

Incorrectness Specification Inference

ANONYMOUS AUTHOR(S)

1 MOTIVATION EXAMPLE: CONCAT

For the concat example,

```
1 let rec concat s1 s2 =
2  match s1 with
3  | [] -> s2
4  | h1 :: t1 ->
5  let s3 = concat t1 s2 in
6  h1 :: s3
```

we expect that the overapproximate triple $\{\Sigma\}$ concat s_1 $s_2 \downarrow \nu\{\Phi\}$ hold, where:

```
\Sigma \equiv \neg dup(s_1) \land \neg dup(s_2)\Phi \equiv \neg dup(v)
```

 $dup(s) \equiv$ the stack s contains some elements appearing for 2 or more times.

 $emp(s) \equiv$ the stack s is empty.

However, this triple is not valid (e.g. concat [1; 2] [2; 3] = [1; 2; 2; 3]) which means the program is buggy. Thus we expect to find an underapproximate triple as its incorrectness specification that summarize the buggy executions of concat. We cannot simply negate the postcondition Φ to build a triple $[\Sigma]concat$ s_1 $s_2 \downarrow \nu[\neg \Phi]$ because there exists unreachable state in the negated postcondition $\neg \Phi$. For example, the stack $\nu \equiv [1;1;1]$ is not reachable, because all elements in the output stack should be contained by the two input stacks s_1 and s_2 , additionally there are three 1s in the output stack, thus at least one of the input stack will contains two 1s which conflicts with the precondition Σ that asks both input stacks having no duplicate element.

1.1 Problem

Thus our goal is to infer *P* and *Q* such that:

- (1) [P] concat $s_1 s_2 \downarrow v[Q]$;
- (2) $P \Longrightarrow \Sigma$;
- (3) $Q \implies \neg \Phi$.

1.2 Solution

One possible result is:

$$P_0 \equiv \neg dup(s_1) \land \neg dup(s_2) \land \exists u, mem(s_1, u) \land mem(s_2, u)$$

$$Q_0 \equiv dup(v) \land \neg dup3(v)$$

where dup3(s) means the stack s contains some elements appearing for 3 or more times.

2 Anon.

Proof fails without inductive invariant

Although P_0 and Q_0 is correct but we cannot verify the triple $[P_0]concat s_1 s_2 \downarrow \nu[Q_0]$ directly, because P_0 and Q_0 is not inductive. More precisely, we expect that,

where *T* is an imperative version (but with recursion) of *concat*:

$$T :=$$

$$(assume \ s_1 = []; \nu := s_2) \oplus$$

$$(assume \ \neg(s_1 := []); (h_1, t_1) := cons^{-1}(s_1); s_3 := T(t_1, s_2); \nu := h_1 :: s_3)$$

Now we do not consider exceptions, thus we label Q as ok (and omitted if the context is clear) and expect the program can terminate normally but reach state over from Φ . Now we show, if we do not introduce the new inductive invariant, the proof will fail.

Notice that, the proof tree actually starts from the post condition $P(s_1, s_2) \land Q(v)$ instead of Q(v), because the incorrectness logic need constraint all variables in the postcondition. Thus the input arguments should be constrained by the precondition $P(s_1, s_2)$. In summary, we add a new rule:

$$\frac{[P(\overline{x})]\overline{y} = T(\overline{x})[P(\overline{x}) \land Q(\overline{y})]}{Spec(T, (P, Q))}$$
 Specification Daully, we add an application rule:
$$\frac{Spec(T, (P, Q))}{Spec(T, (P, Q))}$$
 Apply

$$\frac{Spec(T, (T, Q))}{\forall \overline{x} \ \overline{y}, [P(\overline{x})] \overline{y} = T(\overline{x})[P(\overline{x}) \land Q(\overline{y})]} \text{ Apply}$$
Now we have

Now we have

50 51

52

53

54 55

56

57

58

60

61

65

69

71

73

74

75

76

77

79

81

83

85

86

87

88

89

90

91

92 93

94

95 96

97 98

Assume
$$\frac{[P(s_1, s_2) \land s_1 \neq []]}{[P(s_1, s_2)]} = \text{Assume} \qquad \frac{[P(s_1, s_2) \land s_1 \neq []]}{[P(s_1, s_2) \land s_1 \neq []]} \qquad \frac{[P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1]}{[P(s_1, s_2) \land s_1 \neq []]} \qquad \frac{[P(s_1, s_2) \land s_1 \neq []] \land s_1 = h_1 :: t_1]}{[P(s_1, s_2) \land s_1 \neq []]} \qquad \frac{[P(s_1, s_2) \land s_1 \neq []] \land s_1 = h_1 :: t_1]}{[P(s_1, s_2) \land s_1 \neq []]} \qquad \frac{[P(s_1, s_2) \land s_1 \neq []] \land s_1 = h_1 :: t_1]}{[P(s_1, s_2) \land s_1 \neq []] \land s_1 = h_1 :: t_1]} \qquad \text{Seq}$$

$$\frac{[P(s_1, s_2) \land s_1 \neq []]}{[P(s_1, s_2) \land s_1 \neq []]} \qquad \text{Seq}$$

$$\frac{[P(s_1, s_2) \land s_1 \neq []]}{[P(s_1, s_2) \land s_1 \neq []]} \qquad \text{Choice: 1}$$

Spec(T, (P, Q))We choose the second branch of T, because the first branch will lead $P(s_1, s_2) \land s1 = [] \iff \bot$.

```
Spec(T, (P, Q))
                                                                                                                  [... \wedge Q(s_3)]
                                                                                                                                                                              \exists s_3 \ h_1 \ t_1, P(s_1, s_2) \land Q(v) \implies
[P(t_1, s_2)]s_3 :=
                                                                                                                  v := h_1 :: s_3
                                                                                                                                                                              P(s_1, s_2) \wedge s_1 \neq [] \wedge s_1 = h_1 :: t_1
                                                                                                                                                                             \wedge Q(s_3) \wedge \nu = h_1 :: s_3  Con
                                                   P(s_1, s_2) \wedge \underbrace{s_1 \neq [] \wedge s_1 = h_1}_{\text{Cons}} :: t_1
T(t_1, s_2)[Q(s_3)]
                                                                                                                  [.. \land Q(s_3) \land v = h_1 :: s_3]
              [P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1]s_3 :=
                                                                                                                                     [P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 ::
                                                                                                                                     t_1 \wedge Q(s_3)] v := h_1 :: s_3
              [P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3)]
                                                                                                                                    [\exists ... \land Q(v)]
                                                                    [P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1]
                                                                   s_3:=T(t_1,s_2); v:=h_1::s_3\ [\exists ...\land Q(v)]
```

- Spec

When we encounter the recursive calling $T(t_1, s_2)$, to apply the triple $[P(t_1, s_2)]s_3 := T(t_1, s_2)[Q(s_3)]$ to the current state, we use the consequence rule of the incorrectness logic. It requires

$$P(t_1, s_2) \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1$$

The precondition $P(t_1, s_2)$ does not constraint the variable s_1 and h_1 because they are not the arguments of $T(t_1, s_2)$, which make the proof fail. It push us to add the frame rule to the application rule:

$$\frac{Spec(T,(P,Q)), \overline{z} \cap \overline{x} = \emptyset}{\forall \overline{x} \ \overline{y}, [R(\overline{z}) \wedge P(\overline{x})] \overline{y} = T(\overline{x})[R(\overline{z}) \wedge P(\overline{x}) \wedge Q(\overline{y})]}$$
 Apply-Frame-First-Try which follows the typical frame rule that asks the variable set \overline{z} is disjoint with the variable set \overline{x} . However, even with

 the new application rule, we cannot prove the implication as the body of the implication includes:

$$s_1 = h_1 :: t_1$$

which is a relation between the arguments of calling function (\overline{x}) can the framed variables (\overline{z}) . To solve this, I introduce a stronger application rule:

$$Spec(T, (P, Q)), \overline{z} \cap \overline{x} = \emptyset$$

$$P(\overline{x}) \wedge Q(\overline{y}) \implies \exists \overline{z}, R(\overline{x}, \overline{y}, \overline{z}) \wedge P(\overline{x}) \wedge Q(\overline{y})$$

Apply-Frame

 $\forall \overline{x} \ \overline{y}, [R(\overline{x}, \overline{z}) \land P(\overline{x})] \overline{y} = T(\overline{x}) [R(\overline{x}, \overline{y}, \overline{z}) \land P(\overline{x}) \land Q(\overline{y})]$

where *R* can be built from any variables, but we do not allow any state in $P(\overline{x}) \wedge Q(\overline{y})$ to be invalid after framing.

Now we set $R(\overline{x}, \overline{y}, \overline{z})$ as $s_1 = h_1 :: t_1$ and we just need to prove:

$$P(t_1, s_2) \wedge s_1 = h_1 :: t_1 \implies P(s_1, s_2) \wedge s_1 \neq [] \wedge s_1 = h_1 :: t_1$$

$$[P(t_1, s_2) \wedge s_1 = h_1 :: t_1] s_3 = T(t_1, s_2) [P(s_1, s_2) \wedge Q(t_1, s_2) \wedge s_1 = h_1 :: t_1]$$

$$P(s_1, s_2) \wedge s_1 \neq [] \wedge s_1 = h_1 :: t_1 \wedge Q(s_3) \implies P(s_1, s_2) \wedge Q(t_1, s_2) \wedge s_1 = h_1 :: t_1$$

However, we can still not prove it, as we do not know if $\exists u, mem(s_1, u) \land mem(s_2, u)$ (required by $P(s_1, s_2)$). One counter example is

$$s_1 \equiv [1; 1], s_2 \equiv [1; 3],$$

 $h_1 \equiv 1, t_1 \equiv [1]$

which means the precondition $P(s_1, s_2)$ should be strengthen (or $P(s_1, s_2)$ should be weaken). On the other hand, we encounter another similar implication when we try to finish the proof:

$$P(s_1, s_2) \land Q(v) \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3$$

We first introduce a new specification rule:

$$P(\overline{x})]\overline{y} = T(\overline{x})[R(\overline{x}, \overline{y}, \overline{z}) \land P(\overline{x}) \land Q(\overline{y})]$$

$$P(\overline{x}) \wedge Q(\overline{y}) \implies \exists \overline{z}, R(\overline{x}, \overline{y}, \overline{z}) \wedge P(\overline{x}) \wedge Q(\overline{y})$$

——— Spec-Frame

Spec(T, (P, Q))

Now we set $R(\overline{x}, \overline{y}, \overline{z})$ as $s_1 = h_1 :: t_1 \land v = h_1 :: s_3$ and we just need to prove:

$$P(s_1, s_2) \land Q(v) \land s_1 = h_1 :: t_1 \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: s_3 \implies P(s_1, s_2) \land s_2 = h_1 :: t_1 \land Q(s_3) \land v = h_1 :: t_2 \land Q(s_3) \land v = h_1 :: t_3 \land Q(s_3) \land Q(s_3) \land v = h_1 :: t_3 \land Q(s_3) \land$$

Still, we cannot prove it, as we do not know if $dup(s_3)$ (required by $Q(s_3)$). One counter example is:

$$s_1 \equiv [1; 2], s_2 \equiv [1; 3], \nu = [1; 2; 1; 3]$$

 $h_1 \equiv 1, t_1 \equiv [2], s_3 = [2; 1; 3]$

which means the postcondition Q(v) should be strengthen (or $Q(s_3)$ should be weaken). Let's look deeper to make the problem clear. This counterexample will happen during the execution (unreachable from *concat* [1; 2] [1; 3]). Thus we expect $Q(s_3)$ to be consistent with [2; 1; 3]:

$$s_3 \equiv [2; 1; 3] \models Q(s_3)$$
 (1)

However, we also want $Q(s_3) \implies \neg \Phi$, thus

$$s_3 \equiv [2;1;3] \models dup(s_3) \tag{2}$$

which is impossible, thus (P, Q) is not inductive,

4 Anon.

1.4 Cannot find an inductive invariant

Assume there exists an inductive invariant (P_I, Q_I) can help to prove (P, Q). Following the consequence rule, we expect:

$$\frac{P_I \Longrightarrow P \quad [P_I]C[Q_I] \quad Q \Longrightarrow Q_I}{[P]C[Q]} \text{ Con}$$

where

$$P_{I}(s_{1}, s_{2}) \wedge Q_{I}(v) \wedge s_{1} = h_{1} :: t_{1} \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{2} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{2} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge Q_{I}(s_{3}) \wedge v = h_{1} :: s_{3} \implies P_{I}(s_{1}, s_{2}) \wedge s_{2} \neq [] \wedge s_{2} \neq [] \wedge s_{3} \neq$$

Notice that, the new postcondition Q_I is not required to be a subset of $\neg \Phi$. There are two reachable paths:

$$s_1 \equiv [1; 2], s_2 \equiv [1; 3], \nu = [1; 2; 1; 3]$$

 $h_1 \equiv 1, t_1 \equiv [2], s_3 = [2; 1; 3]$ (X₁)

and

$$s_1 \equiv [2; 1], s_2 \equiv [1; 3], v = [2; 1; 1; 3]$$

 $h_1 \equiv 2, t_1 \equiv [1], s_3 = [1; 1; 3]$ (X₂)

To be proved

Thus we expect Q_I consistent with these four concrete values: [2;1;3], [1;2;1;3], [1;1;3] and [2;1;1;3]. Then Q_I contains both duplicate stacks and non-duplicate stacks, and if a stack s_3 can satisfy Q_I dependents on if h_1 is a member of s_3 . If we do not know the value of h_1 , we cannot decide if a given stack can satisfy Q_I . However, h_1 is not belong to the arguments or the result of calling $s_3 = T(t_1, s_2)$.

1.5 Mutual inductive invariant

I believe the problem is that, we want Q_I to include both duplicate stacks and non-duplicate stacks. Alternatively, if we have two inductive invariants:

$$P_{1} \equiv \neg dup(s_{1}) \land \neg dup(s_{2}) \land \exists u, mem(s_{1}, u) \land mem(s_{2}, u)$$

$$Q_{1} \equiv \neg dup3(v) \land dup(v)$$

$$[P_{1}]v = T(s_{1}, s_{2})[Q_{1}]$$

$$P_{2} \equiv \neg dup(s_{1}) \land \neg dup(s_{2}) \land \forall u, \neg mem(s_{1}, u) \lor \neg mem(s_{2}, u)$$

$$Q_{2} \equiv \neg dup3(v) \land \neg dup(v)$$

$$[P_{2}]v = T(s_{1}, s_{2})[Q_{2}]$$

These two triples have disjointed precondition (with guard $\exists u, mem(s_1, u) \land mem(s_2, u)$) and disjointed postcondition (with guard dup(v)).

Now we revisit the proof tree:

$$\frac{[P_{1}(s_{1},s_{2}) \land s_{1} \neq []]}{[P_{1}(s_{1},s_{2}) \land s_{1} \neq []]} \xrightarrow{Assign} \frac{[P_{1}(s_{1},s_{2}) \land s_{1} \neq [] \land s_{1} = h_{1} :: t_{1}]}{[P_{1}(s_{1},s_{2}) \land s_{1} \neq [] \land s_{1} = h_{1} :: t_{1}]} \xrightarrow{s_{3} := T(t_{1},s_{2}); v := h_{1} :: s_{3}}$$

$$\frac{[P_{1}(s_{1},s_{2}) \land s_{1} \neq []);}{[P_{1}(s_{1},s_{2}) \land s_{1} \neq []]} \xrightarrow{[P_{1}(s_{1},s_{2}) \land s_{1} \neq []](h_{1},t_{1}) := cons^{-1}(s_{1}); ...[... \land Q_{1}(v)]} \xrightarrow{Seq}$$

$$\frac{[P_{1}(s_{1},s_{2})] \text{assume } \neg(s_{1} := []); (h_{1},t_{1}) := cons^{-1}(s_{1}); ...[... \land Q_{1}(v)]}{[P_{1}(s_{1},s_{2})]T(s_{1},s_{2}) = v[F \land P_{1}(s_{1},s_{2}) \land Q_{1}(v)]} \xrightarrow{Spec(T,(P_{1},Q_{1}))} \xrightarrow{Spec-Frame}$$

where F is the framing formula (we will set it later).

In order to distinguish the two concrete executions X_1 and X_2 , we use the disjunction rule

200

201

202

204

205

206

207

208

210

222

224

226

230

231 232

233 234

235

236

237

238

239

240

241

242

243

244

245

```
\frac{[P_1]C[Q_1] \qquad [P_2]C[Q_2]}{[P_1 \vee P_2]C[Q_1 \vee Q_2]} \text{ Disjunction}
```

to split current precondition $P_1(s_1, s_2) \wedge s_1 \neq [] \wedge s_1 = h_1 :: t_1$ by the guard $\exists u, mem(s_1, u) \wedge mem(s_2, u)$ to decide to apply which inductive invariant:

```
 \begin{array}{ll} [P_1(s_1,s_2)... \wedge \exists u, mem(t_1,u) \wedge mem(s_2,u)] & [P_1(s_1,s_2)... \wedge \neg (\exists u, mem(t_1,u) \wedge mem(s_2,u))] \\ s_3 \coloneqq T(t_1,s_2); v \coloneqq h_1 \coloneqq s_3 & s_3 \coloneqq T(t_1,s_2); v \coloneqq h_1 \coloneqq s_3 \\ [\underline{F} \wedge P_1(s_1,s_2) \wedge Q_1(v) \wedge \exists u, mem(t_1,u) \wedge mem(s_2,u)] & [F \wedge P_1(s_1,s_2) \wedge Q_1(v) \wedge \neg (\exists u, mem(t_1,u) \wedge mem(s_2,u))] \\ & [P_1(s_1,s_2) \wedge s_1 \neq [] \wedge s_1 = h_1 \equiv t_1] \\ s_3 \coloneqq T(t_1,s_2); v \coloneqq h_1 \equiv s_3 \\ [F \wedge P_1(s_1,s_2) \wedge Q_1(v)] & \\ & [F \wedge P_1(s_1,s_2) \wedge Q_1(v)] \end{array}  Disj
```

where we plan to apply $[P_1]T[Q_1]$ in the first case and $[P_1]T[Q_1]$ in the second case. However, we want to eliminate the unreachable states from the postcondition $F \wedge P_1(s_1, s_2) \wedge Q_1(\nu)$. For example, in the first case, after we apply the $[P_1]T[Q_1]$, the predicate $dup(s_3)$ should hold. Thus we set F as:

```
F \equiv s_1 = h_1 :: t_1 \wedge v = h_1 :: s_3 \wedge 
((\exists u, mem(t_1, u) \wedge mem(s_2, u)) \implies (dup(s_3) \wedge \neg dup3(s_3))) \wedge 
(\neg (\exists u, mem(t_1, u) \wedge mem(s_2, u)) \implies (\neg dup(s_3) \wedge \neg dup3(s_3) \wedge mem(s_2, h_1)))
```

For the first situation we have:

```
Spec(T, (P_1, Q_1))

    Apply-Frame

[P_1(t_1, s_2) \wedge s_1 = h_1 ::
t_1 \wedge \neg mem(t_1, h_1) \wedge \exists u, mem(t_1, u) \wedge mem(s_2, u)

    Assign

                                                                                                                                                     [...]
s_3 := T(t_1, s_2)
[P_1(t_1, s_2) \land Q_1(s_3) \land s_1 = h_1 ::
                                                                                                                                                     v := h_1 :: s_3
t_1 \wedge \neg mem(t_1, h_1) \wedge \exists u, mem(t_1, u) \wedge mem(s_2, u)
                                                                                                                                                     [.. \wedge \nu = h_1 :: s_3]
                                                                                                                                    - Cons
                                                                                                                                                           [... \land \exists u, mem(t_1, u) \land mem(s_2, u) \land Q_1(s_3))]
                                  [... \land \exists u, mem(t_1, u) \land mem(s_2, u)]
                                 s_3 := T(t_1, s_2)
                                                                                                                                                           v := h_1 :: s_3
                                  [... \land \exists u, mem(t_1, u) \land mem(s_2, u) \land Q_1(s_3))]
                                                                                                                                                           [\dots \wedge Q_1(v) \wedge \exists u, mem(t_1, u) \wedge mem(s_2, u)]
                                                             [P_1(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land \exists u, mem(t_1, u) \land mem(s_2, u)]
                                                             s_3 := T(t_1, s_2); v := h_1 :: s_3
                                                             [ \textcolor{red}{F} \land P_1(s_1, s_2) \land Q_1(v) \land \exists u, mem(t_1, u) \land mem(s_2, u) ]
```

where:

```
\begin{split} \phi_a &\equiv \\ P_1(t_1,s_2) \wedge s_1 &= h_1 :: t_1 \wedge \neg mem(t_1,h_1) \wedge \exists u, mem(t_1,u) \wedge mem(s_2,u) \implies \\ P_1(s_1,s_2) \wedge s_1 &\neq \big[\big] \wedge s_1 &= h_1 :: t_1 \wedge \exists u, mem(t_1,u) \wedge mem(s_2,u) \\ \phi_b &\equiv \\ & F \wedge P_1(s_1,s_2) \wedge Q_1(v) \wedge \exists u, mem(t_1,u) \wedge mem(s_2,u) \implies \\ P_1(s_1,s_2) \wedge s_1 &\neq \big[\big] \wedge s_1 &= h_1 :: t_1 \wedge \exists u, mem(t_1,u) \wedge mem(s_2,u) \wedge Q_1(s_3) \wedge v &= h_1 :: s_3 \end{split}
```

It is easy to check that these two implication are valid.

```
For the second situation we have:
```

```
    Apply-Frame

[P_2(t_1, s_2) \land s_1 = h_1 ::
t_1 \land \neg mem(t_1, h_1) \land mem(s_2, h_1) \land \neg (\exists u, mem(t_1, u) \land mem(s_2, u))]
s_3 := T(t_1, s_2)
                                                                                                                                                    [...]
[P_2(t_1, s_2) \land Q_2(s_3) \land s_1 = h_1 ::
                                                                                                                                                    \nu:=h_1::s_3
t_1 \land \neg mem(t_1,h_1) \land mem(s_2,h_1) \land \neg (\exists u,mem(t_1,u) \land mem(s_2,u)) \rceil
                                                                                                                                                    [.. \wedge v = h_1 :: s_3]
                                                                                                                                     Cons
                                                                                                                                                       [... \land \neg (\exists u, mem(t_1, u) \land mem(s_2, u)) \land Q_1(s_3))]
                      [... \land \neg(\exists u, mem(t_1, u) \land mem(s_2, u))]
                      s_3 := T(t_1, s_2)
                                                                                                                                                       \nu := h_1 :: s_3
                                                                                                                                                       [... \land Q_1(v) \land \neg(\exists u, mem(t_1, u) \land mem(s_2, u))]
                      [... \land \neg(\exists u, mem(t_1, u) \land mem(s_2, u)) \land Q_2(s_3))]
                                                         \overline{[P_1(s_1,s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1 \land \neg (\exists u, mem(t_1,u) \land mem(s_2,u))]}
                                                         s_3 := T(t_1, s_2); v := h_1 :: s_3
                                                         [F \land P_1(s_1, s_2) \land Q_1(v) \land \neg(\exists u, mem(t_1, u) \land mem(s_2, u))]
```

6 Anon.

where:

246 247

248 249

251

253

255 256

257

259 260

261

262

263

269

271

273

281 282

283 284

285 286

287

288

290

291

292

293 294

$$\phi_{a} \equiv P_{2}(t_{1}, s_{2}) \wedge s_{1} = h_{1} :: t_{1} \wedge \neg mem(t_{1}, h_{1}) \wedge mem(s_{2}, h_{1}) \wedge \neg (\exists u, mem(t_{1}, u) \wedge mem(s_{2}, u)) \Longrightarrow P_{1}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge \neg (\exists u, mem(t_{1}, u) \wedge mem(s_{2}, u))$$

$$\phi_{b} \equiv F \wedge P_{1}(s_{1}, s_{2}) \wedge Q_{1}(v) \wedge \neg (\exists u, mem(t_{1}, u) \wedge mem(s_{2}, u)) \Longrightarrow P_{1}(s_{1}, s_{2}) \wedge s_{1} \neq [] \wedge s_{1} = h_{1} :: t_{1} \wedge \neg (\exists u, mem(t_{1}, u) \wedge mem(s_{2}, u)) \wedge Q_{1}(s_{3}) \wedge v = h_{1} :: s_{3}$$

Let's focus on ϕ_b , if stack t_1 and stack s_2 does not contain same element (as $\neg(\exists u, mem(t_1, u) \land mem(s_2, u))$), but s_1 and s_2 does (as P_1), it means the the shared element has to be h_1 :

$$mem(s_1, h_1) \wedge mem(s_2, h_1)$$

It is easy to check that these two implication are valid.

The proof of $Spec(T, (P_2, Q_2))$ is similar, but we do not need the help of (P_1, Q_2) :

```
Spec(T, (P_1, Q_1))

    Apply-Frame

[P_2(t_1, s_2) \land s_1 = h_1 :: t_1 \land \neg mem(t_1, h_1) \land \neg mem(s_2, h_1)]
                                                                                                                                                  v := h_1 :: s_3
[P_2(t_1, s_2) \land Q_2(s_3) \land s_1 = h_1 :: t_1 \land \neg mem(t_1, h_1) \land \neg mem(s_2, h_1)]
                                                                                                                                                  [.. \wedge \nu = h_1 :: s_3]
                                                                                                                                  - Cons

    Con

                                                                                                                                                                              [... \wedge Q_2(s_3))]
                                                      s_3 := T(t_1, s_2)
                                                                                                                                                                              \nu := h_1 :: s_3
                                                                                                                                                                              [\dots \wedge Q_2(\nu)]
                                                      [... \wedge Q_2(s_3))]
                                                            [P_2(s_1, s_2) \land s_1 \neq [] \land s_1 = h_1 :: t_1]
                                                            s_3 := T(t_1, s_2); \nu := h_1 :: s_3
                                                            [F \wedge P_2(s_1, s_2) \wedge Q_2(v)]
```

where

$$F \equiv s_{1} = h_{1} :: t_{1} \land v = h_{1} :: s_{3}$$

$$\phi_{a} \equiv P_{2}(t_{1}, s_{2}) \land s_{1} = h_{1} :: t_{1} \land \neg mem(t_{1}, h_{1}) \land \neg mem(s_{2}, h_{1}) \implies P_{2}(s_{1}, s_{2}) \land s_{1} \neq [] \land s_{1} = h_{1} :: t_{1}$$

$$\phi_{b} \equiv F \land P_{2}(s_{1}, s_{2}) \land Q_{2}(v) \implies P_{2}(s_{1}, s_{2}) \land s_{1} \neq [] \land s_{1} = h_{1} :: t_{1} \land Q_{2}(s_{3}) \land v = h_{1} :: s_{3}$$

It is easy to check that these two implication are valid.

1.6 Single inductive invariant

Can we merge $[P_1]T[Q_1]$ and $[P_2]T[Q_2]$ as a single triple? If we simply apply the disjunction rule, we have:

 $\frac{[P_1]C[Q_1]}{[P_1\vee P_2]C[Q_1\vee Q_2]}$ Disjunction where $P_1\vee P_2$ and $Q_1\vee Q_2$ exactly equal to Σ and $\neg\Phi$ which

is proved not even a underapproximation triple. The problem is that, the disjoint rule approximates too much, especially at the postcondition side (as it should merge Q_1 and Q_2 , but also rules out the unreachable states).

Now we extend the postcondition Q not only describe v but also s_1 and s_2 . Now we have:

$$\begin{split} P_1 &\equiv \neg dup(s_1) \land \neg dup(s_2) \land \exists u, mem(s_1, u) \land mem(s_2, u) \\ Q_1 &\equiv \neg dup3(v) \land dup(v) \\ [P_1]v &= T(s_1, s_2)[P_1 \land Q_1] \\ P_2 &\equiv \neg dup(s_1) \land \neg dup(s_2) \land \forall u, \neg mem(s_1, u) \lor \neg mem(s_2, u) \\ Q_2 &\equiv \neg dup3(v) \land \neg dup(v) \\ [P_2]v &= T(s_1, s_2)[P_2 \land Q_2] \end{split}$$

The a single inductive invariant can be:

$$[P_1 \lor P_2]v = T(s_1, s_2)[(P_1 \land Q_1) \lor (P_2 \land Q_2)]$$

that is:

$$[\neg dup(s_1) \land \neg dup(s_2) \land \exists u, mem(s_1, u) \land mem(s_2, u)]$$

$$v = T(s_1, s_2)$$

$$[\neg dup3(v) \land ((\exists u, mem(s_1, u) \land mem(s_2, u)) \implies dup(v)) \land (\neg (\exists u, mem(s_1, u) \land mem(s_2, u)) \implies \neg dup(v))]$$

ACKNOWLEDGEMENTS REFERENCES