```
function [x ] = gauss_jordon(A,b)
%####A####
   [m1,m2] = size(A);
   if m1 \sim = m2
       error('####A###')
       return
  end
  siz = m1;
   [n1,n2] = size(b);
  %####b####
  if n2 == siz && n1==1
       b = b';
  elseif n1==1 && n2 == siz
      b = b;
  else
       error('b####A####')
   end
   if rank(A)~=rank([A,b])
       error('A###############;');
       return;
  end
  %#A##
  A = [A,b];
  x = zeros(siz,1);
  for i = 1:siz-1
       a_{ii} = abs(A(i,i));
       [max_v,max_id_relative] = max(abs(A(i:siz)));
       max_id = i + max_id_relative - 1;
       if max_id ~=i
           A([i,max_id],:) = A([max_id,i],:);
       end
       %##
       for j = i+1:siz
           A(j,:) = A(j,:) - (A(j,i)/A(i,i)) * A(i,:);
       end
  end
  x(siz) = A(siz,siz+1)/A(siz,siz);
   for i = siz-1:-1:1
       x(i) = (A(i,siz+1) - A(i,i+1:siz)*x(i+1:siz)) / A(i,i);
   end
```

return

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