现代数学物理方法

第四章, SU(N)

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Tensor methods:

Lower & upper indices:

• We begin with relabeling the basis states of su(3) fundamental representation (1,0) = 3,

$$\ket{M_1} = \ket{1/2,\ 1/2\sqrt{3}} = \ket{1}$$
 $E_{-lpha_1}\ket{M_1} = \ket{0,\ -1/\sqrt{3}} = \ket{3}$ $\sqrt{2}E_{-lpha_2}E_{-lpha_1}\ket{M_1} = \ket{-1/2,\ 1/2\sqrt{3}} = \ket{2}$

• The basis states of another su(3) fundamental representation $(0, 1) = \overline{3}$ are re-labelled as:

$$egin{array}{lcl} \left| M_2
ight
angle &=& \left| 1/2, \; -1/2\sqrt{3}
ight
angle &=& \left| ^2
ight
angle \\ E_{-lpha_2} \left| M_2
ight
angle &=& \left| 0, \; 1/\sqrt{3}
ight
angle &=& \left| ^3
ight
angle \ \\ \sqrt{2} E_{-lpha_1} E_{-lpha_2} \left| M_2
ight
angle &=& \left| -1/2, \; -1/2\sqrt{3}
ight
angle &=& \left| ^1
ight
angle \end{array}
ight\}$$

In Rep. 3, the matrices of SU(3) generators X_a are expressed as

$$(X_a)^i_{\ j}$$

so that:

$$\left|X_a\left|_j
ight
angle=\left|_i
ight
angle\,\left(X_a
ight)^i_{\;\;j}$$

Because the Rep. $\bar{\bf 3}$ is the complex conjugate of Rep. $\bf 3$, with generators $-X_a^*$, i.e.,

$$-(X_a^*)_j^{\ i} = -(X_a^T)_j^{\ i} = -(X_a)^i_{\ j}$$

Then,

$$X_a |i\rangle = |j\rangle (-X_a^*)_j^i$$

= $-|j\rangle (X_a)_j^i$

Now, we can define the tensor product representation of su(3).

A typical tensor product representation of su(3) is:

$$\underbrace{\mathbf{3} \times \mathbf{3} \times \cdots \times \mathbf{3}}_{n} \times \underbrace{\mathbf{\bar{3}} \times \mathbf{\bar{3}} \times \cdots \times \mathbf{\bar{3}}}_{m}$$

The basis states of tensor product representation are:

$$\begin{vmatrix} i_1 i_2 \cdots i_m \\ j_1 j_2 \cdots j_n \end{vmatrix} = \begin{vmatrix} i_1 \\ i_2 \\ i_3 \end{vmatrix} \cdots \begin{vmatrix} i_n \\ i_n \\ i_n \end{vmatrix} \begin{vmatrix} i_1 \\ i_2 \\ i_n \end{vmatrix} \cdots \begin{vmatrix} i_n \\ i_n \\ i_n \end{vmatrix}$$

Recalling

$$X_a^{D_1 \times D_2} = X_a^{D_1} \times 1 + 1 \times X_a^{D_2}$$

under the generator action, these basis states transform as follows:

$$egin{aligned} X_a igg| egin{aligned} i_1 i_2 & \cdots i_m \ j_1 j_2 & \cdots j_n \end{pmatrix} &= \sum_{l=1}^n igg| egin{aligned} i_1 i_2 & \cdots i_m \ j_1 j_2 & \cdots j_{l-1} k j_{l+1} & \cdots j_n \end{pmatrix} igg(X_a igg)^k \ &- \sum_{l=1}^m igg| i_1 i_2 & \cdots i_{l-1} k i_{l+1} & \cdots i_m \ j_1 j_2 & \cdots j_n \end{pmatrix} igg(X_a igg)^{i_l} \ & k \end{aligned}$$

An arbitrary state in this tensor product space is,

$$\ket{v} = \ket{\begin{smallmatrix} i_1 i_2 \cdots i_m \ j_1 j_2 \cdots j_n \end{smallmatrix}} v_{i_1 i_2 \cdots i_m}^{j_1 j_2 \cdots j_n}$$

Discussions:

- $v = \left(v_{i_1i_2\cdots i_m}^{j_1j_2\cdots j_n}\right)$ is called a SU(3) tensor.
- In analogy with the concept of *wave function* in QM, we can express the tensor's components as:

$$egin{aligned} v_{i_1i_2\cdots i_m}^{j_1j_2\cdots j_n} &= egin{aligned} i_1i_2\cdots i_m \ j_1j_2\cdots j_n \end{aligned} igg| v \end{aligned}$$

• We can think of the action of the generator X_a on state $|v\rangle$ as an effective action of X_a on the tensor components:

$$X_a\ket{v}=\ket{X_av}$$

Consequently,

$$\begin{split} \left(X_{a}v\right)_{i_{1}i_{2}\cdots i_{m}}^{j_{1}j_{2}\cdots j_{n}} &= \left\langle \substack{i_{1}i_{2}\cdots i_{m}\\ j_{1}j_{2}\cdots j_{n}} \right| X_{a}v\right\rangle \\ &= \left\langle \substack{i_{1}i_{2}\cdots i_{m}\\ j_{1}j_{2}\cdots j_{n}} \right| X_{a} \left| \substack{k_{1}k_{2}\cdots k_{m}\\ l_{1}l_{2}\cdots l_{n}} \right\rangle v_{k_{1}k_{2}\cdots k_{m}}^{l_{1}l_{2}\cdots l_{n}} \\ &= \sum_{q=1}^{n} \left\langle \substack{i_{1}i_{2}\cdots i_{m}\\ j_{1}j_{2}\cdots j_{n}} \right| \substack{k_{1}k_{2}\cdots k_{m}\\ l_{1}\cdots l_{q-1}pl_{q+1}\cdots l_{n}} \right\rangle \left(X_{a}\right)^{p}_{l_{q}} v_{k_{1}k_{2}\cdots k_{m}}^{l_{1}l_{2}\cdots l_{n}} \\ &- \sum_{q=1}^{m} \left\langle \substack{i_{1}i_{2}\cdots i_{m}\\ j_{1}j_{2}\cdots j_{n}} \right| \substack{k_{1}\cdots k_{q-1}pk_{q+1}\cdots k_{m}\\ l_{1}l_{2}\cdots l_{n}} \right\rangle \left(X_{a}\right)^{k_{q}}_{p} v_{k_{1}k_{2}\cdots k_{m}}^{l_{1}l_{2}\cdots l_{n}} \\ &= \sum_{q=1}^{n} \left(X_{a}\right)^{p}_{l_{q}} v_{i_{1}i_{2}\cdots i_{m}}^{j_{1}\cdots j_{q-1}l_{q}j_{q+1}\cdots j_{n}} \delta_{p}^{j_{q}} \\ &- \sum_{q=1}^{m} \left(X_{a}\right)^{k_{q}}_{p} v_{i_{1}i_{2}\cdots i_{m}}^{j_{1}j_{2}\cdots j_{n}} \\ &- \sum_{q=1}^{m} \left(X_{a}\right)^{k_{q}}_{p} v_{i_{1}\cdots i_{q-1}l_{q}i_{q+1}\cdots i_{m}}^{j_{1}j_{2}\cdots j_{n}} \delta_{i_{q}}^{p} \end{split}$$

The action of the SU(3) generators on an arbitrary tensor reads,

$$(X_a v)_{i_1 \cdots i_m}^{j_1 \cdots j_n} = \sum_{l=1}^n (X_a)_{i_l}^{j_l} v_{i_1 i_2 \cdots i_m}^{j_1 \cdots j_{l-1} k j_{l+1} \cdots j_n} - \sum_{l=1}^m (X_a)_{i_l}^k v_{i_1 \cdots i_{l-1} k i_{l+1} \cdots i_m}^{j_1 j_2 \cdots j_n}$$

Invariant tensors:

An invariant tensor of SU(3) is referred to one that does not change under any SU(3) transformations.

SU(3) invariant tensors:

For SU(3), three invariant tensors exist,

- \bullet δ_j^i
- $\mathbf{2} \epsilon_{ijk}$
- \bullet ϵ^{ijk}

Proof:

The invariance of δ_i^i is obvious,

$$(X_a \delta)^i_j = (X_a)^i_k \delta^k_j - (X_a)^k_j \delta^k_k$$

= $(X_a)^i_j - (X_a)^i_j$
= 0

Next we consider the invariance of e^{ijk} and e_{ijk} . e.g.,

$$\left(X_a\epsilon\right)^{ijk}=\left(X_a\right)^i{}_l\epsilon^{ljk}+\left(X_a\right)^j{}_l\epsilon^{ilk}+\left(X_a\right)^k{}_l\epsilon^{ijl}$$

By definition,

$$\epsilon^{ijk} = \epsilon_{ijk} = \left\{ egin{array}{ll} 1 & & ext{if } (ijk) ext{ is an even permutation of } (123) \ -1 & & ext{if } (ijk) ext{ is an odd permutation of } (123) \ 0 & & ext{other cases} \end{array}
ight.$$

Hence,

$$(X_{a}\epsilon)^{123} = (X_{a})^{1}{}_{i}\epsilon^{i23} + (X_{a})^{2}{}_{j}\epsilon^{1j3} + (X_{a})^{3}{}_{k}\epsilon^{12k}$$

$$= (X_{a})^{1}{}_{1} + (X_{a})^{2}{}_{2} + (X_{a})^{3}{}_{3}$$

$$= \operatorname{Tr}(X_{a}) = 0$$

$$(X_{a}\epsilon)^{112} = (X_{a})^{1}{}_{3}\epsilon^{312} + (X_{a})^{1}{}_{3}\epsilon^{132} + (X_{a})^{2}{}_{k}\epsilon^{11k}$$

$$= (X_{a})^{1}{}_{3} - (X_{a})^{1}{}_{3} = 0$$

$$(X_{a}\epsilon)^{111} = (X_{a})^{1}{}_{i}\epsilon^{i11} + (X_{a})^{1}{}_{j}\epsilon^{1j1} + (X_{a})^{1}{}_{k}\epsilon^{11k} = 0$$

Therefore, for arbitrary i, j, k = 1, 2, 3, we have

$$(X_a\epsilon)^{ijk}=0$$

and similarly,

$$(X_a\epsilon)_{ijk}=0$$

Namely, ϵ_{ijk} and ϵ^{ijk} are two *invariant tensors* of SU(3).

Warning:

Though δ^i_j is a SU(3) invariant, both δ^{ij} and δ_{ij} are not invariant under SU(3) transformations.

Explanation:

Since,

$$\left(X_a\delta
ight)^{ij}=\left(X_a
ight)^i_{k}\delta^{kj}+\left(X_a
ight)^j_{k}\delta^{ik}$$

we have:

$$(X_a \delta)^{11} = (X_a)^1_k \delta^{k1} + (X_a)^1_k \delta^{1k} = 2(X_a)^1_1 \neq 0$$

Irreducible representations and symmetry:

We now pick out the states in *tensor product representation* according to the irreducible Rep.(n, m).

The highest weight of Rep.(n, m) of SU(3) reads:

$$ec{M}=nec{M}_1+mec{M}_2$$

where $\vec{M}_1 = \left(\frac{1}{2}, \frac{1}{2\sqrt{3}}\right)$ and $\vec{M}_2 = \left(\frac{1}{2}, -\frac{1}{2\sqrt{3}}\right)$. Therefore, the highest weight state of Rep. (n, m) is

$$\left\{egin{array}{l} \left| egin{array}{l} 222\cdots \ 111\cdots
ight>, & \left\{\#2=m, & \#1=n
ight\} \end{array}
ight.$$

which corresponds to the tensor v_H below,

$$(v_H)_{i_1 i_2 \cdots i_m}^{j_1 j_2 \cdots j_n} = \left\langle \substack{i_1 i_2 \cdots i_m \\ j_1 j_2 \cdots j_n} \right| \substack{222 \cdots \\ 111 \cdots} \right\rangle$$

$$= \mathcal{N} \delta^{j_1 1} \delta^{j_2 1} \cdots \delta^{j_n 1} \delta_{i_1 2} \delta_{i_2 2} \cdots \delta_{i_m 2}$$

with \mathcal{N} the normalization constant.

Discussions:

• The tensor v_H is symmetric for the exchange of any two upper indices, and also symmetric for the exchange of any two lower indices.

$$egin{array}{ll} (v_H)_{i_1 i_2 \cdots i_m}^{j_1 j_2 \cdots j_n} &= \mathcal{N} \; \delta^{j_1 1} \delta^{j_2 1} \cdots \delta^{j_n 1} \delta_{i_1 2} \delta_{i_2 2} \cdots \delta_{i_m 2} \ &= (v_H)_{i_1 i_2 \cdots i_m}^{j_2 j_1 \cdots j_n} &= (v_H)_{i_2 i_1 \cdots i_m}^{j_1 j_2 \cdots j_n} \end{array}$$

• The tensor v_H is *traceless* for one upper and one lower indices,

$$\delta^{i_1}_{j_1} \left(v_H
ight)^{j_1 j_2 \cdots j_n}_{i_1 i_2 \cdots i_m} = 0$$

Both properties of v_H are preserved by SU(3) transformations, under which $v_H \leadsto X_a v_H$:

$$egin{align*} \left(X_{a}v_{H}
ight)_{i_{1}i_{2}\cdots i_{m}}^{j_{1}j_{2}\cdots j_{n}} &= \left(X_{a}v_{H}
ight)_{i_{1}i_{2}\cdots i_{m}}^{j_{2}j_{1}\cdots j_{n}} &= \left(X_{a}v_{H}
ight)_{i_{2}i_{1}\cdots i_{m}}^{j_{1}j_{2}\cdots j_{n}}, \ \delta_{j_{1}}^{i_{1}}ig(X_{a}v_{H}ig)_{i_{1}i_{2}\cdots i_{m}}^{j_{1}j_{2}\cdots j_{n}} &= 0. \end{split}$$

Dimension of SU(3) Rep.(n, m):

In Rep.(n,m) of SU(3), the tensor related to the state $\begin{vmatrix} i_1 i_2 \cdots i_m \\ j_1 j_2 \cdots j_n \end{vmatrix}$ is

$$v=v_{i_1i_2\cdots i_m}^{j_1j_2\cdots j_n}$$

- *v* has *n* upper and *m* lower indices.
- v is separately symmetric in each type of the indices. If there were
 no further constraints, the number of independent components of
 v would be:

$$B(n,m) = \frac{(n+2)!}{n!2!} \frac{(m+2)!}{m!2!} = \frac{1}{4}(n+1)(n+2)(m+1)(m+2)$$

• Unfortunately, v has to be traceless. As a result, v has to satisfy B(n-1,m-1) additional constraints such as $v_{i_1k_3\cdots i_m}^{kj_2j_3\cdots j_n}=0$.

The correct number of independent components of SU(3) tensor in its irreducible Rep. (n, m) is then,

$$D(n,m) = B(n,m) - B(n-1,m-1)$$

$$= \frac{1}{4}(n+1)(m+1)[(n+2)(m+2) - nm]$$

$$= \frac{1}{2}(n+1)(m+1)(n+m+2)$$

D(n, m) could also be interpreted as the dimension of the irreducible Rep.(n, m).

Examples:

$$D(1,0) = D(0,1) = 3,$$

 $D(1,1) = 8,$
 $D(2,0) = D(0,2) = 6,$
 $D(2,1) = D(1,2) = 15,$
 $D(2,2) = 27,$
 $D(3,0) = D(0,3) = 10.$

Clebsch-Gordan decomposition:

Suppose u and v are two SU(3) tensors in Rep. (n, m) and Rep. (p, q), respectively,

 $u=\left(u_{i_1i_2\cdots i_m}^{j_1j_2\cdots j_n}
ight),\quad v=\left(v_{b_1b_2\cdots b_q}^{a_1a_2\cdots a_p}
ight)$

The tensor product of these two tensors

$$u\otimes v=\left(u\otimes v
ight)_{i_1\cdots i_nb_1\cdots b_q}^{j_1\cdots j_na_1\cdots a_p}=\left(u_{i_1i_2\cdots i_m}^{j_1j_2\cdots j_n}v_{b_1b_2\cdots b_q}^{a_1a_2\cdots a_p}
ight)$$

yields a SU(3) tensor in a *reducible* representation.

Strategy for picking out *irreducible representations* from the above reducible representation is,

- Making irreducible representations out of the product of tensors u and v;
- Expressing $u \otimes v$ as a sum of such terms that are proportional to some irreducible representations of SU(3).

Consider the CG-decomposition of $\mathbf{3} \times \mathbf{3}$.

Because **3** is Rep.(1, 0), the tensor of **3** has the form of $u = (u^i)$. Consequently, an arbitrary SU(3) tensor of 3×3 can be written as

$$(u \otimes v)^{ij} = u^i v^j, \qquad i, j = 1, 2, 3$$

We do the Clebsch-Gordan decomposition as follows:

$$u^i v^j = rac{1}{2} (u^i v^j + u^j v^i) + rac{1}{2} (u^i v^j - u^j v^i)$$

- The number of the independent components of symmetric combination $\frac{1}{2}(u^iv^j+u^iv^i)$ is $\frac{1}{2}\cdot 3\cdot 4=6$. This tensor belongs to the irreducible representation $\mathbf{6}=\text{Rep.}(2,0)$.
- The second term (anti-symmetric combination) can be recast as

$$rac{1}{2}(u^iv^j-u^jv^i)=rac{1}{2}(\delta^i_k\delta^j_l-\delta^i_l\delta^j_k)u^kv^l=rac{1}{2}\epsilon^{ijm}\epsilon_{klm}u^kv^l$$

• In view of product $u^i v^j$, ϵ^{ijm} is an invariant tensor. The remaining factor $\epsilon_{klm} u^k v^l$ forms a tensor in $\bar{\bf 3} = \text{Rep.}(0,1)$ as it has only one *bare* lower index.

We conclude that

$$3 \times 3 = 6 + \overline{3}$$

Alternatively but equivalently,

$$(1,0)\otimes(1,0)=(2,0)\oplus(0,1)$$

Consider the tensor product of $3 \times \bar{3}$.

Because the tensors of **3** and $\bar{\mathbf{3}}$ are $u=(u^i)$ and $v=(v_j)$, respectively, the tensor in $\mathbf{3} \times \bar{\mathbf{3}}$ should be

$$(\boldsymbol{u}\otimes \boldsymbol{v})^i_j=\boldsymbol{u}^i\boldsymbol{v}_j$$

The Clebsch-Gordan decomposition is,

$$u^iv_j=\left[u^iv_j-rac{1}{3}\delta^i_ju^kv_k
ight]+rac{1}{3}rac{\delta^i_j}{j}u^kv_k$$

As a result,

$$(1,0)\otimes(0,1)=(1,1)\oplus(0,0)$$

or

$$\mathbf{3} imes \mathbf{\bar{3}} = \mathbf{8} + \mathbf{1}$$

Consider the tensor product of 3×8 .

The tensors of **3** and **8** are $u = (u^i)$ and $v = (v^j_k)$, respectively¹. Therefore, the tensor of **3** × **8** has the form

$$(u \otimes v)_k^{ij} = u^i v^j_{k}$$

¹The tensor of **8** must be traceless, i.e., $v^{j}_{ij} = 0$.

The Clebsch-Gordan decomposition is carried out in the way,

$$u^{i}v^{j}_{k} = \frac{1}{2}(u^{i}v^{j}_{k} + u^{j}v^{i}_{k}) + \frac{1}{2}(u^{i}v^{j}_{k} - u^{j}v^{i}_{k})$$

$$= \frac{1}{2}(u^{i}v^{j}_{k} + u^{j}v^{i}_{k}) + \frac{1}{2}\epsilon^{ijm}\epsilon_{mnl}u^{n}v^{l}_{k}$$

• The first term

term
$$1 = \frac{1}{2} (u^i v^j_k + u^j v^i_k)$$

has been symmetrized about the upper indices i and j. To make it traceless further, we recast it as

$$\begin{array}{ll} \operatorname{term} \ 1 &= \frac{1}{2} \left[\left(u^i v^j_{k} + u^j v^i_{k} \right) - a \delta^i_k u^l v^j_{l} - b \delta^j_k u^l v^i_{l} \right] \\ &\quad + \frac{1}{2} \left(a \delta^i_k u^l v^j_{l} + b \delta^j_k u^l v^i_{l} \right) \end{array}$$

The first row is expected to be in Rep.(2, 1) but the second row in Rep.(1, 0).

The traceless condition in Rep.(2, 1) requires,

$$u^{l}v^{j}_{l}(1-3a-b)=0, \quad u^{l}v^{i}_{l}(1-a-3b)=0.$$

Hence a = b = 1/4. We finally recast the *first* term as:

$$\begin{array}{ll} \operatorname{term} 1 &= \frac{1}{2} \left[\left(\boldsymbol{u}^{i} \boldsymbol{v}^{j}_{k} + \boldsymbol{u}^{j} \boldsymbol{v}^{i}_{k} \right) - \frac{1}{4} \left(\delta^{i}_{k} \boldsymbol{u}^{l} \boldsymbol{v}^{j}_{l} + \delta^{j}_{k} \boldsymbol{u}^{l} \boldsymbol{v}^{i}_{l} \right) \right] \\ &+ \frac{1}{8} \left(\delta^{i}_{k} \boldsymbol{u}^{l} \boldsymbol{v}^{j}_{l} + \delta^{j}_{k} \boldsymbol{u}^{l} \boldsymbol{v}^{i}_{l} \right) \end{array}$$

In the previous formula for decomposition of tensor product $u^i v^j_{\ k}$, the second term reads,

term
$$2 = \frac{1}{2} \epsilon^{ijm} \epsilon_{mnl} u^n v^l_{k}$$

After discarding the invariant tensor e^{ijm} , it has only two lower indices m and k, effectively.

Irreducibility requires the symmetrization about these two indices.
 Therefore,

$$\begin{split} \operatorname{term} 2 &= \frac{1}{2} \epsilon^{ijm} \bigg[\frac{1}{2} (\epsilon_{mnl} u^n v^l_{k} + \epsilon_{knl} u^n v^l_{m}) \\ &+ \frac{1}{2} (\epsilon_{mnl} u^n v^l_{k} - \epsilon_{knl} u^n v^l_{m}) \bigg] \\ &= \frac{1}{4} \epsilon^{ijm} \bigg(\epsilon_{mnl} u^n v^l_{k} + \epsilon_{knl} u^n v^l_{m} \bigg) \\ &+ \frac{1}{4} \epsilon^{ijm} \epsilon_{pnl} u^n v^l_{q} (\delta^p_m \delta^q_k - \delta^q_m \delta^p_k) \\ &= \frac{1}{4} \epsilon^{ijm} \bigg(\epsilon_{mnl} u^n v^l_{k} + \epsilon_{knl} u^n v^l_{m} \bigg) \\ &+ \frac{1}{4} \epsilon^{ijm} \epsilon_{pnl} u^n v^l_{q} \epsilon_{mkr} \epsilon^{pqr} \end{split}$$

On RHS, the first row stands for a symmetric tensor in Rep.(0, 2). Let us now focus on the second row.

$$\begin{split} &\frac{1}{4}\epsilon^{ijm}\epsilon_{pnl}u^nv^l_{q}\epsilon_{mkr}\epsilon^{pqr} = \frac{1}{4}u^nv^l_{q}\left(\delta^i_k\delta^j_r - \delta^j_k\delta^i_r\right)\left(\delta^q_n\delta^r_l - \delta^r_n\delta^q_l\right) \\ &= \frac{1}{4}u^nv^l_{q}\left[\delta^i_k(\delta^j_l\delta^q_n - \delta^j_n\delta^q_l) - \delta^j_k(\delta^i_l\delta^q_n - \delta^i_n\delta^q_l)\right] \\ &= \frac{1}{4}\left[\delta^i_k(u^lv^j_{l} - u^jv^l_{l}) - \delta^j_k(u^lv^i_{l} - u^iv^l_{l})\right] \\ &= \frac{1}{4}\left(\delta^i_ku^lv^j_{l} - \delta^j_ku^lv^i_{l}\right) \end{split}$$

which stands for the tensor of Rep.(1, 0).

In summary,

$$egin{aligned} u^{i}v^{j}_{k} &= rac{1}{2}\left[\left(u^{i}v^{j}_{k} + u^{j}v^{i}_{k}\right) - rac{1}{4}(\delta^{i}_{k}u^{l}v^{j}_{l} + \delta^{j}_{k}u^{l}v^{i}_{l})
ight] \\ &+ rac{1}{4}\epsilon^{ijm}\left(\epsilon_{mnl}u^{n}v^{l}_{k} + \epsilon_{knl}u^{n}v^{l}_{m}
ight) \\ &+ rac{1}{8}\left(3\delta^{i}_{k}u^{l}v^{j}_{l} - \delta^{j}_{k}u^{l}v^{i}_{l}
ight) \end{aligned}$$

It implies:

$$(1,0)\otimes(1,1)=(2,1)\oplus(0,2)\oplus(1,0)$$

Equivalently,

$$3\times8=15+\overline{6}+3$$

Consider the CG-decomposition of 6×3 .

The tensors of **6** and **3** are $u=(u^{ij})$ and $v=(v^k)$, respectively. Consequently, the tensor of **6** \times **3** has the form

$$ig(u \otimes vig)^{ijk} = u^{ij}v^k$$

where u is a symmetric tensor of SU(3) in Rep.(2, 0),

$$u^{ij} = u^{ji}$$

By symmetrizing all of the upper indices,

$$egin{aligned} u^{ij}v^k &= rac{1}{3}\left(u^{ij}v^k + u^{jk}v^i + u^{ki}v^j
ight) \ &+ rac{1}{3}\left(2u^{ij}v^k - u^{jk}v^i - u^{ki}v^j
ight) \end{aligned}$$

The first term on RHS

$$rac{1}{3}\left(u^{ij}v^k+u^{jk}v^i+u^{ki}v^j
ight)$$

is symmetric for exchanging any two indices. It describes a tensor in irreducible Rep. (3, 0) of SU(3).

The second term is recast as:

$$egin{aligned} &rac{1}{3}(2u^{ij}v^k-u^{jk}v^i-u^{ki}v^j) \ &=rac{1}{3}\Big(u^{ij}v^k-u^{jk}v^i\Big)+rac{1}{3}\Big(u^{ij}v^k-u^{ki}v^j\Big) \end{aligned}$$

$$=\frac{1}{3}\bigg(\delta_{m}^{i}\delta_{n}^{k}-\delta_{n}^{i}\delta_{m}^{k}\bigg)u^{mj}v^{n}+\frac{1}{3}\bigg(\delta_{m}^{j}\delta_{n}^{k}-\delta_{n}^{j}\delta_{m}^{k}\bigg)u^{im}v^{n}\\ =\frac{1}{3}\bigg[\epsilon^{ikl}\underbrace{\epsilon_{lmn}u^{mj}v^{n}}_{\text{traceless }\epsilon_{lmn}u^{ml}=0}+\epsilon^{jkl}\underbrace{\epsilon_{lmn}u^{im}v^{n}}_{\text{traceless }\epsilon_{lmn}u^{lm}=0}\bigg]$$

Apart from the invariant tensors e^{ikl} and e^{jkl} , the term is involved in some traceless tensors

$$\epsilon_{lmn}u^{mj}v^n, \quad \epsilon_{lmn}u^{im}v^n$$

Hence, it describes a tensor in the SU(3) irreducible Rep.(1, 1).

In summary,

$$egin{aligned} u^{ij}v^k &= rac{1}{3}\left(u^{ij}v^k + u^{jk}v^i + u^{ki}v^j
ight) \ &+ rac{1}{3}\left(\epsilon^{ikl}\epsilon_{lmn}u^{mj}v^n + \epsilon^{jkl}\epsilon_{lmn}u^{im}v^n
ight) \end{aligned}$$

It implies that,

$$(2,0)\otimes (1,0)=(3,0)\oplus (1,1)$$

Equivalently,

$$6\times3=10+8$$

Corollary:

$$3 \times 3 \times 3 = (6 + \overline{3}) \times 3 = 10 + 8 + 8 + 1$$

Equivalently,

$$(1,0) \otimes (1,0) \otimes (1,0) = (3,0) \oplus (1,1) \oplus (1,1) \oplus (0,0)$$

Homework:

Problems:

- Decompose the product of tensor components $u^i v^{jk}$, where $v^{jk} = v^{kj}$ transforms like a tensor in Rep.6 of SU(3).
- Find the matrix elements $\langle u|X_a|v\rangle$, where X_a stand for the SU(3) generators and $|u\rangle$ and $|v\rangle$ are states in the adjoint representation of SU(3) with tensor components u^i_j and v^i_j . Write the result in terms of the tensor components and the Gell-Mann Matrices.
- **1** In Rep. **6** of SU(3), for each weight find the corresponding tensor component v^{ij} .

Young tableaux in SU(3):

Young tableaux is very convenient in dealing with the Clebsch-Gordan decomposition of the Lie group representations. Here we consider its application in SU(3).

A crucial observation:

The representation $\bar{\mathbf{3}}$ of SU(3) is the antisymmetric product of two 3's,

$$w_i = \epsilon_{ijk} u^j v^k$$

An irreducible SU(3) tensor $\mathscr A$ in Rep.(n,m) has the component structure

$$\mathscr{A}_{j_1\,j_2\cdots j_m}^{i_1\,i_2\cdots i_n}$$

- A is symmetric in upper and lower indices, separately.
- A is traceless for one upper and one lower indices.

We can raise all the lower tensor indices by using the invariant tensor ϵ^{ijk} of SU(3),

$$\epsilon^{j_1k_1l_1}\epsilon^{j_2k_2l_2}\cdots\epsilon^{j_mk_ml_m}\mathscr{A}^{i_1i_2\cdots i_n}_{j_1j_2\cdots j_m}=\mathscr{B}^{k_1l_1k_2l_2\cdots k_ml_mi_1i_2\cdots i_n}$$

• $\mathscr{B}^{k_1l_1k_2l_2\cdots k_ml_mi_1i_2\cdots i_n}$ is antisymmetric in each pair $\{k_a,l_a\}$ for interchange

$$k_a \iff l_a, \quad (a = 1, 2, \cdots, m)$$

and symmetric for exchange of pairs

$$\left\{k_a, l_a\right\} \longleftrightarrow \left\{k_b, l_b\right\}, \quad (a, b = 1, 2, \cdots, m)$$

• Traceless condition of A becomes:

$$\epsilon_{i_1k_1l_1} \mathcal{B}^{k_1l_1k_2l_2\cdots k_ml_mi_1i_2\cdots i_n}$$

$$= \epsilon_{i_2k_2l_2} \mathcal{B}^{k_1l_1k_2l_2\cdots k_ml_mi_1i_2\cdots i_n}$$

$$= \cdots = 0$$

The traceless condition of tensor \mathcal{B} could be shown as follows:

$$\begin{split} \epsilon_{i_1k_1l_1} \mathcal{B}^{k_1l_1k_2l_2\cdots k_ml_mi_1i_2\cdots i_n} \\ &= \epsilon_{i_1k_1l_1} \epsilon^{j_1k_1l_1} \ \epsilon^{j_2k_2l_2} \cdots \epsilon^{j_mk_ml_m} \ \mathcal{A}^{i_1i_2\cdots i_n}_{j_1j_2\cdots j_m} \\ &= 2\delta^{j_1}_{i_1} \ \epsilon^{j_2k_2l_2} \cdots \epsilon^{j_mk_ml_m} \ \mathcal{A}^{i_1i_2\cdots i_n}_{j_1j_2\cdots j_m} \\ &= 2\epsilon^{j_2k_2l_2} \cdots \epsilon^{j_mk_ml_m} \mathcal{A}^{i_1i_2\cdots i_n}_{i_1j_2\cdots j_m} \\ &= 0 \end{split}$$

With such a SU(3) tensor $\mathcal{B}^{k_1l_1k_2l_2\cdots k_ml_mi_1i_2\cdots i_n}$ in Rep.(n, m), we associate a Young tableau

k_1	k_2	 k_m	i_1	i_2	 i_n
l_1	l_2	 l_m			

The Young tableau

k_1	k_2	• • •	k_m	i_1	i_2	 i_n
l_1	l_2		l_m			

describes a tensor

$$\mathscr{B} = \left(\mathscr{B}^{k_1 l_1 k_2 l_2 \cdots k_m l_m i_1 i_2 \cdots i_n} \right)$$

with the following properties:

- It has (n + 2m) upper indices.
- It is antisymmetric for index interchange in every pair $\{k_a, l_a\}$, where $a=1,2,\cdots,m$.
- It is symmetric under arbitrary permutations of the indices i_b and k_a , and separately symmetric under arbitrary permutations of l_a , where $a=1,2,\cdots,m$ and $b=1,2,\cdots,n$.

Question: Why?

Because $\mathscr{A}=E_{-}v_{H}^{2}$, and the SU(3) transformation preserves the permutational symmetries in tensor indices, we are necessary to analyze the claimed symmetries for tensor \mathscr{B}_{H} ,

The **independent** components of \mathscr{B}_H read,

$$\mathscr{B}_{H}^{1313\cdots 1311\cdots 1}=\mathcal{N}\;\epsilon^{213}\epsilon^{213}\cdots\epsilon^{213}=\pm\mathcal{N}$$

corresponding to

$$k_1 = k_2 = \cdots = k_m = i_1 = i_2 = \cdots = i_n = 1$$

 $l_1 = l_2 = \cdots = l_m = 3$

 $^{^{2}}E_{-}$ stands for some SU(3) generator.

Therefore,

- $\ \mathfrak{B}_H$ is symmetric for interchanging the indices in the same rows of the corresponding Young tableau.
- **3** \mathcal{B}_H is antisymmetric for exchanging the indices in the same columns of the corresponding Young tableau.
- **9** Young tableaux can be directly used to represent the irreducible representations of SU(3).

Example 1:

Young tableau

i

can be used to stand for *either* a SU(3) tensor u^i of irreducible representation 3 or 3 itself³.

³For SU(3), **3** is Rep.(1, 0). Similarly, **6** = Rep.(2, 0).

Example 2:

Young tableau

$$\lceil i \mid j \rceil$$

describes *either* a symmetric SU(3) tensor

$$u^{ij} = u^{ji}$$

in Rep.(2,0) = 6 or 6 itself.

Example 3:

Young tableau

describes *either* the antisymmetric SU(3) tensor

$$u^{ij} = -u^{ji} = \epsilon^{ijk} v_k$$

in Rep. $(0, 1) = \mathbf{\bar{3}}$ or $\mathbf{\bar{3}}$ itself.

Example 4:

Young tableau

$$egin{bmatrix} i & j \ k \end{bmatrix}$$

describes either a SU(3) tensor

$$u^{ijk}=u^{jik}=-u^{kji}=\epsilon^{ikl}v_l^j$$

in Rep.(1, 1) = 8 *or* 8 itself.

Example 5:

Young tableau

$$rac{i}{j}$$

is related to the invariant SU(3) tensor ϵ^{ijk} . It represents the trivial Rep.(0,0) = 1.

Example 6:

Young tableau

$$\begin{array}{c} i\\ j\\ k\\ l \end{array}$$

is not allowed in SU(3). The antisymmetric SU(3) tensor

$$u^{ijkl}, \quad \left\{i,j,k,l=1,\ 2,\ 3
ight\}$$

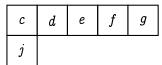
does not exist in any of its representations.

Warning:

• In Young tableaux of SU(3), any columns with 3 boxes contribute a factor proportional to ϵ^{123} and should be ignored. e.g,

a	b	С	d	е	f	g
h	i	j				
k	l					

should be reduced to



● The *SU*(3) tensor which relates to a Young tableau with more than 3 boxes in any column vanishes!

Calculating D(n, m) by using Young tableaux :

The irreducible Rep.(n, m) of SU(3) has dimension

$$D(n,m) = \frac{1}{2}(n+1)(m+1)(n+m+2)$$

Question:

Can D(n, m) be deduced from the corresponding Young tableau?

The answer is absolutely yes. We draw the corresponding Young tableau

k_1	k_2	 k_m	i_1	i_2	 i_n
l_1	l_2	 l_m			

and represent D(n, m) as a fraction:

$$D(n,m) = \frac{a(n,m)}{b(n,m)}$$

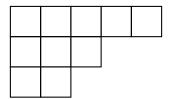
We now introduce the rules for calculating a(n, m) and b(n, m). To this end, we need define two concepts:

- Content m_{ij}
- lacksquare Hook number h_{ij}

for related Young tableau. For later convenience, consider SU(N) for a generic $N \ge 3$. The content m_{ij} for a box at the j-th column of the i-th row is,

$$m_{ij} = j - i$$

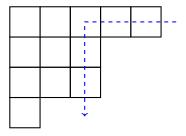
Example: For Young tableau



we have $m_{23} = 1$, $m_{14} = 3$ but $m_{32} = -1$.

To define hook number h_{ij} , we have to introduce the so-called *hook* for each box in Young tableau.

Here is the hook for box at the third column of the first row,



The hook number h_{ij} is the total number of boxes along the hook of the box at the j-th column of the i-th row in the Young tableau.

In given example, we have:

$$h_{13} = 5$$
, $h_{22} = 3$, $h_{21} = 5$.

Dimensions of SU(N) irreducible representations :

$d_{\lceil \lambda ceil}ig(SU(N)ig)$:

The dimension of the irreducible representation of SU(N) described by Young tableau $[\lambda]$ is expressed by a quotient,

$$d_{[\lambda]}ig(SU(N)ig) = \prod_{ij} rac{N + m_{ij}}{h_{ij}}$$

• For SU(3), this formula reduces to:

$$D(n,m) = \frac{a(n,m)}{b(n,m)}$$

where

$$a(n,m) = \prod_{ij} (3+m_{ij}), \qquad b(n,m) = \prod_{ij} h_{ij}.$$

By define the so-called Numerator Young tableau:

3	4	 m+2	m + 3	m+4	• • •	m+n+2
2	3	 m+1				

we can easily get:

$$a(n,m) = \prod_{i=3}^{n+m+2} \prod_{j=2}^{m+1} ij = rac{1}{2}(n+m+2)!(m+1)!$$

We introduce the denominator Young tableau as follows:

where $h_{11} = n + m + 1$, $h_{12} = n + m$, $h_{1m} = n + 2$, $h_{21} = m$, $h_{22} = m - 1$ and $h_{2m} = 1$. Therefore,

$$b(n,m)=\frac{(n+m+1)!m!}{(n+1)}$$

Consequently,

$$D(n,m) = rac{a(n,m)}{b(n,m)}$$

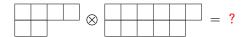
$$= rac{(n+m+2)!(m+1)!}{2} \cdot rac{(n+1)}{(n+m+1)!m!}$$

$$= rac{1}{2}(n+1)(m+1)(n+m+2)$$

This is what we have expected.

Clebsch-Gordan decomposition:

Let us now to discuss the Young tableau rules for decomposing the tensor product of two SU(3) irreducible representations. e.g.,



CG-decomposition rules:

 Mark each box of the second empty tableau with the corresponding number of its row. e.g.,

 Continue by adding all the boxes of the second tableau to the first one. These boxes may only be added to the right or the bottom of the first tableau.

- Each resulting tableau has to be an allowed configuration, i.e., no row is longer than the row above.
- In the case of SU(N), no column must contain more than N boxes.
- Within a row, the numbers in the boxes originating from the second tableau must not decrease from left to right.
- Within a column, the numbers in the boxes originating from the second tableau must increase from top to bottom.
- A box of the *i*-th row of the second Young tableau must not be attached to the first (i-1) rows of the first Young tableau.
- If two tableaux of the same shape are produced, they are counted as different only if the labels are different.

Examples:

Focus on the tensor products of some irreducible representations of SU(3).

The first example is,

By the studied rules,

Namely,

$$3 \times 3 = 6 + \overline{3}$$

Our second example is about the CG-decomposition of



By the studied rules,

i.e.,

$$\mathbf{\bar{3}} \times \mathbf{3} = \mathbf{8} + \mathbf{1}$$

Another example is to ask

$$\square \otimes \square = ?$$

By the studied rules, we have:

i.e.,

$$3 \times \overline{3} = 8 + 1$$

As the 4-th example in SU(3), we consider

By the studied rules, we see that

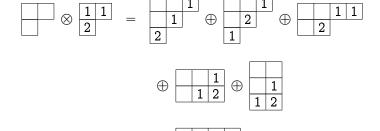
i.e.,

$$\mathbf{\bar{3}} \times \mathbf{\bar{3}} = \mathbf{3} + \mathbf{\bar{6}}$$

Finally, we consider the CG-decomposition of tensor product of



By the studied rules, we have:



i.e.,

$$8 \times 8 = 8 + 8 + 27 + \overline{10} + 1 + 10$$

 \oplus

Homework:

Problems:

- Find $(2, 1) \otimes (2, 1)$ for SU(3). Can you determine which representations appear anti-symmetrically in the tensor product, and which appear symmetrically?
- **2** $Find <math> 10 \times 8$.
- For any Lie group, the tensor product of the adjoint representation with any arbitrary nontrivial representation D must contain D (think about the action of the generators on the states of D and see if you can figure out why this is so.). In particular, you know that for any nontrivial SU(3) representation D. How can you see this using Young tableaux?