The magnetosphere structure of a Kerr black hole: marginally force-free equatorial boundary condition

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The role of equatorial boundary condition in the structure of a force-free black hole magnetosphere was rarely discussed, since previous studies have been focused on the field lines entering the horizon. However, recent high-accuracy general relativistic (GR) force-free electrodynamics (FFE) simulations [1] show that there are both field lines entering the horizon and field lines ending up on the equatorial current sheet within the ergosphere for asymptotic uniform field configuration. For the latter, the equatorial boundary condition is well approximated being marginally force-free, i.e., $B^2 - E^2 \approx 0$, where B and E are the magnetic and electric field strength, respectively. In this paper, we revisit the uniform field solution to the Kerr BH magnetosphere structure and investigate the role of the marginally force-free equatorial boundary condition. We find this boundary condition plays an important role in shaping the BH magnetosphere in various aspects, including the shape of the light surface, the near-horizon field line configuration and the source of the Poynting flux. We also propose an algorithm for numerically solving the GR Grad-Shafranov equation and selfconsistently imposing the marginally force-free equatorial condition. As a result, we find a good agreement between our numerical solutions and the high-accuracy FFE simulations. We also discuss the applicability of the marginally force-free boundary condition and the numerical algorithm for general magnetic field configurations.

I. INTRODUCTION

The Blandford-Znajek (BZ) mechanism [2] is believed to be one of most efficient ways to extract rotation energy from spinning black holes (BHs), which operates in BH systems on all mass scales, from the stellar-mass BHs of gamma-ray bursts to the supermassive BHs of active galactic nuclei. In the past decade, we have studied the BZ mechanism from different approaches and the cross-check among these different approaches has facilitate substantial progress in understanding the underlying detailed physics. Taking the simple monopole magnetic field configuration as an example, the solutions obtained from different approaches are in quantitative agreement, see e.g. [3–6] for general relativistic magnetohydrodynamic simulations, [7–13] for analytic solutions and [14–16] for numerical solutions.

But for other magnetic field configurations, there is no such good agreement, e.g., different approaches do not even reach a consensus on the solution uniqueness for the uniform field configuration. Several force-free electrodynamics (FFE) simulation [5, 17–22] have been done and the BH magnetospheres in these simulations all settle down to a steady state with similar final field configuration, which is an indicator for solution uniqueness. However, a family of analytic solutions were presented for slowly spinning BHs, and no instability mode was found for any of these solutions [21]. Therefore the solution stability is not likely the explanation for the solution uniqueness.

From the viewpoint of numerical solutions, the structure of a BH magnetosphere in axisymmetric and steady

state is governed by the Grad-Shafranov (GS) equation, which is a second-order differential equation of the magnetic flux $A_{\phi}(r,\theta)$, with two eigenfunctions $I(A_{\phi})$ and $\Omega(A_{\phi})$ to be determined. For common field configurations, the two eigenfunctions are determined by requiring the magnetic field line smoothly cross the light surfaces (LSs), where the GS equation degrades to be first-order. But for the uniform field configuration, there exits only one LS, which is insufficient for determining the two eigenfunctions. Following this argument, there should exist infinitely many solutions [15].

To explain the discrepancy about the solution uniqueness from different approaches, Pan et.al. [23] proposed that the two eigenfunctions are connected by the radiation condition at infinity instead of being independent, which was readily confirmed by recent FFE simulations done by East and Yang [1]. In addition, there are other interesting features in the structure of the BH magnetosphere showing up in the simulations, e.g., an equatorial current sheet naturally develops with the ergosphere, and the magnetic dominance marginally loses on the current sheet, i.e. $B^2 - E^2 \approx 0$. Motivated by these simulations, we revisit the uniform field solution and investigate the role of the marginally force-free equatorial boundary condition in the BH magnetosphere structure. We find the qualitative properties of the BH magnetosphere structure are attributed to the marginally forcefree equatorial boundary condition without invoking the GS equation. We also propose an algorithm for numerically solving the GS equation and consistently imposing the the marginally force-free equatorial boundary condition. As a result, we find our numerical solutions are in good agreement with the FFE simulations.

The paper is organized as follows. In Section II, we outline the basic governing equations. In Section III,

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we clarify the radiation condition, boundary conditions and numerical algorithm for the uniform field solution. In Section IV, we generalize the discussion to more field configurations. Summary is given in Section V.

II. BASIC EQUATIONS

In this paper, we adopt the Kerr-Schild coordinate with the line element

$$ds^{2} = -\left(1 - \frac{2r}{\Sigma}\right)dt^{2} + \left(\frac{4r}{\Sigma}\right)drdt + \left(1 + \frac{2r}{\Sigma}\right)dr^{2}$$
$$+ \Sigma d\theta^{2} - \frac{4ar\sin^{2}\theta}{\Sigma}d\phi dt - 2a\left(1 + \frac{2r}{\Sigma}\right)\sin^{2}\theta d\phi dr$$
$$+ \frac{\beta}{\Sigma}\sin^{2}\theta d\phi^{2}$$

where $\Sigma = r^2 + a^2\mu^2$, $\Delta = r^2 - 2r + a^2$, $\beta = \Delta\Sigma + 2r(r^2 + a^2)$, and a is the dimensionless BH spin. In the force-free approximation, electromagnetic energy greatly exceeds that of matter. Consequently, the force-free magnetospheres is governed by energy conservation equation of electromagnetic field, or conventionally called as the GS equation. In the Kerr spacetime, the axisymmetric and steady GS equation can be written in a compact form [23]

$$\left[A_{\phi,rr} + \frac{\sin^2 \theta}{\Delta} A_{\phi,\mu\mu}\right] \mathcal{K}(r,\theta;\Omega)
+ \left[A_{\phi,r} \partial_r^{\Omega} + \frac{\sin^2 \theta}{\Delta} A_{\phi,\mu} \partial_{\mu}^{\Omega}\right] \mathcal{K}(r,\theta;\Omega)
+ \frac{1}{2} \left[A_{\phi,r}^2 + \frac{\sin^2 \theta}{\Delta} A_{\phi,\mu}^2\right] \Omega' \partial_{\Omega} \mathcal{K}(r,\theta;\Omega)
- \frac{\Sigma}{\Delta} II' = 0 ,$$
(1)

where the LS function

$$\mathcal{K}(r,\theta;\Omega) = \frac{\beta}{\Sigma} \Omega^2 \sin^2 \theta - \frac{4ra}{\Sigma} \Omega \sin^2 \theta - \left(1 - \frac{2r}{\Sigma}\right), (2)$$

 $\mu \equiv \cos \theta$, and the primes designate derivatives with respect to A_{ϕ} . $\partial_i^{\Omega}(i=r,\mu)$ denotes the partial derivative with respect to coordinate i with Ω fixed, and ∂_{Ω} is the derivative with respect to Ω .

III. UNIFORM FIELD SOLUTION

A. Solution uniqueness and radiation condition

For common field configurations, there exists two LSs where the LS function vanishes and the GS equation degrades from second order to first order. As proposed by Contopoulos et.al. [14], one can adjust the two eigenfunctions $\Omega(A_{\phi})$ and $I(A_{\phi})$ enabling field lines smoothly cross the two LSs, then the solution $\{\Omega(A_{\phi}), I(A_{\phi}), A_{\phi}(r, \theta)\}$

is uniquely found. But for the vertical field lines, their exists only one LS, which is insufficient for determining two eigenfunctions. Therefore many solutions are expected [15, 16], but the many-solutions scenario is in conflict with several previous FFE simulations [5, 17–22]. To tackle this problem, Pan et. al. [23, 24] proposed that the two eigenfunctions are not independent; instead, they are related by the radiation condition at infinity

$$I = 2\Omega A_{\phi},\tag{3}$$

which has been readily confirmed by recent high-accuracy FFE simulations [1]. Combining with suitable boundary conditions, we expect a unique uniform field solution as indicated by the previous FFE simulations.

B. Boundary conditions

The boundary conditions at infinity (inner infinity $r = r_+$ and outer infinity $r \to \infty$) and on the polar axis can be simply set as

$$A_{\phi,r}|_{r=r_{+},\infty} = 0,$$

 $A_{\phi}|_{\mu=1} = 0,$ (4)

where r_+ is the radius of the event horizon, while the equatorial boundary condition is more uncertain until recent simulations [1] come out which show that there exists an equator current sheet within the ergosphere where the magnetic dominance marginally loses, i.e., $B^2 - E^2 \approx 0$. Motivated by the simulation results, we choose the following equatorial boundary condition in our numerical solutions,

$$A_{\phi,\mu}(\mu = 0, r > 2) = 0,$$
 (5a)

$$B^2 - E^2(\mu = 0, r_+ \le r \le 2) = 0.$$
 (5b)

In fact, Equation (5b) is neither a Dirichlet nor a Neumann boundary condition, since

$$\begin{split} &B^2 - E^2 \\ &= \frac{1}{\sum \sin^2 \theta} \left[-\mathcal{K} \left(A_{\phi,r}^2 + \frac{\sin^2 \theta}{\Delta} A_{\phi,\mu}^2 \right) + \frac{\Sigma}{\Delta} I^2 \right], \end{split} \tag{6}$$

which involves both derivatives $A_{\phi,\mu}$ and $A_{\phi,r}$ on the boundary. As we will see later, it is numerically non-trivial to impose this boundary condition in computation.

We note a coordinate singularity $1/\Delta$ in the expression of B^2-E^2 . To avoid possible numerical difficulty, we use the prescription

$$\int_{A_{\phi}^{\rm HE}}^{A_{\phi}^{\rm EE}} \left(\frac{B^2 - E^2}{B^2 + E^2} \right)^2 dA_{\phi} / \left(A_{\phi}^{\rm EE} - A_{\phi}^{\rm HE} \right) < 10^{-3}, (7)$$

in our computation, as a proxy of the marginally force-free equatorial boundary condition (5b), where $A_{\phi}^{\rm HE}$ and $A_{\phi}^{\rm EE}$ are the magnetic flux enclosed by the horizon and

by the ergosphere, respectively; "HE" and "EE" are short for Horizon-Equator and Ergosphere-Equator, respectively. For definiteness, we choose $B^2 + E^2$ to be the energy density measured by zero-angular-momentum-observers. Explicitly, we have

$$B^{2} + E^{2}$$

$$= \frac{1}{\sum \sin^{2} \theta} \left[\left(\mathcal{K} + \frac{\Delta \Sigma}{\beta} \right) \left(A_{\phi,r}^{2} + \frac{\sin^{2} \theta}{\Delta} A_{\phi,\mu}^{2} \right) + \frac{\Sigma}{\Delta} I^{2} \right]. \tag{8}$$

C. Generic properties of the BH magnetosphere structure

Before delving into the details of numerically solving the GS equations, here we point out that from the radiation condition (3) and the marginally force-free boundary condition (5b) themselves contain rich information about the BH magnetosphere structure.

Let's first find out where the LS intersects with the equator, $r_{\rm LS}|_{\mu=0}$. From the expression of the LS function (2), it is straightforward to see $r_{\rm LS}|_{\mu=0} \leq 2$ for $\Omega \geq 0$. On this point, the LS function \mathcal{K} vanishes, and I must also vanish for satisfying the boundary condition (5b), which in turns indicates a vanishing angular velocity Ω from the radiation condition (3). Due to the frame-dragging effect, Ω must be non-zero inside the ergosphere. Therefore the only possibility is $r_{\rm LS}|_{\mu=0}=2$, i.e. to satisfy the boundary condition (5b), the LS must intersect the equator at r=2, which also justifies our choice of equatorial boundary conditions (5a,5b).

From above analysis, we expect several generic features in the magnetospheres that are independent of the GS equation: (1) the LS runs from $r=r_+$ to r=2 as θ varies from 0 to $\pi/2$, (2) since I vanishes at $r_{\rm LS}|_{\mu=0}$, we expect no current sheet within the magnetosphere except the equatorial current sheet extending from r_+ to 2, which gives rise to a cusp $(A_{\phi,\mu} \neq 0)$ to the equatorial magnetic field lines, (3) magnetic field lines entering the ergosphere end up either on the horizon or on the equatorial current sheet, both of which carry electric current and therefore Poynting flux.

With the guidance of the qualitative properties above, we now proceed to numerically solve the GS equation and quantify these properties.

D. Numerical method

In our computation, we define a new radial coordinate R = r/(1+r), confine our computation domain $R \times \mu$ in the region $[R(r_+), 1] \times [0, 1]$, and implement a uniform 512×64 grid. We aim to find a pair of $\Omega(A_\phi)$ and $I(A_\phi)$ satisfying the radiation condition (3) and enabling field lines smoothly crossing the LS, and suitable normal derivative $A_{\phi,\mu}(\mu=0,r_+\leq r\leq 2)$ on the equator guaranteeing the boundary condition (5b).

The numerical algorithm of searching for the desired eigenfunctions and the equatorial boundary condition $\{\Omega(A_{\phi}), I(A_{\phi}), A_{\phi,\mu}(\mu = 0, r_{+} \leq r \leq 2)\}$ is detailed in the following steps.

1. We choose an initial guess for the field configuration, eigenfunctions $\{\Omega(A_{\phi}), I(A_{\phi})\}$ and equatorial boundary condition as follows

$$A_{\phi} = \frac{B_0}{2} r^2 \sin^2 \theta, \tag{9a}$$

$$\Omega = 0.5\Omega_{\rm H} \left(1 - A_{\phi} / A_{\phi}^{\rm HE} \right), \quad (9b)$$

$$I = \Omega_{\rm H} A_{\phi} \left(1 - A_{\phi} / A_{\phi}^{\rm HE} \right), \quad (9c)$$

$$A_{\phi,\mu}(\mu = 0, r_{+} \le r \le 2) = -(r/r_{+})^{3},$$
 (9d)

where $\Omega_{\rm H} = a/2r_+$ is the angular velocity of the BH.

- 2. We evolve the GS equation (1) using the well-known relaxation method [25] and adjust $II'(A_{\phi})$ until field lines smoothly cross the LS [see e.g. 14–16, 23, for more details].
- 3. Usually the current I found in Step 2 neither satisfies the radiation condition (3) nor guarantees the boundary condition (5b). We adjust $A_{\phi,\mu}(\mu=0,r_+\leq r\leq 2)$ as follows

$$A_{\phi,\mu}|_{\text{new}} = A_{\phi,\mu}|_{\text{old}} + \zeta_1 \times [2\Omega A_{\phi}(2\Omega A_{\phi})' - II'], \quad (10)$$

where ζ_1 is an empirical step size. For each new $A_{\phi,\mu}$, we repeat Step 2 and iterative correction (10) until $A_{\phi,\mu}(\mu=0,r_+\leq r\leq 2)$ converges, i.e. the condition $2\Omega A_{\phi}(2\Omega A_{\phi})'=II'$ is achieved for $A_{\phi}\in (A_{\phi}^{\mathrm{HE}},A_{\phi}^{\mathrm{EE}})$.

4. The remaining task is to adjust $\Omega(0 < A_{\phi} < A_{\phi}^{\rm HE})$ enabling the radiation condition (3) for $A_{\phi} \in (0, A_{\phi}^{\rm HE})$ and to adjust $\Omega(A_{\phi}^{\rm HE} \leq A_{\phi} \leq A_{\phi}^{\rm EE})$ enabling the boundary condition (5b) for $A_{\phi} \in (A_{\phi}^{\rm HE}, A_{\phi}^{\rm EE})$. The first part is straightforward, i.e.,

$$2A_{\phi}\Omega_{\text{new}} = I|_{0 < A_{\phi} < A_{\phi}^{\text{HE}}},\tag{11}$$

and the second part can be realized by iterative correction

$$2A_{\phi}(\Omega_{\text{new}} - \Omega_{\text{old}}) = -\zeta_2 \times \Delta(B^2 - E^2)|_{\mu=0, r_+ \le r \le 2},$$
 (12)

where ζ_2 is again an empirical step size, and we have multiplied factor Δ in the correction term to avoid numerical difficulty in the vicinity of the event horizon. To eliminate unphysical discontinuity in the angular velocity at $A_{\phi}^{\rm HE}$, we fit $\Omega_{\rm new}(A_{\phi})$ on the whole range $(0, A_{\phi}^{\rm EE})$ via a fifth-order polynomial.

5. For the new angular velocity $\Omega_{\text{new}}(A_{\phi})$ obtained in Step 4, we repeat Step 2 to Step 4, until both the radiation condition (3) and the numerical prescription (7) for the boundary condition (5b) is satisfied.

E. Numerical results

In Figure 1, we plot the magnetic field lines enclosing a BH with spin a = 0.99 as an example, which explicitly

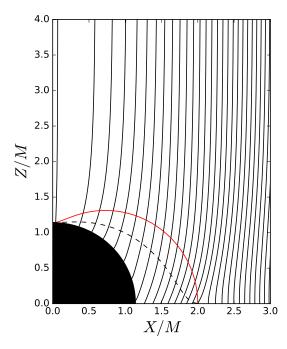


FIG. 1. The configuration of field lines for the magnetosphere of a Kerr BH with spin a=0.99, where the solid/red line is the ergosphere and the dashed/black line is the LS, both of which intersect with the equator at r=2M.

displays the features we anticipated in Section III C and agrees with the simulation results in detail [1].

In Figure 2, we show the angular velocity function $\Omega(A_{\phi})$ for different BH spins and compare it with the counterpart obtained from the simulations [1]. For reference, we also plot the leading-order analytic solution in the slow-rotation limit [1, 11, 26, 27],

$$\Omega = \Omega_{\rm H} \frac{\sqrt{1 - \psi}}{1 + \sqrt{1 - \psi}},\tag{13}$$

where $\psi = A_\phi/(2B_0M^2)$. From our numerical solutions, we find the magnetic flux entering the ergosphere $A_\phi^{\rm EE}$ increases with the BH spin and approaches $2.75B_0M^2$ for extremal spins (upper panel of Figure 2), which is about $\approx 5\%$ lower than the simulation result (Figure 3 in Ref. [1]), while the angular velocity Ω as a function of normalized magnetic flux $A_\phi/A_\phi^{\rm EE}$ is in agreement with the simulation results to high precision.

With the angular velocity $\Omega(A_{\phi})$ obtained, the energy extraction rate from the BH is given by

$$\dot{E} = 4\pi \int_0^{A_\phi^{\rm EE}} \Omega \times I \ dA_\phi. \tag{14}$$

It is straightforward to obtain the energy extraction rate in the slow-rotation limit

$$\dot{E} = 128\pi \left(\frac{17}{24} - \ln 2\right) B_0^2 M^4 \Omega_{\rm H}^2. \tag{15}$$

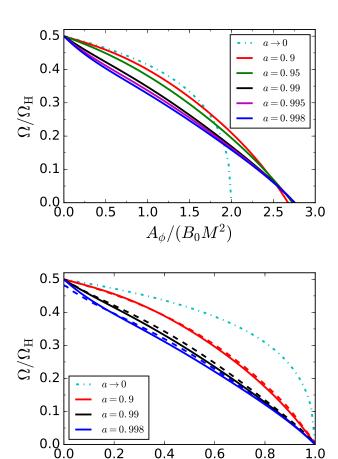


FIG. 2. Upper panel: the angular velocity $\Omega(A_{\phi})$ for different BH spins obtained from our numerical solutions. Lower Panel: comparison of our numerical results (solid lines) with the simulation results of Ref.[1] (dashed lines). For reference, we also plot the leading order analytic solution in dash-dotted lines.

 $A_{\phi}/A_{\phi}^{\,\mathrm{EE}}$

In Figure 3, we compare the energy extraction rate $\dot{E}(\Omega_{\rm H})$ derived from our numerical solutions with East and Yang's simulation results [1], where the data points are taken from either the simulations or our numerical solutions, while the solid lines are corresponding polynomial fitting curves which we require to approach Equation (15) for small spins and to be flat for extremal spins. As expected, our energy extraction rate $\dot{E}(\Omega_{\rm H})$ is $\approx 10\%$ lower than the corresponding simulation results, due to the $\approx 5\%$ smaller magnetic flux $A_{\phi}^{\rm EE}$.

To summarize, the uniform field solution is indeed unique as double confirmed by the high-accuracy FFE simulations and by our numerical solutions, where the radiation condition and the marginally force-free equatorial boundary condition largely shape the structure of the BH magnetosphere.

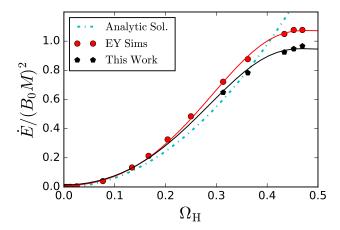


FIG. 3. Comparison of the energy extraction rates $\dot{E}(\Omega_{\rm H})$ obtained from three different approaches: the leading-order analytic solution (15), our numerical solutions and the high-resolution force-free simulations [1].

IV. DISCUSSION

A. Application to general field configurations

In real astrophysical environment, we expect the field lines far away from the central BH are more close to parabolas instead of being strictly vertical. In several previous studies of such field configurations [e.g. 15, 16, 28], due to lacking knowledge of the equatorial boundary condition, the equator within the ergosphere was intentionally excluded out of the computation domain by manually introducing a "wall" extending from the horizon-equator intersection to infinity. Such simplification obviously misses magnetic field lines rooting on the equatorial current sheet, which contribute about half of the total BZ flux for extremal spins in the case of uniform field configuration.

Due to the resemblance of near-horizon field lines in the two cases, it is reasonable to expect an equatorial current develops within the ergosphere, where the magnetic dominance loses, therefore the marginally force-free boundary condition (5b) should also be a good work approximation for studying the BH magnetosphere structure with parabolic magnetic field lines. It is straightforward to solve the GS equation and self-consistently impose the marginally force-free boundary condition following the algorithm detailed in Section III D.

Though we do not numerically solve the GS equation for the general parabolic field configurations, the qualitative properties we summarized in Section III C also apply here, since these properties are the consequence of the radiation condition and the marginally force-free equatorial boundary condition, while the GS equation only serves to quantify them.

B. Near-horizon magnetic field lines

In a previous study [24], we made a claim that "in the steady axisymmetric force-free magnetosphere around a Kerr BH, all magnetic field lines that cross the infinite-redshift surface must intersect the event horizon". This claim is based on the radiation condition

$$I = \Omega \times \mathcal{F}(A_{\phi}), \tag{16}$$

and the assumption of no current sheet within the ergosphere, where the function $\mathcal{F}(A_\phi)$ is of $\mathcal{O}(A_\phi)$ and is field configuration dependent. The basic logic for obtaining the claim is as follows. Ω must be nonzero for all field lines entering the ergosphere due to the frame-dragging effect; as a result, I must be nonzero for these field lines according to the radiation condition. If there is field line entering the ergosphere and crossing the equator, the electric current either flows towards the equator from both the +z and -z side, or flows away from the equator to infinity in both the +z and -z direction. For each case, the charge conservation is violated if there exists no equatorial current sheet.

However, the FFE simulations show that an equatorial current sheet inevitably develops within the ergosphere, where the force-free condition breaks down. Therefore the above claim should be generalized as "in the steady axisymmetric force-free magnetosphere around a Kerr BH, all magnetic field lines that cross the infinite-redshift surface must intersect the event horizon or end up on the equatorial current sheet". Specifically, this claim excludes the existence of field lines entering the ergosphere and crossing the equator vertically.

V. SUMMARY

In the force-free limit, the structure of steady and axisymmetric BH magnetosphere is governed by the GS equation, which is a second-order differential equation about the magnetic flux A_{ϕ} , with two eigenfunctions $\Omega(A_{\phi})$ and $I(A_{\phi})$ to be determined. For common field configurations, there exists two LSs on which the GS equation degrades to be first-order, and the two eigenfunctions are determined by the requirement that magnetic field lines should smoothly cross the two LSs. For the uniform field configuration, there is only one LS, which is insufficient for determine both $\Omega(A_{\phi})$ and $I(A_{\phi})$. Therefore the solution uniqueness of the uniform field configuration has been a controversial problem. To tackle this problem, we proposed that the two functions are related by the radiation condition (3), instead of being independent [23], which was readily confirmed by recent high-accuracy FFE simulations [1]. In these simulations, an equatorial current sheet develops within the ergosphere and the magnetic dominance marginally loses, i.e. $B^2 - E^2 \approx 0$.

Motivated by these simulations, we revisit the problem of the uniform field solution in this paper. We find the radiation condition (3) and the marginally force-free boundary condition (5b) are rather informative, which dictate the BH magnetosphere structure in various aspects, including the shape of the LS, the near-horizon field line configuration and the source of BZ flux (see Section III C for details). Other than these qualitative properties, we also propose an algorithm for numerically solving the GS equation and consistently imposing the marginally force-free equatorial boundary condition. As a result, we find a good agreement between our numerical solutions with the high-accuracy FFE simulations.

In realistic astrophysical environment, we expect the magnetic field lines far away from the central BH are more close to parabolas instead of being strictly vertical. However, we also expect the marginally force-free equatorial boundary condition to be a good working approximation for the parabolic field configurations, due to the resemblance of the near-horizon field configurations

in the two cases. Though we do not numerically solve the GS equation for the parabolic configurations in this paper, the qualitative properties of the uniform field solution summarized in Section III C also apply here, since these properties are dictated by the radiation condition and the marginally force-free boundary condition, while the GS equation only serves to quantify them.

ACKNOWLEDGMENTS

ZP was supported by the UC Davis Dissertation Year Fellowship when this work was started. This research was also supported by Perimeter Institute for Theoretical Physics. Research at Perimeter Institute is supported by the Government of Canada through the Department of Innovation, Science and Economic Development Canada and by the Province of Ontario through the Ministry of Research, Innovation and Science.

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