Assignment 3

Zheyan Liu

Contents

Introduction	1
Question (a)	2
Target variable mpg_cat	2
mpg_cat and categorical variables	2
mpg_cat and continuous variables	4
Question (b)	6
Build logistic regression model and get significant predictors	6
Confusion matrix and fraction of correct predictions	7
Question (c)	8

Introduction

In this problem, you will develop a model to predict whether a given car gets high or low gas mileage based on the dataset "auto.csv". The dataset contains 392 observations. The response variable is mpg cat, which indicates whether the miles per gallon of a car is high or low. The predictors are:

- \bullet cylinders: Number of cylinders between 4 and 8
- displacement: Engine displacement (cu. inches)
- horsepower: Engine horsepower
- weight: Vehicle weight (lbs.)
- acceleration: Time to accelerate from 0 to 60 mph (sec.)
- year: Model year (modulo 100)
- origin: Origin of car (1. American, 2. European, 3. Japanese)

Split the dataset into two parts: training data (70%) and test data (30%).

Question (a)

Produce some graphical or numerical summaries of the data.

The model has 392 observations and 7 independent variables including 2 categorical variables (cylinders, origin) and 5 continuous variables (displacement, horsepower, weight, acceleration, year).

Target variable mpg_cat

Category high and low are balanced

```
df %>%
  group_by(mpg_cat) %>%
  summarise(cnt = n()) %>%
  knitr::kable()
```

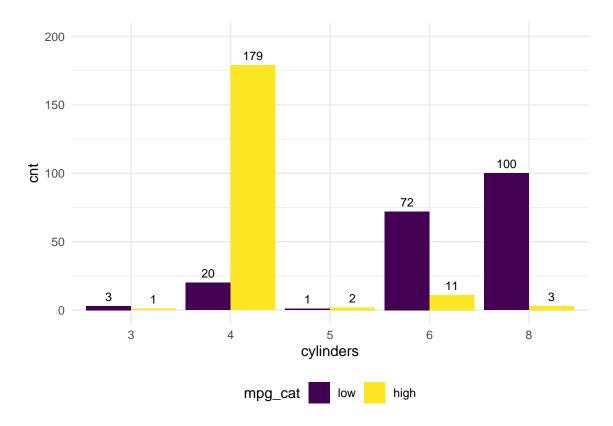
mpg_cat	cnt
low	196
high	196

mpg_cat and categorical variables

Cars with low mpg mostly has 6 or 8 cylinders while those with high mpg has 4 cylinders.

```
df %>% group_by(cylinders, mpg_cat) %>%
  summarise(cnt = n()) %>%
ggplot(aes(x = cylinders, y = cnt, fill = mpg_cat, label = cnt)) +
  geom_bar(stat = "identity", position = "dodge") +
  geom_text(
    aes(label = cnt),
    colour = "black", size = 3.2,
    vjust = -0.6, position = position_dodge(.9)
) + ylim(0, 200)
```

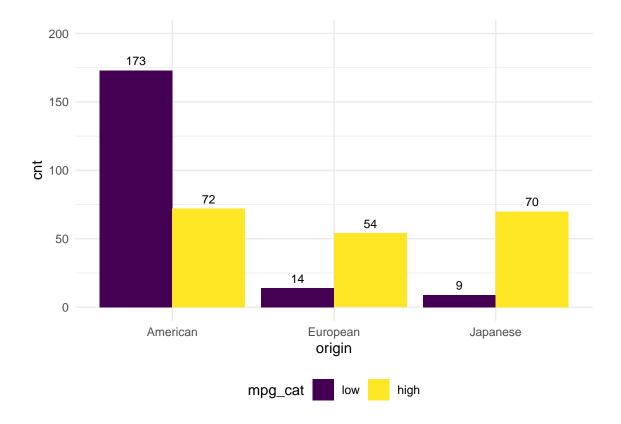
'summarise()' has grouped output by 'cylinders'. You can override using the '.groups' argument.



Cars orgainates in American are more likely to have low mpg (2.4 times more likely), while cars from European and Japanese are more likely to have high mpg.

```
df %>% group_by(origin, mpg_cat) %>%
   summarise(cnt = n()) %>%
ggplot(aes(x = origin, y = cnt, fill = mpg_cat, label = cnt)) +
   geom_bar(stat = "identity", position = "dodge") +
   geom_text(
   aes(label = cnt),
   colour = "black", size = 3.2,
   vjust = -0.6, position = position_dodge(.9)
) + ylim(0, 200)
```

'summarise()' has grouped output by 'origin'. You can override using the '.groups' argument.

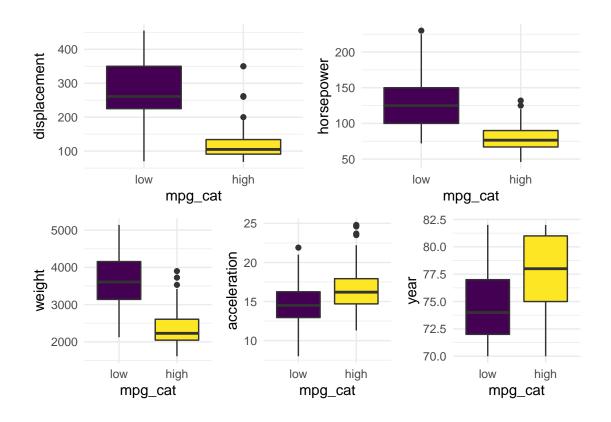


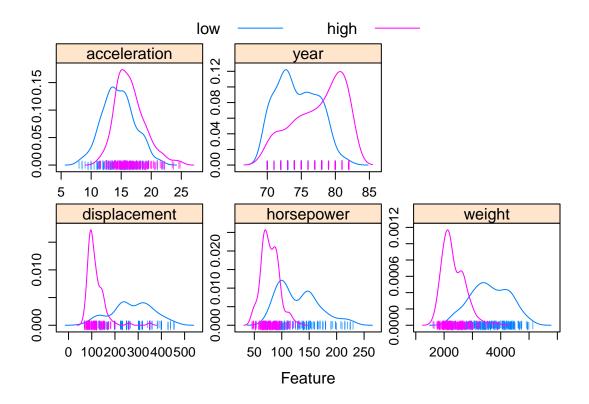
mpg_cat and continuous variables

From the boxplot and feature plot, the median of displacement, horsepower, weight of the high mpg cars is lower than that of the high mpg cars, while the median of acceleration, year of the high mpg cars is higher than that of the high mpg cars

```
library(patchwork)
p1 = ggplot(df, aes(x=mpg_cat, y=displacement, fill = mpg_cat)) +
    geom_boxplot() + theme(legend.position = "none")
p2 = ggplot(df, aes(x=mpg_cat, y=horsepower, fill = mpg_cat)) +
    geom_boxplot() + theme(legend.position = "none")
p3 = ggplot(df, aes(x=mpg_cat, y=weight, fill = mpg_cat)) +
    geom_boxplot() + theme(legend.position = "none")
p4 = ggplot(df, aes(x=mpg_cat, y=acceleration, fill = mpg_cat)) +
    geom_boxplot() + theme(legend.position = "none")
p5 = ggplot(df, aes(x=mpg_cat, y=year, fill = mpg_cat)) +
    geom_boxplot() + theme(legend.position = "none")

(p1 + p2)/(p3 + p4 + p5)
```





Question (b)

Perform a logistic regression using the training data. Do any of the predictors appear to be statistically significant? If so, which ones? Compute the confusion matrix and overall fraction of correct predictions using the test data. Briefly explain what the confusion matrix is telling you.

Build logistic regression model and get significant predictors

```
glm.fit <- glm(mpg_cat ~ .,</pre>
               data = df,
               subset = rowTrain,
               family = binomial(link = "logit"))
summary(glm.fit)
##
## glm(formula = mpg_cat ~ ., family = binomial(link = "logit"),
##
       data = df, subset = rowTrain)
##
## Deviance Residuals:
##
        Min
                    1Q
                          Median
                                         ЗQ
                                                  Max
  -2.30091 -0.08519
                         0.00102
                                   0.10904
                                              2.61952
##
```

```
## Coefficients:
##
                   Estimate Std. Error z value Pr(>|z|)
## (Intercept)
                 -3.614e+01 1.455e+03 -0.025 0.98019
## cylinders4
                 1.704e+01 1.455e+03
                                        0.012 0.99066
## cylinders5
                  1.623e+01 1.455e+03
                                        0.011 0.99110
## cylinders6
                  1.564e+01 1.455e+03
                                       0.011 0.99143
                1.991e+01 1.455e+03
## cylinders8
                                        0.014 0.98909
                 6.475e-03 1.652e-02
## displacement
                                        0.392 0.69511
## horsepower
                 -8.736e-02 3.579e-02 -2.441 0.01466 *
## weight
                 -5.077e-03 1.810e-03 -2.805 0.00503 **
## acceleration
                 -2.128e-02 2.104e-01 -0.101 0.91946
## year
                  5.371e-01
                            1.200e-01
                                        4.475 7.64e-06 ***
## originEuropean 1.178e+00 1.090e+00
                                        1.081 0.27977
                                        2.234 0.02550 *
## originJapanese
                 2.412e+00 1.080e+00
## ---
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
##
## (Dispersion parameter for binomial family taken to be 1)
##
##
      Null deviance: 382.617 on 275 degrees of freedom
## Residual deviance: 85.848 on 264 degrees of freedom
## AIC: 109.85
##
## Number of Fisher Scoring iterations: 14
```

Under 0.05 significance level, The significant predictors are cylinders 4 (reference category is cylinders 2), weight and year.

Confusion matrix and fraction of correct predictions

Confusion matrix

```
## Confusion Matrix and Statistics
##
##
             Reference
## Prediction low high
         low
               51
##
##
         high
              7
                    53
##
##
                  Accuracy : 0.8966
##
                    95% CI: (0.8263, 0.9454)
##
       No Information Rate: 0.5
##
       P-Value [Acc > NIR] : <2e-16
```

```
##
##
                     Kappa: 0.7931
##
   Mcnemar's Test P-Value: 0.7728
##
##
               Sensitivity: 0.9138
##
               Specificity: 0.8793
##
            Pos Pred Value: 0.8833
##
##
            Neg Pred Value: 0.9107
##
                Prevalence: 0.5000
##
            Detection Rate: 0.4569
      Detection Prevalence: 0.5172
##
##
         Balanced Accuracy: 0.8966
##
##
          'Positive' Class : high
##
```

Fraction of correct predictions is 0.8534483.

If we set the threshold to be 0.5, The confusion matrix is telling that

- Sensitivity = 0.8621, 0.8621 of the high mpg cars are detected by the model
- Specificity = 0.8448, 0.8448 of the low mpg cars are detected by the model
- PPV = 0.8475, 0.8475 of the predicted high are actually high
- NPV = 0.8596, 0.8596 of the predicted low are actually low

Question (c)

Train a multivariate adaptive regression spline (MARS) model using the training data. The best tune is when nprune is 9 and degree is 2

```
set.seed(7)
library(vip)
##
## Attaching package: 'vip'
## The following object is masked from 'package:utils':
##
##
       vi
ctrl <- trainControl(method = "repeatedcv",</pre>
                      summaryFunction = twoClassSummary,
                      classProbs = TRUE)
model.mars <- train(x = df[rowTrain,1:7],
                     y = df$mpg_cat[rowTrain],
                     method = "earth",
                     tuneGrid = expand.grid(degree = 1:4,
                                             nprune = 2:16),
                     metric = "ROC",
                     trControl = ctrl)
```

Loading required package: earth

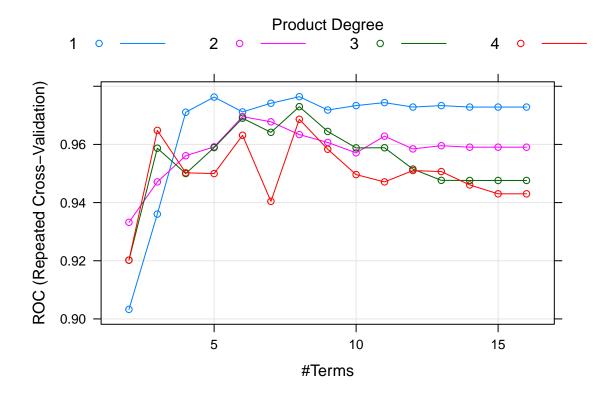
Loading required package: Formula

Loading required package: plotmo

Loading required package: plotrix

Loading required package: TeachingDemos

Best Tune plot(model.mars)



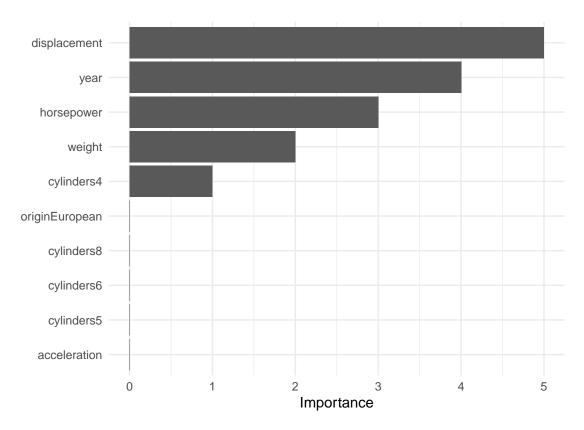
model.mars\$bestTune %>% knitr::kable()

	nprune	degree
7	8	1

coef(model.mars\$finalModel)

##	(Intercept) h(d:	isplacement-232)	h(year-77)	h(horsepower-78)
##	3.12665813	0.15530822	1.41750031	-0.11180905
##	h(weight-2694) h(d:	isplacement-171)	h(weight-2795)	
##	-0.02249845	-0.08332131	0.02069096	

pdp::partial(model.mars, pred.var = c("year"), grid.resolution = 200) %>% autoplot()
vip(model.mars\$finalModel)



Important variables are cylinders 4, year, horsepower, displacement, acceleration and weight.