Probability and Statistical Inference

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Apr 17th 2025

2 Sampling

2.1 Sample Spaces and Probability Models

To describe randomness formally, we need a language that specifies all the possible outcomes and assigns probabilities to them. This is the role of a probability model.

Definition 2.1.1 (Sample Space). A sample space Ω is the set of all possible outcomes of a random experiment. A probability model also requires a rule that assigns probabilities to events, which are subsets of Ω .

Let's look at a few examples to make this concrete.

Example 2.1.2 Coin Tossing In a single coin toss, the outcome is either heads (H) or tails (T). We write:

$$\Omega = \{H, T\}.$$

If the coin is fair, it makes sense to assign:

$$P(\mathbf{H}) = P(\mathbf{T}) = \frac{1}{2}.$$

We can extend this assignment to events involving multiple outcomes. For example,

$$P(\{\mathrm{H\ or\ T}\})=1$$

This kind of modeling is supported by empirical data. By the Law of Large Numbers (LLN), if we toss the coin many times and track how often heads appears, we should see the

relative frequency stabilize around 0.5:

$$P(A) \approx \lim_{n \to \infty} f_n(A).$$

We'll revisit this idea — and formally define the limit plim — later.

2.2 Uniform Probability Models and Discrete Distributions

The coin toss is an example of a uniform probability model: each outcome is equally likely. Let's generalize this to any finite or countable space.

Example 2.2.1 Uniform Distribution Suppose the sample space is:

$$\Omega = \{\omega_1, \omega_2, \dots, \omega_N\}.$$

Then a uniform probability model assigns equal weight to each outcome:

$$P(\omega_i) = \frac{1}{N}$$
, for all $i = 1, ..., N$.

More generally, for any event $A \subseteq \Omega$, we define:

$$P(A) = \frac{|A|}{|\Omega|}.$$

This approach works well for simple random experiments like rolling a die. For example:

$$\Omega = \{1, 2, 3, 4, 5, 6\}, \quad P(i) = \frac{1}{6}.$$

Let A be the event that the outcome is even. Then:

$$A = \{2, 4, 6\}, \quad P(A) = \frac{3}{6} = \frac{1}{2}.$$

Remark 2.1 On Notation Even though we write $P(\omega_i)$ for convenience, we are technically assigning probability to the set $\{\omega_i\}$, not the element itself. That is,

$$P(\omega_i) \equiv P(\{\omega_i\}),$$

since events are subsets of Ω .

2.3 Why the Sample Space Matters

In some problems, how we define Ω completely changes the model.

Example 2.3.1 The Twin Paradox Suppose a family has two children, and we're told that one of them is a girl. What is the probability that both are girls?

Let's break it into two interpretations:

Case 1: We are told the gender of the first child. The second child is still random:

$$\Omega = \{G, B\}, \quad P(G) = \frac{1}{2}.$$

Case 2: We are told at least one child is a girl, but not which one. Then the possible combinations are:

$$\Omega = \{GG, GB, BG\}.$$

Each outcome is equally likely, so:

$$P(GG) = \frac{1}{3}.$$

This example illustrates how the structure of Ω — and what we know — affects the probability model.

2.4 Bernoulli Trials and the Binomial Distribution

Let's now consider what happens when we repeat a simple random experiment multiple times — like flipping a coin, answering a yes/no question, or testing whether a lightbulb works.

Definition 2.4.1 (Bernoulli Trial). A **Bernoulli trial** is a random experiment with only two possible outcomes, usually called "success" (1) and "failure" (0). For example, in a coin flip:

$$\Omega = \{0, 1\}, \quad P(1) = p, \quad P(0) = 1 - p.$$

Here, p is the probability of success.

Now suppose we repeat the experiment n times independently. The full sample space is then:

$$\Omega^n = \{0, 1\}^n,$$

which consists of all sequences of 0s and 1s of length n. For example, a possible outcome could be (1,0,1,1,0) — meaning 3 successes and 2 failures.

We define a function that counts the number of successes: Let $S_n: \Omega^n \to \{0, 1, \dots, n\}$ be the

function

$$S_n(\omega) = \sum_{i=1}^n \omega_i.$$

This counts how many of the n trials resulted in success.

What is the probability that we get exactly x successes in n trials? Each specific sequence with x successes and (n-x) failures has probability:

$$p^x(1-p)^{n-x}.$$

And how many such sequences are there? That's given by a binomial coefficient:

Definition 2.4.2 (Binomial Coefficient).

$$\binom{n}{x} = \frac{n!}{x!(n-x)!}$$

is the number of different sequences (orderings) that contain exactly x successes in n trials.

Putting this together, we get the **binomial distribution**:

Definition 2.4.3 (Binomial Distribution). The probability of observing exactly x successes in n independent Bernoulli trials, each with success probability p, is:

$$P(X = x) = \binom{n}{x} p^x (1-p)^{n-x}, \quad x = 0, 1, \dots, n.$$

This is called the **binomial distribution** with parameters n and p, written:

$$X \sim Binom(n, p)$$
.

Remark 2.2 The binomial formula accounts for both the probability of each individual sequence and the number of such sequences. The sum of all probabilities over x = 0 to n equals 1.