# **HAlg Note**

## **Basic Knowledge**

**Lagrange's Theorem**: If  $H \subseteq G$  is a subgroup, then |H| divides |G|.

**I**: If *G* is finite, then  $g^{|G|} = e \forall g \in G$ . **II**: o(g) | |G| **III**: If |G| = p prime, *G* is cyclic.

Complement-wise Operations:  $\phi: V_1 \times V_2 \rightarrow V_1 \oplus V_2$  by  $\mathbf{l}: (\vec{v_1}, \vec{u_1}) + (\vec{v_2}, \vec{u_2}) := (\vec{v_1} + \vec{v_1}, \vec{u_1} + \vec{u_2})$ ,  $\lambda(\vec{v}, \vec{u}) := (\lambda \vec{v}, \lambda \vec{u})$  (ps: $V_1, V_2$  通过  $\phi$  定义的 map 所形成的 vector space 记作  $V_1 \oplus V_2$ )

**External Direct Sum**: 一个" 代数结构"(Vector Space), 定义为 set 是  $V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n$  且有一组运算法则 component-wise operations

**Projections**:  $pr_i: X_1 \times \cdots \times X_n \to X_i$  by  $(x_1, ..., x_n) \mapsto x_i$  **Canonical Injections**:  $in_i: X_i \to X_1 \times \cdots \times X_n$  by  $x \mapsto (0, ..., 0, x, 0, ..., 0)$ 

$$\begin{aligned} \textbf{Useful Way of Thinking Matrix:} & \ A_{n \times m} B_{m \times n} = A \begin{pmatrix} \mathbf{b}_{*1} & \mathbf{b}_{*2} & \cdots \mathbf{b}_{*n} \end{pmatrix} = \begin{pmatrix} A \mathbf{b}_{*1} & A \mathbf{b}_{*2} & \cdots A \mathbf{b}_{*n} \end{pmatrix} \\ & \ A_{n \times m} B_{m \times n} = \begin{pmatrix} \mathbf{a}_{1*}^T \\ \vdots \\ \mathbf{a}_{n*}^T \end{pmatrix} B = \begin{pmatrix} \mathbf{a}_{1*}^T B \\ \vdots \\ \mathbf{a}_{n*}^T B \end{pmatrix} \\ & A_{n \times m} = A_{n \times m} I_m \\ & = (A \vec{e_1} & A \vec{e_2} & \cdots & A \vec{e_n} \end{pmatrix} \\ & A_{n \times m} B_{m \times n} = \begin{pmatrix} \mathbf{a}_{*1} & \mathbf{a}_{*k} \mathbf{b}_{k*}^T \\ \vdots \\ \mathbf{b}_{m*}^T \end{pmatrix} = \sum_{k=1}^m \mathbf{a}_{*k} \mathbf{b}_{k*}^T \\ & \vdots \\ \mathbf{b}_{m*}^T \end{pmatrix}$$

## Summary

| Name     | <b>Group</b> ( <i>G</i> , *)   | Ring $(R, +, \cdot)$  | <b>Vector Space</b> $(F - V)$  | Module $(R - M)$  |
|----------|--|---|--|---|
| Def      | <b>Closure</b> : $g * h \in G$ $\forall g, h, k \in G$   | $(R, +)$ is abelian group with $0_R \forall a, b, c \in R$                                | $(V, \dotplus)$ is abelian group $\forall \vec{v}, \vec{w} \in V$  | $(M, \dot{+})$ is abelian group $\forall m_1, m_2 \in M$                                      |
|          | Associativity: $(g * h) * k = g * (h * k)$   | $(R,\cdot)$ is <b>monoid</b> with $1_R$ (monoid is closure)                               | $\exists \operatorname{map} F \times V \to V : (\lambda, \vec{v}) \to \lambda \vec{v} \qquad \forall \lambda, \mu \in F$         | $\exists \; \mathrm{map}  R \times M \to M : (r,m) \to rm \qquad \forall \; r_1, r_2 \in R$   |
|          | <b>Identity</b> : $\exists e \in G, e * g = g * e = g$   | i.e. <b>Associativity</b> : , $(a \cdot b) \cdot c = a \cdot (b \cdot c)$                 | $\mathbf{I}: \lambda(\vec{v} \dotplus \vec{w}) = (\lambda \vec{v}) \dotplus (\lambda \vec{w})$                                   | $\mathbf{I}: r(m_1 \dotplus m_2) = (\lambda m_1) \dotplus (\lambda m_2)$                      |
|          | Inverse: $\exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e$   | Identity: $1_R \cdot a = a \cdot 1_R = a$   | $\mathbf{II}: (\lambda + \mu)\vec{v} = (\lambda\vec{v}) \dotplus (\mu\vec{v})$   | $\mathbf{H}: (r_1 + r_2)m_1 = (r_1m_1) \dotplus (r_1m_1)$                                     |
|          |  | <b>Distributive</b> : $a \cdot (b + c) = a \cdot b + a \cdot c$                           | $\mathbf{III} : \lambda(\mu \vec{v}) = (\lambda \mu) \vec{v}$  | III: $r_1(r_2m_1) = (r_1r_2)m_1$  |
|          |  | $(b+c)\cdot a=b\cdot a+c\cdot a$  | $\mathbf{IV}: 1_F \vec{v} = \vec{v}$   | $IV: 1_R m_1 = m_1$   |
| Prop     | $I: (gh)^{-1} = h^{-1}g^{-1}$  | $\mathbf{I.}\ 0 \cdot a = a \cdot 0 = 0 \qquad \forall a, b \in R$                        | $\mathbf{I.} \ 0\vec{v} = 0 \ \text{and} \ \vec{0}\lambda = \vec{0} \qquad \forall \vec{v} \in V, \lambda \in F$                 | $I. 0_R m = 0_M ; r0_M = 0_M  \forall r \in R, m \in M$                                       |
|          |  | $II. (-a) \cdot b = a \cdot (-b) = -(a \cdot b)$  | $II. (-1)\vec{v} = -\vec{v}$   | II. (-r)m = r(-m) = -(rm)   |
|          |  | Commutative Ring: add $\forall a, b \in R, ab = ba$                                       | III. $\lambda \vec{v} = \vec{0} \Leftrightarrow \lambda = 0 \text{ or } \vec{v} = \vec{0} *$                                     |   |
| Remark   | $G, H \text{ groups} \Rightarrow G \times H \text{ also.}$   | For ring $R$ [ $1_R = 0_R \Leftrightarrow R = \{0\}$ ]                                    |  |   |
| e.g.     | Cyclic group; $GL_n$ ; $D_n$ ; $\mathbb Z$   | $Mat(n,F)$ ; $R[X]$ ; $\mathbb{Z}/m\mathbb{Z}$ ; $\mathbb{Z}$                             | $\mathbb{R}[x]_{\leq n}$ ; $Mat(n,F)$ ; $Hom(V,W)$   | $R=\mathbb{Z}$ Abelian Group; $R=F$ Vector Space  |
| Sub      | <b>Subgroup (H)</b> : $\forall h_1, h_2 \in H$   | Subring $(R')$ : $\forall a,b \in R'$   | <b>Subspace (U)</b> : $\forall \vec{v}, \vec{u} \in U, \lambda, \mu \in F$   | <b>Submodule (M')</b> : $\forall m_1, m_2 \in M'$   |
| objects  | I: <i>H</i> ≠ Ø;   | I. $1_R \in R'$   | <b>I</b> . 0 ∈ <i>U</i>  | $\mathbf{I.} \ \mathbf{0_M} \in M' \qquad \forall r_1, r_2 \in R$                             |
|          | $\mathbf{II}: h_1 * h_2 \in H;$  | II. $a - b \in R'$  | II. $\vec{u} + \vec{v} \in U$ and $\lambda \vec{u} \in U$  | II. $m_1 - m_2 \in M'$ and $r_1 m_1 \in M'$   |
|          | $III: h_1^{-1} \in H.$   | III. $ab \in R'$  | (or: $\lambda \vec{u} + \mu \vec{v} \in U$ )   | (or: $r_1 m_1 - r_2 m_2 \in M'$ )   |
| Create   | $H, K$ subgroups $\Rightarrow H \cap K$ also.  | $R, S \text{ subring} \Rightarrow R \cap S \text{ also.}$                                 | $V, W \text{ subspaces} \Rightarrow V \cap W, V + W \text{ also.}$   | $M, N$ submodules $\Rightarrow M \cap N, M + N$ also.   |
| Generate | Generated Group $\langle T \rangle$ :  | Generated Ideal $_R\langle T\rangle$ : R is commutative ring                              | Generated subspaces (T):   | Generated submodules $_R\langle T\rangle$   |
| objects  | $\langle T \rangle := \{ g_1^{a_1} \dots g_k^{a_k}   k \in \mathbb{N}, g_i \in T, a_i \in \mathbb{N} \}$ | $_R\langle T\rangle := \{\sum_{i=1}^n r_i t_i : n \in \mathbb{N}, r_i \in R, t_i \in T\}$ | $\langle T \rangle := \{ \alpha_1 \vec{v_1} + \dots + \alpha_n \vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, n \in \mathbb{N} \}$ | $\langle T \rangle := \{ r_1 t_1 + \dots + r t_n : r_i \in R, t_i \in T, n \in \mathbb{N} \}$ |
| Special  | <b>Cyclic Group</b> : $\langle g \rangle = \{g^k   k \in \mathbb{Z}\}$                                   | <b>Principal Ideal</b> : $_R\langle a\rangle$ i.e. $aR$                                   | $\langle \emptyset \rangle := \{\vec{0}\}$   | Cyclic submodule: If $M =_R \langle t \rangle$  |
| Prop     |  | $\langle T \rangle$ is the smallest the {generated things} con                            | taining $T$ . ps: $\mathbb{X} \ ^2T \subseteq \mathbb{R}  ^4T \subseteq M$   |   |
| Homo     | Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$   | $f: R \to S \text{ hom}: \forall a, b \in R$  | $f:V\to W \qquad \qquad \forall \vec{v}_1,\vec{v}_2\in V,\lambda\in F$   | <b>R-Hom</b> : $f: M \to N \qquad \forall a, b \in M, r \in R$                                |
|          | I. $\phi(g_1 * g_2) = \phi(g_1) * \phi(g_2)$   | $\mathbf{I}. f(a+b) = f(a) + f(b)$  | I. $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$  | I. f(a+b) = f(a) + f(b)   |
|          |  | $\mathbf{II}.f(ab) = f(a)f(b)$  | $\mathbf{II.}f(\lambda\vec{v}_1) = \lambda f(\vec{v}_1)$   | $\mathbf{II}.f(ra)=rf(a)$   |
| Prop A   | $\mathbf{I}: \phi(e_G) = e_H$  | $\mathbf{I}. f(0_R) = 0_S \qquad f(1_R) = 1_S \text{ NOT need}$                           | $\mathbf{I}.f(\vec{0}) = \vec{0}$  | $I. f(0_M) = 0_N \qquad f(1_R) = 1_S \text{ NOT need}$  |
|          | $\mathbf{II}: \phi(g^{-1}) = \phi(g)^{-1}$   | II. f(x - y) = f(x) - f(y)  | $\mathbf{II.} f(\lambda \vec{v} + \mu \vec{u}) = \lambda f(\vec{v}) + \mu f(\vec{u})$  | $\mathbf{II}.f(a-b)=f(a)-f(b)$  |
|          |  | III. $f(a^n) = (f(a))^n$ $f(mx) = mf(x)$  | III. $f \circ g$ is linear map.  |   |
|          | <b>III.</b> $\phi$ is 1-1 $\Leftrightarrow$ ker $\phi = \{e_G\}$   | Iv. $f$ is 1-1 $\Leftrightarrow \ker f = \{0_R\}$   | <b>IV</b> . $f$ is 1-1 iff ker $f = {\vec{0}}$   | <b>III.</b> $f$ is 1-1 iff ker $f = \{0\}$  |
| Ker/Im   | <b>I</b> . $Im(\phi)$ subgroup $\ker(\phi) \lhd G$ normal.   | I. $Im(f)$ subring. $ker(f) \le R$ ideal.   | I. $ker(f)$ ; $Im(f)$ are subspaces.   | I.ker f, Imf are submodules.  |
|          | <b>II</b> . $K \subseteq G$ is subgroup $\Rightarrow \phi(K) \subseteq H$ also.                          | II. $R' \subseteq R$ is subring $\Rightarrow f(R')$ also.                                 | II. Rank-Nullity Theorem   |   |
|          | III. $Ker(\phi)$ subgroup.   |   |  |   |
| Remark   | I I I I I I I I I I I I I I I I I I I  | m(End): = LM & $V = W$ . Automorphism(A   | 1) I O. I. I. I. M   | 11044 P. 1. 1100 .  |

**Normal**  $(H \triangleleft G)$ :  $H \subseteq G$  is normal if:  $\forall g \in G$ , gH = Hg

**Property:** I:  $Ker\phi \lhd G$  II:  $\phi$  is  $1-1 \Rightarrow G \cong im\phi$ 

**Ideal**  $(I \subseteq R)$ : A subset  $I \subseteq R$  (ring) is an ideal if:  $I.I \neq \emptyset$   $II. \forall a, b \in I, a - b \in I$   $III. \forall i \in I, \forall r \in R, ri, ir \in I$  e.g.  $m\mathbb{Z}$ **Property**: If I, I are *ideals* of R. Then I + I;  $I \cap I$  are also ideals.

**Field** (F): A set F is a field with two operators: (addition)  $+: F \times F \to F$ ; ( $\lambda, \mu$ )  $\to \lambda + \mu$  (multiplication)  $: F \times F \to F$ ; ( $\lambda, \mu$ )  $\to \lambda \mu$  if: (F,+) and  $(F\setminus\{0_F\},\cdot)$  are abelian groups with identity  $0_F,1_F$ . and  $\lambda(\mu+\nu)=\lambda\mu+\lambda\nu$   $e.g.Fields:\mathbb{R},\mathbb{C},\mathbb{Q},\mathbb{Z}/p\mathbb{Z}=\mathbb{F}_p$ **Field**: For a ring R: Commutative ring + R has multiplicative inverse = Field.

# **Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis**

**Linearly Independent**:  $L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\}$  is linearly independent if:  $\forall c_1, ..., c_r \in F$ ,  $c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0$ .

• Connect to Matrix: Let  $L = \{\vec{v_1}, ..., \vec{v_n}\}$ , L is LI of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} \in F^n$ ,  $A\vec{x} = 0$  (or  $\vec{0}$ )  $\Rightarrow \vec{x} = 0$ (or  $\vec{0}$ ) (i.e. linear map  $\phi: \vec{x} \mapsto A\vec{x}$  is injective)

**Basis & Dimension**: If V is finitely generated.  $\Rightarrow \exists$  subset  $B \subseteq V$  which is both LI and GS. (B is basis) **Dim**: dim V := |B|

• Connect to Matrix: Let  $B = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T$  s.t.  $\phi : \vec{x} \mapsto A\vec{x}$  is 1-1 & onto (Bijection)

**Relation**[GS,LI,Basis,dim: Let V be vector space. L is linearly independent set, E is generating set, B is basis set.

- 1. **GS|LI**:  $|L| \le |E|$  (can get: dim unique) **LI**  $\to$  **Basis**: If V finite generate  $\Rightarrow \forall L$  can extend to a basis. If  $L = \emptyset$ , prove  $\exists B$  $kerf \cap imf = \{0\}$
- 2. **Basis**|max,min:  $B \Leftrightarrow B$  is minimal GS  $(E) \Leftrightarrow B$  is maximal LI (L). **Uniqueness**|Basis: 每个元素都可以由 basis 唯一表示.
- 3. **Proper Subspaces**: If  $U \subset V$  is proper subspace, then  $\dim U < \dim V$ .  $\Rightarrow$  If  $U \subseteq V$  is subspace and  $\dim U = \dim V$ , then U = V.
- 4. **Dimension Theorem**: If  $U, W \subseteq V$  are subspaces of V, then  $\dim(U + W) = \dim U + \dim W \dim(U \cap W)$

**Complementary**:  $U, W \subseteq V, U, V$  subspaces are complementary  $(V = U \oplus W)$  if:  $\exists \phi : U \times W \to V$  by  $(\vec{u}, \vec{w}) \to \vec{u} + \vec{w}$  is isom.

i.e.  $\forall \vec{v} \in V$ , we have unique  $\vec{u} \in U$ ,  $\vec{w} \in W$  s.t.  $\vec{v} = \vec{u} + \vec{w}$ . ps: It's a linear map.

**Criteria Lemma**: If U, W are subspace of V, then  $V = U \oplus W \Leftrightarrow V = U + W$  and  $U \cap W = \{0\}$ . (需要证明)

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## 4 Linear Mapping | Rank-Nullity | Matrices | Change of Basis ps: 默认 V, W F-Vector Spaces

### 4.1 Linear Mapping | Rank-Nullity

**Property of Linear Map**: Let  $f, g \in Hom$ 

- 1. **Determined**: f is determined by  $f(\vec{b_i})$ ,  $\vec{b_i} \in \mathcal{B}_{basis}$  (\* i.e.  $f(\sum_i \lambda_i \vec{v_i}) := \sum_i \lambda_i f(\vec{v_i})$ )
- 2. **Classification of Vector Spaces**: dim  $V = n \Leftrightarrow f : F^n \stackrel{\sim}{\to} V$  by  $f(\lambda_1, ..., \lambda_n) \mapsto \sum_{i=1}^n \lambda_i \vec{v_i}$  is isomorphism.
- 3. **Left/Right Inverse**: f is  $1-1 \Rightarrow \exists$  left inverse g s.t.  $g \circ f = id$  考虑 direct sum f is onto  $\Rightarrow \exists$  right inverse g s.t.  $f \circ g = id$
- 4.  $^{\ominus}$  More of Left/Right Inverse:  $f \circ g = id \Rightarrow g$  is 1-1 and f is onto. 使用 kernel=0 来证明

**Rank-Nullity Theorem**: For linear map  $f: V \to W$ , dim  $V = \dim(\ker f) + \dim(Imf)$  Following are properties:

- 1. **Injection**: f is  $1-1 \Rightarrow \dim V \le \dim W$  **Surjection**: f is onto  $\Rightarrow \dim V \ge \dim W$  Moreover,  $\dim W = \dim imf$  iff f is onto.
- 2. **Same Dimension**: f is isomorphism  $\Rightarrow$  dim  $V = \dim W$  **Matrix**:  $\forall M$ , column rank  $c(M) = \operatorname{row} \operatorname{rank} r(M)$ .
- 3. **Relation**: If V, W finite generate, and dim  $V = \dim W$ , Then: f is isomorphism  $\Leftrightarrow f$  is 1-1  $\Leftrightarrow f$  is onto.

#### 4.2 Matrices | Change of Basis | Similar Matrices | Trace

**Matrix**: For  $A_{n\times m}$ ,  $B_{m\times p}$ ,  $AB_{n\times p}:=(AB)_{ij}=\sum_{k=1}^m a_{ik}b_{kj}$  **Transpose**:  $A_{m\times n}^T:=(A^T)_{ij}=a_{ji}$ 

**Invertible Matrices**: A is invertible if  $\exists B, C$  s.t. BA = I and AC = I ||  $\exists B, BA = I \Leftrightarrow \exists C, AC = I \Leftrightarrow \exists A^{-1}$   $_{\mathcal{B}}[f^{-1}]_{\mathcal{A}} =_{\mathcal{A}}[f]_{\mathcal{B}}^{-1}$ 

**Representing matrix of linear map**  $_{\mathcal{B}}[f]_{\mathcal{A}}: f: V \to W$  be linear map,  $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of  $V, \mathcal{B} = \{\vec{w_1}, ..., \vec{w_m}\}$  is basis of W.

- 1.  $_{\mathcal{B}}[f]_{\mathcal{A}} := A \text{ (matrix) where } f(\vec{v}_i) = \sum_i A_{ii} \vec{w}_i \qquad \exists M_{\mathcal{B}}^{\mathcal{A}} : Hom_F(V, W) \xrightarrow{\sim} Mat(n \times m; F)$
- 2. If  $\vec{v} \in V$ , then  $_{\mathcal{A}}[\vec{v}] := \mathbf{b}$  (vector) where  $\vec{v} = \sum_i b_i \vec{v_i}$
- 3. Theorems:  $[f \circ g] = [f] \circ [g]$   $_{\mathcal{C}}[f \circ g]_{\mathcal{A}} =_{\mathcal{C}} [f]_{\mathcal{B}} \circ_{\mathcal{B}} [g]_{\mathcal{A}}$   $_{\mathcal{B}}[f(\vec{v})] =_{\mathcal{B}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [\vec{v}]$   $_{\mathcal{A}}[f]_{\mathcal{A}} = I \Leftrightarrow f = id$
- 4. Change of Basis: Define Change of Basis Matrix:= $_{\mathcal{A}}[id_V]_{\mathcal{B}}$   $_{\mathcal{B}'}[f]_{\mathcal{A}'}=_{\mathcal{B}'}[id_W]_{\mathcal{B}}\circ_{\mathcal{B}}[f]_{\mathcal{A}\circ_{\mathcal{A}}}[id_V]_{\mathcal{A}'}$   $_{\mathcal{A}'}[f]_{\mathcal{A}'}=_{\mathcal{A}}[id_V]_{\mathcal{A}'}$   $_{\mathcal{A}'}[f]_{\mathcal{A}\circ_{\mathcal{A}}}[id_V]_{\mathcal{A}'}$  Elementary Matrix:  $I+\lambda E_{ij}$  (cannot  $I-E_{ii}$ ) 就是初等矩阵, 左乘代表 j 行乘  $\lambda$  倍加到第 i 行,右乘代表 j 列乘  $\lambda$  倍加到第 i 列  $\rightarrow$  Invertible!
- 1. 交换 i,j 列/行:  $P_{ij} = diag(1,...,1,-1,1,...,1)(I+E_{ij})(I-E_{ji})(I+E_{ij})$  where -1 in jth place.
- 2. Row Echelon Form|Smith Normal Form: A: REF 通过左乘初等矩阵可以实现 A: S(n, m, r) 通过  $\tilde{A}$  右乘初等矩阵可以实现

Smith Normal Form:  $\forall A$ ,  $\exists$  invertible P, Q s.t.  $PAQ = S(n, m, r) := n \times m$  的矩阵, 对角线前 r 个是 1, 后面 0. Lemma: r = r(A) = c(A)

· Every linear map  $f: V \to W$  can be representing by  $_{\mathcal{B}}[f]_{\mathcal{A}} = S(n, m, r)$  for some basis  $\mathcal{A}, \mathcal{B}$  of V, W.

**Similar Matrices**:  $N = T^{-1}MT \Leftrightarrow M$ , N are similar. Special Case: If  $N =_{\mathcal{B}} [f]_{\mathcal{B}}$ ,  $M =_{\mathcal{A}} [f]_{\mathcal{A}}$ , then  $N = T^{-1}MT$ . where  $T =_{\mathcal{A}} [id_V]_{\mathcal{B}}$ 

- 1. If  $A \sim B$  iff A is similar to B, then  $\sim$  is an equivalence relation.  $A'[f]_{A'} \sim_{A} [f]_{A}$
- 2. If  $\mathcal{B} = \{p(\vec{v_1}), ..., p(\vec{v_n})\}$  and  $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$  where  $p: V \xrightarrow{\sim} V$ . Then  $\mathcal{A}[id_V]_{\mathcal{B}} =_{\mathcal{A}} [p]_{\mathcal{A}}$
- 3. If *V* is a vector space over *F*, [*A*, *B* are *similar* matrices.  $\Leftrightarrow A =_{\mathcal{A}} [f]_{\mathcal{A}}, B =_{\mathcal{B}} [f]_{\mathcal{B}}$  for some basis  $\mathcal{A}, \mathcal{B}; f : V \to V$ ]

**Trace**:  $tr(A) := \sum_i a_{ii}$  and  $tr(f) := tr(A[f]_A) \mid tr(AB) = tr(BA) \quad tr(\lambda A + \mu B) = \lambda tr(A) + \mu tr(B) \quad tr(N) = tr(M)$  if M, N similar.

# 5 Rings | Polynomials | Ideals | Subrings

#### 5.1 Rings | Polynomial Rings

**2nd Def of Ring Homomorphism**: f is ring homomorphism if: 1. f:  $(R, +) \rightarrow (S, +)$  is group homomorphism and 2. f(xy) = f(x)f(y).

**Unit**:  $a \in R$  is unit if it's *Invertible*. i.e.  $\exists a^{-1} \in R$  s.t.  $aa^{-1} = a^{-1}a = 1_R$  **Group of Unit**  $(R^{\times}, \cdot) := \{a \in R : a \text{ is unit}\}$ 

· **Lemma**: If  ${}^1f: R \to S$  homo,  ${}^2f(1_R) = 1_S$ ,  ${}^3x$  is unit of R.  $\Rightarrow {}^1f(x)$  is unit of S.  ${}^2f|_{R^\times}: R^\times \to S^\times$  is group homomorphism.

**Zero-divisors**:  $a \in R$  is zero-divisor if  $\exists b \in R, b \neq 0$  s.t. ab = 0 or ba = 0 Field has no zero-divisors. • e.g.  $\mathbb{Z}^{\times} = \{-1, 1\}$ ;  $1_R$  is a unit.

**Integral Domain**: A *commutative* ring R is an integral domain if it has no zero-divisors. e.g.  $\mathbb{Z}/p\mathbb{Z}, \mathbb{R}, \mathbb{Q}, \mathbb{Z}, ...$ 

**Properties of Integral Domain**:  $\forall a, b \in R$ . **I.**  $ab = 0 \Rightarrow a = 0$  or b = 0 **II.**  $a, b \neq 0 \Rightarrow ab \neq 0$  **III.**  $ac = bc, a \neq 0 \Rightarrow b = c$ 

· Field is Integral Domain Every finite integral domain is a field  $\mathbb{Z}/p\mathbb{Z}$  is field iff p is prime. e.g.(integral domain)  $\mathbb{Z}$ ;  $\mathbb{Z}/p\mathbb{Z}$ 

**Polynomial Ring**  $R[X]: R[X] := \{a_n X^n + \dots + a_1 X + a_0 : a_i \in R, n \in \mathbb{N}\}$  where X is **indeterminate**  $\leftarrow X \notin R$  and  $\forall x \in R, Xa = aX$ 

- 1. **Degree**:  $deg(P) := max\{n \in \mathbb{N} : a_n \neq 0\}$  **Leading Coefficient**:  $a_n$  **Monic**:  $a_n = 1$  ps: Polynomial NOT a function
- 2. **Lemma**:  $^1R$  integral domain/no zero-divisors  $\Rightarrow R[X]$  also.  $^2R$  integral domain or no zero-divisor  $\Rightarrow \deg(PQ) = \deg(P) + \deg(P)$
- 3. **Division and Remainder**: If *R* is integral domain and  $P, Q \in R[X], Q \text{ monic } \exists ! A, B \in R[X] \text{ s.t. } P = AQ + B \text{ and } \deg(B) < \deg(Q)$
- 4. **Function** | **Factorize**: If R is *commutative ring*  $\Rightarrow$   $^1R[X] \rightarrow Maps(R,R)$  (可以视作函数)  $^2\lambda \in R$  is root of  $P \Leftrightarrow (X \lambda) \mid P(X)$
- 5. **Roots**: If R is *Integral domain*: P has at most deg(P) roots.

**Algebraically Closed**: R = F field is *algebraically closed* if every non-constant polynomial has a root in F.

• **Decomposes**: If *F* field is *algebraically closed*  $\Rightarrow$  *P* decomposes into:  $P(X) = a(X - \lambda_1) \cdots (X - \lambda_n)$ ,  $a \in F^{\times}$  i.e.  $a \neq 0$ 

#### 5.2 Equivalence Relation

**Equivalence Relation**: A relation R on a set X is a subset  $R \subseteq X \times X$ . If  $(x, y) \in R$ , we write xRy, if R is Equivalence Relation, then:

**Reflexive:** xRx  $(x \sim x)$  **Symmetric:**  $xRy \Rightarrow yRx$   $(x \sim y \Rightarrow y \sim x)$  **Transitive:** xRy,  $yRz \Rightarrow xRz$   $(x \sim y, y \sim z \Rightarrow x \sim z)$ 

**Partial Order**: A relation R on a set X, xRy. If R is partial order, then:

**Reflexive**:  $xRx \ (x \sim x)$  **Anti-symmetric**:  $xRy, yRx \Rightarrow x = y \ (x \sim y, y \sim x \Rightarrow x = y)$  **Transitive**:  $xRy, yRz \Rightarrow xRz \ (x \sim y, y \sim z \Rightarrow x \sim z)$ 

**Property of Equivalence Relation**: If R ( $\sim$ ) is equivalence relation on X.

- 1. ~ Define the **equivalence classes** of  $x \in X$  as  $E(x) := \{y \in X : x \sim y\}$
- 2. ~ **Partition** *X* into disjoint subsets  $X = \bigcup_i X_i, X_i$  is equivalence class of  $x \in X$ .
- 3.  $x \sim y \iff E(x) = E(y) \iff E(x) \cap E(y) \neq \emptyset$ .

**Set of Equivalence Classes**  $(X/\sim)$ :  $(X/\sim) := \{E(x) : x \in X\}$  **Canonical Projection**:  $can : X \to (X/\sim)$  by  $x \mapsto E(x)$ 

**System of Representatives**:  $Z \subseteq X$  is a system of representatives if 每个等价类都恰好有一个元素代表在 Z 中

Examples: 1 If V F-vector space, W subspace. Then V/W is quotient vector space. 2 If G group, H normal. Then G/H is quotient group. 3 If R ring, I ideal. Then R/I is quotient ring.

Universal Property of the set of Equivalence Classes: If  $f: X \to Z$  is a map s.t.  $x \sim y \Leftrightarrow f(x) = f(y)$ . ( $\sim$  is Equivalence relation) Important Then,  $\exists ! \text{ map } \overline{f}: (X/\sim) \to Z \text{ s.t. } f = \overline{f} \circ can \text{ with } \overline{f}(E(x)) = f(x) \text{ is } \textit{well-defined.}$  Further more,  $\overline{f}: (X/\sim) \xrightarrow{\sim} Im(f)$  ps: Often, if we want to prove  $g: (X/\sim) \to Z$  is well-defined, we need to prove  $x \sim y \Leftrightarrow g(x) = g(y)$  holds.

#### 5.3 Factor Ring | First Isomorphism Theorem

**Coset of Ideal**: Let *I* be an ideal of *R*. Then a+I is a coset of *I*. The  $\sim$  is defined by  $a\sim b \Leftrightarrow a-b\in I$  is an equivalence relation. **Factor Ring**: Let *I* be ideal of *R*.  $R/I:=\{a+I:a\in R\}$  is the set of cosets of *I*. (i.e. R/I is the set of equivalence classes of *R* under  $\sim$ )

- 1. By well-defined operators:  $(x + I) \dotplus (y + I) = (x + y) + I$  and  $(x + I) \cdot (y + I) = xy + I \implies R/I$  is a ring.
- 2.  $x + I = y + I \Leftrightarrow x \sim y \Leftrightarrow x y \in I$  | R is commutative  $\Rightarrow R/I$  also. |  $R/I \neq \{0 + I\}$  iff  $I \neq R$
- 3. The Identity of R/I:  $1_R + I$  The Zero of R/I:  $0_R + I$

**Universal Property of Factor Ring**: Let *R* be a ring and *I* be an ideal of *R*.  $ps:\overline{f}(x+I) = f(x)$ 

- 1. **can**: Mapping  $can : R \to R/I$  by  $x \mapsto x + I$  is <sup>1</sup> surjection, <sup>2</sup> ker(can) = I, <sup>3</sup> can is ring homomorphism.
- 2. **f**: If  ${}^1f: R \to S$  is ring homomorphism and  ${}^2I \subseteq ker(f)$ , then  $\exists ! \, {}^1\overline{f}: R/I \to S$  s.t.  $f = \overline{f} \circ can$  is ring homomorphism.
- 3. **First Isomorphism Theorem**: If  $f: R \to S$  is ring homomorphism  $\Rightarrow \exists ! \overline{f}: R/ker(f) \xrightarrow{\sim} im(f)$  is (ring isomorphism).

**Universal Property of Quotient Group**: Let *G* be a group and *H* be a normal subgroup of *G*.  $ps:\overline{f}(g+N)=f(g)$ 

- 1. **can**: Mapping  $can : G \to G/H$  by  $x \mapsto xH$  is <sup>1</sup> surjection, <sup>2</sup> ker(can) = H, <sup>3</sup> can is group homomorphism.
- 2. **f**: If  ${}^1f:G\to S$  is group homomorphism and  ${}^2H\subseteq ker(f)$ , then  $\exists! \, {}^1\overline{f}:G/H\to S$  s.t.  $f=\overline{f}\circ can$  is group homomorphism.
- 3. **First Isomorphism Theorem**: If  $f: G \to S$  is group homomorphism  $\Rightarrow \exists ! \overline{f}: G/ker(f) \stackrel{\sim}{\to} im(f)$  is (group isomorphism).

#### 5.4 Modules | Submodules | All of That

**Restrict with Scalar**: Let  $f: R \to S$  is a *ring homomorphism*,  $f(1_R) = 1_S$  and M is a S-Module, then M is also a R-Module by: Define the restrict our scalar:  $rm := f(r)m \quad \forall r \in R, m \in M \quad \text{ps: } f(1_R) = 1_S$ 

**Free Module**: Let M be a R-Module. M is free if:  $\forall m \in M$ ,  $\exists ! \ r_1, ..., r_n \in R$  s.t.  $m = r_1 m_1 + \cdots + r_n m_n$  ps:  $m_1, ..., m_n$  is basis of M **Coset of Submodule**: Let N submodule of M. Then m + N coset of N.  $\sim$  is defined by  $m \sim n \Leftrightarrow m - n \in N$  is an equivalence relation.

**Factor Module**: Let N submodule of M.  $M/N := \{m + N : m \in M\}$  is the set of cosets of N.

ps: All properties of M/N are similar to R/I

**Universal Property of Module Quotient**: Let *M* be a module and *N* be a submodule of *M*.  $ps:\overline{f}(x+N)=f(x)$ 

- 1. **can**: Mapping  $can : M \to M/N$  by  $x \mapsto x + N$  is <sup>1</sup> surjection, <sup>2</sup> ker(can) = N, <sup>3</sup> can is module homomorphism.
- 2. **f**: If  ${}^1f: M \to S$  is module homomorphism and  ${}^2N \subseteq ker(f)$ , then  $\exists ! \, {}^1\overline{f}: M/N \to S$  s.t.  $f = \overline{f} \circ can$  is module homomorphism.
- 3. **First Isomorphism Theorem**: If  $f: M \to S$  is module homomorphism  $\Rightarrow \exists ! \overline{f} : M/ker(f) \stackrel{\sim}{\to} im(f)$  is (module isomorphism).
- <sup>⊖</sup> **Second Isomorphism Theorem for Modules**: Let N, K be submodules of R-module  $M \Rightarrow N/(N \cap K) \cong (N + K)/K$  ps: consider  $f: N \to (N + K)/K$  and then we can find  $ker(f) = N \cap K$
- <sup>⊖</sup> **Third Isomorphism Theorem for Modules**: Let N, K be submodules of R-module  $M : K \subseteq N \Rightarrow \frac{M/K}{N/K} \cong M/N$  ps: consider  $f : M/K \to M/N$  and then we can find ker(f) = N/K

# 6 Permutation | Determinants | Eigenvalues and Eigenvectors

#### 6.1 Permutation | Determinants

**Permutation**: A bijection  $\sigma: \{1, ..., n\} \xrightarrow{\sim} \{1, ..., n\}$  is a permutation. All permutations of n elements form a group  $\mathfrak{S}_n$ .

- **1. Transposition**: A transposition is a permutation that exchanges two elements. **Inversion**: A pair of elements (i, j) is an inversion of  $\sigma \in \mathfrak{S}_n$  if i < j but  $\sigma(i) > \sigma(j)$
- 2. Length: The length of a permutation  $\sigma$  is the number of inversions. (i.e.  $\ell(\sigma) := \left| \{(i,j) : i < j, \sigma(i) > \sigma(j) \} \right|$  Sign:  $\operatorname{sgn}(\sigma) := (-1)^{\ell(\sigma)}$  sgn = 1, even;  $\operatorname{sgn} = -1$ , odd
- 3.  $\operatorname{sgn}(a_1 a_2) = -1$   $\operatorname{sgn}(a_1 ... a_n) = (-1)^{n-1}$   $\operatorname{sgn}(\sigma \tau) = \operatorname{sgn}(\sigma) \operatorname{sgn}(\tau)$  Alternating Group:  $A_n := \{ \sigma \in \mathfrak{S}_n : \operatorname{sgn}(\sigma) = 1 \}$
- 4. Graph Meaning of Inversion: Inversion is # edges that cross each other in the graph of permutation. (i.e. 画出的图中,线段交叉的次数)

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Determinant: For matrix A_{n \times n}, with A_{ij} = a_{ij}. \det(A) := \sum_{\sigma \in \mathfrak{S}_n} \operatorname{sgn}(\sigma) a_{1\sigma(1)} \cdots a_{n\sigma(n)} (Leibniz Formula)
                                                                                                                                                           \det(I_0) := 1
                                                                or: \det(A) := \sum_{\sigma^{-1} \in \mathfrak{S}_n} \operatorname{sgn}(\sigma^{-1}) a_{\sigma^{-1}(1)1} \cdots a_{\sigma^{-1}(n)n}
Geometric Meaning of Determinant: Let area(U) denote the area|volume of U. Let A denote a matrix.
 1. det(A) 对 U 操作后的面积 | 体积 = | det(A) | × area(U) 2. sgn(det A) 决定了方向是否改变 (+1 不变,-1 变). (i.e. 顺逆时针变化, 左右 | 上下变化, 手性变化)
Bilinear | Multilinear form: U, V, V_i, W be F-vector space. A mapping H: U \times V \to W or H: V_1 \times \cdots \times V_n \to W is bilinear | multilinear if:
 1. H(\lambda u, v) = \lambda H(u, v)
                                                                        1. H(u_1, ..., \lambda v_i, ..., u_n) = \lambda H(u_1, ..., v_i, ..., u_n) \quad \forall i
 2. H(u + v, w) = H(u, w) + H(v, w)
                                                                        2. H(u_1, ..., v_i + v_j, ..., u_n) = H(u_1, ..., v_i, ..., u_n) + H(u_1, ..., v_j, ..., u_n)
 3. H(u, \lambda v) = \lambda H(u, v)
                                                                            (左边 bilinear, 右边 multilinear)
 4. H(u, v + w) = H(u, v) + H(u, w)
   H is Symmetric if (bilinear): {}^1U = V, {}^2H(u,v) = H(v,u) \ \forall u,v \in U
                         if (multilinear): {}^{1}V_{i} same, {}^{2}H(v_{1},...,v_{n})=H(v_{\sigma(1)},...,v_{\sigma(n)}) \ \forall \sigma \in \mathfrak{S}_{n}
   H is Alternating|Antisymmetric if (bilinear): {}^{1}U = V, {}^{2}H(u,u) = 0 \quad \forall u \in U
```

if (multilinear):  ${}^1V_i$  same,  ${}^2H(v_1,...,v_n)=0$   $\forall v_i=v_i$  (i.e. 只要存在两个及以上相同的, H 结果为 0)

**Lemma I**: If *H* is alternating, then H(u, v) = -H(v, u) $H(v_1, ..., v_i, ..., v_j, ..., v_n) = -H(v_1, ..., v_i, ..., v_i, ..., v_n)$ 

**Lemma II**: If *H* is alternating, then  $H(v_1, ..., v_n) = \operatorname{sgn}(\sigma)H(v_{\sigma(1)}, ..., v_{\sigma(n)})$ 

**Property of Determinant**: Let A, B be  $n \times n$  matrices. F be field. R be commutative ring.

- 1. **Unique on Field**: det :  $F^n \times \cdots \times F^n \to F$  or det :  $Mat(n; F) \to F$  is the <sup>1</sup>unique <sup>2</sup>alternating <sup>3</sup>multilinear form s.t. det( $I_n$ ) =  $I_F$
- 2. **Invertible on Field**: For Mat(n; F), A is invertible  $\Leftrightarrow \det(A) \neq 0$   $\det(A^{-1}) = \det(A)^{-1}$  交换环, 结论成立如果  $\det(A)$  在 R 中有逆
- 3. **Similar on Field**: For *F* field.  $A \sim B \Rightarrow \det(A) = \det(P^{-1}BP) = \det(B)$ Thus, we can define: det(f) for  $f: V \to V$
- 4. **Operations**: If *R* is *commutative ring*, then  $det(AB) = det(A) det(B) det(A^T) = det(A) det(A^{-1}) = det(A)^{-1}$
- 5. **Block Triangular**: If A is block triangular, then  $\det(A) = \prod_{i=1}^n \det(A_i)$  即矩阵分块后如果是对角阵, 行列式等于各个块的行列式乘积 **Common Theorems in Determinant**: Let A be  $n \times n$  matrix. F be field. R be *commutative ring*.
- 1. Cofactor:  $\ln R$ ,  $C_{ij} := (-1)^{i+j} \det(A(i,j))$  where  $A(i,j) \not \in A$  去掉第i 行第j 列的矩阵. Laplace's Expansion:  $\ln R$ ,  $\det(A) = \sum_{j=1}^{n} a_{ij} C_{ij} = \sum_{i=1}^{n} a_{ij} C_{ij}$
- 2. Adjugate Matrix:  $\ln R$   $\operatorname{adj}(A)$   $\operatorname{matrix}$ ,  $\operatorname{adj}(A)_{ij} \coloneqq \mathcal{C}_{ji}$  Cramer's Rule:  $\ln R$   $A \cdot \operatorname{adj}(A) = (\det A)I_n$   $\ln F$ ,  $x_i = \frac{\det(A_i)}{\det(A)} A_i$  代表 A 的第 i 列替换为 b
- 3. Theorem|Need proof: In R,  $\operatorname{adj}(A^T) = \operatorname{adj}(A)^T$  Hint:  $\operatorname{adj}(A^T)_{ij} = c_{ii}^{A^T} = (-1)^{i+j} \operatorname{det}(A^T(i,j)) = (-1)^{i+j} \operatorname{det}(A(j,i)^T) = (-1)^{i+j} \operatorname{det}(A(j,i)) = c_{ii}^A = \operatorname{adj}(A)_{ji}^T = \operatorname{a$
- 4. ★ **Invertibility of Matrix**: In R, matrix A is invertible  $\Leftrightarrow$  det $(A) \in R^{\times}$ e.g.  $\mathbb{Z}^{\times} = \{\pm 1\}$ ;  $\mathbb{C}^{\times}$ ,  $\mathbb{R}^{\times}$ ,  $\mathbb{Q}^{\times} = \mathbb{C}^{*}$ ,  $\mathbb{R}^{*}$ ,  $\mathbb{Q}^{*}$ ;  $\mathbb{F}_{n}^{\times} = \mathbb{F}_{n} \setminus \{0\}$ ;  $\mathbb{Z}[i] = \{\pm 1, \pm i\}$
- 5. **Jacobi's Formula**, Let matrix A s.t.  $a_{ij}(t)$  are functions of t. Then,  $\frac{d}{dt} \det(A) = \operatorname{tr}\left(\operatorname{adj}A \cdot \frac{dA}{dt}\right)$

#### **Eigenvalues | Eigenvectors | Diagonalization**

**Eigenspace**  $E(\lambda, f)$ : Let  $f: V \to V$  linear map (End),  $\lambda \in F$ .  $E(\lambda, f) := \{\vec{v} \in V : f(\vec{v}) = \lambda \vec{v}\}$ .  $\lambda$  is eigenvalue if  $E(\lambda, f) \neq \{0\}$ ps:  $\ker(f - \lambda i d_V)$  is the eigenspace of  $E(\lambda, f)$  and it has a basis of eigenvectors  $\{\vec{v}_1, ..., \vec{v}_r\}$ .

**Existence of Eigenvalues**: For all  $f: V \to V$  linear map.  $^1V$  is finite-dimensional.  $^1F$  is algebraically closed.  $\Rightarrow \exists$  eigenvalues. **Characteristic Polynomial**  $\chi_A(x)$ : Let R be commutative ring.  $A \in Mat(n; R)$ .  $\chi_A(x) := \det(xI_n - A) \in R[x]$ 

**Relation with Eigenvalues**: If *F* is *field*,  $A \in Mat(n; F)$ .  $\lambda$  is eigenvalue of  $A \Leftrightarrow \chi_A(\lambda) = 0$ 

**Similar Matrix**: If *R* is *commutative ring*,  $A, B \in Mat(n; R)$  similar.  $\Rightarrow \chi_A(x) = \chi_B(x)$ Thus:  $\chi_f(x) := \chi_{\mathcal{A}[f]_{\mathcal{A}}}(x)$ Moreover, if  $_{\mathcal{A}}[f]_{\mathcal{A}} = A$  and A is similar to B. Then,  $\exists$  basis  $\mathcal{B}$  s.t.  $_{\mathcal{B}}[f]_{\mathcal{B}} = B$ 

**Remark:** If  $W \subseteq V$  is subspace.  $f: V \to V$  is End.  $f(W) \subseteq W$ . Let  $\mathcal{A} = (\vec{w}_1, ..., \vec{w}_m)$  basis W.  $\mathcal{B} = (\vec{w}_1, ..., \vec{v}_m, \vec{v}_{m+1}, ..., \vec{v}_n)$  basis V.  $\mathcal{C} = (\vec{v}_{m+1} + W, ..., \vec{v}_n + W)$  basis V/W. Suppose  $f(\vec{v_k}) = \sum_{i=1}^m c_{ik}\vec{w_i} + \sum_{j=m+1}^n b_{jk}\vec{v_j}$  Let  $g: W \to W$  by  $w \mapsto f(w)$   $h: V/W \to V/W$  by  $v+W \mapsto f(v)+W$   $e: V/W \to W$  by  $v+W \mapsto \sum_{i=1}^m c_{ik}\vec{w_i}$ Then:  $\chi_f(x) = \chi_g(x)\chi_h(x)$  and  $_{\mathcal{B}}[f]_{\mathcal{B}} = \begin{pmatrix} _{\mathcal{A}}[g]_{\mathcal{A}} & _{\mathcal{A}}[e]_{\mathcal{C}} \\ 0 & _{\mathcal{C}}[h]_{\mathcal{C}} \end{pmatrix} = \begin{pmatrix} a_{ij} & c_{ik} \\ 0 & b_{jk} \end{pmatrix}$ 

**Triangularisability**|A: Let  $A \in Mat(n; F)$ , it is *triangularisable* if  $\exists P$  invertible s.t.  $P^{-1}AP = U$  is upper triangular.

**Triangularisability**  $|f: \text{Let } f: V \to V \text{ be End. } V \text{ is finite-dimensional. the following are equivalent:}$ 

- 1.  $\exists \mathcal{B} = (\vec{v}_1, ..., \vec{v}_n)$  basis s.t.  $f(\vec{v}_i) = \sum_{j=1}^i a_{ji} \vec{v}_j$  (i.e.  $_{\mathbb{B}}[f]_{\mathbb{B}}$  is upper triangular.) we say f is triangularisable
- 2. The characteristic polynomial  $\chi_f(x)$  can be factored into linear factors over F. (ps: If F is algebraically closed, then f is triangularisable) **Corollary I**: Let  $A, B \in Mat(n; F)$ . A is triangularisable  $\Leftrightarrow A$  is similar (Conjugate) to a upper triangular matrix B.

**Corollary II**: Let  $f: V \to V$  be End. V is finite-dimensional. f is  $triangularisable \Leftrightarrow \exists$  subspaces  $V_0 = \{0\} \subset V_1 \subset \cdots \subset V_n = V$  s.t.  $f(V_i) \subseteq V_i$ . **Corollary III**: For  $A \in Mat(n; F)$ . A is nilpotent (i.e.  $A^k = 0$  for some k)  $\Leftrightarrow \chi_A(x) = x^n$ 

Application: 将矩阵 A 进行三角化,可以通过:1. 求特征值,特征向量; 2. 选择一个特征向量为基(通常选量大的); 3. 拓展为 V 的基; 4. 求 A 在新基下的矩阵 B, 此时 B 按分块矩阵看应有一部分三角化; 5. 对 B 未三角化的部分重复

**Diagonalisable** A: Let  $A \in Mat(n; F)$ . A is diagonalisable iff  $\exists$  matrix P s.t.  $P^{-1}AP = diagonalisable$ 

**Diagonalisable**  $f: V \to V$  be End, V is *diagonalisable* iff  $\exists$  basis of V consisting of eigenvectors of f.

**Diagonalisable**|Finite: For V is finite-dimensional. V is diagonalisable  $\Leftrightarrow \exists$  basis  $\mathcal{B}$  s.t.  $_{\mathcal{B}}[f]_{\mathcal{B}} = diag(\lambda_1, ..., \lambda_n)$ , where:  $f(\vec{v}_i) = \lambda_i \vec{v}_i$ **Property**: In finite case,  $\exists P$  consisting of eigenvectors s.t.  $P^{-1}AP = diag(\lambda_1, ..., \lambda_n)$ 

**Corollary**: If all roots of  $\chi_f(x)$  are distinct, then f is diagonalisable.

**LI of Eigenvectors**: Let  $f: V \to V$  be End. V is finite-dimensional. If  $\lambda_1, ..., \lambda_n$  are distinct  $\Rightarrow$  Corresponding eigenvectors are linearly independent.

**Cayley-Hamilton Theorem**: Let R be commutative ring.  $A \in Mat(n; R)$ . Then: for  $\chi_A(x)$   $\chi_A(A) = 0$ 

## 7 Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint

#### 7.1 Inner Product Spaces | Orthogonal Complement / Proj

**Real|Complex Inner Product Space**: Let V vector space over  $F = \mathbb{R}|\mathbb{C}$ . It is an *inner product space* if  $\exists$  mapping  $V \times V \to \mathbb{R}|\mathbb{C}$  s.t.

- 1. Linear in 1st Variable:  $(\lambda \vec{x} + \mu \vec{y}, \vec{z}) = \lambda(\vec{x}, \vec{z}) + \mu(\vec{y}, \vec{z})$   $\forall \lambda, \mu \in F, \hat{x}, \hat{y}, \hat{z} \in V$
- 2. **(Conjugate) Symmetric**:  $(\vec{x}, \vec{y}) = \overline{(\vec{y}, \vec{x})}$  for real,  $(\vec{x}, \vec{y}) = (\vec{y}, \vec{x})$  | Real: *linear* in 2nd variable. Complex: *conjugate linear* in 2nd variable.
- 3. **Positive Definite**:  $(\vec{x}, \vec{x}) \ge 0$  and  $(\vec{x}, \vec{x}) = 0$  iff  $\vec{x} = \vec{0}$  | Complex:  $(\vec{z}, \lambda \vec{x} + \mu \vec{y}) = \overline{\lambda}(\vec{z}, \vec{x}) + \overline{\mu}(\vec{z}, \vec{y})$  ps: **Standard Inner Product in**  $\mathbb{R}^n | \mathbb{C}^n$ :  $(\vec{x}, \vec{y}) = \sum_{i=1}^n x_i y_i$   $(\vec{x}, \vec{y}) = \sum_{i=1}^n x_i \overline{y_i}$  (i.e. dot product  $\vec{x} \cdot \vec{y} = \vec{x}^T \vec{y}$ )

**Special Inner Product**: If  $(\vec{x}, \vec{y}) = \sum_{i,j} a_{ij} x_i \overline{y_j} = \vec{x}^T A \vec{y}$  where  $A_{ij} = a_{ij}$ 

$$\Rightarrow$$
 It is an inner product if:  ${}^{1}\overline{A^{T}} = A$   ${}^{2}\vec{x}^{T}A\vec{x} \ge 0, \forall \vec{x} \in \mathbb{R}^{n} | \mathbb{C}^{n}$   ${}^{3}(\vec{x}, \vec{x}) = 0$  iff  $\vec{x} = \vec{0}$ 

**Norms**: For  $\vec{x}, \vec{y} \in V$  in inner product space.  $\|\vec{x}\| := \sqrt{(\vec{x}, \vec{x})} \ge 0$  **Orthogonal**:  $\vec{x} \perp \vec{y}$  iff  $(\vec{x}, \vec{y}) = 0$ 

- 1. Pythagoras' Theorem: If  $\vec{x} \perp \vec{y}$ , then  $||\vec{x} + \vec{y}||^2 = ||\vec{x}||^2 + ||\vec{y}||^2$ . Metric Space:  $d(\vec{x}, \vec{y}) := ||\vec{x} \vec{y}||$ .
- 2. Cauchy-Schwarz Inequality:  $|(\vec{x}, \vec{y})| \le ||\vec{x}|| ||\vec{y}||$  Triangle Inequality:  $||\vec{x} + \vec{y}|| \le ||\vec{x}|| + ||\vec{y}||$  Scalar:  $||\lambda \vec{x}|| = |\lambda| ||\vec{x}||$  Remark: Cauchy-Schwarz Inequality, "=" iff  $\vec{x}$ ,  $\vec{y}$  are linearly dependent, and they have same direction. (i.e.  $\vec{x} = \lambda \vec{y}$ ,  $\lambda \ge 0$ )

**Orthonormal Family**:  $\{\vec{v}_1, ..., \vec{v}_n\}$  is orthonormal if  ${}^1\|\vec{v}_i\| = 1$  and  ${}^2\vec{v}_i \perp \vec{v}_j$  for  $i \neq j$ . (i.e.  $(\vec{v}_i, \vec{v}_j) = \delta_{ij}$ ) If it is basis, then it is **orthonormal basis**.

- 1. **Observations**: **I.** For  $\{\vec{v}_1, ..., \vec{v}_n\}$  orthonormal basis.  $\vec{v} = \sum_{i=1}^n (\vec{v}, \vec{v}_i) \vec{v}_i$ . **II.** For orthonormal Family, 可直接用勾股定理.  $\Rightarrow$  证明 basis 只需要证 span. 2. **Theorem**: Every finite-dimensional inner product space has an orthonormal basis.
- 3. **Gram-Schmidt Process**: Let  $\{\vec{v}_1, ..., \vec{v}_n\}$  be basis of V. By using following way to get orthonormal basis:

$$\begin{array}{lll} \mathbf{a}. \ \vec{e}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|} & \operatorname{Proj}_{\vec{e}_k} \vec{v}_j = (\vec{v}_j, \vec{e}_k) \vec{e}_k \\ \mathbf{b}. \ \vec{u}_2 = \vec{v}_2 - \operatorname{Proj}_{\vec{e}_1} \vec{v}_2 & \vec{e}_2 = \frac{\vec{u}_2}{\|\vec{u}_2\|} \\ \mathbf{c}. \ \vec{u}_3 = \vec{v}_3 - \operatorname{Proj}_{\vec{e}_1} \vec{v}_3 - \operatorname{Proj}_{\vec{e}_2} \vec{v}_3 & \vec{e}_3 = \frac{\vec{u}_3}{\|\vec{u}_3\|} \\ \mathbf{d}. \ \vec{u}_n = \vec{v}_n - \sum_{i=1}^{n-1} \operatorname{Proj}_{\vec{e}_i} \vec{v}_n & \vec{e}_n = \frac{\vec{u}_n}{\|\vec{u}_n\|} \end{array} \right. \\ \end{array}$$

$$All-In-One:$$

$$\vec{e}_{k+1} = \frac{\vec{v}_{k+1} - \sum_{i=1}^{k} \operatorname{Proj}_{\vec{e}_i} \vec{v}_{k+1}}{\|\vec{v}_{k+1} - \sum_{i=1}^{k} \operatorname{Proj}_{\vec{e}_i} \vec{v}_{k+1}}$$

**Orthogonal Set**: For subset *T* of vector space *V*. **Set Orthogonal to** *A* is  $A^{\perp} := \{\vec{v} \in V : \vec{v} \perp \vec{a}, \forall \vec{a} \in A\}$ 

- 1. **I**.  $A^{\perp}$  is always subspace of V. **II**.  $A^{\perp} = \langle A \rangle^{\perp}$
- 2. **Orthogonal Decomposition Theorem**: Let V be inner product space. W be subspace of V. Then:  $V = W \oplus W^{\perp}$  **Orthogonal Projection**: Let V be inner product space. U be subspace of V, with orthonormal basis  $\{\vec{e}_1, ..., \vec{e}_m\}$ .
- 1. Then: orthogonal projection  $\pi_U: V \to V$  by  $\vec{v} \mapsto \sum_{i=1}^m (\vec{v}, \vec{e}_i) \vec{e}_i$
- 2. I.  $\pi_{II}^2 = \pi_{II}$  II.  $\ker(\pi_{II}) = U^{\perp}$  and  $\operatorname{Im}(\pi_{II}) = U$  III.  $\pi_{II}|_{II} = id_{II}$
- 3. **Orthogonal Decomposition**: For all  $\vec{v} \in V$ ,  $\vec{v} = (\vec{v} \pi_U(\vec{v})) + \pi_U(\vec{v})$  where  $(\vec{v} \pi_U(\vec{v})) \perp \pi_U(\vec{v})$ .
- 4. **Closest Approximation**: Since  $\|\vec{v} \vec{u}\|^2 = \|\vec{v} \pi_U(\vec{v})\|^2 + \|\pi_U(\vec{v}) \vec{u}\|^2 \implies \vec{u} = \pi_U(\vec{v})$  is the closest vector in U to  $\vec{v}$ .

## 7.2 Adjoint and Self-Adjoint

**Orthogonal**: matrix A is orthogonal if  $A^TA = I_n$ . (i.e.  $A^{-1} = A^T$ ) **Unitary**: matrix A is unitary if  $\overline{A}^TA$  or  $A^T\overline{A} = I_n$ . (i.e.  $A^{-1} = \overline{A}^T$ ) **Hermitian**: matrix A is Hermitian if  $\overline{A}^T = A$ . (i.e. A is self-adjoint in  $\mathbb{C}$ ) **Symmetric**: matrix A is symmetric if  $A^T = A$ . (i.e. A is self-adjoint in  $\mathbb{R}$ )

**Useful Tool**: If  $T: V \to W$  is linear map. For matrix  $_{\mathcal{B}}[T]_{\mathcal{A}}$ , The entry  $[_{\mathcal{B}}[T]_{\mathcal{A}}]_{ij} = (T\vec{e}_i, \vec{f}_i)$ 

**IPS isomorphism of** V: A linear map  $T: V \to W$  is *IPS isomorphism* of V (and W) if:  $^1T$  is isomorphism  $^2(T\vec{v}_1, T\vec{v}_2) = (\vec{v}_1, \vec{v}_2) \quad \forall \vec{v}_1, \vec{v}_2 \in V$  **Properties of IPS isomorphism**: Let V, W be inner product spaces,  $\mathcal{A} = \{\vec{e}_1, ..., \vec{e}_m\}, \mathcal{B} = \{\vec{f}_1, ..., \vec{f}_n\}$  are orthonormal basis of V, W.

- 1. Linear map  $T:V\to W$  is IPS isomorphism of V (i.e. T is iso &  $(T\vec{v}_1,T\vec{v}_2)=(\vec{v}_1,\vec{v}_2)$ )  $\iff$  Linear map  $T:V\to W$  maps some orthonormal basis to another.
- 2.  $T: V \to V$  is IPS isomorphism  $\Leftrightarrow _{\mathcal{A}}[T]_{\mathcal{A}}$  is  $orthogonal_{\mathbb{R}}$  or  $unitary_{\mathbb{C}}$  matrix.
- 3. **Similar**: If matrix  $A =_{\mathcal{A}} [f]_{\mathcal{A}}$  and  $B =_{\mathcal{B}} [f]_{\mathcal{B}} \Leftrightarrow B = P^{-1}AP$  and P is is  $orthogonal_{\mathbb{R}}$  or  $unitary_{\mathbb{C}}$  matrix.

**Adjoint**: V is inner product space.  $T, S : V \to V$  are linear maps. T, S are called *adjoint* to one another if  $(T\vec{v}, \vec{w}) = (\vec{v}, S\vec{w}) \quad \forall \vec{v}, \vec{w} \in V$ .

**Self-adjoint**: If  $T = T^*$ , then T is *self-adjoint*. (i.e.  $(T\vec{v}, \vec{w}) = (\vec{v}, T\vec{w})$ )

**Properties of Adjoint**: Let *V* be *inner product spaces*,  $\mathcal{A} = \{\vec{e}_1, ..., \vec{e}_n\}$  are orthonormal basis of *V*.  $T: V \to V$  is linear map.

- 1. Then,  $\exists !$  linear map  $T^*: V \to V$  s.t.  $(T\vec{v}, \vec{w}) = (\vec{v}, T^*\vec{w}) \quad \forall \vec{v}, \vec{w} \in V$ .
- $2. \ \, \mathbf{I.}_{\,\,\mathcal{A}}[T^*]_{\mathcal{A}} = \overline{(_{\mathcal{A}}[T]_{\mathcal{A}})}^T \qquad \text{II. If } T = T^* \text{ (self-adjoint)} \\ \Leftrightarrow \ _{\mathcal{A}}[T]_{\mathcal{A}} = \overline{(_{\mathcal{A}}[T]_{\mathcal{A}})}^T \text{ Hermitian/Symmetric}$
- 3. **IPS isomorphism**:  $T: V \to V$  is IPS isomorphism  $\iff TT^* = T^*T = \mathrm{id}_V \iff {}_{\mathcal{A}}[T]_{\mathcal{A}}$  is  $unitary_{\mathbb{C}}$  or  $orthogonal_{\mathbb{R}}$  matrix. **Normal**: Linear map  $T: V \to V$  is normal if  $TT^* = T^*T$ .

**Properties of Normal**: Let V be inner product spaces,  $\mathcal{A} = \{\vec{e}_1, ..., \vec{e}_n\}$  are orthonormal basis of V.  $T: V \to V$  is linear map.

- 1. T is  $normal \Leftrightarrow \overline{_{\mathcal{A}}[T]_{\mathcal{A}}}^T \cdot_{\mathcal{A}} [T]_{\mathcal{A}} =_{\mathcal{A}} [T]_{\mathcal{A}} \cdot \overline{_{\mathcal{A}}[T]_{\mathcal{A}}}$
- 2. **I.** T is self-adjoint  $\Rightarrow$  T is normal **II**. T is IPS isomorphism  $\Rightarrow$  T is normal.

# Jordan Normal Form | Spectral Theorem

# **Appendix**

 $\begin{array}{lll} \textbf{Appendix} \\ \textbf{Vieta's formulas} \colon \text{For polynomial } P(x) = a_n x^n + \dots + a_1 x + a_0. & \text{Let } x_1, \dots, x_n \text{ be roots of } P(x). \\ x_1 + \dots + x_n = -\frac{a_{n-1}}{a_n} & x_1 \dots x_n = (-1)^n \frac{a_0}{a_n} & x_1 x_2 + x_1 x_3 + \dots + x_{n-1} x_n = \frac{a_{n-2}}{a_n} \\ \textbf{Determinant of Vandermonde Matrix} \colon \text{Let } x_1, \dots, x_n \text{ be distinct elements of } F. & \text{Then} & \det \begin{pmatrix} 1 & x_1 & x_1^2 & \dots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \dots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^{n-1} \end{pmatrix} = \Pi_{1 \le i < j \le n}(x_j - x_i)$