```
function [varargout] = MTGP(hyp, inf, mean, cov, lik, x, y, xs, ys)
% Gaussian Process inference and prediction. The gp function provides a
% flexible framework for Bayesian inference and prediction with Gaussian
% processes for scalar targets, i.e. both regression and binary
% classification. The prior is Gaussian process, defined through specification
% of its mean and covariance function. The likelihood function is also
% specified. Both the prior and the likelihood may have hyperparameters
% associated with them. posterior = prior x likelihood/ marginal likelihood
%
% Two modes are possible: <a href="maining">training</a> or prediction: If no test cases are
% supplied, then the negative log marginal likelihood and its partial
% derivatives w.r.t. the hyperparameters is computed; this mode is used to fit
% the hyperparameters. If test cases are given, then the test set predictive
% probabilities are returned. Usage:
%
                                   ] = gp(hyp, inf, mean, cov, lik, x, y);
%
    training: [n1Z dn1Z
  prediction: [ymu ys2 fmu fs2 ] = gp(hyp, inf, mean, cov, lik, x, y, xs);
           or: [ymu ys2 fmu fs2 lp] = gp(hyp, inf, mean, cov, lik, x, y, xs, ys);
%
%
% where:
%
%
              column vector of hyperparameters
    hyp
              function specifying the inference method
%
    inf
              prior covariance function (see below)
%
    cov
              prior mean function
%
    mean
              likelihood function
%
    lik
%
              n by D matrix of training inputs
    X
              column vector of length n of training targets
%
    У
%
              ns by D matrix of test inputs
    XS
              column vector of length nn of test targets
%
    УS
%
%
    n1Z
              returned value of the negative log marginal likelihood
    dn1Z
%
              column vector of partial derivatives of the negative
%
                 <u>log marginal likelihood</u> w.r.t. each hyperparameter
    ymu
%
              column vector (of length ns) of predictive output means
%
              column vector (of length ns) of predictive output variances
    fmu
              column vector (of length ns) of predictive <u>latent means</u>
%
              column vector (of length ns) of predictive latent variances
%
    fs2
%
    1p
              column vector (of length ns) of log predictive probabilities
%
                              N*X
```

```
struct representation of the (approximate) posterior
%
    post
%
             3rd output in training mode or 6th output in prediction mode
             can be reused in prediction mode gp(.., cov, lik, x, post, xs,..)
%
%
% See also covFunctions.m, infMethods.m, likFunctions.m, meanFunctions.m.
% Copyright (c) by Carl Edward Rasmussen and Hannes Nickisch, 2013-01-21
if nargin<7 | nargin>9
                                  ] = gp(hyp, inf, mean, cov, lik, x, y);')
  disp('Usage: [n1Z dn1Z
          or: [ymu ys2 fmu fs2 ] = gp(hyp, inf, mean, cov, lik, x, y, xs);')
          or: [ymu ys2 fmu fs2 lp] = gp(hyp, inf, mean, cov, lik, x, y, xs, ys);')
  disp('
  return
end
if isempty(mean), mean = {@meanZero}; end
                                                              % set default mean
if ischar(mean) | isa(mean, 'function_handle'), mean = {mean}; end % make cell
if isempty(cov), error('Covariance function cannot be empty'); end % no default
if ischar(cov) | isa(cov, 'function handle'), cov = {cov}; end % make cell
cov1 = cov\{1\}; if isa(cov1, 'function handle'), cov1 = func2str(cov1); end
if isempty(inf)
                                                  % set default inference method
  if strcmp(cov1, 'covFITC'), inf = @infFITC; else inf = @infExact; end
else
  if iscell(inf), inf = inf\{1\}; end
                                                         % cell input is allowed
  if ischar(inf), inf = str2func(inf); end
                                                  % convert into function handle
end
if strcmp(cov1, 'covFITC')
                                                    % only infFITC* are possible
  if isempty(strfind(func2str(inf), 'infFITC')==1)
    error('Only infFITC* are possible inference algorithms')
  end
                               % only one possible class of inference algorithms
end
if isempty(lik), lik = {@likGauss}; end
                                                               % set default lik
if ischar(lik) | isa(lik, 'function_handle'), lik = {lik}; end % make cell
if iscell(lik), likstr = lik{1}; else likstr = lik; end
if ~ischar(likstr), likstr = func2str(likstr); end
D = size(x, 2);
%% these lines have to be added to be able to use Lab covCC chol nD function
if size (x, 2) > 1
    nL = max(x(:,end));
```

```
end
if ~isfield(hyp, 'mean'), hyp. mean = []; end % check the hyp specification
if eval(feval(mean(:))) ~= numel(hyp.mean)
  error('Number of mean function hyperparameters disagree with mean function')
end
if ~isfield(hyp,'cov'), hyp.cov = []; end
if eval(feval(cov{:})) ~= numel(hyp.cov)
  error ('Number of cov function hyperparameters disagree with cov function')
if ~isfield(hyp, 'lik'), hyp.lik = []; end
if eval(feval(lik\{:\})) \sim= numel(hyp.lik)
  error ('Number of lik function hyperparameters disagree with lik function')
end
                                                      % call the inference method
try
 % issue a warning if a classification likelihood is used in conjunction with
 \% labels different from +1 and -1
  if strcmp(likstr, 'likErf') | strcmp(likstr, 'likLogistic')
    if ~isstruct(y)
      uy = unique(y);
      if any(uy^=+1 & uy^=-1)
        warning ('You try classification with labels different from \{+1, -1\}')
      end
    end
  end
  if nargin>7 % compute marginal likelihood and its derivatives only if needed
    if isstruct(y)
      post = y;
                           % reuse a previously computed posterior approximation
    else
      post = inf(hyp, mean, cov, lik, x, y);
    end
  else
    if nargout==1
      [post n1Z] = inf(hyp, mean, cov, lik, x, y); dn1Z = \{\};
    else
      [post n1Z dn1Z] = inf(hyp, mean, cov, 1ik, x, y);
    end
  end
```

catch

```
msgstr = lasterr;
  if nargin > 7, error ('Inference method failed [%s]', msgstr); else
    warning ('Inference method failed [%s] .. attempting to continue', msgstr)
    dn1Z = struct('cov', 0*hyp. cov, 'mean', 0*hyp. mean, 'lik', 0*hyp. lik);
    varargout = {NaN, dn1Z}; return
                                                        % continue with a warning
  end
end
                                                  % if no test cases are provided
if nargin==7
  varargout = {n1Z, dn1Z, post}; % report -log marg lik, derivatives and post
else
  alpha = post.alpha; L = post.L; sW = post.sW;
  if issparse (alpha)
                                       % handle things for sparse representations
    nz = a1pha = 0;
                                                      % determine nonzero indices
    if issparse(L), L = full(L(nz, nz)); end % convert L and sW if necessary
    if issparse(sW), sW = full(sW(nz)); end
  else nz = true(size(alpha, 1), 1); end
                                                      % non-sparse representation
  if nume1(L) == 0
                                       % in case L is not provided, we compute it
    K = \text{feval}(\text{cov}\{:\}, \text{hyp.cov}, x(nz,:));
    L = chol(eye(sum(nz)) + sW*sW'.*K);
  end
  Ltril = all(all(tril(L, -1) == 0));
                                    % is L an upper triangular matrix?
  ns = size(xs, 1);
                                                          % number of data points
                                           % number of data points per mini batch
  nperbatch = 1000;
  nact = 0;
                                   % number of already processed test data points
  ymu = zeros(ns, 1); ys2 = ymu; fmu = ymu; fs2 = ymu; 1p = ymu; % allocate mem
  while nact < ns
                               % process minibatches of test cases to save memory
    id = (nact+1):min(nact+nperbatch, ns);
                                                         % data points to process
    kss = feval(cov\{:\}, hyp.cov, xs(id,:), 'diag');
                                                                  % self-variance
    Ks = feval(cov\{:\}, hyp.cov, x(nz,:), xs(id,:));
                                                              % cross-covariances
    ms = feval(mean\{:\}, hyp.mean, xs(id,:));
    N = size(alpha, 2); % number of alphas (usually 1; more in case of sampling)
    Fmu = repmat(ms, 1, N) + Ks'*full(alpha(nz, :));
                                                          % conditional mean fs f
    fmu(id) = sum(Fmu, 2)/N;
                                                                % predictive means
    if Ltril
                       % L is triangular => use Cholesky parameters (alpha, sW, L)
     V = L' \setminus (repmat(sW, 1, length(id)).*Ks);
      fs2(id) = kss - sum(V.*V, 1);
                                                            % predictive variances
                       % L is not triangular => use alternative parametrisation
      fs2(id) = kss + sum(Ks.*(L*Ks), 1)';
                                                           % predictive variances
    end
```

```
fs2(id) = max(fs2(id), 0); % remove numerical noise i.e. negative variances
   Fs2 = repmat(fs2(id), 1, N); % we have multiple values in case of sampling
    if nargin<9
      [Lp, Ymu, Ys2] = feval(lik{:}, hyp. lik, [], Fmu(:), Fs2(:));
    else
      [Lp, Ymu, Ys2] = feval(lik\{:\}, hyp. lik, repmat(ys(id), 1, N), Fmu(:), Fs2(:));
    end
    1p(id) = sum(reshape(Lp, [], N), 2)/N;
                                              % log probability; sample averaging
                                                     % predictive mean ys \mid y and ...
    ymu(id) = sum(reshape(Ymu, [], N), 2)/N;
                                                                      % .. variance
    ys2(id) = sum(reshape(Ys2, [], N), 2)/N;
    nact = id(end);
                             % set counter to index of last processed data point
  end
  if nargin<9
   varargout = {ymu, ys2, fmu, fs2, [], post};
                                                        % assign output arguments
 else
    varargout = \{ymu, ys2, fmu, fs2, 1p, post\};
 end
end
```