HAlg Note

Basic Knowledge

Lagrange's Theorem: If $H \subseteq G$ is a subgroup, then |H| divides |G|. **I**: If *G* is finite, then $g^{|G|} = e \forall g \in G$. **II**: o(g) | |G| **III**: If |G| = p prime, *G* is cyclic.

Complement-wise Operations: $\phi: V_1 \times V_2 \rightarrow V_1 \oplus V_2$ by $I: (\vec{v_1}, \vec{u_1}) + (\vec{v_2}, \vec{u_2}) := (\vec{v_1} + \vec{v_1}, \vec{u_1} + \vec{u_2})$, $\lambda(\vec{v}, \vec{u}) := (\lambda \vec{v}, \lambda \vec{u})$ (ps: $V_1.V_2$ 通过 ϕ 定义的 map 所形成的 vector space 记作 $V_1 \oplus V_2$)

External Direct Sum: 一个" 代数结构"(Vector Space), 定义为 set 是 $V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n$ 且有一组运算法则 component-wise operations

Projections: $pr_i: X_1 \times \cdots \times X_n \to X_i$ by $(x_1, ..., x_n) \mapsto x_i$ **Canonical Injections**: $in_i: X_i \to X_1 \times \cdots \times X_n$ by $x \mapsto (0, ..., 0, x, 0, ..., 0)$

2 Summary

Name	Group (<i>G</i> , *)	Ring $(R, +, \cdot)$	Vector Space $(F - V)$	Module $(R - M)$
Def	Closure : $g * h \in G$ $\forall g, h, k \in G$	$(R,+)$ is abelian group with $0_R \forall a,b,c \in R$	$(V, \dot{+})$ is abelian group $\forall \vec{v}, \vec{w} \in V$	$(M, \dot{+})$ is abelian group $\forall m_1, m_2 \in M$
	Associativity: $(g * h) * k = g * (h * k)$	(R,\cdot) is monoid with 1_R (monoid is closure)	$\exists \operatorname{map} F \times V \to V : (\lambda, \vec{v}) \to \lambda \vec{v} \qquad \forall \lambda, \mu \in F$	$\exists \; \mathrm{map} \; R \times M \to M : (r,m) \to rm \qquad \qquad \forall \; r_1, r_2 \in R$
	Identity: $\exists e \in G, e * g = g * e = g$	i.e. Associativity: , $(a \cdot b) \cdot c = a \cdot (b \cdot c)$	I: $\lambda(\vec{v} \dotplus \vec{w}) = (\lambda \vec{v}) \dotplus (\lambda \vec{w})$	$\mathbf{I}: r(m_1 \dotplus m_2) = (\lambda m_1) \dotplus (\lambda m_2)$
	Inverse: $\exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e$	Identity: $1_R \cdot a = a \cdot 1_R = a$	$\mathbf{II}: (\lambda + \mu)\vec{v} = (\lambda\vec{v}) \dotplus (\mu\vec{v})$	$\mathbf{II}: (r_1 + r_2)m_1 = (r_1m_1) \dotplus (r_1m_1)$
		Distributive : $a \cdot (b + c) = a \cdot b + a \cdot c$	$\mathbf{III} : \lambda(\mu \vec{v}) = (\lambda \mu) \vec{v}$	III: $r_1(r_2m_1) = (r_1r_2)m_1$
		$(b+c)\cdot a = b\cdot a + c\cdot a$	$IV: 1_F \vec{v} = \vec{v}$	$IV: 1_R m_1 = m_1$
Prop	$\mathbf{I}: (gh)^{-1} = h^{-1}g^{-1}$	$\mathbf{I.}\ 0 \cdot a = a \cdot 0 = 0 \qquad \forall a, b \in R$	$\mathbf{I.} \ 0\vec{v} = 0 \ \text{and} \ \vec{0}\lambda = \vec{0} \qquad \forall \vec{v} \in V, \lambda \in F$	$\mathbf{I.} \ 0_R m = 0_M \ ; r 0_M = 0_M \qquad \forall r \in R, m \in M$
		$\mathbf{II.} (-a) \cdot b = a \cdot (-b) = -(a \cdot b)$	$\mathbf{II.} (-1)\vec{v} = -\vec{v}$	II. (-r)m = r(-m) = -(rm)
		Commutative Ring: add $\forall a, b \in R, ab = ba$	III. $\lambda \vec{v} = \vec{0} \Leftrightarrow \lambda = 0 \text{ or } \vec{v} = \vec{0} \star$	
Remark	$G, H \text{ groups} \Rightarrow G \times H \text{ also.}$	For ring R [$1_R = 0_R \Leftrightarrow R = \{0\}$]		
e.g.	Cyclic group; GL_n ; D_n ; $\mathbb Z$	$Mat(n,F); R[X]; \mathbb{Z}/m\mathbb{Z}; \mathbb{Z}$	$\mathbb{R}[x]_{\leq n}$; $Mat(n,F)$; $Hom(V,W)$	$R=\mathbb{Z}$ Abelian Group; $R=F$ Vector Space
Sub	Subgroup (<i>H</i>) : $\forall h_1, h_2 \in H$	Subring (R') : $\forall a, b \in R'$	Subspace (U): $\forall \vec{v}, \vec{u} \in U, \lambda, \mu \in F$	Submodule (M') : $\forall m_1, m_2 \in M'$
objects	I: <i>H</i> ≠ Ø;	I. $1_R \in R'$	I. 0 ∈ U	$\mathbf{I.} \ 0_{M} \in M' \qquad \forall r_{1}, r_{2} \in R$
	$\mathbf{II}: h_1 * h_2 \in H;$	II. $a - b \in R'$	II. $\vec{u} + \vec{v} \in U$ and $\lambda \vec{u} \in U$	II. $m_1 - m_2 \in M'$ and $r_1 m_1 \in M'$
	III: $h_1^{-1} \in H$.	III. $ab \in R'$	(or: $\lambda \vec{u} + \mu \vec{v} \in U$)	(or: $r_1 m_1 - r_2 m_2 \in M'$)
Create	H, K subgroups $\Rightarrow H \cap K$ also.	$R, S \text{ subring} \Rightarrow R \cap S \text{ also.}$	$V, W \text{ subspaces} \Rightarrow V \cap W, V + W \text{ also.}$	M, N submodules $\Rightarrow M \cap N, M + N$ also.
Generate	Generated Group $\langle T \rangle$:	Generated Ideal $_R\langle T\rangle$: R is commutative ring	Generated subspaces (T):	Generated submodules $_R\langle T\rangle$
objects	$\langle T \rangle := \{ g_1^{a_1} g_k^{a_k} k \in \mathbb{N}, g_i \in T, a_i \in \mathbb{N} \}$	$_{R}\langle T\rangle := \{\sum_{i=1}^{n} r_{i}t_{i} : n \in \mathbb{N}, r_{i} \in R, t_{i} \in T\}$	$\langle T \rangle := \{ \alpha_1 \vec{v_1} + \dots + \alpha_n \vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, n \in \mathbb{N} \}$	$\langle T \rangle := \{ r_1 t_1 + \dots + r t_n : r_i \in R, t_i \in T, n \in \mathbb{N} \}$
Special	Cyclic Group : $\langle g \rangle = \{g^k k \in \mathbb{Z}\}$	Principal Ideal : $_R\langle a\rangle$ i.e. aR	$\langle \emptyset \rangle := \{ \vec{0} \}$	Cyclic submodule: If $M =_R \langle t \rangle$
Prop			(1)	
ттор		$\langle T \rangle$ is the smallest the {generated things} cont	1, 0,	
Homo	Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$	$\langle T \rangle$ is the smallest the {generated things} cont $f: R \to S$ hom: $\forall a, b \in R$	1, 0,	R-Hom : $f: M \to N$ $\forall a, b \in M, r \in R$
			taining T . ps: $\mathbb{R} \setminus T \subseteq R$ $T \subseteq M$	R-Hom : $f: M \to N \qquad \forall a, b \in M, r \in R$ I. $f(a+b) = f(a) + f(b)$
	Homomorphism: ϕ : G → H $\forall g_1, g_2 \in G$	$f: R \to S \text{ hom}: \forall a, b \in R$	taining T . ps: $\mathbb{R}^{1} \mathbb{R}^{2} T \subseteq R$ $^{4}T \subseteq M$ $f: V \to W \qquad \forall \vec{v}_{1}, \vec{v}_{2} \in V, \lambda \in F$	·
	Homomorphism: ϕ : G → H $\forall g_1, g_2 \in G$	$f: R \to S \text{ hom:} \qquad \forall a, b \in R$ $I. f(a+b) = f(a) + f(b)$	taining T . ps: $\mathbb{R} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$\mathbf{I}.f(a+b) = f(a) + f(b)$
Homo	Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$ I. $\phi(g_1 * g_2) = \phi(g_1) * \phi(g_2)$	$f: R \to S \text{ hom:} \qquad \forall a,b \in R$ $I. f(a+b) = f(a) + f(b)$ $II. f(ab) = f(a)f(b)$	taining T . ps: $\mathbb{R} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	I. $f(a+b) = f(a) + f(b)$ II. $f(ra) = rf(a)$
Homo	Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$ I. $\phi(g_1 * g_2) = \phi(g_1) * \phi(g_2)$ I: $\phi(e_G) = e_H$	$f: R \to S$ hom: $\forall a, b \in R$ I. $f(a+b) = f(a) + f(b)$ II. $f(ab) = f(a)f(b)$ I. $f(0_R) = 0_S$ $f(1_R) = 1_S$ NOT need	taining T . ps: $\mathbb{R} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	I. $f(a+b) = f(a) + f(b)$ II. $f(ra) = rf(a)$ I. $f(0_M) = 0_N$ $f(1_R) = 1_S$ NOT need
Homo	Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$ I. $\phi(g_1 * g_2) = \phi(g_1) * \phi(g_2)$ I: $\phi(e_G) = e_H$	$f: R \to S$ hom: $\forall a, b \in R$ I. $f(a+b) = f(a) + f(b)$ II. $f(ab) = f(a)f(b)$ I. $f(0_R) = 0_S$ $f(1_R) = 1_S$ NOT need II. $f(x-y) = f(x) - f(y)$	taining T . ps: $\mathbb{R} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	I. $f(a+b) = f(a) + f(b)$ II. $f(ra) = rf(a)$ I. $f(0_M) = 0_N$ $f(1_R) = 1_S$ NOT need
Ното	Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$ I. $\phi(g_1 * g_2) = \phi(g_1) * \phi(g_2)$ I: $\phi(e_G) = e_H$ II: $\phi(g^{-1}) = \phi(g)^{-1}$	$f: R \to S \text{ hom:}$ $\forall a, b \in R$ I. $f(a+b) = f(a) + f(b)$ II. $f(ab) = f(a)f(b)$ I. $f(0_R) = 0_S$ $f(1_R) = 1_S \text{ NOT need}$ II. $f(x-y) = f(x) - f(y)$ III. $f(a^n) = (f(a))^n$ $f(mx) = mf(x)$	f: $V \to W$ $\forall \vec{v}_1, \vec{v}_2 \in V, \lambda \in F$ I. $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$ II. $f(\vec{0}) = \vec{0}$ II. $f(\lambda \vec{v}_1) = \lambda f(\vec{v}_1) + \mu f(\vec{u})$ III. $f(\vec{0}) = \vec{0}$ III. $f(\vec{v}_1) = \lambda f(\vec{v}_1) + \mu f(\vec{v}_2)$ IIII. $f(\vec{v}_1) = \vec{v}_1 + \mu \vec{v}_2 + \mu \vec{v}_3 + \mu \vec{v}_4 + \mu \vec{v}_4$	I. $f(a + b) = f(a) + f(b)$ II. $f(ra) = rf(a)$ I. $f(0_M) = 0_N$ $f(1_R) = 1_S \text{ NOT need}$ II. $f(a - b) = f(a) - f(b)$
Homo Prop A	Homomorphism: $\phi: G \to H$ $\forall g_1, g_2 \in G$ I. $\phi(g_1 * g_2) = \phi(g_1) * \phi(g_2)$ I: $\phi(e_G) = e_H$ II: $\phi(g^{-1}) = \phi(g)^{-1}$ III. ϕ is $1 \cdot 1 \Leftrightarrow \ker \phi = \{e_G\}$	$f: R \to S \text{ hom:}$ $\forall a,b \in R$ I. $f(a+b) = f(a) + f(b)$ II. $f(ab) = f(a)f(b)$ I. $f(0_R) = 0_S$ $f(1_R) = 1_S \text{ NOT need}$ II. $f(x-y) = f(x) - f(y)$ III. $f(a^n) = (f(a))^n$ $f(mx) = mf(x)$ Iv. $f \text{ is } 1\text{-}1 \Leftrightarrow \ker f = \{0_R\}$	f: $V \to W$ $\forall \vec{v}_1, \vec{v}_2 \in V, \lambda \in F$ I. $f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2)$ II. $f(\lambda \vec{v}_1) = \lambda f(\vec{v}_1)$ I. $f(\vec{0}) = \vec{0}$ II. $f(\lambda \vec{v}_1 + \mu \vec{u}_2) = \lambda f(\vec{v}_1) + \mu f(\vec{u}_2)$ III. $f(\vec{v}_1) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$ III. $f(\vec{v}_1) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$ III. $f(\vec{v}_1) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$ III. $f(\vec{v}_2) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$ III. $f(\vec{v}_2) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$ III. $f(\vec{v}_2) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$ IV. $f(\vec{v}_2) = \lambda f(\vec{v}_2) + \mu f(\vec{v}_2)$	I. $f(a + b) = f(a) + f(b)$ II. $f(ra) = rf(a)$ I. $f(0_M) = 0_N$ $f(1_R) = 1_S \text{ NOT need}$ II. $f(a - b) = f(a) - f(b)$ III. $f \text{ is } 1\text{-}1 \text{ iff ker } f = \{0\}$

Normal $(H \triangleleft G)$: $H \subseteq G$ is normal if: $\forall g \in G$, gH = Hg

Property: **I**: $Ker\phi \lhd G$ **II**: ϕ is $1-1 \Rightarrow G \cong im\phi$

Ideal $(I \subseteq R)$: A subset $I \subseteq R$ (ring) is an ideal if: $I.I \neq \emptyset$ $II. \forall a, b \in I, a - b \in I$ $III. \forall i \in I, \forall r \in R, ri, ir \in I$ e.g. $m\mathbb{Z}$ **Property**: If I, J are *ideals* of R. Then I + J; $I \cap J$ are also ideals.

Field (F): A set F is a field with two operators: (addition) $+: F \times F \to F$; $(\lambda, \mu) \to \lambda + \mu$ (multiplication) $: F \times F \to F$; $(\lambda, \mu) \to \lambda \mu$ if: (F,+) and $(F\setminus\{0_F\},\cdot)$ are abelian groups with identity $0_F,1_F$. and $\lambda(\mu+\nu)=\lambda\mu+\lambda\nu$ $e.g.Fields:\mathbb{R},\mathbb{C},\mathbb{Q},\mathbb{Z}/p\mathbb{Z}=\mathbb{F}_p$ **Field**: For a ring R: Commutative ring + R has multiplicative inverse = Field.

Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis

Linearly Independent: $L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\}$ is linearly independent if: $\forall c_1, ..., c_r \in F$, $c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0$.

• Connect to Matrix: Let $L = \{\vec{v_1}, ..., \vec{v_n}\}$, L is LI of V. Let $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} \in F^n$, $A\vec{x} = 0 \ (or \ \vec{0}) \Rightarrow \vec{x} = 0 \ (or \ \vec{0})$ (i.e. linear map $\phi: \vec{x} \mapsto A\vec{x}$ is injective)

Basis & Dimension: If V is finitely generated. $\Rightarrow \exists$ subset $B \subseteq V$ which is both LI and GS. (B is basis) **Dim**: dim V := |B|

• **Connect to Matrix**: Let $B = \{\vec{v_1}, ..., \vec{v_n}\}$ is basis of V. Let $A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T$ s.t. $\phi : \vec{x} \mapsto A\vec{x}$ is 1-1 & onto (Bijection)

Relation[GS,LI,Basis,dim: Let V] be vector space. L is linearly independent set, E is generating set, B is basis set.

- 1. **GS|LI**: $|L| \le |E|$ (can get: dim unique) **LI** \to **Basis**: If V finite generate $\Rightarrow \forall L$ can extend to a basis. If $L = \emptyset$, prove $\exists B$ $kerf \cap imf = \{0\}$
- 2. **Basis**|max,min: $B \Leftrightarrow B$ is minimal GS $(E) \Leftrightarrow B$ is maximal LI (L). **Uniqueness**|Basis: 每个元素都可以由 basis 唯一表示.
- 3. **Proper Subspaces**: If $U \subset V$ is proper subspace, then dim $U < \dim V$. \Rightarrow If $U \subseteq V$ is subspace and dim $U = \dim V$, then U = V.
- 4. **Dimension Theorem**: If $U, W \subseteq V$ are subspaces of V, then $\dim(U + W) = \dim U + \dim W \dim(U \cap W)$

Complementary: $U, W \subseteq V, U, V$ subspaces are complementary $(V = U \oplus W)$ if: $\exists \phi : U \times W \to V$ by $(\vec{u}, \vec{w}) \mapsto \vec{u} + \vec{w}$ i.e. $\forall \vec{v} \in V$, we have unique $\vec{u} \in U$, $\vec{w} \in W$ s.t. $\vec{v} = \vec{u} + \vec{w}$. ps: It's a linear map.

4 Linear Mapping | Rank-Nullity | Matrices | Change of Basis ps: 默认 V, W F-Vector Spaces

4.1 Linear Mapping | Rank-Nullity

Property of Linear Map: Let $f, g \in Hom$

- 1. **Determined**: f is determined by $f(\vec{b_i})$, $\vec{b_i} \in \mathcal{B}_{basis}$ (* i.e. $f(\sum_i \lambda_i \vec{v_i}) := \sum_i \lambda_i f(\vec{v_i})$)
- 2. **Classification of Vector Spaces**: dim $V = n \Leftrightarrow f : F^n \stackrel{\sim}{\to} V$ by $f(\lambda_1, ..., \lambda_n) \mapsto \sum_{i=1}^n \lambda_i \vec{v_i}$ is isomorphism.
- 3. **Left/Right Inverse**: f is 1-1 \Rightarrow \exists left inverse g s.t. $g \circ f = id$ 考虑 direct sum f is onto \Rightarrow \exists right inverse g s.t. $f \circ g = id$
- 4. Θ More of Left/Right Inverse: $f \circ g = id \Rightarrow g$ is 1-1 and f is onto. 使用 kernel=0 来证明

Rank-Nullity Theorem: For linear map $f: V \to W$, dim $V = \dim(\ker f) + \dim(Imf)$ Following are properties:

- 1. **Injection**: f is $1-1 \Rightarrow \dim V \le \dim W$ **Surjection**: f is onto $\Rightarrow \dim V \ge \dim W$ Moreover, $\dim W = \dim imf$ iff f is onto.
- 2. **Same Dimension**: f is isomorphism \Rightarrow dim $V = \dim W$ **Matrix**: $\forall M$, column rank $c(M) = \operatorname{row} \operatorname{rank} r(M)$.
- 3. **Relation**: If V, W finite generate, and dim $V = \dim W$, Then: f is isomorphism $\Leftrightarrow f$ is 1-1 $\Leftrightarrow f$ is onto.

4.2 Matrices | Change of Basis | Similar Matrices | Trace

Matrix: For $A_{n\times m}$, $B_{m\times p}$, $AB_{n\times p}:=(AB)_{ij}=\sum_{k=1}^m a_{ik}b_{kj}$ **Transpose**: $A_{m\times n}^T:=(A^T)_{ij}=a_{ji}$

Invertible Matrices: A is invertible if $\exists B, C$ s.t. BA = I and AC = I || $\exists B, BA = I \Leftrightarrow \exists C, AC = I \Leftrightarrow \exists A^{-1}$ $_{\mathcal{B}}[f^{-1}]_{\mathcal{A}} =_{\mathcal{A}}[f]_{\mathcal{B}}^{-1}$

Representing matrix of linear map $_{\mathcal{B}}[f]_{\mathcal{A}}: f: V \to W$ be linear map, $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$ is basis of $V, \mathcal{B} = \{\vec{w_1}, ..., \vec{w_m}\}$ is basis of W.

- 1. $_{\mathcal{B}}[f]_{\mathcal{A}} := A \text{ (matrix) where } f(\vec{v}_{i \in \mathcal{A}}) = \sum_{j \in \mathcal{B}} A_{ji} \vec{w}_{j} \qquad \exists M_{\mathcal{B}}^{\mathcal{A}} : Hom_{F}(V, W) \xrightarrow{\sim} Mat(n \times m; F)$
- 2. If $\vec{v} \in V$, then $\mathcal{A}[\vec{v}] := \mathbf{b}$ (vector) where $\vec{v} = \sum_{i \in \mathcal{A}} \mathbf{b}_i \vec{v}_i$
- 3. **Theorems**: $[f \circ g] = [f] \circ [g]$ $_{\mathcal{C}}[f \circ g]_{\mathcal{A}} =_{\mathcal{C}} [f]_{\mathcal{B}} \circ_{\mathcal{B}} [g]_{\mathcal{A}}$ $_{\mathcal{B}}[f(\vec{v})] =_{\mathcal{B}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [\vec{v}]$ $_{\mathcal{A}}[f]_{\mathcal{A}} = I \Leftrightarrow f = id$
- 4. Change of Basis: Define Change of Basis Matrix:= $_{\mathcal{A}}[id_V]_{\mathcal{B}}$ $_{\mathcal{B}'}[f]_{\mathcal{A}'}=_{\mathcal{B}'}[id_W]_{\mathcal{B}}\circ_{\mathcal{B}}[f]_{\mathcal{A}\circ_{\mathcal{A}}}[id_V]_{\mathcal{A}'}$ $_{\mathcal{A}'}[f]_{\mathcal{A}'}=_{\mathcal{A}}[id_V]_{\mathcal{A}'}$ $_{\mathcal{A}'}[f]_{\mathcal{A}\circ_{\mathcal{A}}}[id_V]_{\mathcal{A}'}$ Elementary Matrix: $I+\lambda E_{ij}$ (cannot $I-E_{ii}$) 就是初等矩阵, 左乘代表 j 行乘 λ 倍加到第 i 行,右乘代表 j 列乘 λ 倍加到第 i 列 \rightarrow Invertible!
- 1. 交换 i,j 列/行: $P_{ij} = diag(1,...,1,-1,1,...,1)(I+E_{ij})(I-E_{ji})(I+E_{ij})$ where -1 in jth place.
- 2. Row Echelon Form|Smith Normal Form: A: REF 通过左乘初等矩阵可以实现 A: S(n,m,r) 通过 \tilde{A} 右乘初等矩阵可以实现

Smith Normal Form: $\forall A$, \exists invertible P, Q s.t. $PAQ = S(n, m, r) := n \times m$ 的矩阵, 对角线前 r 个是 1, 后面 0. Lemma: r = r(A) = c(A)

· Every linear map $f: V \to W$ can be representing by $_{\mathcal{B}}[f]_{\mathcal{A}} = S(n, m, r)$ for some basis \mathcal{A}, \mathcal{B} of V, W.

Similar Matrices: $N = T^{-1}MT \Leftrightarrow M$, N are similar. Special Case: If $N =_{\mathcal{B}} [f]_{\mathcal{B}}$, $M =_{\mathcal{A}} [f]_{\mathcal{A}}$, then $N = T^{-1}MT$. where $T =_{\mathcal{A}} [id_V]_{\mathcal{B}}$

- 1. If $A \sim B$ iff A is similar to B, then \sim is an equivalence relation. $A'[f]_{A'} \sim_{A} [f]_{A}$
- 2. If $\mathcal{B} = \{p(\vec{v_1}), ..., p(\vec{v_n})\}$ and $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$ where $p: V \xrightarrow{\sim} V$. Then $\mathcal{A}[id_V]_{\mathcal{B}} =_{\mathcal{A}} [p]_{\mathcal{A}}$
- 3. If *V* is a vector space over *F*, [*A*, *B* are *similar* matrices. $\Leftrightarrow A =_{\mathcal{A}} [f]_{\mathcal{A}}, B =_{\mathcal{B}} [f]_{\mathcal{B}}$ for some basis $\mathcal{A}, \mathcal{B}; f : V \to V$]
- 4. Set of *Endomorphism* is in a bijection correspondence with the equivalence class of matrices under ~. 一个自同态 **End** 就对应一个相似矩阵的等价类

Trace: $tr(A) := \sum_i a_{ii}$ and $tr(f) := tr(A[f]_A) \mid tr(AB) = tr(BA) \quad tr(\lambda A + \mu B) = \lambda tr(A) + \mu tr(B) \quad tr(N) = tr(M)$ if M, N similar.

5 Rings | Polynomials | Ideals | Subrings

5.1 Rings | Polynomial Rings

2nd Def of Ring Homomorphism: f is ring homomorphism if: 1. f: $(R, +) \rightarrow (S, +)$ is group homomorphism and 2. f(xy) = f(x)f(y).

Unit: $a \in R$ is unit if it's *Invertible*. i.e. $\exists a^{-1} \in R$ s.t. $aa^{-1} = a^{-1}a = 1_R$ **Group of Unit** $(R^{\times}, \cdot) := \{a \in R : a \text{ is unit}\}$

· **Lemma**: If ${}^1f: R \to S$ homo, ${}^2f(1_R) = 1_S$, 3x is unit of R. $\Rightarrow {}^1f(x)$ is unit of S. ${}^2f|_{R^\times}: R^\times \to S^\times$ is group homomorphism.

Zero-divisors: $a \in R$ is zero-divisor if $\exists b \in R, b \neq 0$ s.t. ab = 0 or ba = 0 Field has no zero-divisors. • e.g. $\mathbb{Z}^{\times} = \{-1, 1\}$; 1_R is a unit.

Integral Domain: A *commutative* ring R is an integral domain if it has no zero-divisors. e.g. $\mathbb{Z}/p\mathbb{Z}, \mathbb{R}, \mathbb{Q}, \mathbb{Z}, ...$

Properties of Integral Domain: $\forall a, b \in R$. **I.** $ab = 0 \Rightarrow a = 0$ or b = 0 **II.** $a, b \neq 0 \Rightarrow ab \neq 0$ **III.** $ac = bc, a \neq 0 \Rightarrow b = c$

· Field is Integral Domain Every finite integral domain is a field $\mathbb{Z}/p\mathbb{Z}$ is field iff p is prime. e.g.(integral domain) \mathbb{Z} ; $\mathbb{Z}/p\mathbb{Z}$

Polynomial Ring $R[X]: R[X] := \{a_n X^n + \dots + a_1 X + a_0 : a_i \in R, n \in \mathbb{N}\}$ where X is **indeterminate** $\leftarrow X \notin R$ and $\forall x \in R, Xa = aX$

- 1. **Degree**: $deg(P) := max\{n \in \mathbb{N} : a_n \neq 0\}$ **Leading Coefficient**: a_n **Monic**: $a_n = 1$ ps: Polynomial NOT a function
- 2. **Lemma**: 1R integral domain/no zero-divisors $\Rightarrow R[X]$ also. 2R integral domain or no zero-divisor $\Rightarrow \deg(PQ) = \deg(P) + \deg(P)$
- 3. **Division and Remainder**: If *R* is integral domain and $P, Q \in R[X], Q \text{ monic } \exists ! A, B \in R[X] \text{ s.t. } P = AQ + B \text{ and } \deg(B) < \deg(Q)$
- 4. **Function | Factorize**: If R is commutative $ring \Rightarrow {}^1R[X] \rightarrow Maps(R,R)$ (可以视作函数) ${}^2\lambda \in R$ is root of $P \Leftrightarrow (X \lambda) \mid P(X)$
- 5. **Roots**: If R is *Integral domain*: P has at most deg(P) roots.

Algebraically Closed: R = F field is *algebraically closed* if every non-constant polynomial has a root in F.

• **Decomposes**: If *F* field is *algebraically closed* \Rightarrow *P* decomposes into: $P(X) = a(X - \lambda_1) \cdots (X - \lambda_n)$, $a \in F^{\times}$ i.e. $a \neq 0$

5.2 Equivalence Relation

Equivalence Relation: A relation R on a set X is a subset $R \subseteq X \times X$. If $(x, y) \in R$, we write xRy, if R is Equivalence Relation, then:

Reflexive: xRx $(x \sim x)$ **Symmetric:** $xRy \Rightarrow yRx$ $(x \sim y \Rightarrow y \sim x)$ **Transitive:** xRy, $yRz \Rightarrow xRz$ $(x \sim y, y \sim z \Rightarrow x \sim z)$

Partial Order: A relation R on a set X, xRy. If R is partial order, then:

Reflexive: $xRx \ (x \sim x)$ **Anti-symmetric**: $xRy, yRx \Rightarrow x = y \ (x \sim y, y \sim x \Rightarrow x = y)$ **Transitive**: $xRy, yRz \Rightarrow xRz \ (x \sim y, y \sim z \Rightarrow x \sim z)$

Property of Equivalence Relation: If R (\sim) is equivalence relation on X.

- 1. ~ Define the **equivalence classes** of $x \in X$ as $E(x) := \{y \in X : x \sim y\}$
- 2. ~ **Partition** *X* into disjoint subsets $X = \bigcup_i X_i, X_i$ is equivalence class of $x \in X$.
- 3. $x \sim y \iff E(x) = E(y) \iff E(x) \cap E(y) \neq \emptyset$.

Set of Equivalence Classes (X/\sim) : $(X/\sim) := \{E(x) : x \in X\}$ **Canonical Projection**: $can : X \to (X/\sim)$ by $x \mapsto E(x)$

System of Representatives: $Z \subseteq X$ is a system of representatives if 每个等价类都恰好有一个元素代表在 Z 中

Examples: 1 If V F-vector space, W subspace. Then V/W is quotient vector space. 2 If G group, H normal. Then G/H is quotient group. 3 If R ring, I ideal. Then R/I is quotient ring.

Universal Property of the set of Equivalence Classes: If $f: X \to Z$ is a map s.t. $x \sim y \Leftrightarrow f(x) = f(y)$. (\sim is Equivalence relation) Important Then, $\exists ! \text{ map } \overline{f}: (X/\sim) \to Z \text{ s.t. } f = \overline{f} \circ can \text{ with } \overline{f}(E(x)) = f(x) \text{ is } \textit{well-defined.}$ Further more, $\overline{f}: (X/\sim) \xrightarrow{\sim} Im(f)$ ps: Often, if we want to prove $g: (X/\sim) \to Z$ is well-defined, we need to prove $x \sim y \Leftrightarrow g(x) = g(y)$ holds.

5.3 Factor Ring | First Isomorphism Theorem

Coset of Ideal: Let *I* be an ideal of *R*. Then a+I is a coset of *I*. The \sim is defined by $a\sim b \Leftrightarrow a-b\in I$ is an equivalence relation. **Factor Ring**: Let *I* be ideal of *R*. $R/I:=\{a+I:a\in R\}$ is the set of cosets of *I*. (i.e. R/I is the set of equivalence classes of *R* under \sim)

- 1. By well-defined operators: $(x + I) \dotplus (y + I) = (x + y) + I$ and $(x + I) \cdot (y + I) = xy + I \implies R/I$ is a ring.
- 2. $x + I = y + I \Leftrightarrow x \sim y \Leftrightarrow x y \in I$ | R is commutative $\Rightarrow R/I$ also. | $R/I \neq \{0 + I\}$ iff $I \neq R$
- 3. The Identity of R/I: $1_R + I$ The Zero of R/I: $0_R + I$

Universal Property of Factor Ring: Let *R* be a ring and *I* be an ideal of *R*. $ps:\overline{f}(x+I) = f(x)$

- 1. **can**: Mapping $can : R \to R/I$ by $x \mapsto x + I$ is ¹ surjection, ² ker(can) = I, ³ can is ring homomorphism.
- 2. **f**: If ${}^1f: R \to S$ is ring homomorphism and ${}^2I \subseteq ker(f)$, then $\exists ! \, {}^1\overline{f}: R/I \to S$ s.t. $f = \overline{f} \circ can$ is ring homomorphism.
- 3. **First Isomorphism Theorem**: If $f: R \to S$ is ring homomorphism $\Rightarrow \exists ! \overline{f}: R/ker(f) \xrightarrow{\sim} im(f)$ is (ring isomorphism).

Universal Property of Quotient Group: Let *G* be a group and *H* be a normal subgroup of *G*. $ps:\overline{f}(g+N)=f(g)$

- 1. **can**: Mapping $can : G \to G/H$ by $x \mapsto xH$ is ¹ surjection, ² ker(can) = H, ³ can is group homomorphism.
- 2. **f**: If ${}^1f:G\to S$ is group homomorphism and ${}^2H\subseteq ker(f)$, then $\exists! \, {}^1\overline{f}:G/H\to S$ s.t. $f=\overline{f}\circ can$ is group homomorphism.
- 3. **First Isomorphism Theorem**: If $f: G \to S$ is group homomorphism $\Rightarrow \exists ! \overline{f}: G/ker(f) \stackrel{\sim}{\to} im(f)$ is (group isomorphism).

5.4 Modules | Submodules | All of That

Restrict with Scalar: Let $f: R \to S$ is a *ring homomorphism*, $f(1_R) = 1_S$ and M is a S-Module, then M is also a R-Module by: Define the restrict our scalar: $rm := f(r)m \quad \forall r \in R, m \in M \quad \text{ps: } f(1_R) = 1_S$

Free Module: Let M be a R-Module. M is free if: $\forall m \in M$, $\exists ! \ r_1, ..., r_n \in R$ s.t. $m = r_1 m_1 + \cdots + r_n m_n$ ps: $m_1, ..., m_n$ is basis of M **Coset of Submodule**: Let N submodule of M. Then m + N coset of N. \sim is defined by $m \sim n \Leftrightarrow m - n \in N$ is an equivalence relation.

Factor Module: Let N submodule of M. $M/N := \{m + N : m \in M\}$ is the set of cosets of N.

ps: All properties of M/N are similar to R/I

Universal Property of Module Quotient: Let *M* be a module and *N* be a submodule of *M*. $ps:\overline{f}(x+N)=f(x)$

- 1. **can**: Mapping $can : M \to M/N$ by $x \mapsto x + N$ is ¹ surjection, ² ker(can) = N, ³ can is module homomorphism.
- 2. **f**: If ${}^1f: M \to S$ is module homomorphism and ${}^2N \subseteq ker(f)$, then $\exists ! \, {}^1\overline{f}: M/N \to S$ s.t. $f = \overline{f} \circ can$ is module homomorphism.
- 3. **First Isomorphism Theorem**: If $f: M \to S$ is module homomorphism $\Rightarrow \exists ! \overline{f} : M/ker(f) \stackrel{\sim}{\to} im(f)$ is (module isomorphism).
- [⊖] **Second Isomorphism Theorem for Modules**: Let N, K be submodules of R-module $M \Rightarrow N/(N \cap K) \cong (N + K)/K$ ps: consider $f: N \to (N + K)/K$ and then we can find $ker(f) = N \cap K$
- [⊖] **Third Isomorphism Theorem for Modules**: Let N, K be submodules of R-module $M : K \subseteq N \Rightarrow \frac{M/K}{N/K} \cong M/N$ ps: consider $f : M/K \to M/N$ and then we can find ker(f) = N/K

6 Permutation | Determinants | Eigenvalues and Eigenvectors

6.1 Permutation | Determinants

Permutation: A bijection $\sigma: \{1, ..., n\} \xrightarrow{\sim} \{1, ..., n\}$ is a permutation. All permutations of n elements form a group \mathfrak{S}_n .

- **1. Transposition**: A transposition is a permutation that exchanges two elements. **Inversion**: A pair of elements (i, j) is an inversion of $\sigma \in \mathfrak{S}_n$ if i < j but $\sigma(i) > \sigma(j)$
- 2. Length: The length of a permutation σ is the number of inversions. (i.e. $\ell(\sigma) := \left| \{(i,j) : i < j, \sigma(i) > \sigma(j) \} \right|$ Sign: $\operatorname{sgn}(\sigma) := (-1)^{\ell(\sigma)}$ sgn = 1, even; $\operatorname{sgn} = -1$, odd
- 3. $\operatorname{sgn}(a_1 a_2) = -1$ $\operatorname{sgn}(a_1 ... a_n) = (-1)^{n-1}$ $\operatorname{sgn}(\sigma \tau) = \operatorname{sgn}(\sigma) \operatorname{sgn}(\tau)$ Alternating Group: $A_n := \{ \sigma \in \mathfrak{S}_n : \operatorname{sgn}(\sigma) = 1 \}$
- 4. Graph Meaning of Inversion: Inversion is # edges that cross each other in the graph of permutation. (i.e. 画出的图中,线段交叉的次数)

Determinant: For matrix $A_{n \times n}$, with $A_{ij} = a_{ij}$. $\det(A) := \sum_{\sigma \in \mathfrak{S}_n} \operatorname{sgn}(\sigma) a_{1\sigma(1)} \cdots a_{n\sigma(n)}$ (**Leibniz Formula**) $\det(I_0) := 1$ or: $\det(A) := \sum_{\sigma^{-1} \in \mathfrak{S}_n} \operatorname{sgn}(\sigma^{-1}) a_{\sigma^{-1}(1)1} \cdots a_{\sigma^{-1}(n)n}$

Geometric Meaning of Determinant: Let area(U) denote the area|volume of U. Let A denote a matrix.

1. det(A) 对 U 操作后的面积 | 体积 = | det(A) | × area(U) 2. sgn(det A) 决定了方向是否改变 (+1 不变,-1 变). (i.e. 顺逆时针变化, 左右 | 上下变化, 手性变化)

Bilinear | Multilinear form: U, V, V_i, W be F-vector space. A mapping $H: U \times V \to W$ or $H: V_1 \times \cdots \times V_n \to W$ is *bilinear | multilinear* if:

1. $H(\lambda u, v) = \lambda H(u, v)$

3. $H(u, \lambda v) = \lambda H(u, v)$

- 2. H(u + v, w) = H(u, w) + H(v, w)
- 1. $H(u_1, ..., \lambda v_i, ..., u_n) = \lambda H(u_1, ..., v_i, ..., u_n) \quad \forall i$
- 2. $H(u_1, ..., v_i + v_j, ..., u_n) = H(u_1, ..., v_i, ..., u_n) + H(u_1, ..., v_j, ..., u_n)$ (左边 bilinear, 右边 multilinear)
- 4. H(u, v + w) = H(u, v) + H(u, w)

H is **Symmetric** if (bilinear): ${}^1U = V$, ${}^2H(u,v) = H(v,u) \ \forall u,v \in U$

if (multilinear): ${}^{1}V_{i}$ same, ${}^{2}H(v_{1},...,v_{n})=H(v_{\sigma(1)},...,v_{\sigma(n)}) \ \forall \sigma \in \mathfrak{S}_{n}$

H is **Alternating**|**Antisymmetric** if (bilinear): ${}^1U = V$, ${}^2H(u,u) = 0 \ \forall u \in U$

if (multilinear): 1V_i same, ${}^2H(v_1,...,v_n)=0$ $\forall v_i=v_i$ (i.e. 只要存在两个及以上相同的, H 结果为 0)

Lemma I: If *H* is alternating, then H(u, v) = -H(v, u) $H(v_1, ..., v_i, ..., v_i, ..., v_n) = -H(v_1, ..., v_i, ..., v_i, ..., v_n)$

Lemma II: If *H* is alternating, then $H(v_1, ..., v_n) = \operatorname{sgn}(\sigma)H(v_{\sigma(1)}, ..., v_{\sigma(n)})$

Property of Determinant: Let A, B be $n \times n$ matrices. F be field. R be commutative ring.

- 1. **Unique on Field**: det : $F^n \times \cdots \times F^n \to F$ or det : $Mat(n; F) \to F$ is the ¹unique ²alternating ³multilinear form s.t. det(I_n) = I_F
- 2. **Invertible on Field**: For Mat(n; F), A is invertible $\Leftrightarrow \det(A) \neq 0$ $\det(A^{-1}) = \det(A)^{-1}$ 交换环, 结论成立如果 $\det(A)$ 在 R 中有逆
- 3. **Similar on Field**: For *F* field. $A \sim B \Rightarrow \det(A) = \det(P^{-1}BP) = \det(B)$ Thus, we can define: det(f) for $f: V \to V$
- 4. **Operations**: If *R* is *commutative ring*, then $det(AB) = det(A) det(B) det(A^T) = det(A) det(A^{-1}) = det(A)^{-1}$
- 5. **Block Triangular**: If A is block triangular, then $\det(A) = \prod_{i=1}^n \det(A_i)$ 即矩阵分块后如果是对角阵, 行列式等于各个块的行列式乘积 **Common Theorems in Determinant**: Let A be $n \times n$ matrix. F be field. R be *commutative ring*.
- 1. Cofactor: $\ln R$, $C_{ij} := (-1)^{i+j} \det(A(i,j))$ where $A(i,j) \not \in A$ 去掉第i 行第j 列的矩阵. Laplace's Expansion: $\ln R$, $\det(A) = \sum_{j=1}^{n} a_{ij} C_{ij} = \sum_{i=1}^{n} a_{ij} C_{ij}$
- 2. Adjugate Matrix: $\ln R$ $\operatorname{adj}(A)$ matrix , $\operatorname{adj}(A)_{ij} \coloneqq \mathcal{C}_{ji}$ Cramer's Rule: $\ln R$ $A \cdot \operatorname{adj}(A) = (\det A)I_n$ $\ln F$, $x_i = \frac{\det(A_i)}{\det(A)} A_i$ 代表 A 的第 i 列替换为 b
- 3. Theorem|Need proof: In R, $\operatorname{adj}(A^T) = \operatorname{adj}(A)^T$ Hint: $\operatorname{adj}(A^T)_{ij} = c_{ij}^{A^T} = (-1)^{i+j} \det(A^T(i,j)) = (-1)^{i+j} \det(A(j,i)^T) = (-1)^{i+j} \det(A(j,i)) = c_{ji}^A = \operatorname{adj}(A)_{ji}^T = \operatorname{adj}(A)_{ij}^T =$
- 4. ★ **Invertibility of Matrix**: In R, matrix A is invertible \Leftrightarrow det $(A) \in R^{\times}$ e.g. $\mathbb{Z}^{\times} = \{\pm 1\}$; \mathbb{C}^{\times} , \mathbb{R}^{\times} , $\mathbb{Q}^{\times} = \mathbb{C}^{*}$, \mathbb{R}^{*} , \mathbb{Q}^{*} ; $\mathbb{F}_{n}^{\times} = \mathbb{F}_{n} \setminus \{0\}$; $\mathbb{Z}[i] = \{\pm 1, \pm i\}$
- 5. **Jacobi's Formula**, Let matrix A s.t. $a_{ij}(t)$ are functions of t. Then, $\frac{d}{dt} \det(A) = \operatorname{tr}\left(\operatorname{adj}A \cdot \frac{dA}{dt}\right)$

Eigenvalues | Eigenvectors | Diagonalization

Eigenspace $E(\lambda, f)$: Let $f: V \to V$ linear map (End), $\lambda \in F$. $E(\lambda, f) := \{\vec{v} \in V : f(\vec{v}) = \lambda \vec{v}\}$. λ is eigenvalue if $E(\lambda, f) \neq \{0\}$ ps: $\ker(f - \lambda i d_V)$ is the eigenspace of $E(\lambda, f)$ and it has a basis of eigenvectors $\{\vec{v}_1, ..., \vec{v}_r\}$.

Existence of Eigenvalues: For all $f: V \to V$ linear map. 1V is finite-dimensional. 1F is algebraically closed. $\Rightarrow \exists$ eigenvalues. **Characteristic Polynomial** $\chi_A(x)$: Let R be commutative ring. $A \in Mat(n; R)$. $\chi_A(x) := \det(xI_n - A) \in R[x]$

Relation with Eigenvalues: If *F* is *field*, $A \in Mat(n; F)$. λ is eigenvalue of $A \Leftrightarrow \chi_A(\lambda) = 0$

Similar Matrix: If *R* is *commutative ring*, $A, B \in Mat(n; R)$ similar. $\Rightarrow \chi_A(x) = \chi_B(x)$ Thus: $\chi_f(x) := \chi_{\mathcal{A}[f]_{\mathcal{A}}}(x)$

Remark: If $W \subseteq V$ is subspace. $f: V \to V$ is End. $f(W) \subseteq W$. Let $\mathcal{A} = (\vec{w}_1, ..., \vec{w}_m)$ basis W. $\mathcal{B} = (\vec{w}_1, ..., \vec{v}_m, \vec{v}_{m+1}, ..., \vec{v}_n)$ basis V. $\mathcal{C} = (\vec{v}_{m+1} + W, ..., \vec{v}_n + W)$ basis V/W.

 $\text{Suppose } f(\vec{v_k}) = \sum_{i=1}^m c_{ik} \vec{w_i} + \sum_{j=m+1}^n b_{jk} \vec{v_j} \quad \text{Let } g: W \rightarrow W \text{ by } w \mapsto f(w) \quad h: V/W \rightarrow V/W \text{ by } v + W \mapsto f(v) + W \quad e: V/W \rightarrow W \text{ by } v_k + W \mapsto \sum_{i=1}^m c_{ik} \vec{w_i}$ Then: $\chi_f(x) = \chi_g(x)\chi_h(x)$ and $_{\mathcal{B}}[f]_{\mathcal{B}} = \begin{pmatrix} {}_{\mathcal{A}}[g]_{\mathcal{A}} & {}_{\mathcal{A}}[e]_{\mathcal{C}} \\ 0 & {}_{\mathcal{C}}[h]_{\mathcal{C}} \end{pmatrix} = \begin{pmatrix} a_{ij} & c_{ik} \\ 0 & b_{jk} \end{pmatrix}$ ps: $f(\vec{w_j}) = \sum_{i=1}^m a_{ij}\vec{w_i}$ Triangularisability: Let $f: V \to V$ be End. V is finite-dimensional. the following are equivalent:

- 1. $\exists \mathcal{B} = (\vec{v}_1, ..., \vec{v}_n)$ basis s.t. $f(\vec{v}_i) = \sum_{j=1}^i a_{ji} \vec{v}_j$ (i.e. $_{\mathbb{B}}[f]_{\mathbb{B}}$ is upper triangular.) we say f is triangularisable
- 2. The characteristic polynomial $\chi_f(x)$ can be factored into linear factors over F. (ps: If *F* is algebraically closed, then *f* is triangularisable) **Corollary I**: Let $A, B \in Mat(n; F)$. A is triangularisable $\Leftrightarrow A$ is similar (Conjugate) to a upper triangular matrix B.

Corollary II: Let $f: V \to V$ be End. V is finite-dimensional. f is $triangularisable \Leftrightarrow \exists$ subspaces $V_0 = \{0\} \subset V_1 \subset \cdots \subset V_n = V$ s.t. $f(V_i) \subseteq V_i$. **Corollary III**: For $A \in Mat(n; F)$. A is nilpotent (i.e. $A^k = 0$ for some k) $\Leftrightarrow \chi_A(x) = x^n$

Application: 矩阵 A 换基到上三角矩阵,通过找 A 特征值及其对应的特征向量,组成新的基(可能需要广义特征向量/或拓展基),然后计算 A 在新基下的矩阵表示.

Diagonalisable: Let $f: V \to V$ be End, V is *diagonalisable* iff \exists basis of V consisting of eigenvectors of f.

Diagonalisable | **Finite**: For *V* is finite-dimensional. *V* is diagonalisable $\Leftrightarrow \exists$ basis \mathcal{B} s.t. $_{\mathbb{B}}[f]_{\mathbb{B}} = diag(\lambda_1, ..., \lambda_n)$, where: $f(\vec{v}_i) = \lambda_i \vec{v}_i$ **Property**: In finite case, $\exists P$ consisting of eigenvectors s.t. $P^{-1}AP = diag(\lambda_1, ..., \lambda_n)$

LI of Eigenvectors: Let $f: V \to V$ be End. V is finite-dimensional. If $\lambda_1, ..., \lambda_n$ are distinct \Rightarrow Corresponding eigenvectors are linearly independent.

Cayley-Hamilton Theorem: Let *R* be *commutative ring*. $A \in Mat(n; R)$. Then: for $\chi_A(x) = \chi_A(x) = 0$

Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint

Jordan Normal Form | Spectral Theorem 8

Appendix

Appendix Vieta's formulas: For polynomial $P(x) = a_n x^n + \dots + a_1 x + a_0$. Let x_1, \dots, x_n be roots of P(x). $x_1 + \dots + x_n = -\frac{a_{n-1}}{a_n} \quad x_1 \dots x_n = (-1)^n \frac{a_0}{a_n} \quad x_1 x_2 + x_1 x_3 + \dots + x_{n-1} x_n = \frac{a_{n-2}}{a_n}$ Determinant of Vandermonde Matrix: Let x_1, \dots, x_n be distinct elements of F. Then $\det \begin{pmatrix} 1 & x_1 & x_1^2 & \dots & x_{n-1}^{n-1} \\ 1 & x_2 & x_2^2 & \dots & x_{n-1}^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^{n-1} \end{pmatrix} = \prod_{1 \le i < j \le n} (x_j - x_i)$