

```

<sdf>
  <world>
    <model name="ground_plane">
      ...
    </model>
    <model name="vehicle_blue">
      <link name="chassis"> ... </link>
      <link name="front_left_wheel"> ... </link>
      <joint name="front_left_steering_joint"> ... </joint>
      <plugin filename="gz-sim-ackermann-steering-system">
        <left_joint>front_left_wheel_joint</left_joint>
        ...
      </plugin>
      ...
    </model>
  </world>
</sdf>

```

