

Active GNN reading notes

S2: An efficient graph based active learning algorithm with application to nonparametric classification

- Problem setup
 - active learning for binary label prediction on a graph
 - nonparametric active learning, S2 sequentially select vertices to be labeled
 - *cut-set*: $C = \{\{x, y\} \in E : f(x) \neq f(y)\}$
 - *boundary*: $\partial C = \{x \in V : \exists e \in C \text{ with } x \in e\}$ goal is to identify ∂C
 - algorithm assume a noiseless oracle that return label of a multiset of vertices, noisy oracle version algorithms can be transferred from noiseless
 - can be extended to multi-class
- Datasets
 - Digits:
 - Cedar Buffalo binary digits database
 - construct symmetrized 10-nearest-neighbor graph
 - Congressional Voting Records (CVR):
 - 380 vertices, boundary size of 234
 - Grid:
 - synthetic example of a 15x15, positive core in the center
- Methods
 - S2: Shortest Shortest Path

Algorithm 1 S²: Shortest Shortest Path

Input Graph $G = (V, E)$, BUDGET $\leq n$

```
1:  $L \leftarrow \emptyset$ 
2: while 1 do
3:    $x \leftarrow$  Randomly chosen unlabeled vertex
4:   do
5:     Add  $(x, f(x))$  to  $L$ 
6:     Remove from  $G$  all edges whose two ends have different labels.
7:     if  $|L| = \text{BUDGET}$  then
8:       Return LABELCOMPLETION( $G, L$ )
9:     end if
10:  while  $x \leftarrow \text{MSSP}(G, L)$  exists
11: end while
```

- LABELCOMPLETION: Any off-the-shelf graph prediction algorithms

- **MSSP**: return midpoint on the shortest among all the shortest-paths that connect oppositely labeled vertices in L

Sub-routine 2 MSSP

Input Graph $G = (V, E)$, $L \subseteq V$

```

1: for each  $v_i, v_j \in L$  such that  $f(v_i) \neq f(v_j)$  do
2:    $P_{ij} \leftarrow$  shortest path between  $v_i$  and  $v_j$  in  $G$ 
3:    $\ell_{ij} \leftarrow$  length of  $P_{ij}$  ( $\infty$  if no path exists)
4: end for
5:  $(i^*, j^*) \leftarrow \arg \min_{v_i, v_j \in L: f(v_i) \neq f(v_j)} \ell_{ij}$ 
6: if  $(i^*, j^*)$  exists then
7:   Return mid-point of  $P_{i^*j^*}$  (break ties arbitrarily).
8: else
9:   Return  $\emptyset$ 
10: end if

```

- Can be seen as: random sampling + aggressive search
 - aggressive search: like binary search to find the cut-edge, then unzip the cut-edge
- Baselines
 - measure query complexity
 - AFS [On the complexity of finding an unknown cut via vertex queries](#)
 - ZLG [Combining active learning and semi- supervised learning using Gaussian fields and harmonic functions](#)
 - BND [Towards active learning on graphs: An error bound minimization approach](#)

Active Learning for Networked Data

- Problem setup
 - classifying nodes (labels prediction)
 - node features
 - graph structure
 - features/labels of neighbor nodes
 - collective classification:
 - simultaneously predicting labels of all nodes
 - active learning
 - request labels, with goals of decreasing number of labels needed
 - pool-based setting:
 - initially provided with pool of unlabeled examples
 - each step select batch of instances, remove from pool, add to labeled corpus
 - task:
 - collective classification as base learner

- train: active learning learn CC, CO
 - test: ICA + CC
- Methods
 1. cluster nodes based on graph structure: modularity clustering
 2. iterate:
 1. re-train CO, CC
 2. score clusters based on CO/CC disagreement, pick top k clusters
 3. label one of unlabeled node from each of the k clusters, remove them from pool
 - the node with greatest disagreement LD between CO, CC, majority is picked
 4. Semi-supervision and Dimensionality reduction
 1. semi-supervised collective classification method, use CO to predict unobserved neighbor
 2. PCA
 - note:
 - CC: $P(Y_i | X_i, \text{aggr}(N_i))$, consider neighbor labels
 - CO: $P(Y_i | X_i)$ local classifier with only node features
- Datasets
 - [Cora & CiteSeer](#)
 - citation network
 - ignore directions
 - cleaned up
- Baselines
 1. Semi-supervision and Dimensionality Reduction (Base Learner)
 1. CO
 2. CC
 3. CC+Semi-supervision
 4. CC+Semi-supervision+PCA
 2. ALFNET
 1. Random
 2. Uncertainty sampling
 3. Ablation
 1. disagreement: no cluster structure
 2. clustering: select cluster randomly

Active Discriminative Network Representation Learning

- Problem setup

- a network representation learning method under active learning principle
 - pool-based active learning setting, select most informative instance given **query strategy**
 - Then label the selected node, add to labeled set for network representation learning
 - Method
 - AL **Query Strategy**
 - uncertainty measure:
 - **Information Entropy**: prediction from node embedding
 - representativeness measure:
 - **Node centrality**: PageRank centrality
 - **Information density**: K-means on node embedding
 - Active Node Selection
 - Multi-Armed Bandit Method
 - Reward Scheme
 - Active Discriminative Network Representation
 - GCN
 - Datasets
 - Citeseer, Cora, Pubmed
 - sparse BOW feature vector for each document
 - citation links
 - Baselines
 - GCN: randomly select node
 - AGE: linearly combination of AL query strategy
 - ANRMAB-exclude:
 - ANRMAB-entropy
 - ANRMAB-centrality
 - ANRMAB- density
 - Metrics:
 - Macro-F1
 - Micro-F1
-

Towards Active Learning on Graphs: An Error Bound Minimization Approach Quanquan

- Problem setup:
 - adaptive method
 - non-adaptive method: this paper developed

- present data-dependent generalization error bound for LLGC, using transductive Rademacher Complexity
- actively select nodes by minimizing the empirical transductive Rademacher complexity of LLGC on a graph
- present sequential optimization algorithm to select labeled data
- use LLGC as classifier on labeled data
- Method:
 - LLGC:
 - graph-based(semi-supervised) learning method
 - add Graph Regularization
 - Objective function (for selection):
 - expected error on unlabeled \leq empirical error on the labeled data + empirical transductive Rademacher complexity + confidence term
 - non-adaptive, do not know empirical error on the labeled data until label nodes
 - only minimize empirical transductive Rademacher complexity for LLGC
 - Sequential optimization
 - sequentially select nodes to be labeled is to optimize the above objective.

Algorithm 1 Active Learning on Graphs via Generalization Error Bound Minimization (**Bound**)

Input: Adjacency matrix \mathbf{W} , number of nodes to select l , regularization parameter μ ;

Compute $\mathbf{L} = \mathbf{I} - \mathbf{D}^{-\frac{1}{2}} \mathbf{W} \mathbf{D}^{-\frac{1}{2}}$

Perform eigen decomposition $\mathbf{L} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T$

Initialize $\mathbf{H}_0 = \mathbf{\Gamma}^{-1}$, $\mathcal{L}_0 = \emptyset$

for $k = 0 \rightarrow l - 1$ **do**

Compute $i_{k+1} = \arg \max_{i \in \mathcal{V} / \mathcal{L}_k} \frac{\mathbf{u}_i^T \mathbf{H}_k^{-1} \mathbf{\Lambda}^{-1} \mathbf{H}_k^{-1} \mathbf{u}_i}{1 + \mathbf{u}_i^T \mathbf{H}_k^{-1} \mathbf{u}_i}$;

Update $\mathcal{L}_{k+1} = \mathcal{L}_k \cup \{i_{k+1}\}$

Update $\mathbf{H}_{k+1}^{-1} = \mathbf{H}_k^{-1} - \frac{\mathbf{H}_k^{-1} \mathbf{u}_{i_{k+1}} \mathbf{u}_{i_{k+1}}^T \mathbf{H}_k^{-1}}{1 + \mathbf{u}_{i_{k+1}}^T \mathbf{H}_k^{-1} \mathbf{u}_{i_{k+1}}}$

end for

- Learning pipeline:
 - select nodes by active learning
 - train classifier(LLGC) on the graph
- Datasets
 - Cora
 - 2 datasets from DS, PL

- largest connected component is used
 - undirected
 - Coauthor
 - from DBLP
 - author as nodes, weighted edge by papers co-authored
 - Baselines
 - active learning:
 - Random
 - Variance Minimization (VM)
 - METIS
 - Ψ Maximization (Ψ -Max)
 - BOUND: Proposed
 - classifier:
 - LLGC: Proposed
 - GFHF: used in VM
 - MinCut: used in Ψ -Max
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Active Learning on Graphs via Spanning Trees

- Problem setup:
 - node classification, focus on prediction that rely on network topology only
 - homophily bias: linked entities tend to have same class-->clusters
- Method:
 - define:
 - cutsize $\Phi(y)$: number of edges connecting nodes with different labels
 - function $\Psi^*(L)$: small value correspond to good choice of training nodes L that satisfy homophily
 - Together bound from above the number of mistakes on non-training nodes
 - approach:
 - use SEL to minimize Ψ^* on a spanning tree of graph
 - label propagation on entire graph, yields a fast classifier that is better than random selection
- Datasets
 - RCV1 corpus
 - build weighted graph using k-NN
 - DBLP network
 - CORA network

- Baselines
 - Spanning trees generation:
 - RST(Random)
 - BFST(Breadth-first)
 - random selection
 - high-degree
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Bayesian Semi-supervised Learning with Graph Gaussian Processes

- Problem setup:
 - graph-based semi-supervised learning: relational graph of data points is available
 - propose **Gaussian process model, scalable variational** inducing approximation method to perform **inference**
 - review:
 - Gaussian Process
 - **priors** on functions in Bayesian Inference
 - Scalable Variational Inference for GP
 - Graph Laplacian

- $$\mathbf{L} = \mathbf{D} - \mathbf{A}$$

- Graph Laplacian can be viewed as operator on space of functions $g : V \rightarrow \mathbb{R}$

$$\mathbf{L}(g) = \sum_{v \in Ne(n)} [g(n) - g(v)]$$

- Method
 - Graph Gaussian Process
 - Variational Inference with Inducing Points
 - Active learning:
 - GGP as classification model paired with **Σ - optimal (SOPT)** to form active learner, select + retrain classifier for 50 times
- Datasets
 - Cora, Citeseer, Pubmed
- Baselines
 - semi-supervised settings
 - GCN, MoNet, DCNN, DeepWalk, Planetoid, ICA, LP, SemiEmb, ManiReg
 - Active learning setting:

- SOPT+GCN/LP
- RAND+GGP/GCN/LP

Batch Mode Active Learning for Networked Data

- Problem setup
 - Batch mode active learning
 - query k labels of instances S to improve quality of learned classification model
 - define an objective function for active selection Q
 - design efficient algorithms to maximize $Q(S)$
 - selection combine both context and link information
 - present objective function based on maximum uncertainty, maximum impact, and minimum redundancy
 - Underlying model: Framework of Random Walk
- Method
 - Objective function $Q(S)$: combine maximum uncertainty and the maximum impact, naturally satisfy minimum redundancy
 - Use Framework of Random Walk as classification model
 - Combining **Link Information**: integrate link information into **similarity matrix**, extend similarity measure with **Pagerank**
 - Optimization: Greedy selection, monotonic submodular, have good error bound

ALGORITHM 1: Greedy algorithm for batch mode active selection. The algorithm iteratively selects a sample that can maximize $Q(S)$

Input: $U, L, G, \mathbf{x}, \mathbf{y}, k$

Output: S , s.t. $|S| = k$

Calculate transition matrix P ;

Calculate probability vector \mathbf{p} ;

for $v \in U$ **do**

$H[v] \leftarrow p_v \log \frac{1}{p_v} + (1 - p_v) \log \frac{1}{1 - p_v}$;

initialize: $C[v] \leftarrow 0, \max[v] \leftarrow 0$;

end

initialize: $S \leftarrow \emptyset$;

while $|S| < k$ **do**

for $v \in U - S$ **do**

$C[v] \leftarrow$ The summation over $j \in U$;
 of $(H[j])^\beta (\max\{\max[j], w(v, j)\}^{1-\beta})$;

end

 Find $v \in U - S$ to maximize:

$\alpha C[v] + (1 - \alpha) H[v]$;

update: $S \leftarrow S \cup \{v\}$;

update: $\max[j] \leftarrow \max\{\max[j], w(v, j)\}$;

end

- Speed up with parallel algorithm
 - Datasets
 - Gaussian Synthetic Dataset
 - random generated, 17 Gaussian distributions
 - no link information
 - use KNN to learn classification model
 - The Networked Synthetic Dataset
 - without content information
 - Real world with links:
 - Cora, Citeseer, WebKB
 - cast as multiple binary
 - Real World without Links:
 - UCI 20 Newsgroup classification tasks
 - Baselines
 - Real world with links
 - Random
 - Most Uncertainty: largest entropy
 - Active Learning Using Gaussian Fields
 - Hybrid
 - k-means
 - Real world without links
 - Random
 - Most Uncertainty: largest entropy
 - Active Learning Using Gaussian Fields
 - SVM
 - Fisher
 - On Gaussian Synthetic Dataset:
 - Maximum Uncertainty
 - Without Maximum Uncertainty
 - Without Minimum Redundancy
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FEW-SHOT LEARNING ON GRAPHS VIA SUPER- CLASSES BASED ON GRAPH SPECTRAL MEASURES

- Problem setup:
 - few-shot setting:

- training: classifier must generalize well after seeing abundant base-class samples
 - testing: very few samples from novel class
- Details
 - training: set of *base class* labeled graphs $G_B = \{(g_i^{(B)}, y_i^{(B)})\}_{i=1}^n$, set of *novel class* labeled graphs $G_N = \{(g_i^{(N)}, y_i^{(N)})\}_{i=1}^m$ used for fine-tuning, where $m \ll n$, set of labels from base class graphs and novel class graphs are disjoint.
 - testing: set of unlabeled unseen graphs $G_U = \{g_i^{(U)}\}_{i=1}^t$
- Method:
 - Computing super classes
 - Prototype Graphs:
 - partitioned G_B according to graph labels, $G_B = \cup_{i=1}^K G^{(i)}$
 - pick prototype graph p_i for the i-th class with least average spectral distance to rest graphs in the same class
 - Clustering prototype graphs:
 - k -means
 - into k super classes
 - GNN
 - GIN as graph feature extractor
 - Classifier
 - build super-graph:
 - node is graph feature vector
 - build on a batch of *base-labeled* graphs as a collection of k-NN graphs
 - each constituent k-NN graph is built on the graphs belonging to the same super-class
 - super graph passed through multi-layered graph attention network GAT
 - graph embedding passed into MLP to learn associated super-class labels
 - add cross-entropy losses associated with GAT and MLP
 - fine-tune:
 - fix GIN, MLP, tune GAT
- Datasets:
 - Letter-High, TRIANGLES, Reddit-12K, and ENZYMES.
- Baselines:
 - k-NN search on embeddings
 - Supervised:
 - GIN, CapsGNN, Diffpool
 - Unsupervised:
 - AWE, Graph2Vec, Weisfeiler- Lehman subtree Kernel, Graphlet count kernel
 - Few-shot:
 - replace GAT with GCN

- replace classifier with k-NN: GIN-k-NN
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