze Removal

- Layer Designs of DehazeNet
- Multi-scale Mapping
- Local Extremum
- Non-linear Regression

Formulation	Type	Input Size	Num <i>n</i>	Filter <i>f × f</i>	Pad
Feature Extraction	Conv	$3 \times 16 \times 16$	16	5×5	0
	Maxout	$16 \times 12 \times 12$	4	—	0
Multi-scale Mapping	Conv	$4 \times 12 \times 12$	16	3×3	1
			16	5×5	2
			16	7×7	3
Local Extremum	Maxpool	$48 \times 10 \times 10$	48	7×7	0
Non-linear Regression	Conv	$48 \times 6 \times 6$	1	4×4	0
			1	—	0

DehazeNet: An End-to-End System for Single Image Haze Removal

- Training of DehazeNet

- Training data

Two assumptions:

- 1) Image content is independent of medium transmission
(the same image content can appear at any depths of scenes)
- 2) Medium transmission is locally constant (image pixels in a small patch tend to have similar depths)

DehazeNet: An End-to-End System for Single Image Haze Removal

- Training of DehazeNet

- Training data

Assume an arbitrary(任意的) transmission for an individual image patch.

Given a haze-free patch $J(x)$, the atmospheric light A , and random transmission t , a haze image is synthesized.

									000001.jpg 0.10516242
									000002.jpg 0.18558914
									000003.jpg 0.11729032
									000004.jpg 0.16907009
									000005.jpg 0.14768056
									000006.jpg 0.34322159
									000007.jpg 0.96592681
									000008.jpg 0.22404758
									000009.jpg 0.29576940
									000010.jpg 0.29701062
									000011.jpg 0.76015258
									000012.jpg 0.17341965
									000013.jpg 0.40635436
									000014.jpg 0.56143965
									000015.jpg 0.37423851
									000016.jpg 0.74566579
									000017.jpg 0.25431978
									000018.jpg 0.76111873
									000019.jpg 0.77886669
									000020.jpg 0.01341821
									000021.jpg 0.37994670
									000022.jpg 0.07683825
									000023.jpg 0.06725106
									000024.jpg 0.34487915
									000025.jpg 0.52858843
									000026.jpg 0.19900572
									000027.jpg 0.95942324
									000028.jpg 0.48010922
									000029.jpg 0.40867907
									000030.jpg 0.60275455
									000031.jpg 0.45066727
									000032.jpg 0.07839893
									000033.jpg 0.58494760
									000034.jpg 0.98030893
									000035.jpg 0.02719647
									000036.jpg 0.81766764
									000037.jpg 0.57564936
									000038.jpg 0.11626336
									000039.jpg 0.19522155
									000040.jpg 0.93690418
									000041.jpg 0.50169761

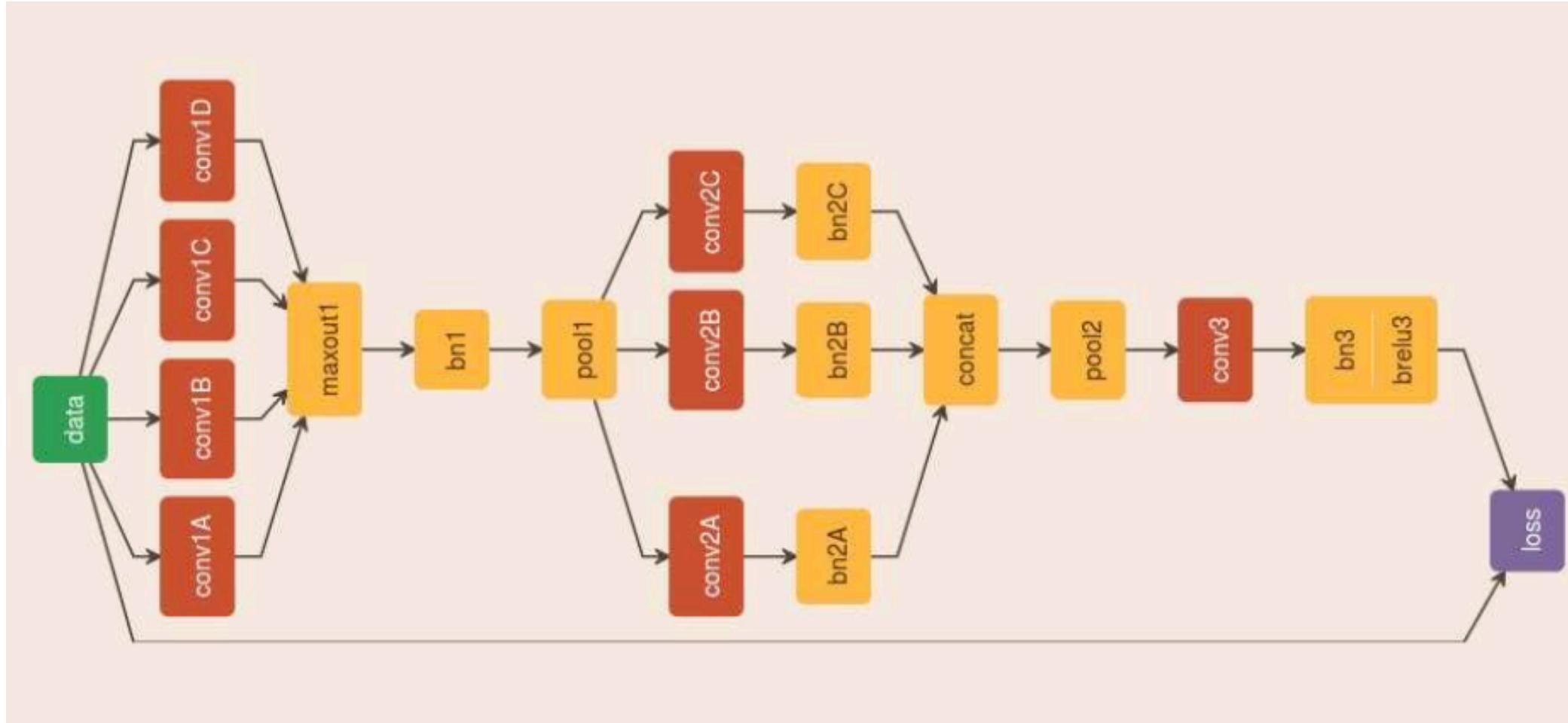
DehazeNet: An End-to-End System for Single Image Haze Removal

● Training of DehazeNet

- Training method
 - 1) In the DehazeNet, supervised learning requires the mapping relationship F between RGB value and medium transmission.
 - 2) Network parameters $\Theta = \{W, B\}$ are achieved through minimizing the loss function between the training patch $I(x)$ and the corresponding ground truth medium transmission t .
 - 3) MSE(Mean Squared Error) as the loss function:

$$L(\theta) = \frac{1}{N} \sum_{i=1}^N \|F(I_i^P; \theta) - t_i\|^2$$

DehazeNet: An End-to-End System for Single Image Haze Removal



DehazeNet: An End-to-End System for Single Image Haze Removal

- Results

