

# Causality

## Talk 2: Directed acyclic graph (DAG) models

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Note: The following slides are primarily adapted from the course materials<sup>1</sup>.

Nov 26, 2025

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<sup>1</sup>C. Heinze-Deml. Causality. URL: <https://stat.ethz.ch/lectures/ss21/causality.php>.



# Directed acyclic graph (DAG) models

Causality

Christina Heinze-Deml

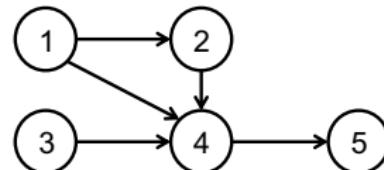
Spring 2021

# Today

- Graph terminology
- Directed acyclic graph (DAG) models
- Markov properties
- d-separation

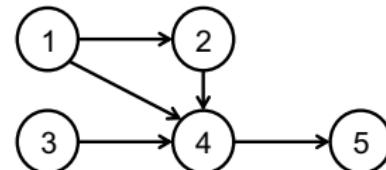
## Graph terminology

- A graph  $G = (V, E)$  consists of vertices (nodes)  $V$  and edges  $E$
- There is at most one edge between every ordered pair of vertices
- Two vertices are adjacent if there is an edge between them
- If all edges are directed ( $i \rightarrow j$ ), the graph is called directed
- A path between  $i$  and  $j$  is a sequence of distinct vertices  $(i, \dots, j)$  such that successive vertices are adjacent
- A directed path from  $i$  to  $j$  is a path between  $i$  and  $j$  where all edges are pointing towards  $j$ , i.e.,  $i \rightarrow \dots \rightarrow j$



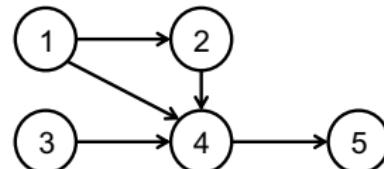
## Graph terminology

- A **cycle** is a path  $(i, j, \dots, k)$  plus an edge between  $k$  and  $i$
- A **directed cycle** is a directed path  $(i, j, \dots, k)$  from  $i$  to  $k$ , plus an edge  $k \rightarrow i$
- A **directed acyclic graph (DAG)** is a directed graph without directed cycles



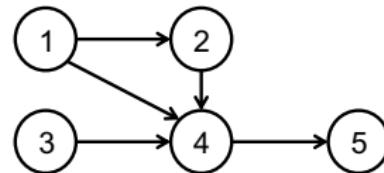
## Graph terminology

- If  $i \rightarrow j$ , then  $i$  is a **parent** of  $j$ , and  $j$  is a **child** of  $i$
- If there is a directed path from  $i$  to  $j$ , then  $i$  is an **ancestor** of  $j$  and  $j$  is a **descendant** of  $i$
- Each vertex is also an ancestor and descendant of itself
- The sets of parents, children, descendants and ancestors of  $i$  in  $G$  are denoted by  $\text{pa}(i, G)$ ,  $\text{ch}(i, G)$ ,  $\text{desc}(i, G)$ ,  $\text{an}(i, G)$
- We omit  $G$  if the graph is clear from the context



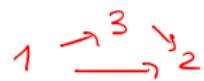
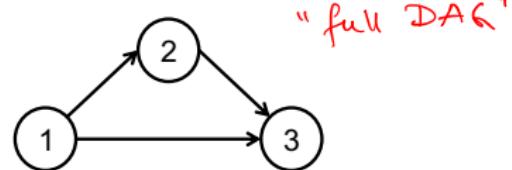
## Graph terminology

- We write sets of vertices in bold face
- The previous definitions are applied disjunctively to sets
  - Example:  $\text{pa}(\mathbf{S}) = \bigcup_{k \in \mathbf{S}} \text{pa}(k)$
- The non-descendants of  $\mathbf{S}$  are the complement of  $\text{desc}(\mathbf{S})$ :  
$$\text{nondesc}(\mathbf{S}) := \mathbf{V} \setminus \text{desc}(\mathbf{S})$$



## Graph terminology

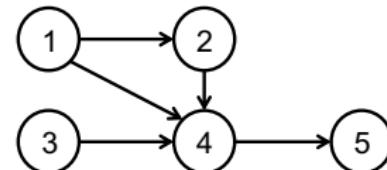
- We call  $G$  **fully connected** if all pairs of nodes are adjacent
- How many possibilities for a fully connected DAG?



$P!$  possibilities ;  $P = |V|$

## DAGs and random variables

- Each vertex represents a random variable:  
vertex  $i$  represents random variable  $X_i$
- If  $A \subseteq V$ , then  $X_A := \{X_i : i \in A\}$
- Edges denote relationships between pairs of variables  
(we will make this more precise)



## Factorization of the joint density

- We can connect a distribution with density  $f$  to a DAG in the following way:
- We always have:

$$f(x_1, \dots, x_p) = f(x_1) \underbrace{f(x_2|x_1)}_{\dots} f(x_p|x_1, \dots, x_{p-1}) \quad \text{"chain rule"}$$

- A set of variables  $X_{\text{pa}(j)}$  is said to be **Markovian parents** of  $X_j$  if it is a minimal subset of  $\{X_1, \dots, X_{j-1}\}$  such that  $f(\underbrace{x_j|x_1, \dots, x_{j-1}}_{\dots}) = f(\underbrace{x_j|x_{\text{pa}(j)}}_{\dots})$
- Note: Markovian parents depend on the chosen ordering of the variables

## Factorization of the joint density

- We always have:

$$f(x_1, \dots, x_p) = f(x_1)f(x_2|x_1) \dots f(x_p|x_1, \dots, x_{p-1})$$

- A set of variables  $X_{\text{pa}(j)}$  is said to be **Markovian parents** of  $X_j$  if it is a minimal subset of  $\{X_1, \dots, X_{j-1}\}$  such that  $f(x_j|x_1, \dots, x_{j-1}) = f(x_j|x_{\text{pa}(j)})$
- Then

$$f(x_1, \dots, x_p) = \prod_{j=1}^p f(x_j|x_{\text{pa}(j)})$$

"factorization  
property"

- We can draw a DAG accordingly
- The distribution is said to **factorize** according to this DAG

## Notes week 2 - I

Consider  $(X_1, X_2, X_3)$  and suppose that  $X_1 \perp\!\!\!\perp X_3 \mid X_2$

is the only (conditional) independence:

$$f(x_1 \mid x_2, x_3) = f(x_1 \mid x_2)$$

$$f(x_3 \mid x_1, x_2) = f(x_3 \mid x_2)$$

Then  $f(x_1, x_2, x_3) = f(x_1) f(x_2) f(x_3 \mid x_1, x_2)$  } simplify  
 $= f(x_1) f(x_2) f(x_3 \mid x_2)$

DAG:  $1 \rightarrow 2 \rightarrow 3$

Or  $f(x_3, x_2, x_1) = f(x_3) f(x_2 \mid x_3) f(x_1 \mid x_2, x_3)$  } simplify  
 $= f(x_3) f(x_2 \mid x_3) f(x_1 \mid x_2)$

DAG:  $3 \rightarrow 2 \rightarrow 1$

Or  $f(x_1, x_3, x_2) = f(x_1) f(x_3 \mid x_1) f(x_2 \mid x_1, x_3)$  cannot simplify further  
DAG:  $1 \overbrace{\longrightarrow}^{ } 3 \rightarrow 2$

Note: Markovian parents depend on the chosen ordering  
of the variables

## Factorization of the joint density

- A distribution can factorize according to several DAGs
- Every distribution factorizes according to a full DAG
  - Note: there are  $p!$  possibilities
- Sometimes a distribution factorizes according to a sparse DAG
  - I.e., a DAG with few edges
  - E.g. first-order Markov chain:
    - $f(x_1, \dots, x_p) = f(x_1)f(x_2|x_1) \dots f(x_p|x_1, \dots, x_{p-1}) = f(x_1)f(x_2|x_1) \dots f(x_p|x_{p-1})$
    - DAG:  $1 \rightarrow 2 \rightarrow \dots \rightarrow p$

## DAG models

- A **DAG model** or **Bayesian network** is a combination  $(G, P)$ , where  $G$  is a DAG and  $P$  is a distribution that factorizes according to  $G$
- DAG models can be used for various purposes:
  - Estimating the joint density from low order conditional densities
  - Reading off conditional independencies from the DAG
  - Probabilistic reasoning (expert systems)
  - Causal inference

## Estimating the joint density

- Estimating the joint density of many variables is generally difficult
  - Example: The joint distribution of  $p$  binary variables requires  $2^p - 1$  parameters
- But if you know that the distribution factorizes according to a DAG, then you only need to estimate  $f(x_i | x_{\text{pa}(i)})$  for  $i = 1, \dots, p$   
 $x_{\text{pa}(i)}$
- If the parent sets are small, this means we only need to estimate low order conditional densities

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## Reading off conditional independencies: Markov property

- First-order Markov models: the future is independent of the past given the present

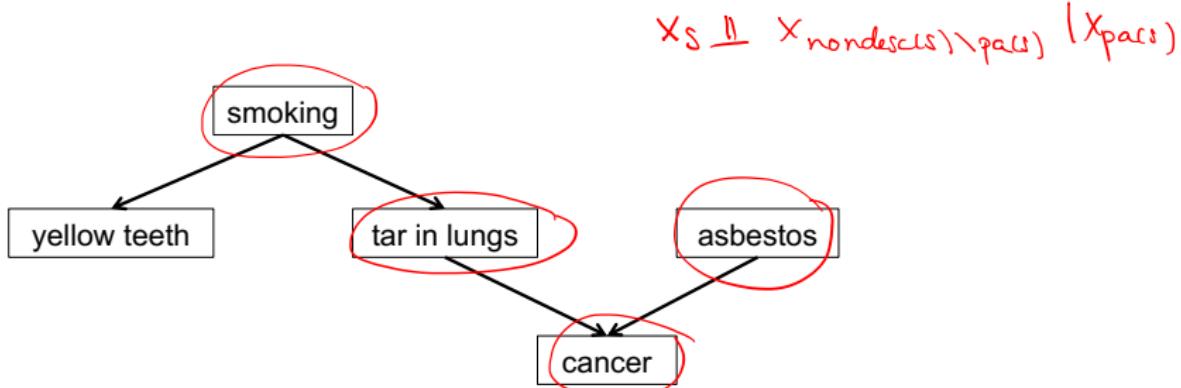
$$1 \rightarrow 2 \rightarrow \dots \rightarrow (t-1) \rightarrow t \rightarrow (t+1)$$

$$X_{t+1} \perp\!\!\!\perp \{X_{t-1}, X_{t-2}, \dots, X_1\} \mid X_t$$

- In DAG models, we have a similar (local) Markov property
- Let  $S$  be any collection of nodes. Then:

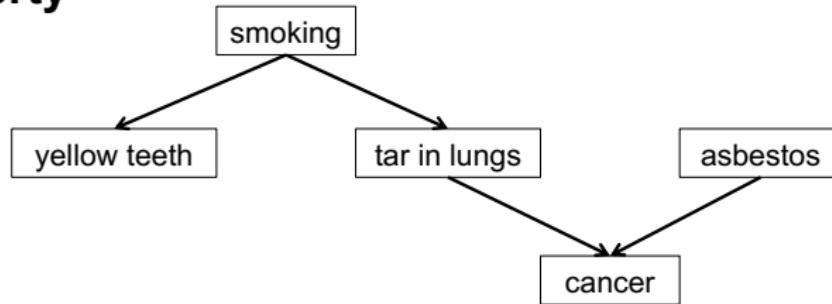
$$X_S \perp\!\!\!\perp X_{\text{nondesc}(S) \setminus \text{pa}(S)} \mid X_{\text{pa}(S)}$$

## Example



- Take  $S = \{\text{yellow teeth}\}$  and apply the local Markov property
- Then:
  - $\text{pa}(\text{yellow teeth}) = \{\text{smoking}\}$
  - $\text{nondesc}(\text{yellow teeth}) = \{\text{smoking, tar, cancer, asbestos}\}$
- Hence,  $\text{yellow teeth} \perp\!\!\! \perp \{\text{tar, cancer, asbestos}\} \mid \text{smoking}$  in any distribution that factorizes according to this DAG

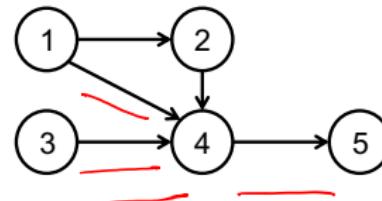
## Markov property



- Is  $\text{tar} \perp\!\!\!\perp \text{asbestos} \mid \text{cancer}$  ?
- The local Markov property cannot be used to read off arbitrary conditional (in)dependencies
  - For this we have d-separation

## Graph terminology

- Need new terminology:
    - A non-endpoint node  $i$  is a **collider on a path** if the path contains  $\rightarrow i \leftarrow$  (arrows collide at  $i$ )
    - Otherwise, it is a **non-collider** on the path
  - Is 4 a collider in the given graph?  $\Leftarrow$  bad question
    - 4 is a collider on the path  $(3, 4, 1)$
    - 4 is a non-collider  $(3, 4, 5)$
- $\Rightarrow$  collider status is always relative to a path!



## d-separation

- A path between  $i$  to  $j$  is **blocked** by a set  $S$  (not containing  $i$  or  $j$ ) if at least one of the following holds:
  - There is a non-collider on the path that is in  $S$ ; or
  - There is a collider on the path such that neither this collider nor any descendants are in  $S$
- A path that is not blocked is **active**
- If all paths between  $i \in A$  and  $j \in B$  are blocked by  $S$ , then  $A$  and  $B$  are **d-separated by  $S$** . Otherwise they are **d-connected given  $S$** .
- Denote d-separation by  $\perp\!\!\!\perp$

## Global Markov property

- **Definition:**

A distribution  $P$  with density  $p$  satisfies the **global Markov property** with respect to a DAG  $G$  if:

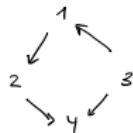
$$\mathbf{A} \text{ and } \mathbf{B} \text{ are d-separated by } \mathbf{S} \text{ in } G \Rightarrow X_{\mathbf{A}} \perp\!\!\!\perp X_{\mathbf{B}} \mid X_{\mathbf{S}} \text{ in } P$$

- **Theorem (Pearl, 1988):**

A distribution  $P$  with density  $p$  satisfies the global Markov property with respect to  $G$  if and only if  $p$  factorizes according to  $G$ .

## Notes week 2 - II

$G:$



A distribution  $P$  is said to satisfy

- \* the **global Markov property** wrt  $G$  if

$$x_2 \perp\!\!\!\perp x_3 \mid x_1$$

and

$$x_1 \perp\!\!\!\perp x_4 \mid x_2, x_3$$

- \* the **Local Markov property** wrt  $G$  if

$$x_2 \perp\!\!\!\perp x_3 \mid x_1$$

$$x_4 \perp\!\!\!\perp x_1 \mid x_2, x_3$$

- \* the **Markov factorization property** wrt  $G$  if

$$p(x_1, x_2, x_3, x_4) = p(x_3) p(x_1 \mid x_3) p(x_2 \mid x_1) p(x_4 \mid x_2, x_3)$$

## Faithfulness

- Given a DAG  $G = (V, E)$ , a distribution  $P$  on  $X_V$  is said to be **faithful** with respect to  $G$  if for all pairwise disjoint subsets  $A, B$  and  $S$  of  $V$ :

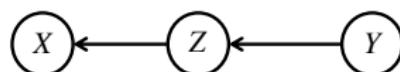
$$X_A \perp\!\!\!\perp X_B | X_S \text{ in } P \Rightarrow A \text{ and } B \text{ are d-separated by } S \text{ in } G$$

## Example



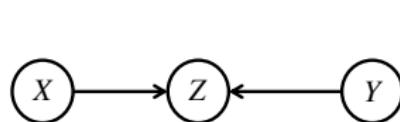
$$X \perp Y|Z$$

e.g. fire  $\rightarrow$  smoke  $\rightarrow$  alarm



$$X \perp Y|Z$$

e.g. shoe size  $\leftarrow$  age of child  $\rightarrow$  reading skills



$$X \not\perp Y|Z$$

e.g. talent  $\rightarrow$  celebrity  $\leftarrow$  beauty

## DAG models

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- DAG models can be used for various purposes:
  - Estimating the joint density from low order conditional densities
  - Reading off conditional independencies from the DAG
  - **Probabilistic reasoning (expert systems)**
  - Causal inference

## Probabilistic reasoning

- Conditional probabilities are rather counterintuitive for many people
- DAGs allow us to obtain conditional probabilities efficiently, using a “message passing” algorithm
  - See R script `02_graphical_models.R`
  - We won’t discuss the details behind these algorithms

# Discussion

Any comments or questions?

We may not always find an answer, and since we're not very familiar with causality, we will need to dedicate more time to this topic.