1) a) write down eigenstates of Sx in 1/2, ±1/2>, eigenstates of Sz

From previous HW, we know  $S_x = \frac{\pi}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ ,  $S_z = \frac{\pi}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ 

we see that Sz has eigenvalues \frac{t}{2} and \frac{th}{2} since it is only non-zero in the diagonal.

$$\begin{pmatrix} \frac{1}{2} - \lambda & D \\ D & -\frac{1}{2} - \lambda \end{pmatrix} = 0 \quad \text{using } \lambda \text{!"}, \text{ we get eigevectors:} \\
\begin{vmatrix} \frac{1}{2} & +\frac{1}{2} & \rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{vmatrix} \frac{1}{2} & -\frac{1}{2} & \rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Now find eigenvalues of  $S_x = \frac{1}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ 

$$\left| \begin{pmatrix} -\lambda & \frac{\pi}{2} \\ \frac{\pi}{2} & -\lambda \end{pmatrix} \right| = \left( \lambda^2 - \frac{\pi^2}{4} \right) = 0$$
, or  $\lambda = \pm \frac{\pi}{2}$ 

For 
$$\lambda = \frac{\hbar}{2}$$
:  $\frac{\hbar}{2} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} a_t \\ b_t \end{pmatrix} = \begin{pmatrix} -a_t + b_t \\ a_t - b_t \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ 

For 
$$\lambda = -\frac{1}{2}$$
:
$$\frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} a_{-} \\ b_{-} \end{pmatrix} = \begin{pmatrix} a_{-} + b_{-} \\ a_{-} + b_{-} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \xrightarrow{\text{Eigenstate of Sx in Sz eigenbasis}}$$
or  $\alpha_{-} = -b_{-} \Rightarrow \nu_{-}^{(x)} = \frac{1}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 2, \frac{1}{2} \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 2, \frac{1}{2} \end{pmatrix} = \frac{1}{2}$ 

Summary:  

$$V_{+}^{(x)} = \frac{1}{12} \left( |\underline{1},\underline{1}\rangle + |\underline{1},\underline{1}\rangle \right) \quad \text{for } \lambda = \frac{1}{2}$$

$$V_{-}^{(x)} = \frac{1}{12} \left( |\underline{1},\underline{1}\rangle - |\underline{1},\underline{1}\rangle \right) \quad \text{for } \lambda = \frac{1}{2}$$

b) write down eigenstates of Lx in terms of 1, m>, eigenstates of Lz.

From previous HW, we Know:

$$L_{\overline{z}} = h \begin{pmatrix} 1 & D & D \\ 0 & D & D \end{pmatrix} \text{ and } L_{\overline{x}} = \frac{h}{\overline{D}} \begin{pmatrix} D & 1 & D \\ 1 & O & 1 \\ D & 1 & D \end{pmatrix}$$

m=1, m=0, m=-1

Since Lz B a diagonal matrix, clearly  $\lambda = \{\lambda_1, \lambda_0, \lambda_1^2 = \{h, 0, -h\}$ 

with eigen vectors 
$$V_{+} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$
  $V_{0} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ 

Now find eigenvalues for Lx:

$$\begin{vmatrix} -\lambda & \frac{\pi}{2} & 0 \\ \frac{\pi}{2} & -\lambda & \frac{\pi}{2} \\ 0 & \frac{\pi}{2} & -\lambda \end{vmatrix} = (-\lambda) \left[\lambda^{2} \left(\frac{\pi}{2}\right)^{2}\right] - \frac{\pi}{2} \left[-\lambda \frac{\pi}{2}\right]$$

$$= -\lambda^{3} + \lambda \left(\frac{\pi}{2}\right)^{2} + \lambda \left(\frac{\pi}{2}\right)^{2}$$

$$= -\lambda^{3} + 2\lambda \left(\frac{\pi}{2}\right)^{2} - \lambda^{2}$$

$$= \lambda \left[2\left(\frac{\pi}{2}\right)^{2} - \lambda^{2}\right]$$

$$\lambda = 0, \pm \pi$$

For 
$$\lambda = \pm \kappa$$
:

b 
$$\pm a = \frac{b}{c}$$
,  $\pm c = \frac{b}{c} =$  let  $b = \frac{1}{c}$ , the  $a = c = \pm 1$ 

$$\frac{1}{5} \sqrt{\frac{1}{2}} = \frac{1}{1} = \frac{1$$

$$L_{3} \quad V_{3} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{2}} \left( |1,1\rangle + |1,-1\rangle \right) \quad \text{for } \lambda = 0$$

2) Spherical Harmonia: 
$$\Gamma(\hat{\theta}, \hat{\phi}) = \langle \hat{n} | 1, m \rangle$$
 in momentum space.

$$\Rightarrow$$
 We can also see this by recognizing  $L = \vec{x} \times \vec{p} = \vec{x} \times -i\hbar \vec{\nabla}_x$   
in position space.  $= -i\hbar(\vec{x} \times \vec{p}_x)$ 

> In momentum space, 
$$X_i = i\hbar \vec{p}_i = i\hbar \vec{\nabla}_p$$
, so  $\vec{L}^= i\hbar \vec{\nabla}_p \times \vec{p} = -i\hbar (\vec{p} \times \vec{\nabla}_p)$ 

B/ companing: 
$$L = -i\hbar(\vec{p} \times \vec{\nabla}) = -i\hbar(\vec{x} \times \vec{\nabla}_{x})$$

which has the same form as position space but  $\vec{x} \rightleftharpoons \vec{p}$ Then we have  $\vec{L}_{x}^{2} + (\vec{x}) \rightarrow \vec{L}_{p}^{2} + (\vec{p})$  Therefore, the solution to  $\vec{L}^2$  in position space,  $\vec{L}^2 + (\vec{x})$  i.e.  $\vec{L}^2 (0, \phi)$ , must have the same form, except that we swap the angular part of  $\vec{x} \rightarrow \vec{p}$ .

i.e.  $\theta \rightarrow \tilde{\theta}$  ,  $\phi \rightarrow \tilde{\phi}$ 

 $\frac{2}{1}\left(\delta,\delta\right) = \frac{(-1)^{1}}{2^{1}t!} \frac{(2t+1)}{4\pi} \frac{(1+m)!}{(1-m)!} e^{im\delta} \frac{1}{sim^{n}\delta} \frac{1}{d(ss\delta)^{t-m}} \left(sin\delta\right)^{2t}$ and  $\frac{2}{1}\left(\delta,\delta\right) = (-1)^{m}\left[\frac{2}{1}\left(\delta,\delta\right)\right]^{\frac{1}{2}}$ 

4) 
$$\gamma(\theta, \phi) = \frac{3\gamma_{1}^{1} + 4\gamma_{7}^{3} + \gamma_{7}^{1}}{\sqrt{26}}$$

Lz 4 = 
$$\frac{1}{26}$$
 (th (3 T1) + 3th (4 T7) + th T7)

we will measure Lz with values

1) to with probability 
$$\left|\frac{3}{126}\right|^2 + \left|\frac{1}{126}\right|^2 = \frac{10}{26}$$
2) 3to With probability  $\left|\frac{4}{126}\right|^2 = \frac{16}{26}$ 

$$\sqrt{L^{2}} = t^{2} \left( \sqrt{11(1+1)} \cdot 3T_{1}^{1} + \sqrt{17(7+1)} \cdot 4T_{7}^{3} + \sqrt{17(7+1)} \cdot T_{7}^{1} \right)$$

$$= t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot 4T_{7}^{3} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{7}^{1} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot T_{1}^{2} \right) = t^{2} \left( \sqrt{12} \cdot 3T_{1}^{1} + \sqrt{56} \cdot$$

L has the possible values:

$$\text{(2)} \sqrt{2} \text{ th}^2 \text{ with probability} : \left| \frac{3}{26} \right|^2 = \frac{9}{26}$$

(2) 156 to With probability:  $\left|\frac{3}{126}\right|^2 = \frac{9}{26}$ 

S) 
$$4(\theta,\phi) = \frac{1}{4\pi} \sin \phi \sin \theta$$

By looking at table,  $Y_1 = 7 \cdot \frac{3}{8\pi} \sin \theta e^{\frac{1}{2}i\phi}$ 

So  $4(\theta,\phi) = \frac{1}{4\pi} \sin \theta \left(\frac{e^{i\phi} - e^{-i\phi}}{2i}\right)$ 

$$= \frac{1}{12i} \left(\frac{3}{8\pi} \sin \theta e^{i\phi} - \frac{3}{8\pi} \sin \theta e^{i\phi}\right)$$

$$= \frac{1}{12i} \left(-Y_1 - Y_1^{-1}\right)$$

$$4(\theta,\phi) = \frac{1}{12i} \left(Y_1 + Y_1^{-1}\right)$$

a) 
$$L_{\overline{z}} \gamma = \frac{1}{12} ((t_1) \gamma_1^2 + (-t_2) \gamma_1^2)$$

It will have measurement to and -to with probability 1/2 for both measurement.

b) 
$$\langle L_{x} \rangle = \langle \frac{L_{+} + L_{-}}{2} \rangle = \frac{*}{4(0, \phi)} \left\{ \frac{1}{2} \frac{1}{12} \left( D + \sqrt{(1-(1))}(1-1+1)} Y_{1}^{p} + \sqrt{(1+1)}(1-1+1)} Y_{1}^{p} + D \right) \right\}$$

$$= 2^{*}(0, \phi) \frac{1}{2} \frac{1}{12} \left( 2\sqrt{2} Y_{1}^{p} \right)$$

$$= \frac{1}{12} \left( Y_{1}^{1} + Y_{1}^{-1} \right)^{*} i Y_{1}^{p}$$

$$\langle L_{x} \rangle = D$$

c) 
$$\langle L^2 \rangle = 4^* L^2 4 = 4^* \frac{1}{6} t^2 (\sqrt{1 + 1}) + \sqrt{1 + 1}$$

$$= 4^* \frac{1}{6} t^2 \sqrt{2} (\sqrt{1 + 1}) + \sqrt{1 + 1}$$

$$= 5 t^2 4^* 4$$

$$= 5 t^2 4^* 4$$

$$= 5 t^2 4^* 4$$