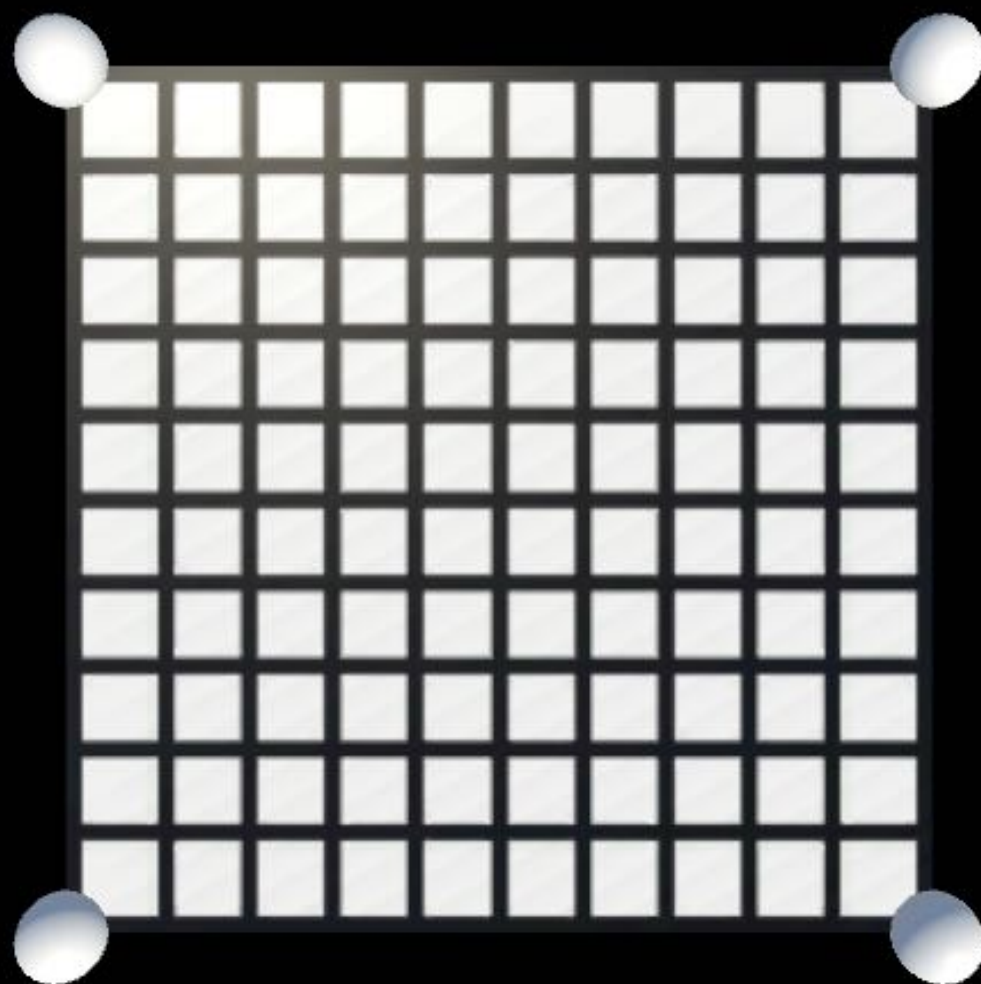


Interaction Design & Virtual Reality

Liwei chan 詹力韋
Assistant Prof.

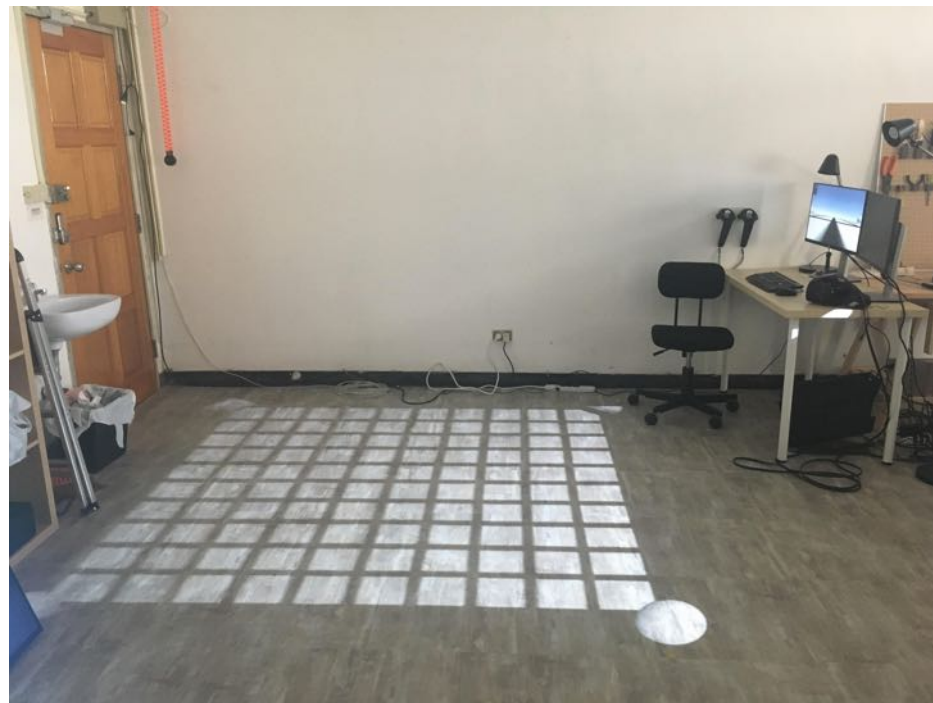
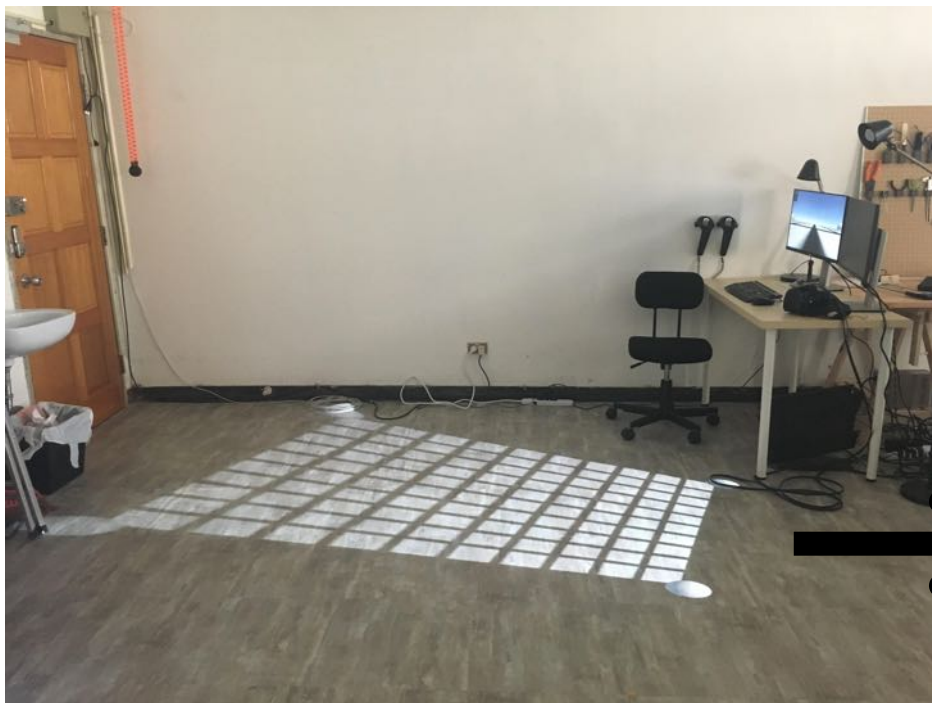
2016.11.29

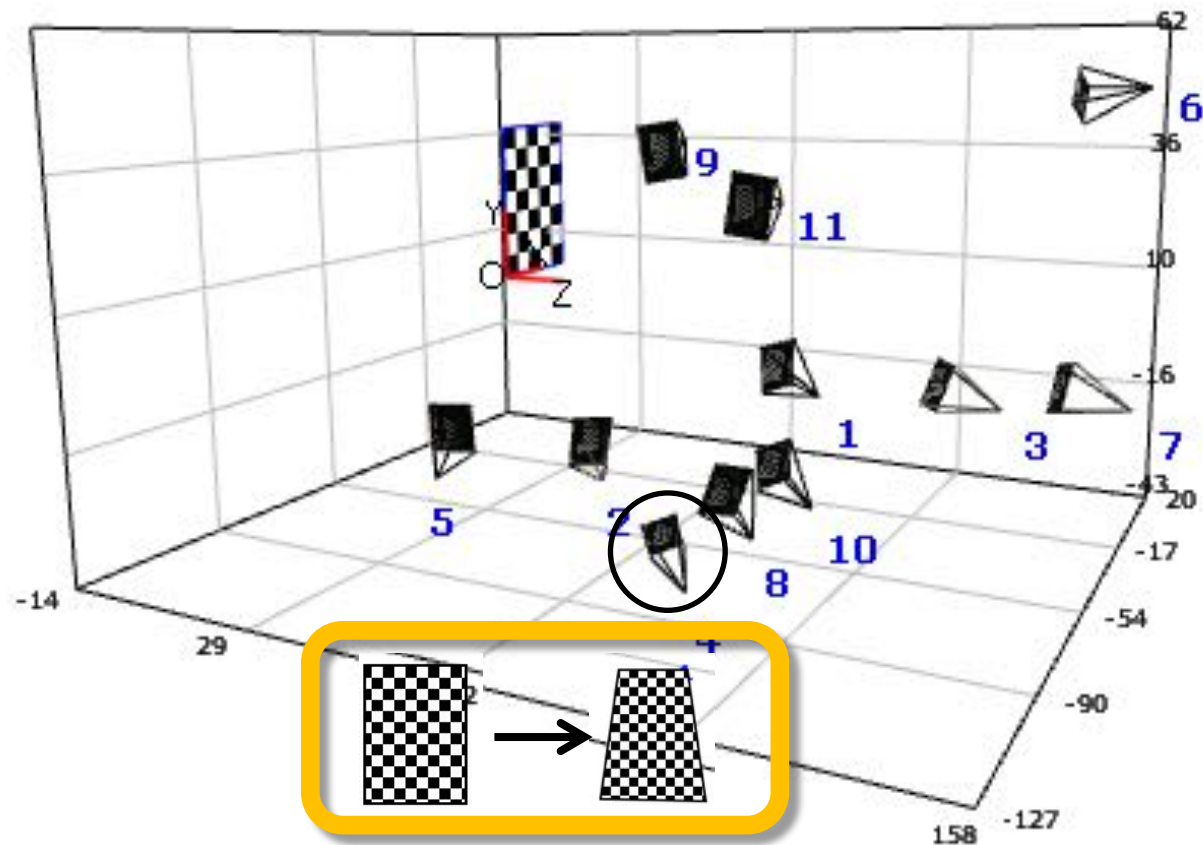
FloorProjection









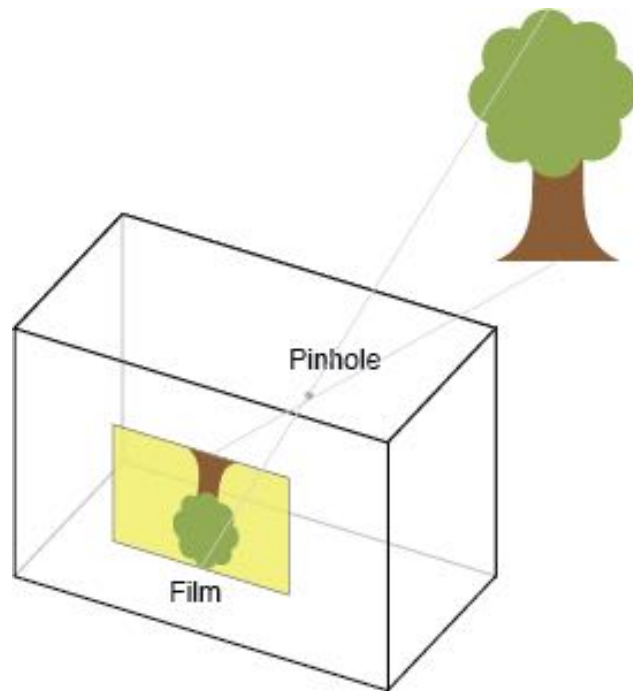


When projecting,
Apply the transformation in advance.
This transformation is called an **extrinsic matrix** of a camera.
This operation is also called **homographic transformation**.

Intrinsic Matrix

<http://ksimek.github.io/2013/08/13/intrinsic/>

Pinhole Camera

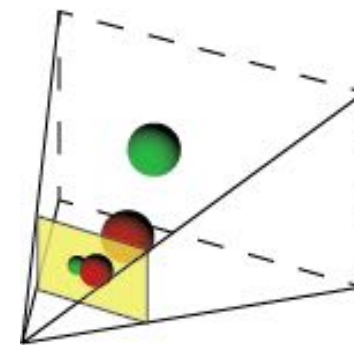
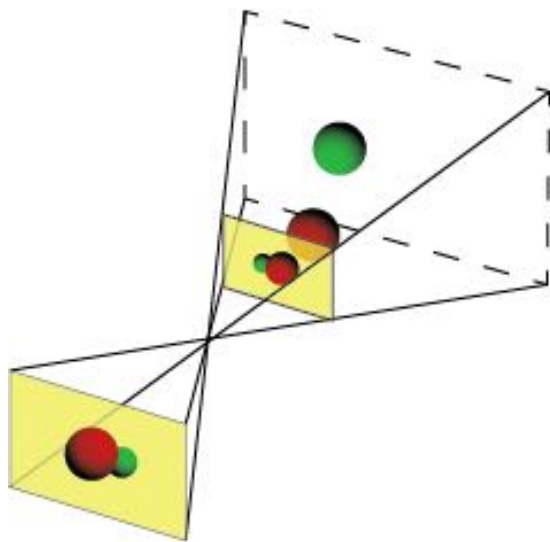


$$K = \begin{pmatrix} f_x & s & x_0 \\ 0 & f_y & y_0 \\ 0 & 0 & 1 \end{pmatrix}$$

Focal Length, f_x, f_y

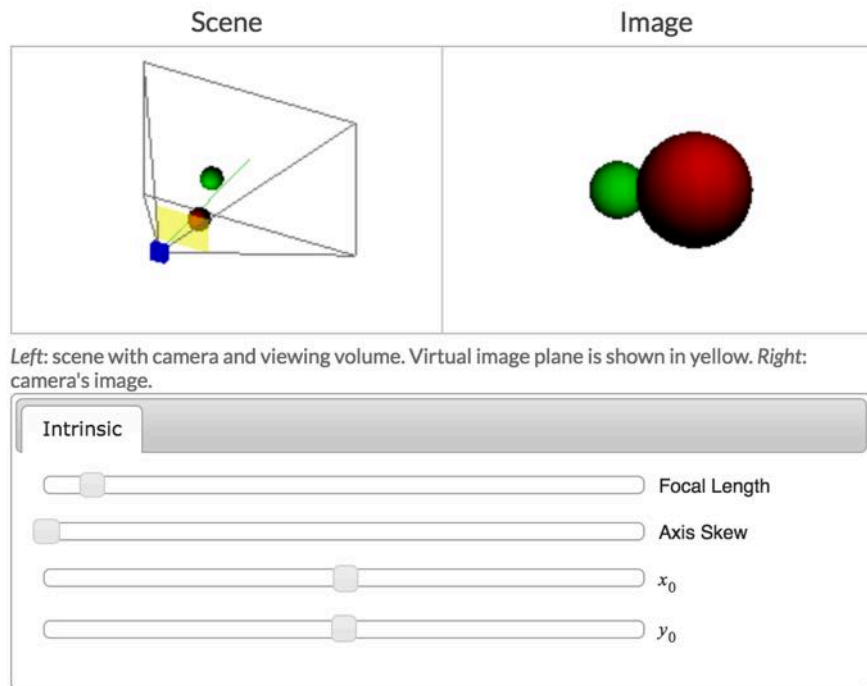
Principal Point Offset, x_0, y_0

Axis Skew, s



With more intuitive
representation

DEMO



<http://ksimek.github.io/2013/08/13/intrinsic/>

$$K = \begin{pmatrix} f_x & s & x_0 \\ 0 & f_y & y_0 \\ 0 & 0 & 1 \end{pmatrix}$$

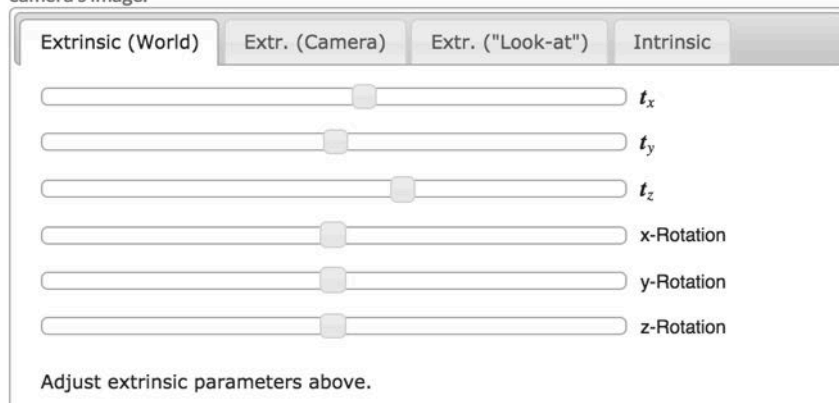
$$= \underbrace{\begin{pmatrix} 1 & 0 & x_0 \\ 0 & 1 & y_0 \\ 0 & 0 & 1 \end{pmatrix}}_{\text{2D Translation}} \times \underbrace{\begin{pmatrix} f_x & 0 & 0 \\ 0 & f_y & 0 \\ 0 & 0 & 1 \end{pmatrix}}_{\text{2D Scaling}} \times \underbrace{\begin{pmatrix} 1 & s/f_x & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}}_{\text{2D Shear}}$$

Extrinsic Matrix

<http://ksimek.github.io/2012/08/22/extrinsic/>

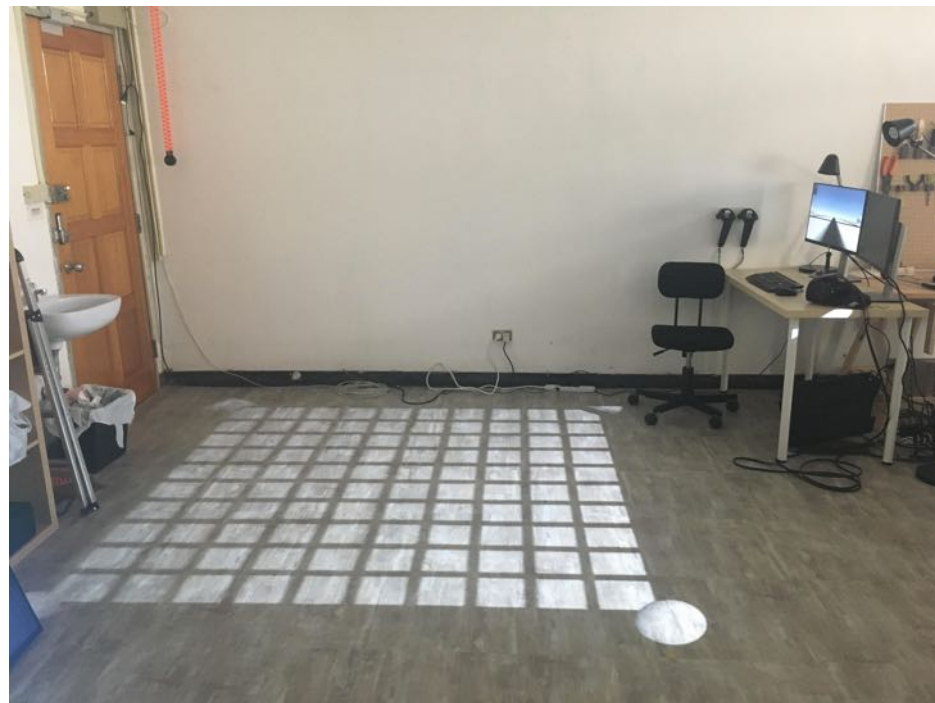
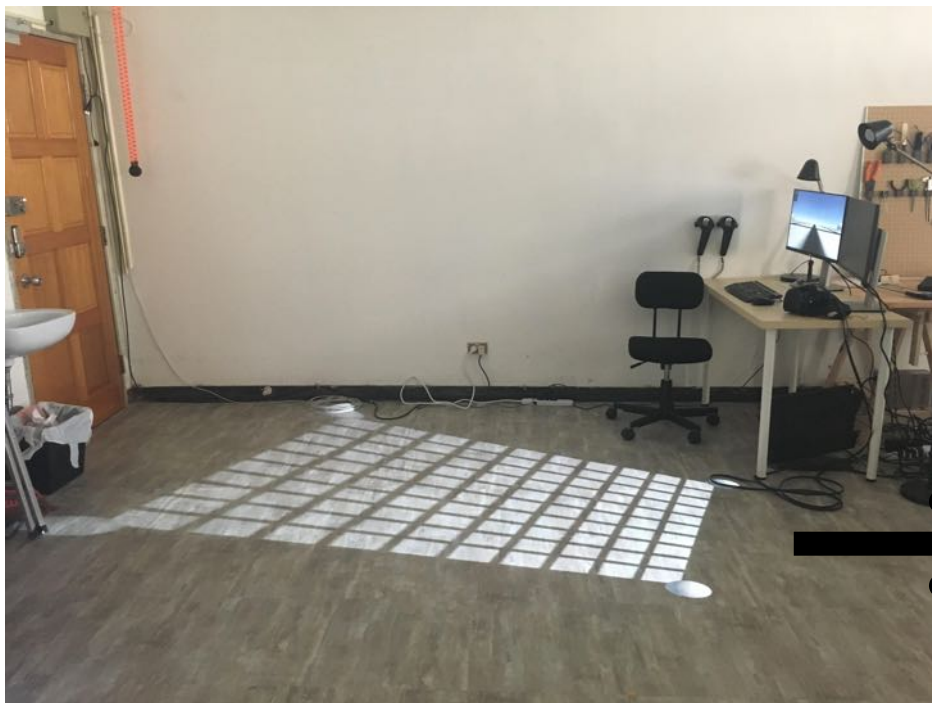


Left: scene with camera and viewing volume. Virtual image plane is shown in yellow. Right: camera's image.



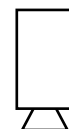
$$[R | t] = \left[\begin{array}{ccc|c} r_{1,1} & r_{1,2} & r_{1,3} & t_1 \\ r_{2,1} & r_{2,2} & r_{2,3} & t_2 \\ r_{3,1} & r_{3,2} & r_{3,3} & t_3 \end{array} \right]$$

$$\begin{aligned} \left[\begin{array}{c|c} R & t \\ \hline \mathbf{0} & 1 \end{array} \right] &= \left[\begin{array}{c|c} I & t \\ \hline \mathbf{0} & 1 \end{array} \right] \times \left[\begin{array}{c|c} R & \mathbf{0} \\ \hline \mathbf{0} & 1 \end{array} \right] \\ &= \left[\begin{array}{ccc|c} 1 & 0 & 0 & t_1 \\ 0 & 1 & 0 & t_2 \\ 0 & 0 & 1 & t_3 \\ \hline 0 & 0 & 0 & 1 \end{array} \right] \times \left[\begin{array}{ccc|c} r_{1,1} & r_{1,2} & r_{1,3} & 0 \\ r_{2,1} & r_{2,2} & r_{2,3} & 0 \\ r_{3,1} & r_{3,2} & r_{3,3} & 0 \\ \hline 0 & 0 & 0 & 1 \end{array} \right] \end{aligned}$$



Change to a camera pose
Such that when the projector

Floor content
texture
(RenderTexture)



Floor content
camera

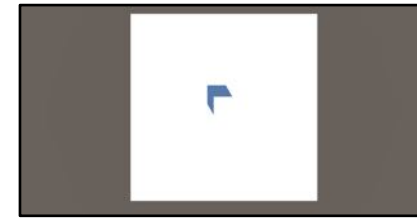


Floor
content
texture



Floor content
camera

Goal is to
put/project
this texture
on the **floor**.



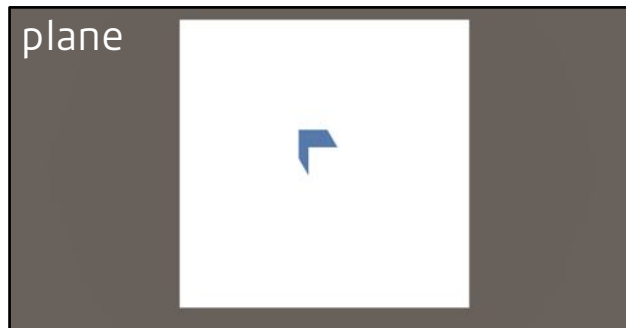
Use mouse:
adjust this keystone
camera pose, such that
the projected
floorContextTexture is
correct on the floor.



Keystone
camera



Physical
floor
projector



**your
scene**

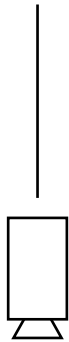


**another
scene**

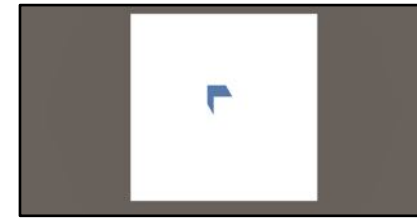
Instead of an independent
“another” scene,

we add **layer (e.g., FloorProjector)**
to separate the scene

Floor
content
texture



Floor content
camera



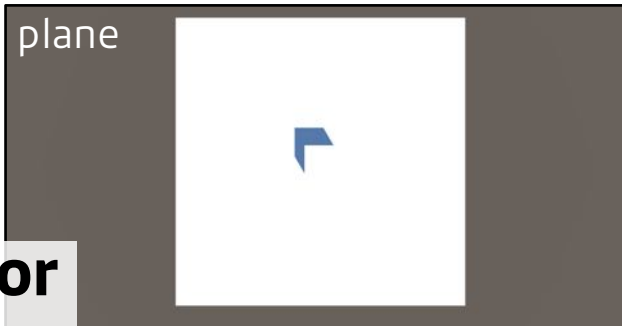
Use mouse:
adjust this keystone
camera pose, such that
the projected
floorContextTexture is
correct on the floor.



Keystone
camera



Physical
floor
projector



**FloorProjector
Layer**

**your
scene**



STEPS for integration:

1. Import floorProject.package
2. Add Tad "CalibrationSphere"
3. Add Layer "FloorProjector"
4. Go to Edit -> Project Settings -> Players, switch to **.NET 2.0.**
5. Double check
 - FloorContentCamera: Target Display -> Display 1
 - FloorContentCamera: Target Eye -> None
 - KeystoneCamera: Target Display -> Display 2
 - KeystoneCamera: Target Eye -> None
6. **Adapt FloorContentCamera pose for your application.**

Unity Personal (64bit) - sampleFloorProjector.unity - testFloorProjection - PC, Mac & Linux Standalone <DX11>

File Edit Assets GameObject Component Tools Window Help

Center Local

Hierarchy

Create All

sampleFloorProjector

Main Camera

Directional Light

FloorContentCamera

Plane

floorProjector

floorContentPlane

KeystoneCamera

RecordPoints

[CameraRig]

Controller (right)

Camera (head)

Camera (eye)

Camera (ears)

Scene

Shaded

2D

Asset Store

Gizmos

All

Account Layers Layout

Inspector

floorProjector

Tag Untagged Layer Default

Transform

Position X 0 Y 0 Z 0

Rotation X 0 Y 0 Z 0

Correspondence Acquisition (Script)

Script CorrespondenceAcquisition

Texture Plane floorContentPlane

Keystone Camera KeystoneCamera (Camera)

Project

Create

Favorites

All Materials

All Models

All Prefabs

All Scripts

Assets

Demigiant

FloorProjection

Materials

Materials

Plugins

SteamVR

UnityVS

Assets FloorProjection



Materials



Calibration



Correspond...



Correspond...



Correspond...



crosshair



DrawLine



floorConten...



grid



PointsReco...



Projection...



Recording



Rotation



RotationCo...



sampleFloo...



Serializabl...



SerializeEx...



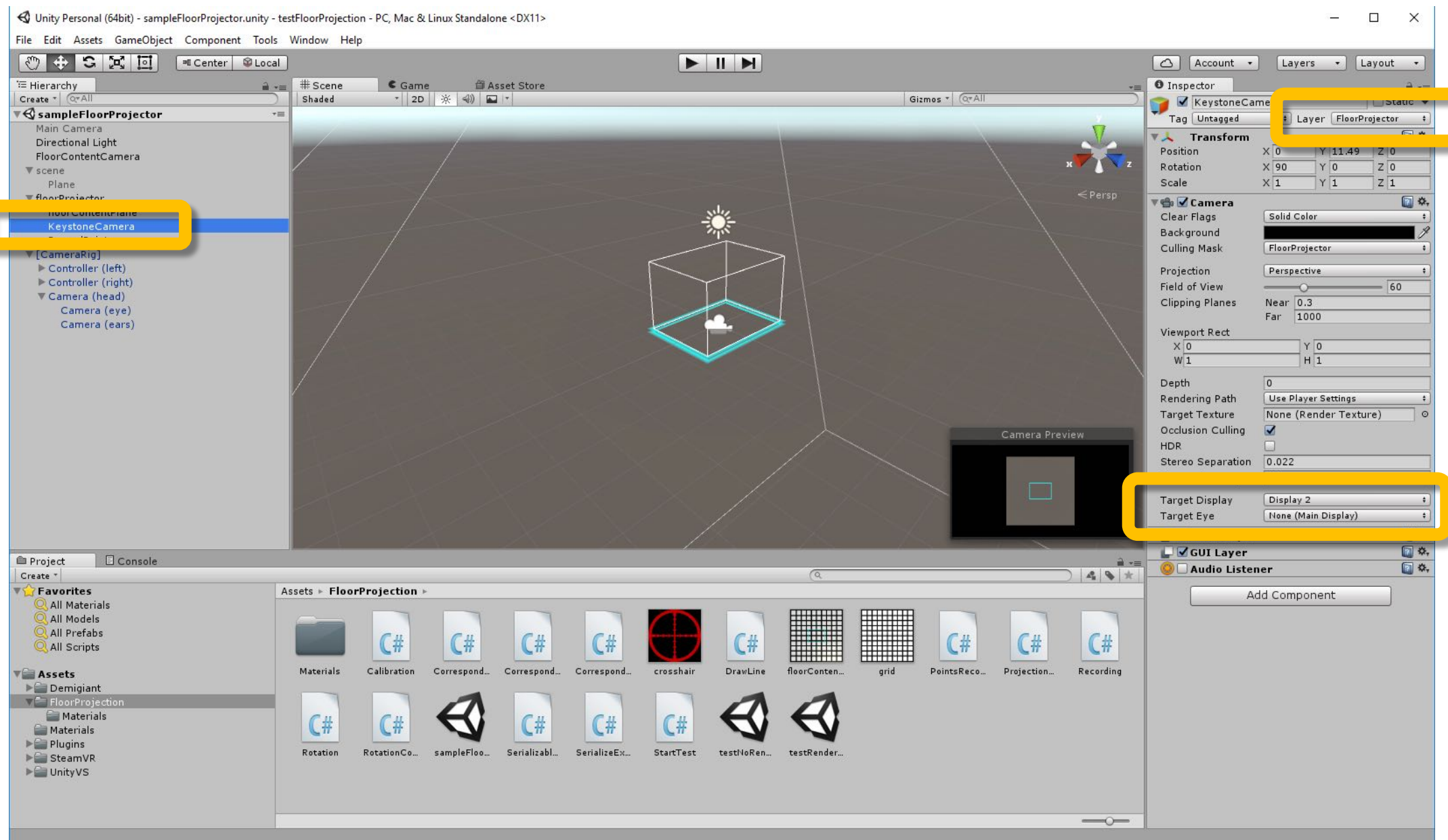
StartTest

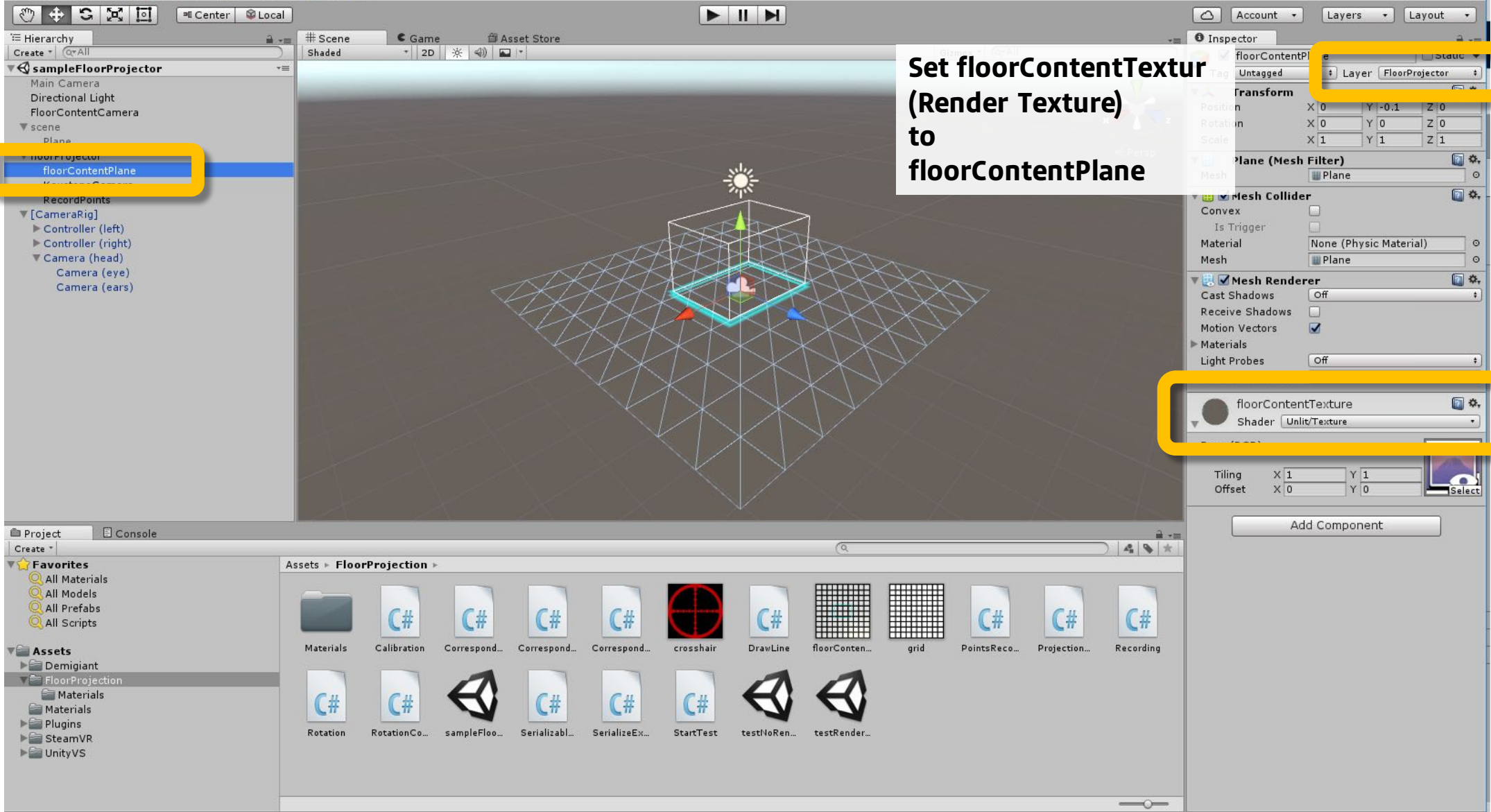


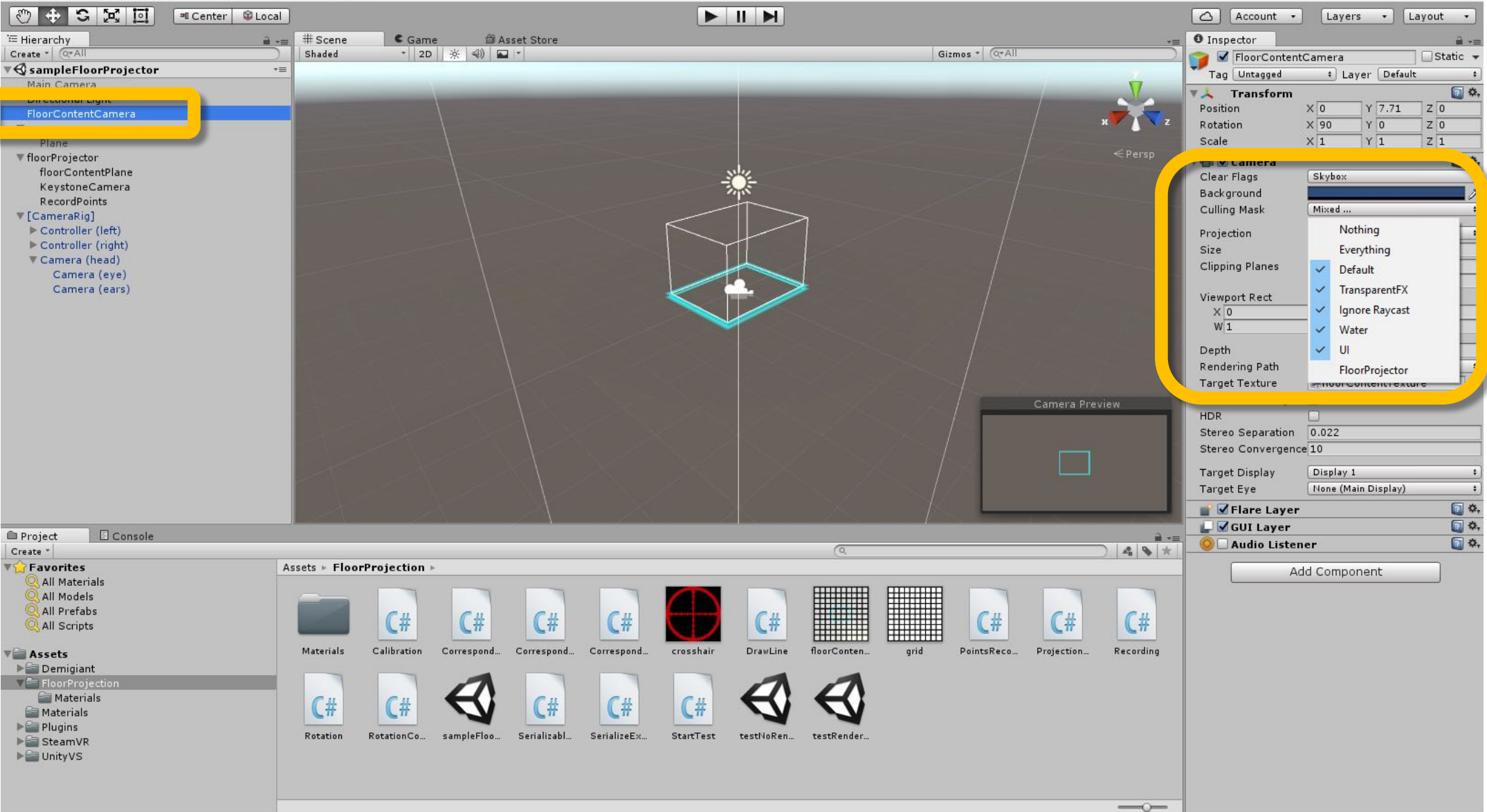
testNoRen...

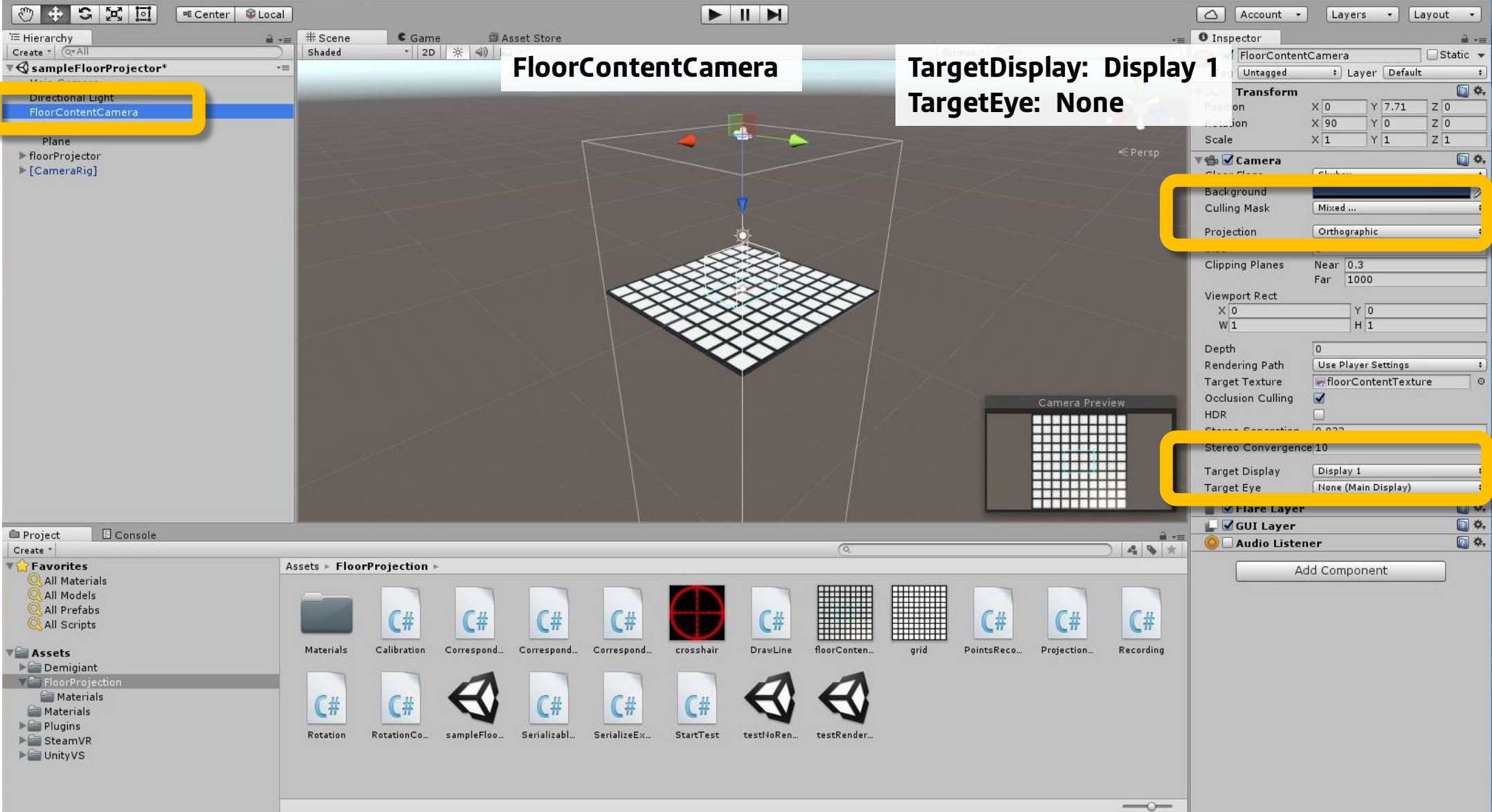


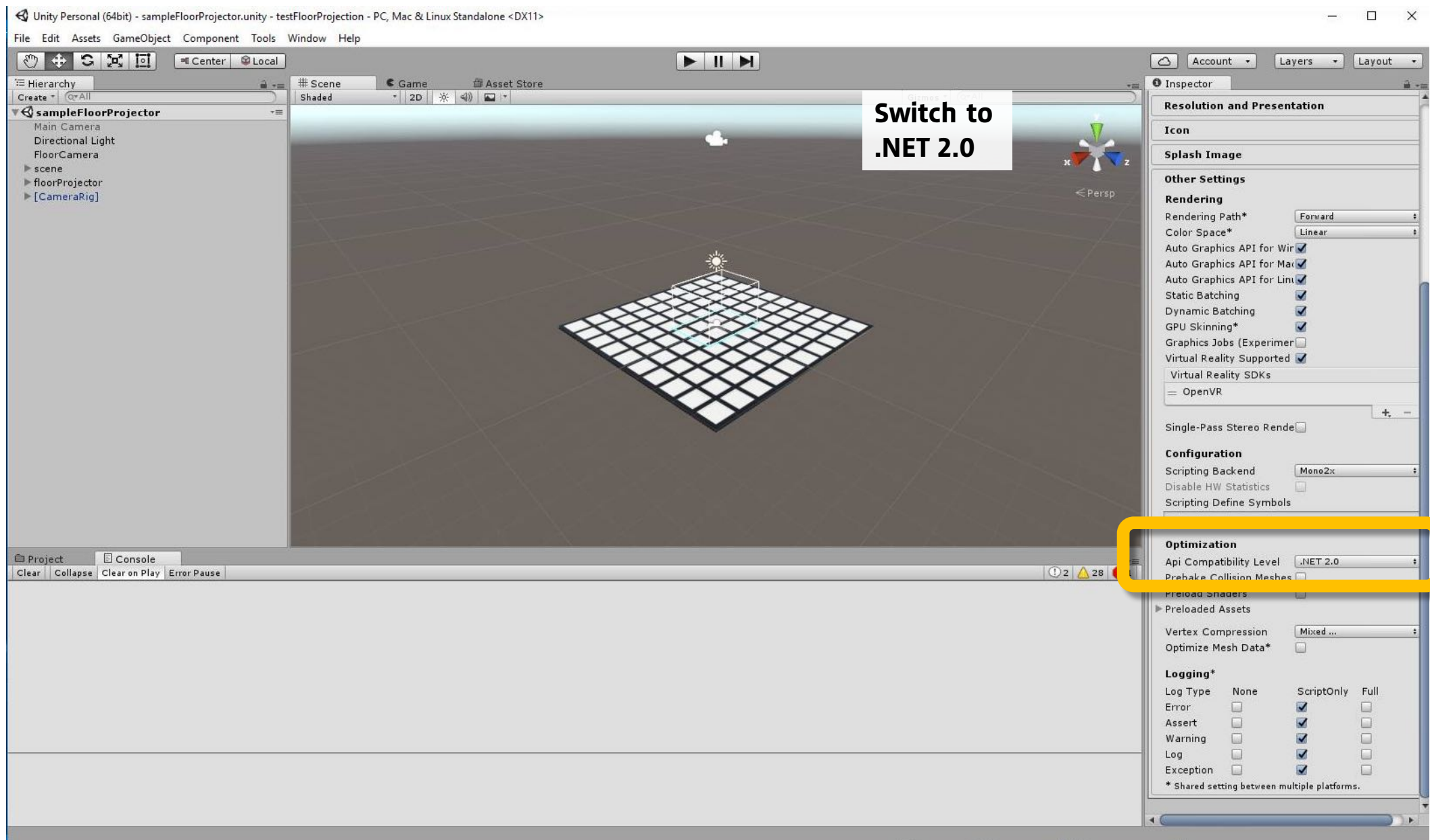
testRender...

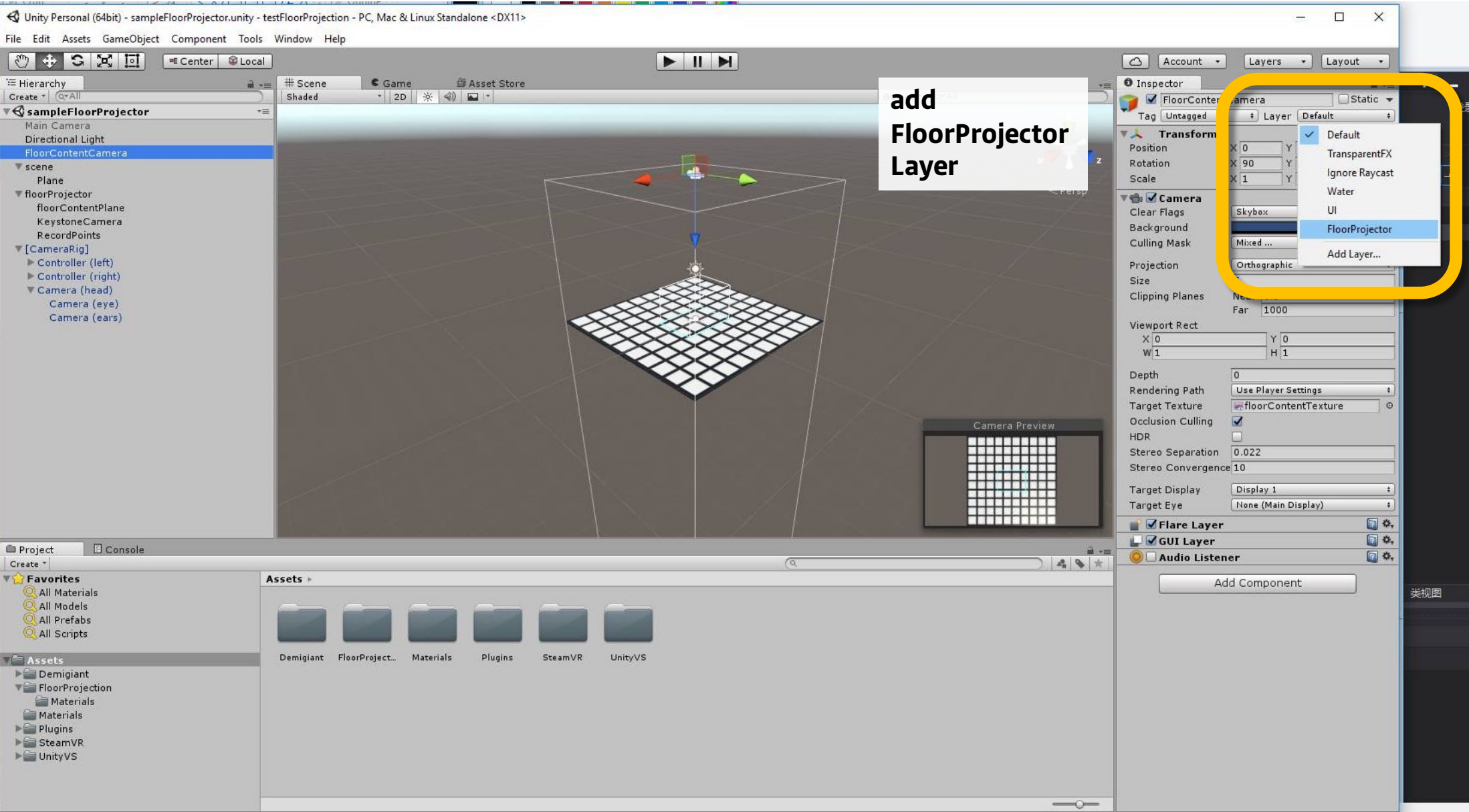












The screenshot displays the Unity 5.6.0f3 interface. The Hierarchy panel on the left shows the scene structure, including the 'sampleFloorProjector' object and its components. The Inspector panel on the right shows the properties of the selected 'Directional Light' component. A yellow box highlights the 'Tag' dropdown menu, which is open, showing a list of tags including 'Untagged', 'Respawn', 'Finish', 'EditorOnly', 'MainCamera', 'Player', 'GameController', and 'CalibrationSphere'. The 'CalibrationSphere' tag is highlighted. A text box in the center of the scene reads 'add CalibrationSphere Tag'. The Project panel at the bottom shows the 'Assets' folder containing various files, including 'Materials', 'Calibration', 'Correspond...', 'crosshair', 'DrawLine', 'floorConten...', 'grid', 'PointsReco...', 'Projection...', 'Recording', 'Rotation', 'RotationCo...', 'sampleFlo...', 'Serializabl...', 'SerializeEx...', 'StartTest', 'testNoRen...', and 'testRender...'.

add
CalibrationSphere
Tag

Inspector

Tag Untagged Layer Default

- Untagged
- Respawn
- Finish
- EditorOnly
- MainCamera
- Player
- GameController
- CalibrationSphere
- Add Tag

Strength 1

Resolution Use Quality Settings

Bias 0.05

Normal Bias 0.4

Shadow Near Plane 0.2

Cookie None (Texture)

Cookie Size 10

Draw Halo

Flare None (Flare)

Render Mode Auto

Culling Mask Everything

Add Component

Assets FloorProjection

Materials Calibration Correspond... Correspond... Correspond... crosshair DrawLine floorConten... grid PointsReco... Projection... Recording

Rotation RotationCo... sampleFlo... Serializabl... SerializeEx... StartTest testNoRen... testRender...

