

Asymmetric - noise - based binary classification using EM algorithm.



Model

1. confusion matrix T .
for i -th annotator: $\begin{bmatrix} \alpha^i & 1-\alpha^i \\ 1-\beta^i & \beta^i \end{bmatrix}$

2. classifier.

$$p(y|x) = \sigma(\omega^T x)$$

Maximum likelihood. $\theta = \{\alpha, \beta, \omega\}$

$$p(D|\theta) = \prod_{i=1}^N p(y_i^1, y_i^2, \dots, y_i^R | x_i; \theta)$$

全概率公式

$$= \prod_{i=1}^N \{ p(y_i^1, y_i^2, \dots, y_i^R | y=1, x_i; \alpha) \cdot p(y=1 | x_i; \omega) + p(y_i^1, y_i^2, \dots, y_i^R | y=0, x_i; \beta) \cdot p(y=0 | x_i; \omega) \}$$

y_i^j 独立

$$= \prod_{i=1}^N \left\{ \prod_{j=1}^R p(y_i^j | y=1, x_i; \alpha) \cdot p(y=1 | x_i; \omega) + \prod_{j=1}^R p(y_i^j | y=0, x_i; \beta) \cdot p(y=0 | x_i; \omega) \right\}$$

独立伯努利分布

$$= \prod_{i=1}^N \underbrace{\frac{\alpha^i}{\prod_{j=1}^R \alpha^i}}_{a_i} \underbrace{(1-\alpha^i)^{1-y_i^1}}_{p_i} \underbrace{\frac{\beta^i}{\prod_{j=1}^R \beta^i}}_{b_i} \underbrace{(1-\beta^i)^{1-y_i^2}}_{1-p_i}$$

$$= \prod_{i=1}^N \underbrace{a_i p_i}_{\text{对应 } y=1 \text{ 时}} + \underbrace{b_i (1-p_i)}_{\text{对应 } y=0 \text{ 时}}$$

$$\hat{\theta}_{ML} = \underset{\theta}{\operatorname{argmax}} \{ \ln p(D|\theta) \}$$

EM algorithm.

E. 通过对 y 的现有估计值, 计算期望的似然值.

$$\text{let } \mu_i = p(y_i=1 | x_i, y_i^1, \dots, y_i^R; \theta)$$

已知 θ, D .

$$\mu_i = \frac{p(y_i^1, \dots, y_i^R | y_i=1, \alpha) \cdot p(y_i=1 | x_i, \omega)}{p(y_i^1, \dots, y_i^R | x_i; \theta)} = \frac{a_i p_i}{a_i p_i + b_i (1-p_i)}$$

M. 最大化求解

$$\theta^{(t+1)} = \underset{\theta}{\operatorname{argmax}} \left\{ \sum_{i=1}^n \mu_i \ln a_i p_i + (1-\mu_i) \ln b_i (1-p_i) \right\}$$

$$\hat{\alpha}^i = \frac{\sum_{i=1}^n \mu_i y_i^1}{\sum_{i=1}^n \mu_i} \quad \hat{\beta}^i = \frac{\sum_{i=1}^n (1-\mu_i) (1-y_i^2)}{\sum_{i=1}^n (1-\mu_i)}$$

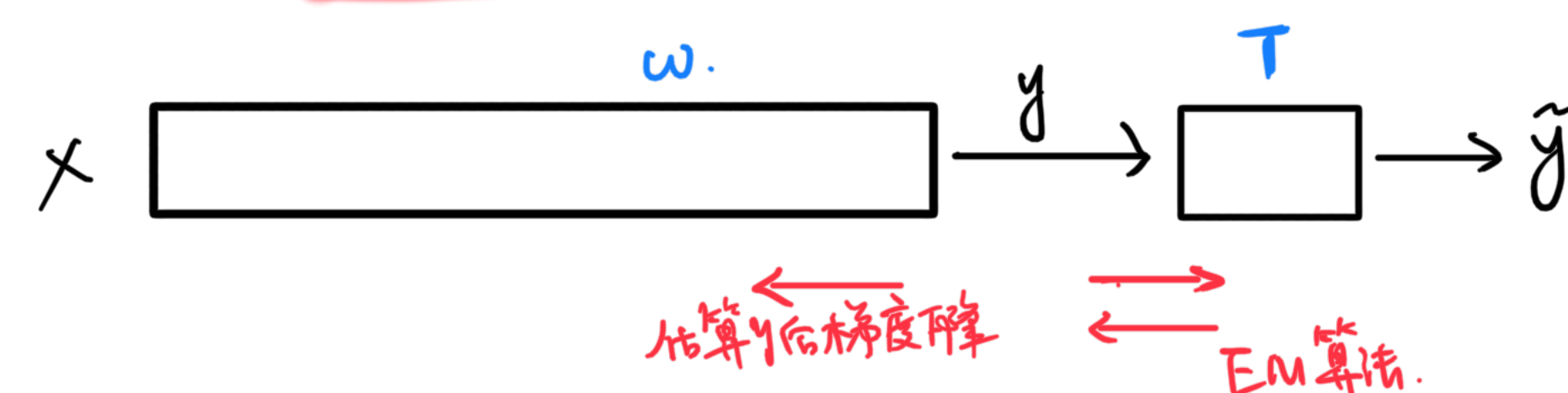
for ω .

$$L(\omega) = \sum_{i=1}^n (\mu_i - \sigma(\omega^T x_i))^2 \quad \text{gradient descent.}$$

总结. (对噪声显式建模 T).



1. generalized EM



从 $p(x, \tilde{y})$ 分布中从两边求得 y

2. Annotation confusion. \longleftarrow 梯度下降



加入正则项使得 $T \rightarrow$ confusion matrix of each annotator.

3. C-model



将 T 等效为 softmax, 使得 T 从 CM 升级为 $u^T x + b$ 的噪声延伸卡.