

## Chapter 6: Searching (Cont.)

## Searching by Elimination

Given:

- a finite set  $W$
- a boolean function  $S$  on  $W$ , such that  $S.w$  holds for some  $w \in W$

derive a program with the following post-condition.

$$S.x$$

Note: if  $S$  is identified with  $\{x \in W \mid S.x\}$ , then the post-condition can be written as

$$R: S \cap \{x\} \neq \emptyset.$$

What is a suitable invariant?

Generalization of the post-condition:

$$R: S \cap \underline{\{x\}} \neq \{\}.$$

gives as invariant

$$P: S \cap \underline{V} \neq \emptyset \wedge \underline{V \subseteq W}$$

which is established by  $V := W$ .

This leads to the following program scheme:

```
{ $S \cap W \neq \emptyset$ }  
 $V := W$ ;  
{invariant:  $S \cap V \neq \emptyset \wedge V \subseteq W$ , bound:  $|V|$ }  
do  $|V| \neq 1 \rightarrow$   
    decrease  $|V|$  under invariance of  $P$   
od;  
 $x :=$  the unique element of  $V$ 
```

Searching by elimination:

```

{ $S \cap W \neq \emptyset$ }
 $V := W$ ;
{invariant:  $S \cap V \neq \emptyset \wedge V \subseteq W$ , bound:  $|V|$ }
do  $|V| \neq 1 \rightarrow$ 
    choose  $a$  and  $b$  in  $|V|$  such that  $a \neq b$ 
    { $a \in V \wedge b \in V \wedge a \neq b \wedge S \cap V \neq \emptyset$ }
    if  $B_0 \rightarrow V := \underline{V \setminus \{a\}}$ 
    []  $B_1 \rightarrow V := \underline{V \setminus \{b\}}$ 
fi
od;
 $x :=$  the unique element of  $V$ 

```

What are  $B_0$  and  $B_1$ ?

$B_0$  and  $B_1$  should be the conditions keeping invariants, i.e.,

$$B_0 \Rightarrow (S \cap V \neq \emptyset \Rightarrow S \cap (V \setminus \{a\}) \neq \emptyset)$$

$$B_1 \Rightarrow (S \cap V \neq \emptyset \Rightarrow S \cap (V \setminus \{b\}) \neq \emptyset)$$

How to calculate out  $B_0$  and  $B_1$ ?

From the calculation

$$\begin{aligned}
 S \cap V \neq \emptyset &\Rightarrow S \cap (V \setminus \{a\}) \neq \emptyset \\
 &\equiv \{a \in V\} \\
 S.a \vee (S \cap (V \setminus \{a\})) \neq \emptyset &\Rightarrow S \cap (V \setminus \{a\}) \neq \emptyset \\
 &\equiv \{ \text{predicate calculus} \} \\
 S.a \Rightarrow S \cap (V \setminus \{a\}) \neq \emptyset \\
 &\Leftarrow \{b \in V \setminus \{a\}\} \\
 S.a \Rightarrow S.b \\
 &\equiv \{ \text{predicate calculus} \} \\
 &\equiv \neg S.a \vee S.b
 \end{aligned}$$

we may have

$$B_0 = \neg S.a \vee S.b.$$

And similarly we may have

$$B_1 = \neg S.b \vee S.a.$$

So we obtain the program:

```

{ $S \cap W \neq \emptyset$ }
 $V := W$ ;
{invariant:  $S \cap V \neq \emptyset \wedge V \subseteq W$ , bound:  $|V|$ }
do  $|V| \neq 1 \rightarrow$ 
    choose  $a$  and  $b$  in  $|V|$  such that  $a \neq b$ 
    { $a \in V \wedge b \in V \wedge a \neq b \wedge S \cap V \neq \emptyset$ }
    if  $\neg S.a \vee S.b \rightarrow V := \underline{V \setminus \{a\}}$ 
    []  $\neg S.b \vee S.a \rightarrow V := \underline{V \setminus \{b\}}$ 
fi
od;
 $x :=$  the unique element of  $V$ 

```



A special case when  $W = [0..N]$ . We may choose  $V$  can be represented by two integers  $a$  and  $b$  as  $[a..b]$ , and the program becomes

```
{(∃i : 0 ≤ i ≤ N : S.i)}  
a, b := 0, N;  
do a ≠ b →  
  if ¬S.a ∨ S.b → a := a + 1  
  □ ¬S.b ∨ S.a → b := b - 1  
fi  
od;  
x := a;
```

## Application 1:

Derive a program that satisfies

```
[[  
  con  $N : int \{N \geq 0\}; b : array [0..N]$  of int;  
  var  $x : int$ ;  
  max location  
   $\{0 \leq x \leq N \wedge f.x = (\max i : 0 \leq i \leq N : f.i)\}$   
  ]]  
   $\{S.x\}$ 
```

How to make use of “Searching by Elimination” to solve this problem?

The post-condition can be rewritten as

$$R: 0 \leq x \leq N \wedge (\forall i: 0 \leq i \leq N: f.i \leq f.x)$$

and we can define  $S$  as

$$S.x \equiv (\forall i: 0 \leq i \leq N: f.i \leq f.x)$$

What is a sufficient condition for  $\neg S.a \vee S.b$ ?

Since

$$\begin{aligned}
 & \neg S.a \vee S.b \\
 \equiv & \{ \text{predicate calculus} \} \\
 & S.a \Rightarrow S.b \\
 \equiv & \{ \text{definition of } S \} \\
 & (\forall i : 0 \leq i \leq N : f.i \leq f.a) \Rightarrow (\forall i : 0 \leq i \leq N : f.i \leq f.b) \\
 \Leftarrow & \{ \text{transitivity of } \leq \} \\
 & f.a \leq f.b
 \end{aligned}$$

we have

$$f.a \leq f.b \Rightarrow \neg S.a \vee S.b$$

Similarly, we can derive

$$f.b \leq f.a \Rightarrow \neg S.b \vee S.a$$

Our solution:

```
var  $a, b$  : int;  
 $a, b$  := 0,  $N$ ;  
do  $a \neq b \rightarrow$   
    if  $f.a \leq f.b \rightarrow a := a + 1$   
    □  $f.b \leq f.a \rightarrow b := b - 1$   
fi  
od;  
 $x := a$ ;
```

## Application 2: The Celebrity Problem

Design a program to compute a *celebrity* among  $N + 1$  persons. A person is a celebrity if he is known by everyone but does not know anyone.

```

||
con  $N : int \{N \geq 0\}; k : \mathbf{array} [0..N] \times [0..N] \mathbf{of} bool;$ 
 $\{(\exists i : 0 \leq i \leq N : (\forall j : j \neq i : k.j.i \wedge \neg k.i.j))\}$ 
var  $x : int;$ 
celebrity
 $\{0 \leq x \leq N \wedge (\forall j : j \neq x : k.j.x \wedge \neg k.x.j)\}$ 
||

```

Here  $k.i.j$  denotes  $i$  knows  $j$ .

We could consider the set  $W$  as  $[0..N]$ . What is  $S$ ?

We choose

$$S.x \equiv (\forall j : j \neq x : k.j.x \wedge \neg k.x.j)$$

We then derive

$$\begin{aligned}
 & \neg S.a \vee S.b \\
 \Leftarrow & \{ \text{predicate calculus} \} \\
 & \neg S.a \\
 \equiv & \{ \text{definition of } S \} \\
 & \neg(\forall j : j \neq a : k.j.a \wedge \neg k.a.j) \\
 \equiv & \{ \text{De Morgan} \} \\
 & (\exists j : j \neq a : \neg k.j.a \vee k.a.j) \\
 \Leftarrow & \{ b \neq a \} \\
 & \neg k.b.a \vee k.a.b
 \end{aligned}$$

We thus obtain the following program:

```
{ $(\exists i : 0 \leq i \leq N : S.i)$ }  
 $a, b := 0, N$ ;  
do  $a \neq b \rightarrow$   
  if  $\neg k.b.a \vee k.a.b \rightarrow a := a + 1$   
     $\square \neg K.a.b \vee K.b.a \rightarrow b := b - 1$   
  fi  
od;  
 $x := a$ ;
```



## Exercises

### Problem 7: The Starting Pit Location Problem

Given are  $N + 1$  pits located along a circular racetrack. The pits are numbered clockwise from 0 up to and including  $N$ . At pit  $i$ , there are  $p.i$  gallons of petrol available. To race from pit  $i$  to its clockwise neighbor one needs  $q.i$  gallons of petrol. One is asked to design a linear algorithm to determine a pit from which it is possible to race a complete lap, starting with an empty fuel tank. To guarantee the existence of such a starting pit, we assume that

$$(\Sigma i : 0 \leq i \leq N : p.i) = (\Sigma i : 0 \leq i \leq N : q.i).$$