# Alternating-direction-method of Multipliers-Based Adaptive Nonnegative Latent Factor Analysis: Supplementary Materials

Yurong Zhong, Kechen Liu, Shangce Gao, Senior Member, IEEE, and Xin Luo, Senior Member, IEEE

This is the supplementary file for the paper entitled *Alternating-direction-method of Multipliers-Based Adaptive Nonnegative Latent Factor Analysis*. Detailed convergence proof of  $A^2NLF$  and additional figures are presented here.

# I. CONVERGENCE OF A<sup>2</sup>NLF

# A. Proof of Lemma 1

Note that learning objective of A<sup>2</sup>NLF-PSO/A<sup>2</sup>NLF-TPE is non-convex. According to [48], any of its limit points where the gradient becomes zero can be a local/global optimum, or saddle point. Hence, such a limit point can be treated as a solution. Supposing that the optimal solution to  $a_{u,k(q)}$  by (4c) is  $a'_{u,k(q)}$ . Thus, it fulfills the following condition:

$$\lambda_{(q)}^{t} \left| \Lambda(u) \right| \left( p_{u,k(q)}^{t} - a_{u,k(q)}^{t} + \frac{h_{u,k(q)}^{t-1}}{\lambda_{(q)}^{t} \left| \Lambda(u) \right|} \right) = 0.$$
 (S1)

Following (4e) and (5c), by applying the update rule of  $h_{u,k(q)}$  to (S1), we have:

$$h'_{u,k(q)} = \left(\eta'_{(q)} - 1\right) \lambda'_{(q)} \left| \Lambda(u) \right| \left(p'_{u,k(q)} - a'_{u,k(q)}\right). \tag{S2}$$

Then (22a) stands based on (S2). Following the same principle, we can derive the optimality condition of (5b) related to  $x_{i,k(a)}$ :

$$\lambda_{(q)}^{t} \left| \Lambda(i) \right| \left( z_{i,k(q)}^{t} - x_{i,k(q)}^{t} + \frac{w_{i,k(q)}^{t-1}}{\lambda_{(q)}^{t} \left| \Lambda(i) \right|} \right) = 0, \implies w_{i,k(q)}^{t} = \left( \eta_{(q)}^{t} - 1 \right) \lambda_{(q)}^{t} \left| \Lambda(i) \right| \left( z_{i,k(q)}^{t} - x_{i,k(q)}^{t} \right). \tag{S3}$$

Then (22b) holds based on (S3). Hence, *Lemma* 1 holds, and **Step 1** is implemented. □

## B. Proof of Lemma 2

Considering the difference between  $g\left(p_{u,k(q)}^{t}, z_{i,k(q)}^{t}, a_{u,k(q)}^{t-1}, x_{i,k(q)}^{t-1}, \psi_{2(q)}^{t-1}\right)$  and  $g\left(\psi_{1(q)}^{t-1}, \psi_{2(q)}^{t-1}\right)$ , we have:

$$g\left(p_{u,k(q)}^{t}, z_{i,k(q)}^{t}, a_{u,k(q)}^{t-1}, x_{i,k(q)}^{t-1}, y_{2(q)}^{t-1}\right) - g\left(y_{1(q)}^{t-1}, y_{2(q)}^{t-1}\right)$$

$$= \left(\sum_{i \in \Lambda(u)} z_{i,k(q)}^{t-1} \left(y_{u,i} - \sum_{l_{i}=1}^{k-1} p_{u,l_{i}(q)}^{t} z_{i,k(q)}^{t} - p_{u,k(q)}^{t} z_{i,k(q)}^{t-1} - \sum_{l_{2}=k+1}^{d} p_{u,l_{2}(q)}^{t-1} z_{i,l_{2}(q)}^{t-1}\right) - \lambda_{(q)}^{t} \left|\Lambda(u)\right| \left(p_{u,k(q)}^{t} - a_{u,k(q)}^{t-1} + \frac{h_{u,k(q)}^{t-1}}{\lambda_{(q)}^{t}} \left|\Lambda(u)\right|\right) \left(p_{u,k(q)}^{t-1} - p_{u,k(q)}^{t}\right) + \left(\sum_{u \in \Lambda(i)} p_{u,k(q)}^{t-1} \left(y_{u,i} - \sum_{l_{i}=1}^{k-1} p_{u,l_{i}(q)}^{t} z_{i,k(q)}^{t} - p_{u,k(q)}^{t-1} z_{i,k(q)}^{t} - \sum_{l_{2}=k+1}^{d} p_{u,l_{2}(q)}^{t-1} z_{i,l_{2}(q)}^{t-1}\right) - \lambda_{(q)}^{t} \left|\Lambda(i)\right| \left(z_{i,k(q)}^{t} - x_{i,k(q)}^{t-1} + \frac{w_{i,k(q)}^{t-1}}{\lambda_{(q)}^{t}} \left|\Lambda(i)\right|\right) \left(z_{i,k(q)}^{t-1} - z_{i,k(q)}^{t}\right) - \frac{1}{2} \left(\sum_{u \in \Lambda(i)} \left(\sum_{i \in \Lambda(u)} \left(z_{i,k(q)}^{t-1} - z_{i,k(q)}^{t-1}\right) + \lambda_{(q)}^{t} \left|\Lambda(i)\right|\right) \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(i)\right|\right) \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2}.$$

where (\*) performs the second-order Taylor expansion of the left term. Then, considering (5a)'s optimality condition, (S4) is

transformed as:

$$g\left(p_{u,k(q)}^{t}, z_{i,k(q)}^{t}, a_{u,k(q)}^{t-1}, x_{i,k(q)}^{t-1}, \psi_{2(q)}^{t-1}\right) - g\left(\psi_{1(q)}^{t-1}, \psi_{2(q)}^{t-1}\right)$$

$$= -\frac{1}{2} \left(\sum_{i \in \Lambda(u)} \left(z_{i,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda\left(u\right)\right|\right) \left(p_{u,k(q)}^{t} - p_{u,k(q)}^{t-1}\right)^{2} - \frac{1}{2} \left(\sum_{u \in \Lambda(i)} \left(p_{u,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda\left(i\right)\right|\right) \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2}.$$
(S5)

Thus, the difference between  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right)$  and  $g\left(p_{u,k(q)}^{t},z_{i,k(q)}^{t},a_{u,k(q)}^{t-1},x_{i,k(q)}^{t-1},\psi_{2(q)}^{t-1}\right)$  is:

$$g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right) - g\left(p_{u,k(q)}^{t},z_{i,k(q)}^{t},a_{u,k(q)}^{t-1},x_{i,k(q)}^{t-1},\psi_{2(q)}^{t-1}\right) = -\left(\lambda_{(q)}^{t}\left|\Lambda(u)\right|/2\right)\left(a_{u,k(q)}^{t}-a_{u,k(q)}^{t-1}\right)^{2} - \left(\lambda_{(q)}^{t}\left|\Lambda(i)\right|/2\right)\left(x_{i,k(q)}^{t}-x_{i,k(q)}^{t-1}\right)^{2}. \tag{S6}$$

Moreover,  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t}\right)$  and  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right)$  yields:

$$\begin{split} g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t}\right) - g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t-1}\right) \\ &= \left(p_{u,k(q)}^{t} - a_{u,k(q)}^{t}\right) \left(h_{u,k(q)}^{t} - h_{u,k(q)}^{t-1}\right) + \left(z_{i,k(q)}^{t} - x_{i,k(q)}^{t}\right) \left(w_{i,k(q)}^{t} - w_{i,k(q)}^{t-1}\right) \\ &= \frac{1}{\eta_{(q)}^{t} \lambda_{(q)}^{t} \left|\Lambda\left(u\right)\right|} \left(h_{u,k(q)}^{t} - h_{u,k(q)}^{t-1}\right)^{2} + \frac{1}{\eta_{(q)}^{t} \lambda_{(q)}^{t} \left|\Lambda\left(i\right)\right|} \left(w_{i,k(q)}^{t} - w_{i,k(q)}^{t-1}\right)^{2} \\ &\leq \frac{2\left|\Lambda\left(u\right)\right|}{\eta_{(q)}^{t} \lambda_{(q)}^{t}} \left(\left(\left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} p_{u,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} p_{u,k(q)}^{t-1}\right)^{2} + \left(\left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} a_{u,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} a_{u,k(q)}^{t-1}\right)^{2} \right) \\ &+ \frac{2\left|\Lambda\left(i\right)\right|}{\eta_{(q)}^{t} \lambda_{(q)}^{t}} \left(\left(\left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} x_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} x_{i,k(q)}^{t-1}\right)^{2} \right), \end{split}$$

where (I) is based on the update rules of  $(h_{u,k(q)}, w_{i,k(q)})$  given in (4e), (4f) and (5c), and (II) is achieved with *Lemma* 1. With (S5)-(S7), we have the following deduction:

$$g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t}\right) - g\left(\psi_{1(q)}^{t-1}, \psi_{2(q)}^{t-1}\right)$$

$$\leq -\frac{1}{2} \left(\sum_{i \in \Lambda(u)} \left(z_{i,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(u)\right| \right) \left(p_{u,k(q)}^{t} - p_{u,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t}}{2} \left|\Lambda(u)\right| \left(a_{u,k(q)}^{t} - a_{u,k(q)}^{t-1}\right)^{2}$$

$$-\frac{1}{2} \left(\sum_{u \in \Lambda(u)} \left(p_{u,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(i)\right| \right) \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t}}{2} \left|\Lambda(i)\right| \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t}}{2} \left|\Lambda(i)\right| \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} a_{u,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} a_{u,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} a_{u,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} a_{u,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} x_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} x_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} x_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} x_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} x_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} x_{i,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t}}{2} \left|\Lambda(u)\right| \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t-1} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t-1} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t-1} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t-1} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t-1} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} z_{i,k(q)}^{t-1} - \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}$$

Owing to (24a), (25a) stands, which indicates that the augmented Lagrangian function (3) related to  $s_{(q)}$  or  $\tau_q$  is non-increasing as  $a'_{u,k(q)} > 0$  and  $x'_{i,k(q)} > 0$ . Then after the *t*-th iteration, the partial objective from (3) related to  $s_{(q)}$  or  $\tau_q$  is formulated as:

$$\begin{split} &g\left(\boldsymbol{\psi}_{1(q)}^{t},\boldsymbol{\psi}_{2(q)}^{t}\right) \\ &= \frac{1}{2} \sum_{\boldsymbol{y}_{u,i} \in \Lambda} \left(\boldsymbol{y}_{u,i} - \sum_{l_{1}=1}^{k} \boldsymbol{p}_{u,l_{1}(q)}^{t} \boldsymbol{z}_{i,l_{1}(q)}^{t} - \sum_{l_{2}=k+1}^{d} \boldsymbol{p}_{u,l_{2}(q)}^{t-1} \boldsymbol{z}_{i,l_{2}(q)}^{t-1}\right)^{2} \\ &+ \sum_{u} \left(\left(\sum_{l_{1}=1}^{k} \boldsymbol{h}_{u,l_{1}(q)}^{t} \left(\boldsymbol{p}_{u,l_{1}(q)}^{t} - \boldsymbol{a}_{u,l_{1}(q)}^{t}\right)\right) + \left(\sum_{l_{2}=k+1}^{d} \boldsymbol{h}_{u,l_{2}(q)}^{t-1} \left(\boldsymbol{p}_{u,l_{2}(q)}^{t-1} - \boldsymbol{a}_{u,l_{2}(q)}^{t-1}\right)\right)\right) + \sum_{i} \left(\left(\sum_{l_{1}=1}^{k} \boldsymbol{w}_{i,l_{1}(q)}^{t} \left(\boldsymbol{z}_{i,l_{1}(q)}^{t} - \boldsymbol{x}_{i,l_{1}(q)}^{t}\right)\right)\right) + \left(\sum_{l_{2}=k+1}^{d} \boldsymbol{w}_{i,l_{2}(q)}^{t-1} \left(\boldsymbol{z}_{i,l_{2}(q)}^{t-1} - \boldsymbol{x}_{i,l_{2}(q)}^{t-1}\right)\right)\right) \\ &+ \sum_{u} \frac{\lambda_{(q)}^{t} \left|\Lambda\left(\boldsymbol{u}\right)\right|}{2} \left(\sum_{l_{1}=1}^{k} \left(\boldsymbol{p}_{u,l_{1}(q)}^{t} - \boldsymbol{a}_{u,l_{1}(q)}^{t}\right)^{2} + \sum_{l_{2}=k+1}^{d} \left(\boldsymbol{p}_{u,l_{2}(q)}^{t-1} - \boldsymbol{a}_{u,l_{2}(q)}^{t-1}\right)^{2}\right) + \sum_{i} \frac{\lambda_{(q)}^{t} \left|\Lambda\left(\boldsymbol{i}\right)\right|}{2} \left(\sum_{l_{1}=1}^{k} \left(\boldsymbol{z}_{i,l_{1}(q)}^{t} - \boldsymbol{x}_{i,l_{1}(q)}^{t}\right)^{2} + \sum_{l_{2}=k+1}^{d} \left(\boldsymbol{z}_{i,l_{2}(q)}^{t-1} - \boldsymbol{x}_{i,l_{2}(q)}^{t-1}\right)^{2}\right). \end{split}$$

By substituting (S2) and (S3) into (S9), we have:

$$g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t}\right)$$

$$= \frac{1}{2} \sum_{y_{u,i} \in \Lambda} \left(y_{u,i} - \sum_{l_{i}=1}^{k} p_{u,l_{1}(q)}^{t} z_{i,l_{i}(q)}^{t} - \sum_{l_{2}=k+1}^{d} p_{u,l_{2}(q)}^{t-1} z_{i,l_{2}(q)}^{t-1}\right)^{2}$$

$$+ \sum_{u} \left|\Lambda\left(u\right)\right| \left(\left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} \sum_{l_{i}=1}^{k} \left(p_{u,l_{1}(q)}^{t} - a_{u,l_{1}(q)}^{t}\right)^{2} + \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} \sum_{l_{2}=k+1}^{d} \left(p_{u,l_{2}(q)}^{t-1} - a_{u,l_{2}(q)}^{t-1}\right)^{2}\right)$$

$$+ \sum_{i} \left|\Lambda\left(i\right)\right| \left(\left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} \sum_{l_{i}=1}^{k} \left(z_{i,l_{1}(q)}^{t} - x_{i,l_{1}(q)}^{t}\right)^{2} + \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} \sum_{l_{2}=k+1}^{d} w_{i,l_{2}(q)}^{t} \left(z_{i,l_{2}(q)}^{t-1} - x_{i,l_{2}(q)}^{t-1}\right)^{2}\right)$$

$$+ \sum_{u} \frac{\lambda_{(q)}^{t} \left|\Lambda\left(u\right)\right|}{2} \left(\sum_{l_{i}=1}^{k} \left(p_{u,l_{1}(q)}^{t} - a_{u,l_{1}(q)}^{t}\right)^{2} + \sum_{l_{i}=k+1}^{d} \left(p_{u,l_{2}(q)}^{t-1} - a_{u,l_{2}(q)}^{t-1}\right)^{2}\right) + \sum_{i} \frac{\lambda_{(q)}^{t} \left|\Lambda\left(i\right)\right|}{2} \left(\sum_{l_{i}=1}^{k} \left(z_{i,l_{1}(q)}^{t} - x_{i,l_{2}(q)}^{t-1}\right)^{2}\right).$$
(S10)

(S10) indicates that if (24b) is fulfilled, (25b) holds, thereby making (3) related to  $s_{(q)}$  or  $\tau_q$  lower-bounded as  $a'_{u,k(q)} > 0$  and  $x'_{i,k(q)} > 0$ . Based on the above inferences, *Lemma* 2 stands, and **Step 2** is implemented.

#### C. Proof of Theorem 1

**Part a.** Following Lemma 2,  $g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t}\right)$  converges as  $t \to \infty$ , indicating that:

$$\lim_{t \to \infty} g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t}\right) - g\left(\psi_{1(q)}^{t-1}, \psi_{2(q)}^{t-1}\right) \to 0.$$
(S11)

With (24), when (S1) is fulfilled, the upper-bound of  $g\left(\psi_{1(q)}',\psi_{2(q)}'\right) - g\left(\psi_{1(q)}',\psi_{2(q)}'\right)$  is zero as  $t \to \infty$ , thereby achieving (26). Following (S8) and (26), we have [24]:

$$\lim_{t \to \infty} \left( p'_{u,k(q)} - p'^{-1}_{u,k(q)} \right) \to 0, \tag{S12a}$$

$$\lim_{t \to \infty} \left( z_{i,k(q)}^t - z_{i,k(q)}^{t-1} \right) \to 0, \tag{S12b}$$

$$\lim_{t \to \infty} \left( a_{u,k(q)}^t - a_{u,k(q)}^{t-1} \right) \to 0, \tag{S12c}$$

$$\lim_{t \to \infty} \left( x_{i,k(q)}^t - x_{i,k(q)}^{t-1} \right) \to 0, \tag{S12d}$$

$$\lim_{t \to \infty} \left( \left( \left( \eta_{(q)}^{t} - 1 \right) \lambda_{(q)}^{t} p_{u,k(q)}^{t} - \left( \eta_{(q)}^{t-1} - 1 \right) \lambda_{(q)}^{t-1} p_{u,k(q)}^{t-1} \right)^{2} + \left( \left( \eta_{(q)}^{t} - 1 \right) \lambda_{(q)}^{t} a_{u,k(q)}^{t} - \left( \eta_{(q)}^{t-1} - 1 \right) \lambda_{(q)}^{t-1} a_{u,k(q)}^{t-1} \right)^{2} \right) \to 0, \tag{S12e}$$

$$\lim_{t \to \infty} \left( \left( \left( \eta_{(q)}^{t} - 1 \right) \lambda_{(q)}^{t} z_{i,k(q)}^{t} - \left( \eta_{(q)}^{t-1} - 1 \right) \lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1} \right)^{2} + \left( \left( \eta_{(q)}^{t} - 1 \right) \lambda_{(q)}^{t} x_{i,k(q)}^{t} - \left( \eta_{(q)}^{t-1} - 1 \right) \lambda_{(q)}^{t-1} x_{i,k(q)}^{t-1} \right)^{2} \right) \to 0.$$
 (S12f)

Based on (22) and (S12), we have the following inferences:

$$\lim_{t \to \infty} \left( h'_{u,k(q)} - h'^{-1}_{u,k(q)} \right) \to 0, \tag{S13a}$$

$$\lim_{t \to \infty} \left( w_{i,k(q)}^t - w_{i,k(q)}^{t-1} \right) \to 0. \tag{S13b}$$

Based on (4e), (4f) and (S13), we conclude that (27) is fulfilled.

**Part b.** Firstly, following (4a), (4b) and (5a), the update rules of  $(p_{u,k(q)}, z_{i,k(q)})$  can be rearranged as:

$$\left(p_{u,k(q)}^{t-1} - p_{u,k(q)}^{t}\right) \left(\sum_{i \in \Lambda(u)} \left(z_{i,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(u)\right|\right) \\
= \sum_{i \in \Lambda(u)} z_{i,k(q)}^{t-1} \left(\sum_{l_{1}=1}^{k} p_{u,l_{1}(q)}^{t} z_{i,l_{1}(q)}^{t} + \sum_{l_{2}=k+1}^{d} p_{u,l_{2}(q)}^{t-1} z_{i,l_{2}(q)}^{t-1} - y_{u,i}\right) + \lambda_{(q)}^{t} \left|\Lambda(u)\right| \left(p_{u,k(q)}^{t-1} - a_{u,k(q)}^{t-1}\right) + h_{u,k(q)}^{t-1},$$
(S14a)

$$\left(z_{i,k(q)}^{t-1} - z_{i,k(q)}^{t}\right) \left(\sum_{u \in \Lambda(i)} \left(p_{i,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(i)\right|\right) \\
= \sum_{u \in \Lambda(i)} p_{u,k(q)}^{t-1} \left(\sum_{l_{1}=1}^{k} p_{u,l_{1}(q)}^{t} z_{i,l_{1}(q)}^{t} + \sum_{l_{2}=k+1}^{d} p_{u,l_{2}(q)}^{t-1} z_{i,l_{2}(q)}^{t-1} - y_{u,i}\right) + \lambda_{(q)}^{t} \left|\Lambda(i)\right| \left(z_{i,k(q)}^{t-1} - x_{i,k(q)}^{t-1}\right) + w_{i,k(q)}^{t-1}.$$
(S14b)

Then by substituting (27) and (S12) into (S14), we have:

$$\sum_{i \in \Lambda(u)} z_{i,k(q)}^{t-1} \left( \sum_{l_i=1}^k p_{u,l_i(q)}^t z_{i,l_i(q)}^t + \sum_{l_2=k+1}^d p_{u,l_2(q)}^{t-1} z_{i,l_2(q)}^{t-1} - y_{u,i} \right) + h_{u,k(q)}^{t-1} \to 0,$$
(S15a)

$$\sum_{u \in \Lambda(i)} p_{u,k(q)}^{t-1} \left( \sum_{l_i=1}^k p_{u,l_1(q)}^t z_{i,l_1(q)}^t + \sum_{l_2=k+1}^d p_{u,l_2(q)}^{t-1} z_{i,l_2(q)}^{t-1} - y_{u,i} \right) + w_{i,k(q)}^{t-1} \to 0.$$
 (S15b)

Hence, considering a limit point  $\{\psi_{1(q)}^*, \psi_{2(q)}^*\}$  of a sequence  $\{\psi_{1(q)}^t, \psi_{2(q)}^t\}$  generated by the update rules of  $\{\psi_{1(q)}, \psi_{2(q)}\}$  based on (4) and (5), the following KKT conditions are satisfied with (27) and (S15):

$$\sum_{i \in \Lambda(u)} z_{i,k(q)}^* \left( \sum_{k=1}^d p_{u,k(q)}^* z_{i,k(q)}^* - y_{u,i} \right) + h_{u,k(q)}^* \to 0,$$
 (S16a)

$$\sum_{u \in \Lambda(i)} p_{u,k(q)}^* \left( \sum_{k=1}^d p_{u,k(q)}^* z_{i,k(q)}^* - y_{u,i} \right) + w_{i,k(q)}^* \to 0,$$
 (S16b)

$$p_{u,k}^* - a_{u,k}^* \to 0,$$
 (S16c)

$$z_{i,k}^* - x_{i,k}^* \to 0.$$
 (S16d)

Afterwards, considering the remaining KKT conditions regarding constraints  $a_{u,k(q)}>0$  and  $x_{i,k(q)}>0$ , we extend the original augmented Lagrangian g:

$$g_{(q)}^{\#} = g_{(q)} - Tr\left(M_{(q)}\left(A_{(q)}\right)^{T}\right) - Tr\left(N_{(q)}\left(X_{(q)}\right)^{T}\right) = g_{(q)} - \sum_{(u,k)} m_{u,k(q)} a_{u,k(q)} - \sum_{(i,k)} n_{i,k(q)} x_{i,k(q)},$$
(S17)

where the operator  $Tr(\cdot)$  computes the trace of an enclosed matrix, and the definition of g(q) is given by:

$$g_{(q)} = \frac{1}{2} \sum_{y_{u,i} \in \Lambda} \left( y_{u,i} - \sum_{k=1}^{d} p_{u,k(q)} z_{i,k(q)} \right)^{2} + \sum_{(u,k)} h_{u,k(q)} \left( p_{u,k(q)} - a_{u,k(q)} \right) + \sum_{(u,k)} \frac{\lambda_{(q)} \left| \Lambda(u) \right|}{2} \left( p_{u,k(q)} - a_{u,k(q)} \right)^{2} + \sum_{(i,k)} w_{i,k(q)} \left( z_{i,k(q)} - x_{i,k(q)} \right) + \sum_{(i,k)} \frac{\lambda_{(q)} \left| \Lambda(i) \right|}{2} \left( z_{i,k(q)} - x_{i,k(q)} \right)^{2}.$$
(S18)

For the partial derivatives of  $g_{(q)}^{\#}$  with  $a_{u,k(q)}$  and  $x_{i,k(q)}$ , we have:

$$\begin{cases} \frac{\partial g_{(q)}^{\#}}{\partial a_{u,k}} = -\lambda_{(q)} \left| \Lambda(u) \right| \left( p_{u,k(q)} - a_{u,k(q)} + \frac{h_{u,k(q)}}{\lambda_{(q)} \left| \Lambda(u) \right|} \right) - m_{u,k(q)} = 0, \\ \frac{\partial g_{(q)}^{\#}}{\partial x_{i,k}} = -\lambda_{(q)} \left| \Lambda(i) \right| \left( z_{i,k(q)} - x_{i,k(q)} + \frac{w_{i,k(q)}}{\lambda_{(q)} \left| \Lambda(i) \right|} \right) - n_{i,k(q)} = 0, \end{cases} \Rightarrow \begin{cases} m_{u,k} = -\lambda_{(q)} \left| \Lambda(u) \right| \left( p_{u,k(q)} - a_{u,k(q)} + \frac{h_{u,k(q)}}{\lambda_{(q)} \left| \Lambda(u) \right|} \right), \\ m_{i,k} = -\lambda_{(q)} \left| \Lambda(i) \right| \left( z_{i,k(q)} - x_{i,k(q)} + \frac{w_{i,k(q)}}{\lambda_{(q)} \left| \Lambda(i) \right|} \right). \end{cases}$$

$$(S19)$$

Then, with the KKT conditions of  $\forall m_{u,k(q)}$ ,  $a_{u,k(q)}$ :  $m_{u,k(q)}a_{u,k(q)}=0$  and  $\forall n_{i,k(q)}$ ,  $x_{i,k(q)}$ :  $n_{i,k(q)}x_{i,k(q)}=0$  for (S17), we achieve the following equations based on (S19) [19, 21, 24, 39]:

$$\begin{cases} a_{u,k(q)} \left( -\lambda_{(q)} \left| \Lambda(u) \right| \left( p_{u,k(q)} - a_{u,k(q)} + \frac{h_{u,k(q)}}{\lambda_{(q)} \left| \Lambda(u) \right|} \right) \right) = 0, \\ x_{i,k(q)} \left( -\lambda_{(q)} \left| \Lambda(i) \right| \left( z_{i,k(q)} - x_{i,k(q)} + \frac{w_{i,k(q)}}{\lambda_{(q)} \left| \Lambda(i) \right|} \right) \right) = 0, \end{cases} \Rightarrow \begin{cases} a_{u,k(q)} = p_{u,k(q)} + \frac{h_{u,k(q)}}{\lambda_{(q)} \left| \Lambda(u) \right|}, \\ x_{i,k(q)} = z_{i,k(q)} + \frac{w_{i,k(q)}}{\lambda_{(q)} \left| \Lambda(i) \right|}. \end{cases}$$
(S20)

To satisfy the nonnegativity of output LFs  $a_{u,k(q)}$  and  $x_{i,k(q)}$ , (S20) can be rewritten as:

$$\begin{cases} a_{u,k(q)} = \max\left(0, p_{u,k(q)} + \frac{h_{u,k(q)}}{\lambda_{(q)} \left| \Lambda(u) \right|} \right), \\ x_{i,k(q)} = \max\left(0, z_{i,k(q)} + \frac{w_{i,k(q)}}{\lambda_{(q)} \left| \Lambda(i) \right|} \right). \end{cases}$$
(S21)

Note that (S21) is consistent with the update rules of  $a_{u,k(q)}$  and  $x_{i,k(q)}$  based on (4c) and (4d). Therefore, (S17)-(S21) show that learning rules of A<sup>2</sup>NLF-PSO/A<sup>2</sup>NLF-TPE are closely connected with the KKT conditions of its learning objective.

Then considering the KKT conditions related to  $a_{u,k(q)}$ :

$$\frac{\partial g_{(q)}^{\#}}{\partial a_{u,k(q)}}\Big|_{a_{u,k(q)}=a_{u,k(q)}^{*}=a_{u,k(q)}^{*}} = -\lambda_{(q)}^{*} \left| \Lambda(u) \right| \left( p_{u,k(q)}^{*} - a_{u,k(q)}^{*} + \frac{h_{u,k(q)}^{*}}{\lambda_{(q)}^{*} \left| \Lambda(u) \right|} \right) - m_{u,k(q)}^{*} = 0, \tag{S22a}$$

$$m_{u,k(q)}^* a_{u,k(q)}^* = 0,$$
 (S22b)

$$a_{u,k(q)}^* \ge 0, \tag{S22c}$$

$$m_{u,k(q)}^* \ge 0, \tag{S22d}$$

where  $a_{u,k(q)}^*$  is a KKT stationary point of  $a_{u,k(q)}$ , and  $m_{u,k(q)}^*$  is a limit point of the sequence  $\{m_{u,k(q)}^i\}$  generated by the update rules of  $m_{u,k}$  based on (S19). According to (S17)-(S21) and  $a_{u,k(q)}^i$ =0, conditions (S22a)-(S22c) are satisfied. Thus, we have:

$$m_{u,k(q)}^* = -\lambda_{(q)}^* \left| \Lambda(u) \right| \left( p_{u,k(q)}^* - a_{u,k(q)}^* + \frac{h_{u,k(q)}^*}{\lambda_{(q)}^* \left| \Lambda(u) \right|} \right). \tag{S23}$$

Thus, we focus on condition (S22d). Since  $a_{u,k(q)}^{t} > 0$  in this case, the update rule for  $a_{u,k(q)}$  is given as:

$$a_{u,k(q)}^* \leftarrow p_{u,k(q)}^* + \frac{h_{u,k(q)}^*}{\lambda_{(a)}^* |\Lambda(u)|}.$$
 (S24)

By substituting (S24) into (S23), we have  $m_{u,k(q)}^*=0$ . Hence, conditions (S22c) and (S22d) are fulfilled. Note that as  $x'_{i,k(q)}>0$  in this case, the proof regarding the KKT conditions of  $x_{u,k(q)}$  can be achieved similarly. *Theorem* 1 stands, and **Step 3** is implemented.  $\Box$ 

### D. Proof of Lemma 3

The difference between  $g\left(p_{u,k(q)}^{t},z_{i,k(q)}^{t},a_{u,k(q)}^{t-1},x_{i,k(q)}^{t-1},\psi_{2(q)}^{t-1}\right)$  and  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right)$  in this case is also given by (S5). Considering the fact of  $a_{u,k(q)}^{t}=0$  and,  $x_{i,k(q)}^{t}>0$  the difference between  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right)$  and  $g\left(p_{u,k(q)}^{t},z_{i,k(q)}^{t},a_{u,k(q)}^{t-1},x_{i,k(q)}^{t-1},\psi_{2(q)}^{t-1}\right)$  is:

$$g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right) - g\left(p_{u,k(q)}^{t},z_{i,k(q)}^{t},a_{u,k(q)}^{t-1},x_{i,k(q)}^{t-1},\psi_{2(q)}^{t-1}\right) = -\frac{\lambda_{(q)}^{t}\left|\Lambda\left(u\right)\right|}{2}\left(a_{u,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t}\left|\Lambda\left(i\right)\right|}{2}\left(x_{i,k(q)}^{t}-x_{i,k(q)}^{t-1}\right)^{2}.$$
(S25)

Moreover,  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t}\right)$  and  $g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right)$  yields:

$$\begin{split} &g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t}\right)-g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t-1}\right)\\ &=\left(p_{u,k(q)}^{t}-a_{u,k(q)}^{t}\right)\left(h_{u,k(q)}^{t}-h_{u,k(q)}^{t-1}\right)+\left(z_{i,k(q)}^{t}-x_{i,k(q)}^{t}\right)\left(w_{i,k(q)}^{t}-w_{i,k(q)}^{t-1}\right)\\ &=\eta_{(q)}^{t}\lambda_{(q)}^{t}\left|\Lambda\left(u\right)\right|\left(p_{u,k(q)}^{t}-a_{u,k(q)}^{t}\right)^{2}+\frac{1}{\eta_{(q)}^{t}\lambda_{(q)}^{t}\left|\Lambda\left(i\right)\right|}\left(w_{i,k(q)}^{t}-w_{i,k(q)}^{t-1}\right)^{2}\\ &\stackrel{\text{(II)}}{\leq}\eta_{(q)}^{t}\lambda_{(q)}^{t}\left|\Lambda\left(u\right)\right|\left(p_{u,k(q)}^{t}\right)^{2}+\frac{2\left|\Lambda\left(i\right)\right|}{\eta_{(q)}^{t}\lambda_{(q)}^{t}}\left(\left(\left(\eta_{(q)}^{t}-1\right)\lambda_{(q)}^{t}z_{i,k(q)}^{t}-\left(\eta_{(q)}^{t-1}-1\right)\lambda_{(q)}^{t-1}z_{i,k(q)}^{t-1}\right)^{2}+\left(\left(\eta_{(q)}^{t}-1\right)\lambda_{(q)}^{t}x_{i,k(q)}^{t}-\left(\eta_{(q)}^{t-1}-1\right)\lambda_{(q)}^{t-1}x_{i,k(q)}^{t-1}\right)^{2},\end{split}$$

where (I) is based on the update rules of  $(h_{u,k(q)}, w_{i,k(q)})$  given in (4e), (4f) and (5c), and (II) is achieved with (22b) and  $a'_{u,k(q)}$ =0. With (S5), (S25) and (S26), we have the following deduction:

$$g\left(\psi_{1(q)}^{t}, \psi_{2(q)}^{t}\right) - g\left(\psi_{1(q)}^{t-1}, \psi_{2(q)}^{t-1}\right)$$

$$\leq -\frac{1}{2} \left(\sum_{i \in \Lambda(u)} \left(z_{i,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(u)\right| \right) \left(p_{u,k(q)}^{t} - p_{u,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t} \left|\Lambda(u)\right|}{2} \left(a_{u,k(q)}^{t-1}\right)^{2}$$

$$-\frac{1}{2} \left(\sum_{u \in \Lambda(i)} \left(p_{u,k(q)}^{t-1}\right)^{2} + \lambda_{(q)}^{t} \left|\Lambda(i)\right| \right) \left(z_{i,k(q)}^{t} - z_{i,k(q)}^{t-1}\right)^{2} - \frac{\lambda_{(q)}^{t} \left|\Lambda(i)\right|}{2} \left(x_{i,k(q)}^{t} - x_{i,k(q)}^{t-1}\right)^{2}$$

$$+ \eta_{(q)}^{t} \lambda_{(q)}^{t} \left|\Lambda(u)\right| \left(p_{u,k(q)}^{t}\right)^{2} + \frac{2\left|\Lambda(i)\right|}{\eta_{(q)}^{t} \lambda_{(q)}^{t}} \left(\left(\left(\eta_{(q)}^{t} - 1\right)\lambda_{(q)}^{t} z_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right)\lambda_{(q)}^{t-1} z_{i,k(q)}^{t-1}\right)^{2} + \left(\left(\eta_{(q)}^{t} - 1\right)\lambda_{(q)}^{t} x_{i,k(q)}^{t} - \left(\eta_{(q)}^{t-1} - 1\right)\lambda_{(q)}^{t} x_{i,k(q)}^{t-1}\right)^{2}.$$
(S27)

Owing to (29), (25a) stands, which indicates that the augmented Lagrangian function (3) related to  $s_{(q)}$  or  $\tau_q$  is non-increasing as  $a'_{u,k(q)}$ =0 and  $x'_{i,k(q)}$ >0 in this case. Then after the t-th iteration, we substitute  $a'_{u,k(q)}$ =0 into (S10):

$$g\left(\psi_{1(q)}^{t},\psi_{2(q)}^{t}\right) = \frac{1}{2} \sum_{y_{u,l} \in \Lambda} \left(y_{u,i} - \sum_{l_{i}=1}^{k} p_{u,l_{i}(q)}^{t} z_{i,l_{i}(q)}^{t} - \sum_{l_{2}=k+1}^{d} p_{u,l_{2}(q)}^{t-1} z_{i,l_{2}(q)}^{t-1}\right)^{2} + \left(p_{u,k_{i}(q)}^{t}\right)^{2} + \left(p_{u,k_{i}(q)}^{t}\right)^{2} + \left(p_{u,k_{i}(q)}^{t-1}\right) \lambda_{(q)}^{t-1} \sum_{l_{2}=k+1}^{d} \left(p_{u,l_{2}(q)}^{t-1} - a_{u,l_{2}(q)}^{t}\right)^{2} + \left(p_{u,k_{i}(q)}^{t-1}\right)^{2} + \left(p_{u,l_{2}(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} \sum_{l_{2}=k+1}^{d} \left(p_{u,l_{2}(q)}^{t-1} - a_{u,l_{2}(q)}^{t-1}\right)^{2} \right) + \sum_{i} \left| \Lambda(i) \right| \left( \left(\eta_{(q)}^{t} - 1\right) \lambda_{(q)}^{t} \sum_{l_{i}=1}^{k} \left(z_{i,l_{i}(q)}^{t} - x_{i,l_{i}(q)}^{t}\right)^{2} + \left(\eta_{(q)}^{t-1} - 1\right) \lambda_{(q)}^{t-1} \sum_{l_{2}=k+1}^{d} w_{i,l_{2}(q)}^{t} \left(z_{i,l_{2}(q)}^{t-1} - x_{i,l_{2}(q)}^{t-1}\right)^{2} \right) + \sum_{i} \frac{\lambda_{(q)}^{t} \left| \Lambda(u) \right|}{2} \left( \sum_{l_{i}=1}^{k-1} \left(p_{u,l_{i}(q)}^{t} - a_{u,l_{i}(q)}^{t}\right)^{2} + \sum_{l_{2}=k+1}^{d} \left(p_{u,l_{2}(q)}^{t-1} - a_{u,l_{2}(q)}^{t-1}\right)^{2} \right) + \sum_{i} \frac{\lambda_{(q)}^{t} \left| \Lambda(i) \right|}{2} \left( \sum_{l_{i}=1}^{k} \left(z_{i,l_{i}(q)}^{t} - x_{i,l_{i}(q)}^{t}\right)^{2} + \sum_{l_{2}=k+1}^{d} \left(z_{i,l_{2}(q)}^{t-1} - x_{i,l_{2}(q)}^{t-1}\right)^{2} \right) \right)$$

(S28) indicates that if (24b) is fulfilled, (25b) holds, thereby making (3) related to  $s_{(q)}$  or  $\tau_q$  lower-bounded as  $a'_{u,k(q)}$ =0, and  $x'_{i,k(q)}$ >0 in this case. Based on the above inferences, *Lemma* 2 stands, and **Step 4** is implemented.

#### E. Proof of Theorem 2

**Part a.** Following Lemma 3,  $g\left(\psi_{1(q)}^t, \psi_{2(q)}^t\right)$  converges as  $t \to \infty$ , indicating that (S11) is fulfilled. With (26), (29) and (S27), we have (S12a), (S12b), (S12d), (S12f) and the following inferences:

$$\lim_{t \to \infty} a_{u,k(q)}^{t-1} \to 0, \tag{S29a}$$

$$\lim_{t \to \infty} p_{u,k(q)}^t \to 0. \tag{S29b}$$

Then according to (S12f), (S13b) is fulfilled. Hence, based on (S13b), (S29b) and  $a'_{u,k(q)}=0$ , (27) is fulfilled.

**Part b.** Firstly, considering a limit point  $\{\psi_{1(q)}^*, \psi_{2(q)}^*\}$  of a sequence  $\{\psi_{1(q)}^t, \psi_{2(q)}^t\}$  generated by the update rules of  $\{\psi_{1(q)}, \psi_{2(q)}\}$  based on (4) and (5), according to (27) and (S15), (S16) holds when  $a'_{u,k(q)}=0$ , and  $x'_{i,k(q)}>0$  in this case. Then considering the KKT conditions related to  $a_{u,k(q)}$ , i.e., (S22).

According to (S17)-(S21) and with  $a'_{u,k(q)}$ =0, conditions (S22a)-(S22c) are naturally satisfied. Thus, we focus on analyzing condition (S22d). Since we have  $a'_{u,k(q)}$ =0 in this case, the following inequality holds:

$$p_{u,k(q)}^* + \frac{h_{u,k(q)}^*}{\lambda_{(q)}^* |\Lambda(u)|} \le 0.$$
 (S30)

Note that (S30) indicates that:

$$m_{u,k(q)}^* = -\lambda_{(q)}^* \left| \Lambda(u) \right| \left( p_{u,k(q)}^* + \frac{h_{u,k(q)}^*}{\lambda_{(q)}^* \left| \Lambda(u) \right|} \right) \ge 0.$$
 (S31)

Thus, condition (S22) are all fulfilled in this case. Note that as  $x'_{i,k(q)} > 0$  in this case, the proof regarding the KKT conditions of  $x_{u,k(q)}$  can be achieved similarly. *Theorem* 2 stands, and **Step 5** is implemented.

# II. ADDITIONAL FIGURES

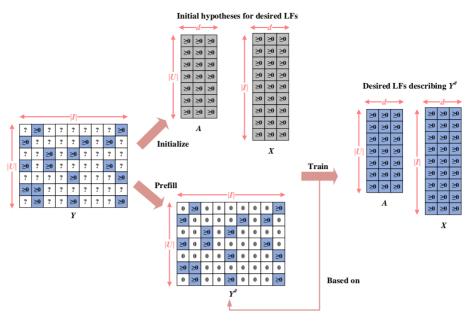


Fig. S1. Processing flow of an NMF model.

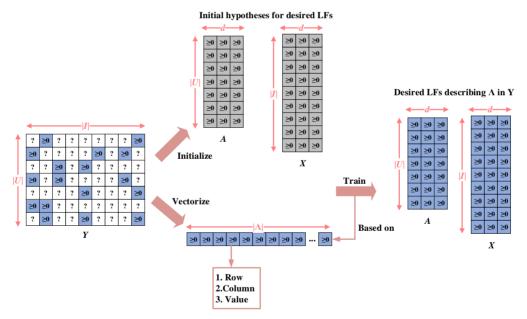


Fig. S2. Processing flow of an NLFA model.

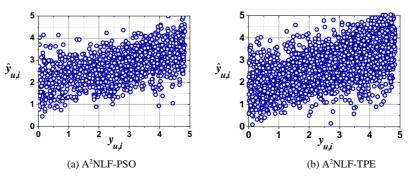


Fig. S3. Relations between  $y_{u,i}$  in  $\Lambda$  and corresponding  $\hat{y}_{u,i}$  generated by an A<sup>2</sup>NLF-PSO/A<sup>2</sup>NLF-TPE model on D2 as d=20.

# III. ADDITIONAL TABLES

TABLE S.I. Grid-search Range of Hyper-parameters in M1-8 on D1-4.

No.	Hyper-parameters	Grid-searching Range
110.	· · · · · · · · · · · · · · · · · · ·	
M1	Augmentation coefficient $\lambda$	2-6, 2-4,, 28
	Learning rate $\eta$	$8, 4, 2, 1, 2^{-1}, 2^{-2}, 2^{-3}$
M2	Penalty coefficient $\lambda$	2, 1.8,, 0.8
М3	Regularization coefficient $\mu$	$8, 4, 2, 1, 2^{-1}, 2^{-2}, 2^{-3}$
IVIS	$L_p$ coefficient $p$	1.2, 1.3,, 2.0
M4	Penalty coefficient $\alpha$	1, 10,, 10 <sup>5</sup>
IV14	Penalty coefficient $\beta$	$10, 10^2,, 10^6$
M5	Penalty coefficient $\rho$	$2^{-3}, 2^{-5},, 2^{-17}$
	Regularization coefficient $\lambda$	10 <sup>-6</sup> , 5×10 <sup>-5</sup> ,, 10 <sup>-3</sup>
M6	Learning rate $\eta$	10 <sup>-5</sup> , 5×10 <sup>-4</sup> ,, 10 <sup>-2</sup>
	Batch size bs	$2^5, 2^6, 2^7, 2^8, 2^9, 2^{10}$
	Regularization coefficient $\lambda$	10 <sup>-5</sup> , 5×10 <sup>-4</sup> ,, 10 <sup>-2</sup>
<b>M7</b>	Learning rate $\eta$	10 <sup>-5</sup> , 5×10 <sup>-4</sup> ,, 10 <sup>-2</sup>
	Batch size bs	$2^8, 2^9, 2^{10}, 2^{11}, 2^{12}, 2^{13}$
	Regularization coefficient $\lambda$	10 <sup>-6</sup> , 5×10 <sup>-5</sup> ,, 10 <sup>-3</sup>
<b>M8</b>	Learning rate $\eta$	10 <sup>-6</sup> , 5×10 <sup>-5</sup> ,, 10 <sup>-3</sup>
	Batch size bs	$2^{11}, 2^{12}, 2^{13}, 2^{14}, 2^{15}, 2^{16}$

TABLE S.II. Optimal Hyper-parameters during M1's Ten Times' Training Process on D1-4

No.	Type	1	2	3	4	5	6	7	8	9	10
D1	RMSE	$\lambda = 2^{-4}, \eta = 2$	$\lambda = 2^{-4}, \eta = 2$	$\lambda = 2^{-4}, \eta = 2$	$\lambda = 2^{-2}, \eta = 1$	$\lambda = 2^{-4}, \eta = 2$	$\lambda = 2^{-2}, \eta = 1$	$\lambda = 2^{-4}, \eta = 2$			
ъ1	MAE	$\lambda = 2^{-2}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$	$\lambda = 2^{-2}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$	$\lambda = 2^{-2}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$	$\lambda = 2^{-4}, \eta = 1$
D2	RMSE	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda = 1, \eta = 2^{-1}$	$\lambda$ =1, $\eta$ =1	$\lambda=1, \eta=2$	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$
D2	MAE	$\lambda=1, \eta=2$	$\lambda=1, \eta=2$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$	$\lambda=1, \eta=2$
D2	RMSE	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$
D3	MAE	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda = 1, \eta = 2^{-2}$	$\lambda=1, \eta=2$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-2}$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$	$\lambda=1, \eta=2$
D4	RMSE	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$			
D4	MAE	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda=1, \eta=1$	$\lambda=1, \eta=2$	$\lambda=1, \eta=2$	$\lambda=1, \eta=1$	$\lambda = 1, \eta = 2^{-1}$	$\lambda = 1, \eta = 2^{-1}$	$\lambda = 1, \eta = 2^{-1}$

TABLE S.III. Optimal Hyper-parameters during M2's Ten Times' Training Process on D1-4

No.	Type	1	2	3	4	5	6	7	8	9	10
D1	RMSE	$\lambda=1.6$	$\lambda=1.6$	$\lambda=1.6$	$\lambda=1.8$	$\lambda=1.6$	$\lambda=1.8$	$\lambda=1.6$	$\lambda=1.8$	$\lambda$ =1.6	$\lambda$ =1.6
	MAE	λ=1.8	λ=1.8	λ=1.8	$\lambda=1.8$	λ=1.8	λ=1.8	λ=1.2	λ=1.8	λ=1.8	λ=1.2
D2	RMSE	λ=1.8	λ=1.8	$\lambda=1.8$	$\lambda=1.8$	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8
D2	MAE	λ=1.8	λ=1.8	$\lambda=1.8$	$\lambda=1.8$	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8
D2	RMSE	λ=1.8	λ=1.8	$\lambda=1.8$	$\lambda=1.8$	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8
D3	MAE	λ=1.8	λ=1.8	$\lambda=1.8$	$\lambda=1.8$	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8	λ=1.8
D4	RMSE	<sup>1</sup> Failure									
D4	MAE	<sup>1</sup> Failure									

<sup>&</sup>lt;sup>1</sup>M2 fails to obtain the final results on D4: their memory requirements are too large to meet on our experimental environment as shown in Table VI.

TABLE S.IV. Optimal Hyper-parameters during M3's Ten Times' Training Process on D1-4

No.	Type	1	2	3	4	5	6	7	8	9	10
	RMSE	$\mu=2^{-1}$ ,	$\mu = 2^{-1}$ ,	$\mu = 2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,
D1	KNISE	p=1.9	p = 1.8	p = 1.7	p=1.8	p=1.8	p=1.7	p = 1.8	p=1.9	p=1.8	p=1.8
DΙ	MAE	$\mu = 2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,
	MAE	p=1.8	p = 1.9	p=1.8	p=1.7	p=1.8	p=1.7	p = 1.8	p = 1.8	p=1.9	p=1.9
	RMSE	u-2 n-1 0	u=4 n=10	$\mu$ =4 $p$ =1.9	$\mu=2^{-1}$ ,	$\mu=2^{-1}$ ,	$\mu$ =2, $p$ =1.9	$\mu=2^{-1}$ ,	u=2 n=10	u_2 n_1 °	u=2 n=1 9
<b>D2</b>	KWISE	$\mu$ =2, $p$ =1.9	$\mu$ =4, $p$ =1.9	$\mu$ =4 $p$ =1.9	p=1.8	p=1.9	$\mu$ =2, $p$ =1.9	p = 1.8	$\mu$ =2, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =2, $p$ =1.8
	MAE	$\mu$ =4, $p$ =1.9	$\mu$ =2, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =4, $p$ =1.9	$\mu$ =4, $p$ =1.9	$\mu$ =2, $p$ =1.9	$\mu$ =1, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =2, $p$ =1.8	$\mu$ =2, $p$ =1.9
D3	RMSE	$\mu$ =4, $p$ =1.9	$\mu$ =4, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =2, $p$ =1.8	$\mu$ =4, $p$ =1.9	$\mu$ =4, $p$ =1.9	$\mu$ =2, $p$ =1.9			
D3	MAE	$\mu$ =2, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =2, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =4, $p$ =1.9	$\mu$ =4, $p$ =1.9	$\mu$ =4, $p$ =1.9	$\mu$ =2, $p$ =1.8	$\mu$ =2, $p$ =1.9	$\mu$ =2, $p$ =1.9
D4	RMSE	<sup>1</sup> Failure									
<i>D</i> 4	MAE	<sup>1</sup> Failure									

<sup>&</sup>lt;sup>1</sup>M3 fails to obtain the final results on D4: their memory requirements are too large to meet on our experimental environment as shown in Table VI.

TABLE S.V. Optimal Hyper-parameters during M4's Ten Times' Training Process on D1-4

	Type	1	2	3	4	5	6	7	8	9	10
D	RMSE	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,			
D1 —	IVISE	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^{3}$
	MAE	$\alpha = 10^4$ ,	$\alpha = 10^{3}$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^3$ ,
IV.	VIAL	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^{4}$	$\beta = 10^4$					
D	RMSE	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^{3}$ ,	$\alpha = 10^{3}$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,
D2 —	IVISE	$\beta = 10^4$	$\beta = 10^{2}$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^{2}$	$\beta = 10^{3}$	$\beta = 10^{4}$	$\beta = 10^{2}$	$\beta = 10^{3}$
	MAE	$\alpha = 10^3$ ,	$\alpha = 10^{3}$ ,	$\alpha = 10^3$ ,	$\alpha = 10^{3}$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,			
	VIAL	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^{3}$
D	RMSE	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha=10^3$ ,	$\alpha = 10^{3}$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,
D3 —	IVISE	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^{3}$
	MAE	$\alpha = 10^3$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,	$\alpha = 10^3$ ,	$\alpha = 10^3$ ,	$\alpha = 10^4$ ,	$\alpha = 10^3$ ,
	VIAL	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^{3}$	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^4$	$\beta = 10^{3}$	$\beta = 10^4$
D4 R	RMSE	<sup>1</sup> Failure									
N	MAE	<sup>1</sup> Failure									

<sup>&</sup>lt;sup>1</sup>M4 fails to obtain the final results on D4: their memory requirements are too large to meet on our experimental environment as shown in Table VI.

TABLE S.VI. Optimal Hyper-parameters during M5's Ten Times' Training Process on D1-4

No.	Type	1	2	3	4	5	6	7	8	9	10
D1	RMSE	$\rho = 2^{-5}$									
D1	MAE	$\rho = 2^{-7}$	$\rho = 2^{-5}$	$\rho = 2^{-7}$	$\rho = 2^{-5}$	$\rho = 2^{-5}$	$\rho = 2^{-7}$	$\rho = 2^{-5}$	$\rho = 2^{-5}$	$\rho = 2^{-7}$	$\rho = 2^{-5}$
D2	RMSE	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-15}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$
D2	MAE	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-15}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-15}$
D2	RMSE	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$
D3	MAE	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$	$\rho = 2^{-13}$	$\rho = 2^{-15}$	$\rho = 2^{-15}$	$\rho = 2^{-13}$
D4	RMSE	<sup>1</sup> Failure									
<i>D</i> 4	MAE	<sup>1</sup> Failure									

<sup>&</sup>lt;sup>1</sup>M5 fails to obtain the final results on D4: their memory requirements are too large to meet on our experimental environment as shown in Table VI.

TABLE S.VII. Optimal Hyper-parameters during M6's Ten Times' Training Process on D1-4

No.	Туре	1	2	3	4	5	6	7	8	9	10
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-3}$ ,	λ=10 <sup>-4</sup> ,	λ=10 <sup>-5</sup> ,	λ=10 <sup>-3</sup> ,	λ=10 <sup>-5</sup> ,	λ=10 <sup>-4</sup> ,	λ=10 <sup>-3</sup> ,
	RMSE	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,
D1		1bs=29	bs=29								
וע		$\lambda = 10^{-5}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-2}$ ,			
	MAE	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,
		bs=29									
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-1}$ ,	$\lambda = 10^{-1}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-1}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-1}$ ,	$\lambda = 10^{-4}$ ,
	RMSE	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,
<b>D2</b>		$bs=2^6$	$bs=2^6$	$bs=2^6$	$bs=2^6$	$bs=2^6$	$bs=2^6$	bs=2 <sup>6</sup>	$bs=2^6$	$bs=2^6$	bs=2 <sup>6</sup>
DZ		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,
	MAE	$\eta = 10^{-2}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-2}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,				
		bs=2 <sup>6</sup>									
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,				
	RMSE	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,				
<b>D3</b>		bs=2 <sup>7</sup>									
DS		$\lambda = 10^{-5}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-4}$ ,					
	MAE	$\eta = 10^{-3}$ ,									
		bs=2 <sup>7</sup>									
		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-3}$ ,
	RMSE	$\eta = 10^{-4}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-4}$ ,
D4		bs=29									
D4		$\lambda = 10^{-2}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-5}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,	$\lambda = 10^{-2}$ ,			
	MAE	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,
		$bs=2^9$	$bs=2^9$	$bs=2^9$	$bs=2^9$	bs=29	$bs=2^9$	$bs=2^9$	$bs=2^9$	$bs=2^9$	$bs=2^9$

<sup>&</sup>lt;sup>1</sup>The abbreviation 'bs' denotes the batch size adopted by M6 on an HDI matrix.

TABLE S.VIII. Optimal Hyper-parameters during M7's Ten Times' Training Process on D1-4

No.	Туре	1	2	3	4	5	6	7	8	9	10
		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	λ=10 <sup>-3</sup> ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	RMSE	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 10^{-3}$ ,
D1		$^{1}bs=2^{11}$	bs=211	$bs=2^{11}$	bs=211	bs=211	bs=211	bs=211	$bs=2^{11}$	bs=211	bs=211
DI		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	MAE	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,
		bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=211	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=211	bs=211
		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	RMSE	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,
<b>D2</b>		bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=210	bs=2 <sup>10</sup>
DZ		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	MAE	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,
		bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>	bs=2 <sup>10</sup>
		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	RMSE	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 10^{-3}$ ,
D3		bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>
DS		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	MAE	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,
		bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>	bs=2 <sup>11</sup>
		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	RMSE	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-2}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,
D4		bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>
DŦ		$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 5 \times 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,	$\lambda = 10^{-3}$ ,
	MAE	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,	$\eta = 5 \times 10^{-3}$ ,	$\eta = 10^{-3}$ ,
		bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>	bs=2 <sup>12</sup>

<sup>&</sup>lt;sup>1</sup>The abbreviation 'bs' denotes batch size adopted by M7 on an HDI matrix.

TABLE S.IX. Optimal Hyper-parameters during M8's Ten Times' Training Process on D1-4

No.	Type	1	2	3	4	5	6	7	8	9	10
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	RMSE	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,
<b>D</b> 1		$^{1}bs=2^{14}$	bs=214	bs=214	$bs=2^{14}$	bs=214	bs=214	bs=214	bs=214	bs=214	bs=214
DI		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	MAE	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-5}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,
		bs=214	bs=214	bs=214	bs=214	$bs=2^{14}$	$bs=2^{14}$	$bs=2^{14}$	$bs=2^{14}$	bs=214	$bs=2^{14}$
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	RMSE	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-5}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,
<b>D2</b>		bs=213	bs=213	bs=213	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=213	bs=2 <sup>13</sup>	bs=213	bs=213
DZ		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	MAE	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-5}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,
		bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	RMSE	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-5}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,
D3		bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>
DS		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 5 \times 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	MAE	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-5}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,
		bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>	bs=2 <sup>13</sup>
		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	RMSE	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,
D4		bs=2 <sup>14</sup>	bs=2 <sup>14</sup>	bs=2 <sup>14</sup>	bs=2 <sup>14</sup>	bs=2 <sup>14</sup>	bs=2 <sup>14</sup>	bs=214	bs=2 <sup>14</sup>	bs=2 <sup>14</sup>	bs=2 <sup>14</sup>
D4		$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,	$\lambda = 10^{-4}$ ,
	MAE	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 5 \times 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,	$\eta = 10^{-4}$ ,
		bs=214	bs=214	bs=214	bs=214	$bs=2^{14}$	bs=214	bs=214	bs=214	bs=214	bs=214

<sup>&</sup>lt;sup>1</sup>The abbreviation 'bs' denotes batch size adopted by M7 on an HDI matrix.

TABLE S.X. RMSE, MAE and Time Cost of M1, M9 and M10 on D1-4.

Dataset	Model	Case	Prediction Accuracy	<sup>1</sup> Tuning Time Cost (Secs)	<sup>2</sup> Testing Time Cost (Secs)	Total Time Cost (Secs)
	M1	RMSE	0.2373 ±2.2E-6	428 ±22.7	6±2.4	434±25
	M1	MAE	0.1815±1.1E-6	439±25.4	6±2.8	445 ±28
D1	MO	RMSE	0.2339±2.7E-4	-	-	46 ±4
DI	M9	MAE	0.1793±3.3E-4	-	-	60±5
	M10	RMSE	0.2573±1.4E-6	-	-	387±33
	MIIO	MAE	0.2015 ±2.8E-6	-	-	396±46
	M1	RMSE	1.0187±1.1E-6	271 ±45.4	4±1.7	275 ±47
	IVII	MAE	0.8079±2.5E-6	305±38.3	3 <u>±</u> 0.9	308±39
D2	M9	RMSE	1.0158±6.4E-4	-	-	25±5
DZ	M9	MAE	0.7848±9.3E-4	-	-	29±8
	M10	RMSE	1.0209 ±2.0E-5	-	-	87±11
	MIIO	MAE	0.7883±1.3E-5	-	-	85±9
	M1	RMSE	0.8665±7.8E-4	739±72.3	21 ±14.7	759±87
	IVII	MAE	0.6829±1.7E-6	756±53.8	3±0.5	763 ±54
D3	M9	RMSE	0.8673±1.3E-3	-	-	26±6
D3	M9	MAE	0.6785±9.6E-5	-	-	30±9
	M10	RMSE	0.8684±4.7E-4	-	-	487±59
	WHO	MAE	0.6793 ±2.8E-5	-	-	268±40
	M1	RMSE	0.8096±2.9E-6	2,934±353.8	38±24.6	3,972±378
	IVII	MAE	0.6221 ±7.9E-7	9,203±828.9	33±20.4	9,236±849
D4	D4 M0		0.8091 ±3.0E-3	-	-	334±46
D4	D4 M9		0.6191±1.7E-4	-	-	358±31
	M10	RMSE	0.8086±6.0E-5	-	-	3731±311
	WHU	MAE	0.6199±7.1E-6	-	-	5532±566

<sup>&</sup>lt;sup>1</sup>Time cost consumed by M1 for manually grid-searching optimal hyper-parameters; <sup>2</sup>Time cost consumed by M1 with obtained hyper-parameters.

TABLE S.XI. Results of the Wilcoxon Signed-ranks Test for M9 on RMSE/MAE of Table S.IX

Comparison	<b>R</b> +	R-	¹p-value
M9 vs M1	34	2	0.0234
M9 vs M2	36	0	0.0078
M9 vs M3	36	0	0.0078
M9 vs M4	36	0	0.0078
M9 vs M5	36	0	0.0078
M9 vs M6	33	3	0.0391
M9 vs M7	36	0	0.0078
M9 vs M8	36	0	0.0078

<sup>&</sup>lt;sup>1</sup>With a significance level of 0.05, the accepted hypotheses are highlighted.

TABLE S.XII. Results of the Wilcoxon Signed-ranks Test for M10 on RMSE/MAE of Table S.IX

Comparison	R+	R-	¹p-value
M10 vs M1	20.5	15.5	0.7656
M10 vs M2	36	0	0.0078
M10 vs M3	36	0	0.0078
M10 vs M4	29	7	0.1484
M10 vs M5	36	0	0.0078
M10 vs M6	30	6	0.1094
M10 vs M7	29.5	6.5	0.1172
M10 vs M8	36	0	0.0078

<sup>&</sup>lt;sup>1</sup>With a significance level of 0.05, the accepted hypotheses are highlighted.

TABLE S.XIII. Results of the Wilcoxon Signed-ranks Test for M9 on Total Time Cost of Table S.X

Comparison	<b>R</b> +	R-	¹p-value
M9 vs M1	36	0	0.0078
M9 vs M2	36	0	0.0078
M9 vs M3	36	0	0.0078
M9 vs M4	36	0	0.0078
M9 vs M5	36	0	0.0078
M9 vs M6	36	0	0.0078
M9 vs M7	36	0	0.0078
M9 vs M8	36	0	0.0078

<sup>&</sup>lt;sup>1</sup>With a significance level of 0.05, the accepted hypotheses are highlighted.

TABLE S.XIV. Results of the Wilcoxon Signed-ranks Test for M10 on Total Time Cost of Table S.X

Comparison	R+	R-	¹p-value
M10 vs M1	36	0	0.0078
M10 vs M2	35	1	0.0156
M10 vs M3	36	0	0.0078
M10 vs M4	36	0	0.0078
M10 vs M5	33	3	0.0391
M10 vs M6	36	0	0.0078
M10 vs M7	36	0	0.0078
M10 vs M8	36	0	0.0078

 $<sup>^{1}\</sup>mbox{With a significance level of 0.05}$ , the accepted hypotheses are highlighted.