

(\*calculate the equation of photon motion first\*)

(\*upper index metric, lower index momentum\*)

ClearAll["Global`\*"];

[清除全部](#)

$$g_{ij} = \left\{ \left\{ \frac{-\left((a^2 + r^2)^2 - a^2(a^2 - 2r + r^2)\sin[\theta]^2\right)}{(r^2 + a^2 \cos[\theta]^2)(a^2 - 2r + r^2)}, \theta, \theta, -\frac{2ar}{(r^2 + a^2 \cos[\theta]^2)(a^2 - 2r + r^2)} \right\}, \right. \\ \left. \left\{ \theta, \frac{a^2 - 2r + r^2}{r^2 + a^2 \cos[\theta]^2}, \theta, \theta \right\}, \left\{ \theta, \theta, \frac{1}{r^2 + a^2 \cos[\theta]^2}, \theta \right\}, \right. \\ \left. \left\{ -\frac{2ar}{(r^2 + a^2 \cos[\theta]^2)(a^2 - 2r + r^2)}, \theta, \theta, \frac{(a^2 - 2r + r^2) - a^2 \sin[\theta]^2}{(r^2 + a^2 \cos[\theta]^2)(a^2 - 2r + r^2) \sin[\theta]^2} \right\} \right\};$$

p = {pt, pr, pθ, pφ};

$$H = \frac{1}{2} (\text{Sum}[g_{ij}[[i, j]] \times p[[i]] \times p[[j]], \{i, 1, 4\}, \{j, 1, 4\}]);$$

[求和](#)

du = {td, rd, θd, φd, prd, pθd};

td = D[H, pt] // Simplify;

[偏导](#)

[化简](#)

rd = D[H, pr] // Simplify;

[偏导](#)

[化简](#)

θd = D[H, pθ] // Simplify;

[偏导](#)

[化简](#)

φd = D[H, pφ] // Simplify;

[偏导](#)

[化简](#)

prd = -D[H, r] // Simplify;

[偏导](#)

[化简](#)

pθd = -D[H, θ] // Simplify;

[偏导](#)

[化简](#)

Deom = du /.

{pt → -EE, pφ → LL, t → t[λ], r → r[λ], θ → θ[λ], φ → φ[λ], pr → pr[λ], pθ → pθ[λ]}

Print["-----Done

[打印](#)

1-----"]

$$\begin{aligned}
\text{Out}[*]= & \left\{ -\frac{-a^4 \text{EE} + 2 a \text{LL} r[\lambda] - 2 a^2 \text{EE} r[\lambda]^2 - \text{EE} r[\lambda]^4 + a^2 \text{EE} (a^2 + (-2 + r[\lambda]) r[\lambda]) \text{Sin}[\theta[\lambda]]^2}{(a^2 + (-2 + r[\lambda]) r[\lambda]) (a^2 \text{Cos}[\theta[\lambda]]^2 + r[\lambda]^2)}, \right. \\
& \frac{\text{pr}[\lambda] (a^2 + (-2 + r[\lambda]) r[\lambda])}{a^2 \text{Cos}[\theta[\lambda]]^2 + r[\lambda]^2}, \frac{\text{p}\theta[\lambda]}{a^2 \text{Cos}[\theta[\lambda]]^2 + r[\lambda]^2}, \\
& \frac{-a (a \text{LL} - 2 \text{EE} r[\lambda]) + \text{LL} \text{Csc}[\theta[\lambda]]^2 (a^2 + (-2 + r[\lambda]) r[\lambda])}{(a^2 + (-2 + r[\lambda]) r[\lambda]) (a^2 \text{Cos}[\theta[\lambda]]^2 + r[\lambda]^2)}, \\
& \left( -a^2 \text{Cos}[\theta[\lambda]]^2 (2 a^3 \text{EE} \text{LL} - 2 a \text{EE} \text{LL} r[\lambda]^2 + \text{pr}[\lambda]^2 (-2 + r[\lambda])^2 (-1 + r[\lambda]) r[\lambda]^2 - \right. \\
& \quad \text{EE}^2 (-3 + r[\lambda]) r[\lambda]^4 + a^4 (\text{pr}[\lambda]^2 (-1 + r[\lambda]) - \text{EE}^2 (1 + r[\lambda])) + \\
& \quad a^2 (-1 + r[\lambda]) (\text{LL}^2 + 2 r[\lambda] (\text{pr}[\lambda]^2 (-2 + r[\lambda]) - \text{EE}^2 r[\lambda])) + \\
& \quad r[\lambda] (-a^6 \text{EE}^2 - a^4 \text{LL}^2 + a^6 \text{pr}[\lambda]^2 + a^4 \text{p}\theta[\lambda]^2 + 3 a^4 \text{EE}^2 r[\lambda] + 2 a^3 \text{EE} \text{LL} r[\lambda] + \\
& \quad 3 a^2 \text{LL}^2 r[\lambda] - 5 a^4 \text{pr}[\lambda]^2 r[\lambda] - 4 a^2 \text{p}\theta[\lambda]^2 r[\lambda] - 2 a^4 \text{EE}^2 r[\lambda]^2 - 8 a \text{EE} \text{LL} r[\lambda]^2 - \\
& \quad 2 a^2 \text{LL}^2 r[\lambda]^2 + 8 a^2 \text{pr}[\lambda]^2 r[\lambda]^2 + 2 a^4 \text{pr}[\lambda]^2 r[\lambda]^2 + 4 \text{p}\theta[\lambda]^2 r[\lambda]^2 + \\
& \quad 2 a^2 \text{p}\theta[\lambda]^2 r[\lambda]^2 + 2 a^2 \text{EE}^2 r[\lambda]^3 + 6 a \text{EE} \text{LL} r[\lambda]^3 - 4 \text{pr}[\lambda]^2 r[\lambda]^3 - 6 a^2 \text{pr}[\lambda]^2 r[\lambda]^3 - \\
& \quad 4 \text{p}\theta[\lambda]^2 r[\lambda]^3 - a^2 \text{EE}^2 r[\lambda]^4 + 4 \text{pr}[\lambda]^2 r[\lambda]^4 + a^2 \text{pr}[\lambda]^2 r[\lambda]^4 + \text{p}\theta[\lambda]^2 r[\lambda]^4 - \\
& \quad \text{EE}^2 r[\lambda]^5 - \text{pr}[\lambda]^2 r[\lambda]^5 + \text{LL}^2 \text{Csc}[\theta[\lambda]]^2 (a^2 + (-2 + r[\lambda]) r[\lambda])^2 + \\
& \quad \left. a^2 \text{EE}^2 (a^2 + (-2 + r[\lambda]) r[\lambda])^2 \text{Sin}[\theta[\lambda]]^2) \right) / \\
& \left( (a^2 + (-2 + r[\lambda]) r[\lambda])^2 (a^2 \text{Cos}[\theta[\lambda]]^2 + r[\lambda]^2)^2 \right), \\
& \left( a^2 \text{LL}^2 \text{Cot}[\theta[\lambda]]^3 (a^2 + (-2 + r[\lambda]) r[\lambda]) + \frac{1}{2} \text{LL}^2 \text{Cot}[\theta[\lambda]] \text{Csc}[\theta[\lambda]]^2 \right. \\
& \quad (a^2 + (-2 + r[\lambda]) r[\lambda]) (-a^2 + a^2 \text{Cos}[2 \theta[\lambda]] + 2 r[\lambda]^2) - a^2 \text{Cos}[\theta[\lambda]] \\
& \quad (a^4 \text{pr}[\lambda]^2 + 4 a \text{EE} \text{LL} r[\lambda] + a^2 (-\text{LL}^2 + \text{p}\theta[\lambda]^2 - 2 \text{EE}^2 r[\lambda] + 2 \text{pr}[\lambda]^2 (-2 + r[\lambda]) r[\lambda]) + \\
& \quad \left. r[\lambda] (\text{p}\theta[\lambda]^2 (-2 + r[\lambda]) + r[\lambda] (\text{pr}[\lambda]^2 (-2 + r[\lambda])^2 - 2 \text{EE}^2 r[\lambda])) \right) \text{Sin}[\theta[\lambda]] \Big) / \\
& \left. \left( (a^2 + (-2 + r[\lambda]) r[\lambda]) (a^2 \text{Cos}[\theta[\lambda]]^2 + r[\lambda]^2)^2 \right) \right\}
\end{aligned}$$

-----Done 1-----

(\*Kerr metric\*)

ClearAll[MetricDown];

[清除全部](#)

MetricDown[a\_][{t\_, r\_,  $\theta$ \_,  $\phi$ \_}] := Module[{tt, rr,  $\theta\theta$ ,  $\phi\phi$ , t $\phi$ ,  $\Sigma$ ,  $\Delta$ },

[模块](#)

$\Sigma = r^2 + a^2 \text{Cos}[\theta]^2$ ;

$\Delta = r^2 - 2 r + a^2$ ;

tt = - (1 - (2 r) /  $\Sigma$ ) ;

rr =  $\Sigma$  /  $\Delta$ ;

$\theta\theta = \Sigma$ ;

$\phi\phi = (r^2 + a^2 + (1 / \Sigma) \times 2 a^2 r \text{Sin}[\theta]^2) \text{Sin}[\theta]^2$ ;

t $\phi$  = - (1 /  $\Sigma$ )  $\times 2 a r \text{Sin}[\theta]^2$ ;

$\begin{pmatrix} \text{tt} & \theta & \theta & \text{t}\phi \\ \theta & \text{rr} & \theta & \theta \\ \theta & \theta & \theta\theta & \theta \\ \text{t}\phi & \theta & \theta & \phi\phi \end{pmatrix}$ ;

ClearAll[MetricUp];

[清除全部](#)

⏏

```
MetricUp[a_][{t_, r_,  $\theta$ _,  $\phi$ _}] := Block[块{tt, rr,  $\theta\theta$ ,  $\phi\phi$ , t $\phi$ ,  $\Sigma$ ,  $\Delta$ },
```

$$\Sigma = r^2 + a^2 \cos[\theta]^2;$$

$$\Delta = r^2 - 2 r + a^2;$$

$$tt = -1 - \frac{2 r (r^2 + a^2)}{\Delta \Sigma};$$

$$rr = \Delta / \Sigma;$$

$$\theta\theta = 1 / \Sigma;$$

$$\phi\phi = \frac{(\Delta - a^2 \sin[\theta]^2)}{\Delta \Sigma \sin[\theta]^2};$$

$$t\phi = -2 a \frac{r}{\Delta \Sigma};$$

$$\begin{pmatrix} tt & 0 & 0 & t\phi \\ 0 & rr & 0 & 0 \\ 0 & 0 & \theta\theta & 0 \\ t\phi & 0 & 0 & \phi\phi \end{pmatrix};$$

(\*change  $\theta$  to  $\theta \sim \pi$ , change  $\psi$  to  $\theta \sim 2\pi$ \*)

```
ClearAll[WrapAngle];
```

[清除全部](#)

```
WrapAngle[a1_, a2_] := Module[{x1 = a1, x2 = a2},  
模块
```

```
While[x1 >  $\pi$ , x1 = x1 - 2  $\pi$ ];
```

[While循环](#)

```
While[x1 < - $\pi$ , x1 = x1 + 2  $\pi$ ];
```

[While循环](#)

```
If[x1 < 0, x1 = -x1; x2 = x2 +  $\pi$ ];
```

[如果](#)

```
While[x2  $\geq$  2  $\pi$ , x2 = x2 - 2  $\pi$ ];
```

[While循环](#)

```
While[x2 < 0, x2 = x2 + 2  $\pi$ ];
```

[While循环](#)

```
{x1, x2}];
```

(\*ZAMO\*)

```
ClearAll[LocalTetrads];
```

[清除全部](#)

```
LocalTetrads[pos_, metric_] := Module[{e0, e1, e2, e3, gtt, grr,  $g\theta\theta$ ,  $g\phi\phi$ , gt $\phi$ },  
模块
```

```
{gtt, grr,  $g\theta\theta$ ,  $g\phi\phi$ , gt $\phi$ } = Extract[metric, {{1, 1}, {2, 2}, {3, 3}, {4, 4}, {1, 4}}];
```

[提取](#)

```
e0 =  $\sqrt{-(g\phi\phi / (gtt g\phi\phi - gt\phi gt\phi))}$  {1, 0, 0, - (gt $\phi$  /  $g\phi\phi$ )}; (*et*)
```

```
e1 = {0, - (1 / ( $\sqrt{grr}$ )), 0, 0}; (*er*)
```

```
e2 = {0, 0, 1 / ( $\sqrt{g\theta\theta}$ ), 0}; (*e $\theta$ *)
```

```
e3 = {0, 0, 0, - (1 / ( $\sqrt{g\phi\phi}$ ))}; (*e $\phi$ *)
```

```
{e0, e1, e2, e3}];
```

(\*get the initial direction of the light and the upper index 4-velocity\*)

```
ClearAll[GetRayDirection];
```

[清除全部](#)

```
GetRayDirection[metric_, pos_, fov_, npix_][i_, j_] :=
```

```

Module[{λdot, xscr, yscr, θx, ψx, vel, e0, e1, e2, e3, κ},
  模块
  {xscr, yscr} = (2 Tan[fov / 2] / npix) (# - (1 / 2) (npix + 1)) & /@ {i, j};
  正切
  {θx, ψx} = WrapAngle[2 ArcTan[(1 / 2) (√(xscr² + yscr²))], ArcTan[-yscr, -xscr]];
  反正切
  vel = N@{Cos[θx], Sin[θx] Cos[ψx], Sin[θx] Sin[ψx]};
  余弦 正弦 余弦 正弦 正弦
  {e0, e1, e2, e3} = N@LocalTetrads[pos, metric];
  数值运算
  κ = 1;
  λdot = -κ e0 + vel[[1] e1 + vel[[2] e2 + vel[[3] e3];
  λdot];
  (*calculate the upper index 4-velocity of the disk fluid*)
  ClearAll[uDisk];
  清除全部
  uDisk[a_, r_, θ_, ϕ_] :=
  Module[{ut, ur, uϕ, Σ, Δ, guptt, guptϕ, gupϕϕ, gdowntt, gdowntϕ, gdownϕϕ, gdownrr},
    模块
    If[r > rISCO,
      如果
      (*outside the ISCO*)
      
$$u_t = N \left[ \frac{\sqrt{\frac{r^3 + a^2 (2+r)}{r (a^2 + (-2+r) r)}}}{\sqrt{1 - \frac{(a^2 - 2 a \sqrt{r} + r^2)^2}{(a^2 + (-2+r) r) (a + r^{3/2})^2}}} \right];$$

      数值运算
      ur = 0;
      
$$u_\phi = \frac{\sqrt{\frac{r^3 + a^2 (2+r)}{r (a^2 + (-2+r) r)}}}{(a + r^{3/2}) \sqrt{1 - \frac{(a^2 - 2 a \sqrt{r} + r^2)^2}{(a^2 + (-2+r) r) (a + r^{3/2})^2}}};$$

      (*inside the ISCO*)
      Σ = r²;
      Δ = r² - 2 r + a²;
      guptt = -1 -  $\frac{2 r (r^2 + a^2)}{\Delta \Sigma}$ ;
      guptϕ = -2 a  $\frac{r}{\Delta \Sigma}$ ;
      gupϕϕ =  $\frac{\Delta - a^2}{\Delta \Sigma}$ ;
      gdowntt = -(1 - (2 r) / Σ);
      gdowntϕ = -(1 / Σ) × 2 a r;
      gdownϕϕ = r² + a² + (1 / Σ) × 2 a² r;
      gdownrr = Σ / Δ;
      ut = -eISCO guptt + lISCO guptϕ;
      uϕ = -eISCO guptϕ + lISCO gupϕϕ;
    ]
  ]

```

```

ur = -  $\sqrt{\frac{\text{gdown}t t \text{ ut}^2 + 2 \text{ gdown}t \phi \text{ ut } u\phi + \text{gdown}\phi\phi \text{ u}\phi^2 + 1}{-\text{gdown}r r}}$ ;
{ut,  $\theta$ , ur,  $u\phi$ };

(*Emission profile*)
J[r_] := Exp[- $\frac{1}{2} \text{Log}[\frac{r}{\text{horizon}\theta}]^2 - 2 \text{Log}[\frac{r}{\text{horizon}\theta}]$ ];

(*numerical solve the eom of a single ray*)
ClearAll[TraceSingleRay];
TraceSingleRay[a0_, pos_, fov_, npix_][i_, j_] :=
Module[
initialConditions, sol, frame, momentum, eom, intensity = 0,
redshift = 1, redshift1 = 1, redshift2 = 1, imgorder = 0,
horizon = N@ $(1 + \sqrt{1 - a0^2})$ ;
metric = MetricDown[a0][pos];
 $\lambda$ dot = GetRayDirection[metric, pos, fov, npix][i, j];
momentum = metric. $\lambda$ dot;
{E0, L0} = {-momentum[[1]], momentum[[4]]};
idata = Join[pos, {momentum[[2]], momentum[[3]]}];
initialConditions = Thread[{t[0], r[0],  $\theta$ [0],  $\phi$ [0], pr[0], p $\theta$ [0]} == idata];
eom = Thread[{t'[ $\lambda$ ], r'[ $\lambda$ ],  $\theta$ '[ $\lambda$ ],  $\phi$ '[ $\lambda$ ], pr'[ $\lambda$ ], p $\theta$ '[ $\lambda$ ]} == Deom];
eqns = N[Join[eom, initialConditions] /. {a → a0, EE → E0, LL → L0}];
sol = NDSolve[eqns, {t, r,  $\theta$ ,  $\phi$ , pr, p $\theta$ }, { $\lambda$ , 0,  $\lambda$ F}, Method → {"EventLocator",
"Event" → {r[ $\lambda$ ] - 1.01 horizon, r[ $\lambda$ ] - 10000 horizon,  $\theta$ [ $\lambda$ ] -  $\frac{\pi}{2}$ }, "EventAction" →
{Throw[ $\lambda$ F =  $\lambda$ , "StopIntegration"], Throw[ $\lambda$ F =  $\lambda$ , "StopIntegration"],
imgorder = imgorder + 1;
If[1.01 horizon ≤ r[ $\lambda$ ] ≤ 60 horizon,
redshift = -  $\frac{1}{u\text{Disk}[a0, r[\lambda], \theta[\lambda], \phi[\lambda]] \cdot \{E0, -pr[\lambda], -p\theta[\lambda], -L0\}}$ ;
intensity = intensity + redshift3 * J[r[ $\lambda$ ]];
If[imgorder == 1, redshift1 = redshift];
If[imgorder == 2, redshift2 = redshift];
}];
{intensity, redshift1, redshift2, imgorder}];

```

```

(*Progress Indicator*)
ClearAll[MonitorParallelTable];
清除全部
MonitorParallelTable[expr_, npix_] := Module[{res, iterCount = npix2, progress = 0},
模块
  SetSharedVariable[progress];
  设置共享变量
  res = Monitor[ParallelTable[(progress++;
  监控      并行产生表格
    expr[j, i]), {i, 1, npix}, {j, 1, npix}],
    Column[{ToString@progress <> " of " <> ToString@iterCount,
列      转换为字符串      转换为字符串
      ProgressIndicator[progress, {0, iterCount}]}], Alignment -> Center]];
      进度指示器      对齐      居中
  UnsetShared[progress];
  停止共享
  res];
(*trace all rays*)
ClearAll[TraceRay];
清除全部
TraceRay[a_, pos_, fov_, npix_] :=
  MonitorParallelTable[TraceSingleRay[a, pos, fov, npix], npix];
Print["-----Done
打印
  2-----"]
-----Done 2-----

(*Begin here*)
开始
ClearAll[result]
清除全部
a0 = 0.99;
horizon0 = 1 +  $\sqrt{1 - a0^2}$ ;
(*!!ATTENTION!!*)
(*!!These three numbers should be caculated by another code!!*)
rISCO = 1.4545; lISCO = 1.56836; eISCO = 0.73597;
pos = {0, 500, 80  $\pi$  / 180, 0};
fov = 3  $\pi$  / 180;
npix = 256; (*should be even*)
AbsoluteTiming[result = TraceRay[a0, pos, fov, npix];]
绝对时间

```

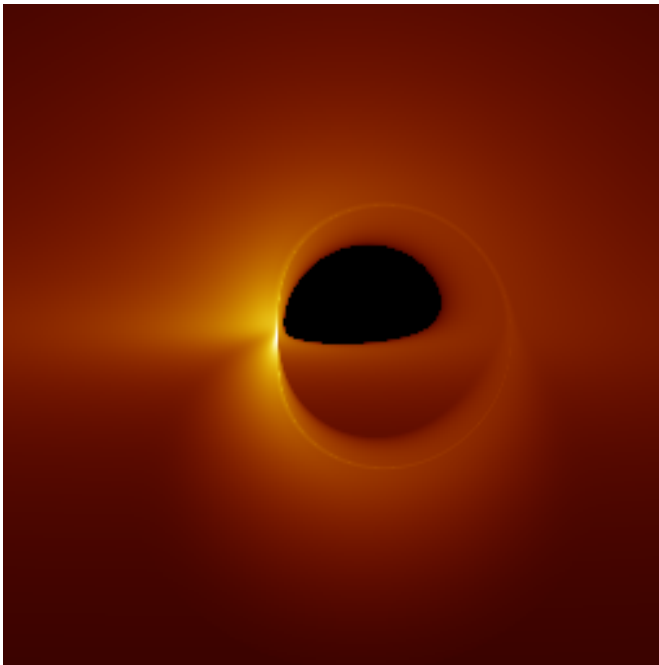
Out[ ]= {117.838, Null}

```

(*plot intensity*)
intenplot = Re@result[[All, All, 1]];
Imax = Max[intenplot];
pltint =
  MatrixPlot[intenplot, DataReversed → {True, False}, AspectRatio → 1, Frame → False,
    ColorFunction → Function[a, RGBColor[(a / Imax)1/12, (a / Imax)1/4, (a / Imax)2]],
    ColorFunctionScaling → False, PlotLegends → None]
(*GraphicsRow[{pltint, BarLegend[
  {Function[a, RGBColor[(a / Imax)1/12, (a / Imax)1/4, (a / Imax)2]], {0, Imax}}]}] *)

```

Out[ ]=

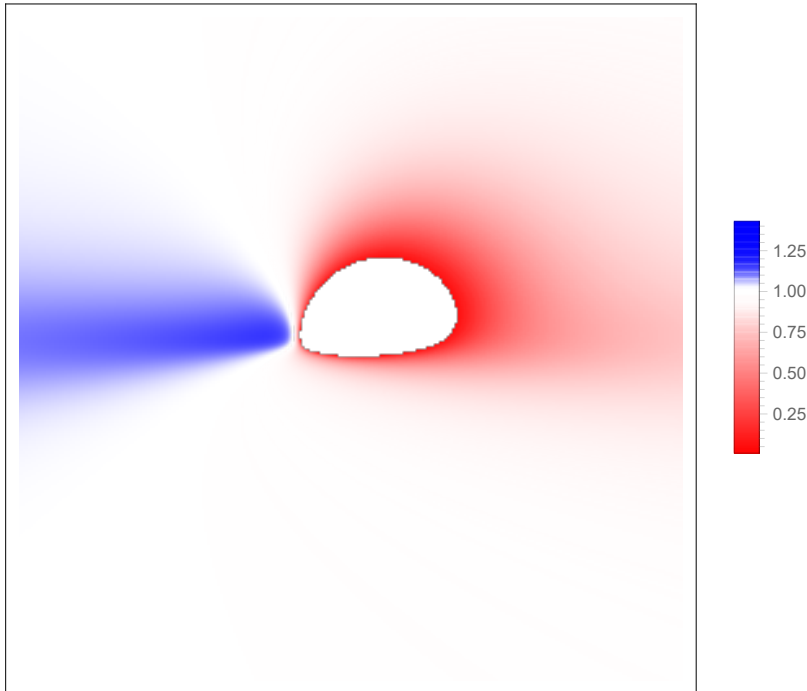


```

(*plot redshift for n=1*)
plttrs1 = ArrayPlot[Re@result[[All, All, 2]],
  \[图示数组\] \[实部\] \[全部\] \[全部\],
  DataReversed → {True, False}, PlotLegends → Automatic,
  \[数据颠倒否\] \[真\] \[假\] \[绘图的图例\] \[自动\],
  ColorFunction → Function[a, RGBColor[If[a < 1, 1, 3 * (1 - a)], If[a < 1, a, 3 * (1 - a)],
  \[颜色函数\] \[纯函数\] \[RGB颜色\] \[如果\] \[如果\],
  If[a < 1, a, 1], 1 - 1 / (1 + (a - 1) ^ 2 / 0.05)], ColorFunctionScaling → False]
\[如果\] \[颜色函数缩放\] \[假\]

```

Out[ ]=



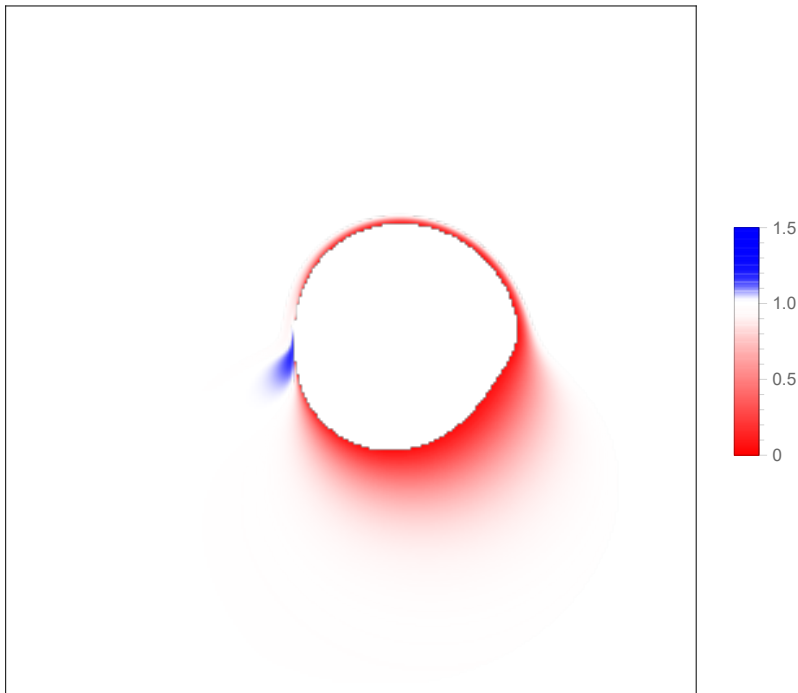


```

(*plot redshift for n=2*)
pltrs2 = ArrayPlot[Re@result[[All, All, 3]],
  图示数组 实部 全部 全部,
  DataReversed → {True, False}, PlotLegends → Automatic,
  数据颠倒否 真 假 绘图的图例 自动,
  ColorFunction → Function[a, RGBColor[If[a < 1, 1, 3 * (1 - a)], If[a < 1, a, 3 * (1 - a)],
  颜色函数 纯函数 RGB颜色 如果 如果,
  If[a < 1, a, 1], 1 - 1 / (1 + (a - 1) ^ 2 / 0.05)], ColorFunctionScaling → False]
如果 颜色函数缩放 假

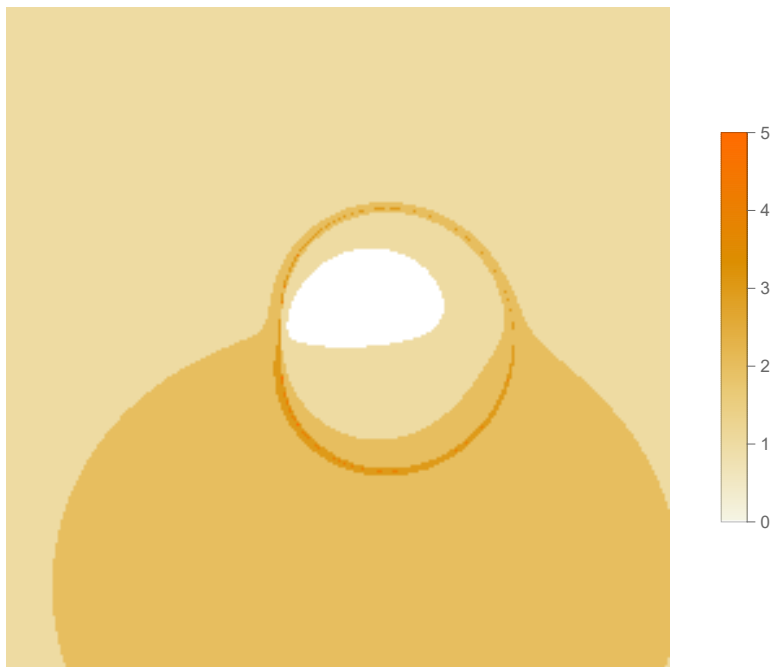
```

Out[ ]=



```
(*plot the maximum number of times that the ray crosses the equatorial plane*)
plttimes = MatrixPlot[result[[All, All, -1]], DataReversed → {True, False},
  AspectRatio → 1, Frame → False, PlotLegends → Automatic]
```

Out[ ]=



```
In[ ]:= ColorData["Gradients"]
```

颜色数据

```
Grid[Partition[Show[ColorData[#, "Image"], ImageSize → 110] & /@
```

格子

划分

显示

颜色数据

图像

图像尺寸

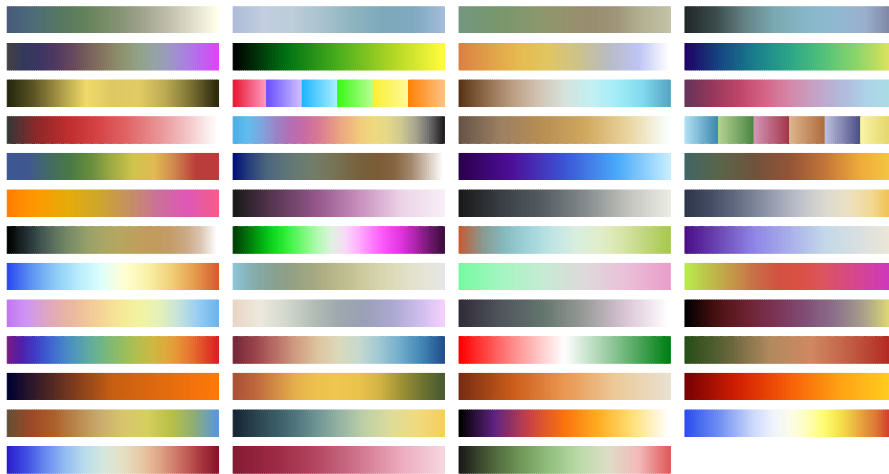
```
ColorData["Gradients"], 4, 4, 1, {}], Spacings → .5]
```

颜色数据

间隔

```
Out[ ]:= {AlpineColors, Aquamarine, ArmyColors, AtlanticColors, AuroraColors, AvocadoColors,
BeachColors, BlueGreenYellow, BrassTones, BrightBands, BrownCyanTones,
CandyColors, CherryTones, CMYKColors, CoffeeTones, DarkBands, DarkRainbow,
DarkTerrain, DeepSeaColors, FallColors, FruitPunchColors, FuchsiaTones, GrayTones,
GrayYellowTones, GreenBrownTerrain, GreenPinkTones, IslandColors, LakeColors,
LightTemperatureMap, LightTerrain, MintColors, NeonColors, Pastel, PearlColors,
PigeonTones, PlumColors, Rainbow, RedBlueTones, RedGreenSplit, RoseColors, RustTones,
SandyTerrain, SiennaTones, SolarColors, SouthwestColors, StarryNightColors,
SunsetColors, TemperatureMap, ThermometerColors, ValentineTones, WatermelonColors}
```

```
Out[ ]:=
```



```
In[ ]:= (*Export[FileNameJoin[{NotebookDirectory[], "rs_fov"<>ToString[fov* $\frac{180}{\pi}$ ]}<>
```

导出

文件名连接

当前笔记本的目录

转换为字符串

```
"d_a"<>ToString[1000 a0]<>"_obs"<>ToString[pos[[3]]* $\frac{180}{\pi}$ ]}<>"d.png"]],
```

转换为字符串

转换为字符串

```
pltg, ImageSize → 1600, ImageResolution → 500] *)
```

图像尺寸

图像分辨率