

Hamiltonian of Phase Space:

$$L = \frac{1}{2} m l^2 \dot{\phi}^2 + mgl \cos \phi \quad \leftarrow \text{Lagrangian of pendulum.}$$

$$p_{\phi} = \frac{\partial L}{\partial \dot{\phi}} = m l^2 \dot{\phi} \Rightarrow \dot{\phi} = \frac{p_{\phi}}{m l^2}$$

$$\mathcal{H} = p_{\phi} \dot{\phi} - L$$

$$= \frac{1}{2} \frac{p_{\phi}^2}{m l^2} - mgl \cos \phi$$

$$\text{So } \dot{\phi} = \frac{\partial \mathcal{H}}{\partial p_{\phi}} \quad \text{and} \quad \dot{p}_{\phi} = -\frac{\partial \mathcal{H}}{\partial \phi}$$

$$\text{For small } \theta, \quad \cos \theta = 1 - \frac{\theta^2}{2}$$

$$E = \frac{p_{\theta}^2}{2} + \frac{\theta^2}{2} + \text{const}$$

$\nwarrow \nearrow$
circle in phase space

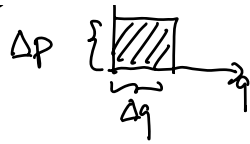
$$\left. \begin{array}{l} q \rightarrow Q(t) = \frac{1}{2} a t^2 + \frac{p}{m} t + q \\ p \rightarrow P(t) = m a t + p \end{array} \right\} (q, p) \rightarrow (Q(t, q, p), P(t, q, p))$$

Liouville Theorem:

\Rightarrow The area in phase-space is constant in time.

Proof: $p \uparrow$

$$p \rightarrow P(t) = p - \frac{\partial \mathcal{H}}{\partial q} \delta t = p + \dot{p} \delta t$$



$$q \rightarrow Q(t) = q + \frac{\partial H}{\partial p} \delta t = q + \dot{q} \delta t$$

$$d(\Delta p) = (\dot{p}|_{\text{top}} - \dot{p}|_{\text{bot}}) \delta t$$

$$= \frac{\partial \dot{p}}{\partial p} \Delta p \delta t$$

$$= -\frac{\partial^2 H}{\partial p \partial q} \Delta p \delta t \quad \hookrightarrow \quad \dot{p} = \frac{\partial H}{\partial q}$$

$$d(\Delta q) = (\dot{q}|_{\text{right}} - \dot{q}|_{\text{left}}) \delta t$$

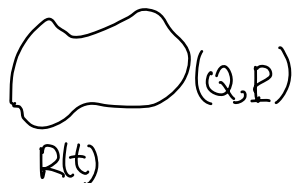
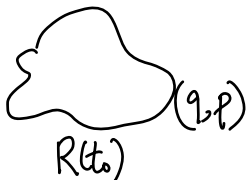
$$= \frac{\partial \dot{q}}{\partial q} \Delta q \delta t$$

$$= \frac{\partial^2 H}{\partial p \partial q} \Delta q \delta t$$

Then:

$$\begin{aligned} d(\Delta p \Delta q) &= d(\Delta p) \Delta q + \Delta p d(\Delta q) \\ &= \left(-\frac{\partial^2 H}{\partial p \partial q} + \frac{\partial^2 H}{\partial p \partial q} \right) \Delta p \Delta q \delta t \\ &\approx 0 \end{aligned}$$

Second proof:



$$\text{Area} = \int_{R(t)} dQ dP = \int_{R(t_0)} \left| \frac{\partial(Q, P)}{\partial(q, p)} \right| dq dp$$

$$q \rightarrow Q(\delta t, p, q) = q + \frac{\partial H}{\partial p} \delta t = q + \dot{Q}(q, p) \delta t$$

$$P \rightarrow P(q, p, t) = P - \frac{\partial H}{\partial q} \delta t = P + \dot{P}(q, p) \delta t$$

$$\text{Jacobian: } \frac{\partial(Q, P)}{\partial(q, p)} = \begin{pmatrix} \frac{\partial Q}{\partial q} & \frac{\partial Q}{\partial p} \\ \frac{\partial P}{\partial q} & \frac{\partial P}{\partial p} \end{pmatrix}$$

$$\begin{aligned} \hookrightarrow \text{use:} \\ Q(t) = q + \frac{\partial H}{\partial p} \delta t \\ P(t) = p - \frac{\partial H}{\partial q} \delta t \end{aligned} \quad \hookrightarrow = \begin{vmatrix} 1 + \delta t \frac{\partial^2 H}{\partial p \partial q} & \delta t \frac{\partial^2 H}{\partial p^2} \\ -\delta t \frac{\partial^2 H}{\partial q^2} & 1 - \delta t \frac{\partial^2 H}{\partial p \partial q} \end{vmatrix}$$

$$\begin{aligned} \hookrightarrow &= 1 + \delta t^2 \left\{ -\left(\frac{\partial^2 H}{\partial p \partial q}\right)^2 + \frac{\partial^2 H}{\partial p^2} \frac{\partial^2 H}{\partial q^2} \right\} \\ &\downarrow \\ &\approx 1 + \mathcal{O}(\delta t^2) \end{aligned}$$

$$\text{So } A = \int_{R(t)} dQ dP = \int_{R(t_0)} \left| \frac{\partial(Q, P)}{\partial(q, p)} \right| dq dp \approx \int_{R(t_0)} dq dp$$

For multiple coordinate:

$$q^i \rightarrow Q^i(q, p) = q^i + \frac{\partial H}{\partial p_i} \delta t$$

$$p^i \rightarrow P^i(q, p) = p^i - \frac{\partial H}{\partial q^i} \delta t$$

$$A(t) = \int_{R(t)} dQ^i dP_i = \int_{R(t_0)} \left| \frac{\partial(Q, P)}{\partial(q, p)} \right| dq^i dp_i$$

$$J = \frac{\chi(Q, P)}{\chi(q, p)} = \begin{pmatrix} \frac{\partial Q^i}{\partial q^j} & \frac{\partial Q^i}{\partial p_j} \\ \frac{\partial P_i}{\partial q^j} & \frac{\partial P_i}{\partial p_j} \end{pmatrix}$$

$$\hookrightarrow = \begin{vmatrix} \delta'_{ij} + \delta t \frac{\partial^2 \mathcal{H}}{\partial p_i \partial q^j} & \frac{\partial^2 \mathcal{H}}{\partial p_i \partial p_j} \delta t \\ \frac{-\partial^2 \mathcal{H}}{\partial q^i \partial q^j} & \delta'_{ij} - \delta t \frac{\partial^2 \mathcal{H}}{\partial p_i \partial q^j} \end{vmatrix}$$

$$\det A = \exp \left\{ \text{Tr} \left(\overset{\text{natural log}}{\log A} \right) \right\}$$

$$= e^{\log \lambda_1 + \log \lambda_2 + \dots}$$

$$= (\lambda_1)(\lambda_2) \dots (\lambda_n)$$

Since $A \approx I + \delta t M$ ← terms with \mathcal{H} .

$$\log A = \log(I + \delta t M)$$

$$\log A \stackrel{!}{=} \delta t M \quad \text{by Taylor}$$

$$\hookrightarrow \text{Tr} \log A = \text{Tr}(\delta t M)$$

$$\text{and } \text{Tr}(\delta t M) = \sum_i \frac{\partial^2 \mathcal{H}}{\partial q^i \partial p_j} - \frac{\partial^2 \mathcal{H}}{\partial q^i \partial p_j} = 0.$$

then $\exp(\text{Tr}(\delta t M)) = I + \text{Tr}(\delta t M)$ by Taylor.

Then

$$\exp\{\text{Tr} \log A\} = 1 + \text{Tr}(A - I) \approx 1$$

If $V(t) = \int_{R(t)} dQ dP = V(t_0) = \int_{R(t_0)} dq dp \leftarrow \text{volume.}$

then $f(t, q, p) = \frac{dN}{dp dq} \leftarrow \# \text{ density} = \text{phase space density.}$

then $N = \int dq dp f(t, q, p)$ is constant since
of particles are constant.

If dN , $dp dq$ are both constant, f : phase-space density
is also constant.

$$\frac{df}{dt} = \frac{\partial f}{\partial q} \frac{dq}{dt} + \frac{\partial f}{\partial p} \frac{dp}{dt} + \frac{\partial f}{\partial t} = 0$$

$$\hookrightarrow \boxed{\frac{\partial f}{\partial t} + \frac{\partial f}{\partial q} \frac{\partial H}{\partial p} - \frac{\partial f}{\partial p} \frac{\partial H}{\partial q} = 0} \quad \text{Liouville Equation.}$$

Define Poisson bracket:

$$\{f, H\} = \frac{\partial f}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial H}{\partial q_i} \frac{\partial f}{\partial p_i}$$

then Liouville Eq: f is p.s. density

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \{f, H\} = 0.$$

properties of Poisson bracket:

$$\boxed{\text{For arbitrary } O(t, q, p) \quad \frac{dO}{dt} = \frac{\partial O}{\partial t} + \{O, H\}}$$

$$1) \{f, g\} = -\{g, f\}$$

$$2) \{f_1 + f_2, g\} = \{f_1, g\} + \{f_2, g\}$$

$$3) \{f, g, h\} = \{f, h\}g + f\{g, h\} \quad \leftarrow \text{Leibniz rule.}$$

$$4) \{f_1, \{f_2, f_3\}\} + \{f_3, \{f_1, f_2\}\} + \{f_2, \{f_3, f_1\}\} = 0$$

Jacobian Identity.

$$5) \{q^i, q^j\} = 0$$

$$\{p_i, p_j\} = 0$$

$$\{q^i, p_j\} = \delta^i_j$$

$$6) \{f, p_i\} = \frac{\partial f}{\partial q^i}$$

$$\{f, q^i\} = -\frac{\partial f}{\partial p_i}$$

$$7) \dot{q} = \{q, H\} = -\{H, q\} = \frac{\partial H}{\partial p}$$

$$\dot{p} = \{p, H\} = -\{H, p\} = -\frac{\partial H}{\partial q}$$

Poisson Theorem:

If I and J are constant in time, so $I(q,p)$ and $J(q,p)$

$$\text{or } \dot{I} = \{I, H\} = 0 \quad \text{and} \quad \dot{J} = \{J, H\} = 0$$

then $\{I, J\}$ is also constant.

Proof:

$$\begin{aligned} \frac{d\{I, J\}}{dt} &= \{\{I, J\}, H\} \\ &= -\{H, \{I, J\}\} \\ &= \{J, \underbrace{\{H, I\}}_{-\frac{dI}{dt}}\} + \{I, \underbrace{\{J, H\}}_{\dot{J}}\} = 0 \\ &\quad -\frac{dI}{dt} = -\frac{\dot{I}}{\dot{I}} + \{H, I\} \end{aligned}$$

Ex: $\vec{L} = \vec{r} \times \vec{p}$

$$L_1 = r_2 p_3 - r_3 p_2$$

$$L_2 = r_3 p_1 - r_1 p_3$$

$$\{L_1, L_2\} = \{r_2 p_3 - r_3 p_2, r_3 p_1 - r_1 p_3\}$$

$$\begin{aligned} &= \{r_2 p_3, r_3 p_1\} + \{r_3 p_2, r_1 p_3\} - \underbrace{\{r_3 p_2, r_3 p_1\}} - \underbrace{\{r_2 p_3, r_1 p_3\}} \\ & \quad | \quad \quad \quad / \end{aligned}$$

$$= \{\cancel{r_2 r_3 r_1}\} r_3 + r_2 \{r_3, r_1\}$$

$$+ \{\cancel{r_3 r_1 r_2}\} r_2 + r_3 \{r_2, r_1\}$$

$$L_3 \perp r_1 r_2 - r_2 r_1$$