

# Mathematics for Computer Science

## Linear Algebra

### Lecture 2: Systems of Linear Equations

Andrei Krokhin

October 13, 2020

# Contents for today's lecture

- Systems of linear equations;
- Elementary row operations on matrices;
- Row echelon form and reduced row echelon form;
- Solving linear systems: Gaussian elimination;
- Examples and exercises.



# A linear system with one solution

Solve linear system

$$x - y = 1$$

$$2x + y = 6$$

Eliminate  $x$  from the 2nd equation by adding  $-2$  times the 1st equation to the 2nd.

$$x - y = 1$$

$$3y = 4$$

We have  $y = 4/3$ , and from the 1st equation  $x = 7/3$ .  
This system has **one solution**.

# A linear system with no solutions

Solve linear system

$$x + y = 4$$

$$3x + 3y = 6$$

Eliminate  $x$  from the 2nd equation by adding  $-3$  times the 1st equation to the 2nd.

$$x + y = 4$$

$$0 = -6$$

The 2nd equation is contradictory. This system has **no solutions**.

# A linear system with infinitely many solutions

Solve linear system

$$4x - 2y = 1$$

$$8x - 4y = 2$$

Eliminate  $x$  from the 2nd equation by adding  $-3$  times the 1st equation to the 2nd.

$$4x - 2y = 1$$

$$0 = 0$$

The 2nd equation imposes no restrictions on  $x$  and  $y$ , can be omitted.

Any pair of values for  $x$  and  $y$  that satisfies  $4x - 2y = 1$  is a solution.

Solving for  $x$ , we get  $x = \frac{1}{4} + \frac{1}{2}y$ .

The solution set can be described as the set of all pairs of numbers of the form  $x = \frac{1}{4} + \frac{1}{2}y, y$  ( $y$  is a **free variable** here).

This system has **infinitely many solutions**.

# Matrix form of a linear system

A linear system

$$\begin{aligned}a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= b_2 \\&\vdots = \vdots \\a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= b_m\end{aligned}$$

can be written in a matrix form as  $A\mathbf{x} = \mathbf{b}$  where

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad \text{and} \quad \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

The matrix  $A$  is called the **coefficient matrix** of the system.

If  $A$  is (square and) invertible then the solution can be found as  $\mathbf{x} = A^{-1}\mathbf{b}$ .

# The augmented matrix and elementary row operations

The **augmented matrix** of a linear system is the matrix

$$(A|\mathbf{b}) = \left( \begin{array}{cccc|c} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{array} \right)$$

The basic method for solving a linear system is to perform algebraic operations on the system that (a) do not alter the solution set and (b) produce increasingly simpler systems. Typically the operations are

- Multiply an equation through by a non-zero constant;
- Interchange two equations;
- Add a constant times one equation to another.

This corresponds to the **elementary row operations** on the augmented matrix:

- Multiply a row through by a non-zero constant;
- Interchange two rows;
- Add a constant times one row to another.



# Row echelon form

Assume that we transform the augmented matrix of a linear system in variables  $x, y, z$  to the form

$$\left( \begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{array} \right).$$

Then we know the solution: it's  $x = 1, y = 2, z = 3$ .

A matrix is in **row echelon form** if it has the following properties:

- If a row is not all 0s then the first non-zero number in it is 1 (the **leading 1**)
- The rows that are all 0s (if any) are grouped together at the bottom
- If two successive rows are not all 0s then the leading 1 of the higher row occurs further to the left than the leading 1 of the lower row.

A matrix is in **reduced row echelon form** if it has the above properties, plus

- Each column that contains a leading 1 has 0s everywhere else.

Strategy for solving linear systems: use elementary row operations to transform the augmented matrix to (reduced) row echelon form.

## Extracting solutions from row echelon form

Assume that we have transformed the augmented matrix of a linear system to a (reduced) row echelon form.

Examples:

$$\left( \begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right) \quad \left( \begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right) \quad \left( \begin{array}{ccc|c} 1 & -1 & 0 & 2 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

We have the following possibilities:

- Some row has a leading 1 in the last column.  
Then the system includes equation  $0 \cdot x_1 + \dots + 0 \cdot x_n = 1$ .  
Then we know the system has no solutions.
- The number of leading 1s is equal to the number of variables  
(and there is no leading 1 in the last column).  
Then the system has a unique solution.
- The number of leading 1s is smaller than the number of variables  
(and there is no leading 1 in the last column).  
Then the system has infinitely many solutions.

## General solution (and an example)

Assume a matrix in reduced row echelon form is as follows:

$$\left( \begin{array}{cccc|c} 1 & -1 & 0 & 2 & 2 \\ 0 & 0 & 1 & -1 & 5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

In equations, this is

$$\begin{array}{ccccccc} x_1 & & -x_2 & & & +2x_4 & = 2 \\ & & & x_3 & & -x_4 & = 5 \end{array}$$

- The variables corresponding to the leading 1s ( $x_1$  and  $x_3$  in the example) are the **leading variables**.
- The other variables are **free variables**.
- **General solution**: the leading variables expressed via free variables.
- For the above system:  $x_1 = x_2 - 2x_4 + 2$ ,  $x_3 = x_4 + 5$  (where  $x_2$  and  $x_4$  are arbitrary numbers).

# Gaussian elimination procedure

Goal: Transform a matrix to row echelon form by using row operations.

**Step 1.** Locate the **pivot column** – leftmost column that contains a non-zero.

$$\begin{pmatrix} 0 & 0 & -2 & 0 & 7 & 12 \\ 2 & 4 & -10 & 6 & 12 & 28 \\ 2 & 4 & -5 & 6 & -5 & -1 \end{pmatrix}$$

**Step 2.** Choose a **pivot** - a non-zero in the pivot column and interchange the first row with another row (if necessary) to move the pivot to the top in this column

$$\begin{pmatrix} 2 & 4 & -10 & 6 & 12 & 28 \\ 0 & 0 & -2 & 0 & 7 & 12 \\ 2 & 4 & -5 & 6 & -5 & -1 \end{pmatrix}$$

**Step 3.** If  $a$  is the pivot, multiply the first row by  $1/a$  (to get a leading 1).

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & -2 & 0 & 7 & 12 \\ 2 & 4 & -5 & 6 & -5 & -1 \end{pmatrix}$$

## Gaussian elimination procedure, cont'd

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & -2 & 0 & 7 & 12 \\ 2 & 4 & -5 & 6 & -5 & -1 \end{pmatrix}$$

**Step 4.** Add suitable multiples of the first row to the rows below so that all numbers below the leading 1 are 0s.

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & -2 & 0 & 7 & 12 \\ 0 & 0 & 5 & 0 & -17 & -29 \end{pmatrix}$$

**Step 5.** Now separate the top row from the rest (“draw a line below it”) and repeat Steps 1–5 for the matrix below the line.

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ \hline 0 & 0 & -2 & 0 & 7 & 12 \\ 0 & 0 & 5 & 0 & -17 & -29 \end{pmatrix}$$

## Gaussian elimination procedure, cont'd

$$\left( \begin{array}{cccccc} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & -2 & 0 & 7 & 12 \\ 0 & 0 & 5 & 0 & -17 & -29 \end{array} \right)$$

$$\left( \begin{array}{cccccc} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & 1 & 0 & -7/2 & -6 \\ 0 & 0 & 5 & 0 & -17 & -29 \end{array} \right)$$

$$\left( \begin{array}{cccccc} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & 1 & 0 & -7/2 & -6 \\ 0 & 0 & 0 & 0 & 1/2 & 1 \end{array} \right)$$

$$\left( \begin{array}{cccccc} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & 1 & 0 & -7/2 & -6 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{array} \right)$$

The last matrix is in row echelon form, it is the output of Gaussian elimination.

## Gauss-Jordan elimination

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & 1 & 0 & -7/2 & -6 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{pmatrix}$$

To find the reduced row echelon form, we need one step on top of Gaussian.

**Step 6.** Beginning from the last non-0 row and working upward, add suitable multiples of each row to create 0s above the leading 1s.

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{pmatrix} \quad \text{added } (7/2) \times \text{3rd row to 2nd row}$$

$$\begin{pmatrix} 1 & 2 & -5 & 3 & 0 & 2 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{pmatrix} \quad \text{added } (-6) \times \text{3rd row to 1st row}$$

$$\begin{pmatrix} 1 & 2 & 0 & 3 & 0 & 7 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{pmatrix} \quad \text{added } 5 \times \text{2nd row to 1st row}$$

## Example

Solve linear system by Gauss-Jordan elimination:

$$\begin{array}{rrrrrr} & & -2x_3 & & +7x_5 & = 12 \\ 2x_1 & +4x_2 & -10x_3 & +6x_4 & +12x_5 & = 28 \\ 2x_1 & +4x_2 & -5x_3 & +6x_4 & -5x_5 & = -1 \end{array}$$

The augmented matrix of system is

$$\left( \begin{array}{ccccc|c} 0 & 0 & -2 & 0 & 7 & 12 \\ 2 & 4 & -10 & 6 & 12 & 28 \\ 2 & 4 & -5 & 6 & -5 & -1 \end{array} \right)$$

We have already transformed the above matrix to reduced row echelon form (see four previous slides):

$$\left( \begin{array}{ccccc|c} 1 & 2 & 0 & 3 & 0 & 7 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{array} \right)$$

The general solution of the system is  $x_1 = -2x_2 - 3x_4 + 7$ ,  $x_3 = 1$ ,  $x_5 = 2$ .



# Homogeneous linear systems

- A linear system  $A\mathbf{x} = \mathbf{b}$  is **homogeneous** if  $\mathbf{b}$  is all 0s.
- Such a system has a **trivial solution**:  $\mathbf{x}$  is all 0s. Any other solution is called **non-trivial**.

## Theorem

*If a homogeneous linear system has  $n$  variables and the reduced row echelon form of its augmented matrix has  $r$  non-0 rows then the system has  $n - r$  free variables.*

The above theorem follows immediately from the shape of the reduced row echelon form.

Being consistent and having free variables implies having infinitely many solutions.

## Corollary

*A homogeneous linear system with more variables than equations has infinitely many solutions.*