

# 形态学边缘提取

---

$$\beta(A) = A - (A \ominus B)$$

实现代码：

```
def contour_morphology(image):  
    return image - cv2.erode(image, np.ones((3, 3), np.uint8))
```

实现很简单，原图减腐蚀的图

## 结果

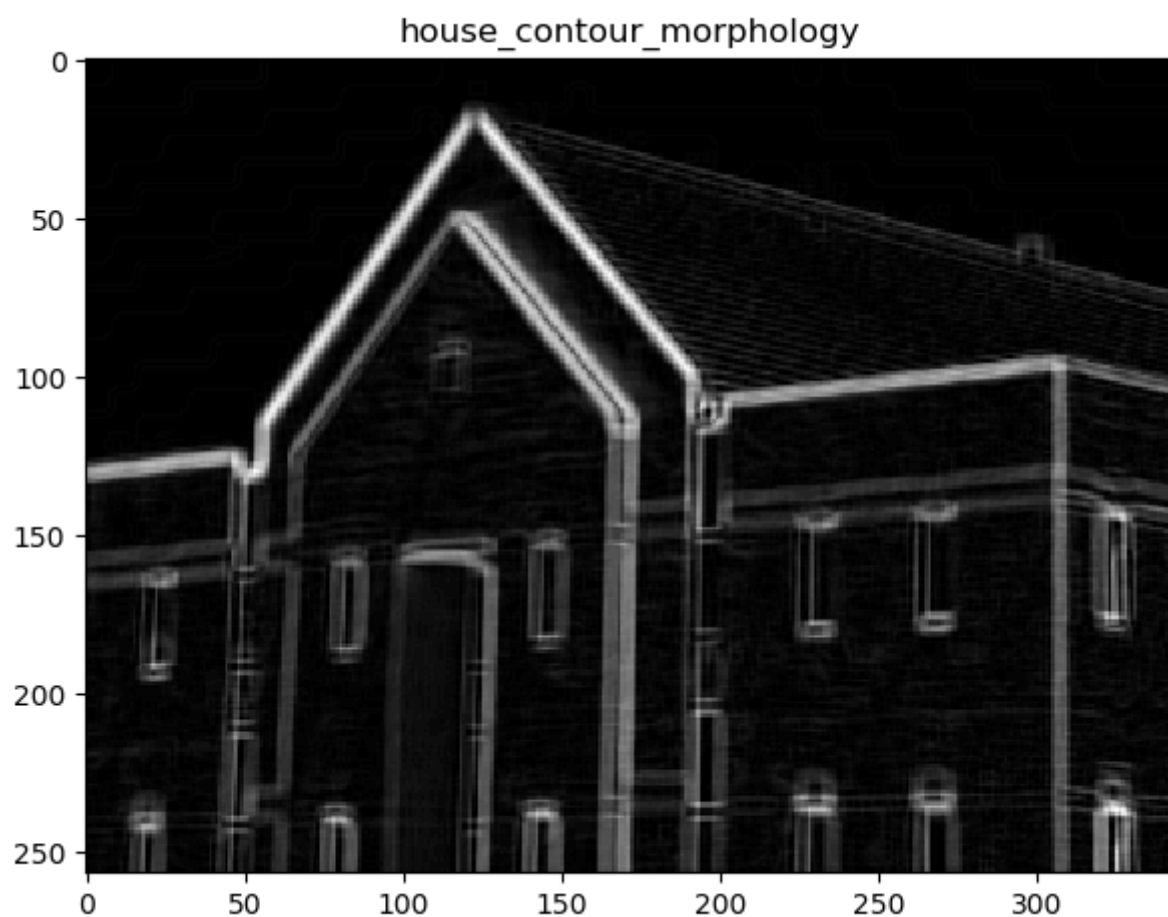


为了去除房顶瓦片，对其进行均值平滑处理后的结果

```
mask_averaging = np.array([  
    [1, 1, 1, 1, 1],  
    [1, 1, 1, 1, 1],
```

```
[1, 1, 1, 1, 1],  
[1, 1, 1, 1, 1],  
[1, 1, 1, 1, 1],  
], np.float)/25  
house_averaging = cv2.filter2D(house, -1, mask_averaging)  
house_contour_morphology = contour_morphology(house_averaging )
```

## 结果



虽然瓦片被去除了，可是轮廓边粗了，房顶边缘变弱

# 线的检测

---

```
mask_45 = np.array([
    [-1, -1, 2],
    [-1, 2, -1],
    [2, -1, -1],
])

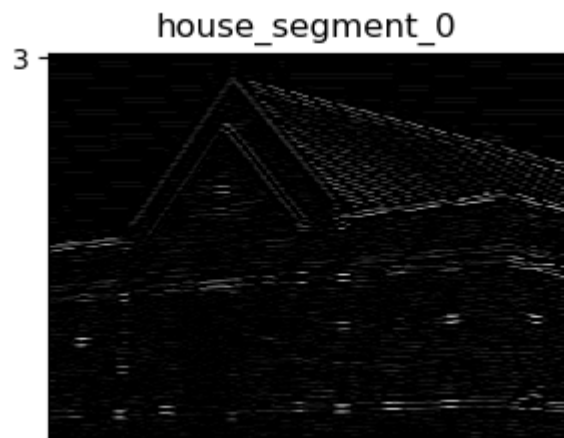
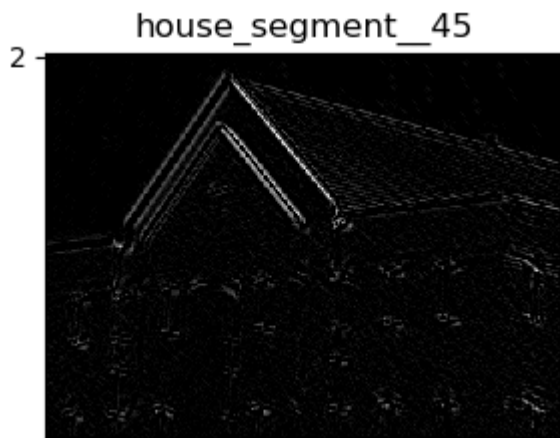
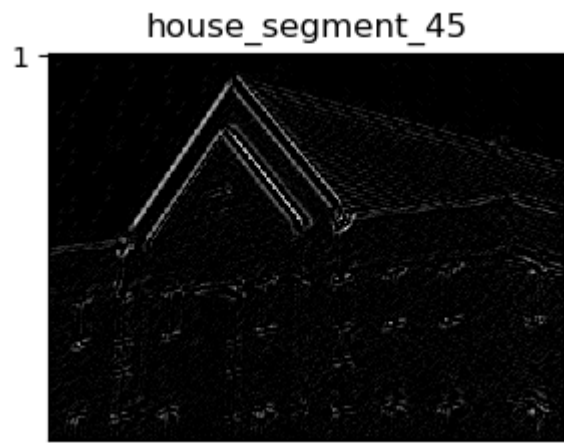
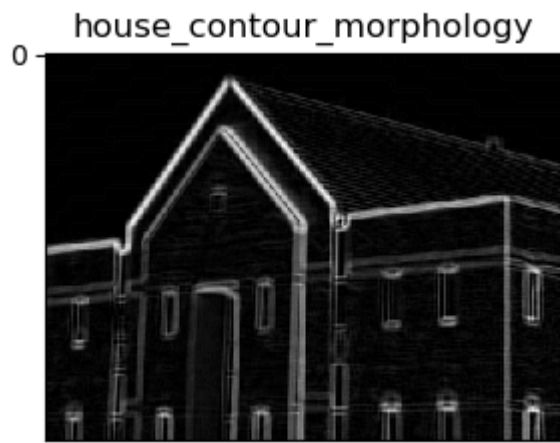
house_segment_45 = cv2.filter2D(house_contour_morphology, -1, mask_45)
mask__45 = np.array([
    [2, -1, -1],
    [-1, 2, -1],
    [-1, -1, 2],
])

house_segment__45 = cv2.filter2D(house_contour_morphology, -1, mask__45)
mask_0 = np.array([
    [-1, -1, -1],
    [2, 2, 2],
    [-1, -1, -1],
])

house_segment_0 = cv2.filter2D(house_contour_morphology, -1, mask_0)
```

用上一步的输出house\_contour\_morphology作为输入：

## 结果



方向固定，不能很好的检测直线

## 梯度算子

---

```
mask_sobel_horizontal = np.array([
    [-1, -2, -1],
    [0, 0, 0],
    [1, 2, 1],
])

mask_sobel_vertical = np.array([
    [-1, 0, 1],
    [-2, 0, 2],
    [-1, 0, 1],
])

mask_sobel_diagonal = np.array([
    [-2, -1, 0],
    [-1, 0, 1],
    [0, 1, 2],
])
```

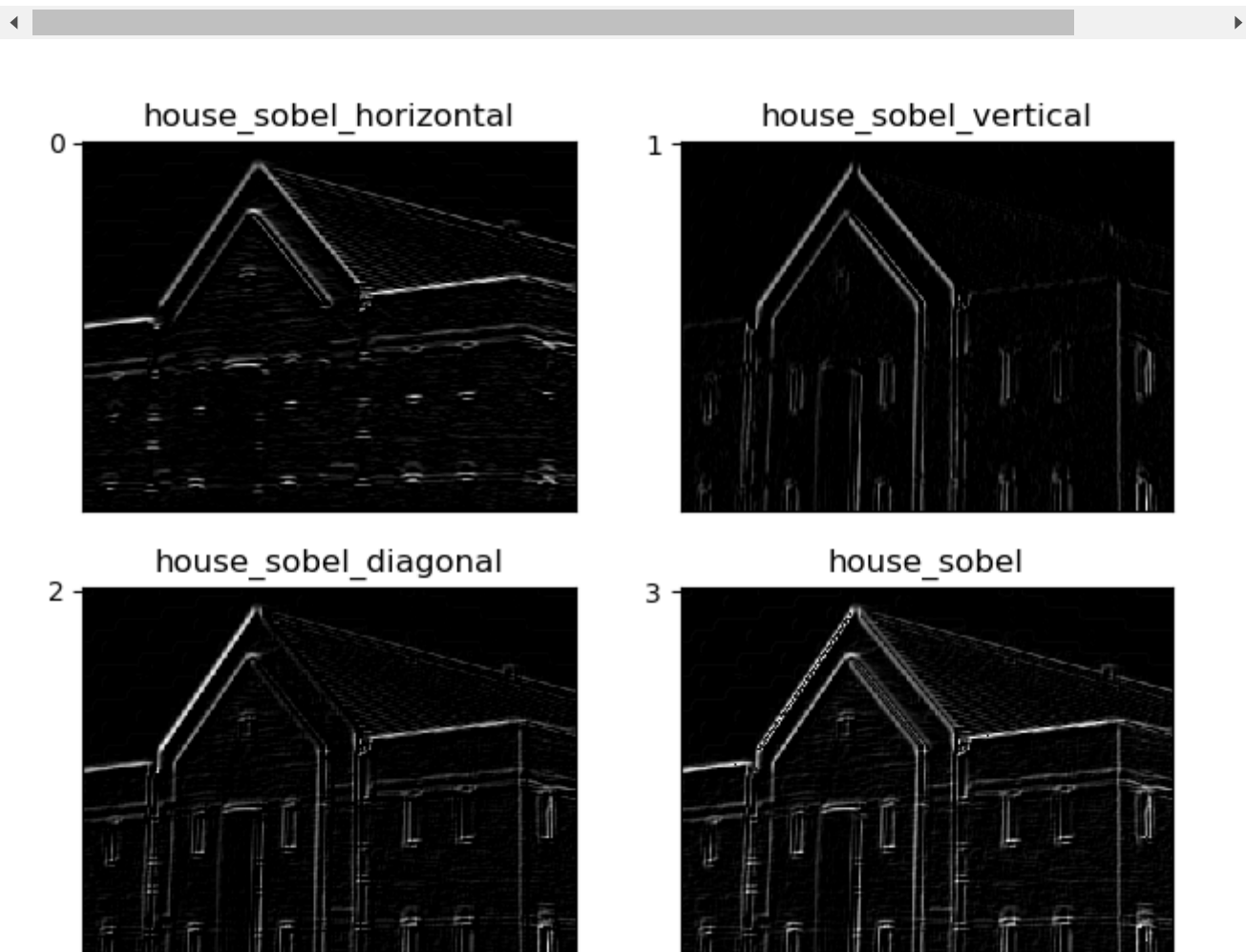
```

house_sobel_horizontal = cv2.filter2D(house_contour_morphology, -1, mask_sobel_h)
house_sobel_vertical = cv2.filter2D(house_contour_morphology, -1, mask_sobel_ver)
house_sobel_diagonal = cv2.filter2D(house_contour_morphology, -1, mask_sobel_dia)
plt_show_opcv("house_sobel", house_sobel)

```

用上一步的输出house\_contour\_morphology作为输入:

### 结果



## 霍夫/Hough变换

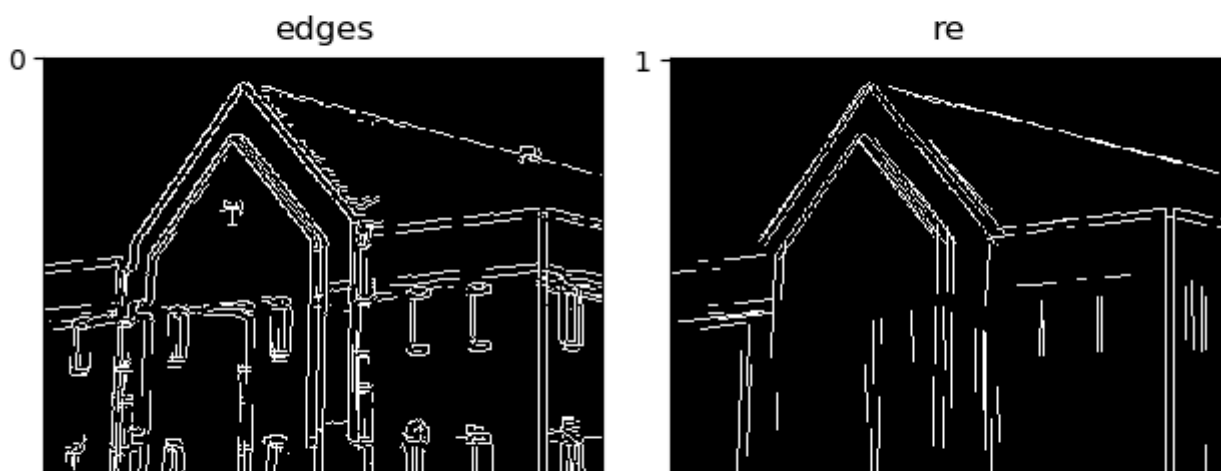
```

edges = cv2.Canny(house_contour_morphology, 50, 20)
re = np.zeros(house.shape, np.uint8)
lines = cv2.HoughLinesP(edges, 1, np.pi/180, 30, minLineLength=30, maxLineGap=5)
lines = lines[:, 0, :]
for x1, y1, x2, y2 in lines:
    cv2.line(re, (x1, y1), (x2, y2), (255, 255, 255), 1)

```

先用Canny算法进行边缘检测，再用霍夫变换检测直线轮廓。用上一步的输出  
house\_contour\_morphology作为输入：

## 结果



原图作为输入：

