

## LECTURE 7: LINEAR LIE GROUPS

### 1. THE GENERAL LINEAR GROUP

Recall that  $M(n, \mathbb{R})$ , the set of all  $n \times n$  real matrices, is diffeomorphic to  $\mathbb{R}^{n^2}$ .

**Definition 1.1.** A *linear Lie group*, or *matrix Lie group*, is a submanifold of  $M(n, \mathbb{R})$  which is also a Lie group, with group structure the matrix multiplication.

Let's begin with the “largest” linear Lie group, the *general linear group*

$$\mathrm{GL}(n, \mathbb{R}) = \{X \in M(n, \mathbb{R}) \mid \det X \neq 0\}.$$

Since the determinant map is continuous,  $\mathrm{GL}(n, \mathbb{R})$  is open in  $M(n, \mathbb{R})$  and thus a submanifold. Moreover,  $\mathrm{GL}(n, \mathbb{R})$  is closed under the group multiplication and inversion operations, so it is a Lie group. Obviously  $\mathrm{GL}(n, \mathbb{R})$  is an  $n^2$ -dimensional noncompact Lie group, and it is not connected. In fact, it consists of exactly two connected components,

$$\mathrm{GL}_+(n, \mathbb{R}) = \{X \in M(n, \mathbb{R}) \mid \det X > 0\}$$

and

$$\mathrm{GL}_-(n, \mathbb{R}) = \{X \in M(n, \mathbb{R}) \mid \det X < 0\}.$$

The fact that  $\mathrm{GL}(n, \mathbb{R})$  is an open subset of  $M(n, \mathbb{R}) \simeq \mathbb{R}^{n^2}$  also implies that the Lie algebra of  $\mathrm{GL}(n, \mathbb{R})$ , as the tangent space at  $e = I_n$ , is the set  $M(n, \mathbb{R})$  itself, i.e.

$$\mathfrak{gl}(n, \mathbb{R}) = \{A \mid A \text{ is an } n \times n \text{ real matrix}\}.$$

To figure out the Lie bracket operation, we take a matrix  $A = (A_{ij})_{n \times n} \in \mathfrak{g}$ , and take the global coordinate system by  $(X^{ij})$ . Then the corresponding tangent vector at  $T_{I_n} \mathrm{GL}(n, \mathbb{R})$  is  $\sum A_{ij} \frac{\partial}{\partial X^{ij}}$ , and the corresponding left-invariant vector on  $G$  at the matrix  $X = (X^{ij})$  is  $\sum X^{ik} A_{kj} \frac{\partial}{\partial X^{ij}}$ . It follows that the Lie bracket  $[A, B]$  between matrices  $A, B \in \mathfrak{g}$  is the matrix corresponding to

$$\begin{aligned} \left[ \sum X^{ik} A_{kj} \frac{\partial}{\partial X^{ij}}, \sum X^{pq} B_{qr} \frac{\partial}{\partial X^{pr}} \right] &= \sum X^{ik} A_{kj} B_{jr} \frac{\partial}{\partial X^{ir}} - \sum X^{pq} B_{qr} A_{rj} \frac{\partial}{\partial X^{pj}} \\ &= \sum X^{ik} (A_{kr} B_{rj} - B_{kr} A_{rj}) \frac{\partial}{\partial X^{ij}}. \end{aligned}$$

In other words, the Lie bracket operation on  $\mathfrak{g}$  is the matrix commutator

$$[A, B] = AB - BA.$$

Given any  $A \in \mathfrak{gl}(n, \mathbb{R})$ , we can define the matrix exponential

$$e^A = I_n + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \cdots + \frac{A^n}{n!} + \cdots.$$

It is easy to check that the series converges, and

$$e^{sA}e^{tA} = e^{(s+t)A}.$$

Notice that  $e^{0A} = I_n$ , we have  $(e^{tA})^{-1} = e^{-tA}$ . In particular,  $e^{tA} \in \mathrm{GL}(n, \mathbb{R})$ . So  $e^{tA}$  is a one-parameter subgroup of  $\mathrm{GL}(n, \mathbb{R})$ . Since  $\frac{d}{dt}|_{t=0}e^{tA} = A$ , we conclude that the exponential map  $\exp : \mathfrak{gl}(n, \mathbb{R}) \rightarrow \mathrm{GL}(n, \mathbb{R})$  is

$$\exp(A) = e^A = I_n + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \cdots.$$

Note that  $\exp$  is not surjective, not even surjective to  $\mathrm{GL}_+(n, \mathbb{R})$ .

*Remark.* Alternatively, one can first show that  $e^{tA}$  is the one-parameter subgroup of  $\mathrm{GL}(n, \mathbb{R})$  generated by  $A \in \mathfrak{gl}(n, \mathbb{R})$ , and thus the Lie bracket structure on  $\mathfrak{gl}(n, \mathbb{R})$  is

$$[A, B] = \frac{d}{dt} \Big|_{t=0} \frac{d}{ds} \Big|_{s=0} (e^{tA}e^{sB}e^{-tA}) = \frac{d}{dt} \Big|_{t=0} (e^{tA}Be^{-tA}) = AB - BA.$$

## 2. LIE SUBGROUPS OF $\mathrm{GL}(n, \mathbb{R})$

Before we continue to study other linear Lie groups, we need some general results on Lie subgroups. More details and proofs of these results will be discussed later.

**Definition 2.1.** A subgroup  $H$  of a Lie group  $G$  is called a *Lie subgroup* if it is a Lie group (with respect to the induced group operation), and the inclusion map  $\iota_H : H \hookrightarrow G$  is an immersion (and therefore a Lie group homomorphism).

Suppose  $H$  is a Lie subgroup of  $G$ , and  $\mathfrak{h}$  be the Lie algebra of  $H$ . Since  $\iota : H \hookrightarrow G$  is an immersion and is a Lie group homomorphism,  $d\iota_H : \mathfrak{h} \rightarrow \mathfrak{g}$  is injective and is a Lie algebra homomorphism. So we can think of  $\mathfrak{h}$  as a *Lie subalgebra* (= a linear subspace that is closed under the Lie bracket) of  $\mathfrak{g}$ . Note that a one-parameter subgroup of  $H$  is automatically a one-parameter of  $G$  (with initial vector in  $T_eH$ ), so the exponential map  $\exp_H : \mathfrak{h} \rightarrow H$  is exactly the restriction of  $\exp_G : \mathfrak{g} \rightarrow G$  onto  $\mathfrak{h}$ . The following theorem, which we will prove later, is very useful in determine the Lie algebra of a Lie subgroup.

**Theorem 2.2.** Suppose  $H$  is a Lie subgroup of  $G$ . Then as a Lie subalgebra of  $\mathfrak{g}$ ,

$$\mathfrak{h} = \{X \in \mathfrak{g} \mid \exp_G(tX) \in H \text{ for all } t \in \mathbb{R}\}.$$

Now we are ready to study other linear Lie groups. By definition they are Lie subgroups of  $\mathrm{GL}(n, \mathbb{R})$ .

*Example. (The special linear group)* The special linear group is defined as

$$\mathrm{SL}(n, \mathbb{R}) = \{X \in \mathrm{GL}(n, \mathbb{R}) : \det X = 1\}.$$

It is easy see that  $\mathrm{SL}(n, \mathbb{R})$  is a subgroup of  $\mathrm{GL}(n, \mathbb{R})$ . In PSET 1 we have seen that  $\mathrm{SL}(n, \mathbb{R})$  is an  $n^2 - 1$  dimensional submanifold of  $\mathrm{GL}(n, \mathbb{R})$ . It follows that  $\mathrm{SL}(n, \mathbb{R})$  is a (connected non-compact) Lie subgroup of  $\mathrm{GL}(n, \mathbb{R})$ .

To determine its Lie algebra  $\mathfrak{sl}(n, \mathbb{R})$ , we notice that

$$\det e^A = e^{\text{Tr}(A)}.$$

So for an  $n \times n$  matrix  $A$ ,  $e^A \in \text{SL}(n, \mathbb{R})$  if and only if  $\text{Tr}(A) = 0$ . We conclude

$$\mathfrak{sl}(n, \mathbb{R}) = \{A \in \mathfrak{gl}(n, \mathbb{R}) \mid \text{Tr}(A) = 0\}.$$

*Example. (The orthogonal group)* Next let's consider the *orthogonal group*

$$\text{O}(n) = \{X \in \text{GL}(n, \mathbb{R}) : X^T X = I_n\}.$$

This is another subgroup of  $\text{GL}(n, \mathbb{R})$ . In PSET 1 we have seen that  $\text{O}(n)$  is an  $\frac{n(n-1)}{2}$  dimensional submanifold of  $\text{GL}(n, \mathbb{R})$ . So  $\text{O}(n)$  is an  $\frac{n(n-1)}{2}$  dimensional Lie subgroup of  $\text{GL}(n, \mathbb{R})$ . Note that  $\text{O}(n)$  is compact.

To figure out its Lie algebra  $\mathfrak{o}(n)$ , we note that  $(e^A)^T = e^{A^T}$ , so

$$(e^{tA})^T e^{tA} = I_n \iff e^{tA^T} = e^{-tA}$$

For all  $t$ . Since the exponential map is locally bijective, we conclude that  $A \in \mathfrak{o}(n)$  if and only if  $A^T = -A$ . So

$$\mathfrak{o}(n) = \{A \in \mathfrak{gl}(n, \mathbb{R}) \mid A^T + A = 0\},$$

which is the space of  $n \times n$  skew-symmetric matrices.

Notice that  $\text{O}(n)$  is not connected. It consists of two connected components, and the connected component of identity is called the *special orthogonal groups*

$$\text{SO}(n) = \{X \in \text{GL}(n, \mathbb{R}) : X^T X = I_n, \det X = 1\} = \text{O}(n) \cap \text{SL}(n, \mathbb{R}).$$

Its Lie algebra  $\mathfrak{so}(n)$  is the same as  $\mathfrak{o}(n)$ .

*Example. (The symplectic group)* The *symplectic group* is by definition

$$\text{Sp}(2n, \mathbb{R}) = \{X \in \text{GL}(2n, \mathbb{R}) : X^T J X = J\},$$

where Let  $J = \begin{pmatrix} 0 & I_n \\ -I_n & 0 \end{pmatrix}$ . It is a Lie group of dimension  $n(2n+1)$  with Lie algebra

$$\begin{aligned} \mathfrak{sp}(2n, \mathbb{R}) &= \{A \in \mathfrak{gl}(2n, \mathbb{R}) \mid JA + A^T J = 0\} \\ &= \left\{A = \begin{pmatrix} A_1 & A_2 \\ A_3 & A_4 \end{pmatrix} \mid A_i \in M(n, \mathbb{R}), A_1 = -A_4^T, A_2 = A_2^T, A_3 = A_3^T\right\}. \end{aligned}$$

This, as well as the orthogonal group in the previous example, are special cases of the following more general example. Let  $\beta : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$  be a bilinear form on  $\mathbb{R}^n$ . Consider the set of all invertible  $n \times n$  matrices that preserves  $\beta$ ,

$$\text{GL}_\beta(n, \mathbb{R}) = \{X \in \text{GL}(n, \mathbb{R}) \mid \beta(Xu, Xv) = \beta(u, v) \text{ for all } u, v \in \mathbb{R}^n\}.$$

In matrix form, there is a matrix  $B$  such that  $\beta(u, v) = u^T B v$ . Then

$$\text{GL}_\beta(n, \mathbb{R}) = \{X \in \text{GL}(n, \mathbb{R}) \mid X^T B X = B\}.$$

**Lemma 2.3.**  $\mathrm{GL}_\beta(n, \mathbb{R})$  is a linear Lie group with Lie algebra

$$\mathfrak{gl}_\beta(n, \mathbb{R}) = \{A \in \mathfrak{gl}(n, \mathbb{R}) \mid A^T B + BA = 0\}.$$

*Proof.* One can easily check that  $\mathrm{GL}_\beta(n, \mathbb{R})$  is a subgroup of  $\mathrm{GL}(n, \mathbb{R})$ , and it is topologically a closed subset. According to the Cartan's closed subgroup theorem that we will prove later, it is a Lie subgroup.

To describe its Lie algebra, notice that  $A \in \mathfrak{gl}_\beta(n, \mathbb{R})$  if and only if  $e^{tA} \in \mathrm{GL}_\beta(n, \mathbb{R})$ , i.e.  $e^{tA^T} B e^{tA} = B$ . By taking  $t$  derivative at  $t = 0$ , we get  $A^T B + BA = 0$ . Conversely, if  $A^T B + BA = 0$ , i.e.  $tA^T B = B(-tA)$ , one can easily derive by definition that  $e^{tA^T} B = B e^{-tA}$ , i.e.  $e^{tA^T} B e^{tA} = B$ . This completes the proof.  $\square$

Notice that in the case  $B = I_n$  ( $\beta$  = the standard inner product on  $\mathbb{R}^n$ ), we get the orthogonal group  $O(n)$ , and in the case  $B = J$  ( $\beta$  = the standard symplectic form on  $\mathbb{R}^{2n}$ ), we get the symplectic group above. If we take  $\beta$  to be the standard inner product of signature  $(p, n - p)$ ,

$$\beta(x, y) = \sum_{i=1}^p x_i y_i - \sum_{i=p+1}^n x_i y_i,$$

then we will get the *indefinite orthogonal group*  $O(p, n - p)$ ,

$$O(p, n - p) = \{X \in GL(n, \mathbb{R}) \mid X^T I(p, n - p) X = I(p, n - p)\},$$

where  $I(p, n - p) = \mathrm{diag}(I_p, -I_{n-p})$ . Its Lie algebra is

$$\mathfrak{o}(p, n - p) = \{X \in \mathfrak{gl}(n, \mathbb{R}) \mid A^T I(p, n - p) + I(p, n - p) A = 0\}.$$

*Example. (The unitary group)* All the previous examples generalize to complex matrices. In particular, the *unitary groups*

$$U(n) = \{X \in GL(n, \mathbb{C}) : \overline{X}^T X = I_n\}$$

is a Lie subgroup of  $GL(n, \mathbb{C})$  with Lie algebra

$$\mathfrak{u}(n) = \{A \in \mathfrak{gl}(n, \mathbb{C}) \mid \overline{A}^T + A = 0\},$$

the space of skew-Hermitian matrices.

Also the *special unitary groups*

$$SU(n) = U(n) \cap SL(n, \mathbb{C})$$

has Lie algebra

$$\mathfrak{su}(n) = \{A \in M(n, \mathbb{C}) \mid \overline{A}^T + A = 0, \mathrm{Tr}(A) = 0\}.$$

Also we have the *compact symplectic group*

$$\mathrm{Sp}(n) = U(2n) \cap \mathrm{Sp}(2n, \mathbb{C}).$$

This is a real compact Lie group of dimension  $n(2n + 1)$ .