

1 Basic Knowledge

Def of Group $(G, *)$: A set G with a operator $*$ is a group if: **Closure**: $\forall g, h \in G, g * h \in G$; **Associativity**: $\forall g, h, k \in G, (g * h) * k = g * (h * k)$; **Identity**: $\exists e \in G, \forall g \in G, e * g = g * e = g$; **Inverse**: $\forall g \in G, \exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e$. G, H groups, then $G \times H$ also.

Field (F) : A set F is a field with two operators: (addition) $+$: $F \times F \rightarrow F; (\lambda, \mu) \rightarrow \lambda + \mu$ (multiplication) \cdot : $F \times F \rightarrow F; (\lambda, \mu) \rightarrow \lambda \mu$ if: $(F, +)$ and $(F \setminus \{0_F\}, \cdot)$ are abelian groups with identity $0_F, 1_F$. and $\lambda(\mu + \nu) = \lambda\mu + \lambda\nu$ e.g. *Fields*: $\mathbb{R}, \mathbb{C}, \mathbb{Q}, \mathbb{Z}/p\mathbb{Z}$

F-Vector Space (V): A set V over a field F is a vector space if: V is an abelian group $V = (V, +)$ and $\forall \vec{v}, \vec{w} \in V, \lambda, \mu \in F$
 $\exists \text{ map } F \times V \rightarrow V: (\lambda, \vec{v}) \rightarrow \lambda \vec{v}$ satisfies: **I**: $\lambda(\vec{v} + \vec{w}) = (\lambda \vec{v}) + (\lambda \vec{w})$ **II**: $(\lambda + \mu)\vec{v} = (\lambda \vec{v}) + (\mu \vec{v})$ **III**: $\lambda(\mu \vec{v}) = (\lambda \mu)\vec{v}$ **IV**: $1_F \vec{v} = \vec{v}$

Vector Subspaces Criterion: $U \subseteq V$ is a subspace of V if: **I**. $\vec{0} \in U$ **II**. $\forall \vec{u}, \vec{v} \in U, \forall \lambda \in F: \lambda \vec{u} + \vec{v} \in U$ and $\lambda \vec{u} \in U$ (or: $\lambda \vec{u} + \mu \vec{v} \in U$)
property: If U, W are subspaces of V , then $U \cap W$ and $U + W$ are also subspaces of V . ps: $U + W := \{\vec{u} + \vec{w} : \vec{u} \in U, \vec{w} \in W\}$

Complement-wise Operations: $\phi: V_1 \times V_2 \rightarrow V_1 \oplus V_2$ by $I: (\vec{v}_1, \vec{u}_1) + (\vec{v}_2, \vec{u}_2) := (\vec{v}_1 + \vec{v}_2, \vec{u}_1 + \vec{u}_2), \lambda(\vec{v}, \vec{u}) := (\lambda \vec{v}, \lambda \vec{u})$ (ps: V_1, V_2 通过 ϕ 定义的 map 所形成的 vector space 记作 $V_1 \oplus V_2$)

Projections: $pr_i: X_1 \times \dots \times X_n \rightarrow X_i$ by $(x_1, \dots, x_n) \mapsto x_i$ **Canonical Injections**: $in_i: X_i \rightarrow X_1 \times \dots \times X_n$ by $x \mapsto (0, \dots, 0, x, 0, \dots, 0)$

2 Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis

Generating (subspaces) $\langle T \rangle$: $\langle T \rangle := \{\alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n : \alpha_i \in F, \vec{v}_i \in T, r \in \mathbb{N}\}$ $\langle \emptyset \rangle := \{\vec{0}\}$ If T is subspace $\Rightarrow \langle T \rangle = T$.

- Proposition**: $\langle T \rangle$ is the smallest subspace containing T . (i.e. $\langle T \rangle$ is the intersection of all subspaces containing T)
- Generating Set**: V is vector space, $T \subseteq V$. T is generating set of V if $\langle T \rangle = V$. **Finitely Generated**: \exists finite set $T, \langle T \rangle = V$
- External Direct Sum**: 一个“代数结构”, 定义为 set 是 $V_1 \oplus \dots \oplus V_n := V_1 \times \dots \times V_n$ 且有一组运算法则 component-wise operations
- Connect to Matrix**: Let $E = \{\vec{v}_1, \dots, \vec{v}_n\}$, E is GS of V . Let $A = [\vec{v}_1, \dots, \vec{v}_n] \Rightarrow \forall \vec{b} \in V, \exists \vec{x} = (x_1, \dots, x_n)^T$ s.t. $A\vec{x} = \vec{b}$ (i.e. linear map: $\phi: \vec{x} \mapsto A\vec{x}$ is surjective)

Linearly Independent: $L = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r\}$ is linearly independent if: $\forall c_1, \dots, c_r \in F, c_1 \vec{v}_1 + \dots + c_r \vec{v}_r = \vec{0} \Rightarrow c_1 = \dots = c_r = 0$.

Connect to Matrix: Let $L = \{\vec{v}_1, \dots, \vec{v}_n\}$, L is LI of V . Let $A = [\vec{v}_1, \dots, \vec{v}_n] \Rightarrow \forall \vec{x} \in F^n, A\vec{x} = \vec{0}$ (or $\vec{0} \Rightarrow \vec{x} = \vec{0}$) (i.e. linear map $\phi: \vec{x} \mapsto A\vec{x}$ is injective)

Basis & Dimension: If V is finitely generated. $\Rightarrow \exists$ subset $B \subseteq V$ which is both LI and GS. (B is basis) **Dim**: $\dim V := |B|$

Connect to Matrix: Let $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ is basis of V . Let $A = [\vec{v}_1, \dots, \vec{v}_n] \Rightarrow \forall \vec{x} = (x_1, \dots, x_n)^T$ s.t. $\phi: \vec{x} \mapsto A\vec{x}$ is 1-1 & onto (Bijection)

Relation|GS,LI,Basis,dim: Let V be vector space. L is linearly independent set, E is generating set, B is basis set.

- GS|LI**: $|L| \leq |E|$ (can get: dim unique) **LI→Basis**: If V finite generate $\Rightarrow \forall L$ can extend to a basis. If $L = \emptyset$, prove $\exists B$
- Basis|max,min**: $B \Leftrightarrow B$ is minimal GS (E) $\Leftrightarrow B$ is maximal LI (L). **Uniqueness|Basis**: 每个元素都可以由 basis 唯一表示.
- Proper Subspaces**: If $U \subset V$ is proper subspace, then $\dim U < \dim V$. \Rightarrow If $U \subseteq V$ is subspace and $\dim U = \dim V$, then $U = V$.
- Dimension Theorem**: $\dim(U + W) = \dim U + \dim W - \dim(U \cap W)$