

# **ECE637 Lab report 8**

## **Image Halftoning**

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## Section 1 . Thresholding

### 1. The plot of original image and binary image.



*Figure 1.1 original image*



*Figure 1.2 binary image*

## 2. RMSE and fidelity values

**RMSE = 87.393316543870510**

**fidelity = 77.337149172432460**

## 3. Code of fidelity

```
function fide = fidelity(f,b)

const = 0;
for k = -3:3
    for l = -3:3
        const = const + exp(-(k^2 + l^2)/4);
    end
end
C = 1/const;

[m,n] = size(f);
f1 = 255*(f/255).^2.2;
b1 = 255*(b/255).^2.2;

fb = zeros(m+6,n+6);
bb = zeros(m+6,n+6);

for i = 1:m
    for j = 1:n
        fb(i+3,j+3) = f1(i,j);
        bb(i+3,j+3) = b1(i,j);
    end
end

for i = 1:m
    for j = 1:n
        sum1 = 0;
        sum2 = 0;
        for k = -3:3
            for l = -3:3
                sum1 = sum1 + fb(i+3+k,j+3+l)*C*exp(-(k^2 + l^2)/4);
```

```

sum2 = sum2 + bb(i+3+k,j+3+1)*C*exp(-(k^2 +
1^2)/4);
end
end
fl(i,j) = 255*(sum1/255)^(1/3);
bl(i,j) = 255*(sum2/255)^(1/3);
end
end
fide = 0;
for i = 1:m
    for j = 1:n
        fide = fide+ ((fl(i,j)-bl(i,j))^2);
    end
end
fide = sqrt(fide/(m*n));

```

## Session 2. Ordered dithering

### 1. Three matrices:

$$I_2 = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

$$I_4 = \begin{bmatrix} 5 & 9 & 6 & 10 \\ 13 & 1 & 14 & 2 \\ 7 & 11 & 4 & 8 \\ 15 & 3 & 12 & 0 \end{bmatrix}$$

$$I_8 = \begin{bmatrix} 21 & 37 & 25 & 41 & 22 & 38 & 26 & 42 \\ 53 & 5 & 57 & 9 & 54 & 6 & 58 & 10 \\ 29 & 45 & 17 & 33 & 30 & 46 & 18 & 34 \\ 61 & 13 & 49 & 1 & 62 & 14 & 50 & 2 \\ 23 & 39 & 27 & 43 & 20 & 36 & 24 & 40 \\ 55 & 7 & 59 & 11 & 52 & 4 & 56 & 8 \\ 31 & 47 & 19 & 35 & 28 & 44 & 16 & 32 \\ 63 & 15 & 51 & 3 & 60 & 12 & 48 & 0 \end{bmatrix}$$

### 2. RMSE and fidelity values

**2×2 dither pattern:**

**RMSE = 74.368723619209850**

**Fidelity = 52.012277527030150**

**4×4 dither pattern:**

**RMSE =81.838823772004600**

**Fidelity = 61.220489655455864**

**8×8 dither pattern:**

**RMSE = 81.447589682057970**

**Fidelity = 60.812270846722900**

### **3.Image results**



*Figure 2.1 ordered dithering 2x2*



*Figure 2.2 ordered dithering 4x4*



*Figure 2.2 ordered dithering 8x8*

## Session 3. Error diffusion

### 1. error diffusion code:

```
clc;
clear;

T = 127;
H = [1/16, 5/16, 3/16; 7/16, 0, 0];
f = imread('E:\2016spring\ECE637\lab8\house.tif');
f = double(f);
[m,n] = size(f);

f1 = 255*(f/255).^2.2;
error = zeros(m+1,n+2);
b = zeros(m,n);

for i = 1:m
    for j = 1:n
        f1(i,j) = f1(i,j) + sum(sum(error(i:i+1,j:j+2).*H));
        if(f1(i,j) > T)
            b(i,j) = 255;
        else
            b(i,j) = 0;
        end
        error(i+1,j+1) = f1(i,j) - b(i,j);
    end
end

RMSE = 0;
for i = 1:m
    for j = 1:n
        RMSE = RMSE + (((f1(i,j)-b(i,j))^2)/(m*n));
    end
end
RMSE = sqrt(RMSE);

fide = fidelity(f1,b);

image(b)
colormap(gray(256));

truesize
imwrite(uint8(b),'error_diffusion.tif')
```

## 2. Error diffusion result:



*Figure 3.1 error diffusion*

**RMSE = 84.132962841636100**

**Fidelity = 28.367870007414123**

Method	thresholding	2x2 dither	4x4 dither	8x8 dither	error diffusion
RMSE	87.39331654 3870510	74.36872361 9209850	81.83882377 2004600	81.44758968 2057970	84.1329
Fidelity	77.33714917 2432460	52.01227752 7030150	61.22048965 5455864	60.81227084 6722900	28.36787000 7414123

For RMSE value, thresholding method results in the largest value.

Meanwhile, different sizes of dither pattern are giving different results.

For error diffusion, its value is close to thresholding.

On the other hand, fidelity is giving an reasonable result. Thresholding



is the largest, followed by 8x8, 4x4 and 2x2 dithering. The fidelity value for error diffusion is smallest one.

By comparing the intuitively image quality, RMSE is not providing a reliable result.

However, fidelity actually provides much more reliable results. The smaller the fidelity value, the better the image quality.