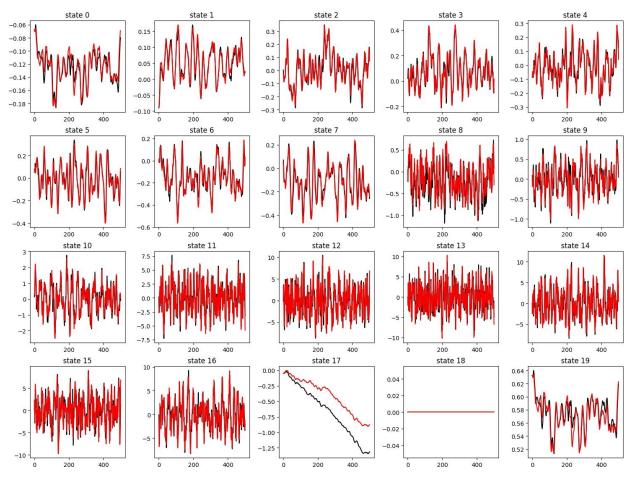
Problem 1

(a)

Model predictions (red) versus ground truth (black) for open-loop predictions



(b) Predictions for state 17 is most inaccurate. This is probably because the test trajectory keeps decreasing for this dimension, so the prediction errors are accumulated.

Problem 2

Random policy

ReturnAvg -145.931 ReturnMax -113.702

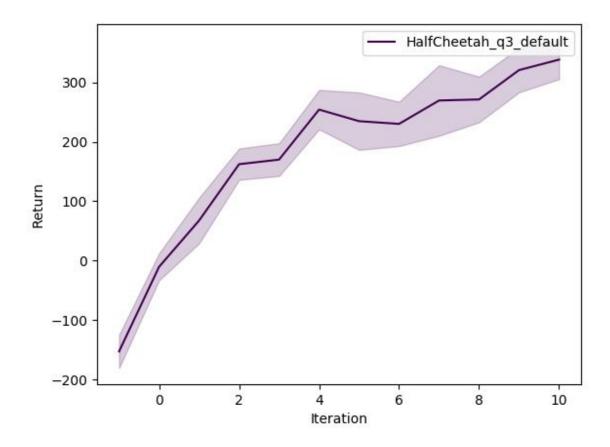
ReturnMin -194.955

ReturnStd 24.4834

Trained policy

ReturnAvg -3.95774
ReturnMax 57.4863
ReturnMin -36.0475
ReturnStd 28.4027
TrainingLossFinal 107.842
TrainingLossStart 5269.59

Problem 3a



Problem 3b

