## **HAlg Note**

## 1 Basic Knowledge

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Def of Group (G, *): A set G with a operator * is a group if: Closure: \forall g, h \in G, g * h \in G; Associativity: \forall g, h, k \in G, (g * h) * k = g * (h * k); Identity: \exists e \in G, \forall g \in G, e * g = g * e = g; Inverse: \forall g \in G, \exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e. G, H groups, then G \times H also. Field (F): A set F is a field with two operators: (addition)+: F \times F \to F; (\lambda, \mu) \to \lambda + \mu (multiplication)·: F \times F \to F; (\lambda, \mu) \to \lambda \mu if: (F, +) and (F \setminus \{0_F\}, \cdot) are abelian groups with identity (0_F, 1_F). and (0_F, 1_F) and (0_F, 1_F
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## 2 Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis

**Generating (subspaces)**  $\langle T \rangle$ :  $\langle T \rangle := \{ \alpha_1 \vec{v_1} + \dots + \alpha_n \vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, r \in \mathbb{N} \}$   $\langle \emptyset \rangle := \{ \vec{0} \}$  If T is subspace  $\Rightarrow \langle T \rangle = T$ .

- 1. **Proposition**:  $\langle T \rangle$  is the smallest subspace containing T. (i.e.  $\langle T \rangle$  is the intersection of all subspaces containing T)
- 2. **Generating Set**: *V* is vector space,  $T \subseteq V$ . *T* is generating set of *V* if  $\langle T \rangle = V$ . **Finitely Generated**:  $\exists$  finite set T,  $\langle T \rangle = V$
- 3. **External Direct Sum**: 一个" 代数结构", 定义为 set 是  $V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n$  且有一组运算法则 component-wise operations
- 4. **Connect to Matrix**: Let  $E = \{\vec{v_1}, ..., \vec{v_n}\}$ , E is GS of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{b} \in V$ ,  $\exists \vec{x} = (x_1, ..., x_n)^T$  s.t.  $A\vec{x} = \vec{b}$  (i.e. linear map: $\phi : \vec{x} \mapsto A\vec{x}$  is surjective) **Linearly Independent**:  $L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\}$  is linearly independent if:  $\forall c_1, ..., c_r \in F$ ,  $c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0$ .
- Connect to Matrix: Let  $L = \{\vec{v_1}, ..., \vec{v_n}\}$ , L is LI of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} \in F^n$ ,  $A\vec{x} = 0$  (or  $\vec{0}$ )  $\Rightarrow \vec{x} = 0$ (or  $\vec{0}$ ) (i.e. linear map  $\phi: \vec{x} \mapsto A\vec{x}$  is injective)

**Basis & Dimension**: If *V* is finitely generated.  $\Rightarrow \exists$  subset  $B \subseteq V$  which is both LI and GS. (*B* is basis) **Dim**: dim V := |B|

• **Connect to Matrix**: Let  $B = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T$  s.t.  $\phi : \vec{x} \mapsto A\vec{x}$  is 1-1 & onto (Bijection)

**Relation** | **GS,LI,Basis,dim**: Let *V* be vector space. *L* is linearly independent set, *E* is generating set, *B* is basis set.

- 1. **GS**|**LI**:  $|L| \le |E|$  (can get: dim unique) **LI** $\rightarrow$ **Basis**: If V finite generate  $\Rightarrow \forall L$  can extend to a basis. If  $L = \emptyset$ , prove  $\exists B$
- 2. **Basis**|max,min:  $B \Leftrightarrow B$  is minimal GS (E)  $\Leftrightarrow B$  is maximal LI (L). **Uniqueness**|Basis: 每个元素都可以由 basis 唯一表示.
- 3. **Proper Subspaces**: If  $U \subset V$  is proper subspace, then  $\dim U < \dim V$ .  $\Rightarrow$  If  $U \subseteq V$  is subspace and  $\dim U = \dim V$ , then U = V.
- 4. **Dimension Theorem**: If  $U, W \subseteq V$  are subspaces of V, then  $\dim(U + W) = \dim U + \dim W \dim(U \cap W)$ **Complementary**:  $U, W \subseteq V, U, V$  subspaces are complementary  $(V = U \oplus W)$  if:  $\exists \phi : U \times W \to V$  by  $(\vec{u}, \vec{w}) \mapsto \vec{u} + \vec{w}$

i.e.  $\forall \vec{v} \in V$ , we have unique  $\vec{u} \in U$ ,  $\vec{w} \in W$  s.t.  $\vec{v} = \vec{u} + \vec{w}$ . ps: It's a linear map.

3 Linear Mapping | Rank-Nullity | Matrices | Change of Basis ps: \#\(\mathre{\pi}\)\ \(\mu\_{\text{F-Vector Spaces.}}\)

**Linear Mapping/Homomorphism(Hom)**:  $f: V \to W$  is linear map if:  $\forall \vec{v}_1, \vec{v}_2 \in V, \forall \lambda \in F.$   $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$  and  $f(\lambda \vec{v}_1) = \lambda f(\vec{v}_1)$ 

- $\textbf{· Isomorphism} : = \text{LM \& Bij.} \quad \textbf{Endomorphism(End)} : = \text{LM \& } V = W. \quad \textbf{Automorphism(Aut)} : = \text{LM \& } V = W \quad \textbf{Monomorphism} : = \text{LM \& 1-1.} \quad \textbf{Epimorphism} : = \text{LM \& onto.}$
- $\textbf{\cdot Kernel} : \ker f := \{ \vec{v} \in V : f(\vec{v}) = \vec{0} \} \\ (\text{It's subspace}) \quad \textbf{Image} : Imf := \{ f(\vec{v}) : \vec{v} \in V \} \\ (\text{It's subspace}) \quad \textbf{Rank} := \dim(Imf) \quad \textbf{Nullity} := \dim(\ker f) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f := \{ x \in X : f(x) = x \} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f$

**Property of Linear Map**: Let  $f, g \in Hom$ :  $\mathbf{a}. f(\vec{0}) = \vec{0}$   $\mathbf{b}. f$  is 1-1 iff  $\ker f = \{\vec{0}\}$   $\mathbf{c}. f \circ g$  is linear map.

- 1. **Determined**: f is determined by  $f(\vec{b_i}), \vec{b_i} \in \mathcal{B}_{basis}$  (\*i.e.  $f(\sum_i \lambda_i \vec{v_i}) \coloneqq \sum_i \lambda_i f(\vec{v_i})$ )
- 2. **Classification of Vector Spaces**: dim  $V = n \Leftrightarrow f : F^n \stackrel{\sim}{\to} V$  by  $f(\lambda_1, ..., \lambda_n) \mapsto \sum_{i=1}^n \lambda_i \vec{v_i}$  is isomorphism.

**Rank-Nullity Theorem**: For linear map  $f: V \to W$ , dim  $V = \dim(\ker f) + \dim(Imf)$  Following are properties:

- 1. **Injection**: f is  $1-1 \Rightarrow \dim V \le \dim W$  **Surjection**: f is onto  $\Rightarrow \dim V \ge \dim W$  Moreover,  $\dim W = \dim \inf f$  iff f is onto.
- 2. **Same Dimension**: f is isomorphism  $\Rightarrow$  dim  $V = \dim W$  **Matrix**:  $\forall M$ , column rank  $c(M) = \operatorname{row} \operatorname{rank} r(M)$ .
- 3. **Relation**: If V, W finite generate, and dim  $V = \dim W$ , Then: f is isomorphism  $\Leftrightarrow f$  is 1-1  $\Leftrightarrow f$  is onto.

**Matrix**: For  $A_{n\times m}$ ,  $B_{m\times p}$ ,  $AB_{n\times p}:=(AB)_{ij}=\sum_{k=1}^m a_{ik}b_{kj}$  **Transpose**:  $A_{m\times n}^T:=(A^T)_{ij}=a_{ji}$ 

**Invertible Matrices**: *A* is invertible if  $\exists B, C$  s.t. BA = I and AC = I

**Representing matrix of linear map**  $_{\mathcal{B}}[f]_{\mathcal{A}}: f: V \to W$  be linear map,  $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of  $V, \mathcal{B} = \{\vec{w_1}, ..., \vec{w_m}\}$  is basis of W.

Then  $_{\mathcal{B}}[f]_{\mathcal{A}} = A \text{ (matrix) where } f(\vec{v}_{i \in \mathcal{A}}) = \sum_{j \in \mathcal{B}} A_{ji} \vec{w}_j \qquad \exists \phi : Mat(n \times m; F) \xrightarrow{\sim} Hom_F(F^m, F^n) \Rightarrow [\ [f] = I \Leftrightarrow f = id\ ]$ 

- Theorems:  $[f \circ g] = [f] \circ [g]$   $\mathcal{C}[f \circ g]_{\mathcal{A}} = \mathcal{C}[f]_{\mathcal{B}} \circ_{\mathcal{B}}[g]_{\mathcal{A}}$   $\mathcal{B}[f(\vec{v})] =_{\mathcal{B}}[f]_{\mathcal{A}} \circ_{\mathcal{A}}[\vec{v}]$
- 4 Rings | Polynomials | Ideals | Subrings
- 5 Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint
- 6 Jordan Normal Form | Spectral Theorem