



上海交通大学  
SHANGHAI JIAO TONG UNIVERSITY

# Relational/Graph Learning

Teacher: Zheng Wang

Social Network Analysis (NIS8023)

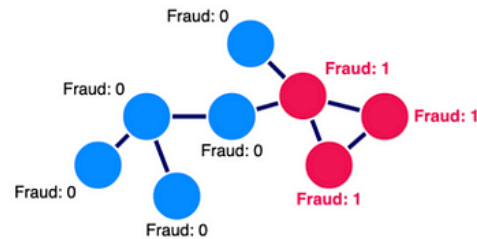
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# The Aim of Graph Learning

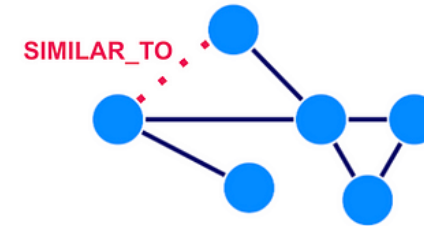


- Graph learning, machine learning on graphs, aims to learn complex relationships among nodes and the topological structure of graphs.



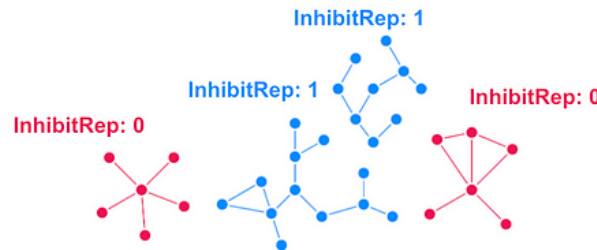
## Node Property Prediction

Predict a discrete or continuous node property, called **node classification** and **node regression** respectively.



## Link Prediction

Predict if a relationship should exist between two nodes. Often a binary classification task, but can sometimes include more link types or continuous properties.



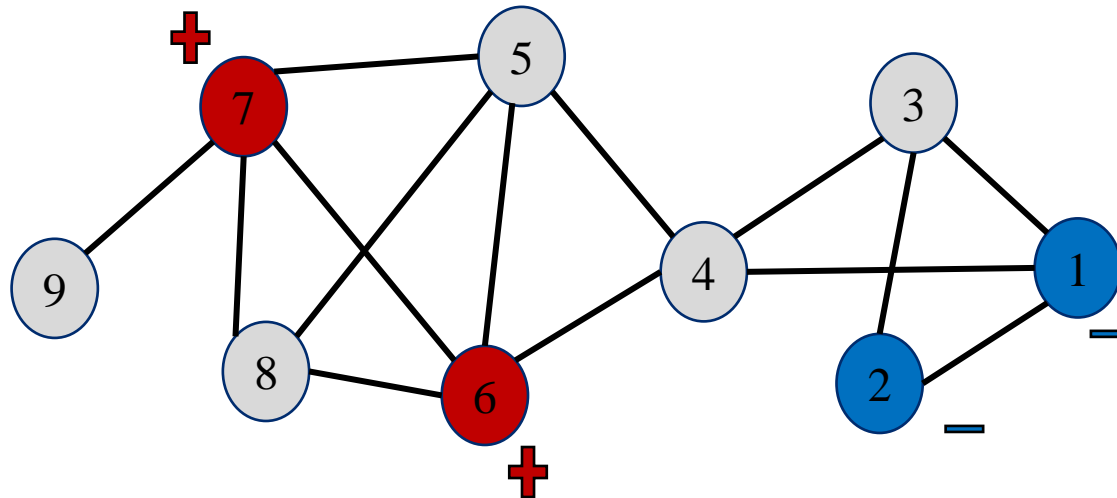
## Graph Property Prediction

Predict a discrete or continuous property of a graph or subgraph.



# A Graph Node Classification Example

- **Objective:** Exploit the structural information within a graph to enhance the prediction of node attributes or labels.



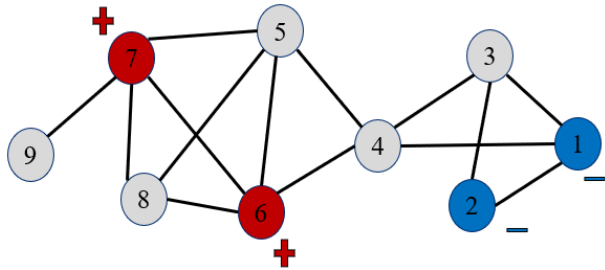
Given the graph structure with some labeled nodes (i.e., 1, 2, 6, 7 are labeled), predict the labels for the remaining nodes.



# Outline

- **Shallow Methods**
  - Weighted-vote relational neighbor
  - Label Propagation
- **Deep Learning Methods**

# Recap: Traditional Non-Graph Learning Methods



**Node features (by edge)**

$$u_1 = [0, 1, 1, 1, 0, 0, 0, 0, 0]$$

$$u_2 = [1, 0, 1, 0, 0, 0, 0, 0, 0]$$

$\vdots$

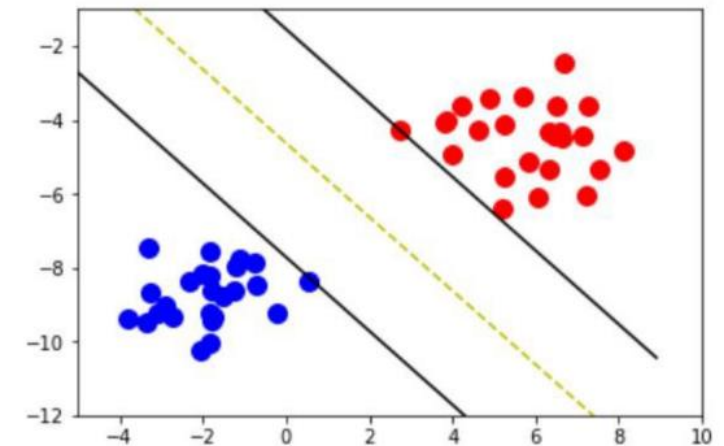
**Node labels**

$$y_1 = 0$$

$$y_2 = 0$$

$$y_6 = 1$$

$$y_7 = 1$$

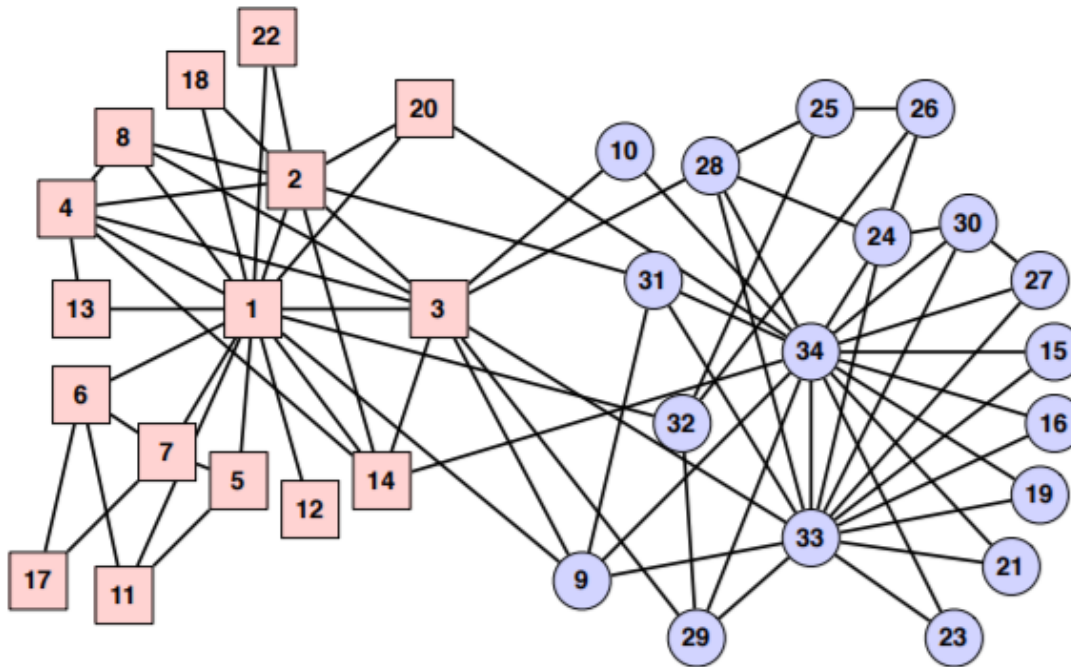


Common classifiers: (like linear classifiers and SVMs)

# How To Use Graph Information Effectively?



- Observation: Linked nodes tend to have similar labels



The karate club with ground truth



# The Key Idea Is “Collective Classification”

- Definition: Perform collaborative classification of unlabeled nodes in a partially labeled network using techniques such as label propagation or approximate inference [1]. Two typical methods:
  - Weighted-vote relational neighbor
  - Label propagation

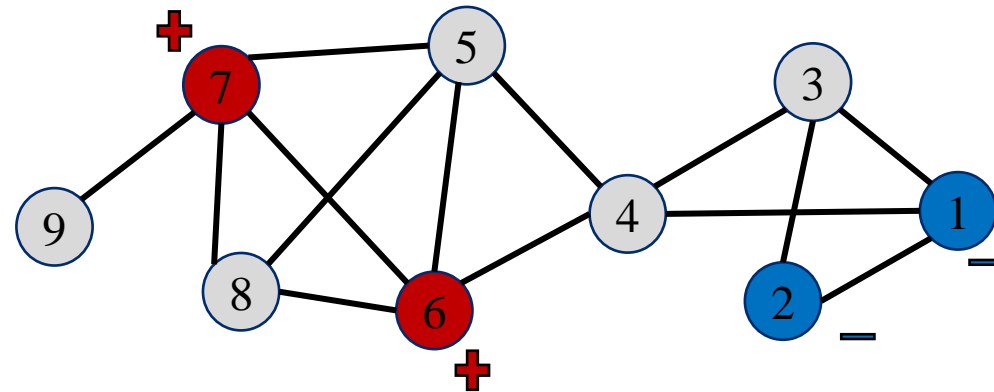


# Weighted-vote Relational Neighbor (wvRN)

- The labels of unlabeled node  $v_i$  are determined by a weighted vote among their neighbors  $\mathcal{N}(v_i)$ .

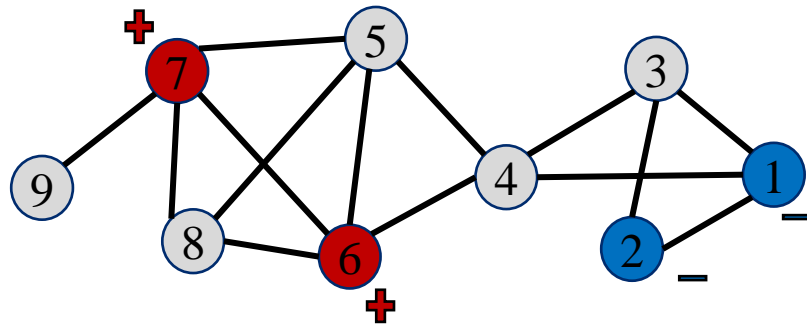
$$P(y_i = 1 | \mathcal{N}(v_i)) = \frac{1}{|\mathcal{N}(v_i)|} \sum_{v_j \in \mathcal{N}(v_i)} P(y_j = 1 | \mathcal{N}(v_j))$$

$y_i$  is the label of node  $v_i$



# Weighted-vote Relational Neighbor (wvRN)

- The key idea
  1. Keep the labels of labeled nodes fixed.
  2. Recalculate probabilities iteratively based on neighbors' labels until convergence.



# An Example of wvRN

## Initialization of unlabeled nodes

$$P(y_i = 1 | \mathcal{N}(v_i)) = 0.5$$

- For node  $v_3$ ,  $\mathcal{N}(v_3) = \{1, 2, 4\}$

$$P(y_1 = 1 | \mathcal{N}(v_1)) = 0$$

$$P(y_2 = 1 | \mathcal{N}(v_2)) = 0$$

$$P(y_4 = 1 | \mathcal{N}(v_4)) = 0.5$$

$$P(y_3 = 1 | \mathcal{N}(v_3)) = 1/3(0 + 0 + 0.5) = 0.17$$

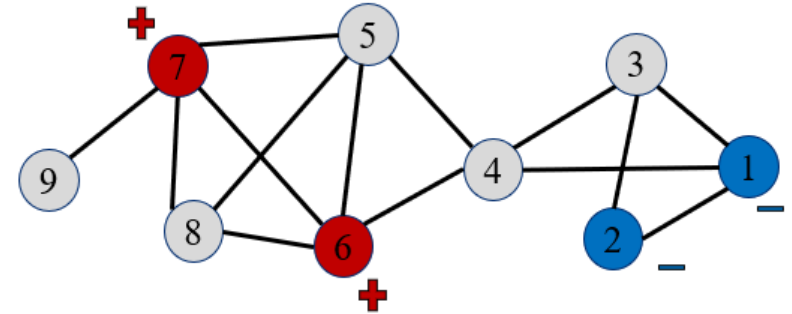
- For node  $v_4$ ,  $\mathcal{N}(v_4) = \{1, 3, 5, 6\}$

$$P(y_4 = 1 | \mathcal{N}(v_4)) = \frac{1}{4}(0 + 0.17 + 0.5 + 1) = 0.42$$

- For node  $v_5$ ,  $\mathcal{N}(v_5) = \{4, 6, 7, 8\}$

$$P(y_5 = 1 | \mathcal{N}(v_5)) = \frac{1}{4}(0.42 + 1 + 1 + 0.5) = 0.73$$

...



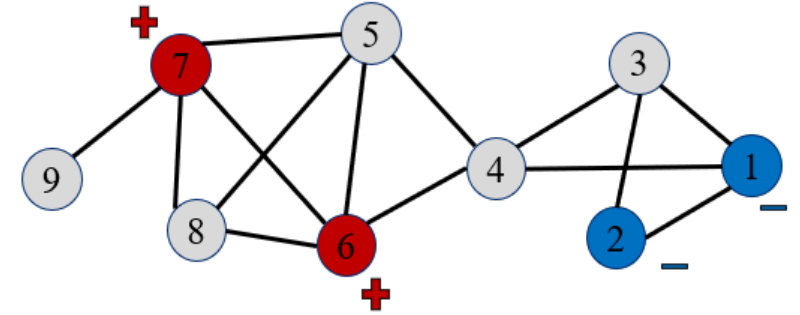
$$\mathbf{p}^{(1)} = \begin{bmatrix} 0 \\ 0 \\ 0.17 \\ 0.42 \\ 0.73 \\ 1 \\ 1 \\ 0.91 \\ 1.00 \end{bmatrix}$$

# Iteration Results



- Converge after 5 iterations

- Nodes 5, 8, 9: + ( $P(v_i) > 0.5$ )
- Node 3: - ( $P(v_i) < 0.5$ )
- Node 4 is around  $P(v_i) = 0.5$

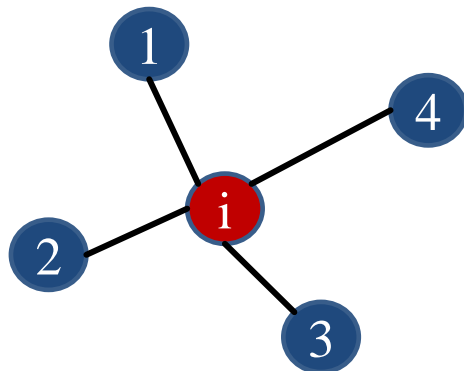


$$\mathbf{p}^{(1)} = \begin{bmatrix} 0 \\ 0 \\ 0.17 \\ 0.42 \\ 0.73 \\ 1 \\ 1 \\ 0.91 \\ 1.00 \end{bmatrix}, \mathbf{p}^{(2)} = \begin{bmatrix} 0 \\ 0 \\ 0.14 \\ 0.47 \\ 0.85 \\ 1 \\ 1 \\ 0.95 \\ 1.00 \end{bmatrix}, \mathbf{p}^{(3)} = \begin{bmatrix} 0 \\ 0 \\ 0.16 \\ 0.50 \\ 0.86 \\ 1 \\ 1 \\ 0.95 \\ 1.00 \end{bmatrix}, \mathbf{p}^{(4)} = \begin{bmatrix} 0 \\ 0 \\ 0.17 \\ 0.51 \\ 0.87 \\ 1 \\ 1 \\ 0.96 \\ 1.00 \end{bmatrix}, \mathbf{p}^{(5)} = \begin{bmatrix} 0 \\ 0 \\ 0.17 \\ 0.51 \\ 0.87 \\ 1 \\ 1 \\ 0.96 \\ 1.00 \end{bmatrix}.$$

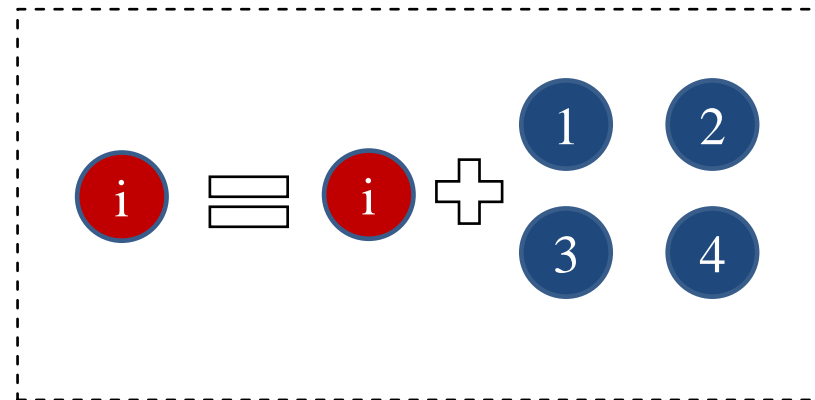
# Label Propagation (Consistency Method)

## ■ Intuition

1. Each node iteratively spreads its label to neighbors.
2. Each node partly keeps its initial label information.



Given graph and label information



The process of label propagation

- Zhou D, Bousquet O, Lal T N, et al. Learning with local and global consistency[C] //Advances in neural information processing systems. 2004: 321-328.

# Symbol Notations



- **G**: Input network structure
- **F**: Classification result matrix on nodes

$$F_{n \times c} = \begin{bmatrix} F_{11} & F_{12} & \dots & F_{1c} \\ \dots & \dots & \dots & \dots \\ F_{n1} & F_{n2} & \dots & F_{nc} \end{bmatrix} \quad \text{by labeling } v_i \text{ as } y_i = \operatorname{argmax}_{j \leq c} F_{ij}$$

- **Y**: Initial labels of nodes

$$Y_{ij} = \begin{cases} 1, & \text{if } v_i \text{ is labeled as } y_i = j \\ 0, & \text{otherwise} \end{cases}$$

# Consistency Method



- Symmetric normalization of  $G$ :

$$S = D^{-\frac{1}{2}} G D^{-\frac{1}{2}}$$

where  $D_{ii} = \sum_j G_{ij}$  is the degree matrix of the network.

- Iterate  $F(t+1) = \alpha S F(t) + (1-\alpha)Y$  until converge
- Let  $F^*$  represent the limit of the sequence  $\{F(t)\}$ . The final classification result is:

$$y_i = \arg \max_{j \leq c} F_{ij}^*$$



# The Closed-Form Solution of the Consistency Method

- Through the iterative equation, we obtain:

$$F(t) = (\alpha S)^{t-1}Y + (1 - \alpha) \sum_{i=0}^{t-1} (\alpha S)^i Y.$$

The advantage  
of normalization

Since  $0 < \alpha < 1$  and the eigenvalues of  $S$  in  $[-1, 1]$

- As  $\lim_{t \rightarrow \infty} (\alpha S)^{t-1} = 0$ , and  $\lim_{t \rightarrow \infty} \sum_{i=0}^{t-1} (\alpha S)^i = (I - \alpha S)^{-1}$ , we get:

$$F^* = \lim_{t \rightarrow \infty} F(t) = (1 - \alpha)(I - \alpha S)^{-1}Y$$



Thanks for your time.  
QA.

