# Mathematics for Computer Science Linear Algebra

Lecture 8: General (real) vector spaces

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### Contents for today's lecture

- General real vector spaces abstract vectors
- Subspaces
- Linear combinations and spanning
- Fields abstract scalars

### Reminder: Euclidean vector spaces $\mathbb{R}^n$

- $\mathbb{R}^n = \{(a_1, \dots, a_n) \mid \text{ all } a_i \in \mathbb{R}\}$ , vectors are *n*-tuples of real numbers
- Operations on  $\mathbb{R}^n$ : addition and multiplication by a real scalar

$$(a_1, \ldots, a_n) + (b_1, \ldots, b_n) = (a_1 + b_1, \ldots, a_n + b_n)$$
  
 $k(a_1, \ldots, a_n) = (ka_1, \ldots, ka_n)$ 

# General (real) vector spaces

#### **Definition**

Let V be a set equipped with operations of "addition" and "multiplication by scalars", that is, for every  $\mathbf{u}, \mathbf{v} \in V$  and every  $k \in \mathbb{R}$ ,

- the "sum"  $\mathbf{u} + \mathbf{v} \in V$  is defined, and
- the "product"  $k\mathbf{u} \in V$  is defined.

V is called a (real) vector space, or linear space, if the following 8 axioms hold:

- 0 u + v = v + u
- u + (v + w) = (u + v) + w,
- **3** there is an element  $\mathbf{0} \in V$  such that  $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$  for all  $\mathbf{u}$ ,
- **①** for each  $\mathbf{u} \in V$ , there is  $-\mathbf{u} \in V$  such that  $\mathbf{u} + (-\mathbf{u}) = (-\mathbf{u}) + \mathbf{u} = \mathbf{0}$ ,

- 0 1u = u.

The elements from V are called vectors.

### Examples of vector spaces

- $\mathbb{R}^n = \{(a_1, \dots, a_n) \mid \text{ all } a_i \in \mathbb{R}\}$  is a vector space.
- The set  $\mathbb{R}^{\infty}$  of all infinite sequences  $\mathbf{u} = (u_1, u_2, \dots, u_n, \dots)$  is a vector space with operations of point-wise addition and multiplication (just as in  $\mathbb{R}^n$ ).

$$(u_1, u_2, \dots, u_n, \dots) + (v_1, v_2, \dots, v_n, \dots) = (u_1 + v_1, u_2 + v_2, \dots, u_n + v_n, \dots)$$
  
 $k(u_1, u_2, \dots, u_n, \dots) = (ku_1, ku_2, \dots, ku_n, \dots)$ 

- All matrices of fixed size  $m \times n$  form a vector space, denoted  $\mathbb{M}_{mn}$ , with the usual operations of matrix addition and multiplication by scalars.
- The set  $F(-\infty, \infty)$  of real-valued functions with point-wise operations: if  $\mathbf{f} = f(x)$  and  $\mathbf{g} = g(x)$  then

$$(\mathbf{f} + \mathbf{g})(x) = f(x) + g(x)$$
$$(k\mathbf{f})(x) = k \cdot f(x)$$

is a vector space.

## An unusual example and a non-example

An unusual vector space: Let V be the set of all real numbers, and, for any vectors  $\mathbf{u} = u$  and  $\mathbf{v} = v$  in it, define

- $\mathbf{u} + \mathbf{v} = u \cdot v$ , i.e. define "addition" as the usual multiplication,
- $k\mathbf{u} = u^k$ , i.e. define "multiplication by a scalar" as the usual exponentiation.

One can check that this is indeed a vector space, i.e. all 8 axioms hold.

- Axiom 1  $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$  translates to  $u \cdot v = v \cdot u$ , which holds.
- For Axiom 3, what is an element  $\mathbf{0} \in V$  with  $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$  for all  $\mathbf{u}$ ?
- Axiom 5  $k(\mathbf{u} + \mathbf{v}) = k\mathbf{u} + k\mathbf{v}$  translates to  $(u \cdot v)^k = u^k \cdot v^k$ , which holds.
- Exercise: Check that all remaining axioms also hold.

A non-example. Modify  $\mathbb{R}^2$  as follows: re-define  $k(u_1,u_2)$  to be  $(ku_1,0)$ . One can check that the first 7 axioms are satisfied, but  $1\mathbf{u} \neq \mathbf{u}$  for any  $\mathbf{u} = (u_1,u_2)$  with  $u_2 \neq 0$ . Hence this modified object is not a vector space.

### Subspaces

#### Definition

A subset W of a vector space V is called a subspace of V if W is itself a vector space, with the operations inherited from V.

- ullet To verify that W is a subspace of V, we don't need to check all 8 axioms.
- We only need to check that W is closed under the operations of V, that is, if  $\mathbf{u}, \mathbf{v} \in W$  and  $k \in \mathbb{R}$  then  $\mathbf{u} + \mathbf{v} \in W$  and  $k\mathbf{u} \in W$ .

#### Examples of subspaces:

- ullet  $\{ oldsymbol{0} \}$  is a subspace (the zero subspace) of any vector space.
- For any fixed vector  $\mathbf{a} \in V$ , the set  $\{k\mathbf{a} \mid k \in \mathbb{R}\}$  is a subspace of V. Indeed, if  $\mathbf{u} = k_1\mathbf{a}$  and  $\mathbf{v} = k_2\mathbf{a}$  then  $\mathbf{u} + \mathbf{v} = (k_1 + k_2)\mathbf{a}$  and  $k\mathbf{u} = k(k_1\mathbf{a}) = (kk_1)\mathbf{a}$ .
- The solution set of any homogeneous linear system  $A\mathbf{x} = \mathbf{0}$  with n variables is a subspace of  $\mathbb{R}^n$ . Indeed, if  $\mathbf{u}$  and  $\mathbf{v}$  are solutions, i.e.  $A\mathbf{u} = \mathbf{0}$  and  $A\mathbf{v} = \mathbf{0}$ , and  $k \in \mathbb{R}$  is any scalar then

$$A(u + v) = Au + Av = 0 + 0 = 0$$
 and  $A(ku) = k(Au) = k0 = 0$ .

# Examples of subspaces of $F(-\infty, \infty)$

Recall the vector space  $F(-\infty,\infty)$  of real-valued functions with point-wise operations: if  $\mathbf{f}=f(x)$  and  $\mathbf{g}=g(x)$  then

$$(\mathbf{f} + \mathbf{g})(x) = f(x) + g(x)$$
$$(k\mathbf{f})(x) = k \cdot f(x)$$

It is easy to see that the following sets are subspaces of  $F(-\infty,\infty)$ .

- $C(-\infty,\infty)$  is the set of all continuous functions in  $F(-\infty,\infty)$ .
- $D(-\infty,\infty)$  is the set of all differentiable functions in  $F(-\infty,\infty)$ .
- $P_{\infty}$  is the set of all polynomials, i.e. functions  $p(x) = a_0 + a_1 x + \ldots + a_k x^k$
- $P_n$  is the set of all polynomials of degree  $\leq n$ (the degree of a polynomial is the largest k such that  $a_k \neq 0$ .)

In fact, each of them is a subspace of all the spaces above it in the list.

### Linear combinations

#### **Definition**

A vector  $\mathbf{w} \in V$  is a linear combination of vectors  $\mathbf{v}_1, \dots, \mathbf{v}_r \in V$  if  $\mathbf{w} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_r \mathbf{v}_r$  for some scalars  $k_1, \dots, k_r$ .

How do we determine whether a given  $\mathbf{w} \in \mathbb{R}^n$  is a linear combination of given  $\mathbf{v}_1, \dots, \mathbf{v}_r \in \mathbb{R}^n$ ?

We show this on an example in  $\mathbb{R}^3$ : Let  $\mathbf{v}_1=(1,2,-1)$  and  $\mathbf{v}_2=(6,4,2)$ . Which of vectors  $\mathbf{w}=(9,2,7)$  and  $\mathbf{w}'=(4,-1,8)$  is a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ ?

Here's what we need to find out:

• Are there scalars  $k_1$  and  $k_2$  such that  $\mathbf{w} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2$ , or

$$(9,2,7) = (k_1 + 6k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$$
?

• Are there scalars  $k_1'$  and  $k_2'$  such that  $\mathbf{w}' = k_1'\mathbf{v}_1 + k_2'\mathbf{v}_2$ , or

$$(4,-1,8) = (k'_1 + 6k'_2, 2k'_1 + 4k'_2, -k'_1 + 2k'_2)$$
?

### Example continued

- Does this have a solution:  $(9,2,7) = (k_1 + 6k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$ ?
- Does this have a solution:  $(4, -1, 8) = (k'_1 + 6k'_2, 2k'_1 + 4k'_2, -k'_1 + 2k'_2)$ ?

Algorithm: re-write the vector equation as a linear system (or directly as the augmented matrix of the system) and transform the matrix to row echelon form:

Recall: a solution exists  $\Leftrightarrow$  row echelon form has  $\underline{no}$  leading 1 in the last column.

Conclusion:  $\mathbf{w}$  is a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ , but  $\mathbf{w}'$  is not.

If actual values for  $k_1$  and  $k_2$  are needed, finish solving the first system.

### Linear combinations

How do we determine whether a given  $\mathbf{w} \in \mathbb{R}^n$  is a linear combination of given  $\mathbf{v}_1, \dots, \mathbf{v}_r \in \mathbb{R}^n$ ?

#### General algorithm:

- **①** Form the matrix  $A = [\mathbf{v}_1 | \dots | \mathbf{v}_r | \mathbf{w}]$  whose columns are our vectors.
- 2 Transform A to row echelon form B.
- lacktriangledown If B has  $\underline{no}$  leading 1 in the last column, answer yes. Otherwise, answer no.

### Span

Recall that a vector  $\mathbf{w} \in V$  is a linear combination of vectors  $\mathbf{v}_1, \dots, \mathbf{v}_r \in V$  if  $\mathbf{w} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_r \mathbf{v}_r$  for some scalars  $k_1, \dots, k_r$ .

#### Definition

For a non-empty subset S of a vector space V, the span of S, denoted span(S), is the set of all linear combinations of vectors in S.

#### Theorem

If S is a non-empty subset of a vector space V then  $\operatorname{span}(S)$  is a subspace of V. Moreover, it is the smallest (inclusion-wise) subspace of V that contains S.

#### Proof.

The proof is almost obvious. Clearly, if  $\mathbf{u}$  and  $\mathbf{v}$  are linear combinations of vectors from S then so is  $\mathbf{u} + \mathbf{v}$ , and, for any  $k \in \mathbb{R}$ , so is  $k\mathbf{u}$ . So, span(S) is a subspace. Now, let W be any subspace of V such that  $S \subseteq W$ . Since W is closed under the operations of V, every linear combination of vectors in S must be in W. Hence, we have  $span(S) \subseteq W$ .

# Spanning $\mathbb{R}^n$

The standard unit vectors in  $\mathbb{R}^n$  are  $\mathbf{e}_1 = (1, 0, \dots, 0), \dots, \ \mathbf{e}_n = (0, \dots, 0, 1).$ 

They span  $\mathbb{R}^n$  because any vector  $(a_1,a_2,\ldots,a_n)\in\mathbb{R}^n$  can be represented as

$$(a_1, a_2, \ldots, a_n) = a_1 \mathbf{e}_1 + a_2 \mathbf{e}_2 + \ldots + a_n \mathbf{e}_n.$$

#### Theorem

For any  $\mathbf{v}_1, \dots, \mathbf{v}_n \in \mathbb{R}^n$ , we have  $span(\mathbf{v}_1, \dots, \mathbf{v}_n) = \mathbb{R}^n$  iff  $det([\mathbf{v}_1| \dots |\mathbf{v}_n]) \neq 0$ .

#### Proof.

- Observe: we have  $span(\mathbf{v}_1, \dots, \mathbf{v}_n) = \mathbb{R}^n$  iff  $\mathbf{e}_1, \dots, \mathbf{e}_n \in span(\mathbf{v}_1, \dots, \mathbf{v}_n)$ , i.e. each vector  $\mathbf{e}_i$  is a linear combination of the  $\mathbf{v}_i$ 's (Why?)
- Let  $A = [\mathbf{v}_1 | \dots | \mathbf{v}_n]$  and observe that  $I = [\mathbf{e}_1 | \dots | \mathbf{e}_n]$ .
- Each vector  $\mathbf{e}_j$  is a linear combination of the  $\mathbf{v}_i$ 's iff there is a matrix  $B = (b_{ij})$  such that AB = I. Specifically, in this case  $\mathbf{e}_i = b_{1i}\mathbf{v}_1 + \dots b_{ni}\mathbf{v}_n$  for all j.
- Such B exists iff A is invertible, i.e. iff  $det(A) \neq 0$ .



### **Fields**

A vector space involves two types of objects: vectors and scalars

We have made vectors abstract, but used only real numbers as scalars.

In full generality, any field can be used as the set of scalars.

A field is an algebraic structure: any set with operations denoted by +, -,  $\cdot$ ,  $\div$  defined on it so that the operations satisfy the usual (for  $\mathbb{R}$ ) properties such as:

- a+b=b+a, and  $a\cdot b=b\cdot a$
- (a+b)+c=a+(b+c) and  $(a\cdot b)\cdot c=a\cdot (b\cdot c)$
- $a \cdot (b+c) = a \cdot b + a \cdot c$
- there is a "0" element for addition and a "1" element for multiplication
- each element a has a negative -a and each non-0 element has an inverse  $a^{-1}$ . Then a - b = a + (-b) and, if  $b \neq 0$ ,  $a/b = a \cdot b^{-1}$ .

A non-example: The integers  $\mathbb{Z}$  do not form a field - why?

# Examples of fields

### Examples of infinite fields (other than $\mathbb{R}$ ):

- The rational numbers  $\mathbb{Q} = \{ \frac{m}{n} \mid m, n \in \mathbb{Z} \text{ and } n \neq 0 \}.$
- The complex numbers  $\mathbb{C} = \{a + bi \mid a, b \in \mathbb{R} \text{ and } i^2 = -1\}.$

### Examples of finite fields:

- The two-element field, denoted  $\mathbb{Z}_2$  or  $\mathrm{GF}(2)$ : the set  $\{0,1\}$  with addition  $\oplus$  (aka XOR) and multiplication (aka AND) modulo 2.
- More generally,  $\mathbb{Z}_p$  or  $\mathrm{GF}(p)$  for a <u>prime</u> number p: same as above, but with the set  $\{0,1,\ldots,p-1\}$  and operations working modulo p.
- Even more generally, arbitrary finite fields  $GF(p^k)$  with  $p^k$  elements where p is a prime and  $k \ge 1$ . The operations are more involved than just mod  $p^k$ .

#### Application in coding theory:

• Vector spaces formed by n-tuples of elements from  $\mathrm{GF}(p^k)$  – i.e. like  $\mathbb{R}^n$ , but with  $\mathrm{GF}(p^k)$  in place of  $\mathbb{R}$  – are of central importance in coding theory. Subspaces of these spaces are called linear codes — this is a special type of error-correcting codes.

# What we learnt today

#### General vector spaces

- Definition and examples
- Subspaces
- Linear combinations and span
- Fields abstract scalars

#### Next time:

- Linear (in)dependence
- Bases and dimension of vector spaces