Homework 3: Recurrent Neural Networks

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1 Exercise 1: Backpropagation through Time

Consider the RNN (Recurrent Neural Network) in Figure 1:

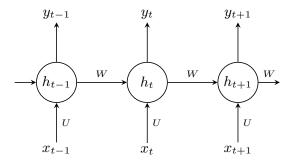


Figure 1: A recurrent neural network.

Each state h_t is given by:

$$h_t = \sigma(Wh_{t-1} + Ux_t)$$
, where $\sigma(z) = \frac{1}{1 + \exp(-z)}$.

Let L be a loss function defined as the sum over the losses L_t at every time step until time T: $L = \sum_{t=0}^{T} L_t$, where L_t is a scalar loss depending on h_t .

In the following, we want to derive the gradient of this loss function with respect to the parameter W.

- (a) Suppose we have $y = \sigma(Wx)$ where $y \in \mathbb{R}^n, x \in \mathbb{R}^d$ and $W \in \mathbb{R}^{n \times d}$. Derive the Jacobian $\frac{\partial y}{\partial x} = \operatorname{diag}(\sigma')W \in \mathbb{R}^{n \times d}$.
 - (b) Derive the quantity $\frac{\partial L}{\partial W} = \sum_{t=0}^{T} \sum_{k=1}^{t} \frac{\partial L_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$.

2 Exercise 2: Vanishing/Exploding Gradients in RNNs

In this exercise, we want to understand why RNNs (Recurrent Neural Networks) are especially prone to the Vanishing/Exploding Gradients problem and what role the eigenvalues

of the weight matrix play. Consider part (b) of exercise 1 again.

- (a) Write down $\frac{\partial L}{\partial W}$ as expanded sum for T=3. You should see that if we want to backpropagate through n timesteps, we have to multiply the matrix $\operatorname{diag}(\sigma')W$ n times with itself.
- (b) Remember that any diagonalizable (square) matrix M can be represented by its eigendecomposition $M = Q\Lambda Q^{-1}$ where Q is a matrix whose i-th column corresponds to the i-th eigenvector of M and Λ is a diagonal matrix with the corresponding eigenvalues placed on the diagonals. Recall that every eigenvector v_i satisfies this linear equation $Mv_i = \lambda_i v_i$, where $\lambda_i = \Lambda_{ii}$ is an eigenvalue of M. Proof by induction that for such a matrix the product $\prod_{i=1}^n M$ can be represented as: $M^n = Q\Lambda^n Q^{-1}$.
 - (c) Consider the weight matrix $\begin{bmatrix} 0.58 & 0.24 \\ 0.24 & 0.72 \end{bmatrix}$. Its eigendecomposition is:

$$W = Q\Lambda Q^{-1} = \begin{bmatrix} 0.8 & -0.6 \\ 0.6 & 0.8 \end{bmatrix} \begin{bmatrix} 0.4 & 0 \\ 0 & 0.9 \end{bmatrix} \begin{bmatrix} 0.8 & 0.6 \\ -0.6 & 0.8 \end{bmatrix}$$

Calculate W^{30} . What do you observe? What happens in general if the absolute value of all eigenvalues of W is smaller than 1? What happens if the absolute value of any eigenvalue of W is larger than 1? What if all eigenvalues are 1?

3 Exercise 3: LSTMs

Recall the elements of a module in an LSTM and the corresponding computations, where ⊙ stands for pointwise multiplication. For a good explanation on LSTMs you can refer to http://colah.github.io/posts/2015-08-Understanding-LSTMs/. Consider the LSTM in Figure 2.

- (a) What do the gates f_t , i_t and o_t do?
- (b) Which of the quantities next to the figure are always positive?

Let's now try to understand how this architecture approaches the vanishing gradients problem. To calculate the gradient $\frac{\partial L}{\partial \theta}$, where θ stands for the parameters (W_f, W_o, W_i, W_c) , we now have to consider the cell state C_t instead of h_t . Like h_t in normal RNNs, C_t will also depend on the previous cell states C_{t-1}, \ldots, C_0 , so we get a formula of the form:

$$\frac{\partial L}{\partial W} = \sum_{t=0}^{T} \sum_{k=1}^{t} \frac{\partial L}{\partial C_t} \frac{\partial C_t}{\partial C_k} \frac{\partial C_k}{\partial W},$$

where note that the real formula is a bit more complicated since C_t also depends on f_t , i_t and \tilde{C}_t , which in turn all depend on W, but this can be neglected.

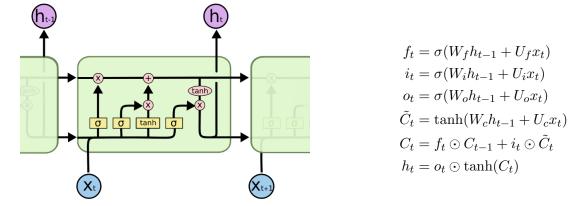


Figure 2: A Long Short Term Memory network.

(c) We know that $\frac{\partial C_t}{\partial C_k} = \prod_{i=k+1}^t \frac{\partial C_t}{\partial C_{t-1}}$. Let $f_t = 1$ and $i_t = 0$ such that $C_t = C_{t-1}$ for all t. What is the gradient $\frac{\partial C_t}{\partial C_k}$ in this case?