

Your Presentation

You

The Ohio State University

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Introduction

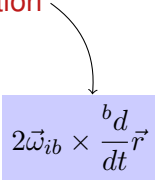
- Your introduction goes here!
- Use `itemize` to organize your main points.

Examples

Some examples of commonly used commands and features are included, to help you get started.

Rigid body dynamics

- Coriolis acceleration

$$\vec{a}_p = \vec{a}_o + \frac{{}^b d^2}{dt^2} \vec{r} + 2\vec{\omega}_{ib} \times \frac{{}^b d}{dt} \vec{r} + \vec{\alpha}_{ib} \times \vec{r} + \vec{\omega}_{ib} \times (\vec{\omega}_{ib} \times \vec{r})$$


Rigid body dynamics

- Coriolis acceleration

$$\vec{a}_p = \vec{a}_o + \frac{{}^b d^2}{dt^2} \vec{r} + \underbrace{2\vec{\omega}_{ib} \times \frac{{}^b d}{dt} \vec{r}}_{\text{Coriolis acceleration}} + \underbrace{\vec{\alpha}_{ib} \times \vec{r}}_{\text{Transversal acceleration}} + \underbrace{\vec{\omega}_{ib} \times (\vec{\omega}_{ib} \times \vec{r})}_{\text{Centrifugal acceleration}}$$

- Transversal acceleration

Rigid body dynamics

- Coriolis acceleration

$$\vec{a}_p = \vec{a}_o + \frac{{}^b d^2}{dt^2} \vec{r} + \boxed{2\vec{\omega}_{ib} \times \frac{{}^b d}{dt} \vec{r}} + \textcolor{red}{\vec{\alpha}_{ib} \times \vec{r}} + \boxed{\vec{\omega}_{ib} \times (\vec{\omega}_{ib} \times \vec{r})}$$

- Transversal acceleration

- Centripetal acceleration

Tables and Figures

- Use `tabular` for basic tables — see Table 1, for example.
- You can upload a figure (JPEG, PNG or PDF) using the files menu.
- To include it in your document, use the `includegraphics` command (see the comment below in the source code).

Item	Quantity
Widgets	42
Gadgets	13

Table: An example table.

Readable Mathematics

Let X_1, X_2, \dots, X_n be a sequence of independent and identically distributed random variables with $E[X_i] = \mu$ and $\text{Var}[X_i] = \sigma^2 < \infty$, and let

$$S_n = \frac{X_1 + X_2 + \dots + X_n}{n} = \frac{1}{n} \sum_i^n X_i$$

denote their mean. Then as n approaches infinity, the random variables $\sqrt{n}(S_n - \mu)$ converge in distribution to a normal $\mathcal{N}(0, \sigma^2)$.