HAlg Note

1 Basic Knowledge

Def of Group $(G, *)$: A set G with a operator $*$ is a group if: **Closure**: $\forall g, h \in G, g * h \in G$; **Associativity**: $\forall g, h, k \in G, (g * h) * k = g * (h * k)$;
Identity: $\exists e \in G, \forall g \in G, e * g = g * e = g$; **Inverse**: $\forall g \in G, \exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e$. G, H groups, then $G \times H$ also.

Field (F): A set F is a field with two operators: (addition)$+ : F \times F \to F; (\lambda, \mu) \to \lambda + \mu$ (multiplication)$\cdot : F \times F \to F; (\lambda, \mu) \to \lambda\mu$ if:
$(F, +)$ and $(F \setminus \{0_F\}, \cdot)$ are abelian groups with identity $0_F, 1_F$. and $\lambda(\mu + \nu) = \lambda\mu + \lambda\nu$ $e.g. Fields : \mathbb{R}, \mathbb{C}, \mathbb{Q}, \mathbb{Z}/p\mathbb{Z}$

F-Vector Space (V): A set V over a field F is a vector space if: V is an abelian group $V = (V, \dot{+})$ and $\forall \vec{v}, \vec{w} \in V$ $\lambda, \mu \in F$
$\exists$ map $F \times V \to V : (\lambda, \vec{v}) \to \lambda\vec{v}$ satisfies: **I**: $\lambda(\vec{v} \dot{+} \vec{w}) = (\lambda\vec{v}) \dot{+} (\lambda\vec{w})$ **II**: $(\lambda + \mu)\vec{v} = (\lambda\vec{v}) \dot{+} (\mu\vec{v})$ **III**: $\lambda(\mu\vec{v}) = (\lambda\mu)\vec{v}$ **IV**: $1_F\vec{v} = \vec{v}$

Vector Subspaces Criterion: $U \subseteq V$ is a subspace of V if: **I**. $\vec{0} \in U$ **II**. $\forall \vec{u}, \vec{v} \in U, \forall \lambda \in F$: $\vec{u} + \vec{v} \in U$ and $\lambda\vec{u} \in U$ (or: $\lambda\vec{u} + \mu\vec{v} \in U$)

· **property**: If U, W are subspaces of V, then $U \cap W$ and $U + W$ are also subspaces of V. ps: $U + W := \{\vec{u} + \vec{w} : \vec{u} \in U, \vec{w} \in W\}$

Complement-wise Operations: $\phi : V_1 \times V_2 \to V_1 \oplus V_2$ by **I**:$(\vec{v_1}, \vec{u_1}) + (\vec{v_2}, \vec{u_2}) := (\vec{v_1} + \vec{v_1}, \vec{u_1} + \vec{u_2})$, $\lambda(\vec{v}, \vec{u}) := (\lambda\vec{v}, \lambda\vec{u})$ (ps:V_1, V_2 通过 ϕ 定义的 map 所形成的 vector space 记作 $V_1 \oplus V_2$)

Projections: $pr_i : X_1 \times \cdots \times X_n \to X_i$ by $(x_1, ..., x_n) \mapsto x_i$ **Canonical Injections**: $in_i : X_i \to X_1 \times \cdots \times X_n$ by $x \mapsto (0, ..., 0, x, 0, ..., 0)$

2 Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis

Generating (subspaces) $\langle T \rangle$: $\langle T \rangle := \{\alpha_1\vec{v_1} + \cdots + \alpha_n\vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, r \in \mathbb{N}\}$ $\langle \emptyset \rangle := \{\vec{0}\}$ If T is subspace $\Rightarrow \langle T \rangle = T$.

1. **Proposition**: $\langle T \rangle$ is the smallest subspace containing T. (i.e. $\langle T \rangle$ is the intersection of all subspaces containing T)
2. **Generating Set**: V is vector space, $T \subseteq V$. T is generating set of V if $\langle T \rangle = V$. **Finitely Generated**: $\exists$ finite set $T, \langle T \rangle = V$
3. **External Direct Sum**: 一个" 代数结构", 定义为 set 是 $V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n$ 且有一组运算法则 component-wise operations
4. **Connect to Matrix**: Let $E = \{\vec{v_1}, ..., \vec{v_n}\}$, E is GS of V. Let $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{b} \in V, \exists \vec{x} = (x_1, ..., x_n)^T$ s.t. $A\vec{x} = \vec{b}$ (i.e. linear map:$\phi : \vec{x} \mapsto A\vec{x}$ is surjective)

Linearly Independent: $L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\}$ is linearly independent if: $\forall c_1, ..., c_r \in F, c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0$.

· **Connect to Matrix**: Let $L = \{\vec{v_1}, ..., \vec{v_n}\}$, L is LI of V. Let $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} \in F^n, A\vec{x} = 0\ (or\ \vec{0}) \Rightarrow \vec{x} = 0 (or\ \vec{0})$ (i.e. linear map ϕ:$\vec{x} \mapsto A\vec{x}$ is injective)

Basis & Dimension: If V is finitely generated. $\Rightarrow \exists$ subset $B \subseteq V$ which is both LI and GS. (B is basis) **Dim**: $\dim V := |B|$

· **Connect to Matrix**: Let $B = \{\vec{v_1}, ..., \vec{v_n}\}$ is basis of V. Let $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T$ s.t. $\phi : \vec{x} \mapsto A\vec{x}$ is 1-1 & onto (Bijection)

Relation|GS,LI,Basis,dim: Let V be vector space. L is linearly independent set, E is generating set, B is basis set.

1. **GS|LI**: $|L| \leq |E|$ (can get: dim unique) **LI→Basis**: If V finite generate $\Rightarrow \forall L$ can extend to a basis. If $L = \emptyset$, prove $\exists B$
2. **Basis|max,min**: $B \Leftrightarrow B$ is minimal GS $(E) \Leftrightarrow B$ is maximal LI (L). **Uniqueness|Basis**: 每个元素都可以由 basis 唯一表示.
3. **Proper Subspaces**: If $U \subset V$ is proper subspace, then $\dim U < \dim V$. $\Rightarrow$ If $U \subseteq V$ is subspace and $\dim U = \dim V$, then $U = V$.
4. **Dimension Theorem**: $\dim(U + W) = \dim U + \dim W - \dim(U \cap W)$

3 Linear Mapping | Rank-Nullity| Matrices | Change of Basis

4 Rings | Polynomials | Ideals | Subrings

5 Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint

6 Jordan Normal Form | Spectral Theorem