Basic Knowledge

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HAlg Note
Def of Group (G, *): A set G with a operator * is a group if: Closure: \forall g, h \in G, g * h \in G; Associativity: \forall g, h, k \in G, (g * h) * k = g * (h * k);
                                Identity: \exists e \in G, \forall g \in G, e * g = g * e = g; Inverse: \forall g \in G, \exists g^{-1} \in G, g * g^{-1} = g^{-1} * g = e. G, H groups, then G \times H also.
Field (F): A set F is a field with two operators: (addition) +: F \times F \to F; (\lambda, \mu) \to \lambda + \mu (multiplication) : F \times F \to F; (\lambda, \mu) \to \lambda \mu if:
               (F,+) and (F \setminus \{0_F\},\cdot) are abelian groups with identity (0_F,1_F). and \lambda(\mu+\nu)=\lambda\mu+\lambda\nu e.g.Fields: \mathbb{R}, \mathbb{C}, \mathbb{Q}, \mathbb{Z}/p\mathbb{Z}=\mathbb{F}_p
F-Vector Space (V): A set V over a field F is a vector space if: V is an abelian group V = (V, +) and \forall \vec{v}, \vec{w} \in V \lambda, \mu \in F e.g. Poly : \mathbb{R}[x]_{\leq n}
               \exists \text{ map } F \times V \rightarrow V : (\lambda, \vec{v}) \rightarrow \lambda \vec{v} \text{ satisfies: } \mathbf{I} : \lambda(\vec{v} \dotplus \vec{w}) = (\lambda \vec{v}) \dotplus (\lambda \vec{w}) \quad \mathbf{II} : (\lambda + \mu)\vec{v} = (\lambda \vec{v}) \dotplus (\mu \vec{v}) \quad \mathbf{III} : \lambda(\mu \vec{v}) = (\lambda \mu)\vec{v} \quad \mathbf{IV} : 1_F \vec{v} = \vec{v}
Vector Subspaces Criterion: U \subseteq V is a subspace of V if: \vec{I} : \vec{0} \in U II. \forall \vec{u}, \vec{v} \in U, \forall \lambda \in F : \vec{u} + \vec{v} \in U and \lambda \vec{u} \in U (or: \lambda \vec{u} + \mu \vec{v} \in U)
• property: If U, W are subspaces of V, then U \cap W and U + W are also subspaces of V. ps: U + W := \{\vec{u} + \vec{w} : \vec{u} \in U, \vec{w} \in W\}
Complement-wise Operations: \phi: V_1 \times V_2 \rightarrow V_1 \oplus V_2 by \mathbf{I}: (\vec{v_1}, \vec{u_1}) + (\vec{v_2}, \vec{u_2}) := (\vec{v_1} + \vec{v_1}, \vec{u_1} + \vec{u_2}), \ \lambda(\vec{v}, \vec{u}) := (\lambda \vec{v}, \lambda \vec{u}) \text{ (ps:} V_1, V_2 \text{ 通过} \phi 定义的 map 所形成的 vector space 记作 V_1 \oplus V_2 )
Projections: pr_i: X_1 \times \cdots \times X_n \to X_i by (x_1, ..., x_n) \mapsto x_i Canonical Injections: in_i: X_i \to X_1 \times \cdots \times X_n by x \mapsto (0, ..., 0, x, 0, ..., 0)
    Vector Spaces/Subspaces | Generating Set | Linear Independent | Basis
Generating (subspaces) \langle T \rangle: \langle T \rangle := \{ \alpha_1 \vec{v_1} + \dots + \alpha_n \vec{v_n} : \alpha_i \in F, \vec{v_i} \in T, r \in \mathbb{N} \} \langle \emptyset \rangle := \{ \vec{0} \} If T is subspace \Rightarrow \langle T \rangle = T.
 1. Proposition: \langle T \rangle is the smallest subspace containing T. (i.e. \langle T \rangle is the intersection of all subspaces containing T)
 2. Generating Set: V is vector space, T \subseteq V. T is generating set of V if \langle T \rangle = V. Finitely Generated: \exists finite set T, \langle T \rangle = V
 3. External Direct Sum: 一个" 代数结构", 定义为 set 是 V_1 \oplus \cdots \oplus V_n := V_1 \times \cdots \times V_n 且有一组运算法则 component-wise operations
 4. Connect to Matrix: Let E = \{\vec{v_1}, ..., \vec{v_n}\}, E is GS of V. Let A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{b} \in V, \exists \vec{x} = (x_1, ..., x_n)^T s.t. A\vec{x} = \vec{b} (i.e. linear map:\phi : \vec{x} \mapsto A\vec{x} is surjective)
Linearly Independent: L = \{\vec{v_1}, \vec{v_2}, ..., \vec{v_r}\} is linearly independent if: \forall c_1, ..., c_r \in F, c_1\vec{v_1} + \cdots + c_r\vec{v_r} = \vec{0} \Rightarrow c_1 = \cdots = c_r = 0.
 \textbf{\cdot Connect to Matrix} \text{: Let } L = \{\vec{v_1},...,\vec{v_n}\}, L \text{ is LI of } V. \text{ Let } A = [\vec{v_1},...,\vec{v_n}] \Rightarrow \forall \vec{x} \in F^n, A\vec{x} = 0 \text{ } (or \ \vec{0}) \Rightarrow \vec{x} = 0 \text{ } (or \ \vec{0}) \text{ } (i.e. \text{ linear map } \phi : \vec{x} \mapsto A\vec{x} \text{ is injective}) 
Basis & Dimension: If V is finitely generated. \Rightarrow \exists subset B \subseteq V which is both LI and GS. (B is basis) Dim: dim V := |B|
• Connect to Matrix: Let B = \{\vec{v_1}, ..., \vec{v_n}\} is basis of V. Let A = [\vec{v_1}, ..., \vec{v_n}] \Rightarrow \forall \vec{x} = (x_1, ..., x_n)^T s.t. \phi : \vec{x} \mapsto A\vec{x} is 1-1 & onto (Bijection)
Relation[GS,LI,Basis,dim: Let V be vector space. L is linearly independent set, E is generating set, B is basis set.
 1. GS|LI: |L| \le |E| (can get: dim unique) LI \rightarrow Basis: If V finite generate \Rightarrow \forall L can extend to a basis. If L = \emptyset, prove \exists B
                                                                                                                                                                               kerf \cap imf = \{0\}
 2. Basis|max,min: B \Leftrightarrow B is minimal GS (E) \Leftrightarrow B is maximal LI (L). Uniqueness|Basis: 每个元素都可以由 basis 唯一表示.
 3. Proper Subspaces: If U \subset V is proper subspace, then \dim U < \dim V. \Rightarrow If U \subseteq V is subspace and \dim U = \dim V, then U = V.
 4. Dimension Theorem: If U, W \subseteq V are subspaces of V, then \dim(U+W) = \dim U + \dim W - \dim(U\cap W)
Complementary: U, W \subseteq V, U, V subspaces are complementary (V = U \oplus W) if: \exists \phi : U \times W \to V by (\vec{u}, \vec{w}) \mapsto \vec{u} + \vec{w}
                             i.e. \forall \vec{v} \in V, we have unique \vec{u} \in U, \vec{w} \in W s.t. \vec{v} = \vec{u} + \vec{w}. ps: It's a linear map.
    Linear Mapping | Rank-Nullity | Matrices | Change of Basis
Linear Mapping/Homomorphism(Hom): f: V \to W is linear map if: \forall \vec{v}_1, \vec{v}_2 \in V, \forall \lambda \in F. f(\vec{v}_1 + \vec{v}_2) = f(\vec{v}_1) + f(\vec{v}_2) and f(\lambda \vec{v}_1) = \lambda f(\vec{v}_1)
· Isomorphism: = LM & Bij. Endomorphism(End): = LM & V = W. Automorphism(Aut): = LM & V = W Monomorphism: = LM & 1-1. Epimorphism: = LM & onto.
· Kernel: \ker f := \{ \vec{v} \in V : f(\vec{v}) = \vec{0} \} (It's subspace) Image: Imf := \{ f(\vec{v}) : \vec{v} \in V \} (It's subspace) Rank:= \dim(Imf) Nullity:= \dim(\ker f) Fixed Point X^f : X^f := \{x \in X : f(x) = x \}
Property of Linear Map: Let f, g \in Hom: \mathbf{a}. f(\vec{0}) = \vec{0} \mathbf{b}. f is 1-1 iff \ker f = \{\vec{0}\} \mathbf{c}. f \circ g is linear map.
 1. Determined: f is determined by f(\vec{b_i}), \vec{b_i} \in \mathcal{B}_{basis} (* i.e. f(\sum_i \lambda_i \vec{v_i}) := \sum_i \lambda_i f(\vec{v_i}))
 2. Classification of Vector Spaces: dim V = n \Leftrightarrow f : F^n \stackrel{\sim}{\to} V by f(\lambda_1, ..., \lambda_n) \mapsto \sum_{i=1}^n \lambda_i \vec{v_i} is isomorphism.
 3. Left/Right Inverse: f is 1-1 \Rightarrow \exists left inverse g s.t. g \circ f = id 考虑 direct sum f is onto \Rightarrow \exists right inverse g s.t. f \circ g = id
 4. ^{\Theta} More of Left/Right Inverse: f \circ g = id \Rightarrow g is 1-1 and f is onto. 使用 kernel=0 来证明
Rank-Nullity Theorem: For linear map f: V \to W, dim V = \dim(\ker f) + \dim(Imf)
                                                                                                                                                 Following are properties:
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- 1. **Injection**: f is $1-1 \Rightarrow \dim V \le \dim W$ **Surjection**: f is onto $\Rightarrow \dim V \ge \dim W$ Moreover, $\dim W = \dim imf$ iff f is onto.
- 2. **Same Dimension**: f is isomorphism $\Rightarrow \dim V = \dim W$ **Matrix**: $\forall M$, column rank c(M) = row rank r(M).
- 3. **Relation**: If V, W finite generate, and dim $V = \dim W$, Then: f is isomorphism $\Leftrightarrow f$ is 1-1 $\Leftrightarrow f$ is onto.

Matrix: For $A_{n\times m}$, $B_{m\times p}$, $AB_{n\times p}:=(AB)_{ij}=\sum_{k=1}^m a_{ik}b_{kj}$ **Transpose**: $A_{m\times n}^T:=(A^T)_{ij}=a_{ji}$

Invertible Matrices: A is invertible if $\exists B, C$ s.t. BA = I and AC = I $\exists B, BA = I \Leftrightarrow \exists C, AC = I \Leftrightarrow \exists A^{-1}$ $\exists C \in AC = I \Leftrightarrow AC AC =$

Representing matrix of linear map $_{\mathcal{B}}[f]_{\mathcal{A}}: f: V \to W$ be linear map, $\mathcal{A} = \{\vec{v_1}, ..., \vec{v_n}\}$ is basis of V, $\mathcal{B} = \{\vec{w_1}, ..., \vec{w_m}\}$ is basis of W.

- 1. $_{\mathcal{B}}[f]_{\mathcal{A}} := A \text{ (matrix) where } f(\vec{v}_{i \in \mathcal{A}}) = \sum_{i \in \mathcal{B}} A_{ii} \vec{w}_{i} \qquad \exists M_{\mathcal{B}}^{\mathcal{A}} : Hom_{F}(V, W) \xrightarrow{\sim} Mat(n \times m; F)$
- 2. If $\vec{v} \in V$, then $_{\mathcal{A}}[\vec{v}] := \mathbf{b}$ (vector) where $\vec{v} = \sum_{i \in \mathcal{A}} \mathbf{b}_i \vec{v}_i$
- $_{\mathcal{B}}[f(\vec{v})] =_{\mathcal{B}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [\vec{v}] \qquad _{\mathcal{A}} [f]_{\mathcal{A}} = I \Leftrightarrow f = id$ 3. **Theorems**: $[f \circ g] = [f] \circ [g]$ $c[f \circ g]_{\mathcal{A}} = c[f]_{\mathcal{B}} \circ_{\mathcal{B}} [g]_{\mathcal{A}}$
- 4. **Change of Basis**: Define *Change of Basis Matrix*:= $_{\mathcal{A}}[id_V]_{\mathcal{B}}$ $_{\mathcal{B}'}[f]_{\mathcal{A}'} =_{\mathcal{B}'} [id_W]_{\mathcal{B}} \circ_{\mathcal{B}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [id_V]_{\mathcal{A}'} \qquad _{\mathcal{A}'}[f]_{\mathcal{A}'} =_{\mathcal{A}} [id_V]_{\mathcal{A}'}^{-1} \circ_{\mathcal{A}} [f]_{\mathcal{A}} \circ_{\mathcal{A}} [id_V]_{\mathcal{A}'}$ **Elementary Matrix**: $I + \lambda E_{ij}$ (cannot $I - E_{ii}$) 就是初等矩阵, 左乘代表 j 行乘 λ 倍加到第 i 行, 右乘代表 j 列乘 λ 倍加到第 i 列 \Rightarrow Invertible! 1. 交换 i, j 列/行: $P_{ij} = diag(1, ..., 1, -1, 1, ..., 1)(I + E_{ij})(I - E_{ji})(I + E_{ij})$ where -1 in jth place.
- 2. Row Echelon Form|Smith Normal Form: A: REF 通过左乘初等矩阵可以实现 A: S(n,m,r) 通过 $\stackrel{\sim}{A}$ 右乘初等矩阵可以实现 Smith Normal Form: $\forall A$, \exists invertible P, Q s.t. $PAQ = S(n, m, r) := n \times m$ 的矩阵, 对角线前 r 个是 1, 后面 0. Lemma: r = r(A) = c(A)**Similar Matrices**: If $N = T^{-1}MT$, then M, N are similar. Special Case: If $N =_{\mathcal{B}} [f]_{\mathcal{B}}$, $M =_{\mathcal{A}} [f]_{\mathcal{A}}$, then $N = T^{-1}MT$. where $T =_{\mathcal{A}} [id_V]_{\mathcal{B}}$ **Trace**: $tr(A) := \sum_i a_{ii}$ and $tr(f) := tr(A[f]_A) \mid tr(AB) = tr(BA) \quad tr(\lambda A + \mu B) = \lambda tr(A) + \mu tr(B) \quad tr(N) = tr(M)$ if M, N similar. Copyright By Jingren Zhou | Page 1

- 4 Rings | Polynomials | Ideals | Subrings
- 5 Inner Product Spaces | Orthogonal Complement / Proj | Adjoints and Self-Adjoint
- 6 Jordan Normal Form | Spectral Theorem