hw3: report

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Task A: standard RNN [30pts]
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- 2. Training and validation curves.
 - 2.1. LSTM1 clip
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Task A: standard RNN [30pts]

In task A, I construct a standard RNN (including LSTM, GRU). Use Nvidia RTX 1080 to accelerate my experiment, the following experiments will focus on these aspects:

- RNN type
 - LSTM [1] & GRU [2]
- Different number of layers
 - **1 & 2 & 4 & 8 & 16**
- use gradient clip or not

```
# Hyperparameter setting
ninput = 300
nhid = 300
lr = 0.001 if use Adam else 5
clip = 0.1
epochs = 100
train_batch_size = 20
eval_batch_size = 10
bptt = 100
dropout = 0.5
nlayers and nhead (Transformer) are control variables
```

1. PPL & Time

Sorry for not having enough time to go through all possible situations. The summary results are shown in the table below.

No.	Model	Train PPL	Valid PPL	Test PPL	ms/batch	Trainable params
1	LSTM1_clip	48.28	125.68	119.51	43	20722478
2	LSTM1_original	943.23	662.08	622.36	53	20722478
3	LSTM2_clip	56.27	123.40	116.42	51	21444878
4	LSTM4_clip	68.45	138.52	130.30	82	22889678
5	LSTM8_clip	1021.24	985.30	965.01	131	25779278
6	GRU1_clip	45.06	125.96	119.69	85	20541878

```
ps1: LSTM2 means: nlayers = 2
```

ps2: clip means: use gradient clip and Adam optimizer; original means: only use SGD optimizer.

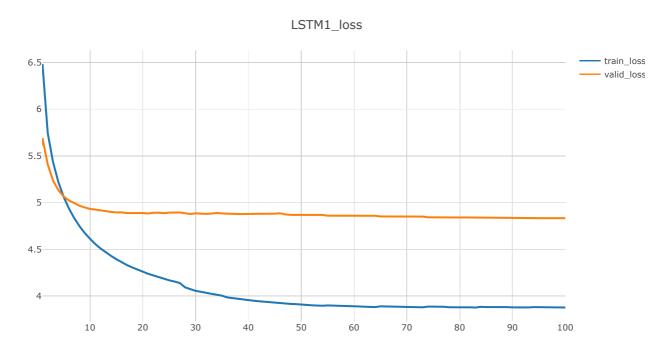
Result analysis:

- Compare 1 and 6, The effects of LSTM1 and GRU1 are similar, and both are around 119 pp1. However, even though LSTM1 has more trainable parameters than GRU1, LSTM1's efficiency is twice that of GRU1 (43 vs 85). The reason does not rule out that when GRU1 is training, the same GPU is occupied by other processes.
- Compare 1 and 2, gradient clipping can significantly improve LSTM.
- Compare 1, 3, 4 and 5, nlayers has a non-linear relationship with ppl, when nlayers is 2, ppl is the best, which is 116.42.

2. Training and validation curves.

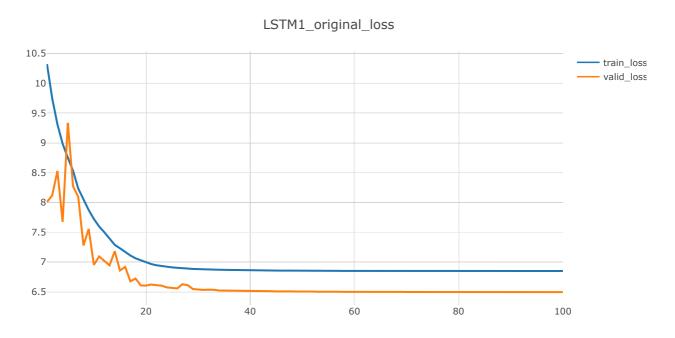
2.1. LSTM1_clip

Use Visdom to visualize training and validation curves. This model achieves **4.78** loss and **119.51** ppl on the **test** set. The training and validation curves are as follows:



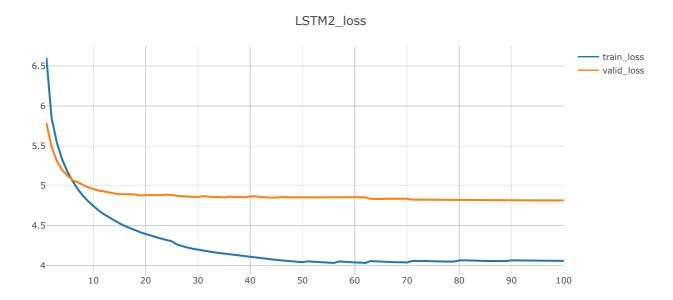
2.2. LSTM1_original

Use Visdom to visualize training and validation curves. This model achieves 6.43 loss and 622.36 ppl on the test set. The training and validation curves are as follows:



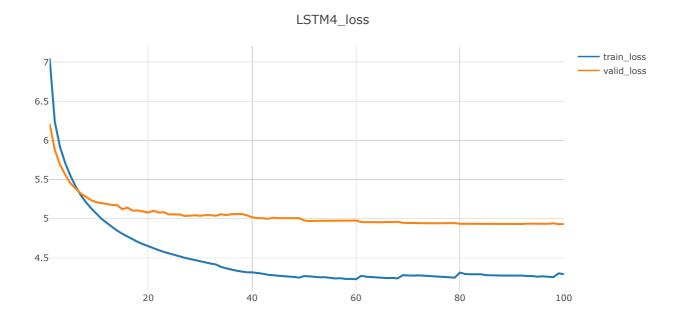
2.3. LSTM2_clip

Use Visdom to visualize training and validation curves. This model achieves 4.76 loss and 116.42 ppl on the test set. The training and validation curves are as follows:



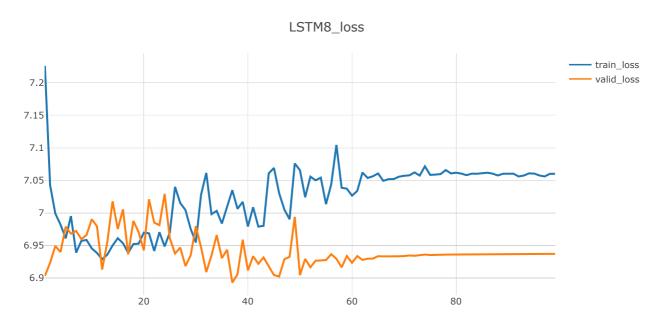
2.4. LSTM4_clip

Use Visdom to visualize training and validation curves. This model achieves **4.87** loss and **130.30** ppl on the **test** set. The training and validation curves are as follows:



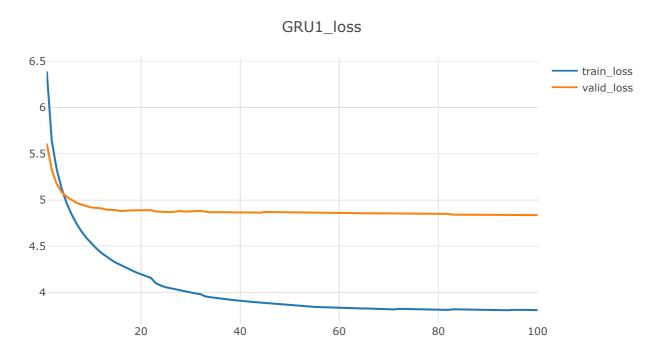
2.5. LSTM8_clip

Use Visdom to visualize training and validation curves. This model achieves 6.87 loss and 965.01 ppl on the test set. The training and validation curves are as follows:



2.6. GRU1_clip

Use Visdom to visualize training and validation curves. This model achieves **4.78** loss and **119.69** ppl on the **test** set. The training and validation curves are as follows:



Task B: standard Transformer [30pts]

In task B, I construct a standard Transformer [3] (Attention is All You Need). Use Nvidia RTX 1080 to accelerate my experiment, the following experiments will focus on these aspects:

- Different number of layers
 - **2 & 4**
- Different number of heads
 - **2 & 4**
- use gradient clip or not

1. PPL & Time

Sorry for not having enough time to go through all possible situations. The summary results are shown in the table below.

No.	Model	Train PPL	Valid PPL	Test PPL	ms/batch	Trainable params
1	Trans11_clip	178.58	255.90	232.54	39	20543078
2	Trans22_clip	156.45	201.86	184.38	48	21086078
3	Trans22_orginal	61.16	328.09	303.34	49	21086078
4	Trans42_clip	147.38	178.75	163.98	61	22172078
5	Trans24_clip	151.26	195.54	178.75	49	21086078

ps: Trans42 means: nlayers = 4 and nhead = 2

ps2: clip means: use gradient clip and SGD optimizer; original means: only use Adam optimizer.

Result analysis:

- Compare 1, 2, 4 and 5, appropriately increasing nlayers and nhead can effectively increase ppl. In the limited experimental results, 4 nlayers and 2 nhead work best. Besides, nlayers and efficiency (ms/batch) are positively correlated.
- Compare 2 and 3, gradient clipping can significantly improve Transformer.

2. Training and validation curves.

2.1. Trans11_clip

Use Visdom to visualize training and validation curves. This model achieves **5.45** loss and **232.54** ppl on the **test** set. The training and validation curves are as follows:



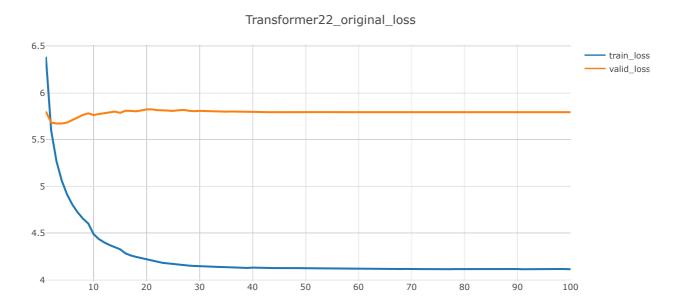
2.2. Trans22_clip

Use Visdom to visualize training and validation curves. This model achieves **5.22** loss and **184.38** ppl on the **test** set. The training and validation curves are as follows:



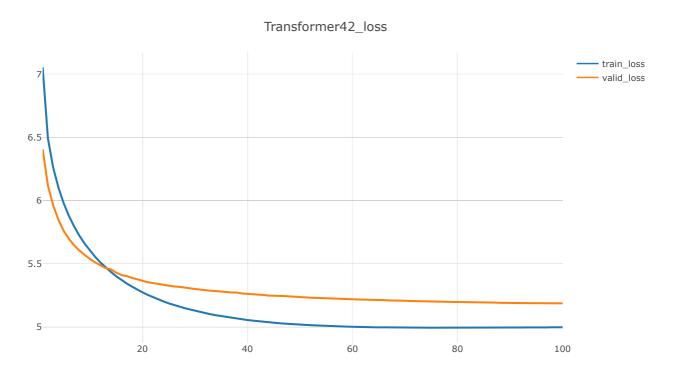
2.3. Trans22_original

Use Visdom to visualize training and validation curves. This model achieves **5.71** loss and **303.34** ppl on the **test** set. The training and validation curves are as follows:



2.4. Trans42_clip

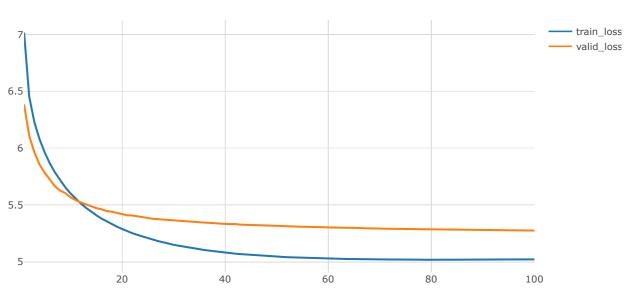
Use Visdom to visualize training and validation curves. This model achieves **5.10** loss and **163.98** ppl on the **test** set. The training and validation curves are as follows:



2.5. Trans24_clip

Use Visdom to visualize training and validation curves. This model achieves **5.19** loss and **178.75** ppl on the **test** set. The training and validation curves are as follows:





Other Tasks

1. Data Preparation [10pts]

1.1. Text Data Process

Since my torchtext version is 0.8.1, and the data.py in start-code can only run on 0.9.1, I can only refer to the online tutorial to rewrite data.py. There is a Dictionary class, which realizes the mutual conversion between word and index, and records the frequency of each word. In main class Corpus, the construction process is as follows:

- Call add_corpus to add words from 3 text files such as "wiki.train.tokens" to the dictionary
- sort the words by word frequency in descending order
 - this is for using adaptive softmax: it assumes that the most frequent word get index 0
- Call tokenize to tokenize the contents of 3 text files
- Call batchify. Its function and process are as follows:

```
Starting from sequential data, batchify arranges the dataset into columns.

For instance, with the alphabet as the sequence and batch size 4, we'd get

# ragms ra
```

- Work out how cleanly we can divide the dataset into batch-size parts.
- Trim off any extra elements that wouldn't cleanly fit (remainders).
- Evenly divide the data across the batch-size batches.
- Finally, we can call get_batch to get data and target.

```
get_batch subdivides the source data into chunks of length args.bptt.

If source is equal to the example output of the batchify function, with a bptt-limit of 2, we'd get the following two Variables for i = 0:

# rag m s r r b h n t r
# b h n t l c i o u l

Note that despite the name of the function, the subdivison of data is not done along the batch dimension (i.e. dimension 1), since that was handled by the batchify function. The chunks are along dimension 0, corresponding to the seq_len dimension in the LSTM.
```

1.2. Image Data Process

Refer to the official Pytorch tutorial [4], the image data processing flow is as follows:

- load all image files, sorting them to ensure that they are aligned
- load images and masks
- note that we haven't converted the mask to RGB, because each color corresponds to a different instance with 0 being background
- convert the PIL Image into a numpy array
- instances are encoded as different colors
- remove first id, because it is the background
- split the color-encoded mask into a set of binary masks
- get bounding box coordinates for each mask

- convert everything into a torch. Tensor
- suppose all instances are not crowd

2. Technical Details [10pts]

The language modeling task is to assign a probability for the likelihood of a given word (or a sequence of words) to follow a sequence of words. The nn.TransformerEncoder consists of multiple layers of nn.TransformerEncoderLayer. Along with the input sequence, a square attention mask is required because the self-attention layers in nn.TransformerEncoder are only allowed to attend the earlier positions in the sequence. For the language modeling task, any tokens on the future positions should be masked.

The implementation of mask in the code is as follows:

```
def generate_square_subsequent_mask(self, sz):
    mask = (torch.triu(torch.ones(sz, sz)) == 1).transpose(0, 1)
    mask = mask.float().masked_fill(mask == 0, float('-inf')).masked_fill(mask == 1, float(0.0))
    return mask
```

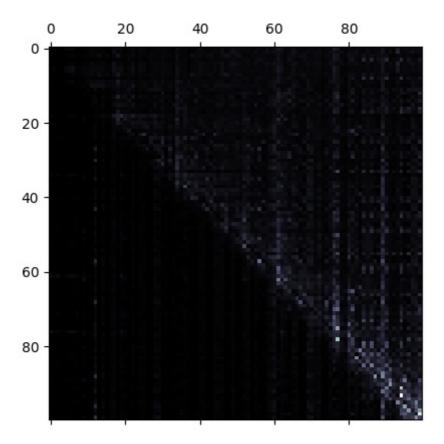
And it will be used on transformer encoder in forward:

```
def forward(self, src, src_mask):
    attention = self.get_attention(src)
    src = self.encoder(src) * math.sqrt(self.ninp)
    src = self.pos_encoder(src)
    output = self.transformer_encoder(src, src_mask)
    output = self.decoder(output)
    return output, attention
```

3. Attention Visualization [10pts]

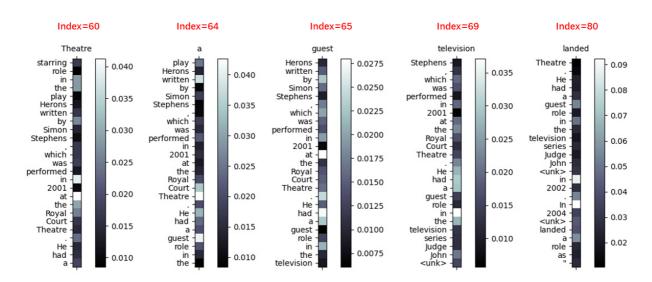
Use data from the first batch of the test set to visualize attention. It is a 100-word sentence:

The entire attention matrix is as follows:



Next, I chose a few different words to observe the results of their attention:

"Theatre" | "a" | "guest" | "television" | "landed"



Result analysis:

- "Theatre" is more related to "at" and "in"
- "a" is more related to "Theatre" and "guest"
- · ...
- The Transformer can learn meaningful attention values.

4. Extra Techniques [10pts]

Refer to the official Pytorch tutorial [4], I use gradient clip to improve my model.

 ${\tt clip_grad_norm\ helps\ prevent\ the\ exploding\ gradient\ problem\ in\ RNNs\ /\ LSTMs.}$

The comparison results are as follows:

No.	Model	Train PPL	Valid PPL	Test PPL	ms/batch	Trainable params
1	LSTM1_clip	48.28	125.68	119.51	43	20722478
2	LSTM1_original	943.23	662.08	622.36	53	20722478
3	Trans22_clip	156.45	201.86	184.38	48	21086078
4	Trans22_orginal	61.16	328.09	303.34	49	21086078

For detailed results, please refer to the report section of Task A and Task B. As shown in the above table, gradient clip can significantly improve my model, whether it is LSTM or Transformer

references

- [1] Hochreiter, Sepp, and Jürgen Schmidhuber. "Long short-term memory." Neural computation 9.8 (1997): 1735-1780.
- [2] Chung, Junyoung, et al. "Empirical evaluation of gated recurrent neural networks on sequence modeling." *arXiv preprint arXiv:1412.3555* (2014).
- [3] Vaswani, Ashish, et al. "Attention is all you need." arXiv preprint arXiv:1706.03762 (2017).
- [4] https://pytorch.org/tutorials/