

Less is more: Adaptive strategies in continuous time causal learning

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Background

Causal learning from observational data

Association/correlation

- Hume (1777/1975) argued that causal relations are not directly observable and therefore must be inferred on the basis of observable cues.
 - E.g., contiguity, temporal order -> *co-occurrence* of cause and effect

Causal learning from observational data

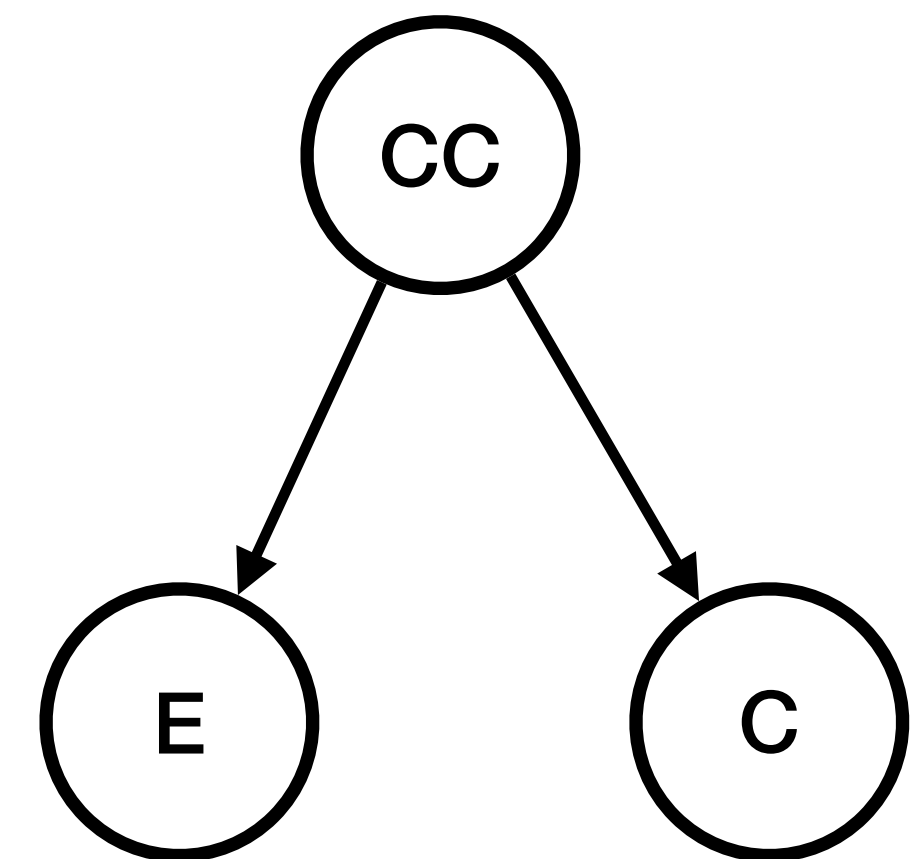
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- ΔP model (Jenkins & Ward, 1965)
 - Contingency: $\Delta P = P(E | C) - P(E | \neg C)$

Causal learning from observational data

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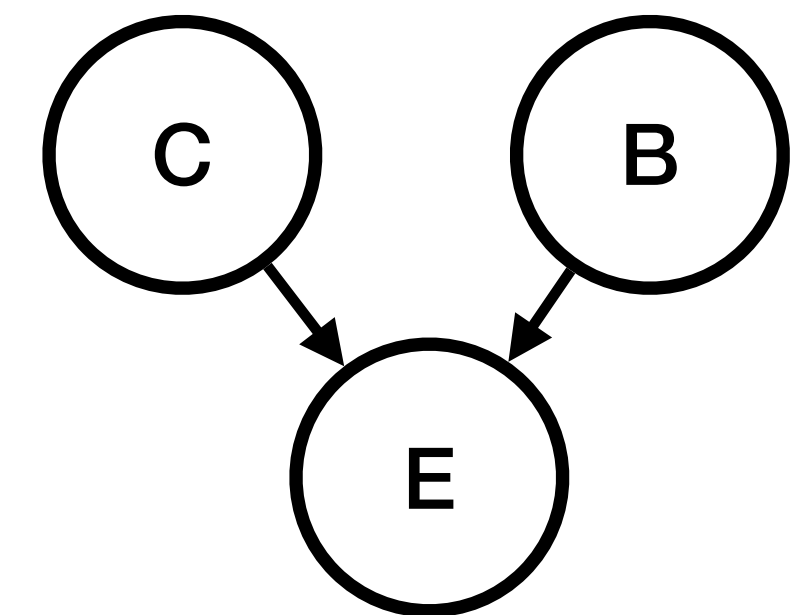


Causal learning from observational data

Causal strength

- Propose causal representations as opposed to associative ones.
- Power PC theory (short for a causal power theory of the probabilistic contrast model; Cheng, 1997)

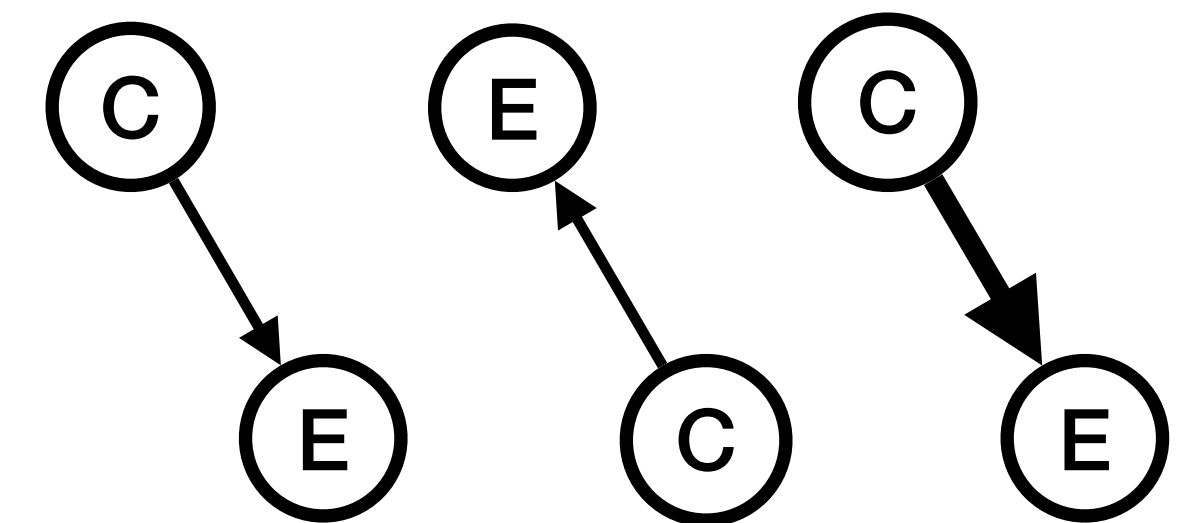
- Consider background cause:
$$P = \frac{P(E | C) - P(E | \neg C)}{1 - P(E | \neg C)}$$



Causal learning from observational data

Causal strength & structure

- Representation: causal Bayesian network (Pearl, 2000)
 - Probabilistic graphical model that represents a set of variables and their conditional dependencies via a directed acyclic graph (DAG)
 - A causal network is a Bayesian network with the requirement that the relationships be causal.
- Goal:
 - Structure learning & parameter estimation

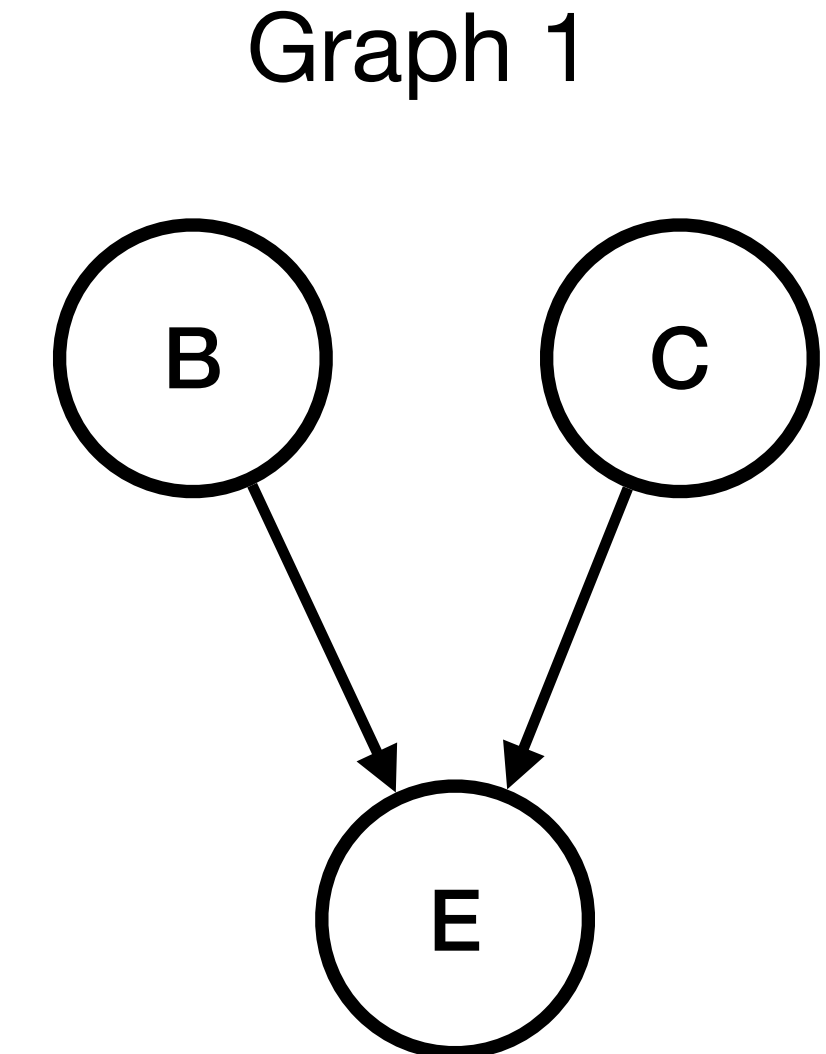
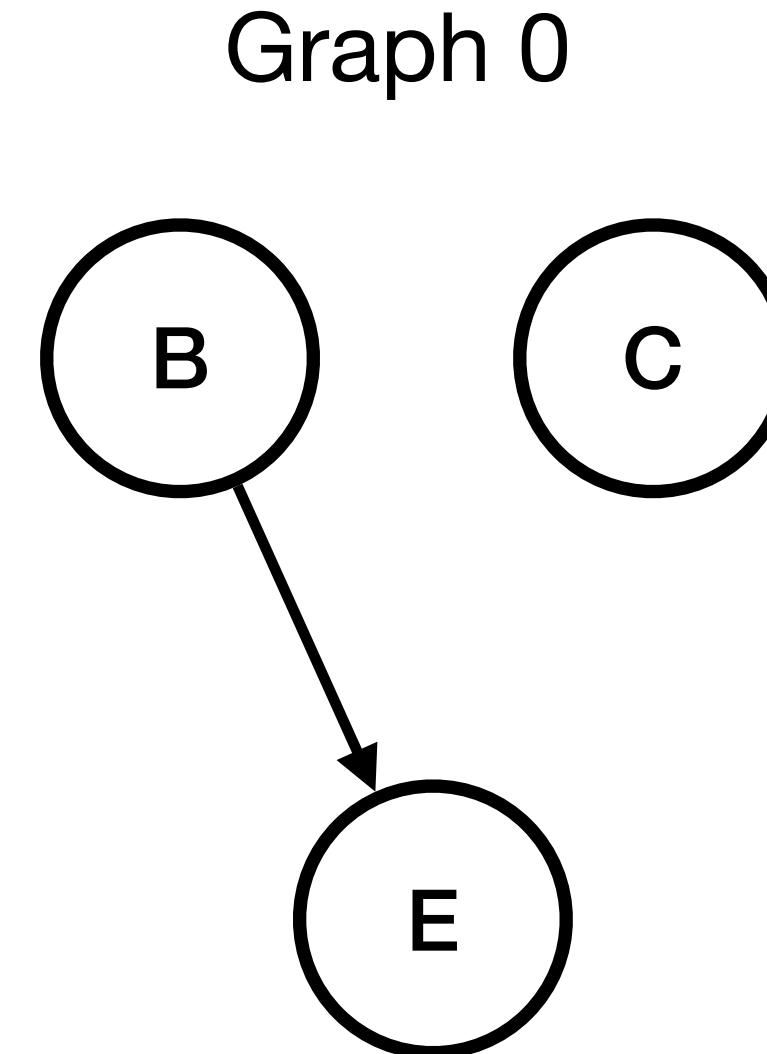


Causal learning from observational data

Causal strength & structure

- Causal support (Griffiths & Tenenbaum, 2005)
 - Evidence the data provide for the existence of a causal structure

- $$\text{Support} = \log \frac{P(D \mid G_1)}{P(D \mid G_0)}$$



Causal learning from observational data

Causal strength & structure

- Complexity of structure learning

- Two hypotheses: $\text{Support} = \log \frac{P(D \mid G_1)}{P(D \mid G_0)}$

- Full Bayesian model: $P(G_i \mid D) = \frac{P(D \mid G_i) P(G_i)}{\sum_{G \in \mathcal{G}} P(D \mid G) P(G)}$

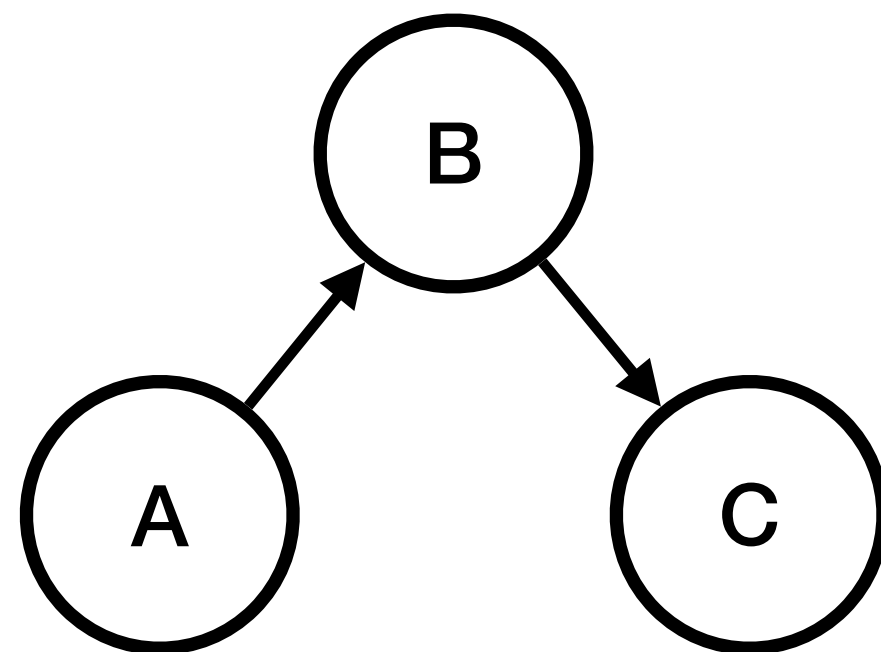
Causal learning from observational data

Causal strength & structure

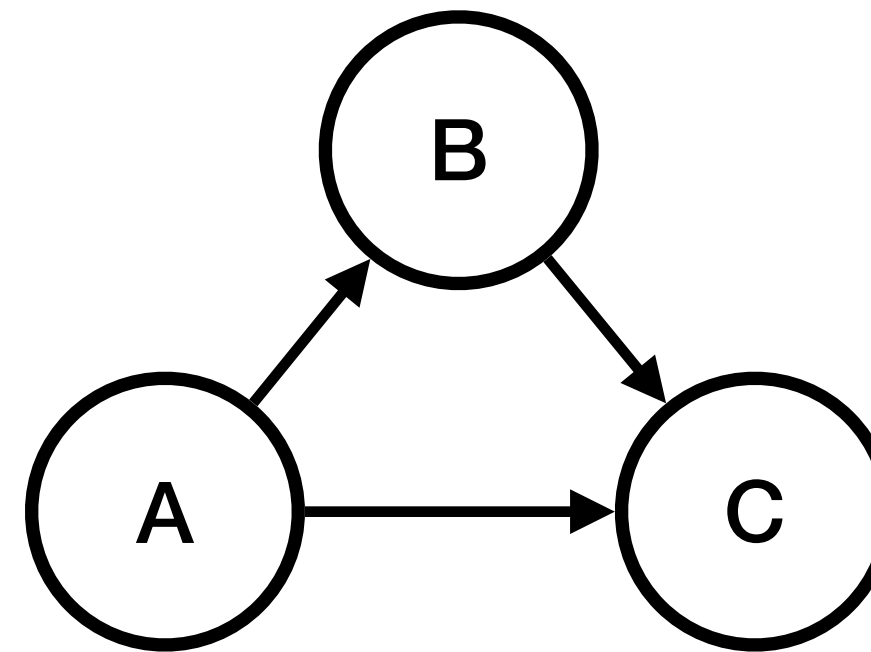
- Complexity of structure learning

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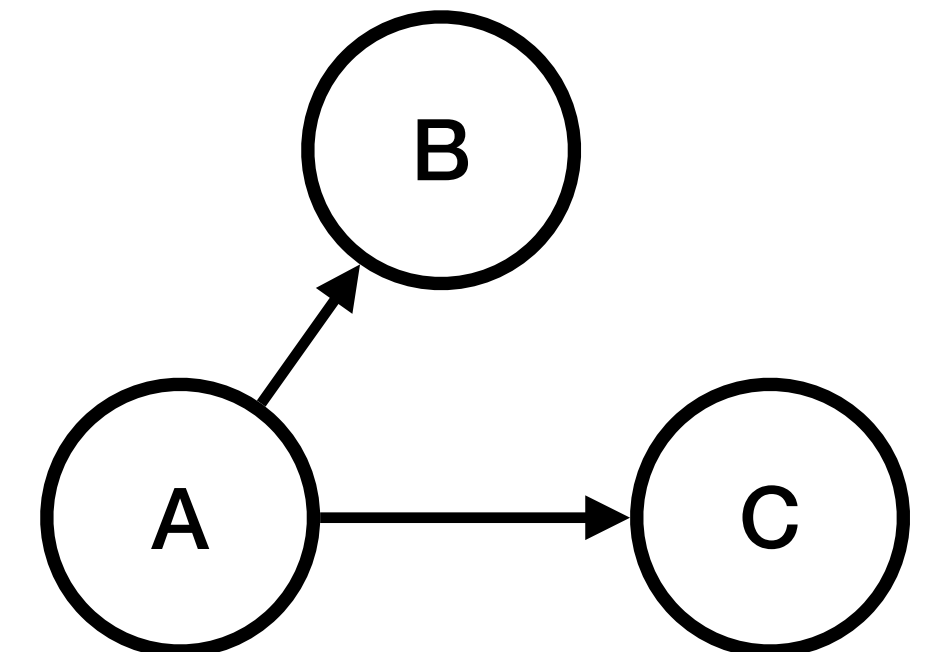
Chain



Confound



Common cause



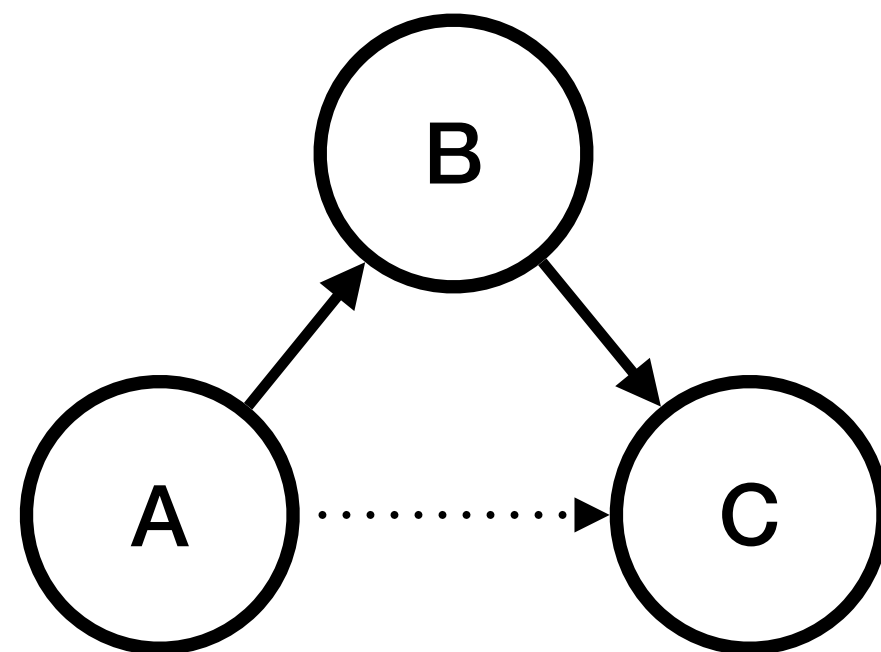
Causal learning from observational data

Causal strength & structure

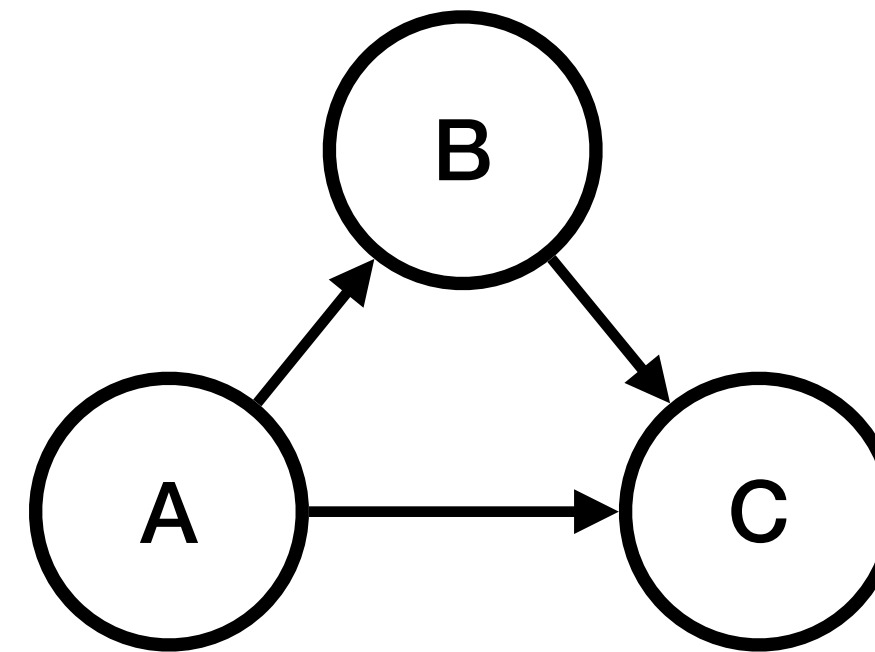
- Complexity of structure learning

- Full Bayesian model
$$P(G_i | D) = \frac{P(D | G_i) P(G_i)}{\sum_{G \in \mathcal{G}} P(D | G) P(G)}$$

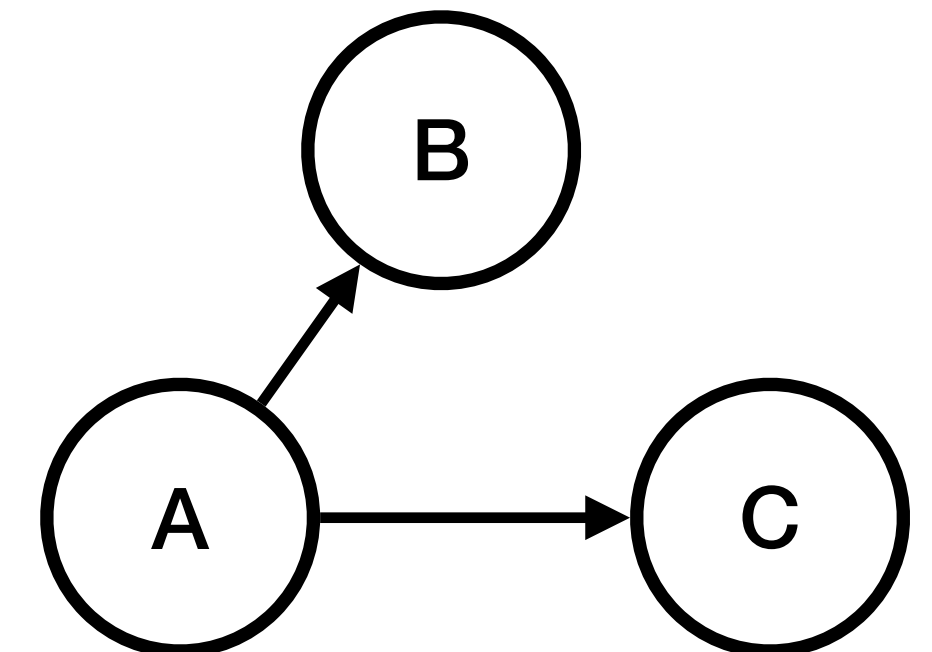
Chain



Confound



Common cause



Causal learning from heuristics

Descriptive model of model updating

- Single-effect (Waldmann, 2008) & local computations (Fernbach & Sloman, 2009)
 - $D^t \rightarrow G_{\text{update}}^t$
 - $G^{t+1} = G^t \cup G_{\text{update}}^t$
- Local updating (Neurath ship; Bramley et al., 2017)
 - Local modification: $\{G_i^{t+1}\} \in \text{edit}(G^t)$
 - Inference: $p(G_i^{t+1} \mid D^t) \propto \text{dist}(G_i^{t+1}, G^t) + p(D^t \mid G_i^{t+1})$

Waldmann, M. R., Cheng, P. W., Hagmayer, Y., & Blaisdell, A. P. (2008). Causal learning in rats and humans: A minimal rational model. *The probabilistic mind. Prospects for Bayesian cognitive science*, 453-484.

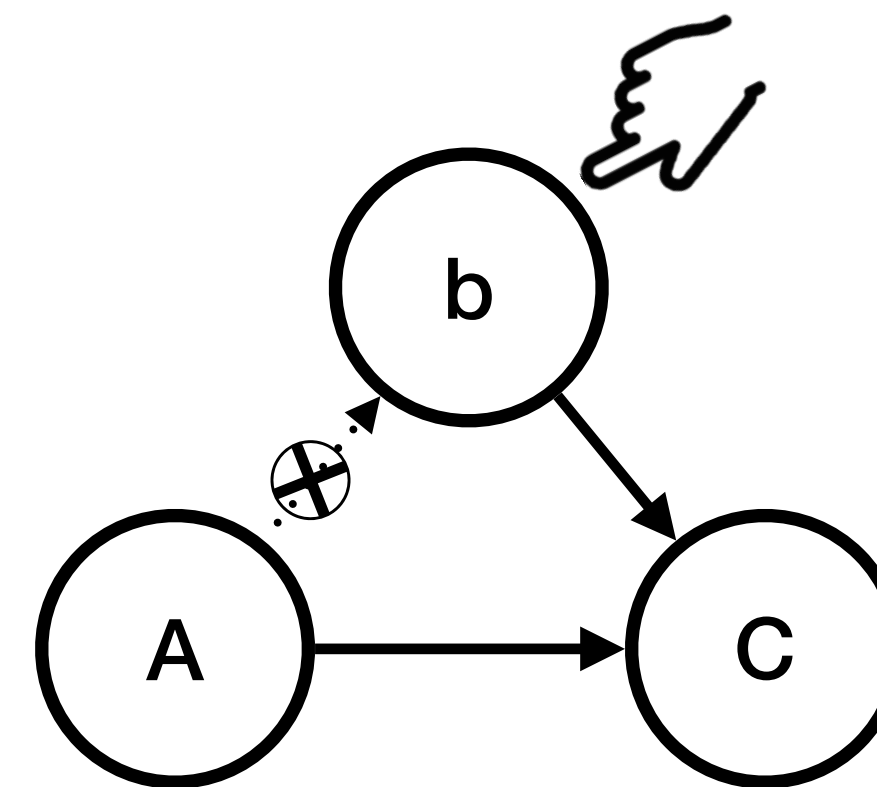
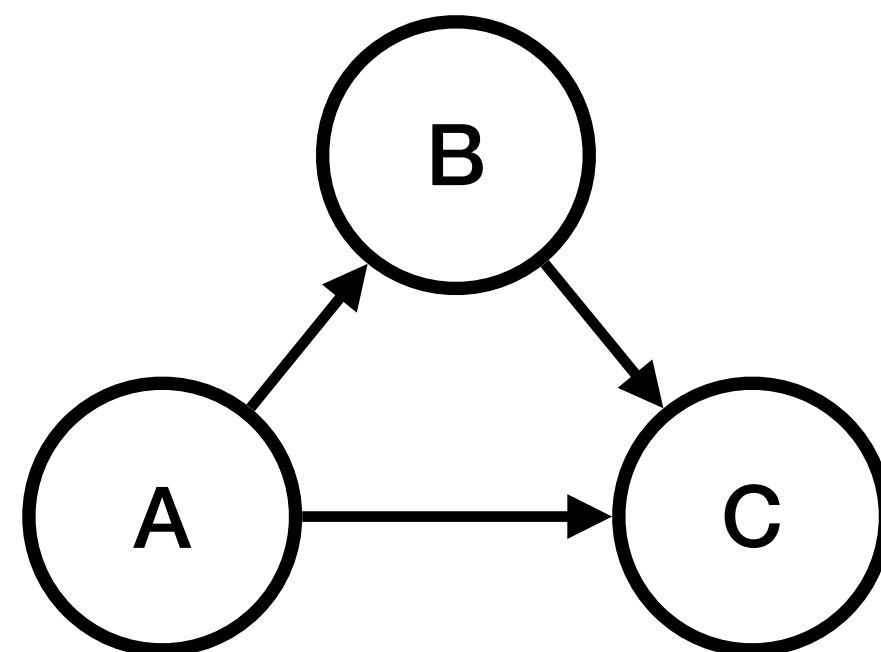
Fernbach, P. M., & Sloman, S. A. (2009). Causal learning with local computations. *Journal of experimental psychology: Learning, memory, and cognition*, 35(3), 678.

Bramley, N. R., Dayan, P., Griffiths, T. L., & Lagnado, D. A. (2017). Formalizing Neurath's ship: Approximate algorithms for online causal learning. *Psychological review*, 124(3), 301.

Causal learning from intervention

Motivation

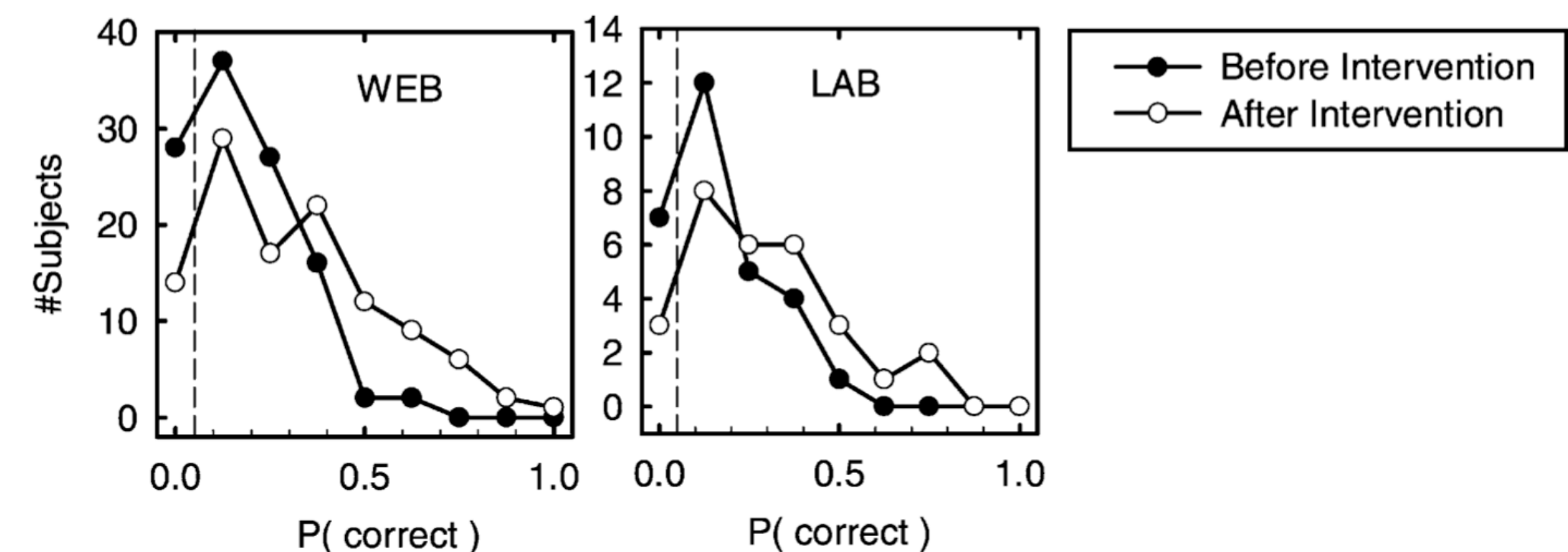
- Theory
 - Intervention has been deemed the hallmark of causality (e.g., Pearl, 2000; Woodward, 2003) in the sense that A causes B if and only if a sufficient intervention to change the state of A would also change B .



Causal learning from intervention

Motivation

- Empirical evidence
 - A common finding is that given just observational data, participants' inferences are strikingly suboptimal.
 - Lagnado and Sloman's (2004) Experiment 1, three variables, observing 50 trials of how events covaried -> 5 out of 36 participants identified the correct model
- Accuracy improvement before and after intervention (Steyvers et al., 2010)



Causal learning from *active* intervention

Descriptive model

- Complexity of the structure
 - Heuristics of updating the model
- Complexity of the space of intervention choices (active causal learning)
 - Heuristics of choosing interventions

Causal learning from *active* intervention

Descriptive model of intervention strategies

- Conservative & Forgetful (Bramley et al., 2014)
 - Prioritize interventions that maximize *information gain*, showing a preference for reducing overall uncertainty - $H^t(G) - H^t(G \mid D = \{\text{obs, interv}\})$
 - Forgetful but conservative
- Adaptive (Coenen et al., 2014)
 - Information gain + confirmation

Bramley, N. R., Lagnado, D. A., & Speekenbrink, M. (2015). Conservative forgetful scholars: How people learn causal structure through sequences of interventions. *Journal of Experimental Psychology: Learning, Memory, and Cognition*, 41(3), 708.

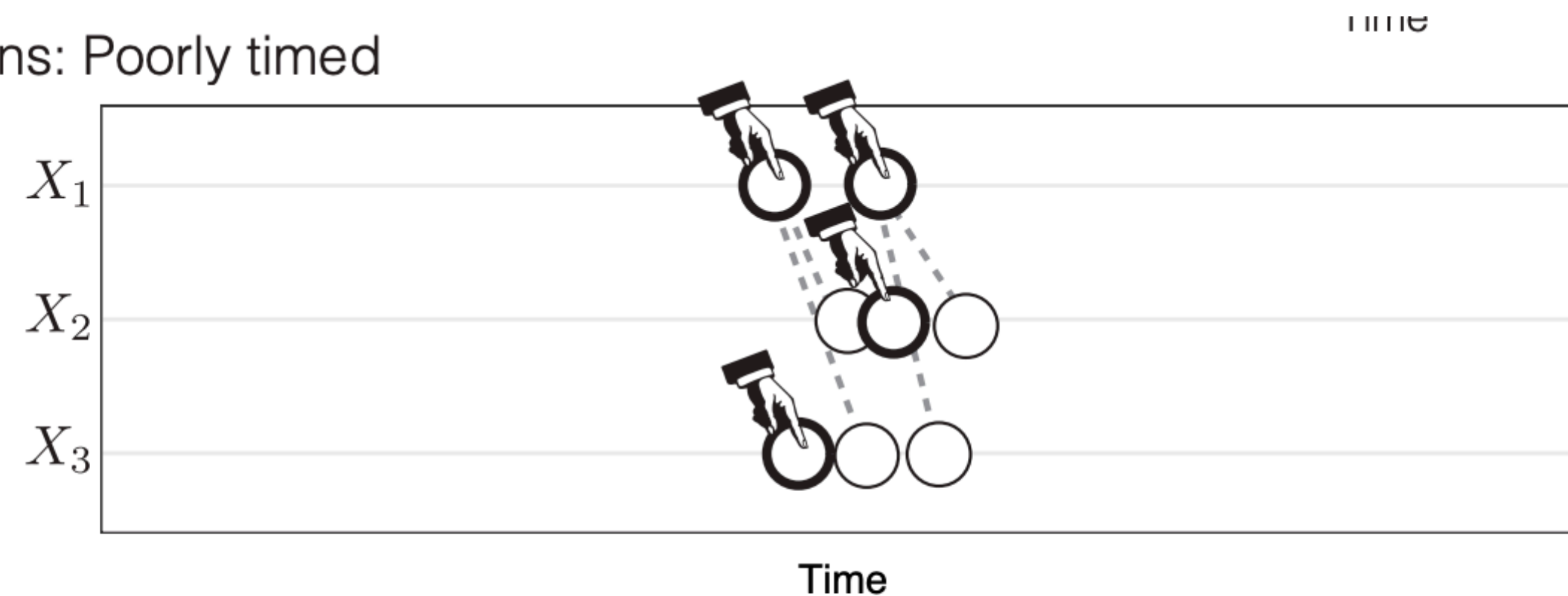
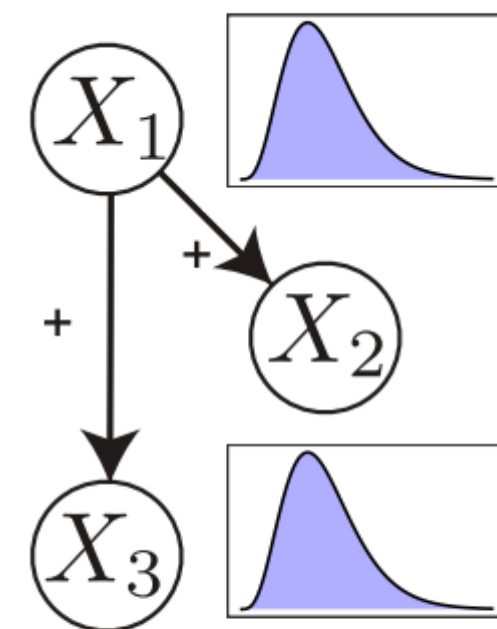
Coenen, A., Rehder, B., & Gureckis, T. M. (2015). Strategies to intervene on causal systems are adaptively selected. *Cognitive psychology*, 79, 102-133.

Causal learning from active intervention in continuous time

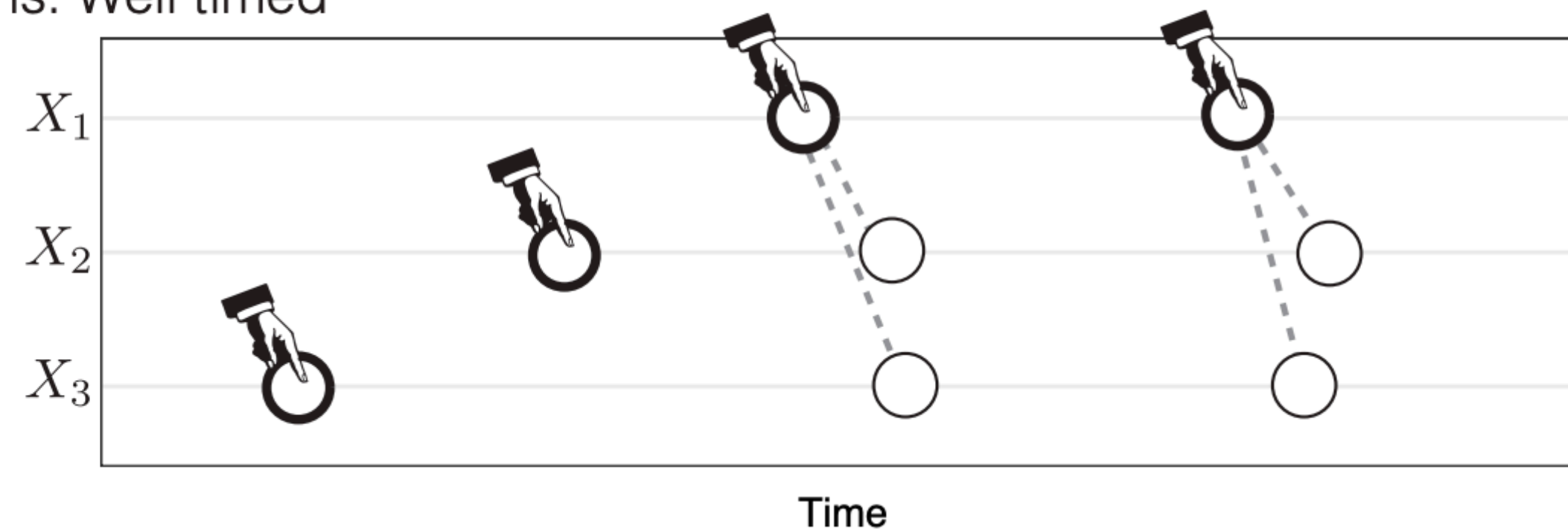
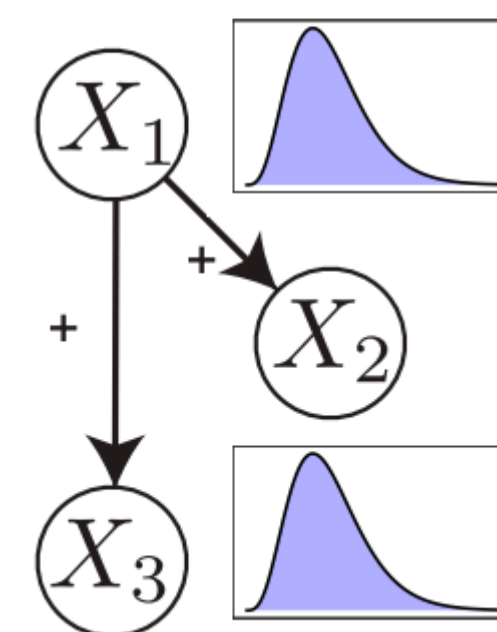
Motivation

- Choosing *where* to intervene -> choosing *when* and *where* to intervene

e) Freeform interventions: Poorly timed



f) Freeform interventions: Well timed



Motivation

Position of this work

- Descriptive model of causal learning (heuristics)
 - model updating and intervention selection
- Active, continuous time

Motivation of this work

- Existing works: algorithmic complexity of learning
 - It focused on identifying the key parameters of inference models which best match participants rather than on its interaction with prior knowledge
- This work: the integration of new data given pre-existing beliefs

Main

- In the present study, we investigate the inference mechanisms that people use to learn complex causal structures in continuous time, and how this learning is influenced by prior beliefs.

Hypothesis

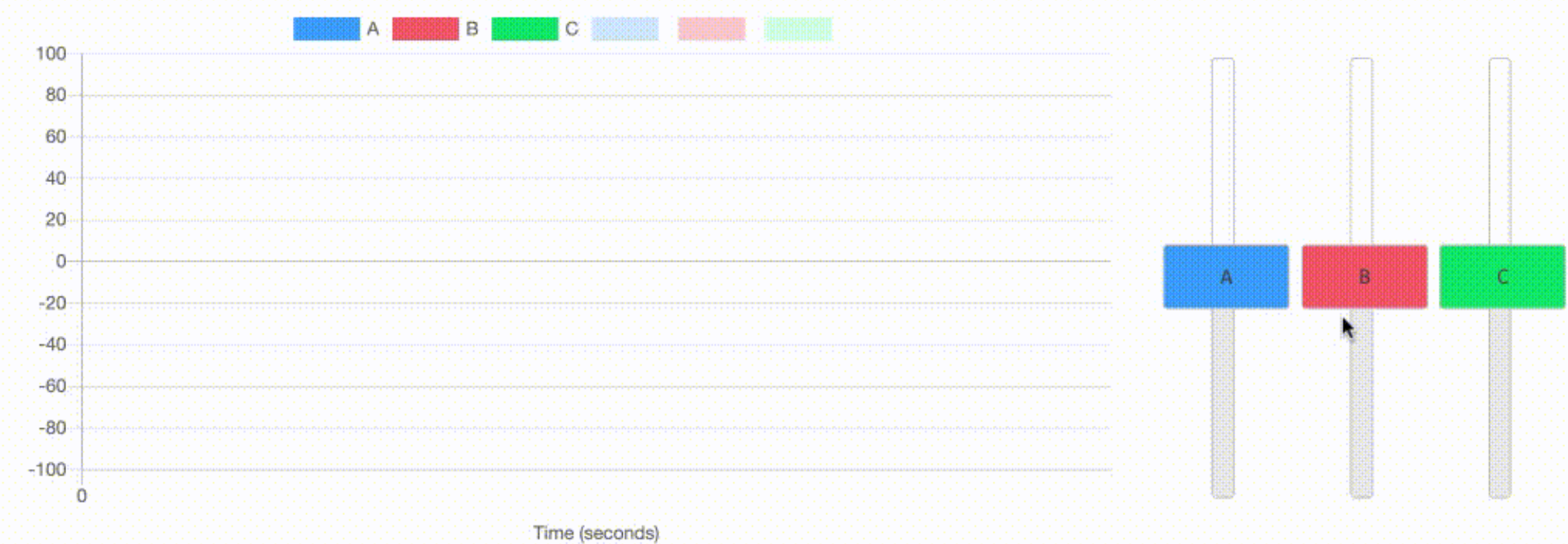
- We expect participants' judgements to be best captured by computational models that selectively consider data during or *at least around intervening times* and which focus *on the direct links from the intervened upon node*.
- We expect participants to be less accurate in domain-specific contexts when the *ground truth graph diverges from their prior judgements*. We propose two alternative but not exclusive mechanisms by which such a result may occur:
 1. Direct single dependence: participants' posterior beliefs are influenced by their prior beliefs solely by biasing the *inference process*
 2. Direct and action-mediated dependence: participants' posterior beliefs are influenced by their prior beliefs by affecting the entire *active learning process (inference and interventions)*.

Experiment and behavior results

Paradigm

Demo for *Less is more: Adaptive strategies in continuous time causal learning* (2023)

Press the Start button to launch the process, the Pause button freezes it and Reset scraps all data. Use the sliders on the right to make interventions. You can choose different causal structures using the drop down menu. You can use the table below to create your own graph, we recommend sticking to values between -1 and 1. The theta spinner changes the strength of the drift.



Start Pause Reset

Choose your causal model:
Causal Chain

Matrix Γ	A	B	C
A \rightarrow	\	1	0
B \rightarrow	0	\	1
C \rightarrow	0	0	\

Euler-Maruyama Approximation:

$$X_{t+1} = X_t + \theta(X_t^\top \Gamma - X_t)dt + \sigma dW_t$$

$$dt = 0.2 \quad \theta = 0.5$$

- 3 sliders represent 3 variables
- The values of the variables are computed according to Ornstein-Uhlenbeck processes

$$p(x_{t+dt} | x_t, y_t, \theta, \sigma, dt) = \mathcal{N}\left(x_t + \theta\left(\mu_x(x_t, y_t) - x_t\right)dt, \sigma dt\right)$$

$$\mu_x(x_t, y_t) = \beta(x_t) + \gamma_{xx}x_t + \gamma_{yx}y_t$$

Paradigm



Reminder of the rules:

- 0: no arrow from variable A to variable B means no effect of variable A on variable B
- 1: one positive arrow from A to B means that **MORE of A** results in **MORE of B**
- 2: two positive arrows from A to B means that **MORE of A** results in **a lot MORE of B**
- -1: one negative arrow from A to B means that **MORE of A** results in **LESS of B**
- -2: two negative arrows from A to B means that **MORE of A** results in **a lot LESS of B**

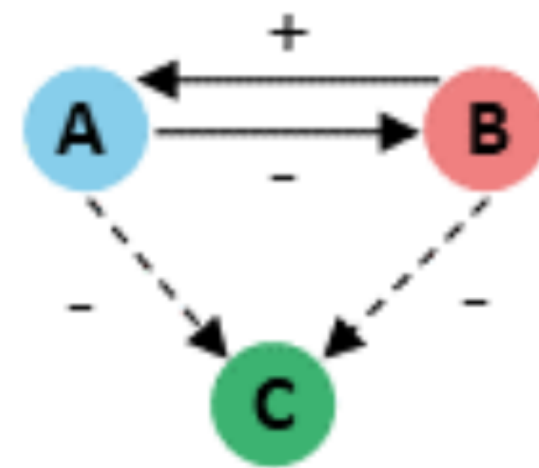


Experiment 1

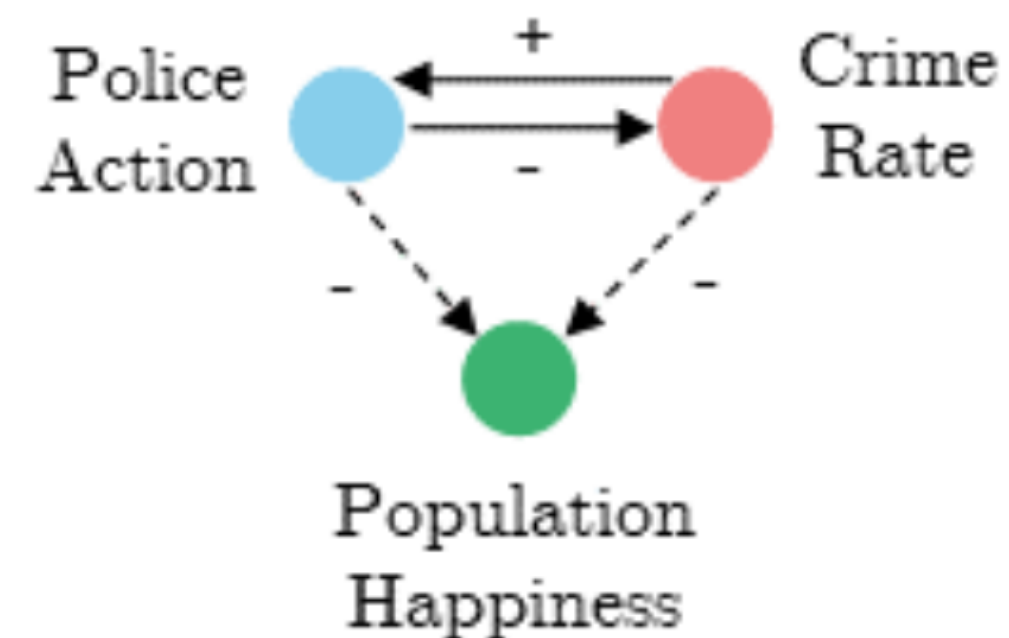
Impact of semantic labels

- Test whether participants would perform differently if the variables were
 - labelled meaningfully, i.e. crime rate, police action and population happiness,
 - or generically, i.e. blue, red and green.
- See if the agreement between elicited prior and ground truth graphs would predict participants' ability to recover the correct structure.

A. Generic condition graph



B. Label condition graph

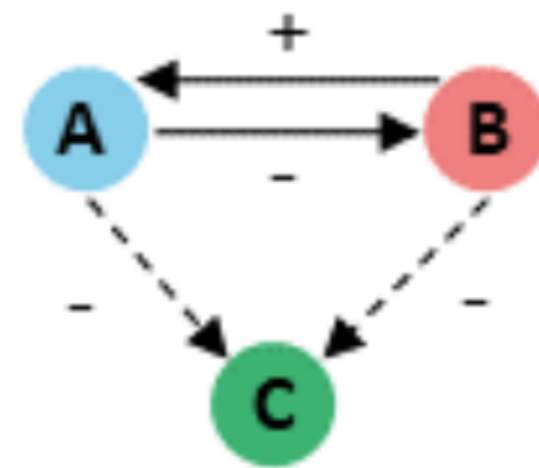


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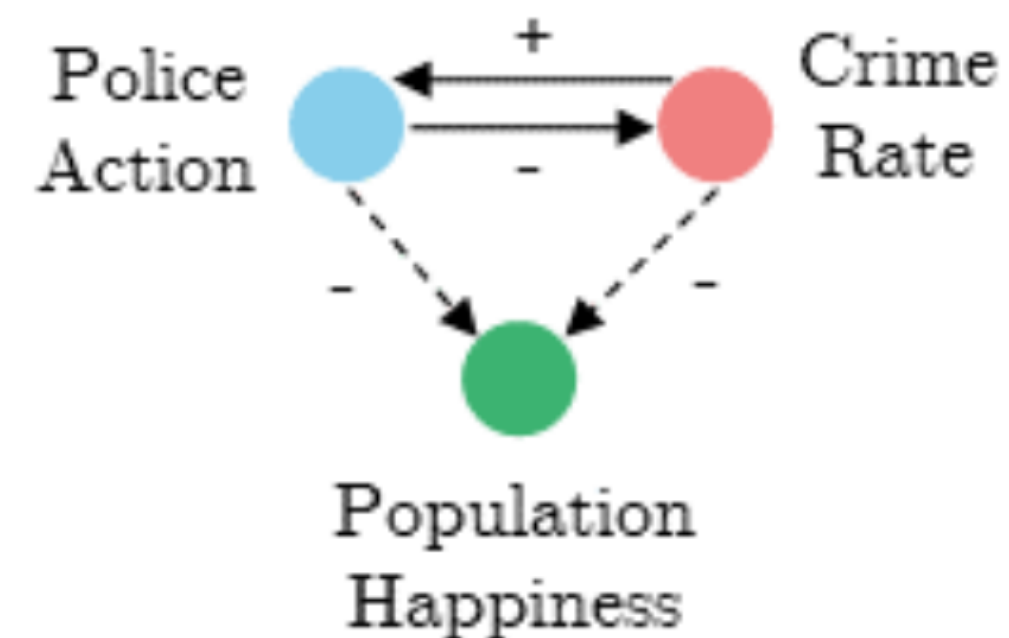
Impact of semantic labels

- Participants were randomly allocated to a *generic* or a *label* condition.
 - Label: crime rate, police action and population happiness
- 3 generic causal learning trials + 1 controlled trial.

A. Generic condition graph



B. Label condition graph



Experiment 1 results

Impact of semantic labels and prior

- **Correct Link Recovery:** accurately reported correct causal links 63% of the time, surpassing the chance level (33%)
 - **Difficulty with Link Strengths:** recovered weak (40%) vs. strong links (50%)
 - **Difficulty with Negative Links:** recovered positive links (87%) vs. negative links (73%)
- **Label Influence:** Labeling *did not* significantly impact overall accuracy, with meaningful (67%) vs. generic labels (66%)
- **Prior Influence:** Participants whose prior were closer to the ground truth were on average more accurate
- **Intervention Usage:** The average number of interventions was 7.18/trial with 3.38 (± 3.96) seconds
- **Structure Complexity:**
 - Participants performed better on simpler graphs (e.g., collider and common cause structures) with accuracies of 78% and 76%, respectively, versus 68% for complex chain graphs.
 - In complex chain graphs, participants often failed to recognize certain direct links and reported non-existent ones, showing difficulties with complex causal structures.

Experiment 2

Impact of ground truth-prior congruence

- Three scenarios:
 - Criminality: crime rate, police action and population happiness
 - Real estate: house prices, desirability and population density
 - Finance: virus cases, stock prices and lockdown measure
- Difficulty level - (inverse) similarity between ground truth and prior:
 - Congruent: [0.8, 0.9]
 - Incongruent: [0.45, 0.55]
 - Implausible: [0.05, 0.15]

Similarity between two graphs

$$\text{acc}(\gamma) = 1 - \frac{\| \gamma_{gt} - \gamma \|}{\| \gamma_{gt} - \gamma_* \|}$$

Ground truth γ_{gt} and estimated γ are 6-d vectors of the strength of each link

Furthest possible graph γ_* from γ_{gt}

Experiment 2

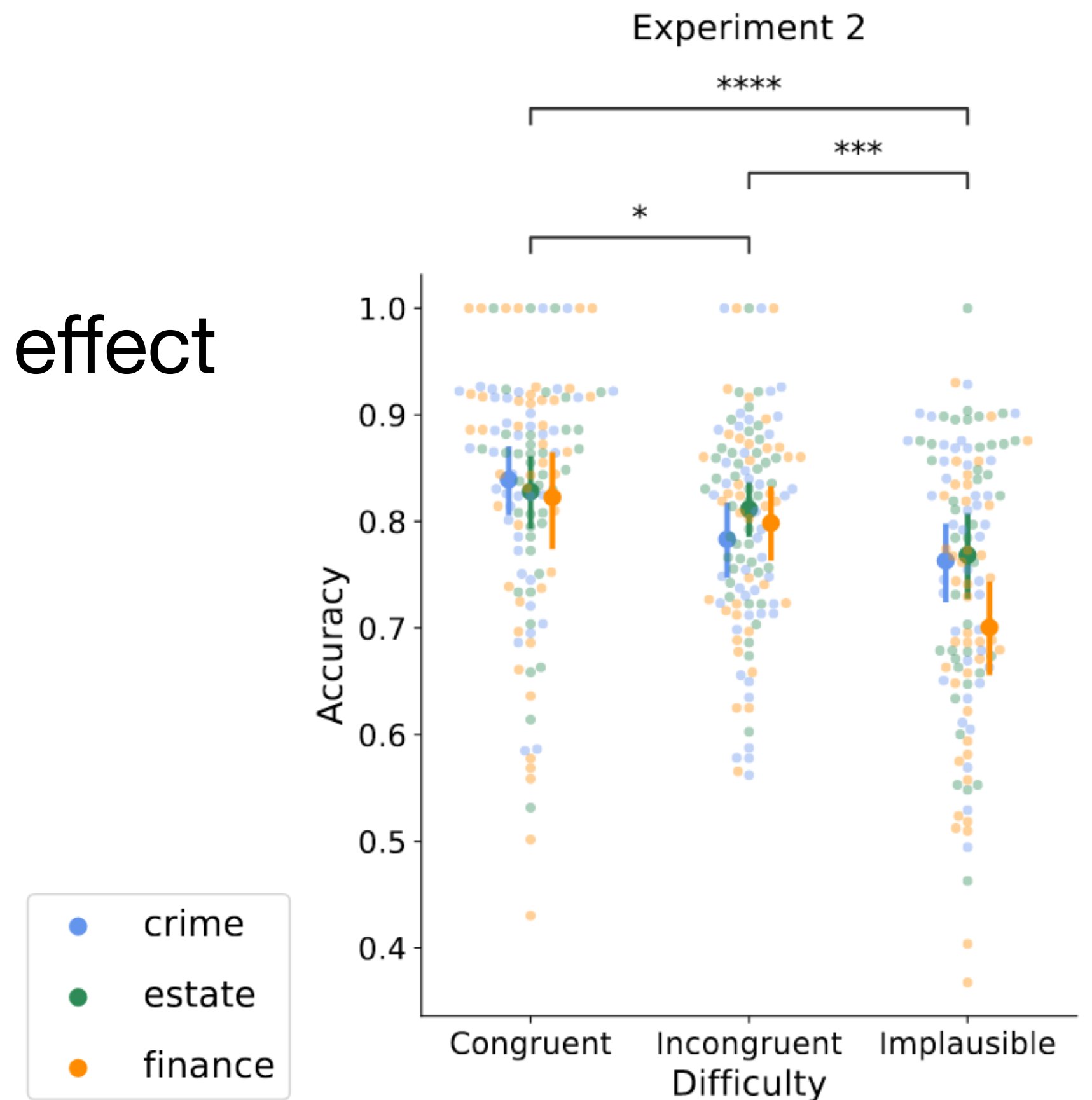
Impact of ground truth-prior congruence

- 1 simpler generic graph (chain, common cause or collider) + 3 labeled trials
 - Each participant sees exactly one of each scenario and one of each prior condition

Experiment 2 results

Impact of ground truth-prior congruence

- **Scenario Impact:** the finance scenario was more challenging
- **Difficulty Impact:** difficulty level had a significant effect on accuracy



Experiment 3 & 4

Impact of *constrained* ground truth-prior congruence

- Make the manipulation more aligned with how people actually reason about causality (focusing on link direction rather than abstract distance)
- Avoid unintended structural complexities, like indirect effects, which made some graphs harder to learn and confounded the previous results.

Experiment 3 & 4

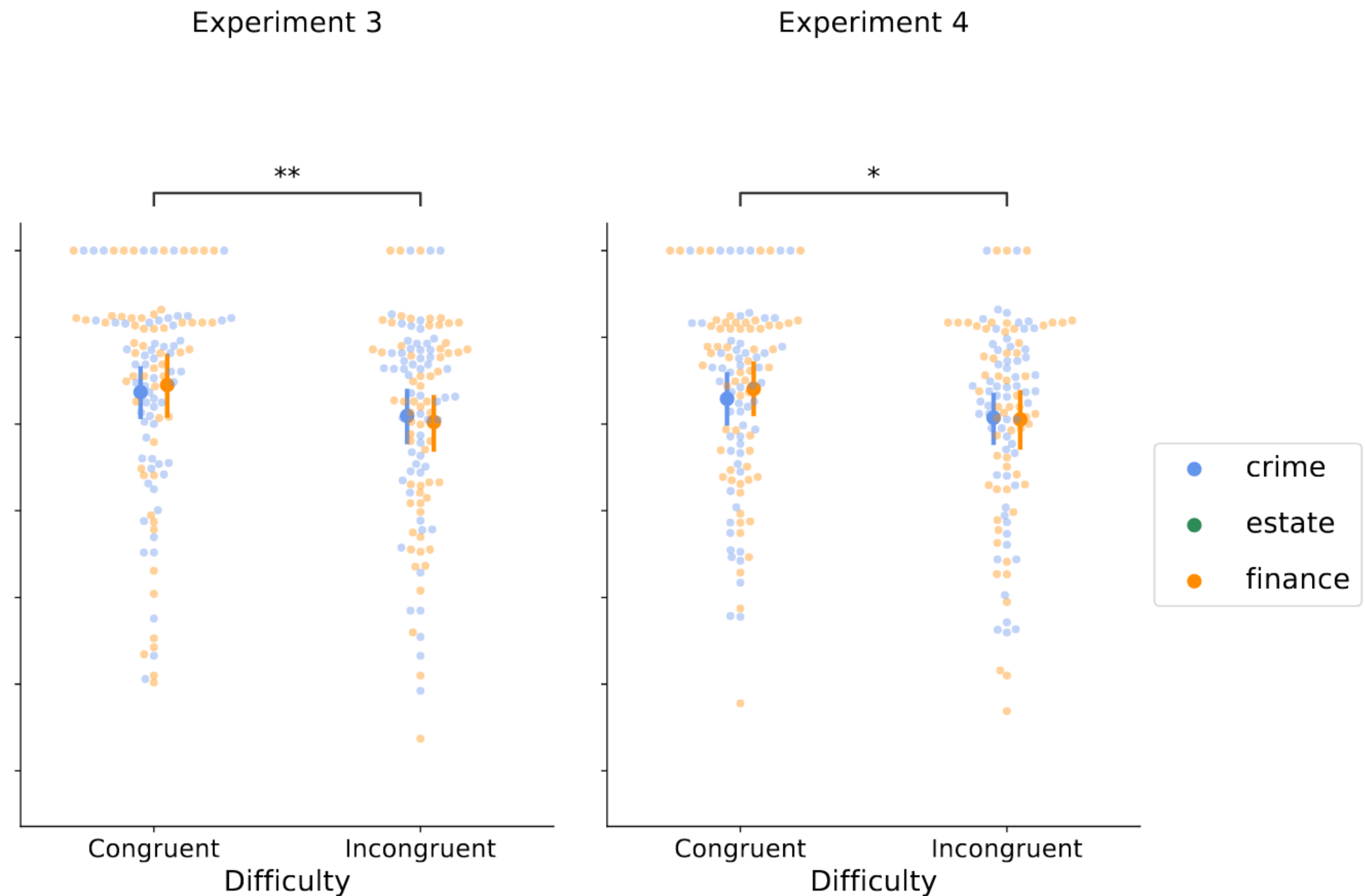
Impact of *constrained* ground truth-prior congruence

- Difficulty condition
 - Congruent: the ground truth is exactly the prior judgement.
 - Incongruent: the ground truth is the prior judgement graph but the direction of all links has been inverted, e.g. a chain $A \rightarrow B, B \rightarrow C$ is now $C \rightarrow B, B \rightarrow A$.
- As only two difficulty conditions are left, we dropped the estate scenario.

Experiment 3 results

Impact of *constrained* ground truth-prior congruence

- **Effect of Scenario:** no
- **Effect of Difficulty:** yes



Modeling

All comparison models

- Inference over
 - graph structure Γ ,
 - system parameter θ ,
 - noise σ ,
- Fit inverse temperature parameter τ
- Normative model: full inference $p(\Gamma, \theta, \sigma \mid X_{1:t})$
- Local computation: $\Gamma = \gamma_1 \cup \dots \cup \gamma_6 \mid X_{1:t}$
- Causal event abstraction

$$\text{Causal Event} = \begin{cases} 1, & \text{if } X \geq T_X \text{ and } Y \geq T_Y \\ 0, & \text{otherwise} \end{cases}$$
- Adaptive selective LC: temporal locality & link focus

$$p(x_{t+dt} \mid x_t, y_t, \theta, \sigma, dt) \\ = \mathcal{N}\left(x_t + \theta\left(\mu_x(x_t, y_t) - x_t\right) dt, \sigma dt\right)$$

$$\mu_x(x_t, y_t) = \beta(x_t) + \gamma_{xx}x_t + \gamma_{yx}y_t$$

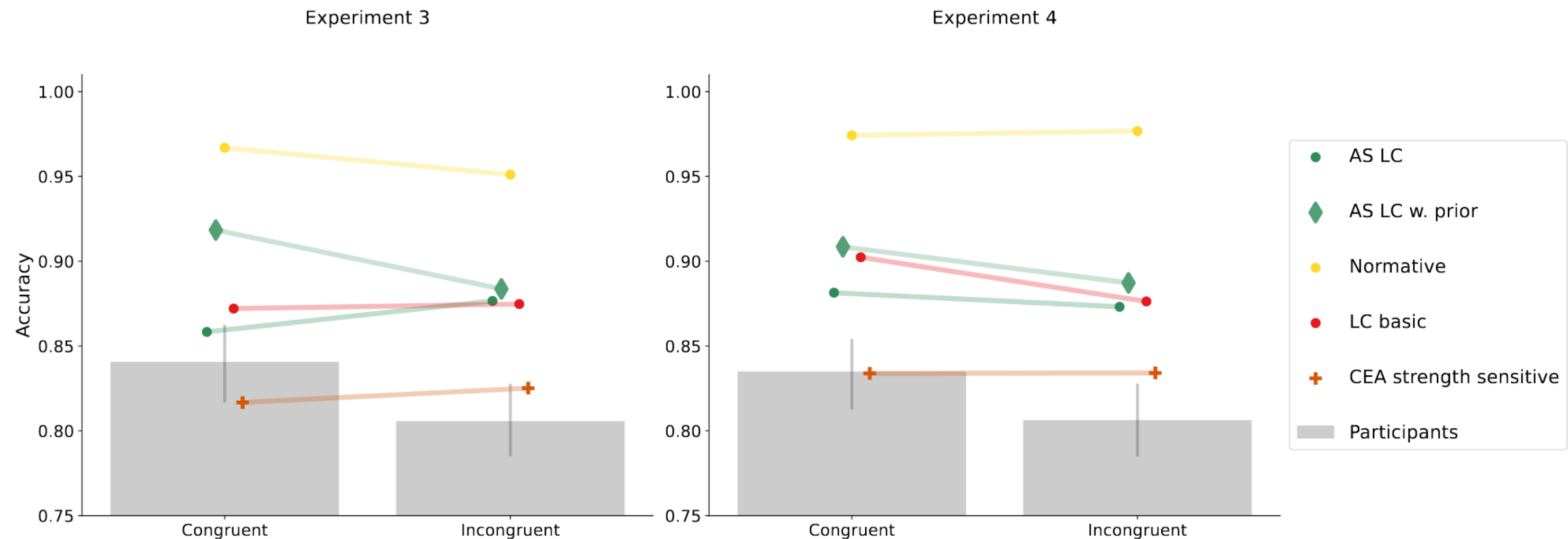
Model fitting results

- AS LC model provides a better fit than the Causal Event Abstraction (CEA) model both at individual and group levels.
- AS LC achieves similar or better performance than basic LC, even when only using data from interventions.
- Some participants showed a bias towards prior judgments, aligning with a model that has a non-flat prior distribution.

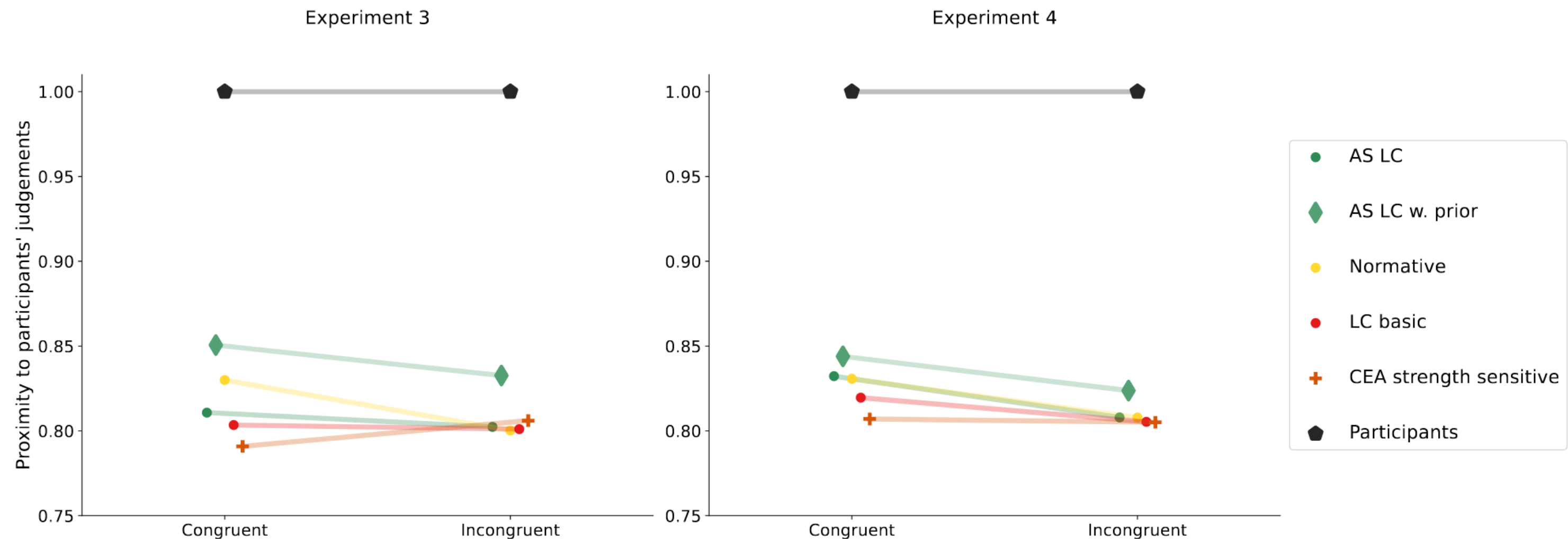
Model fitting results

- The AS LC model provided the best fit for participants' behavior at both group and individual levels.

A. Accuracies of key models in both conditions



B. Proximity of key models to participants' judgements



The prior shapes the inference process

- Participants were categorized based on whether their behavior was best fit by the Adaptive Selective LC (AS LC) model with a non-flat prior or with a flat prior (uniform).

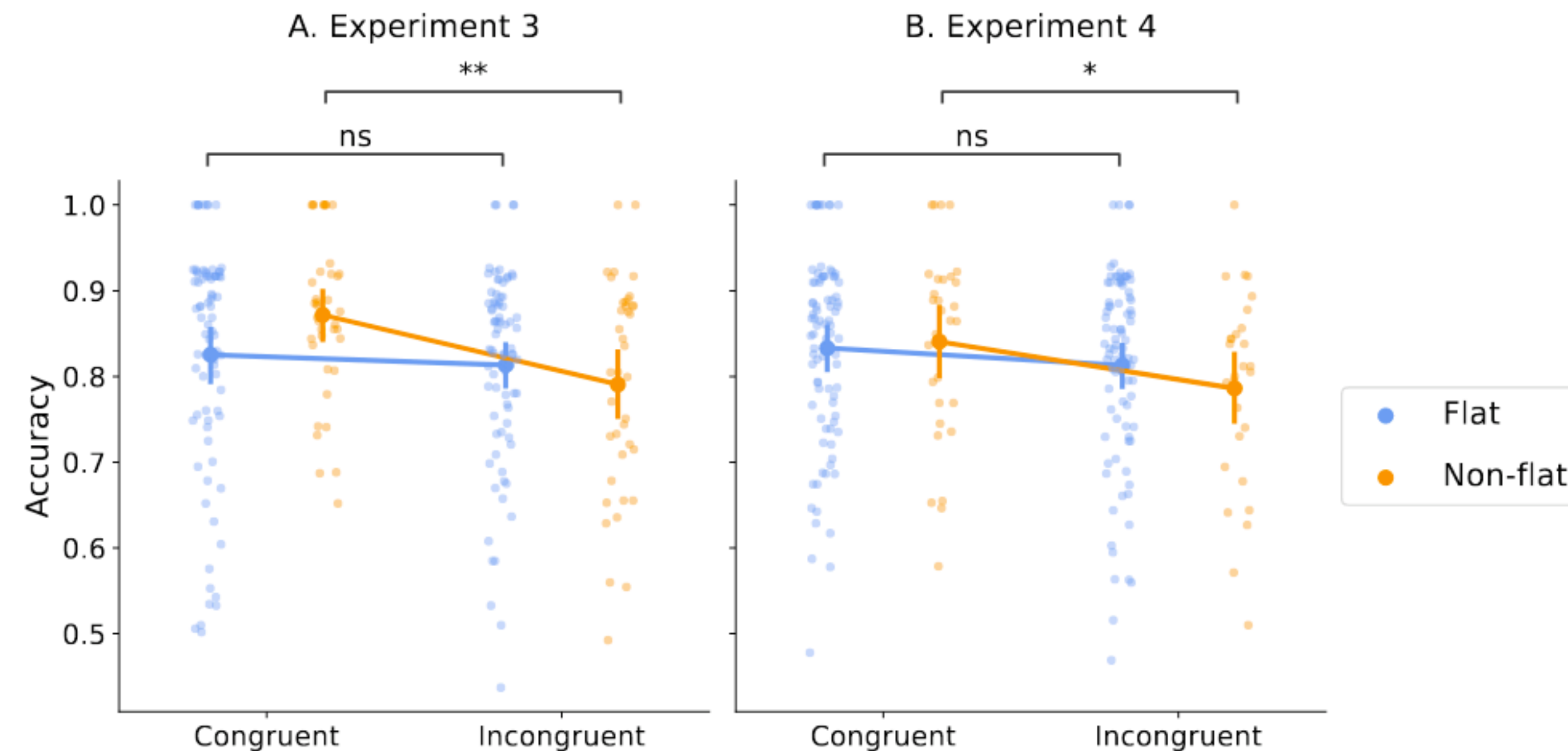
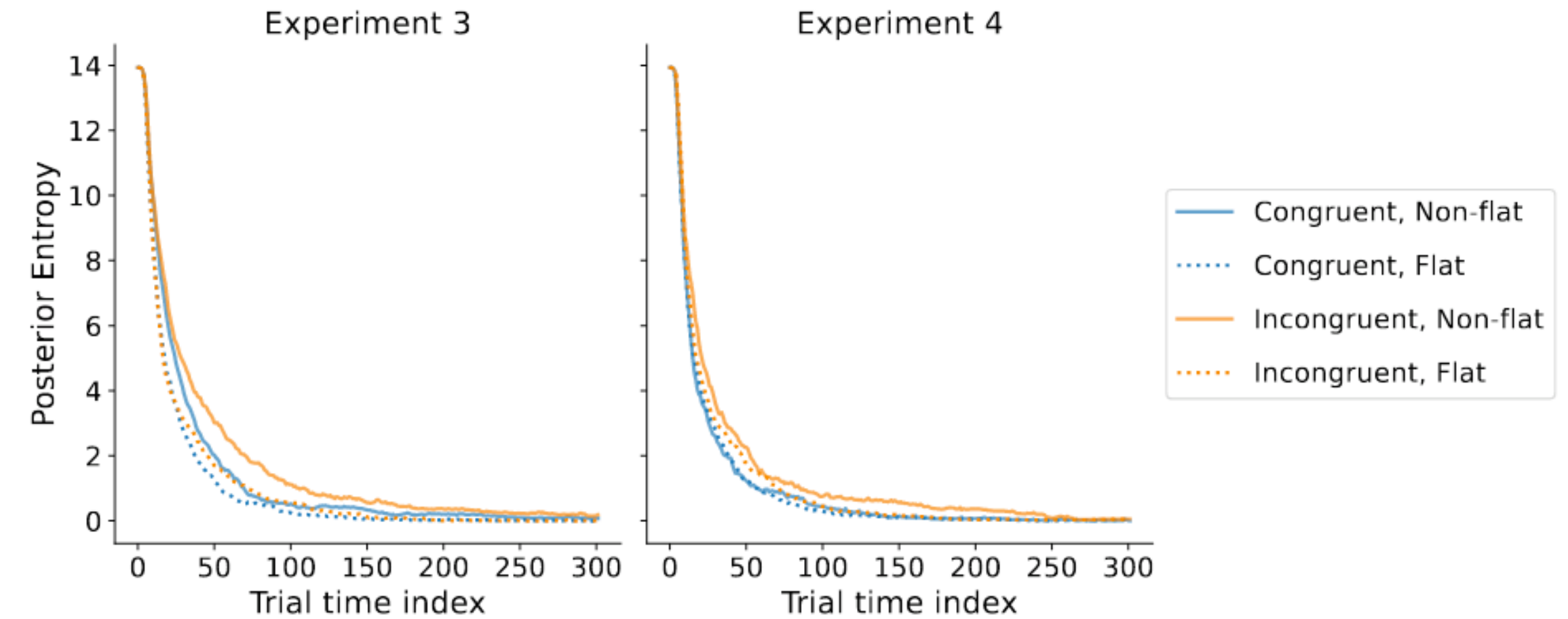


Figure 8: Mean differences in accuracy between condition for participants best fit by AD LC with a non-flat prior parameter and those best fit with assuming a flat prior and interactions with trial difficulty for experiment 3 and 4.

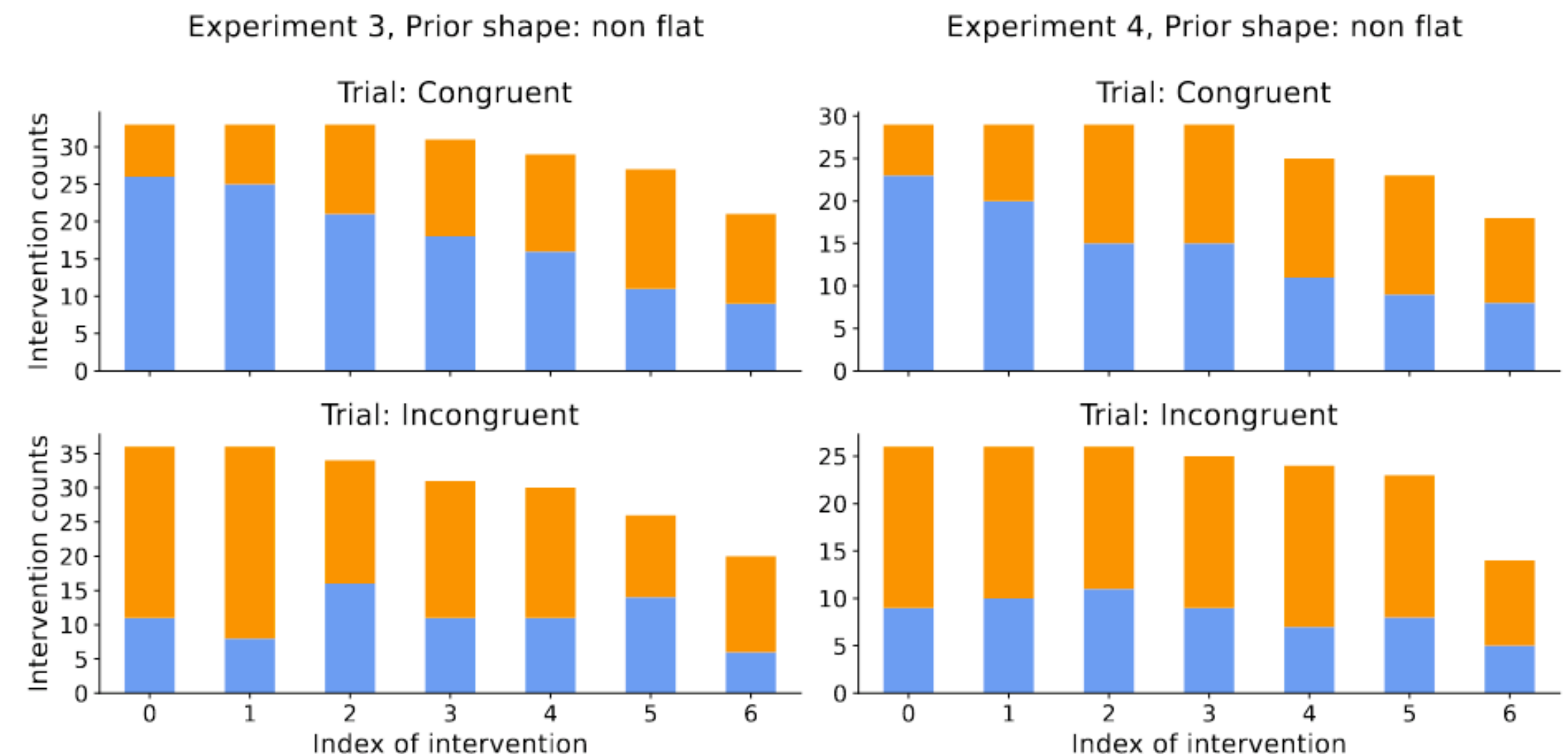
The prior shapes the intervention process

- Participants with a non-flat prior in incongruent trials
- Have higher posterior entropy in actions
- Favor interventions on the root node

A. Diagnosticity of interventions for participants best fit with a flat or non flat prior



B. Number of interventions performed on the root node of the prior graph for participants with non flat priors



Summary

Summary of findings

- Behaviour
 - Participants who relied on prior beliefs performed better when these beliefs aligned with the ground truth, reducing errors associated with chain bias (mistaking indirect effects as direct).
 - When the ground truth contradicted prior beliefs, participants' intervention policies were less diagnostic, leading to worse performance.
- Modeling
 - An adapted Local Computations (LC) model, which considers data only during and shortly after interventions, closely matched participant behavior.