# **HAlg Note**

### 1 Basic Knowledge

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Def of Group (G, *): A set G with a operator * is a group if: Closure: \forall g, h \in G, g * h \in G; Associativity: \forall g, h, k \in G, (g * h) * k = g * (h * k); Identity: \exists e \in G, \forall g \in G, e * g = g * e = g; Inverse: \forall g \in G, \exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e. G, H groups, then G \times H also. Subgroup: H \subseteq G is a subgroup if: \forall h_1, h_2 \in H I: H \neq \emptyset; II: h_1 * h_2 \in H; III: h_1^{-1} \in H.

Field (F): A set F is a field with two operators: (addition)+: F \times F \to F; (\lambda, \mu) \to \lambda + \mu (multiplication)·: F \times F \to F; (\lambda, \mu) \to \lambda \mu if: (F, +) and (F \setminus \{0_F\}, \cdot) are abelian groups with identity 0_F, 1_F. and \lambda(\mu + \nu) = \lambda \mu + \lambda \nu e.g.Fields : \mathbb{R}, \mathbb{C}, \mathbb{Q}, \mathbb{Z}/p\mathbb{Z} = \mathbb{F}_p

F-Vector Space (V): A set V over a field F is a vector space if: V is an abelian group V = (V, \dot{+}) and \forall \vec{v}, \vec{w} \in V \lambda, \mu \in F e.g. P oly: \mathbb{R}[x]_{\leq n} P map P \times V \to V : (\lambda, \vec{v}) \to \lambda \vec{v} satisfies: I: \lambda(\vec{v} + \vec{w}) = (\lambda \vec{v}) + (\lambda \vec{w}) II: (\lambda + \mu)\vec{v} = (\lambda \vec{v}) + (\mu \vec{v}) III: \lambda(\mu \vec{v}) = (\lambda \mu)\vec{v} IV: 1_F \vec{v} = \vec{v}

Vector Subspaces Criterion: U \subseteq V is a subspace of V if: I. \vec{0} \in U II. \forall \vec{u}, \vec{v} \in U, \forall \lambda \in F: \vec{u} + \vec{v} \in U and \lambda \vec{u} \in U (or: \lambda \vec{u} + \mu \vec{v} \in U)

• property: If U, W are subspaces of V, then U \cap W and U + W are also subspaces of V. ps: U + W := \{\vec{u} + \vec{w} : \vec{u} \in U, \vec{w} \in W\}

Complement-wise Operations: \phi : V_1 \times V_2 \to V_1 \oplus V_2 by \mathbf{E}(\vec{v}_1, \vec{u}_1) + (\vec{v}_2, \vec{u}_2) := (\vec{v}_1 + \vec{v}_1, \vec{u}_1 + \vec{u}_2), \lambda(\vec{v}, \vec{u}) := (\lambda \vec{v}, \lambda \vec{u}) (ps: V_1, V_2 \oplus V_3) and V_3 \oplus V_4 \oplus V_4 or V_4 \oplus V_4 \oplus V_4.
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**Projections**:  $pr_i: X_1 \times \cdots \times X_n \to X_i$  by  $(x_1, ..., x_n) \mapsto x_i$  **Canonical Injections**:  $in_i: X_i \to X_1 \times \cdots \times X_n$  by  $x \mapsto (0, ..., 0, x, 0, ..., 0)$ 

## 2 Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis

**Generating (subspaces)**  $\langle T \rangle$ :  $\langle T \rangle := \{ \alpha_1 \vec{v_1} + \dots + \alpha_n \vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, r \in \mathbb{N} \}$   $\langle \emptyset \rangle := \{ \vec{0} \}$  If T is subspace  $\Rightarrow \langle T \rangle = T$ .

- 1. **Proposition**:  $\langle T \rangle$  is the smallest subspace containing T. (i.e.  $\langle T \rangle$  is the intersection of all subspaces containing T)
- 2. **Generating Set**: *V* is vector space,  $T \subseteq V$ . *T* is generating set of *V* if  $\langle T \rangle = V$ . **Finitely Generated**:  $\exists$  finite set T,  $\langle T \rangle = V$
- 3. **External Direct Sum**: 一个" 代数结构", 定义为 set 是  $V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n$  且有一组运算法则 component-wise operations
- 4. **Connect to Matrix**: Let  $E = \{\vec{v_1}, ..., \vec{v_n}\}$ , E is GS of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{b} \in V$ ,  $\exists \vec{x} = (x_1, ..., x_n)^T$  s.t.  $A\vec{x} = \vec{b}$  (i.e. linear map: $\phi : \vec{x} \mapsto A\vec{x}$  is surjective)
- **Linearly Independent**:  $L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\}$  is linearly independent if:  $\forall c_1, ..., c_r \in F, c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0$ . • **Connect to Matrix**: Let  $L = \{\vec{v_1}, ..., \vec{v_n}\}$ , L is LI of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} \in F^n$ ,  $A\vec{x} = 0$  (or  $\vec{0}$ )  $\Rightarrow \vec{x} = 0$ (or  $\vec{0}$ ) (i.e. linear map  $\phi: \vec{x} \mapsto A\vec{x}$  is injective)

**Basis & Dimension**: If *V* is finitely generated.  $\Rightarrow \exists$  subset  $B \subseteq V$  which is both LI and GS. (*B* is basis) **Dim**: dim V := |B|

• Connect to Matrix: Let  $B = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T$  s.t.  $\phi : \vec{x} \mapsto A\vec{x}$  is 1-1 & onto (Bijection)

**Relation** [GS,LI,Basis,dim: Let V be vector space. L is linearly independent set, E is generating set, B is basis set.

- 1. **GS**|**LI**:  $|L| \le |E|$  (can get: dim unique) **LI** $\to$ **Basis**: If V finite generate  $\Rightarrow \forall L$  can extend to a basis. If  $L = \emptyset$ , prove  $\exists B$   $kerf \cap imf = \{0\}$
- 2. **Basis**|max,min:  $B \Leftrightarrow B$  is minimal GS  $(E) \Leftrightarrow B$  is maximal LI (L). **Uniqueness**|Basis: 每个元素都可以由 basis 唯一表示.
- 3. **Proper Subspaces**: If  $U \subset V$  is proper subspace, then  $\dim U < \dim V$ .  $\Rightarrow$  If  $U \subseteq V$  is subspace and  $\dim U = \dim V$ , then U = V.
- 4. **Dimension Theorem**: If  $U, W \subseteq V$  are subspaces of V, then  $\dim(U+W) = \dim U + \dim W \dim(U\cap W)$

**Complementary**:  $U, W \subseteq V, U, V$  subspaces are complementary  $(V = U \oplus W)$  if:  $\exists \phi : U \times W \to V$  by  $(\vec{u}, \vec{w}) \mapsto \vec{u} + \vec{w}$  i.e.  $\forall \vec{v} \in V$ , we have unique  $\vec{u} \in U, \vec{w} \in W$  s.t.  $\vec{v} = \vec{u} + \vec{w}$ . ps: It's a linear map.

# 3 Linear Mapping | Rank-Nullity | Matrices | Change of Basis ps: 默认 V, W F-Vector Space

### 3.1 Linear Mapping | Rank-Nullity

**Linear Mapping/Homomorphism(Hom)**:  $f: V \to W$  is linear map if:  $\forall \vec{v}_1, \vec{v}_2 \in V, \forall \lambda \in F.$   $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$  and  $f(\lambda \vec{v}_1) = \lambda f(\vec{v}_1)$ 

· Isomorphism: = LM & Bij. Endomorphism(End): = LM & V = W. Automorphism(Aut): = LM & V = W Monomorphism: = LM & 1-1. Epimorphism: = LM & onto.

 $\textbf{Kernel}: \ker f := \{\vec{v} \in V : f(\vec{v}) = \vec{0}\} \\ (\text{It's subspace}) \quad \textbf{Image}: Imf := \{f(\vec{v}) : \vec{v} \in V\} \\ (\text{It's subspace}) \quad \textbf{Rank} := \dim(Imf) \quad \textbf{Nullity} := \dim(\ker f) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x)$ 

**Property of Linear Map**: Let  $f, g \in Hom$ :  $\mathbf{a}. f(\vec{0}) = \vec{0}$   $\mathbf{b}. f$  is 1-1 iff  $\ker f = \{\vec{0}\}$   $\mathbf{c}. f \circ g$  is linear map.

- 1. **Determined**: f is determined by  $f(\vec{b_i})$ ,  $\vec{b_i} \in \mathcal{B}_{basis}$  (\* i.e.  $f(\sum_i \lambda_i \vec{v_i}) := \sum_i \lambda_i f(\vec{v_i})$ )
- 2. **Classification of Vector Spaces**: dim  $V = n \Leftrightarrow f : F^n \xrightarrow{\sim} V$  by  $f(\lambda_1, ..., \lambda_n) \mapsto \sum_{i=1}^n \lambda_i \vec{v_i}$  is isomorphism.
- 3. **Left/Right Inverse**: f is 1-1  $\Rightarrow$   $\exists$  left inverse g s.t.  $g \circ f = id$  考虑 direct sum f is onto  $\Rightarrow$   $\exists$  right inverse g s.t.  $f \circ g = id$
- 4.  $^{\Theta}$  More of Left/Right Inverse:  $f \circ g = id \Rightarrow g$  is 1-1 and f is onto. 使用 kernel=0 来证明

**Rank-Nullity Theorem**: For linear map  $f: V \to W$ , dim  $V = \dim(\ker f) + \dim(Imf)$  Following are properties:

- 1. **Injection**: f is  $1-1 \Rightarrow \dim V \le \dim W$  **Surjection**: f is onto  $\Rightarrow \dim V \ge \dim W$  Moreover,  $\dim W = \dim imf$  iff f is onto.
- 2. **Same Dimension**: f is isomorphism  $\Rightarrow$  dim  $V = \dim W$  **Matrix**:  $\forall M$ , column rank  $c(M) = \operatorname{row} \operatorname{rank} r(M)$ .
- 3. **Relation**: If V, W finite generate, and dim  $V = \dim W$ , Then: f is isomorphism  $\Leftrightarrow f$  is  $1-1 \Leftrightarrow f$  is onto.

### 3.2 Matrices | Change of Basis | Similar Matrices | Trace

- 2. If  $\vec{v} \in V$ , then  $_{\mathcal{A}}[\vec{v}] := \mathbf{b}$  (vector) where  $\vec{v} = \sum_{i \in \mathcal{A}} \mathbf{b}_i \vec{v}_i$
- 3. Theorems:  $[f \circ g] = [f] \circ [g]$   $_{\mathcal{C}}[f \circ g]_{\mathcal{A}} =_{\mathcal{C}} [f]_{\mathcal{B}} \circ_{\mathcal{B}} [g]_{\mathcal{A}}$   $_{\mathcal{B}}[f(\vec{v})] =_{\mathcal{B}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [\vec{v}]$   $_{\mathcal{A}}[f]_{\mathcal{A}} = I \Leftrightarrow f = id$
- 4. **Change of Basis**: Define Change of Basis Matrix:= $_{\mathcal{A}}[id_V]_{\mathcal{B}}$   $_{\mathcal{B}'}[f]_{\mathcal{A}'} =_{\mathcal{B}'}[id_W]_{\mathcal{B}} \circ_{\mathcal{B}}[f]_{\mathcal{A}} \circ_{\mathcal{A}}[id_V]_{\mathcal{A}'}$   $_{\mathcal{A}'}[f]_{\mathcal{A}'} =_{\mathcal{A}}[id_V]_{\mathcal{A}'}^{-1} \circ_{\mathcal{A}}[f]_{\mathcal{A}} \circ_{\mathcal{A}}[id_V]_{\mathcal{A}'}$

- **Similar Matrices**:  $N = T^{-1}MT \Leftrightarrow M, N$  are similar. Special Case: If  $N =_{\mathcal{B}} [f]_{\mathcal{B}}, M =_{\mathcal{A}} [f]_{\mathcal{A}}$ , then  $N = T^{-1}MT$ . where  $T =_{\mathcal{A}} [id_V]_{\mathcal{B}}$ 1. If  $A \sim B$  iff A is similar to B, then  $\sim$  is an equivalence relation.  $A' [f]_{\mathcal{A}'} \sim_{\mathcal{A}} [f]_{\mathcal{A}}$
- 2. If  $\mathcal{B} = \{p(\vec{v_1}), ..., p(\vec{v_n})\}$  and  $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$  where  $p: V \xrightarrow{\sim} V$ . Then  $\mathcal{A}[id_V]_{\mathcal{B}} =_{\mathcal{A}} [p]_{\mathcal{A}}$
- 3. If *V* is a vector space over *F*, [*A*, *B* are *similar* matrices.  $\Leftrightarrow A =_{\mathcal{A}} [f]_{\mathcal{A}}, B =_{\mathcal{B}} [f]_{\mathcal{B}}$  for some basis  $\mathcal{A}, \mathcal{B}; f : V \to V$ ]
- 4. Set of Endomorphism is in a bijection correspondence with the equivalence class of matrices under  $\sim$ . 一个自同态 End 就对应一个相似矩阵的等价类 **Trace**:  $tr(A) := \sum_i a_{ii}$  and  $tr(f) := tr(_{\mathcal{A}}[f]_{\mathcal{A}}) \mid tr(AB) = tr(BA) \quad tr(\lambda A + \mu B) = \lambda tr(A) + \mu tr(B) \quad tr(N) = tr(M)$  if M, N similar.

### 4 Rings | Polynomials | Ideals | Subrings

#### 4.1 Rings | Polynomial Rings

**Ring**  $(R, +, \cdot)$ : A set R with two operators  $+, \cdot$  is a ring if:

- 1. (R, +) is an abelian group with identity  $0_R$ . Commutative Ring: add:  $\forall a, b \in R, ab = ba$ .
- 2.  $(R, \cdot)$  is a **monoid** with identity  $1_R$ . i.e. **Associativity**:  $\forall a, b, c \in R, (a \cdot b) \cdot c = a \cdot (b \cdot c)$ . **Identity**:  $\forall a \in R, 1_R \cdot a = a \cdot 1_R = a$ .
- 3. **Distributive**:  $\forall a, b, c \in R$ :  $a \cdot (b+c) = a \cdot b + a \cdot c$  and  $(b+c) \cdot a = b \cdot a + c \cdot a$ . ps: 默认 monoid 是 closure 的
- · If R is ring  $\Rightarrow$   $[1_R = 0_R \Leftrightarrow R = \{0\}]$  i.e. For any non-zero ring,  $1_R \neq 0_R$  Field: Commutative ring + multiplicative inverse = Field.

**Properties of Ring**:  $\forall a, b \in R$ . I.0 ·  $a = a \cdot 0 = 0$  II.  $(-a) \cdot b = a \cdot (-b) = -(a \cdot b)$  III.  $(-a) \cdot (-b) = a \cdot b$ 

**Unit**:  $a \in R$  is unit if it's *Invertible*. i.e.  $\exists a^{-1} \in R$  s.t.  $aa^{-1} = a^{-1}a = 1_R$  **Group of Unit**  $(R^{\times}, \cdot) := \{a \in R : a \text{ is unit}\}$ 

**Zero-divisors**:  $a \in R$  is zero-divisor if  $\exists b \in R, b \neq 0$  s.t. ab = 0 or ba = 0 Field has no zero-divisors. • e.g.  $\mathbb{Z}^{\times} = \{-1, 1\}$ ;  $1_R$  is a unit. **Integral Domain**: A commutative ring R is an integral domain if it has no zero-divisors. • e.g.  $\mathbb{Z}/p\mathbb{Z}$ ,  $\mathbb{R}$ ,  $\mathbb{Q}$ ,  $\mathbb{Z}$ , ...

**Properties of Integral Domain**:  $\forall a, b \in R$ . **I.**  $ab = 0 \Rightarrow a = 0$  or b = 0 **II.**  $a, b \neq 0 \Rightarrow ab \neq 0$  **III.**  $ac = bc, a \neq 0 \Rightarrow b = c$ 

· Field is Integral Domain Every finite integral domain is a field  $\mathbb{Z}/p\mathbb{Z}$  is field iff p is prime. e.g.(integral domain)  $\mathbb{Z}$ ;  $\mathbb{Z}/p\mathbb{Z}$ 

**Polynomial Ring**  $R[X]: R[X] := \{a_n X^n + \dots + a_1 X + a_0 : a_i \in R, n \in \mathbb{N}\}$  where X is **indeterminate**  $\Leftarrow X \notin R$  and  $\forall x \in R, Xa = aX$ 

- 1. **Degree**:  $\deg(P) := \max\{n \in \mathbb{N} : a_n \neq 0\}$  **Leading Coefficient**:  $a_n$  **Monic**:  $a_n = 1$  ps: Polynomial NOT a function
- 2. **Lemma**:  $^1R$  integral domain/no zero-divisors  $\Rightarrow R[X]$  also.  $^2R$  integral domain or no zero-divisor  $\Rightarrow \deg(PQ) = \deg(P) + \deg(P)$
- 3. **Division and Remainder**: If R is integral domain and P,  $Q \in R[X]$ , Q monic  $\exists ! A, B \in R[X]$  s.t. P = AQ + B and  $\deg(B) < \deg(Q)$
- 4. **Function** | **Factorize**: If R is *commutative ring*  $\Rightarrow$   $^1R[X] \rightarrow Maps(R,R)$  (可以视作函数)  $^2\lambda \in R$  is root of  $P \Leftrightarrow (X \lambda) \mid P(X)$
- 5. **Roots**: If R is *Integral domain*: P has at most deg(P) roots.

**Algebraically Closed**: R = F field is *algebraically closed* if every non-constant polynomial has a root in F. e.g.  $\mathbb{C}$ 

• **Decomposes**: If *F* field is *algebraically closed*  $\Rightarrow$  *P* decomposes into:  $P(X) = a(X - \lambda_1) \cdots (X - \lambda_n)$ ,  $a \in F^{\times}$  i.e.  $a \neq 0$ 

#### 4.2 Homomorphism | Ideals | Subrings

**Ideal**  $(I \subseteq R)$ : A subset  $I \subseteq R$  (ring) is an ideal if: **I.**  $I \neq \emptyset$  **II.**  $\forall a, b \in I, a - b \in I$  **III.**  $\forall i \in I, \forall r \in R, ri, ir \in I$ 

- 1. **Generated Ideal**  $_R\langle T\rangle$ :  $T\subseteq R$  (ring), where R is *commutative ring*. We define  $_R\langle T\rangle:=\{\sum_{i=1}^n r_it_i:n\in\mathbb{N},r_i\in R,t_i\in T\}$ 
  - · Lemma:  $_R\langle T\rangle$  is the smallest ideal containing T. Principal Ideal:  $_R\langle a\rangle$  Proper Ideal:  $I\neq R$  ps:  $_R$  一定是 commutative ring
- 2. If I, J are ideals of R. Then I + J;  $I \cap J$  are also ideals.

**Subring Test**:  $R' \subseteq R$  (ring) is a subring if: **I**.  $1_R \in R'$  **II**.  $\forall a, b \in R'$ ,  $a - b \in R'$  **III**.  $\forall a, b \in R'$ ,  $ab \in R'$ 

· If  $f: R \to S$  is ring homomorphism, and R' is subring of R.  $\Rightarrow f(R')$  is subring of S.

**Ring Homomorphism**: R, S are rings,  $f: R \to S$  is ring homomorphism if: I. f(a+b) = f(a) + f(b) II. f(ab) = f(a)f(b)  $f(1_R) = 1_S$  is NOT need

- 1. **Second Def**: f is ring homomorphism if:  $f:(R,+) \to (S,+)$  is group homomorphism and f(xy) = f(x)f(y).
- 2. I.  $f(0_R) = 0_S$  II. f(-a) = -f(a) III.  $f(a^n) = (f(a))^n$  IV. f(x y) = f(x) f(y) V. f(mx) = mf(x)
- 3. **Kernel**:  $\ker f := \{a \in R : f(a) = 0_S\}$  is an *ideal* **Image**:  $Imf := \{f(a) : a \in R\}$  is a *subring*. **1-1**: f is 1-1  $\Leftrightarrow$   $\ker f = \{0_R\}$

#### 4.3 Equivalence Relation

### 5 Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint

### 6 Jordan Normal Form | Spectral Theorem