```
function [K] = MTGP covQPSisoUU shift(hyp, x, z, i)
 2
3
     % Stationary covariance function for a quasi-periodic function based on a
     % multiplication of a Matern and Periodic function
4
5
6
             - only elements of x(:,1:end-1)/z(:,1:end-1) will be analyzed,
 7
             -x(:,end)/z(:,end) will be ignored, as it contains only the label
     information
8
          - independent of the label all x values will have the same hyp
9
             - feature scaling hyperparameter is fixed to 1
10
             - output scaling hyperparameter is fixed to 1
11
12
     % k(x,y) = exp(-((x-theta s) - ((y-theta s)))'*inv(P)*((x-theta s) - ((y-theta s)))'
     (y-theta s)^q)/2) * ...
13
                     \exp(-2*\sin^2(pi^*||(x-theta s)-(y-theta s)||/p))
14
15
     % where the P matrix is ell^2 times the unit matrix.
16
     % The hyperparameters are:
17
     용
18
     % hyp = [log(ell)]
19
     응
               log(p);
20
     용
               theta s(1)
21
     응
                 . . .
22
     용
               theta s(nL-1)]
23
24
     % modified by Robert Duerichen
25
     % 8/11/2013
26
27
     % See also COVFUNCTIONS.M.
28
29
     if nargin<2, K = 'nL+1'; return; end</pre>
                                                                    % report number of
     parameters
30
     if nargin<3, z = []; end
                                                                    % make sure, z exists
31
     xeqz = numel(z) == 0; dg = strcmp(z, 'diag') && numel(z) > 0;
                                                                  % determine mode
32
33
34
    nL = max(x(:,2));
                                                           % get number of labels
                                                           % characteristic length scale
35
     ell = \exp(hyp(1));
36
     p = \exp(hyp(2));
                                                           % period
37
     shift = (hyp(3:end));
                                                           % time shift hyp
38
39
    %% perform shift
40
     for ii = 2:nL
41
        x(x(:,2) == ii,1) = x(x(:,2) == ii,1) + shift(ii-1);
42
        if ~isempty(z)
43
            z(z(:,2) == ii,1) = z(z(:,2) == ii,1) + shift(ii-1);
44
        end
45
     end
46
47
     % precompute distances
48
     if dq
                                                                            % vector kxx
49
       K_p = zeros(size(x(:,1),1),1);
50
       K_{se} = zeros(size(x(:,1),1),1);
51
     else
52
       if xeqz
                                                                  % symmetric matrix Kxx
53
         K_se = sq_dist(x(:,1:end-1)'/ell);
54
         K_p = sqrt(sq_dist(x(:,1:end-1)'));
55
                                                                % cross covariances Kxz
56
         K se = sq dist(x(:,1:end-1)'/ell,z(:,1:end-1)'/ell);
57
         K p = sqrt(sq dist(x(:,1:end-1)',z(:,1:end-1)'));
58
59
     end
60
61
    K p = pi*K p/p;
62
     if nargin<4</pre>
                                                                           % covariances
63
         K p = \sin(K p); K p = K p.*K p; K p = \exp(-2*K p);
64
         K se = exp(-K se/2);
65
         K = K p.*K se;
66
                                                                           % derivatives
     else
67
         if i<=nL+1
68
             if i==1
                             % derivatives of the se hyperparameter
```

```
69
                 K p = \sin(K p); K p = K p.*K p; K p = \exp(-2*K p);
70
                 K = K_p.*exp(-K_se/2).*K_se;
71
             elseif i==2
                                  % derivatives of the periodic hyperparameter
                 K se = exp(-K_se/2);
72
73
                 R = \sin(K p); K = K se.* 4.*exp(-2*R.*R).*R.*cos(K p).*K p;
74
             else % derivatives of the shift hyperparameters
75
               ind_i = (x(:,2) ==i-1);
76
               ind ni = (x(:,2) \sim =i-1);
77
               B = zeros(length(x));
78
               B(ind_ni,ind_i) = ones(sum(ind_ni),sum(ind_i));
79
               B(ind_i,ind_ni) = -ones(sum(ind_i),sum(ind ni));
80
81
82
               A = repmat(x(:,1),[1 length(x)]);
83
84
               R = sin(K p);
85
               dK p = B.*4.*exp(-2*R.*R).*R.*cos(K p).*pi./p.*sign(A-A');
86
87
               dK se = B.*((A-A')./(ell^2).*exp(-K se/2));
88
89
               K p = \sin(K p); K p = K p.*K p; K p = \exp(-2*K p);
90
               K se = exp(-K se/2);
91
92
               K = dK_se.*K_p + K_se.*dK_p;
93
           end
94
         else
95
             error('Unknown hyperparameter')
96
         end
97
```

98

end