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HW# 10

1) Radiation from antennas:

a) Find charge density: ρ

$$\vec{J}(\vec{r}, t) = \begin{cases} 0 & z < -\frac{1}{2} \\ I \delta(x) \delta(y) \sin \omega t \hat{z} & -\frac{1}{2} \leq z \leq \frac{1}{2} \\ 0 & z > \frac{1}{2} \end{cases}$$

$$\text{or } \vec{J}(\vec{r}, t) = I \delta(x) \delta(y) \sin \omega t \left[\theta\left(z + \frac{1}{2}\right) - \theta\left(z - \frac{1}{2}\right) \right]$$

Via charge conservation, continuity equation:

$$\partial_t \rho + \vec{\nabla} \cdot \vec{J} = 0$$

Since \vec{J} only has component in \hat{z} , then:

$$\frac{\partial \rho}{\partial t} = -\partial_z J = -\partial_z \left(I \delta(x) \delta(y) \sin \omega t \left[\theta\left(z + \frac{1}{2}\right) - \theta\left(z - \frac{1}{2}\right) \right] \right)$$

using $\frac{d}{dx} \theta(x) = \delta(x)$

$$\partial_t \rho = -I \delta(x) \delta(y) \sin \omega t \left[\delta\left(z + \frac{1}{2}\right) - \delta\left(z - \frac{1}{2}\right) \right]$$

$$\text{then } \rho = \int -I \delta(x) \delta(y) \sin \omega t \left[\delta\left(z + \frac{1}{2}\right) - \delta\left(z - \frac{1}{2}\right) \right] dt$$

$$\rho = \frac{1}{\omega} I \delta(x) \delta(y) \cos \omega t \left[\delta\left(z + \frac{1}{2}\right) - \delta\left(z - \frac{1}{2}\right) \right] + C$$

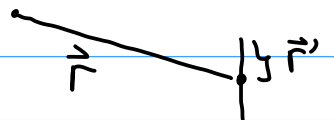
\uparrow
 $C = 0$ since
no static

given $\frac{dP}{d\Omega} = \frac{\mu_0}{16\pi^2 c} \left| \hat{n} \times \int d^3r' [\dot{\vec{J}}(\vec{r}', t)]_{\text{ret}} \right|^2$

b) Find angular distribution of radiated power.

$\rightarrow \dot{\vec{J}}(\vec{r}, t) = \omega I \delta(x) \delta(y) \cos \omega t \left[\theta(z + \frac{1}{2}) - \theta(z - \frac{1}{2}) \right] \hat{z}$

with $t_{\text{ret}} = t - \frac{1}{c} |\vec{r} - \vec{r}'|$



assume $\left| \frac{\vec{r}'}{r} \right| \ll 1$, then

$$|\vec{r} - \vec{r}'| = \sqrt{r^2 - 2\vec{r} \cdot \vec{r}' + r'^2}$$

$$= \sqrt{r^2 \left(1 - 2\hat{r} \cdot \hat{r}' \left(\frac{r'}{r} \right) + \underbrace{\left(\frac{r'}{r} \right)^2}_{\text{ignore}} \right)}$$

$$\approx r \left(1 - 2\hat{r} \cdot \hat{r}' \left(\frac{r'}{r} \right) \right)^{1/2}$$

$$\approx r \left(1 - \hat{r} \cdot \hat{r}' \left(\frac{r'}{r} \right) \right)$$

$$= r - \hat{r} \cdot \vec{r}'$$

replace \hat{r} with \hat{n}

$$= r - \hat{n} \cdot \vec{r}'$$

then $t_{\text{ret}} = t - \frac{1}{c} |\vec{r} - \vec{r}'| \approx t - \frac{1}{c} (r - \hat{n} \cdot \vec{r}')$

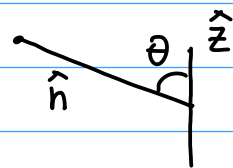
then

$$\frac{dP}{d\Omega} = \frac{\mu_0}{16\pi^2 c} \left| \hat{n} \times \int dx' dy' dz' \omega I \delta(x) \delta(y) \left[\theta(z + \frac{1}{2}) - \theta(z - \frac{1}{2}) \right] \cos \omega \left[t - \frac{1}{c} (r - \hat{n} \cdot \vec{r}') \right] \hat{z} \right|$$

$$\hat{n} \cdot \vec{r}' = (x' \hat{n} \cdot \hat{x}' + y' \hat{n} \cdot \hat{y}' + z' \hat{n} \cdot \hat{z}')$$

we can integrate x' and y' easily due to $\delta(x)$ and $\delta(y)$, then $x', y' \rightarrow 0$

so $\hat{n} \cdot \vec{r}' \rightarrow z' \hat{n} \cdot \hat{z}' = z \cos \theta$



$$\hookrightarrow \frac{dP}{d\Omega} = \frac{\mu_0}{16\pi^2 c} \left| \hat{n} \times \int_{-1/2}^{1/2} dz' \omega I \cos\left\{\omega\left[t - \frac{r}{c} + \frac{z'}{c} \cos\theta\right]\right\} \hat{z} \right|^2$$

with $\cos(\alpha + \beta) = \cos\alpha \cos\beta - \sin\alpha \sin\beta$

then $\cos\left\{\omega t - \frac{\omega r}{c} + z' \frac{\omega}{c} \cos\theta\right\} = \cos\left(\omega t - \frac{\omega r}{c}\right) \cos\left(z' \frac{\omega}{c} \cos\theta\right) - \sin\left(\omega t - \frac{\omega r}{c}\right) \sin\left(z' \frac{\omega}{c} \cos\theta\right)$

then $\int dz' \cos\left\{\omega\left[t - \frac{r}{c} + \frac{z'}{c} \cos\theta\right]\right\}$

$$\hookrightarrow = \int_{-1/2}^{1/2} dz' \left[\cos\left(\omega t - \frac{\omega r}{c}\right) \cos\left(z' \frac{\omega}{c} \cos\theta\right) - \sin\left(\omega t - \frac{\omega r}{c}\right) \sin\left(z' \frac{\omega}{c} \cos\theta\right) \right]$$

odd terms integrate to 0.

$$= \cos\left(\omega t - \frac{\omega r}{c}\right) \frac{2 \sin\left(\frac{\omega l}{2c} \cos\theta\right)}{\frac{\omega}{c} \cos\theta}$$

so

$$\hookrightarrow \frac{dP}{d\Omega} = \frac{\mu_0 (\omega I)^2}{16\pi^2 c} \left| (\hat{n} \times \hat{z}) \right|^2 \frac{4c^2}{\omega^2 \cos^2\theta} \cos^2\left(\omega t - \frac{\omega r}{c}\right) \sin^2\left(\frac{\omega l}{2c} \cos\theta\right)$$

\rightarrow we know the magnitude of cross-product between 2 vectors $|\vec{a} \times \vec{b}| = |a| |b| \sin\theta$,

so $|\hat{n} \times \hat{z}|^2 = \sin^2\theta$

Lastly:

$$\hookrightarrow \frac{dP}{d\Omega} = \frac{\mu_0 (\omega I)^2}{16\pi^2 \epsilon} \sin^2 \theta \frac{4c^2}{\omega^2 \cos^2 \theta} \cos^2\left(\omega t - \frac{\omega r}{c}\right) \sin^2\left(\frac{\omega l}{2c} \cos \theta\right)$$

$$\boxed{\frac{dP}{d\Omega} = \frac{\mu_0 I^2 c}{4\pi^2} \tan^2 \theta \cos^2\left(\omega t - \frac{\omega r}{c}\right) \sin^2\left(\frac{\omega l}{2c} \cos \theta\right)}$$

c) Find $\langle \frac{dP}{d\Omega} \rangle_t$

$$\langle \frac{dP}{d\Omega} \rangle = \frac{\mu_0 I^2 c}{4\pi^2} \tan^2 \theta \sin^2\left(\frac{\omega l}{2c} \cos \theta\right) \langle \cos^2\left(\omega t - \frac{\omega r}{c}\right) \rangle_t$$

One cycle has period $T = \frac{2\pi}{\omega}$

$$\begin{aligned} \text{so } \langle \cos^2\left(\omega t - \frac{\omega r}{c}\right) \rangle_t &= \frac{1}{T} \int_{\frac{r}{c}}^{\frac{r}{c} + T} dt \cos^2\left[\omega\left(t - \frac{r}{c}\right)\right] \\ &= \frac{\omega}{2\pi} \left(\frac{\sin\left[2\omega\left(t - \frac{r}{c}\right)\right]}{4\omega} + \frac{1}{2} t \right) \Bigg|_{\frac{r}{c}}^{\frac{r}{c} + \frac{2\pi}{\omega}} \\ &= \frac{\cancel{\omega}}{\cancel{2\pi}} \frac{1}{2} \frac{\cancel{2\pi}}{\cancel{\omega}} \\ &= \frac{1}{2} \end{aligned}$$

$$\text{so } \boxed{\langle \frac{dP}{d\Omega} \rangle = \frac{\mu_0 I^2 c}{8\pi^2} \tan^2 \theta \sin^2\left(\frac{\omega l}{2c} \cos \theta\right)}$$

d) i) let $\omega = \frac{2\pi c}{\lambda}$

then $\langle \frac{dP}{d\Omega} \rangle = \frac{\mu_0 I^2 c}{8\pi^2} \tan^2 \theta \sin^2 \left(\frac{l}{2c} \frac{2\pi c}{\lambda} \cos \theta \right)$

$$\boxed{\langle \frac{dP}{d\Omega} \rangle = \frac{\mu_0 I^2 c}{8\pi^2} \tan^2 \theta \sin^2 \left(\frac{\pi l}{\lambda} \cos \theta \right)}$$

ii) $\theta = \frac{\pi}{2}$

then $\langle \frac{dP}{d\Omega} \rangle \big|_{\theta=\frac{\pi}{2}} = \frac{\mu_0 I^2 c}{8\pi^2} \frac{\sin^2(\frac{\pi}{2})}{\cos^2(\frac{\pi}{2})} \sin^2 \left(\frac{\pi l}{\lambda} \underbrace{\cos \frac{\pi}{2}}_{=0} \right)$

expand $\cos \theta$ around $\frac{\pi}{2}$ and $\sin \theta$ around 0 and $\frac{\pi}{2}$

$$\cos \theta \big|_{\frac{\pi}{2}} = 0 - \sin \theta \big|_{\frac{\pi}{2}} \theta \approx -\theta$$

$$\sin \theta \big|_{\frac{\pi}{2}} \approx 1$$

$$\sin \theta \big|_0 \approx \theta$$

$$\langle \frac{dP}{d\Omega} \rangle \approx \frac{\mu_0 I^2 c}{8\pi^2} \frac{1}{\theta^2} \left(\frac{\pi l}{\lambda} \theta \right)^2$$

$$\approx \frac{\mu_0 I^2 c}{8\pi^2} \cancel{\pi^2} \left(\frac{l}{\lambda} \right)^2$$

$$\boxed{\langle \frac{dP}{d\Omega} \rangle \approx \frac{\mu_0 I^2 c}{8} \left(\frac{l}{\lambda} \right)^2} \leftarrow \text{quadratic in length, } \sim l^2$$

iii) $\langle \frac{dP}{d\Omega} \rangle$ if $l \ll \lambda$, $\sin^2\left(\frac{l}{\lambda} \pi \cos\theta\right) \approx \left(\frac{l}{\lambda} \pi \cos\theta\right)^2$

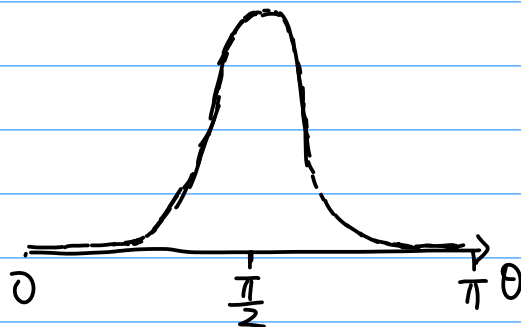
$$\langle \frac{dP}{d\Omega} \rangle = \frac{\mu_0 I^2 c}{8\pi^2} \tan^2\theta \sin^2\left(\frac{\pi l}{\lambda} \cos\theta\right)$$

$$\approx \frac{\mu_0 I^2 c}{8\pi^2} \tan^2\theta \left(\frac{\pi l}{\lambda} \cos\theta\right)^2$$

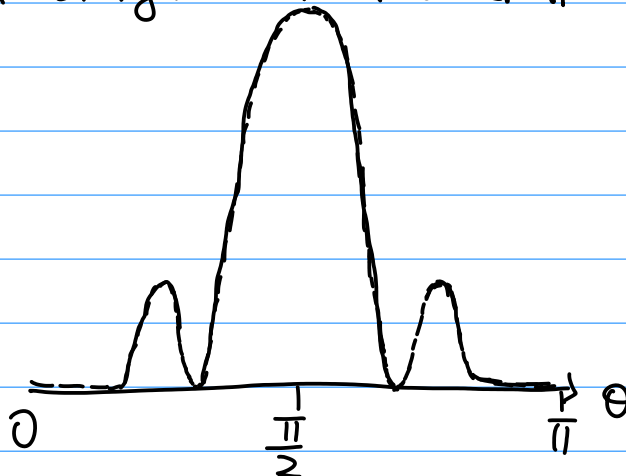
$$\boxed{\langle \frac{dP}{d\Omega} \rangle \approx \frac{\mu_0 I^2 c}{8} \left(\frac{l}{\lambda}\right)^2 \sin^2\theta}$$

iv) If I plot $\langle \frac{dP}{d\Omega} \rangle = \frac{\mu_0 I^2 c}{8\pi^2} \tan^2\theta \sin^2\left(\frac{\pi l}{\lambda} \cos\theta\right)$

then if $l < \lambda$, then I see 1 lobe.



if $\lambda < l < 2\lambda$, then I see 3 lobes, the middle one get stronger and two small ones around it.





2) Coiled Optical Fibers

$$\frac{d}{ds} \begin{pmatrix} \vec{T} \\ \vec{N} \\ \vec{B} \end{pmatrix} = \begin{pmatrix} 0 & \overset{\text{arc length.}}{k(s)} & 0 \\ -k(s) & 0 & \tau(s) \\ 0 & -\tau(s) & 0 \end{pmatrix} \begin{pmatrix} \vec{T} \\ \vec{N} \\ \vec{B} \end{pmatrix}$$

a) Calculate $\vec{T}, \vec{N}, \vec{B}, k(s)$ and $\tau(s)$

Since $\vec{R}(s) \propto (\cos qs \hat{x} + \sin qs \hat{y} + hqs \hat{z})$, then

$$\text{let } \vec{R}(s) = \underset{\substack{\downarrow \\ \text{proportional constant}}}{A} (\cos qs \hat{x} + \sin qs \hat{y} + hqs \hat{z})$$

In Frenet-Serret Frame:

the tangent unit vector \vec{T} (parallel with \vec{R}) is simply

$$\vec{T} = \frac{d}{ds} \vec{R} = Aq (-\sin qs \hat{x} + \cos qs \hat{y} + h \hat{z})$$

Since \vec{T} is a unit vector, then $\vec{T} \cdot \vec{T} = \frac{d}{ds} \vec{R} \cdot \frac{d}{ds} \vec{R} = 1$

then we can determine proportion constant A :

$$\text{as } 1 = |\vec{T}|^2 = A^2 q^2 (\underbrace{\sin^2 qs + \cos^2 qs}_{=1} + h^2)$$

$$\text{so } \boxed{A = \frac{1}{q\sqrt{1+h^2}}}$$

$$\text{thus } \boxed{\vec{T} = \frac{1}{\sqrt{1+h^2}} (-\sin qs \hat{x} + \cos qs \hat{y} + h \hat{z})}$$

By looking at Frenet-Serret matrix, we see

$$\frac{d\vec{T}}{ds} = K(s) \vec{N}$$

and since \vec{N} is unit vector, $K(s) = \sqrt{\frac{d\vec{T}}{ds} \cdot \frac{d\vec{T}}{ds}} = \left| \frac{d\vec{T}}{ds} \right|$

$$\text{and } \vec{N} = \frac{\frac{d\vec{T}}{ds}}{K(s)}$$

$$\text{we see } \frac{d\vec{T}}{ds} = \frac{-9}{\sqrt{1+h^2}} (\cos qs \hat{x} + \sin qs \hat{y})$$

$$\text{so } K = \left| \frac{d\vec{T}}{ds} \right| = \sqrt{\frac{9^2}{1+h^2} (\cos^2 qs + \sin^2 qs)} = \frac{9}{\sqrt{1+h^2}}$$

$$\text{Then } \vec{N} = \frac{\frac{d\vec{T}}{ds}}{\frac{9}{\sqrt{1+h^2}}} = \frac{-\frac{9}{\sqrt{1+h^2}} (\cos qs \hat{x} + \sin qs \hat{y})}{\frac{9}{\sqrt{1+h^2}}}$$

$$\hookrightarrow \vec{N} = -(\cos qs \hat{x} + \sin qs \hat{y})$$

Since we have \vec{T} and \vec{N} , the third normal vector is just the cross product of the first two,

$$\begin{aligned}\vec{B} &= \vec{T} \times \vec{N} = \frac{1}{\sqrt{1+h^2}} (-\sin\varphi_s \hat{x} + \cos\varphi_s \hat{y} + h \hat{z}) \\ &\quad \times -(\cos\varphi_s \hat{x} + \sin\varphi_s \hat{y}) \\ &= \frac{-1}{\sqrt{1+h^2}} (-h \sin\varphi_s \hat{x} + h \cos\varphi_s \hat{y} - (\sin^2\varphi_s + \cos^2\varphi_s) \hat{z}) \\ &= \frac{1}{\sqrt{1+h^2}} (h \sin\varphi_s \hat{x} - h \cos\varphi_s \hat{y} + \hat{z})\end{aligned}$$

Then from matrix, we see

$$\frac{d}{ds} \vec{B} = -\tau \vec{N}$$

then $\frac{d}{ds} \vec{B} = \frac{1}{\sqrt{1+h^2}} (h \cos\varphi_s \hat{x} + h \sin\varphi_s \hat{y}) = -\tau (-\cos\varphi_s \hat{x} - \sin\varphi_s \hat{y})$

By matching:

$$\tau = \frac{h}{\sqrt{1+h^2}}$$

b) The electric field in transverse direction is given by

$$\vec{E}(r, s) = e^{iqs} f(r) [C_1(s) \vec{N}(s) + C_2(s) \vec{B}(s)]$$

since $k(s)$ is comparable to the inverse of fiber bend length, and a gentle coiling means k^2 is very small, so ignore k^2 term.

then we're given:

$$i \frac{d}{ds} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} 0 & i\tau(s) \\ -i\tau(s) & 0 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

This is analogous to the Schrodinger equation.

$$i\hbar \frac{d}{dt} \psi(\vec{r}, t) = \hat{H} \psi$$

where $\frac{d}{ds} = \hbar \frac{d}{dt}$ and $\hat{H} = \begin{pmatrix} 0 & i\tau(s) \\ -i\tau(s) & 0 \end{pmatrix}$

we know time-dependent Schrodinger equation has solutions: if Hamiltonian at different times commute, then:

$$\psi(t) = \exp \left\{ -\frac{i}{\hbar} \int_{t_0}^t dt' \hat{H}(t') \right\} \psi(t=t_0)$$

For our Hamiltonian, $\hat{H} = -\tau(s) \sigma_y$ and σ_y commutes with itself. so by using this solution we then have:

$$\begin{aligned} \begin{pmatrix} C_1(s) \\ C_2(s) \end{pmatrix} &= \exp \left\{ -i \int_{-\infty}^s ds' \begin{pmatrix} 0 & i\tau(s') \\ -i\tau(s') & 0 \end{pmatrix} \right\} \begin{pmatrix} C_1(s=-\infty) \\ C_2(s=-\infty) \end{pmatrix} \\ &= \exp \left\{ -i \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} \underbrace{\int_{-\infty}^s ds' \tau(s')}_{\equiv A(s)} \right\} \begin{pmatrix} C_1(s=-\infty) \\ C_2(s=-\infty) \end{pmatrix} \end{aligned}$$

$$L_s = \exp \left\{ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} A(s) \right\} \begin{pmatrix} C_1(s=-\infty) \\ C_2(s=-\infty) \end{pmatrix}$$

We note that Taylor expansion of exponential:

$$\exp(x) = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

then

$$\exp \left\{ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} A(s) \right\} = \sum_{n=0}^{\infty} \frac{A^n}{n!} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^n$$

Note that

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = -1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^3 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^4 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^5 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

Thus we observe the following pattern for

$$\sum_{n=0}^{\infty} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^n = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \sum_{\substack{n=\text{even} \\ =0,2,4,\dots}}^{\infty} (i)^n - \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \sum_{\substack{n=\text{odd} \\ =1,3,5,\dots}}^{\infty} (i)^{n+1}$$

$$\begin{array}{l} n \rightarrow 2k \\ \downarrow \\ = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \sum_{k=0}^{\infty} (i)^{2k} - i \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \sum_{k=0}^{\infty} (i)^{2k+1} \end{array}$$

$$\begin{array}{l} i^{2k} \rightarrow (-1)^k \\ i^{2k+1} \rightarrow (-1)^k i \\ \downarrow \\ = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \sum_{k=0}^{\infty} (-1)^k - i \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \sum_{k=0}^{\infty} (-1)^k i \end{array}$$

Now all together

$$\begin{aligned}
 \exp\left\{\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} A(s)\right\} &= \sum_{n=0}^{\infty} \frac{A^n}{n!} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^n \\
 &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \underbrace{\sum_{k=0}^{\infty} \frac{A^{2k}}{(2k)!} (-1)^k}_{\cos(A)} + \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \underbrace{\sum_{k=0}^{\infty} \frac{A^{2k+1}}{(2k+1)!} (-1)^k}_{\sin(A)} \\
 &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cos A + \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \sin A
 \end{aligned}$$

Therefore:

$$\begin{pmatrix} C_1(s) \\ C_2(s) \end{pmatrix} = \begin{pmatrix} \cos A & \sin A \\ -\sin A & \cos A \end{pmatrix} \begin{pmatrix} \overset{\text{cos } \alpha}{C_1(s=-\infty)} \\ \underset{\text{sin } \alpha}{C_2(s=-\infty)} \end{pmatrix}$$

Knowing that we initially have linear polarization at $s = -\infty$ with angle α relative to \vec{N} , so $C_1(-\infty) = \cos \alpha$ and hence $C_2(-\infty) = \sin \alpha$

$$\begin{aligned}
 \text{then } C_1(s) &= \cos A \cos \alpha + \sin A \sin \alpha \\
 C_2(s) &= -\cos \alpha \sin A + \sin \alpha \cos A
 \end{aligned}$$

$$\begin{aligned}
 \text{With Trig Identity: } \cos(\alpha - \beta) &= \cos \alpha \cos \beta + \sin \alpha \sin \beta \\
 \sin(\alpha - \beta) &= \sin \alpha \cos \beta - \cos \alpha \sin \beta
 \end{aligned}$$

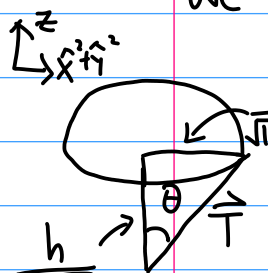
$$\Rightarrow \begin{cases} C_1(s) = \cos(\alpha - A(s)) \\ C_2(s) = \sin(\alpha - A(s)) \end{cases} \quad \text{so } \frac{C_2(s)}{C_1(s)} = \tan(\alpha - A(s))$$

$$\text{where } A(s) = \int_{-\infty}^s ds' T(s')$$

c) Show a complete helical turn induces a polarization rotation equal to the solid angle swept out by the tangent to the curve.

know helix follow $\vec{R}(s) = \frac{1}{\sqrt{1+h^2}} (\cos qs \hat{x} + \sin qs \hat{y} + hqs \hat{z})$

we found the tangent vector in part a):



$$\vec{T} = \frac{d\vec{R}}{ds} = \frac{1}{\sqrt{1+h^2}} (-\sin qs \hat{x} + \cos qs \hat{y} + h \hat{z})$$

as tangent vector rotates, $(-\sin qs \hat{x} + \cos qs \hat{y})$ sweeps out a circle with a constant vector in \hat{z} with a constant θ .

with this geometry we know the solid angle that it swept out is:

$$\Omega = \int_0^\theta \int_0^{2\pi} \sin\theta d\theta d\phi$$

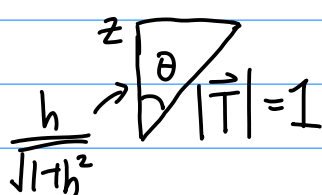
by looking at the geometry:

then

$$\Omega = \int_0^{\tan^{-1}(1/h)} \sin\theta' d\theta' \int_0^{2\pi} d\phi = -\cos\theta' \Big|_0^\theta \cdot 2\pi$$

$$= 2\pi (1 - \cos\theta)$$

if we look at the geometry, we observe



$$\cos\theta = \vec{T} \cdot \hat{z} = \frac{h}{\sqrt{1+h^2}}$$

so

$$\boxed{\Omega = 2\pi \left(1 - \frac{h}{\sqrt{1+h^2}}\right)}$$

Now find the induced polarization

since $A(s) = \int dS \tau(s')$

then $\Delta A = \Delta S \tau(s)$

we know $(-\sin qs \hat{x} + \cos qs \hat{y})$ completes a full turn

when $qs = 2\pi n \rightarrow \boxed{S = \frac{2\pi}{q} n}$

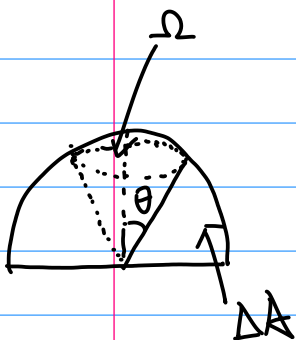
so the change of S over 1 full turn, i.e. $n=1$, is

$$\Delta S = \frac{2\pi}{q}$$

we also know $\tau = \frac{qh}{\sqrt{1+h^2}}$

so $\Delta A = \Delta S \tau = \frac{2\pi}{q} \frac{qh}{\sqrt{1+h^2}} = 2\pi \frac{h}{\sqrt{1+h^2}}$

so we see $\Omega = 2\pi \left(1 - \frac{h}{\sqrt{1+h^2}}\right) = 2\pi - \Delta A$



or $\boxed{\Omega + \Delta A = 2\pi}$

(cone-shape) area swept out by the tangent-vector complement area. This is the full half hemisphere.

3) Green functions:

a) $\mathcal{L}_t Y(t) = F(t)$, $\mathcal{L}_t = \frac{d^2}{dt^2} + W(t)^2$

i) Given $Y(t=t_0) = P$, $\dot{Y}(t=t_0) = V$, and $F(t)$

Green's Function follows:

$$\mathcal{L}_t G(t, t') = \delta(t - t')$$

First evaluate the follow expression

$$\int_{t_0}^t d\tau Y(\tau) \underbrace{\mathcal{L}_\tau G(\tau, t')}_{\delta(\tau - t')} - G(\tau, t') \underbrace{\mathcal{L}_\tau Y(\tau)}_{F(\tau)} = \int_{t_0}^t d\tau \left\{ Y(\tau) \cancel{\mathcal{L}_\tau^2 G(\tau, t')} + W(\tau)^2 \cancel{G(\tau, t')} Y(\tau) - G(\tau, t') \mathcal{L}_\tau^2 Y(\tau) - \cancel{G(\tau, t') W(\tau)^2 Y(\tau)} \right\}$$

$$\Rightarrow \textcircled{1} Y(t') - \int_{t_0}^t d\tau G(\tau, t') F(\tau) = \int_{t_0}^t d\tau \left[Y(\tau) \mathcal{L}_\tau^2 G(\tau, t') - G(\tau, t') \mathcal{L}_\tau^2 Y(\tau) \right]$$

Then by Green's Theorem:

$$\textcircled{2} \int_{t_0}^t d\tau \left[Y(\tau) \mathcal{L}_\tau^2 G(\tau, t') - G(\tau, t') \mathcal{L}_\tau^2 Y(\tau) \right] = \int_{t_0}^t d\tau \mathcal{L}_\tau \left[Y(\tau) \mathcal{L}_\tau G(\tau, t') - G(\tau, t') \mathcal{L}_\tau Y(\tau) \right]$$

$$= \left[Y(t) \cancel{\mathcal{L}_\tau G(\tau, t')} \right]_t - \underbrace{Y(t_0)}_P \mathcal{L}_\tau G(\tau, t') \Big|_{t_0} - G(t, t') \mathcal{L}_\tau Y(\tau) \Big|_t + G(t_0, t') \underbrace{\mathcal{L}_\tau Y(\tau)}_V \Big|_{t_0}$$

choose Boundary condition for $G(\tau, t')$
such that $G(t, t') = \mathcal{L}_\tau G(\tau, t') \Big|_t = 0$

By equating (1) and (2):

$$Y(t') - \int_{t_0}^t d\tau G(\tau, t') F(\tau) = -P \partial_\tau G(\tau, t') \Big|_{t_0} + V G(t_0, t')$$

$$\hookrightarrow Y(t') = \underbrace{\int_{t_0}^t d\tau G(\tau, t') F(\tau)}_{\text{arrow}} - P \partial_\tau G(\tau, t') \Big|_{t_0} + V G(t_0, t')$$

$$\int_{t_0}^t d\tau G(\tau, t') F(\tau) = \int_{t_0}^{t'} d\tau G(\tau, t') F(\tau) + \int_{t'}^t d\tau G(\tau, t') F(\tau)$$

we expect $G(t, t') = 0$ for $t > t'$

Then switch dummy variable: $t' \rightarrow t$, $\tau \rightarrow t'$

$$\hookrightarrow Y(t) = \int_{t_0}^t dt' G(t', t) F(t') - P \partial_{t_0} G(t_0, t) + V G(t_0, t)$$

ii) Solve for G with case $W(t) = \Omega$, then express $\gamma(t)$

$$\Rightarrow \partial_t^2 G(t, t_0) + \Omega^2 G(t, t_0) = \delta(t - t_0)$$

We know $G(t, t_0) = 0$ for $t < t_0$ since there has not been an excitation.

Let's determine boundary condition:

We know G is continuous at $t = t_0$, but $G(t, t_0) \big|_{t=t_0-\epsilon} \overset{\text{before the excitation.}}{=} 0$

so by continuity: $\boxed{\lim_{t \rightarrow t_0^+} G(t, t_0) = 0} \quad (1)$

We can determine second boundary condition by integrating around t_0

$$\int_{t_0-\epsilon}^{t_0+\epsilon} dt \left[\frac{d^2}{dt^2} G(t, t_0) + \Omega^2 G(t, t_0) \right] = \int_{t_0-\epsilon}^{t_0+\epsilon} dt \delta(t - t_0) = 1$$

$$\hookrightarrow \frac{d}{dt} G(t, t_0) \bigg|_{t_0-\epsilon}^{t_0+\epsilon} + \underbrace{\int_{t_0-\epsilon}^{t_0+\epsilon} dt \Omega^2 G(t, t_0)}_{=0} = 1$$

$= 0$ due to causality, $\lim_{t \rightarrow t_0-\epsilon} G(t, t_0) = 0$

and due to continuity: $\lim_{t \rightarrow t_0+\epsilon} G(t, t_0) = 0$

so integrand $= 0$

$$\hookrightarrow \frac{d}{dt} G(t, t_0) \bigg|_{t_0+\epsilon} - \frac{d}{dt} G(t, t_0) \bigg|_{t_0-\epsilon} = 1$$

$= 0$ since $G(t, t_0) = 0$ for $t < t_0$

$$\hookrightarrow \boxed{\frac{d}{dt} G(t, t_0) \bigg|_{t_0+\epsilon} = 1} \leftarrow \text{boundary condition. } (2)$$

We know for $t < t_0$, $G(t, t_0) = 0$ due to causality

Now for $t > t_0$, $\delta(t - t_0) = 0$, so $G(t, t_0)$ obeys:

$$\partial_t^2 G(t, t_0) + \Omega^2 G(t, t_0) = 0$$

which has solution of the form $G(t, t_0) = \alpha \sin \Omega t + \beta \cos \Omega t$ with 2 constants, α and β depending on initial condition.

Now with condition $\lim_{t \rightarrow t_0 + \epsilon} G(t, t_0) = 0$

$$\text{then } G(t, t_0) \Big|_{t=t_0+\epsilon} = \alpha \sin \Omega t_0 + \beta \cos \Omega t_0 = 0$$

Then use the condition we derived before: $\frac{d}{dt} G(t, t_0) \Big|_{t=t_0+\epsilon} = 1$

$$\Rightarrow \Omega \alpha \cos \Omega t_0 - \Omega \beta \sin \Omega t_0 = 1$$

$$\hookrightarrow \alpha \cos \Omega t_0 - \beta \sin \Omega t_0 = \frac{1}{\Omega}$$

$$\text{then we have: } \begin{pmatrix} \sin \Omega t_0 & \cos \Omega t_0 \\ \cos \Omega t_0 & -\sin \Omega t_0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{1}{\Omega} \end{pmatrix}$$

solve by inverse matrix:

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} \sin \Omega t_0 & \cos \Omega t_0 \\ \cos \Omega t_0 & -\sin \Omega t_0 \end{pmatrix} \begin{pmatrix} 0 \\ \frac{1}{\Omega} \end{pmatrix}$$

$$\hookrightarrow \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} \frac{1}{\Omega} \cos \Omega t_0 \\ -\frac{1}{\Omega} \sin \Omega t_0 \end{pmatrix}$$

then $G(t, t_0) = \frac{1}{2} (\cos \Omega t_0 \sin \Omega t - \sin \Omega t_0 \cos \Omega t)$

with trig identity

$$\boxed{G(t, t_0) = -\frac{1}{2} \sin[\Omega(t - t_0)]}$$

then plug into our formula from i)

$$\hookrightarrow Y(t) = \int_{t_0}^t dt' G(t', t) F(t') - P \partial_{t_0} G(t_0, t) + V G(t_0, t)$$

By matching the respective dummy index:

$$G(t', t) = -\frac{1}{2} \sin[\Omega(t' - t)] = \frac{1}{2} \sin[\Omega(t - t')]$$

$$G(t_0, t) = -\frac{1}{2} \sin[\Omega(t_0 - t)] = \frac{1}{2} \sin[\Omega(t - t_0)]$$

$$\partial_{t_0} G(t_0, t) = \frac{\partial}{\partial t_0} \left(\frac{1}{2} \sin[\Omega(t - t_0)] \right) = -\cos[\Omega(t - t_0)]$$

$$\boxed{\therefore Y(t) = \int_{t_0}^t dt' \frac{1}{2} \sin[\Omega(t - t')] F(t') + P \cos[\Omega(t - t_0)] + V \frac{1}{2} \sin[\Omega(t - t_0)]}$$

iii) Variation of parameters method:

to solve: $\ddot{y} + p(t)\dot{y} + q(t)y = f(t)$

know homogeneous solution, i.e. when $f(t) = 0$

$$\hookrightarrow a_1 y_1(t) + a_2 y_2(t) = y(t)$$

let's vary a_1, a_2 so $a_1(t)y_1(t) + a_2(t)y_2(t) = y(t)$

with constraint: $\frac{d}{dt}(\dot{a}_1 y_1 + \dot{a}_2 y_2) = 0$ $\ddot{a}_1 y_1 + \dot{a}_1 \dot{y}_1 + \ddot{a}_2 y_2 + \dot{a}_2 \dot{y}_2 = 0$

If we put solution into $\ddot{y} + p\dot{y} + qy = f(t)$

$$\hookrightarrow (\ddot{a}_1 y_1 + 2\dot{a}_1 \dot{y}_1 + \underline{a_1 \ddot{y}_1}) + (\ddot{a}_2 y_2 + 2\dot{a}_2 \dot{y}_2 + \underline{a_2 \ddot{y}_2})$$

$$+ p(\dot{a}_1 y_1 + \underline{a_1 \dot{y}_1} + \dot{a}_2 y_2 + \underline{a_2 \dot{y}_2})$$

$$+ q(\underline{a_1 y_1} + \underline{a_2 y_2}) = f(t)$$

$$\hookrightarrow a_1 (\underbrace{\ddot{y}_1 + p\dot{y}_1 + qy_1}_{=0 \text{ due to homogeneous}}) + a_2 (\underbrace{\ddot{y}_2 + p\dot{y}_2 + qy_2}_{=0 \text{ due to homogeneous}})$$

$$+ \underbrace{\ddot{a}_1 y_1 + \ddot{a}_2 y_2 + \dot{a}_1 \dot{y}_1 + \dot{a}_2 \dot{y}_2}_{=0 \text{ due to constraint}} + p(\underbrace{\dot{a}_1 y_1 + \dot{a}_2 y_2}_{=0 \text{ due to constraint}})$$

$$+ \underbrace{\dot{a}_1 \dot{y}_1 + \dot{a}_2 \dot{y}_2}_{\text{only non-zero terms}} = f(t)$$

In the end: $\dot{a}_1 \dot{\gamma}_1 + \dot{a}_2 \dot{\gamma}_2 = f(t)$

along with constraint: $\dot{a}_1 \gamma_1 + \dot{a}_2 \gamma_2 = 0$

$$\begin{pmatrix} \dot{\gamma}_1 & \dot{\gamma}_2 \\ \gamma_1 & \gamma_2 \end{pmatrix} \begin{pmatrix} \dot{a}_1 \\ \dot{a}_2 \end{pmatrix} = \begin{pmatrix} f(t) \\ 0 \end{pmatrix}$$

$$\hookrightarrow \begin{pmatrix} \dot{a}_1 \\ \dot{a}_2 \end{pmatrix} = \frac{1}{\underbrace{\dot{\gamma}_1 \gamma_2 - \dot{\gamma}_2 \gamma_1}_{-\frac{1}{\Omega}}} \begin{pmatrix} \gamma_2 & -\dot{\gamma}_2 \\ -\gamma_1 & \dot{\gamma}_1 \end{pmatrix} \begin{pmatrix} f \\ 0 \end{pmatrix}$$

then

$$\left. \begin{aligned} a_1 &= - \int_{\alpha_1}^t d\tau \frac{\gamma_2(\tau) f(\tau)}{\Omega} \\ a_2 &= - \int_{\alpha_2}^t d\tau \frac{-\gamma_1(\tau) f(\tau)}{\Omega} \end{aligned} \right\} \gamma(t) = \gamma_1(t) \left(- \int_{\alpha_1}^t d\tau \frac{\gamma_2(\tau) f(\tau)}{\Omega} \right) + \gamma_2(t) \left(\int_{\alpha_2}^t d\tau \frac{\gamma_1(\tau) f(\tau)}{\Omega} \right)$$

For our problem: $\left(\frac{d^2}{dt^2} + \Omega^2 \right) \gamma = F(t)$

know homogeneous solution $\gamma(t) = a_1 \underbrace{\cos \Omega t}_{\gamma_1} + a_2 \underbrace{\sin \Omega t}_{\gamma_2}$

then $\frac{1}{\dot{\gamma}_1 \gamma_2 - \dot{\gamma}_2 \gamma_1} = \frac{1}{\Omega (-\sin^2 \Omega t - \cos^2 \Omega t)} = -\frac{1}{\Omega}$

$$\text{then } y(t) = -\frac{1}{2} \left(\cos \Omega t \int_{\alpha_1}^t d\tau \sin(\Omega \tau) F(\tau) - \sin \Omega t \int_{\alpha_2}^t d\tau \cos(\Omega \tau) F(\tau) \right)$$

$$y(t) = -\frac{1}{2} \left(\cos \Omega t \left[\int_{t_0}^t d\tau \sin(\Omega \tau) F(\tau) + \int_{\alpha_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) \right] - \sin \Omega t \left[\int_{t_0}^t d\tau \cos(\Omega \tau) F(\tau) + \int_{\alpha_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau) \right] \right)$$

\swarrow constant.
 \uparrow some constant

Now re arrange: $= -\sin[\Omega(t-\tau)]$

$$y(t) = -\frac{1}{2} \left(\int_{t_0}^t d\tau \left(\cos \Omega t \sin \Omega \tau - \sin \Omega t \cos \Omega \tau \right) F(\tau) + \cos \Omega t \int_{\alpha_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) - \sin \Omega t \int_{\alpha_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau) \right)$$

$$\Rightarrow y(t) = \frac{1}{2} \int_{t_0}^t d\tau \sin[\Omega(t-\tau)] F(\tau) - \frac{1}{2} \cos \Omega t \int_{\alpha_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) + \frac{1}{2} \sin \Omega t \int_{\alpha_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau)$$

Now determine constants:

use initial condition $y(t_0) = P$ $\frac{d}{dt} y|_{t_0} = V$

$$y(t_0) = P = -\frac{1}{2} \left(\cos \Omega t_0 \int_{\alpha_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) - \sin \Omega t_0 \int_{\alpha_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau) \right)$$

$$\left. \frac{d}{dt} y \right|_{t_0} = V = \sin \Omega t_0 \int_{\Omega_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) + \cos \Omega t_0 \int_{\Omega_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau)$$

$$\begin{pmatrix} -\frac{1}{\Omega} \cos \Omega t_0 & \frac{1}{\Omega} \sin \Omega t_0 \\ \sin \Omega t_0 & \cos \Omega t_0 \end{pmatrix} \begin{pmatrix} \int_{\Omega_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) \\ \int_{\Omega_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau) \end{pmatrix} = \begin{pmatrix} P \\ V \end{pmatrix}$$

$$\begin{pmatrix} \int_{\Omega_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) \\ \int_{\Omega_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau) \end{pmatrix} = \begin{pmatrix} -\Omega \cos \Omega t_0 & \sin \Omega t_0 \\ \Omega \sin \Omega t_0 & \cos \Omega t_0 \end{pmatrix} \begin{pmatrix} P \\ V \end{pmatrix}$$

Plug in constants:

$$y(t) = \frac{1}{\Omega} \int_{t_0}^t d\tau \sin[\Omega(t-\tau)] F(\tau) - \frac{1}{\Omega} \cos \Omega t \int_{\Omega_1}^{t_0} d\tau \sin(\Omega \tau) F(\tau) + \frac{1}{\Omega} \sin \Omega t \int_{\Omega_2}^{t_0} d\tau \cos(\Omega \tau) F(\tau)$$

$$= \frac{1}{\Omega} \int_{t_0}^t d\tau \sin(\Omega(t-\tau)) F(\tau)$$

$$- \frac{1}{\Omega} \cos \Omega t [-P \Omega \cos \Omega t_0 + V \sin \Omega t_0] + \frac{1}{\Omega} \sin \Omega t [P \Omega \sin \Omega t_0 + V \cos \Omega t_0]$$

$$= \frac{1}{\Omega} \int_{t_0}^t d\tau \sin(\Omega(t-\tau)) F(\tau)$$

$$+ P [\underbrace{\cos \Omega t \cos \Omega t_0 + \sin \Omega t \sin \Omega t_0}_{\cos[\Omega(t-t_0)]}] + \frac{V}{\Omega} [\underbrace{\sin \Omega t \cos \Omega t_0 - \cos \Omega t \sin \Omega t_0}_{\sin[\Omega(t-t_0)]}]$$

let $\tau \rightarrow t'$

$$y(t) = \frac{1}{\Omega} \int_{t_0}^t dt' \sin[\Omega(t-t')] F(t') + P \cos[\Omega(t-t_0)] + \frac{V}{\Omega} \sin[\Omega(t-t_0)]$$

Same answer as part ii)

b)

$$m \ddot{R}_a + \sum_{b=1}^N K_{ab} R_b = H_a(t)$$

Real, symmetric

lets try an ansatz for $G_a \sim E_a e^{-i\omega t}$

then $\ddot{G}_a = -\omega^2 E_a e^{-i\omega t}$ where E_a represent
size N eigenvector for each oscillator.
↓
 N -normal modes

Now Green's function obey:

$$m \ddot{G}_a(t, t_0) + K_{ab} G_b(t, t_0) = \delta_a(t - t_0)$$

$$\hookrightarrow -m\omega^2 E_a e^{-i\omega t} + \sum_{b=1}^N K_{ab} E_b e^{-i\omega t} = \delta_a(t - t_0)$$

For $t \neq t_0$, $\delta_a(t - t_0) = 0$, we obey homogeneous eq:

$$m\omega^2 E_a e^{i\omega t} = K_{ab} E_b e^{i\omega t}$$

$$m\omega^2 E_a \stackrel{\uparrow}{=} K_{ab} E_b$$

we observe K_{ab} has eigenvalue of $m\omega^2 \delta_{ab}$
and eigenvector of E_b

by solving $\det(m\omega^2 \delta_{ab} - K_{ab}) = 0$ for G

we obtain corresponding ω_{\pm} for G

then we have a general solution for G :

$$G_a(t, t_0) = \sum_{j=1}^N C_j^+ E_a^j e^{-i\omega_j(t-t_0)} + C_j^- E_a^j e^{i\omega_j(t-t_0)}$$

with boundary condition.

$$\lim_{t \rightarrow t_0 - \epsilon} G_a(t, t_0) = 0$$

$$\hookrightarrow C_j^+ E_a^j + C_j^- E_a^j = 0 \quad \leftarrow \text{first condition}$$

$$\text{let } C_j^+ = -C_j^- \quad (1)$$

Integrate to get second boundary condition

$$\int_{t_0 - \epsilon}^{t_0 + \epsilon} dt (m \ddot{G}_a + K_{ab} G_b) = 1$$

$$\hookrightarrow m \left. \frac{dG_a}{dt}(t, t_0) \right|_{t_0} = 1$$

$$\hookrightarrow -im\omega_j (C_j^+ E_a^j - C_j^- E_a^j) = 1$$

using (1)

$$\hookrightarrow (-2im\omega_j C_j^+) E_a^j = 1$$

$$\hookrightarrow C_j^+ = \frac{1}{-2im} [\omega_j]^{-1}$$

$$\text{then } G_a(t, t_0) = \sum \frac{1}{2im} E_a^j (e^{-i\omega_j(t-t_0)} - e^{i\omega_j(t-t_0)}) [\omega_j]^{-1}$$

$$G_a(t, t_0) = \sum_{j=1}^N \frac{1}{m} [\omega_j]^{-1} E_a^j \sin[\omega_j(t-t_0)]$$

Now use result from part a)

$$\text{let } P_a = R_a(t=t_0) \quad V_a = \dot{R}_a(t=t_0)$$

Now let $E_a^j = V_{ab}^j$ where V_{ab}^j represent individual element in the matrix

Then using solution found in part a), and plug in $G_a(t, t_0)$:

$$\begin{aligned} \hookrightarrow R_a(t) = & \int_{t_0}^t dt' \frac{1}{m} [\omega^j]^{-1} E_a^j \sin[\omega^j(t' - t_0)] H_b(t') \\ & - P_a \frac{1}{m} E_a^j \cos[\omega^j(t - t_0)] + V_a \frac{1}{m} [\omega^j]^{-1} E_a^j \sin[\omega^j(t - t_0)] \end{aligned}$$