## 1 Basic Knowledge

# **HAlg Note**

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Def of Group (G, *): A set G with a operator * is a group if: Closure: \forall g, h \in G, g * h \in G; Associativity: \forall g, h, k \in G, (g * h) * k = g * (h * k); Identity: \exists e \in G, \forall g \in G, e * g = g * e = g; Inverse: \forall g \in G, \exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e. G, H groups, then G \times H also. Field (F): A set F is a field with two operators: (addition)+: F \times F \to F; (\lambda, \mu) \to \lambda + \mu (multiplication)·: F \times F \to F; (\lambda, \mu) \to \lambda \mu if: (F, +) and (F \setminus \{0_F\}, \cdot) are abelian groups with identity 0_F, 1_F. and \lambda(\mu + \nu) = \lambda \mu + \lambda \nu e.g.Fields: \mathbb{R}, \mathbb{C}, \mathbb{Q}, \mathbb{Z}/p\mathbb{Z} = \mathbb{F}_p F-Vector Space (V): A set V over a field F is a vector space if: V is an abelian group V = (V, +) and \forall \vec{v}, \vec{w} \in V \lambda, \mu \in F e.g. Poly: \mathbb{R}[x]_{< n} = map F \times V \to V : (\lambda, \vec{v}) \to \lambda \vec{v} satisfies: \mathbf{I}: \lambda(\vec{v} + \vec{w}) = (\lambda \vec{v}) + (\lambda \vec{w}) \mathbf{II}: (\lambda + \mu)\vec{v} = (\lambda \vec{v}) + (\mu \vec{v}) \mathbf{III}: \lambda(\mu \vec{v}) = (\lambda \mu)\vec{v} \mathbf{IV}: 1_F \vec{v} = \vec{v} Vector Subspaces Criterion: U \subseteq V is a subspace of V if: \mathbf{I}. \vec{0} \in U \mathbf{II}. \forall \vec{u}, \vec{v} \in U, \forall \lambda \in F: \vec{u} + \vec{v} \in U and \lambda \vec{u} \in U (or: \lambda \vec{u} + \mu \vec{v} \in U) \cdot property: If U, W are subspaces of V, then U \cap W and U + W are also subspaces of V. ps: U + W := \{\vec{u} + \vec{w} : \vec{u} \in U, \vec{w} \in W\} Complement-wise Operations: \phi: V_1 \times V_2 \to V_1 \oplus V_2 by \mathbf{I}: (\vec{v_1}, \vec{u_1}) + (\vec{v_2}, \vec{u_2}) := (\vec{v_1} + \vec{v_1}, \vec{u_1} + \vec{u_2}), \lambda(\vec{v}, \vec{u}) := (\lambda \vec{v}, \lambda \vec{u}) (ps:V_1, V_2 \cong \mathcal{U} \neq \mathcal{U} \cong \mathcal{U} \cong \mathcal{U} \cong \mathcal{U}) Projections: pr_i: X_1 \times \cdots \times X_n \to X_i by (x_1, ..., x_n) \mapsto x_i Canonical Injections: in_i: X_i \to X_1 \times \cdots \times X_n by x \mapsto (0, ..., 0, x, 0, ..., 0)
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### 2 Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis

**Generating (subspaces)**  $\langle T \rangle$ :  $\langle T \rangle := \{ \alpha_1 \vec{v_1} + \dots + \alpha_n \vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, r \in \mathbb{N} \}$   $\langle \emptyset \rangle := \{ \vec{0} \}$  If T is subspace  $\Rightarrow \langle T \rangle = T$ .

- 1. **Proposition**:  $\langle T \rangle$  is the smallest subspace containing T. (i.e.  $\langle T \rangle$  is the intersection of all subspaces containing T)
- 2. **Generating Set**: *V* is vector space,  $T \subseteq V$ . *T* is generating set of *V* if  $\langle T \rangle = V$ . **Finitely Generated**:  $\exists$  finite set T,  $\langle T \rangle = V$
- 3. **External Direct Sum**: 一个" 代数结构", 定义为 set 是  $V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n$  且有一组运算法则 component-wise operations
- 4. **Connect to Matrix**: Let  $E = \{\vec{v_1}, ..., \vec{v_n}\}$ , E is GS of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{b} \in V$ ,  $\exists \vec{x} = (x_1, ..., x_n)^T$  s.t.  $A\vec{x} = \vec{b}$  (i.e. linear map: $\phi : \vec{x} \mapsto A\vec{x}$  is surjective) **Linearly Independent**:  $L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\}$  is linearly independent if:  $\forall c_1, ..., c_r \in F$ ,  $c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0$ .
- Connect to Matrix: Let  $L = \{\vec{v_1}, ..., \vec{v_n}\}$ , L is LI of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} \in F^n$ ,  $A\vec{x} = 0$  (or  $\vec{0}$ )  $\Rightarrow \vec{x} = 0$ (or  $\vec{0}$ ) (i.e. linear map  $\phi: \vec{x} \mapsto A\vec{x}$  is injective)

**Basis & Dimension**: If V is finitely generated.  $\Rightarrow \exists$  subset  $B \subseteq V$  which is both LI and GS. (B is basis) **Dim**: dim V := |B|

• **Connect to Matrix**: Let  $B = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of V. Let  $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T$  s.t.  $\phi : \vec{x} \mapsto A\vec{x}$  is 1-1 & onto (Bijection)

**Relation**|**GS,LI,Basis,dim**: Let *V* be vector space. *L* is linearly independent set, *E* is generating set, *B* is basis set.

- 1. **GS|LI**:  $|L| \le |E|$  (can get: dim unique) **LI** $\rightarrow$ **Basis**: If V finite generate  $\Rightarrow \forall L$  can extend to a basis. If  $L = \emptyset$ , prove  $\exists B$
- 2. **Basis**|max,min:  $B \Leftrightarrow B$  is minimal GS  $(E) \Leftrightarrow B$  is maximal LI (L). **Uniqueness**|Basis: 每个元素都可以由 basis 唯一表示.
- 3. **Proper Subspaces**: If  $U \subset V$  is proper subspace, then  $\dim U < \dim V$ .  $\Rightarrow$  If  $U \subseteq V$  is subspace and  $\dim U = \dim V$ , then U = V.
- 4. **Dimension Theorem**: If  $U, W \subseteq V$  are subspaces of V, then  $\dim(U+W) = \dim U + \dim W \dim(U\cap W)$

**Complementary**:  $U, W \subseteq V, U, V$  subspaces are complementary  $(V = U \oplus W)$  if:  $\exists \phi : U \times W \to V$  by  $(\vec{u}, \vec{w}) \mapsto \vec{u} + \vec{w}$  i.e.  $\forall \vec{v} \in V$ , we have unique  $\vec{u} \in U, \vec{w} \in W$  s.t.  $\vec{v} = \vec{u} + \vec{w}$ . ps: It's a linear map.

#### 3 Linear Mapping | Rank-Nullity | Matrices | Change of Basis ps: #til V, W F-Vector Space

**Linear Mapping/Homomorphism(Hom)**:  $f: V \to W$  is linear map if:  $\forall \vec{v}_1, \vec{v}_2 \in V, \forall \lambda \in F$ .  $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$  and  $f(\lambda \vec{v}_1) = \lambda f(\vec{v}_1)$ 

- Isomorphism: = LM & Bij. Endomorphism(End): = LM & V = W. Automorphism(Aut): = LM & V = W Monomorphism: = LM & 1-1. Epimorphism: = LM & onto.
- $\textbf{Kernel}: \ker f := \{\vec{v} \in V : f(\vec{v}) = \vec{0}\} \\ (\text{It's subspace}) \quad \textbf{Image}: Imf := \{f(\vec{v}) : \vec{v} \in V\} \\ (\text{It's subspace}) \quad \textbf{Rank} := \dim(Imf) \quad \textbf{Nullity} := \dim(\ker f) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f : X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x) = x\} \\ (\text{It's Subspace}) \quad \textbf{Fixed Point } X^f := \{x \in X : f(x) = x\} \\$

**Property of Linear Map**: Let  $f, g \in Hom$ :  $\mathbf{a}.f(\vec{0}) = \vec{0}$   $\mathbf{b}. f$  is 1-1 iff  $\ker f = {\vec{0}}$   $\mathbf{c}. f \circ g$  is linear map.

- 1. **Determined**: f is determined by  $f(\vec{b_i})$ ,  $\vec{b_i} \in \mathcal{B}_{basis}$  (\* i.e.  $f(\sum_i \lambda_i \vec{v_i}) := \sum_i \lambda_i f(\vec{v_i})$ )
- 2. **Classification of Vector Spaces**: dim  $V = n \Leftrightarrow f : F^n \xrightarrow{\sim} V$  by  $f(\lambda_1, ..., \lambda_n) \mapsto \sum_{i=1}^n \lambda_i \vec{v_i}$  is isomorphism.
- 3. **Left/Right Inverse**: f is  $1-1 \Rightarrow \exists$  left inverse g s.t.  $g \circ f = id$  考虑 direct sum f is onto  $\Rightarrow \exists$  right inverse g s.t.  $f \circ g = id$
- 4.  $\Theta$  More of Left/Right Inverse:  $f \circ g = id \Rightarrow g$  is 1-1 and f is onto.  $\oplus$  # kernel=0 # ж# #

**Rank-Nullity Theorem**: For linear map  $f: V \to W$ , dim  $V = \dim(\ker f) + \dim(Imf)$  Following are properties:

- 1. **Injection**: f is 1-1  $\Rightarrow$  dim  $V \le \dim W$  **Surjection**: f is onto  $\Rightarrow$  dim  $V \ge \dim W$  Moreover, dim  $W = \dim imf$  iff f is onto.
- 2. **Same Dimension**: f is isomorphism  $\Rightarrow$  dim  $V = \dim W$  **Matrix**:  $\forall M$ , column rank  $c(M) = \operatorname{row} \operatorname{rank} r(M)$ .
- 3. **Relation**: If V, W finite generate, and dim  $V = \dim W$ , Then: f is isomorphism  $\Leftrightarrow f$  is 1-1  $\Leftrightarrow f$  is onto.

**Matrix**: For  $A_{n \times m}$ ,  $B_{m \times p}$ ,  $AB_{n \times p} := (AB)_{ij} = \sum_{k=1}^{m} a_{ik} b_{kj}$  **Transpose**:  $A_{m \times n}^{T} := (A^{T})_{ij} = a_{ji}$   $[a^{-1}] = [a]^{-1}$ 

**Invertible Matrices**: *A* is invertible if  $\exists B, C$  s.t. BA = I and AC = I ||  $\exists B, BA = I \Leftrightarrow \exists C, AC = I \Leftrightarrow \exists A^{-1}$ 

**Representing matrix of linear map**  $_{\mathcal{B}}[f]_{\mathcal{A}}: f: V \to W$  be linear map,  $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$  is basis of  $V, \mathcal{B} = \{\vec{w_1}, ..., \vec{w_m}\}$  is basis of W.

Then  $_{\mathcal{B}}[f]_{\mathcal{A}} = A$  (matrix) where  $f(\vec{v}_{i \in \mathcal{A}}) = \sum_{j \in \mathcal{B}} A_{ji} \vec{w}_j \qquad \exists \phi : Hom_F(V, W) \xrightarrow{\sim} Mat(n \times m; F)$ 

· Theorems:  $[f \circ g] = [f] \circ [g]$   $c[f \circ g]_{\mathcal{A}} = c[f]_{\mathcal{B}} \circ_{\mathcal{B}} [g]_{\mathcal{A}}$   $g[f(\vec{v})] =_{\mathcal{B}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [\vec{v}]$   $\mathcal{A}[f]_{\mathcal{A}} = I \Leftrightarrow f = id$ Elementary Matrix:  $I + \lambda E_{ij}$  (cannot  $I - E_{ii}$ ) 就是初等矩阵, 左乘代表 j 行乘  $\lambda$  倍加到第 i 行, 右乘代表 j 列乘  $\lambda$  倍加到第 i 列  $\Rightarrow$  Invertible! · 交换 i, j 列/行:  $P_{ij} = diag(1, ..., 1, -1, 1, ..., 1)(I + E_{ij})(I - E_{ji})(I + E_{ij})$  where -1 in jth place.

Row Echelon Form | Smith Normal Form: A: REF 通过左乘初等矩阵可以实现 A: S(n, m, r) 通过  $\tilde{A}$  右乘初等矩阵可以实现

· Smith Normal Form:  $\forall A, \exists$  invertible P, Q s.t.  $PAQ = S(n, m, r) := n \times m$  的矩阵, 对角线前 r 个是 1, 后面 0. Lemma: r = r(A) = c(A)

## 4 Rings | Polynomials | Ideals | Subrings

- 5 Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint
- 6 Jordan Normal Form | Spectral Theorem