

Retarded Green Function

$$\left(m \frac{d^2}{dt^2} + m\gamma \frac{d}{dt} + m\omega^2 \right) X = \delta(t - t_0) = F(t)$$

L_t

Here force is a delta function symbolizing an impulsive kick.

Now suppose the solution to this equation

is $\underline{x(t)} = G_R(t, t_0)$ \Leftarrow call $G_R(t, t_0)$ \Rightarrow Green's func.

Or t depends on t_0 , or when you kick the system.

$$L_t G_R(t, t_0) = \delta(t - t_0)$$

Then we can use $G_R(t, t_0)$ to find the solution of the original equation.

Then the specific solution is

$$X_S(t) = \int_{-\infty}^{\infty} dt_0 G_R(t, t_0) F(t_0)$$

after we determined the Green function,

To prove:

$\cap \infty$

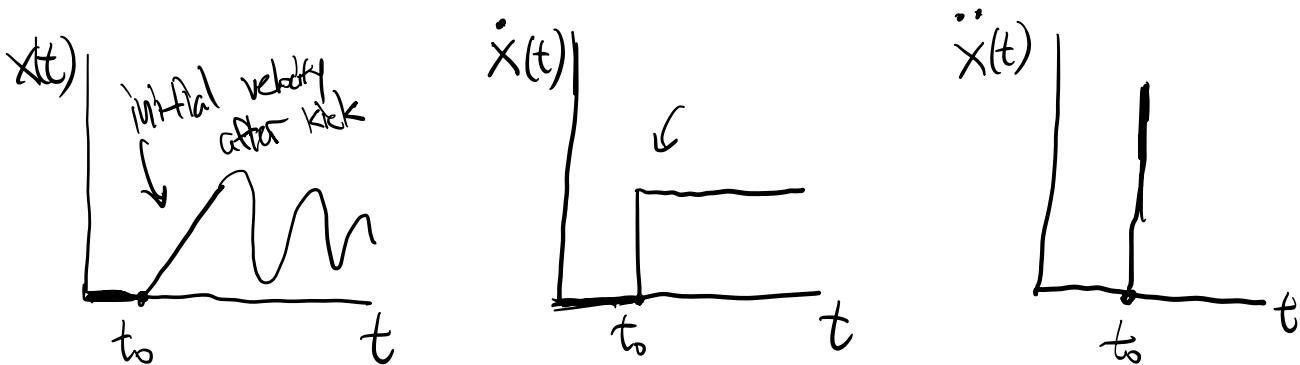
$$\mathcal{L}_t X_S(t) = \int_{-\infty}^{\infty} dt_0 \underbrace{\mathcal{L}_t G_R(t, t_0)}_{\delta(t-t_0)} F(t_0)$$

$$\mathcal{L}_t X_S(t) = F(t)$$

Green Function:

A function that satisfy the following equation:

$$\left(m \frac{d^2}{dt^2} + m\gamma \frac{d}{dt} + m\omega^2 \right) G_R(t, t_0) = \delta(t - t_0) = F(t)$$



Need few conditions

↖ No movement before the kick.

① $G_R(t, t_0) = 0$ for $t < t_0$ ← Retarded condition.

② $t > t_0$ $\mathcal{L}_t G_R(t, t_0) = 0$ ← G_R satisfies Homogeneous solution.

Boundary Conditions:

① Continuity: $\lim_{t \rightarrow t_0^+} G_R(t, t_0) = 0$

② Determine G by integrate equation of motion.

$$\int_{t_0-\epsilon}^{t_0+\epsilon} dt \left[m \frac{d^2 G}{dt^2} + m\gamma \frac{dG}{dt} + m\omega^2 G \right] = \int_{t_0-\epsilon}^{t_0+\epsilon} dt \delta(t - t_0) = 1$$

$$\int_{t_0-\epsilon}^{t_0+\epsilon} dt m\omega^2 G(t, t_0) = 0$$

Since $\lim_{t \rightarrow t_0^-} G_R(t, t_0) = 0$, condition ①

then due to continuity, $\lim_{t \rightarrow t_0^+} G_R(t, t_0) = 0$.

so overall $\int_{t_0-\epsilon}^{t_0+\epsilon} dt G(t, t_0) m\omega^2 = 0$

$$\hookrightarrow m \frac{dG}{dt} \Big|_{t=t_0-\epsilon}^{t=t_0+\epsilon} + m\gamma G \Big|_{t=t_0-\epsilon}^{t=t_0+\epsilon} = 1$$

≈ 0 since

G is continuous.

$$m \frac{dG}{dt} \Big|_{t=t_0-\epsilon}^{t=t_0+\epsilon} = m \frac{dG}{dt}(t_0+\epsilon, t_0) - \underbrace{m \frac{dG}{dt}(t_0-\epsilon, t_0)}_{=0} = 1$$

t

$\Rightarrow 0$ since

$$\lim_{t \rightarrow t_0^-} \frac{dG}{dt} = 0$$

$$\hookrightarrow \boxed{m \frac{dG}{dt} \Big|_{t=t_0} = 1}$$

Use it to find constant
amplitude and phase for $t > t_0$.
 \rightarrow used to reproduce initial condition.

For $t > t_0$, we have $\delta(t-t_0) = 0$, so E_R take
the form of homogeneous solution.

$$\begin{cases} G_R(t, t_0) = X_h(t) = A \cos(-\omega(t-t_0) + \phi) e^{-\frac{\eta}{2}(t-t_0)} & \text{for } t > t_0 \\ G_R(t, t_0) = 0 & \text{for } t < t_0 \end{cases}$$

Now use boundary conditions to determine
amplitude A , and ϕ .

$$\textcircled{1} \quad \lim_{t \rightarrow t_0^+} G_R(t, t_0) = 0$$

$$\textcircled{2} \quad m \frac{dG_R(t, t_0)}{dt} \Big|_{t=t_0} = 1$$

Then the condition \textcircled{1} implies $\phi = \frac{\pi}{2}$

$$G_R = A \cos(-\omega'(t-t_0) + \frac{\pi}{2}) e^{-\frac{\eta}{2}(t-t_0)}$$

$$= -A \sin(-\omega'(t-t_0)) e^{-\frac{\eta}{2}(t-t_0)}$$

Condition \textcircled{2}

$$m \frac{dG}{dt} \Big|_{t=t_0} = -\omega'^2 m A \cos(-\omega'(t-t_0)) e^{-\frac{\eta}{2}(t-t_0)} \Big|_{t=t_0}$$

$$-\frac{\eta}{2} A m \sin(-\omega'(t-t_0)) e^{-\frac{\eta}{2}(t-t_0)} \Big|_{t=t_0} = 1$$

$$\hookrightarrow -\omega'^2 m A = 1$$

$$\Rightarrow A = \frac{-1}{\omega'^2 m}$$

Then

$$G_R(t, t_0) = \frac{-1}{\omega'^2 m} \sin(-\omega'(t-t_0)) e^{-\frac{\eta}{2}(t-t_0)} \quad \text{for } t > t_0$$

$$G_R(t, t_0) = 0 \quad \text{for } t < t_0$$

Combine both by using $\Theta(t-t_0) = \begin{cases} 1 & t > t_0 \\ 0 & \text{otherwise} \end{cases}$

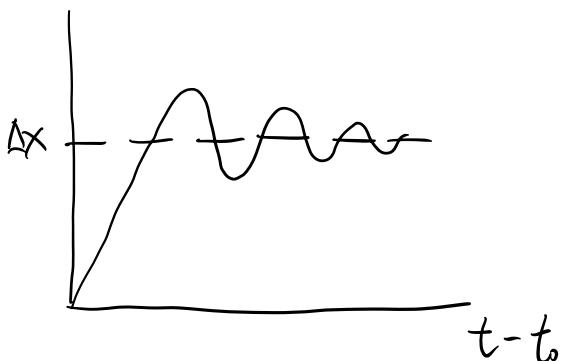
$$\hookrightarrow G_R(t, t_0) = \frac{-\Theta(t-t_0)}{m^2} \sin(-\omega(t-t_0)) e^{-\frac{\gamma}{2}(t-t_0)}$$

Examples:

Consider

$$f(t) = \begin{cases} 0 & t < 0 \\ f_0 & t > 0 \end{cases}$$

expect $t \rightarrow \infty$ $\Delta x = f_0 / m\omega_0^2$



Know

$$X_S(t) = \int_{-\infty}^{\infty} dt_0 G_R(t, t_0) F(t_0)$$

and recall $G_R(t, t_0) = 0$ when $t < t_0$

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We also know $\bar{F}(t_0) = \begin{cases} 0 & t_0 < 0 \\ f_0 & t_0 > 0 \end{cases}$ or $t_0 > t$

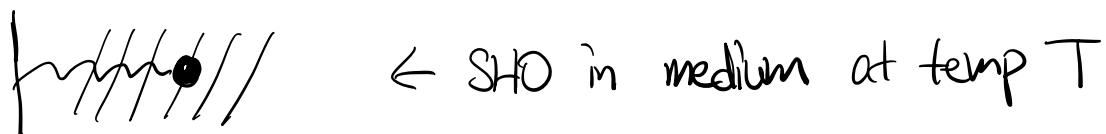
$$\begin{aligned} X_S(t) &= \int_{-\infty}^0 \int_0^t \int_t^\infty dt_0 G_R(t, t_0) \bar{F}(t_0) \\ &\stackrel{!}{=} \int_0^t dt_0 G_R(t, t_0) F(t_0) \\ &\stackrel{!}{=} \int_0^t dt_0 G_R(t, t_0) f_0 \end{aligned}$$

$$X_S(t) \stackrel{!}{=} \int_0^t e^{-\frac{\gamma}{2}(t-t_0)} \frac{\sin(\omega(t-t_0))}{m\omega_b} f_0 dt_0$$

↑ Finds the specific solution.

Example 2:

Brownian Motion:



$$\left(m \frac{d^2}{dt^2} + m\gamma \frac{d}{dt} + m\omega_b^2 \right) X = F(t)$$

Force by medium

Consider random force since the timescale of the medium exerting the force is very short.

For random force:

$$\langle F(t) \rangle = 0$$

$$\langle F(t) F(t') \rangle = A \delta(t-t') \quad \begin{matrix} \leftarrow \text{squared force is zero} \\ \text{correlated when } t=t' \end{matrix}$$

\Rightarrow at late times,

$$P(x,p) = C e^{-H/T} \quad H = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

$$E = \langle H \rangle = \frac{\int dx dp P(x,p) H}{\int dx dp P(x,p)} = T$$

If at rest at $t=0$:

$$x(t) = \int_0^\infty G_R(t,t_0) F(t_0) dt_0$$

$$x(t) = \int_0^t \frac{F(t_0)}{m\omega_0} e^{-\frac{\eta}{2}(t-t_0)} \sin \omega_0(t-t_0) dt_0$$

Then the energy?

$$E = \frac{1}{2} m \omega_0^2 x^2 + \frac{1}{2} m \dot{x}^2$$

$$\begin{aligned} &= \frac{1}{2} \int_0^t dt_0 \int_0^t dt_0' \underbrace{\langle F(t_0) F(t_0') \rangle}_{m^2 \omega_0^2} e^{-\frac{\gamma}{2}(t-t_0)} e^{-\frac{\gamma}{2}(t-t_0')} \\ &\quad \times \left(\frac{1}{2} m \omega_0^2 \left[\sin \omega_0(t-t_0) \sin \omega_0(t-t_0') \right. \right. \\ &\quad \left. \left. + \cos \omega_0(t-t_0) \cos \omega_0(t-t_0') \right] \right) \end{aligned}$$

$$\text{Since } \langle F(t) F(t') \rangle = A \delta(t-t')$$

then

$$\begin{aligned} E &= \int_0^t dt_0 \int_0^t dt_0' \underbrace{\langle F(t_0) F(t_0') \rangle}_{m^2 \omega_0^2} e^{-\frac{\gamma}{2}(t-t_0)} e^{-\frac{\gamma}{2}(t-t_0')} \\ &\quad \times \left(\frac{1}{2} m \omega_0^2 \left[\sin \omega_0(t-t_0) \sin \omega_0(t-t_0') \right. \right. \\ &\quad \left. \left. + \cos \omega_0(t-t_0) \cos \omega_0(t-t_0') \right] \right) \end{aligned}$$

$$\begin{aligned} &= A \int_0^t dt_0 \frac{\delta(t-t_0)}{m^2 \omega_0^2} e^{-\frac{\gamma}{2}(t-t_0)} e^{-\frac{\gamma}{2}(t-t_0')} \\ &\quad \times \frac{1}{2} m \omega_0^2 \left(\sin \omega_0(t-t_0) \sin \omega_0(t-t_0') \right. \\ &\quad \left. + \cos \omega_0(t-t_0) \cos \omega_0(t-t_0') \right) \end{aligned}$$

$$\sim 2 \sin(\omega_0(t-t_0)) \sin(\omega_0(t-t'))$$

$$+ \cos(\omega_0(t-t_0)) \cos(\omega_0(t-t')) \Big)$$

$$= \int_0^t dt' A e^{-\eta(t-t')} \frac{1}{2} m \omega_0^2 \frac{1}{m^2 \omega_0^2} (\sin^2 \omega_0(t-t') + \cos^2 \omega_0(t-t'))$$

$$= \int_{t_0}^t dt' \frac{A}{2m} e^{-\eta(t-t')}$$

$$= \frac{A}{2m\eta} e^{-\eta(t-t_0)} \Big|_0^t$$

$$= \frac{A}{2m\eta} (1 - e^{-\eta t})$$

at $t > \infty$, $E = T$

so $\boxed{A = 2m\eta T}$ $\langle F(t) F(t') \rangle = 2m\eta T \delta(t-t')$

Example 3: HW#7 problem 2:

a) Determine the retarded green function for the following:

$$i) \frac{da}{dt} - i\omega_0 a = 0$$

Determine green function by integrating dt around $\int_{t-\epsilon}^{t+\epsilon}$

$$\int \left(dG_R - i\omega_0 \tau_{t+\epsilon} \right) dt - \int_{t-\epsilon}^{t+\epsilon} \tau(t-t') dt = 1$$

$$\int_{t_0-\epsilon}^{t_0} \left(\frac{d}{dt} - i\omega_0 \right) G_R(t, t_0) dt = \int_{t_0-\epsilon}^{t_0} \left(\frac{d}{dt} - i\omega_0 \right) G_R(t, t_0) dt$$

$$G_R \Big|_{t=t_0}^{t=t_0+\epsilon} - \underbrace{\int_{t_0-\epsilon}^{t_0+\epsilon} i\omega_0 G_R(t, t_0) dt}_{=0} = 1$$

$G_R(t, t_0) = 0$ for $t < t_0$
 $G_R(t, t_0) = 0$ for $t > t_0$
 Homogeneous condition.

$$G_R \Big|_{t=t_0+\epsilon} - G_R \Big|_{t=t_0} = 1$$

$G_R = 0$ for $t < t_0$

$$G_R \Big|_{t=t_0+\epsilon} = 1$$

For $\frac{da}{dt} - i\omega_0 a = 0$

$$G_R(t, t_0) = A e^{-i\omega_0(t-t_0)} + \phi$$

$$G_R(t_0+\epsilon, t_0) = A e^{i\phi} = 1$$

$$A = e^{-i\phi}$$

$$G_R(t, t_0) = e^{-i\omega_0(t-t_0)} \quad \text{for } t > t_0$$

$$G_R(t, t_0) = 0 \quad \text{for } t < t_0$$

ii) $\ddot{x} + \gamma \dot{x} = 0$

Get green function, replace equation with

$$\frac{d^2}{dt^2} r \propto 1 + n \frac{d}{dt} r \propto 1 - \delta(t - t_0)$$

$$\frac{d}{dt^2} G_R(t, t_0) + \eta \frac{d}{dt} G_R(t, t_0) = 0 \quad (1)$$

$$\int_{t-\epsilon}^{t+\epsilon} \left(\frac{d^2}{dt^2} G_R(t, t_0) + \eta \frac{d}{dt} G_R(t, t_0) \right) dt = \int_{t-\epsilon}^{t+\epsilon} f(t-t_0) dt = 1$$

$$\frac{d}{dt} G_R(t, t_0) \Big|_{t=t_0} + \eta G_R \Big|_{t=t_0}^{t+\epsilon} = 1$$

$$\frac{d}{dt} G_R(t, t_0) \Big|_{t=t_0} - \underbrace{\frac{d}{dt} G_R(t, t_0)}_{=0} + \eta \left(\underbrace{G_R \Big|_{t=t_0}}_{\text{since } G_R \Big|_{t=t_0}=0} - \underbrace{G_R \Big|_{t=t_0-\epsilon}}_{\substack{=0 \\ \text{due to continuity}}} \right) = 1$$

Since $G_R = 0$ for $t < t_0$.

$$\frac{d}{dt} G_R(t, t_0) \Big|_{t=t_0} = 1$$

$$\text{For } t > t_0, \quad \ddot{G}_R + \eta \dot{G}_R = 0$$

$$\frac{d}{dt} G_R(t, t_0) = A e^{-\eta(t-t_0)} + \phi$$

$$G_R(t, t_0) = \frac{A}{\eta} e^{-\eta(t-t_0)} + \phi = \frac{A}{\eta} e^{-\eta(t-t_0)} e^\phi + \text{const}$$

$$= A' e^{-\eta(t-t_0)} + B$$

$$\text{Know } G_R(t, t_0) \Big|_{t=t_0} = 0$$

$$G_R(t_0, t_0) = A' + B = 0 \quad \text{or} \quad A' = -B$$

$-n(t-t_0)$

$$\text{So } G_R(t, t_0) = B(-e^{-\eta(t-t_0)} + 1)$$

$$\text{know } \left. \frac{dG_R}{dt} \right|_{t=t_0} = 1$$

$$\hookrightarrow B\eta e^{\eta(t-t_0)} \Big|_{t_0} = 1$$

$$\hookrightarrow B\eta = 1$$

$$B = \frac{1}{\eta}$$

then

$$G_R(t, t_0) = \frac{1}{\eta} (1 - e^{-\eta(t-t_0)}) \quad \text{for } t > t_0$$

$$G_R(t, t_0) = 0 \quad \text{for } t < t_0$$

b) Consider : $\ddot{x} + \omega^2 x = \frac{f(t)}{m}$

write as an equation for $a = \dot{x} + i\omega x$ and use previous green function to find the specific sol, $a(t)$.

$$a = \dot{x} + i\omega x$$

$$\frac{da}{dt} = \ddot{x} + i\omega \dot{x}$$

$$\begin{aligned} \frac{da}{dt} - i\omega_0 a &= \ddot{x} + i\omega_0 \dot{x} - i\omega_0 \dot{x} + \omega_0^2 x \\ &\stackrel{!}{=} \ddot{x} + \omega_0^2 x \end{aligned}$$

$$\hookrightarrow \frac{da}{dt} - i\omega_0 a = \frac{f(t)}{m}$$

Find specific solution by integrating the green function:

$$a(t) = \int dt_0 G_R(t, t_0) F(t_0)$$

$$= \int_{-\infty}^{\infty} dt_0 \Theta(t-t_0) e^{-i\omega_0(t-t_0)} \frac{f(t_0)}{m}$$

Since $G_R(t, t_0) = 0$ for $t < t_0$ or $t_0 > t$

$$= \int_{-\infty}^t dt_0 \Theta(t-t_0) e^{-i\omega_0(t-t_0)} \frac{f(t_0)}{m}$$

$$= e^{i\omega_0 t} \int_{-\infty}^t dt_0 e^{i\omega_0 t_0} \frac{f(t_0)}{m}$$

c) Suppose the force approaches zero at $\pm\infty$.

If the oscillator was initially at rest
determine the total work done by external force.

$$E = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} m \omega_0^2 x^2$$

$$= \frac{1}{2} m (\dot{x}^2 + \omega_0^2 x^2)$$

$$= \frac{1}{2} m (a a^*)$$

$$= \frac{1}{2} m |a|^2$$

$$= \frac{1}{2} m \left(\frac{e^{i\omega_0 t}}{m} \int_{-\infty}^t dt_0 e^{i\omega_0 t_0} f(t_0) \right)^2$$

$$E = \frac{1}{2} m \frac{1}{m^2} |f(\omega)|^2 e^{i\omega t} \cancel{e^{-i\omega t}}$$

$$E = \frac{1}{2m} |f(\omega)|^2$$

d) consider $f(t) = \begin{cases} F_0 & 0 < t < T \\ 0 & \text{otherwise.} \end{cases}$

$$E = \frac{1}{2m} \left| \int_0^T dt e^{i\omega_0 t} F_0 \right|^2$$

$$= \frac{1}{2m} F_0^2 \left| \int_0^T dt e^{i\omega_0 t} \right|^2$$

$$= \frac{1}{2m} F_0^2 \left| -\frac{i}{\omega_0} (e^{i\omega_0 T} - 1) \right|^2$$

$$= \frac{1}{2m} F_0^2 \left(\frac{-i}{\omega_0} (e^{i\omega_0 T} - 1) \right) \left(\frac{i}{\omega_0} (e^{-i\omega_0 T} - 1) \right)$$

$$= \frac{1}{2m\omega_0^2} F_0^2 \left(2 - (e^{i\omega_0 T} + e^{-i\omega_0 T}) \right)$$

$$= \frac{1}{m\omega_0^2} F_0^2 \left(\underbrace{1 - \cos \omega_0 T}_{2 \sin^2 \left(\frac{\omega_0 T}{2} \right)} \right)$$

$$= \frac{2F_0^2}{m\omega_0^2} \sin^2 \left(\frac{\omega_0 T}{2} \right)$$