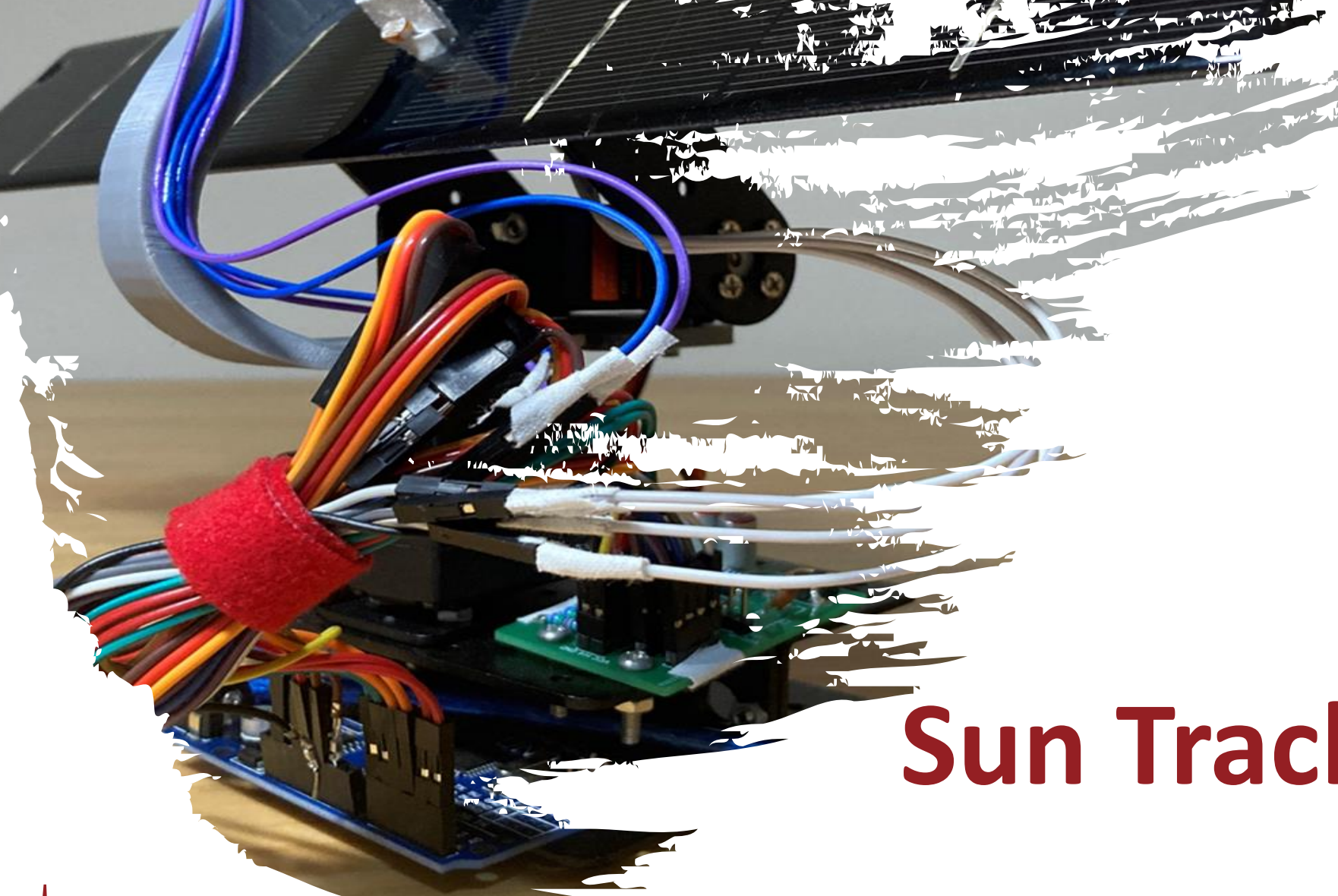




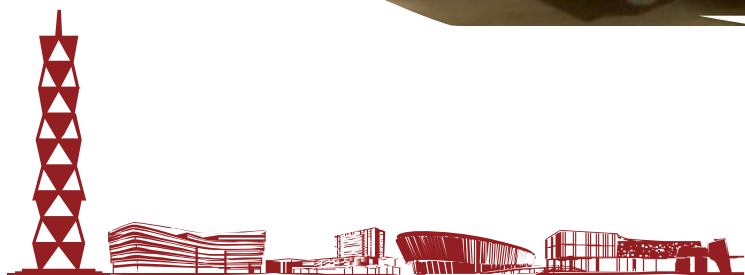
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ShanghaiTech University



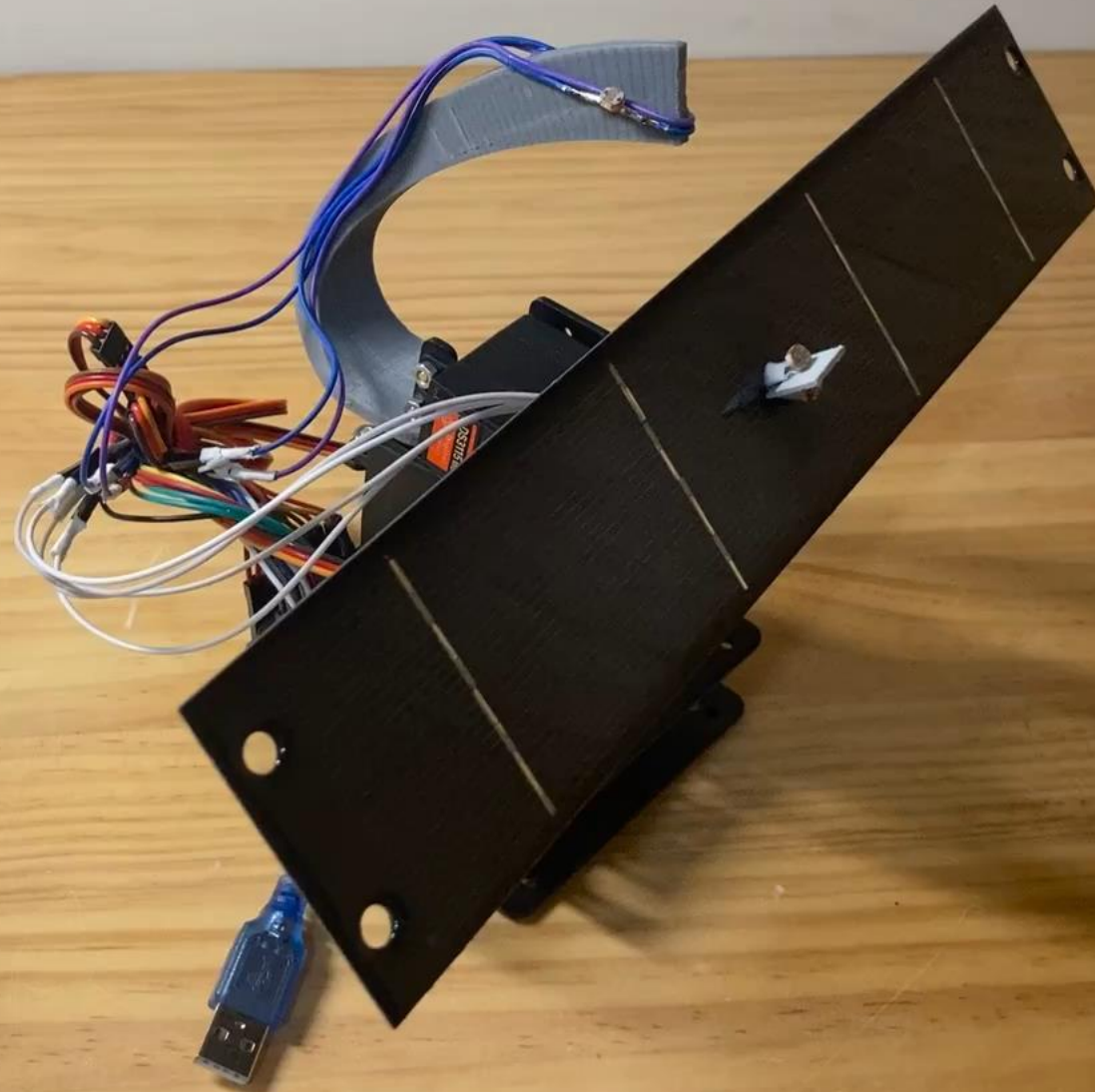
# Sun Tracking System

朱宇轩

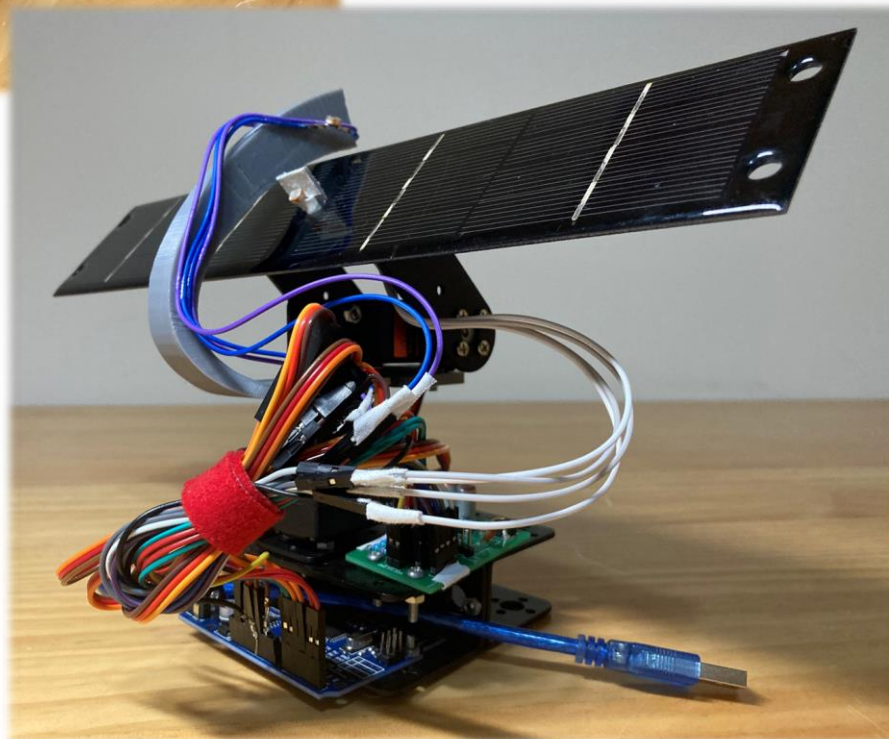
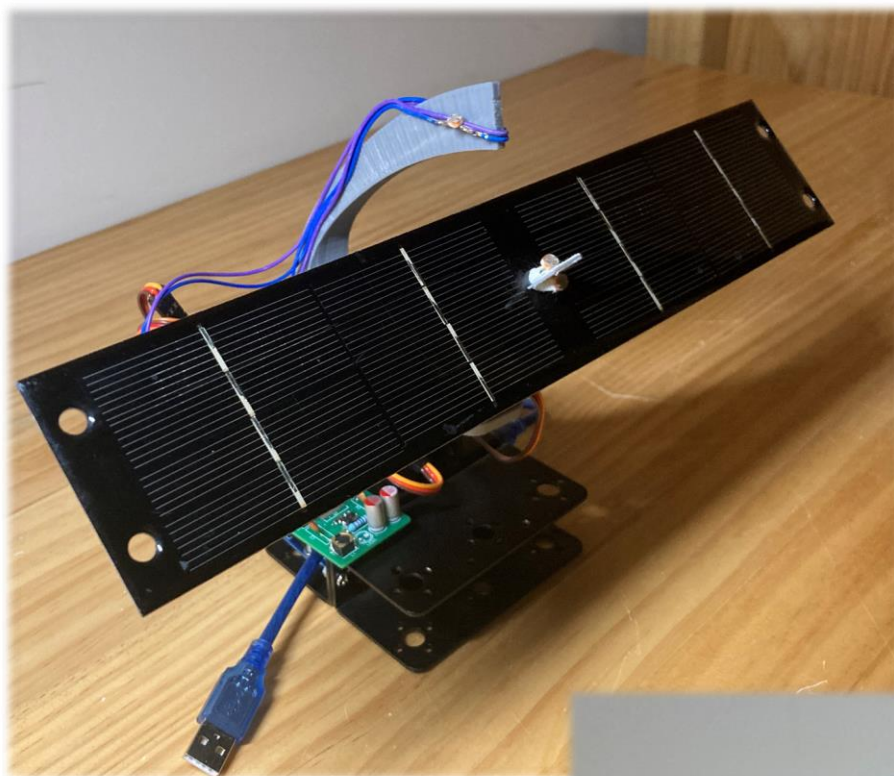
2021.10.8

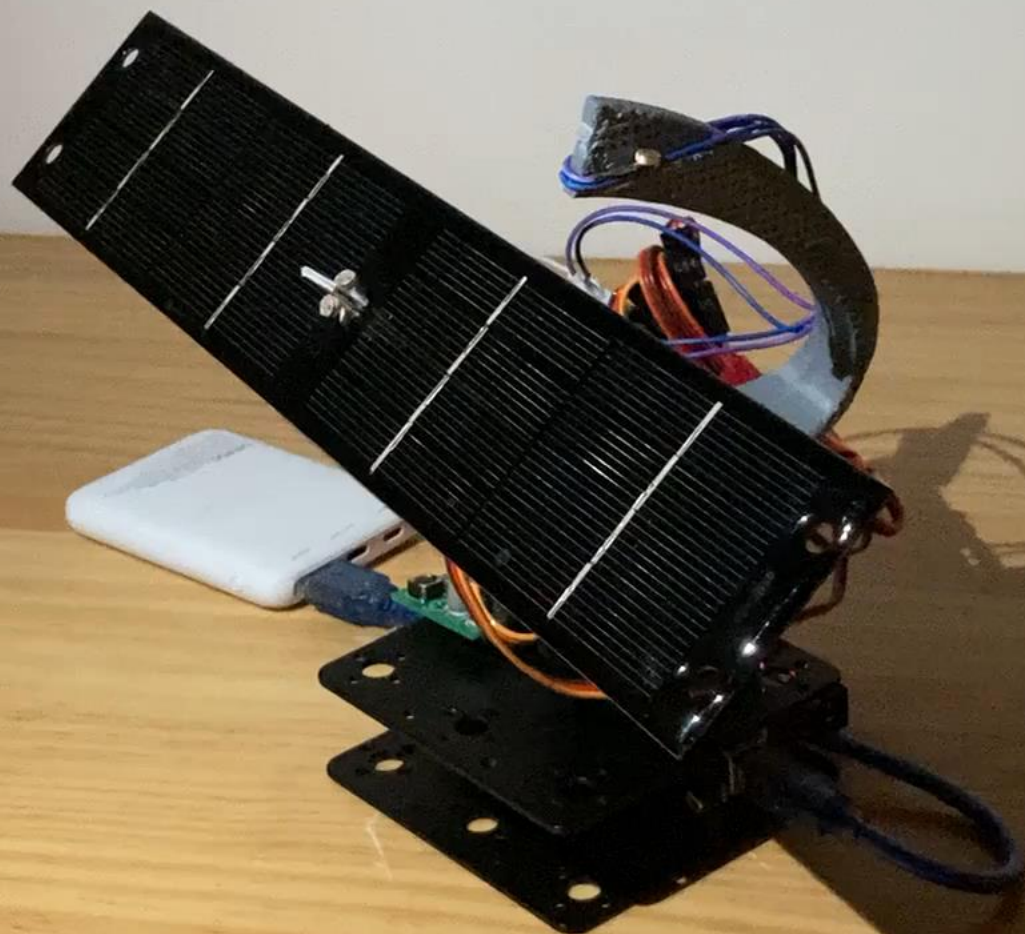


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日在哪里

日的闪现

# 逐日

怎么追日

没日咋办

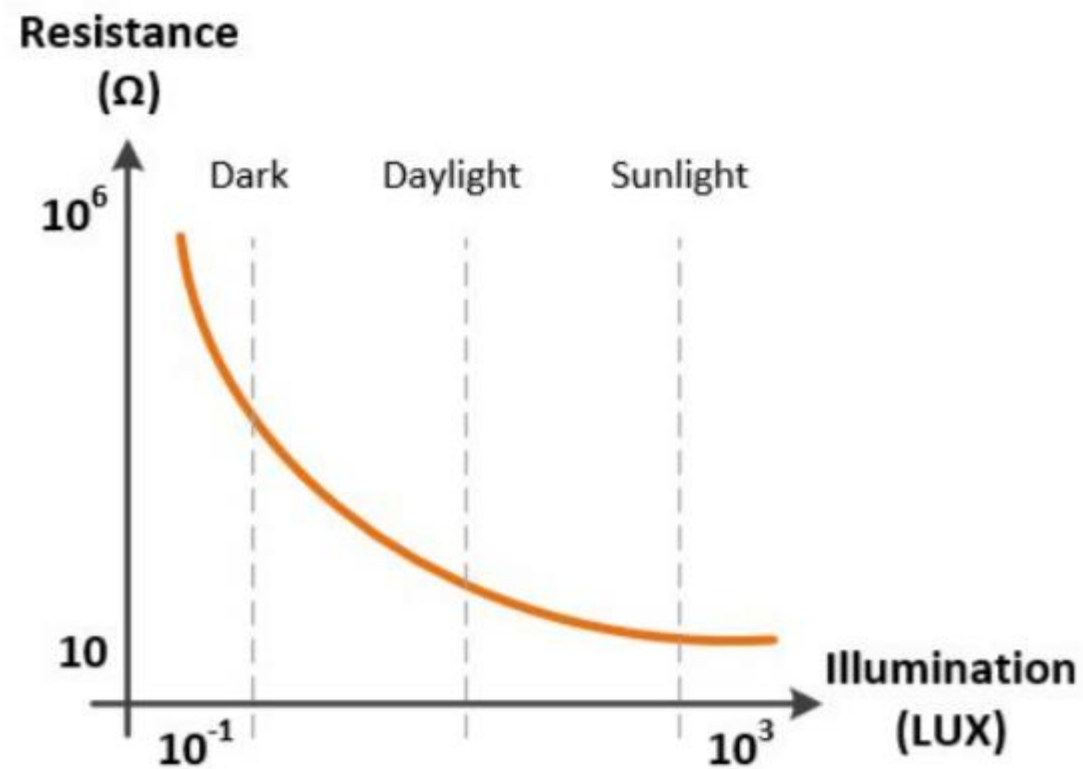
日用没用





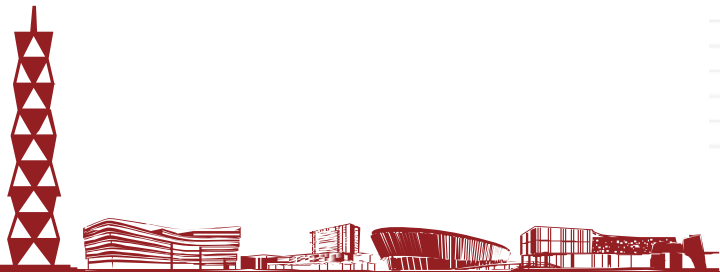
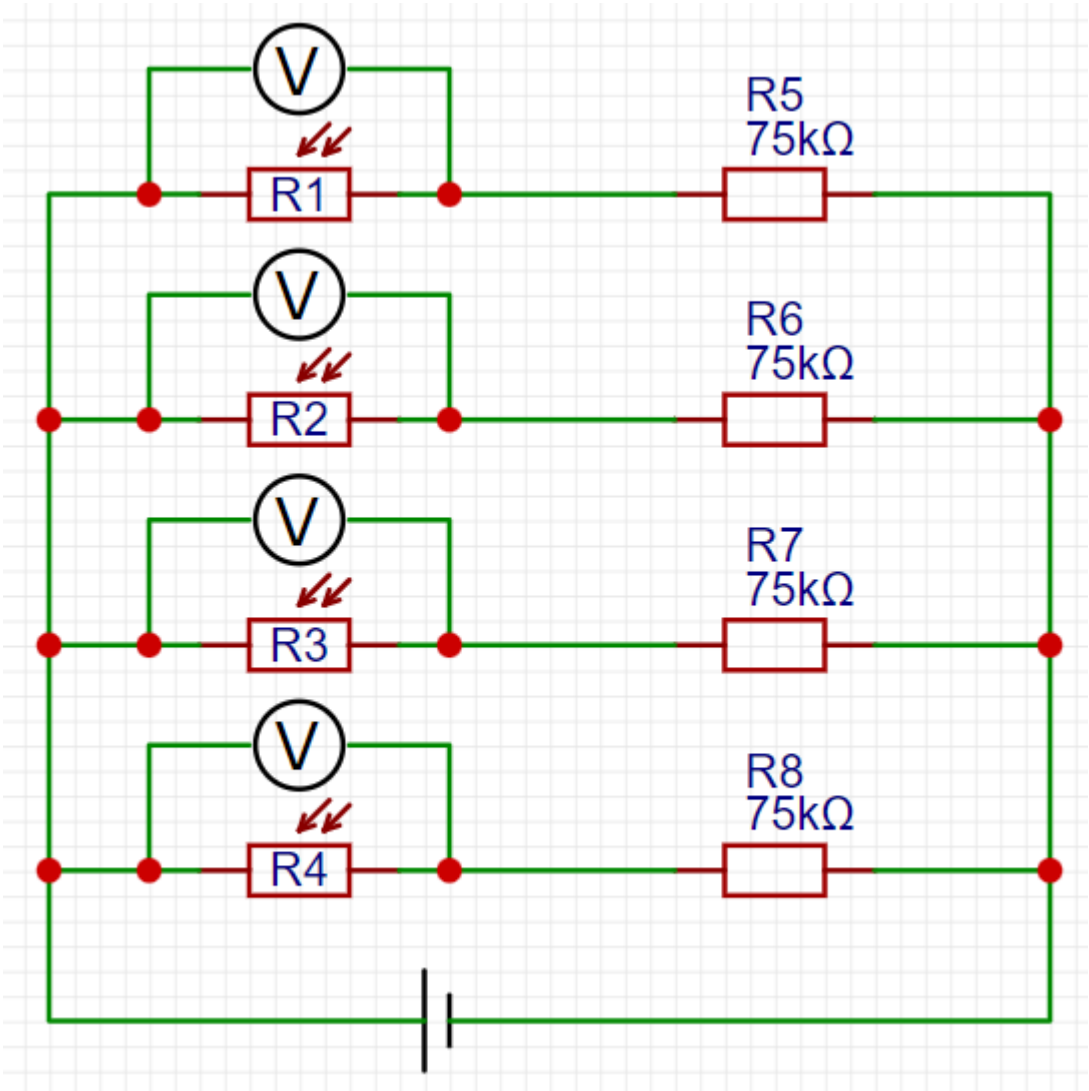


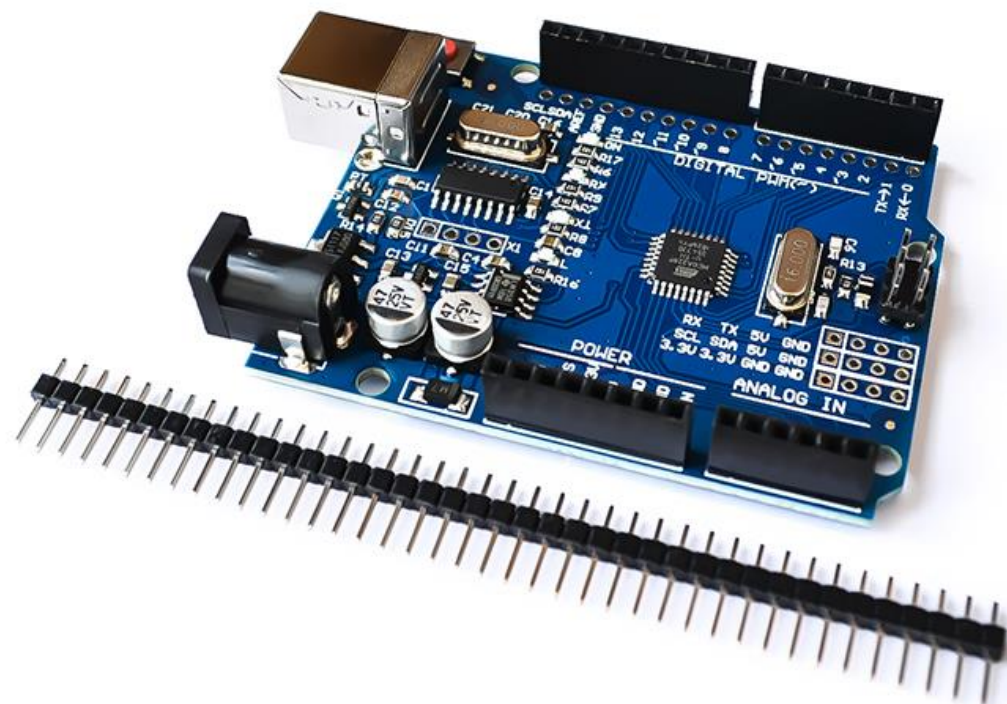
光敏电阻





# 日在哪里





读取

写入

供电

运算

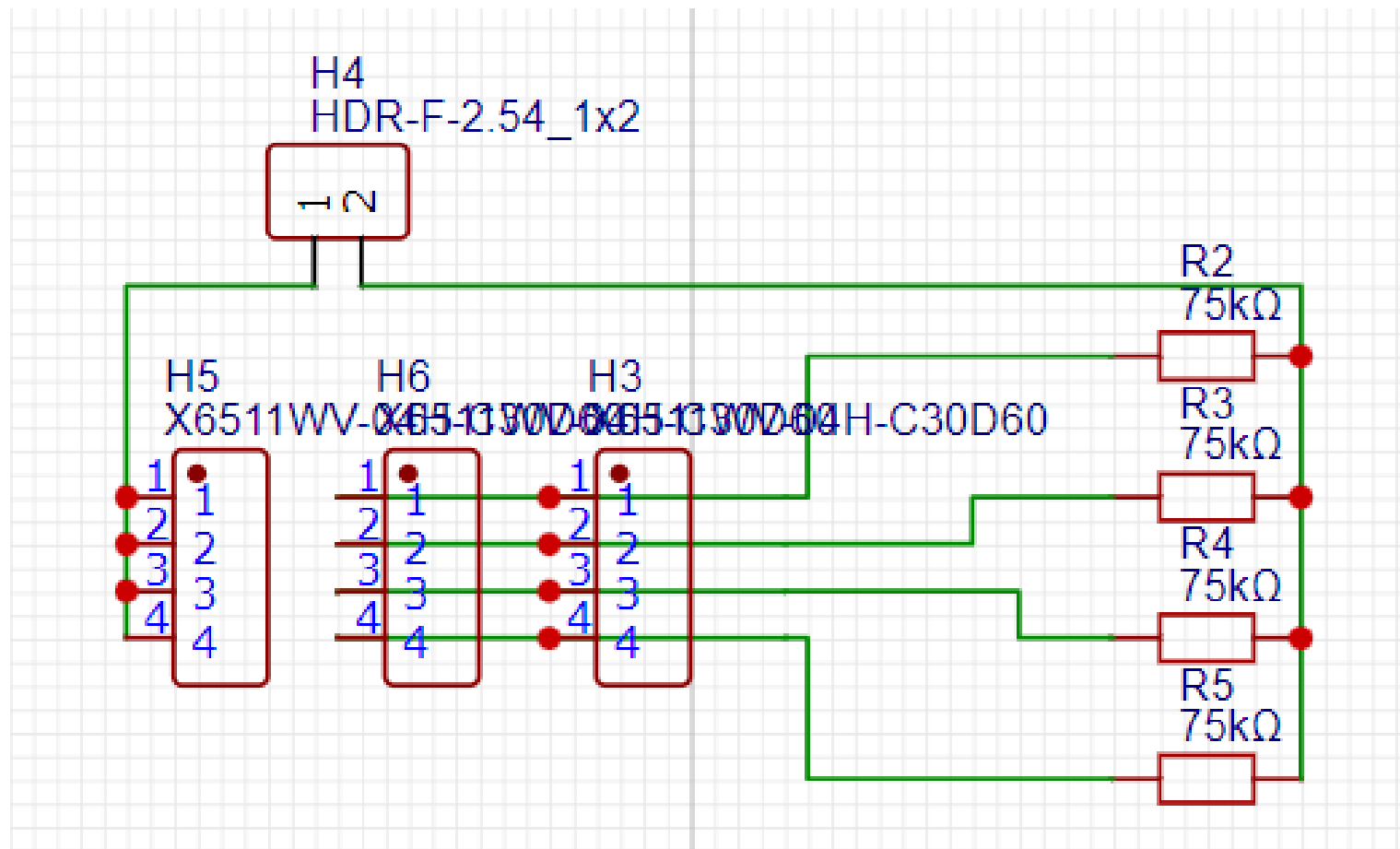
比较

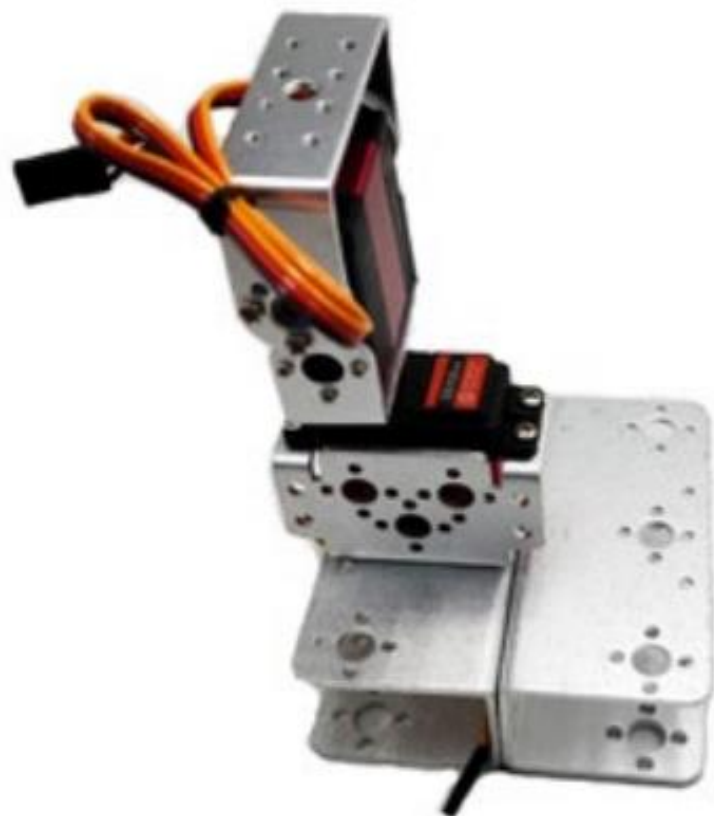
Arduino





# 日在哪里





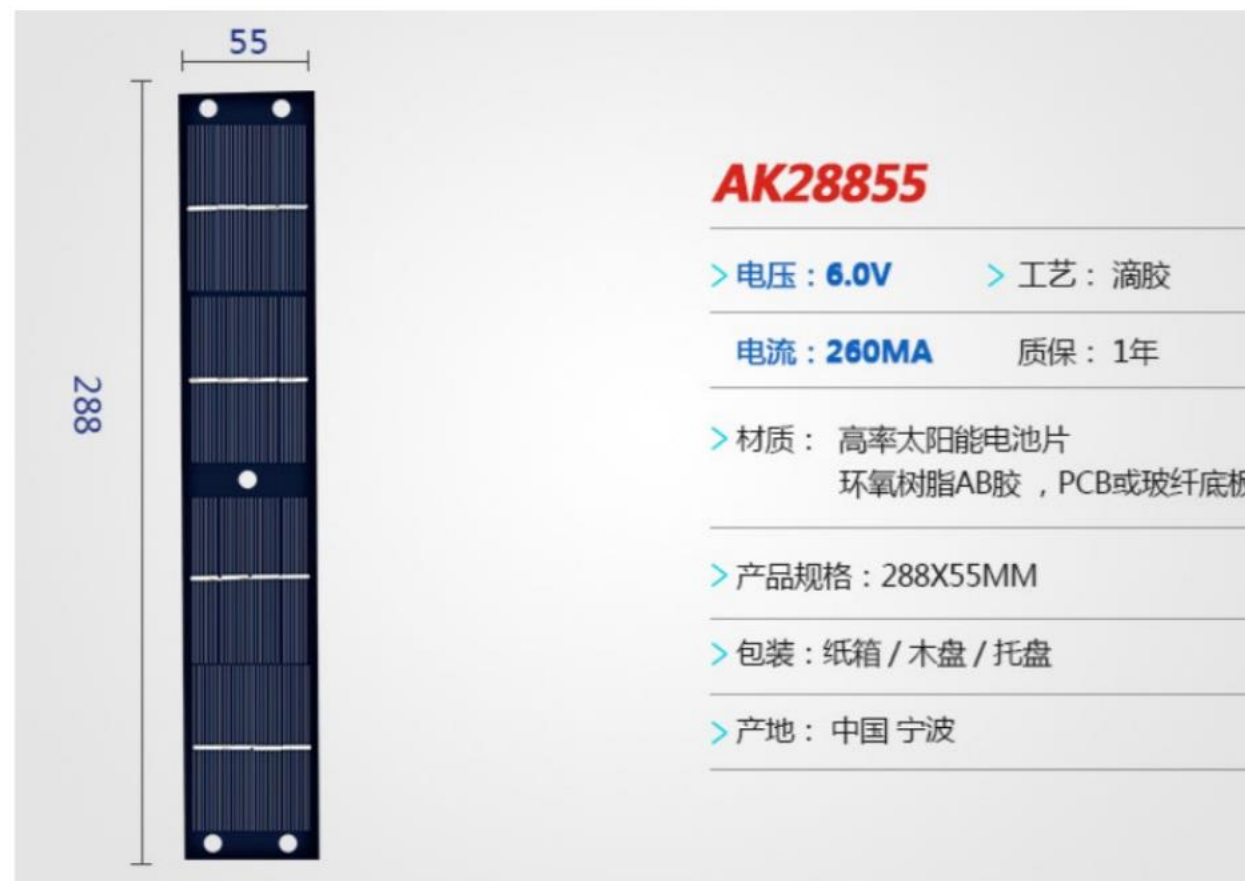
## 伺服电机



```
if (analogRead(A5) > analogRead(A4) + 100) {  
    servo_A3.write((servo_A3.read() + rota));  
    delay(5);  
  
} else if (analogRead(A4) > analogRead(A5) + 100) {  
    servo_A3.write((servo_A3.read() - rota));  
    delay(5);  
}  
  
if (analogRead(A1) > analogRead(A0) + 50) {  
    if (rota == 1 && servo_A2.read() < 90 || rota == -1 && servo_A2.read() >= 90) {  
        servo_A2.write((servo_A2.read() + 1));  
        delay(5);  
    }  
} else if (analogRead(A0) > analogRead(A1) + 50) {  
    if (rota == 1 && servo_A2.read() <= 90 || rota == -1 && servo_A2.read() > 90) {  
        servo_A2.write((servo_A2.read() - 1));  
        delay(5);  
    }  
}
```

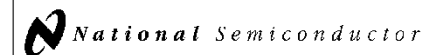








LM2596S



PRELIMINARY  
February 1996

## LM2596 SIMPLE SWITCHER® Power Converter 150 kHz 3A Step-Down Voltage Regulator

### General Description

The LM2596 series of regulators are monolithic integrated circuits that provide all the active functions for a step-down (buck) switching regulator, capable of driving a 3A load with excellent line and load regulation. These devices are available in fixed output voltages of 3.3V, 5V, 12V, and an adjustable output version.

Requiring a minimum number of external components, these regulators are simple to use and include internal frequency compensation<sup>†</sup>, and a fixed-frequency oscillator.

The LM2596 series operates at a switching frequency of 150 kHz thus allowing smaller sized filter components than what would be needed with lower frequency switching regulators. Available in a standard 5-lead TO-220 package with several different lead bend options, and a 5-lead TO-263 surface mount package.

A standard series of inductors are available from several different manufacturers optimized for use with the LM2596 series. This feature greatly simplifies the design of switch-mode power supplies.

Other features include a guaranteed  $\pm 4\%$  tolerance on output voltage under specified input voltage and output load conditions, and  $\pm 15\%$  on the oscillator frequency. External shutdown is included, featuring typically 80  $\mu$ A standby current. Self protection features include a two stage frequency reducing current limit for the output switch and an over

temperature shutdown for complete protection under fault conditions.

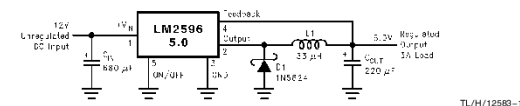
### Features

- 3.3V, 5V, 12V, and adjustable output versions
- Adjustable version output voltage range, 1.2V to 37V  $\pm 4\%$  max over line and load conditions
- Available in TO-220 and TO-263 packages
- Guaranteed 3A output load current
- Input voltage range up to 40V
- Requires only 4 external components
- Excellent line and load regulation specifications
- 150 kHz fixed frequency internal oscillator
- TTL shutdown capability
- Low power standby mode,  $I_Q$  typically 80  $\mu$ A
- High efficiency
- Uses readily available standard inductors
- Thermal shutdown and current limit protection

### Applications

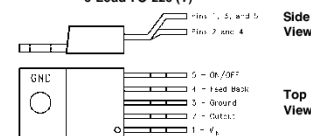
- Simple high-efficiency step-down (buck) regulator
- On-card switching regulators
- Positive to negative converter

### Typical Application (Fixed Output Voltage Versions)



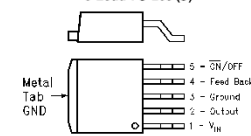
### Connection Diagrams and Ordering Information

#### Bent and Staggered Leads, Through Hole Package 5-Lead TO-220 (T)



Order Number LM2596T-3.3, LM2596T-5.0,  
LM2596T-12 or LM2596T-ADJ  
See NS Package Number T05D

#### Surface Mount Package 5-Lead TO-263 (S)



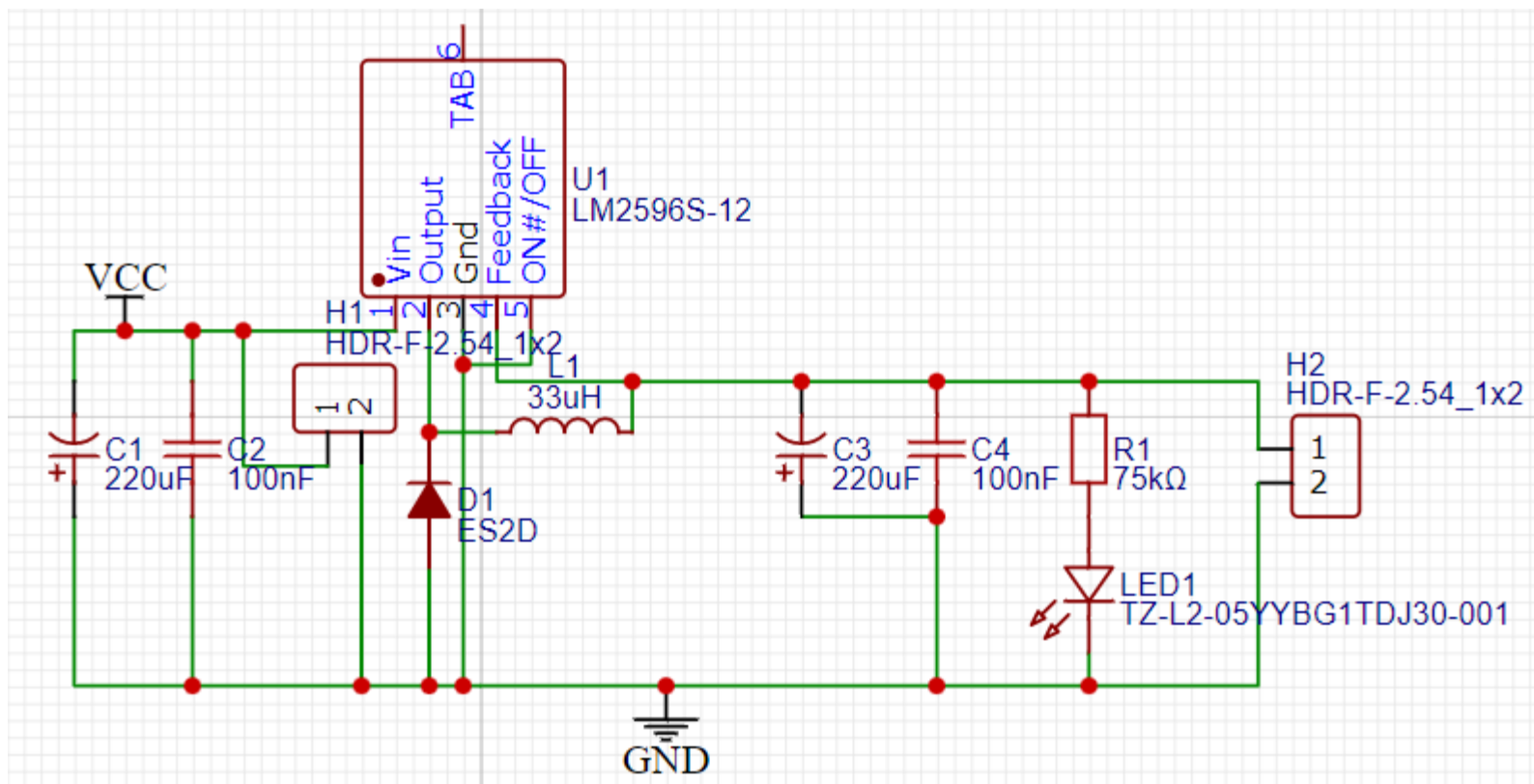
Order Number LM2596S-3.3, LM2596S-5.0,  
LM2596S-12 or LM2596S-ADJ  
See NS Package Number T55B

<sup>†</sup>Patent Number 5,382,918.  
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R9D-830M26/Printed in U. S. A.

LM2596 SIMPLE SWITCHER® Power Converter 150 kHz 3A Step-Down Voltage Regulator



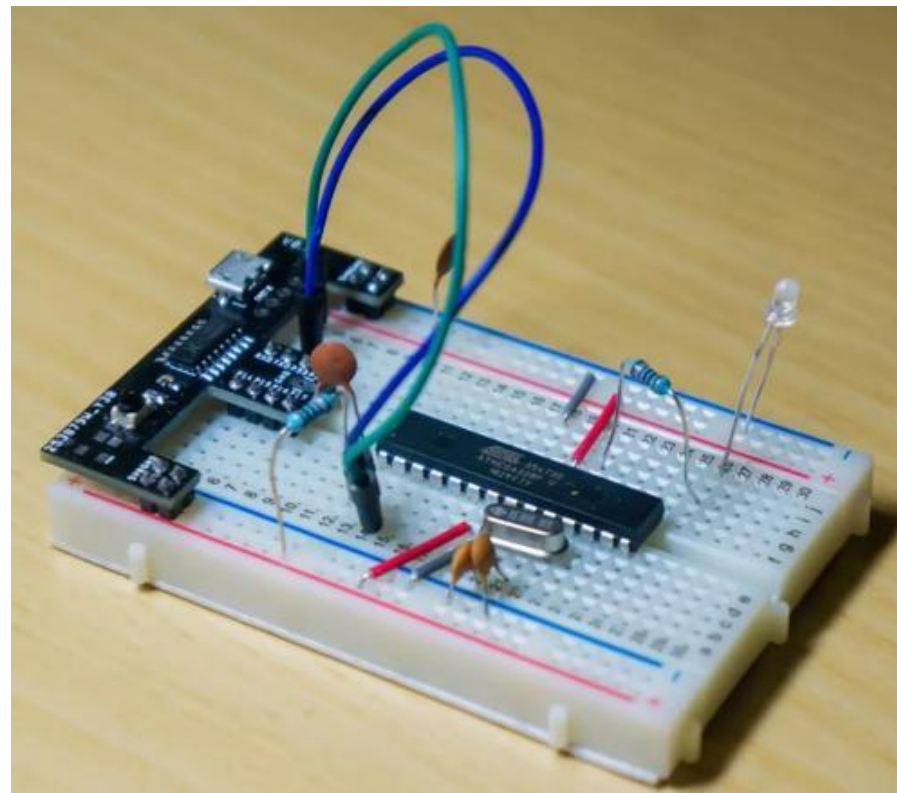




# 日用没用



面包板



Print





# 日用没用

立创EDA 标准 文件 编辑 放置 格式 视图 设计 工具 制造 高级 设置 帮助

个人 Zhu52520

工程

过滤

元件 (7)

网络 (6 / 10)

设计管理器

基础库

元件库

立创商城

嘉立创

技术支持

回收站

开始

New Project

\*PCB\_New Project

300 350 400 450 500 550 600 650

700 650 600 550 500 450

LED2  
48-213/T7D-BQ1R2QY/3C

LED3  
48-213/T7D-BQ1R2QY/3C

R2  
100

LED1  
48-213/T7D-BQ1R2QY/3C

R1  
100

SW1  
BTSA-N-S-5

B1  
CR1220-2

Sheet\_1

电气工具

绘图...

选中数量 0

画布属性

背景色 #FFFFFF

网格可见 是

网格颜色 #CCCCCC

网格样式 实线

网格大小 5

吸附 是

栅格尺寸 5

ALT键栅格 5

光标X 710

光标Y 630

光标DX 391

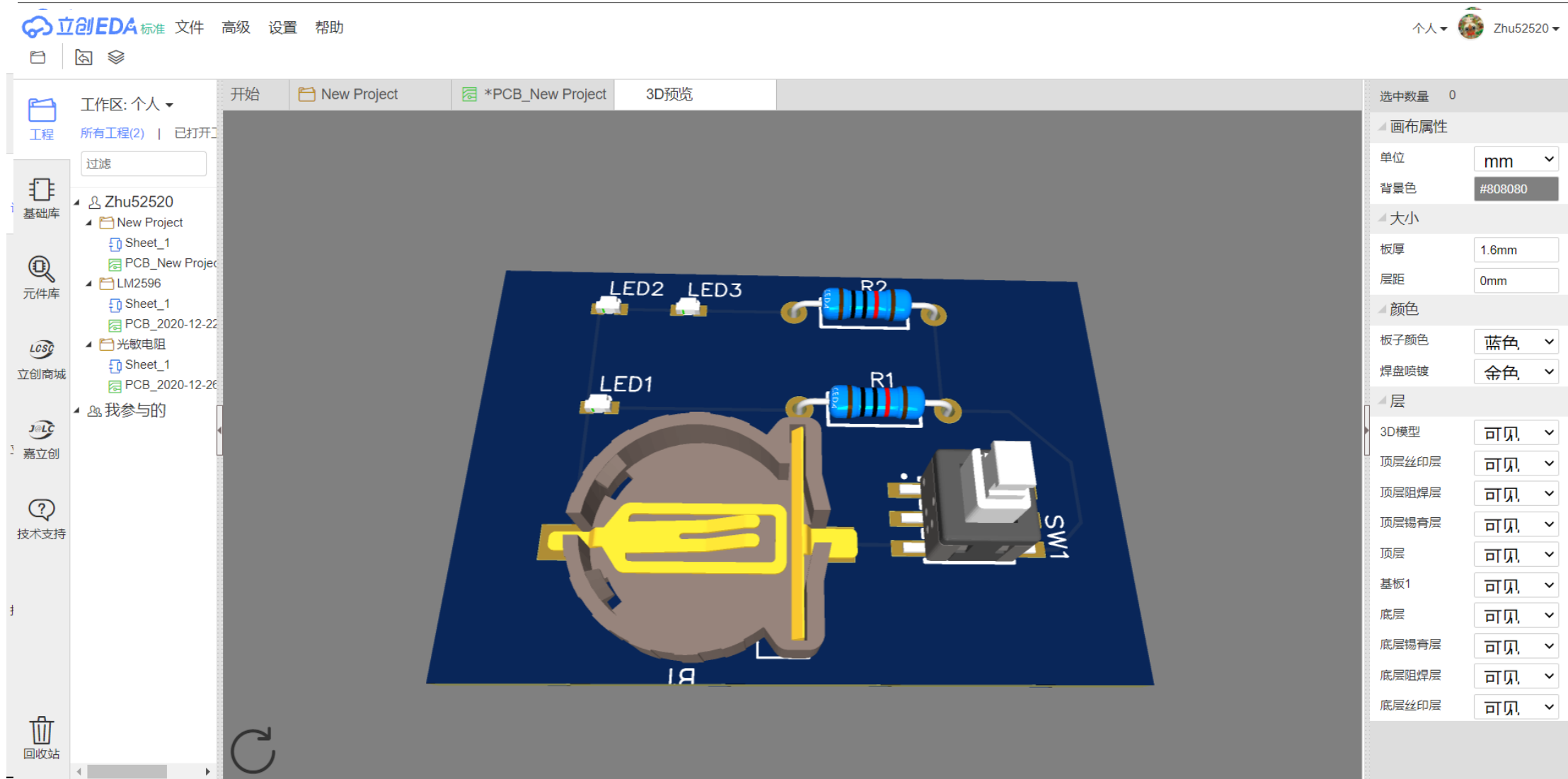
光标DY -31



# 日用没用



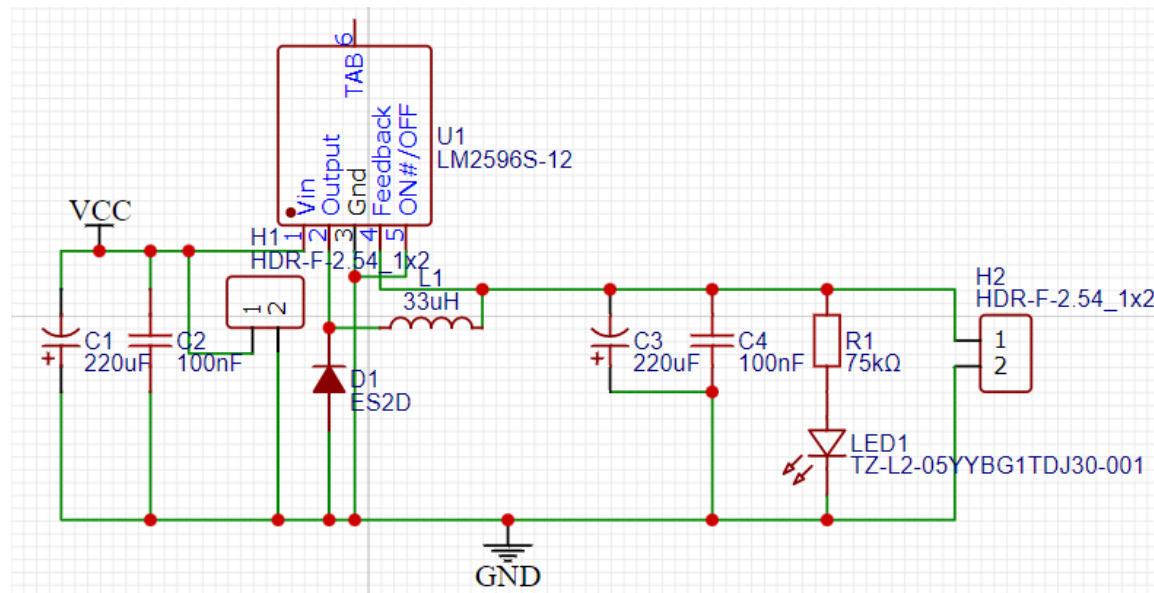
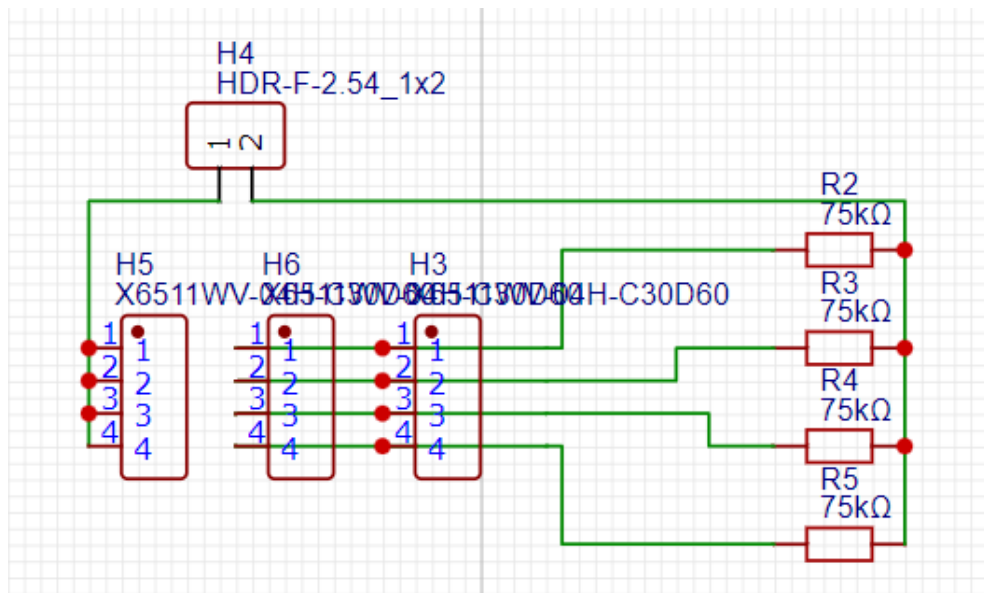
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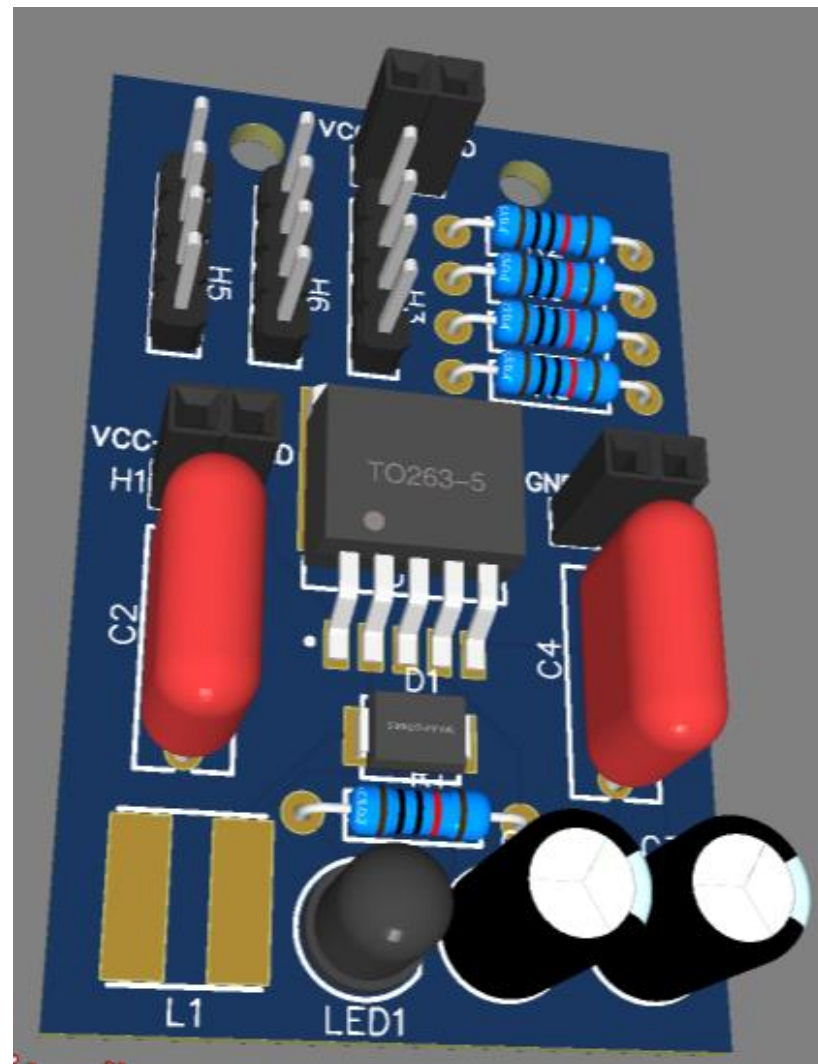
立志成才 报国裕民

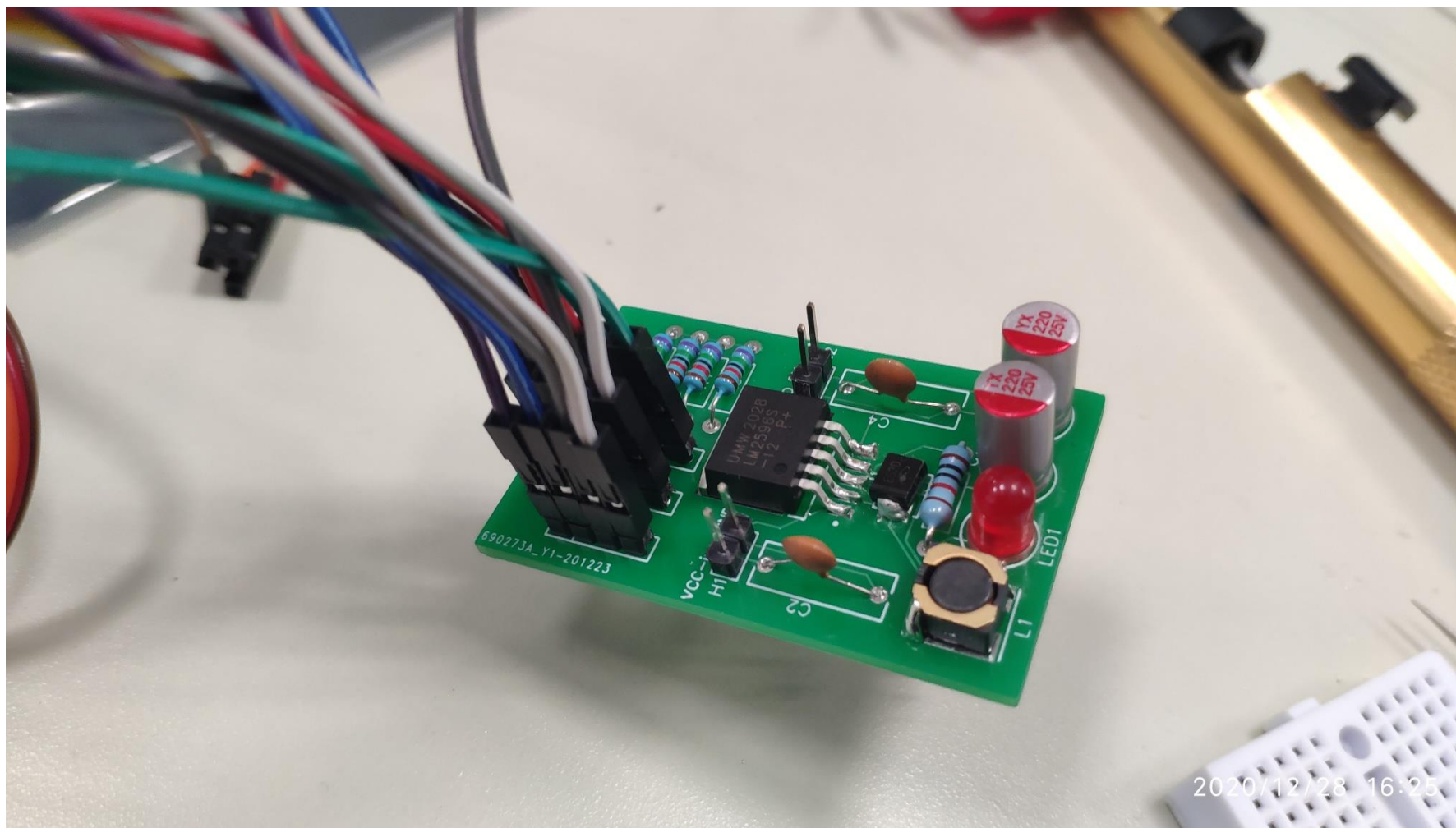


# 日用没用



# 日用没用









# 没日咋办



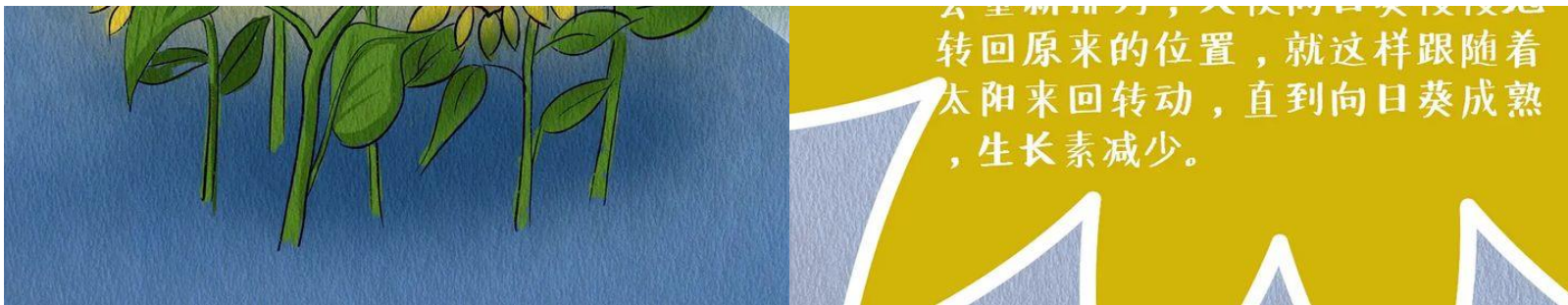
太阳下山之后，**向日葵怎么回头？**



月半弯，月光下的你显得特别的好看。

有个问题困扰我很多年，向日葵跟着太阳转，从东边转到西边。那第二天早上是怎么回到东边的？一个猛甩头？是的，你晚上走过向日葵花海，几十万株向日葵突然就一个猛回头。吓得你从此生活不能自理。

发布于 2015-10-23





# 没日咋办



```
while (flag == 1) {  
    if ((analogRead(A5) <= 800 && analogRead(A4) <= 800) && (analogRead(A1) <= 800  
&& analogRead(A0) <= 800)) {  
        flag = 0;  
        break;  
    }  
    .....  
    servo_A3.write(90);  
    delay(7);  
    servo_A2.write(90);  
    delay(7);  
    flag = 1;
```





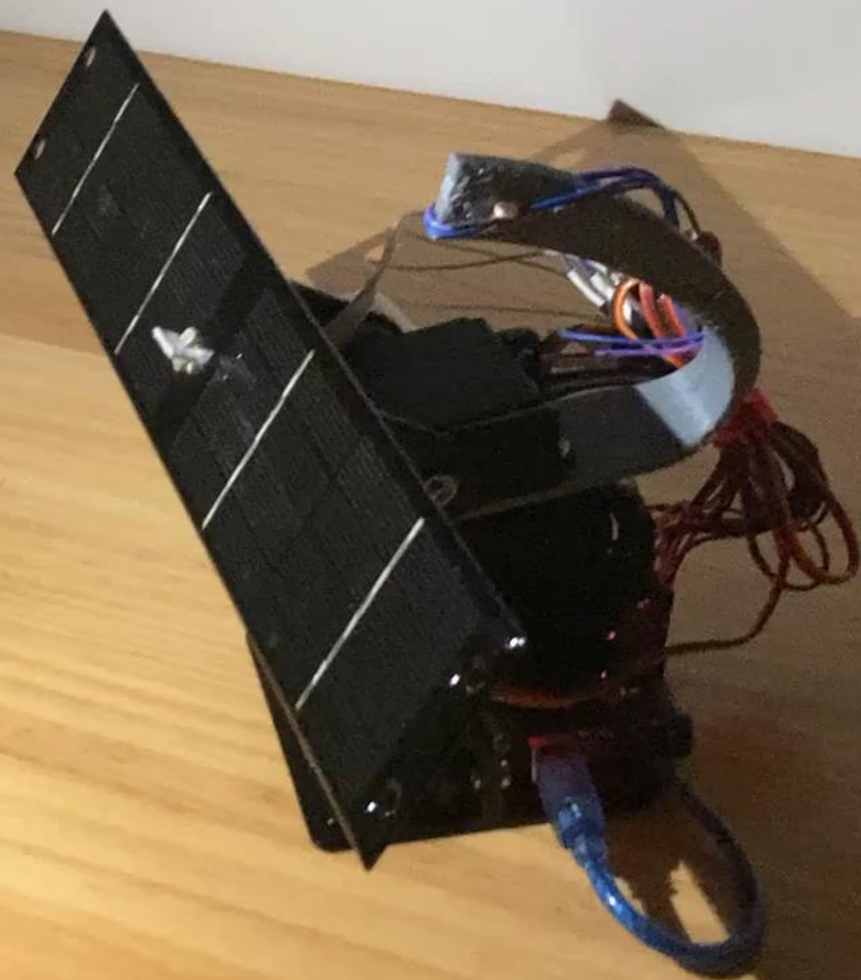
# 日的闪现



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# 日的闪现



```
if (analogRead(A5) > analogRead(A4) + 100) {  
    servo_A3.write((servo_A3.read() + rota));  
    delay(5);  
  
} else if (analogRead(A4) > analogRead(A5) + 100) {  
    servo_A3.write((servo_A3.read() - rota));  
    delay(5);  
}  
  
if (analogRead(A1) > analogRead(A0) + 50) {  
    if (rota == 1 && servo_A2.read() < 90 || rota == -1 && servo_A2.read() >= 90) {  
        servo_A2.write((servo_A2.read() + 1));  
        delay(5);  
    }  
} else if (analogRead(A0) > analogRead(A1) + 50) {  
    if (rota == 1 && servo_A2.read() <= 90 || rota == -1 && servo_A2.read() > 90) {  
        servo_A2.write((servo_A2.read() - 1));  
        delay(5);  
    }  
}
```





# 日的闪现



```
if (servo_A3.read() == 180 && (servo_A2.read() >= 120 || servo_A2.read() <= 60)) {  
    servo_A2.write((180 - servo_A2.read()));  
    delay(750);  
    servo_A3.write(5);  
    delay(750);  
    rota = rota * -1;  
  
}  
  
if (servo_A3.read() == 0 && (servo_A2.read() >= 120 || servo_A2.read() <= 60)) {  
    servo_A2.write((180 - servo_A2.read()));  
    delay(750);  
    servo_A3.write(175);  
    delay(750);  
    rota = rota * -1;  
  
}
```

