

Scattering Coefficient and Kirchhoff Approximation

1. Reflection of Plane wave (Reflected by x_1 axis)

We assume that a plane P-wave u_p (or S-wave u_s) with incident direction $d_0 = (\sin t_0, \cos t_0)$ at a plane $\Gamma := x \in \mathbb{R}^2 : x_0 = 0$.

1.1. P-wave

We denote incident P-wave [1, p172] as

$$u^0 = A_0(\sin t_0, \cos t_0)^T e^{\mathbf{i}k_p(x_1 \sin t_0 + x_2 \cos t_0)} \quad (1.1)$$

and its stress as

$$\sigma(u^0) = \mathbf{i}k_p A_0(2\mu \sin t_0 \cos t_0, \lambda + 2\mu \cos^2 t_0)^T e^{\mathbf{i}k_p(x_1 \sin t_0 + x_2 \cos t_0)}$$

The reflected P-wave is represented as

$$\begin{aligned} u^1 &= A_1(\sin t_1, -\cos t_1)^T e^{\mathbf{i}k_p(x_1 \sin t_1 - x_2 \cos t_1)} \\ \sigma(u^1) &= \mathbf{i}k_p A_1(-2\mu \sin t_1 \cos t_1, \lambda + 2\mu \cos^2 t_1)^T e^{\mathbf{i}k_p(x_1 \sin t_1 - x_2 \cos t_1)} \end{aligned}$$

and reflected S-wave as

$$\begin{aligned} u^2 &= A_2(\cos t_2, \sin t_2)^T e^{\mathbf{i}k_s(x_1 \sin t_2 - x_2 \cos t_2)} \\ \sigma(u^2) &= \mathbf{i}k_s A_2(\mu(\sin^2 t_2 - \cos^2 t_2), -2\mu \sin t_2 \cos t_2)^T e^{\mathbf{i}k_s(x_1 \sin t_2 - x_2 \cos t_2)} \end{aligned}$$

We consider the clamped condition, then the total field on the $x_2 = 0$ vanish:

$$u^0(x_1, 0) + u^1(x_1, 0) + u^2(x_1, 0) = 0$$

for any $x_1 \in \mathbb{R}$. A simple computation show that

$$\begin{aligned} t_1 = t_0 \quad \text{and} \quad \frac{\sin t_2}{\sin t_0} &= \frac{k_p}{k_s} := \kappa \\ A_0 = \cos(t_0 - t_2) \quad A_1 = \cos(t_0 + t_2) \quad A_2 &= -\sin 2t_0 \end{aligned}$$

1.2. S-wave

Similarly, we denote incident S-wave as

$$u^0 = A_0(-\cos t_0, \sin t_0)^T e^{\mathbf{i}k_p(x_1 \sin t_0 + x_2 \cos t_0)} \quad (1.2)$$

$$\sigma(u^0) = \mathbf{i}k_s(\mu(\sin^2 t_0 - \cos^2 t_0), 2\mu \sin t_0 \cos t_0)^T e^{\mathbf{i}k_p(x_1 \sin t_0 + x_2 \cos t_0)} \quad (1.3)$$

The reflected P-wave is represented as

$$\begin{aligned} u^1 &= A_1(\sin t_1, -\cos t_1)^T e^{\mathbf{i}k_p(x_1 \sin t_1 - x_2 \cos t_1)} \\ \sigma(u^1) &= \mathbf{i}k_p A_1(-2\mu \sin t_1 \cos t_1, \lambda + 2\mu \cos^2 t_1)^T e^{\mathbf{i}k_p(x_1 \sin t_1 - x_2 \cos t_1)} \end{aligned}$$

and reflected S-wave as

$$\begin{aligned} u^2 &= A_2(\cos t_2, \sin t_2)^T e^{\mathbf{i}k_s(x_1 \sin t_2 - x_2 \cos t_2)} \\ \sigma(u^2) &= \mathbf{i}k_s A_2(\mu(\sin^2 t_2 - \cos^2 t_2), -2\mu \sin t_2 \cos t_2)^T e^{\mathbf{i}k_s(x_1 \sin t_2 - x_2 \cos t_2)} \end{aligned}$$

The result is

$$\begin{aligned} t_2 = t_0 \quad \text{and} \quad \frac{\sin t_1}{\sin t_0} &= \frac{k_s}{k_p} = \frac{1}{\kappa} \\ A_0 = \cos(t_0 - t_1) \quad A_1 = \sin 2t_0 \quad A_2 &= \cos(t_0 + t_1) \end{aligned}$$

2. Reflection of Plane wave (General Case)

Thus, for the general case, the solution for the scattering of a plane P-wave u_p (or S-wave u_s) with incident direction d_0 at a plane $\Gamma := x \in \mathbb{R}^2 : x \cdot \nu = 0$ through the origin with normal vector ν is described by

$$u = u_p + u_{p,p} + u_{p,s} = A_0 d_0 e^{ikp x \cdot d_0} + A_1 d_1 e^{ikp x \cdot d_1} + A_2 d_2^\perp e^{iks x \cdot d_2} \quad (2.1)$$

$$u = u_s + u_{s,p} + u_{s,s} = A_0 d_0^\perp e^{iks x \cdot d_0} + A_1 d_1 e^{ikp x \cdot d_1} + A_2 d_2^\perp e^{iks x \cdot d_2} \quad (2.2)$$

where $d_i = (d_i^1, d_i^2)^T$ are unit vectors, $d_i^\perp = (d_i^2, -d_i^1)^T$ and A_i are corresponding amplitude. For fixed boundary, we have $u = 0$ for $x \in \Gamma$. Let $d_0 = (\sin t_0, \cos t_0)$ and $\nu = (\sin \phi, \cos \phi)^T$, and taking a rotation transformation such that

$$\hat{x} = Sx \quad \text{and} \quad x = S^T \hat{x}$$

where

$$S = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix} = \begin{bmatrix} (\nu^\perp)^T \\ \nu^T \end{bmatrix}$$

Before proceeding, we give a theorem concerning axis transformation.

Theorem 2.1 *Let $u(x) \in \mathbb{C}^2$ and*

$$\Delta_e^x := \begin{pmatrix} (\lambda + 2\mu) \frac{\partial^2}{\partial x_1^2} + (\lambda + \mu) \frac{\partial^2}{\partial x_1 \partial x_2} + \mu \frac{\partial^2}{\partial x_2^2} \\ \mu \frac{\partial^2}{\partial x_1^2} + (\lambda + \mu) \frac{\partial^2}{\partial x_1 \partial x_2} + (\lambda + 2\mu) \frac{\partial^2}{\partial x_2^2} \end{pmatrix}$$

. Assume that $u(x)$ satisfies $\Delta_e^x u(x) + \omega^2 u(x) = 0$, then we have $\Delta_e^{\hat{x}} \hat{u}(\hat{x}) + \omega^2 \hat{u}(\hat{x}) = 0$ where $\hat{u}(\hat{x}) := Su(S^T \hat{x})$.

Proof. since

$$\begin{aligned} \frac{\partial^2}{\partial \hat{x}_1^2} &= \cos^2 \phi \frac{\partial^2}{\partial x_1^2} - 2 \cos \phi \sin \phi \frac{\partial^2}{\partial x_1 \partial x_2} + \sin^2 \phi \frac{\partial^2}{\partial x_2^2} \\ \frac{\partial^2}{\partial \hat{x}_2^2} &= \sin^2 \phi \frac{\partial^2}{\partial x_1^2} + 2 \cos \phi \sin \phi \frac{\partial^2}{\partial x_1 \partial x_2} + \cos^2 \phi \frac{\partial^2}{\partial x_2^2} \\ \frac{\partial^2}{\partial \hat{x}_1 \partial \hat{x}_2} &= \cos \phi \sin \phi \frac{\partial^2}{\partial x_1^2} + (\cos^2 \phi - \sin^2 \phi) \frac{\partial^2}{\partial x_1 \partial x_2} - \cos \phi \sin \phi \frac{\partial^2}{\partial x_2^2} \end{aligned}$$

This completes proof after substituting above equation into $\Delta_e^{\hat{x}} \hat{u}(\hat{x})$. \square

Let

$$\begin{aligned} \hat{d}_i &= S d_i, \quad \hat{\nu} = S \nu = (0, 1)^T \\ \hat{d}_0 &= (\sin(\theta - \phi), \cos(\theta - \phi))^T = ((d_0, \nu^\perp), (d_0, \nu))^T \\ \hat{u}_p(\hat{x}) &:= Su_p(S^T x) = A_0 (\sin(\theta - \phi), \cos(\theta - \phi))^T e^{ik_p \hat{x}_1 \sin(\theta - \phi) + \hat{x}_2 \cos(\theta - \phi)} \end{aligned}$$

Using results in section 1, we have

$$\begin{aligned} \hat{d}_1 &= (\sin(\theta - \phi), -\cos(\theta - \phi))^T = ((d_0, \nu^\perp), (d_0, \nu))^T \\ \hat{d}_2 &= (\sin t_2, -\cos t_2)^T = (\kappa(d_0, \nu^\perp), -\text{sgn}((d_0, \nu)) \sqrt{1 - \kappa^2(d_0, \nu^\perp)^2})^T \\ A_0 &= \cos(\theta - \phi - t_2) = -\hat{d}_1 \cdot \hat{d}_2 = -d_1 \cdot d_2 \end{aligned}$$

$$\begin{aligned}
A_1 &= \cos(\theta - \phi + t_2) = \hat{d}_0 \cdot \hat{d}_2 = d_0 \cdot d_2 \\
A_2 &= -\sin 2(\theta - \phi) = 2(\hat{d}_0, \hat{\nu})(\hat{d}_0, \hat{\nu}^\perp) = -2(d_0, \nu)(d_0, \nu^\perp)
\end{aligned}$$

where $\sin t_2 = \kappa \sin(\theta - \phi)$. After a standard computation, we get for P-wave:

$$d_1 = S^T \hat{d}_1 = d_0 - 2\alpha\nu \quad (2.3)$$

$$d_2 = S^T \hat{d}_2 = \kappa d_0 - \beta\nu \quad (2.4)$$

$$A_0 = -\kappa(d_0, \nu)^2 + \kappa(d_0, \nu^\perp)^2 + \beta(d_0, \nu) \quad (2.5)$$

$$A_1 = -\kappa + \beta(d_0, \nu) \quad (2.6)$$

$$A_2 = -2(d_0, \nu)(d_0, \nu^\perp) \quad (2.7)$$

where $\alpha = (d_0, \nu)$, $\beta = \kappa\alpha + \operatorname{sgn}(\alpha)\sqrt{\kappa^2\alpha^2 - \kappa^2 + 1}$ and $\kappa = k_p/k_s$. Similarly, for S-wave, we have

$$d_1 = \kappa_1 d_0 - \gamma\nu \quad (2.8)$$

$$d_2 = d_0 - 2\alpha\nu \quad (2.9)$$

$$A_0 = -\kappa_1(d_0, \nu)^2 + \kappa_1(d, \nu^\perp)^2 + \gamma(d, \nu) \quad (2.10)$$

$$A_1 = 2(d_0, \nu)(d_0, \nu^\perp) \quad (2.11)$$

$$A_2 = -\kappa_1 + \gamma(d_0, \nu) \quad (2.12)$$

where $\gamma = \kappa_1\alpha + \operatorname{sgn}(\alpha)\sqrt{\kappa_1^2\alpha^2 - \kappa_1^2 + 1}$ and $\kappa_1 = 1/\kappa$. Thus the traction of $u(x)$ on the plane Γ can be obtained. For P-wave

$$\begin{aligned}
\sigma(u) \cdot \nu &= [\mathbf{i}k_p A_0(\lambda\nu + 2\mu(d_0, \nu)d_0) + \mathbf{i}k_p A_1(\lambda\nu + 2\mu(d_1, \nu)d_1) \\
&+ \mathbf{i}k_s A_2\mu((d_2, \nu)d_2^\perp + (d_2^\perp, \nu)d_2)]e^{\mathbf{i}k_p x \cdot d_0} := \mathbf{i}k_p A_0 \hat{\mathbf{R}}_p(x, d_0, \nu)e^{\mathbf{i}k_p x \cdot d_0}
\end{aligned} \quad (2.13)$$

For S-wave

$$\begin{aligned}
\sigma(u) \cdot \nu &= [\mathbf{i}k_s A_0\mu((d_0, \nu)d_0^\perp + (d_0^\perp, \nu)d_0) + \mathbf{i}k_p A_1(\lambda\nu + 2\mu(d_1, \nu)d_1) \\
&+ \mathbf{i}k_s A_2\mu((d_2, \nu)d_2^\perp + (d_2^\perp, \nu)d_2)]e^{\mathbf{i}k_s x \cdot d_0} := \mathbf{i}k_s A_0 \hat{\mathbf{R}}_s(x, d_0, \nu)e^{\mathbf{i}k_s x \cdot d_0}
\end{aligned} \quad (2.14)$$

Definition 2.1 For any unit vector $d \in \mathbb{R}^2$, let $u_p^i = de^{\mathbf{i}k_p x \cdot d}$ or $u_s^i = d^\perp e^{\mathbf{i}k_s x \cdot d}$ be the incident wave and $u_\alpha^s = u_\alpha^s(x; d)$ be the radiation solution of the Navier equation:

$$u_\alpha^s + \omega^2 u_\alpha^s = 0 \quad \text{in } \mathbb{R}^2 \setminus \bar{D} \quad (2.15)$$

$$\Delta_\epsilon u_\alpha^s = -u_\alpha^i \quad \text{on } \partial D \quad (2.16)$$

The scattering coefficient $\mathbf{R}_\alpha(x; d)$ for $x \in \partial D$ is defined by the relation

$$\sigma(u_\alpha^s + u_\alpha^i) \cdot \nu = \mathbf{i}k_\alpha \mathbf{R}_\alpha(x; d)e^{\mathbf{i}k_\alpha x \cdot d} \quad \text{on } \partial D$$

where $\alpha = p, s$.

A convex object D locally may be considered at each point x as a plane with normal $\nu(x)$. Then the scattering coefficient can be approximated (Kirchhoff approximation) by

$$\mathbf{R}_\alpha(x; d) \approx \begin{cases} \hat{\mathbf{R}}_\alpha(x; d, \nu(x)) & \text{if } x \in \partial D_d^- = \{x \in \partial D, \nu(x) \cdot d < 0\}, \\ 0 & \text{if } x \in \partial D_d^+ = \{x \in \partial D, \nu(x) \cdot d \geq 0\}. \end{cases}$$

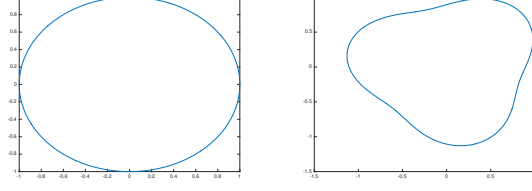


Figure 1.

3. Numerical examples

In this section we present several numerical examples to show the effectiveness of Kirchhoff approximation. To synthesize the real scattering coefficient we compute the solution $\sigma(u_\alpha^s + u_\alpha^i) \cdot \nu$ of the scattering problems by representing the ansatz solution as the single layer potential with the Green tensor $\mathbb{G}(x, y)$ as the kernel

$$u^s(x) = \int_{\Gamma_D} -\mathbb{G}(y, x)^T \sigma(u^s(y) + u^i(y)) \nu ds(y) = -u^i(x) \quad \text{on } x \in \Gamma_D$$

and discretizing the integral equation by standard Nyström methods [2]. Let $\mathbf{R}_\alpha(x; d) = (\mathbf{R}_\alpha^1(x; d), \mathbf{R}_\alpha^2(x; d))^T$, then we have

$$\mathbf{R}_\alpha^j(x; d) = \frac{\sigma(u^s(y) + u^i(y)) \nu \cdot e_j}{\mathbf{i} k_\alpha e^{\mathbf{i} k_\alpha x \cdot d}} \quad (3.1)$$

and we can compute $\hat{\mathbf{R}}_\alpha(x; d) = (\hat{\mathbf{R}}_\alpha^1(x; d), \hat{\mathbf{R}}_\alpha^2(x; d))^T$ by (2.13) and (2.14). In all our numerical examples we choose Lamé constant $\lambda = 1/2$, $\mu = 1/4$ and

$$\begin{aligned} u_p^i &= (\cos t, \sin t)^T e^{\mathbf{i} k_p (x_1 \cos t + x_2 \sin t)} \\ u_s^i &= (\sin t, -\cos t)^T e^{\mathbf{i} k_s (x_1 \cos t + x_2 \sin t)} \end{aligned}$$

where $t \in [0, 2\pi]$. The boundaries of the obstacles used in our numerical experiments are parameterized as follows,

$$\text{Circle: } x_1 = \cos(\theta), \quad x_2 = \sin(\theta);$$

$$\text{Pear: } \rho = 0.5(2 + 0.3 \cos(3\theta)), \quad x_1 = \sin \frac{\pi}{4} \rho (\cos \theta - \sin \theta), \quad x_2 = \sin \frac{\pi}{4} \rho (\cos \theta + \sin \theta)$$

where $\theta \in [0, 2\pi]$ and depicted as figure 1.

In the following examples, figure 2-9, the angular frequency $\omega = \pi, 2\pi, 4\pi, 8\pi$.

References

- [1] Achenbach J 1980 *Wave Propagation in Elastic Solids* (North-Holland)
- [2] Colton D and Kress R 1998 *Inverse Acoustic and Electromagnetic Scattering Problems* (Heidelberg: Springer)

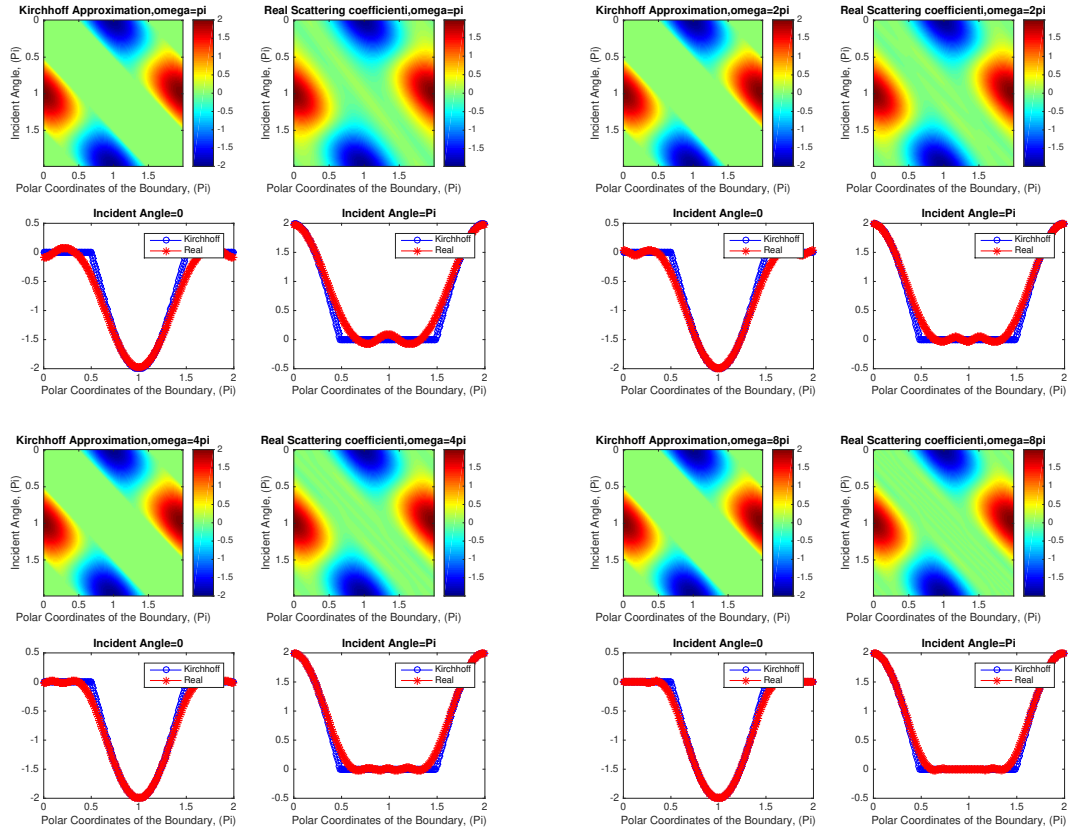


Figure 2. R_p^1 and \hat{R}_p^1 for circle

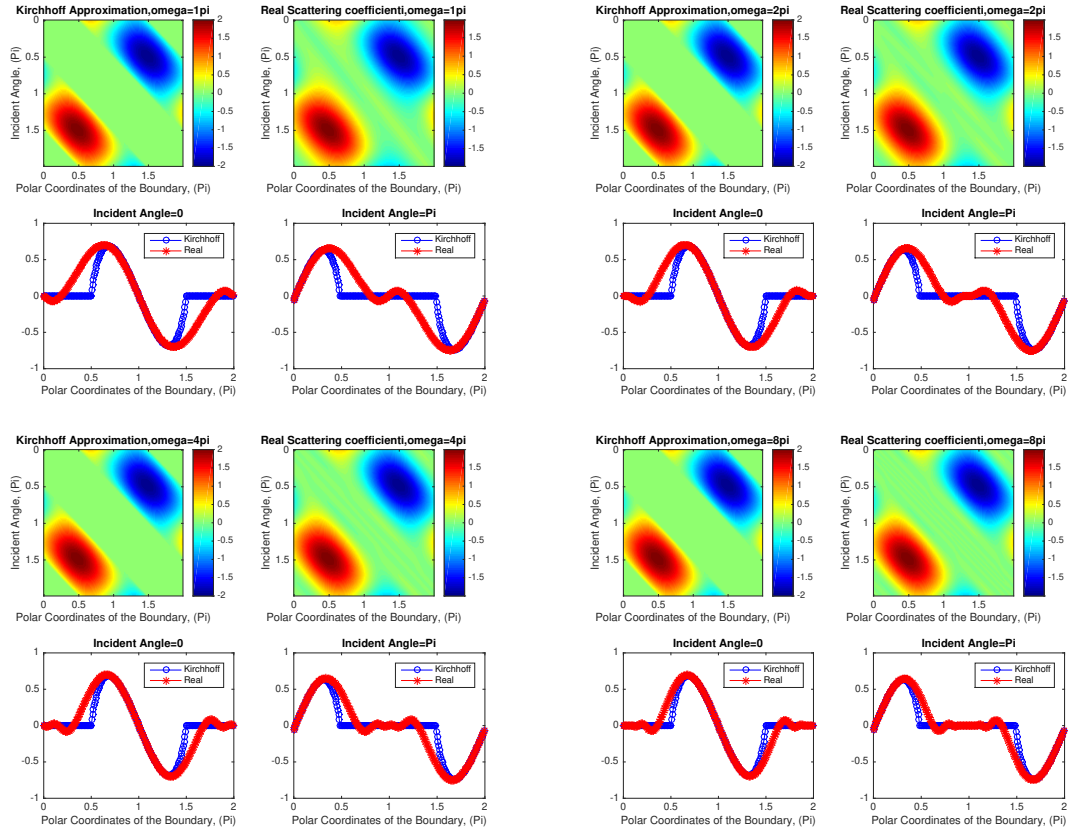


Figure 3. R_p^2 and \hat{R}_p^2 for circle

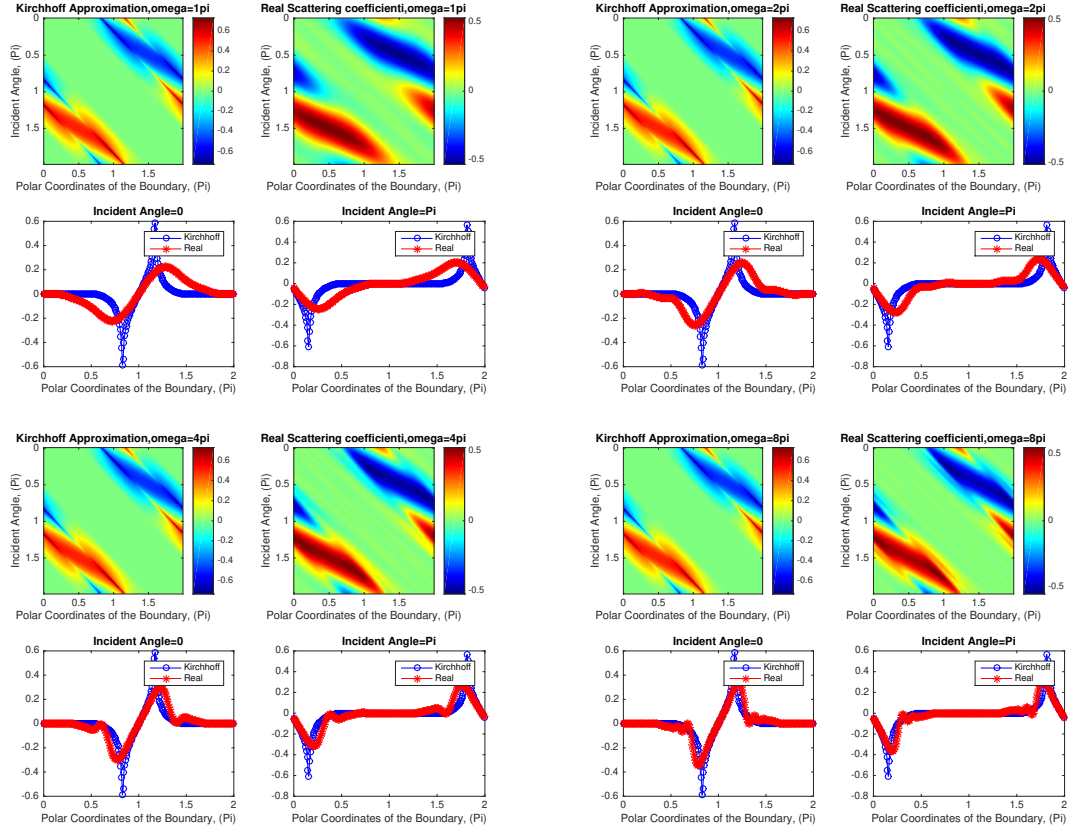


Figure 4. R_s^1 and \hat{R}_s^1 for circle

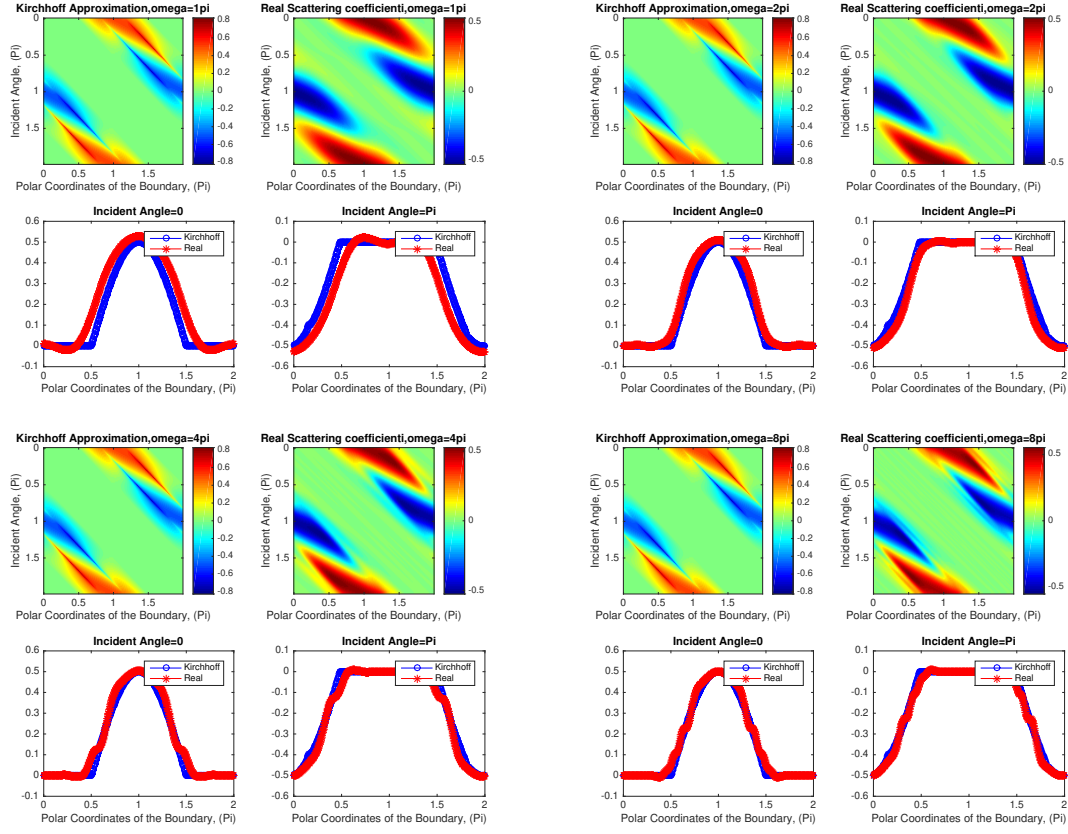


Figure 5. R_s^2 and \hat{R}_s^2 for circle

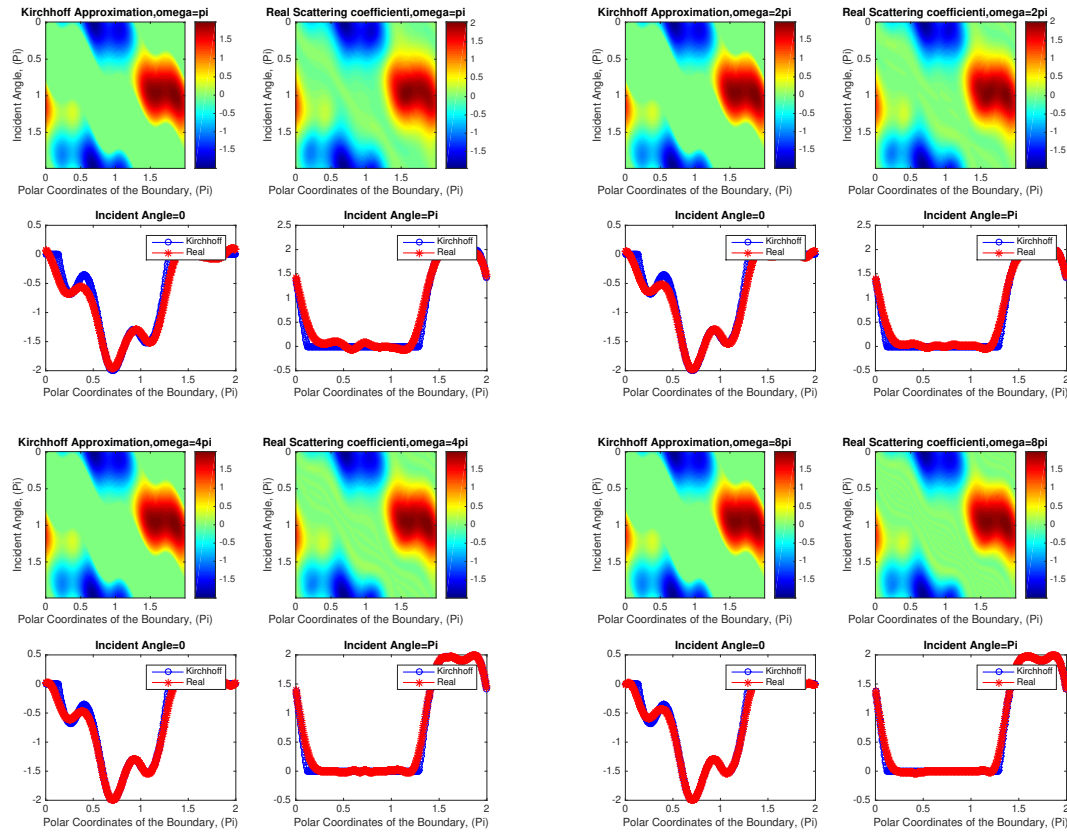


Figure 6. \mathbf{R}_p^1 and $\hat{\mathbf{R}}_p^1$ for pear

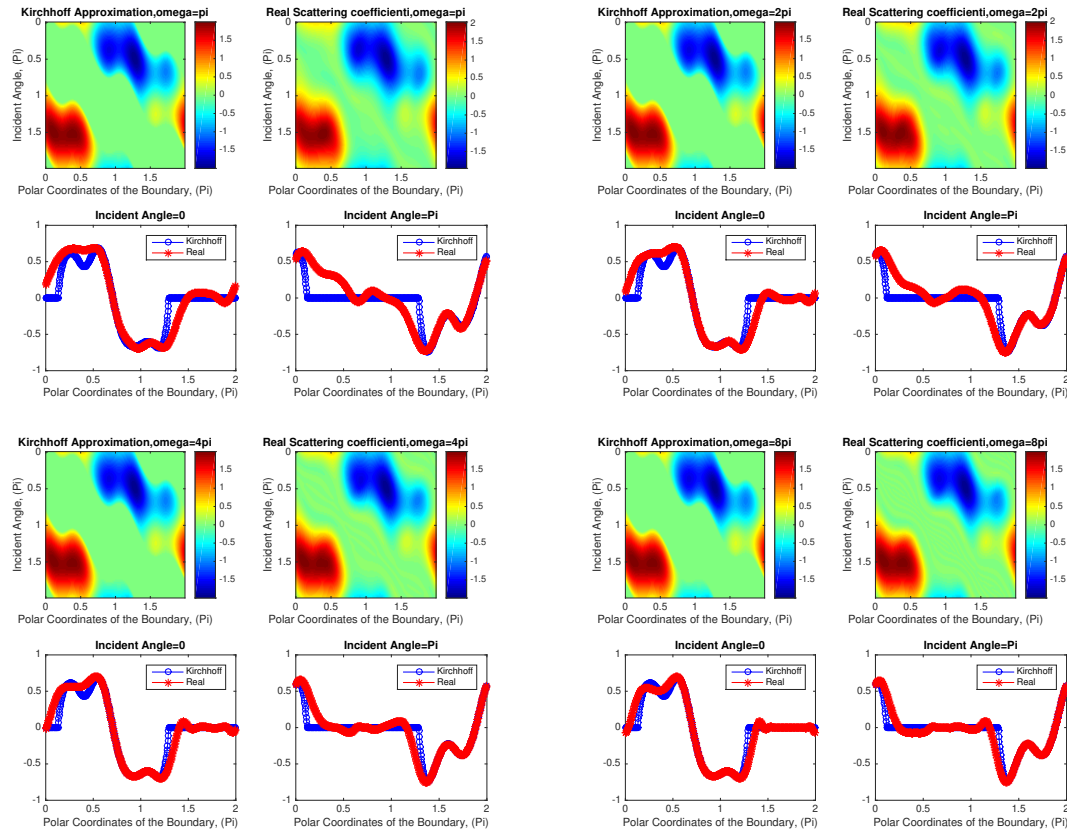


Figure 7. R_p^2 and \hat{R}_p^2 for pear

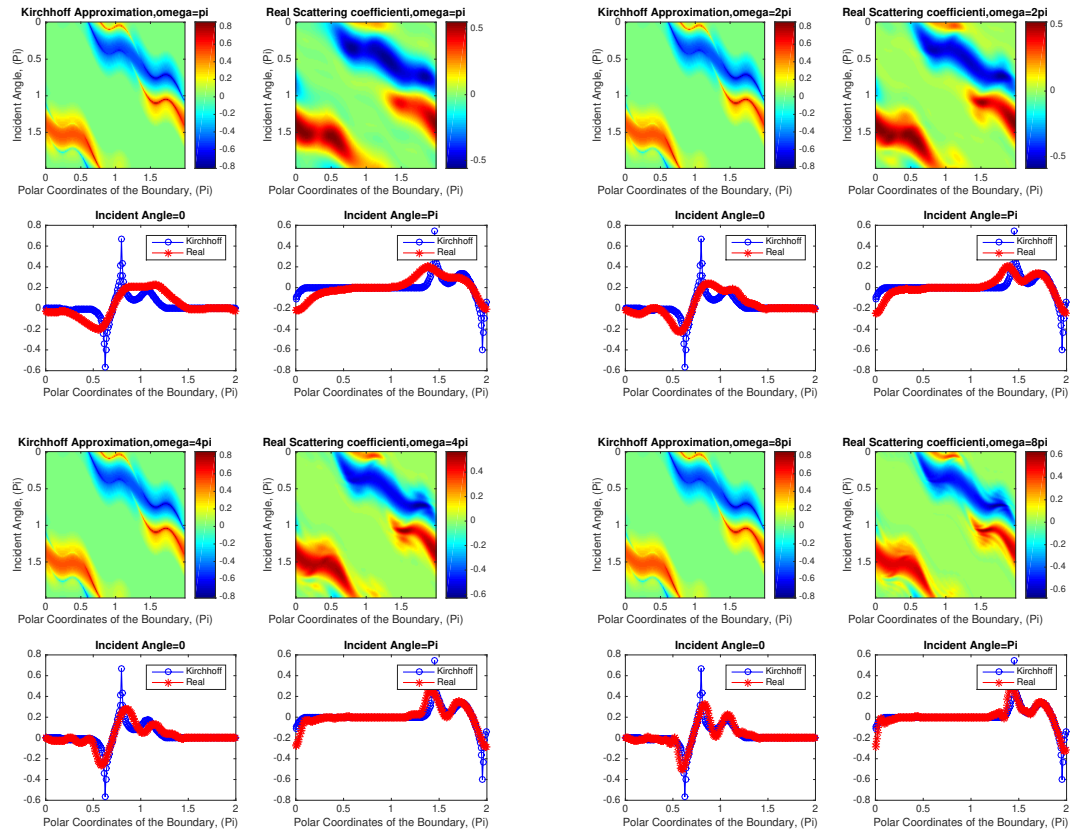


Figure 8. R_s^1 and \hat{R}_s^1 for pear

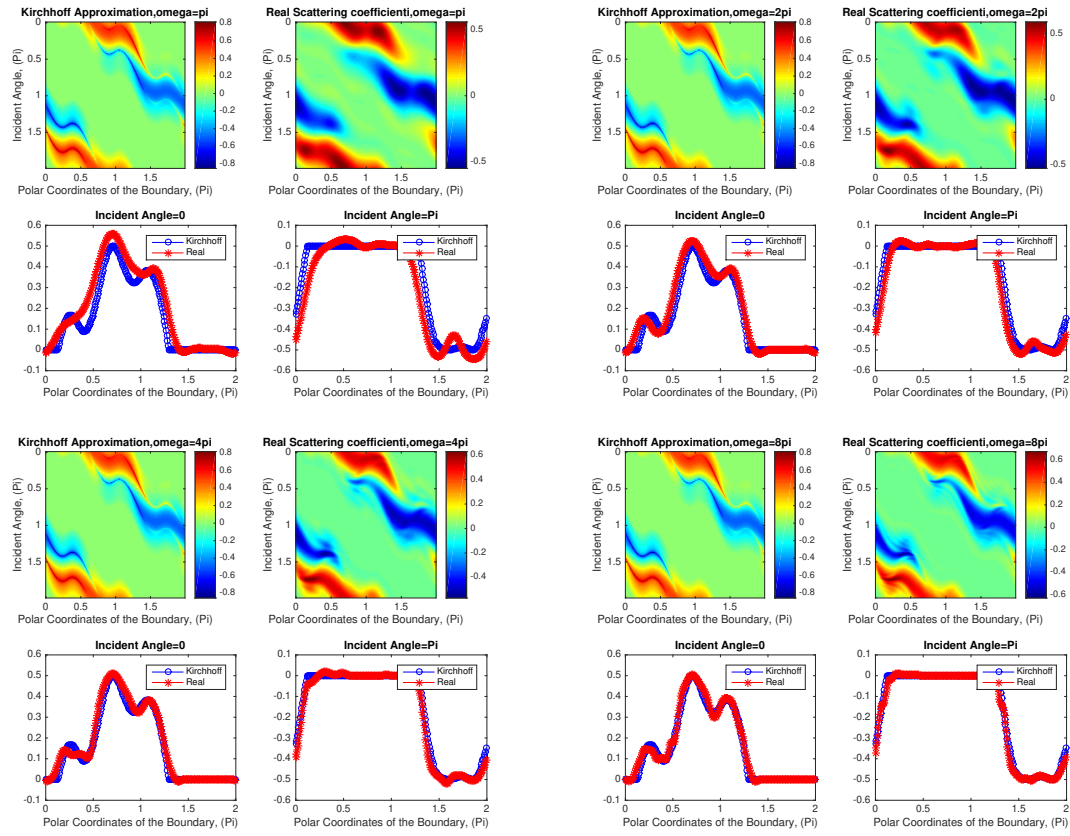


Figure 9. R_s^2 and \hat{R}_s^2 for pear