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2.4 PRIORITY QUEUES

- *API and elementary implementations*
- *binary heaps*
- *heapsort*
- *event-driven simulation*

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Priority queue

Collections. Insert and delete items. Which item to delete?

Stack. Remove the item most recently added.

Queue. Remove the item least recently added.

Randomized queue. Remove a random item.

Priority queue. Remove the largest (or smallest) item.

operation	*argument*	*return value*
insert	P	
insert	Q	
insert	E	
remove max		Q
insert	X	
insert	A	
insert	M	
remove max		X
insert	P	
insert	L	
insert	E	
remove max		P

Priority queue API

Requirement. Generic items are `Comparable`.

Key must be Comparable
(bounded type parameter)

`public class MaxPQ<Key extends Comparable<Key>>`

	`MaxPQ()`	*create an empty priority queue*
	`MaxPQ(Key[] a)`	*create a priority queue with given keys*
`void`	`insert(Key v)`	*insert a key into the priority queue*
`Key`	`delMax()`	*return and remove the largest key*
`boolean`	`isEmpty()`	*is the priority queue empty?*
`Key`	`max()`	*return the largest key*
`int`	`size()`	*number of entries in the priority queue*

Priority queue applications

- Event-driven simulation. [customers in a line, colliding particles]
- Numerical computation. [reducing roundoff error]
- Data compression. [Huffman codes]
- Graph searching. [Dijkstra's algorithm, Prim's algorithm]
- Number theory. [sum of powers]
- Artificial intelligence. [A* search]
- Statistics. [maintain largest M values in a sequence]
- Operating systems. [load balancing, interrupt handling]
- Discrete optimization. [bin packing, scheduling]
- Spam filtering. [Bayesian spam filter]

Generalizes: stack, queue, randomized queue.

Priority queue client example

Challenge. Find the largest M items in a stream of N items.

- Fraud detection: isolate $$ transactions.
- File maintenance: find biggest files or directories.

N huge, M large

Constraint. Not enough memory to store N items.

```
% more tinyBatch.txt
Turing        6/17/1990    644.08
vonNeumann    3/26/2002   4121.85
Dijkstra      8/22/2007   2678.40
vonNeumann    1/11/1999   4409.74
Dijkstra     11/18/1995    837.42
Hoare         5/10/1993   3229.27
vonNeumann    2/12/1994   4732.35
Hoare         8/18/1992   4381.21
Turing        1/11/2002     66.10
Thompson      2/27/2000   4747.08
Turing        2/11/1991   2156.86
Hoare         8/12/2003   1025.70
vonNeumann   10/13/1993   2520.97
Dijkstra      9/10/2000    708.95
Turing       10/12/1993   3532.36
Hoare         2/10/2005   4050.20
```

```
% java TopM 5 < tinyBatch.txt
Thompson      2/27/2000   4747.08
vonNeumann    2/12/1994   4732.35
vonNeumann    1/11/1999   4409.74
Hoare         8/18/1992   4381.21
vonNeumann    3/26/2002   4121.85
```

sort key

Priority queue client example

Challenge. Find the largest M items in a stream of N items.

- Fraud detection: isolate $$ transactions.
- File maintenance: find biggest files or directories.

N huge, M large

Constraint. Not enough memory to store N items.

```
MinPQ<Transaction> pq = new MinPQ<Transaction>();

while (StdIn.hasNextLine())
{
   String line = StdIn.readLine();
   Transaction item = new Transaction(line);
   pq.insert(item);
   if (pq.size() > M)
      pq.delMin();
}
```

use a min-oriented pq

Transaction data type is Comparable (ordered by $$)

pq contains largest M items

Priority queue client example

Challenge. Find the largest M items in a stream of N items.

order of growth of finding the largest M in a stream of N items

implementation	time	space
sort	N log N	N
elementary PQ	M N	M
binary heap	N log M	M
best in theory	N	M

Priority queue: unordered and ordered array implementation

operation	argument	return value	size	contents (unordered)							contents (ordered)						
insert	P		1	P							P						
insert	Q		2	P	Q						P	Q					
insert	E		3	P	Q	E					E	P	Q				
remove max		Q	2	P	E						E	P					
insert	X		3	P	E	X					E	P	X				
insert	A		4	P	E	X	A				A	E	P	X			
insert	M		5	P	E	X	A	M			A	E	M	P	X		
remove max		X	4	P	E	M	A				A	E	M	P			
insert	P		5	P	E	M	A	P			A	E	M	P	P		
insert	L		6	P	E	M	A	P	L		A	E	L	M	P	P	
insert	E		7	P	E	M	A	P	L	E	A	E	E	L	M	P	P
remove max		P	6	E	M	A	P	L	E		A	E	E	L	M	P	

A sequence of operations on a priority queue

Priority queue: unordered array implementation

```
public class UnorderedMaxPQ<Key extends Comparable<Key>>
{
   private Key[] pq;   // pq[i] = ith element on pq
   private int N;      // number of elements on pq

   public UnorderedMaxPQ(int capacity)
   {  pq = (Key[]) new Comparable[capacity];  }

   public boolean isEmpty()
   {  return N == 0; }

   public void insert(Key x)
   {  pq[N++] = x;  }

   public Key delMax()
   {
      int max = 0;
      for (int i = 1; i < N; i++)
         if (less(max, i)) max = i;
      exch(max, N-1);
      return pq[--N];
   }
}
```

no generic array creation

less() and exch() similar to sorting methods

null out entry to prevent loitering

Priority queue elementary implementations

Challenge. Implement all operations efficiently.

order of growth of running time for priority queue with N items

implementation	insert	del max	max
unordered array	1	N	N
ordered array	N	1	1
goal	log N	log N	log N

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2.4 Priority Queues

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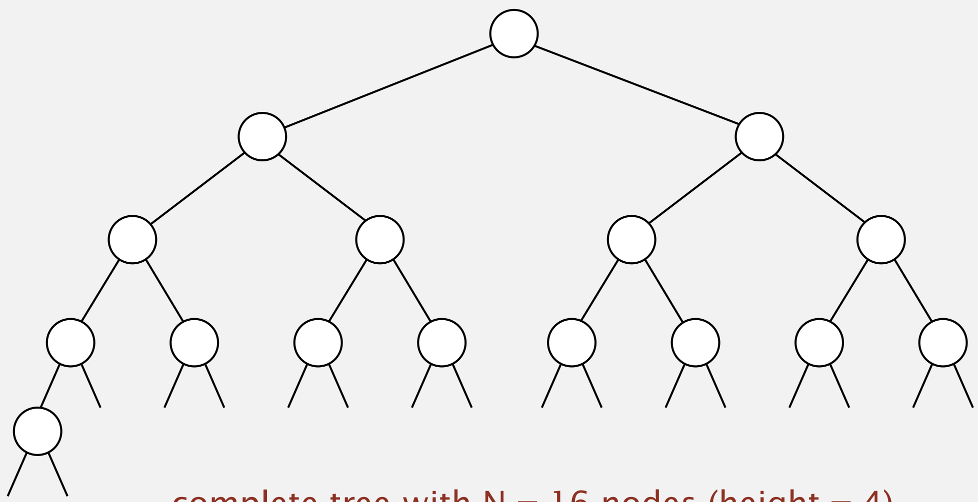
- heapsort
- event-driven simulation

Complete binary tree

Binary tree. Empty or node with links to left and right binary trees.

Complete tree. Perfectly balanced, except for bottom level.



complete tree with N = 16 nodes (height = 4)

Property. Height of complete tree with N nodes is $\lfloor \lg N \rfloor$.

Pf. Height only increases when N is a power of 2.

A complete binary tree in nature

Binary heap representations

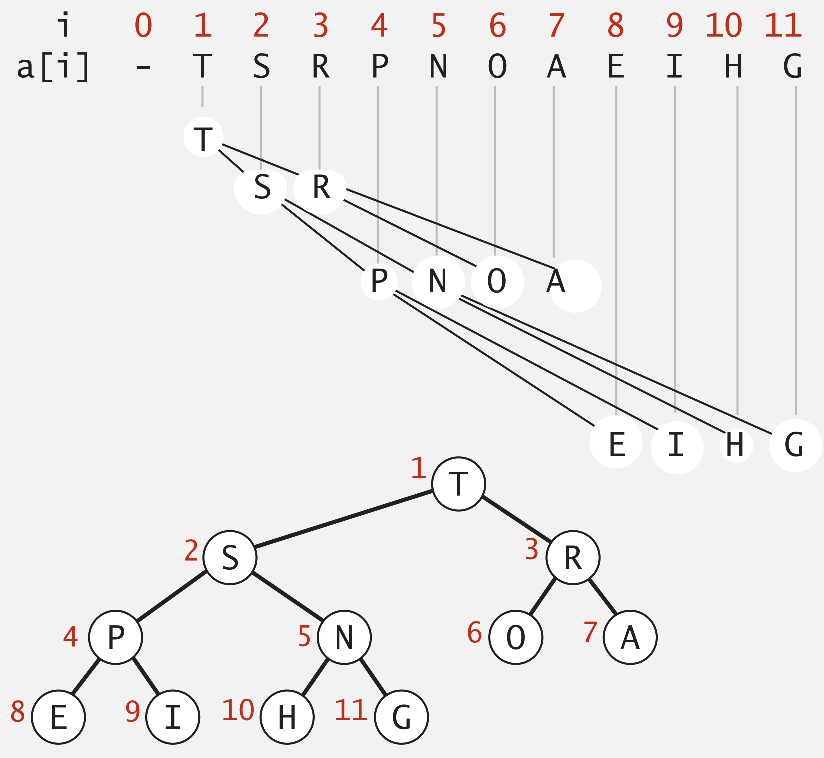
Binary heap. Array representation of a heap-ordered complete binary tree.

Heap-ordered binary tree.

- Keys in nodes.
- Parent's key no smaller than children's keys.

Array representation.

- Indices start at 1.
- Take nodes in level order.
- No explicit links needed!



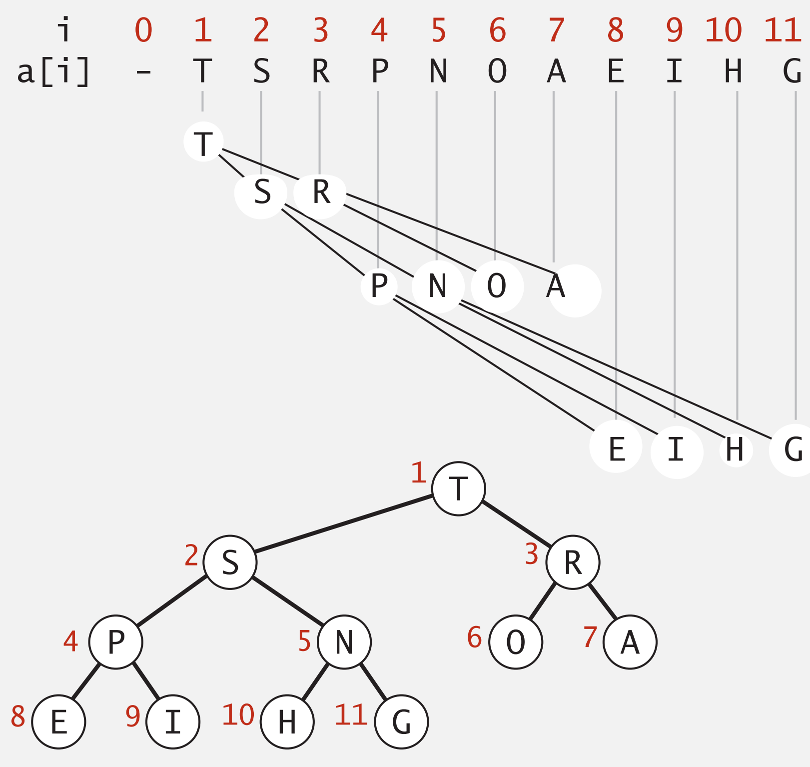
Heap representations

Binary heap properties

Proposition. Largest key is `a[1]`, which is root of binary tree.

Proposition. Can use array indices to move through tree.

- Parent of node at `k` is at `k/2`.
- Children of node at `k` are at `2k` and `2k+1`.



Heap representations

Promotion in a heap

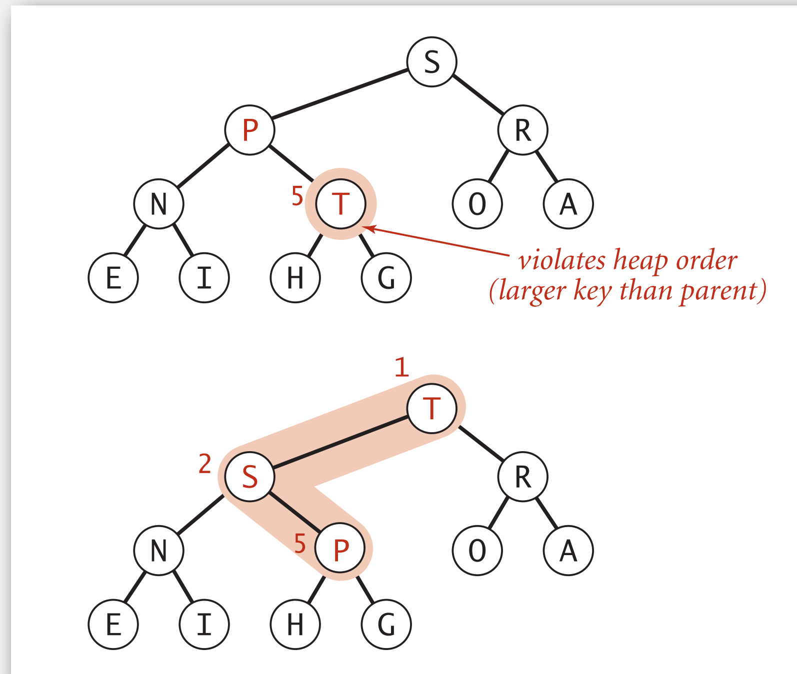
Scenario. Child's key becomes larger key than its parent's key.

To eliminate the violation:

- Exchange key in child with key in parent.
- Repeat until heap order restored.

```
private void swim(int k)
{
   while (k > 1 && less(k/2, k))
   {
      exch(k, k/2);
      k = k/2;
   }
}
```

parent of node at k is at k/2



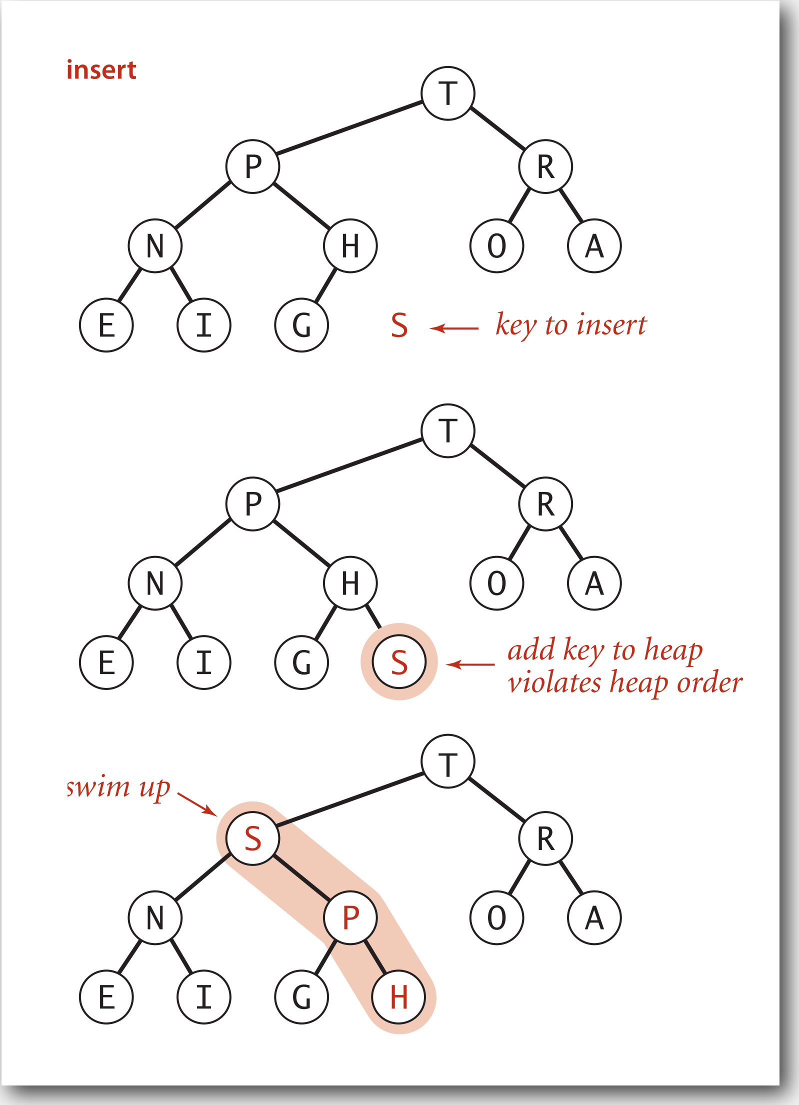
Peter principle. Node promoted to level of incompetence.

Insertion in a heap

Insert. Add node at end, then swim it up.

Cost. At most $1 + \lg N$ compares.

```
public void insert(Key x)
{
   pq[++N] = x;
   swim(N);
}
```



Demotion in a heap

Scenario. Parent's key becomes smaller than one (or both) of its children's.

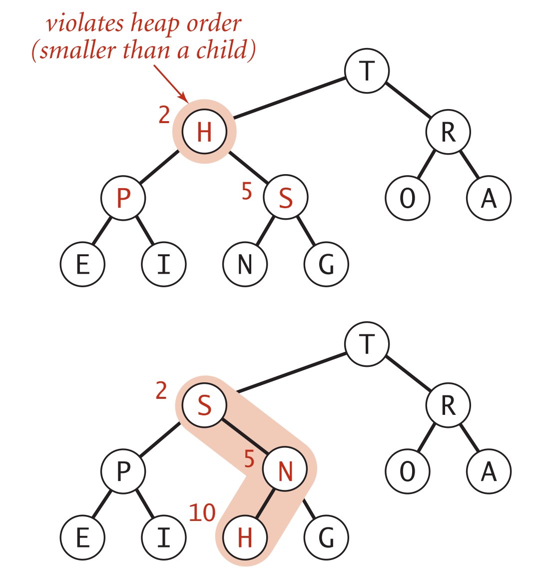
To eliminate the violation:

why not smaller child?

- Exchange key in parent with key in larger child.
- Repeat until heap order restored.

```
private void sink(int k)
{
   while (2*k <= N)
   {
      int j = 2*k;
      if (j < N && less(j, j+1)) j++;
      if (!less(k, j)) break;
      exch(k, j);
      k = j;
   }
}
```

children of node at k are 2k and 2k+1



Top-down reheapify (sink)

Power struggle. Better subordinate promoted.

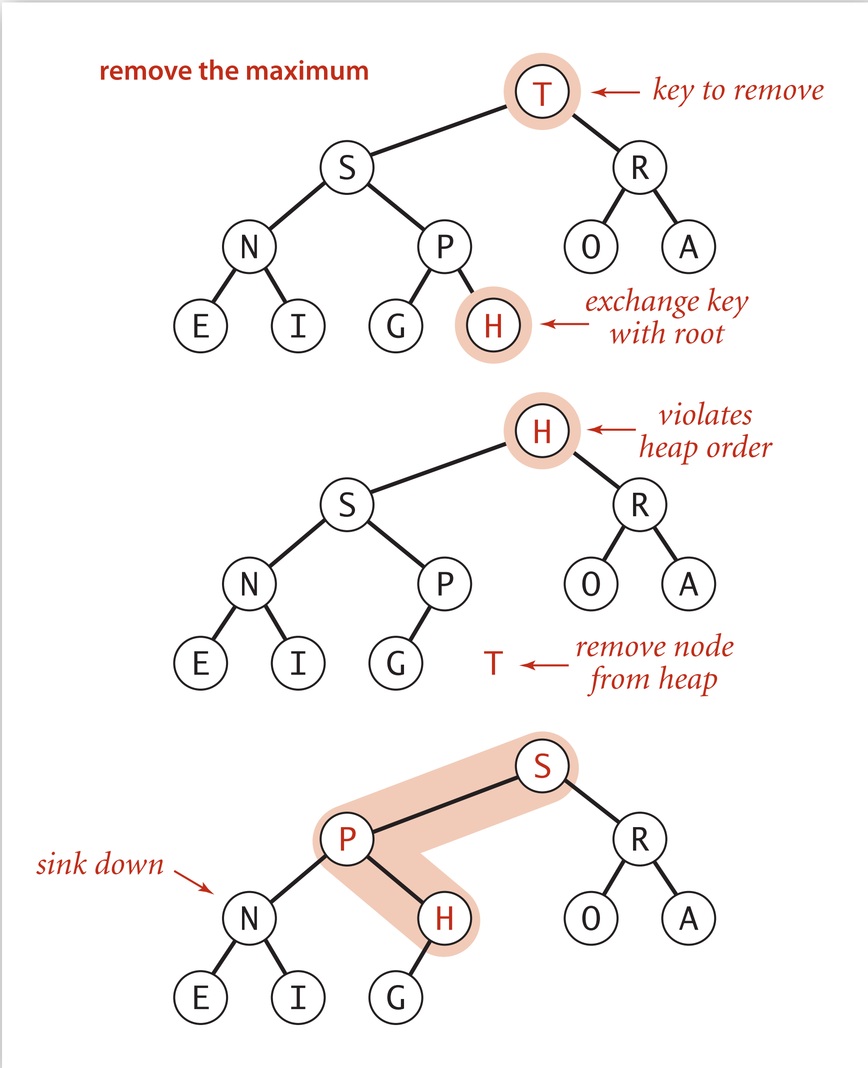
Delete the maximum in a heap

Delete max. Exchange root with node at end, then sink it down.

Cost. At most $2 \lg N$ compares.

```
public Key delMax()
{
   Key max = pq[1];
   exch(1, N--);
   sink(1);
   pq[N+1] = null;
   return max;
}
```

prevent loitering

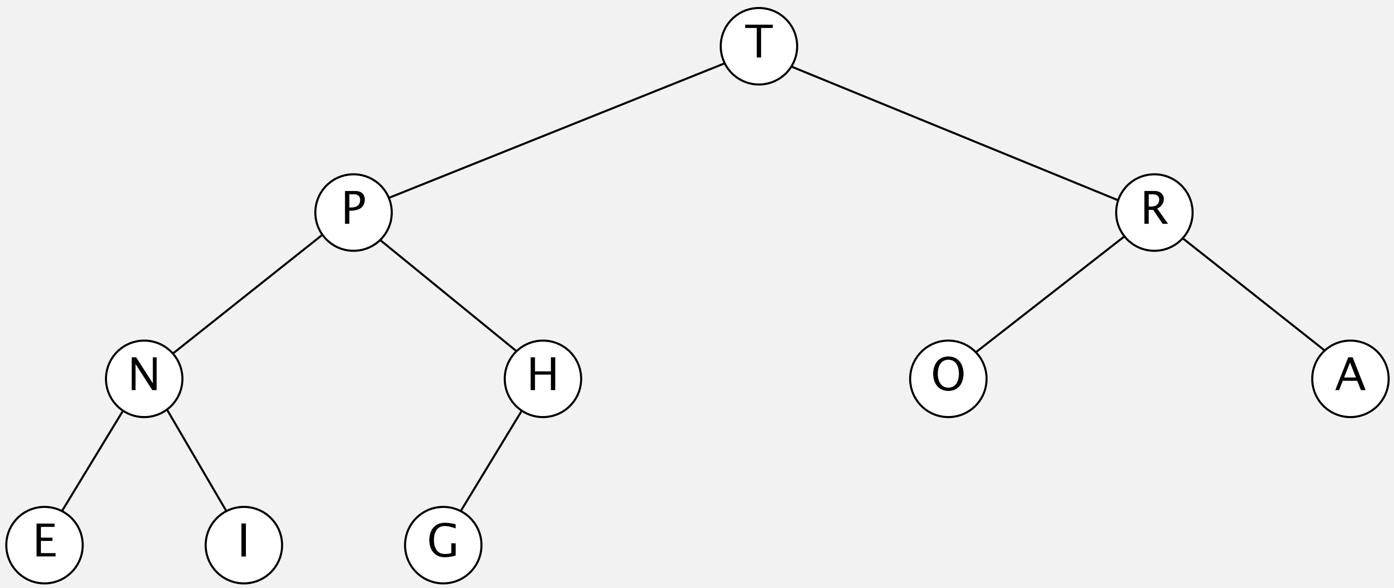


Binary heap demo

Insert. Add node at end, then swim it up.

Remove the maximum. Exchange root with node at end, then sink it down.

heap ordered



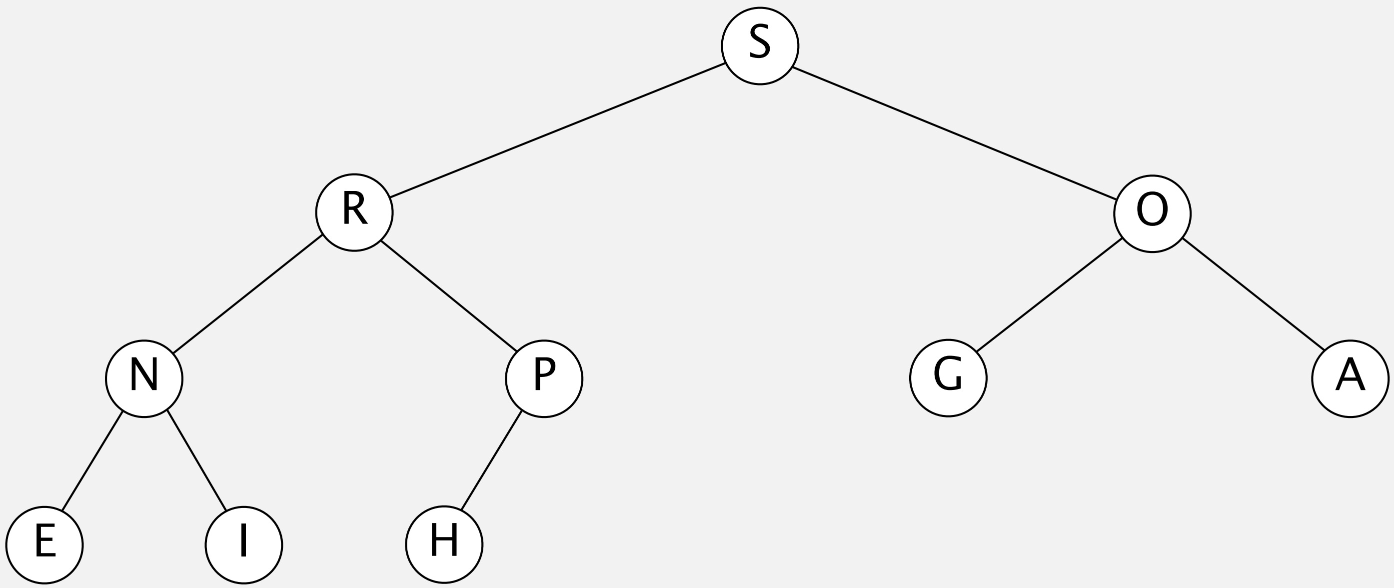
T	P	R	N	H	O	A	E	I	G	

Binary heap demo

Insert. Add node at end, then swim it up.

Remove the maximum. Exchange root with node at end, then sink it down.

heap ordered



S	R	O	N	P	G	A	E	I	H	

Binary heap: Java implementation

```
public class MaxPQ<Key extends Comparable<Key>>
{
   private Key[] pq;
   private int N;

   public MaxPQ(int capacity)
   {  pq = (Key[]) new Comparable[capacity+1];  }

   public boolean isEmpty()
   {   return N == 0;   }
   public void insert(Key key)
   public Key delMax()
   {   /* see previous code */  }

   private void swim(int k)
   private void sink(int k)
   {   /* see previous code */  }

   private boolean less(int i, int j)
   {   return pq[i].compareTo(pq[j]) < 0;  }
   private void exch(int i, int j)
   {   Key t = pq[i]; pq[i] = pq[j]; pq[j] = t;  }
}
```

fixed capacity (for simplicity)

PQ ops

heap helper functions

array helper functions

Priority queues implementation cost summary

order-of-growth of running time for priority queue with N items

implementation	insert	del max	max
unordered array	1	N	N
ordered array	N	1	1
binary heap	log N	log N	1
d-ary heap	$\log_d N$	$d \log_d N$	1
Fibonacci	1	log N †	1
impossible	1	1	1

← why impossible?

† amortized

Binary heap considerations

Immutability of keys.

- Assumption: client does not change keys while they're on the PQ.
- Best practice: use immutable keys.

Underflow and overflow.

- Underflow: throw exception if deleting from empty PQ.
- Overflow: add no-arg constructor and use resizing array.

leads to log N
amortized time per op
(how to make worst case?)

Minimum-oriented priority queue.

- Replace `less()` with `greater()`.
- Implement `greater()`.

Other operations.

- Remove an arbitrary item.
- Change the priority of an item.

can implement with `sink()` and `swim()` [stay tuned]

Immutability: implementing in Java

Data type. Set of values and operations on those values.

Immutable data type. Can't change the data type value once created.

```
public final class Vector {
   private final int N;
   private final double[] data;

   public Vector(double[] data) {
      this.N = data.length;
      this.data = new double[N];
      for (int i = 0; i < N; i++)
         this.data[i] = data[i];
   }

   …
}
```

can't override instance methods

all instance variables private and final

defensive copy of mutable instance variables

instance methods don't change instance variables

Immutable. String, Integer, Double, Color, Vector, Transaction, Point2D.

Mutable. StringBuilder, Stack, Counter, Java array.

Immutability: properties

Data type. Set of values and operations on those values.

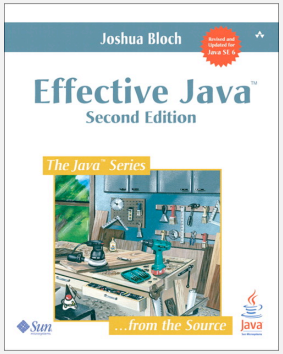
Immutable data type. Can't change the data type value once created.

Advantages.

- Simplifies debugging.
- Safer in presence of hostile code.
- Simplifies concurrent programming.
- Safe to use as key in priority queue or symbol table.

Disadvantage. Must create new object for each data type value.

> *" Classes should be immutable unless there's a very good reason to make them mutable.... If a class cannot be made immutable, you should still limit its mutability as much as possible. "*
>
> *— Joshua Bloch (Java architect)*



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2.4 Priority Queues

- API and elementary implementations
- binary heaps
- heapsort
- event-driven simulation

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- API and elementary implementations
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- *heapsort*
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Heapsort

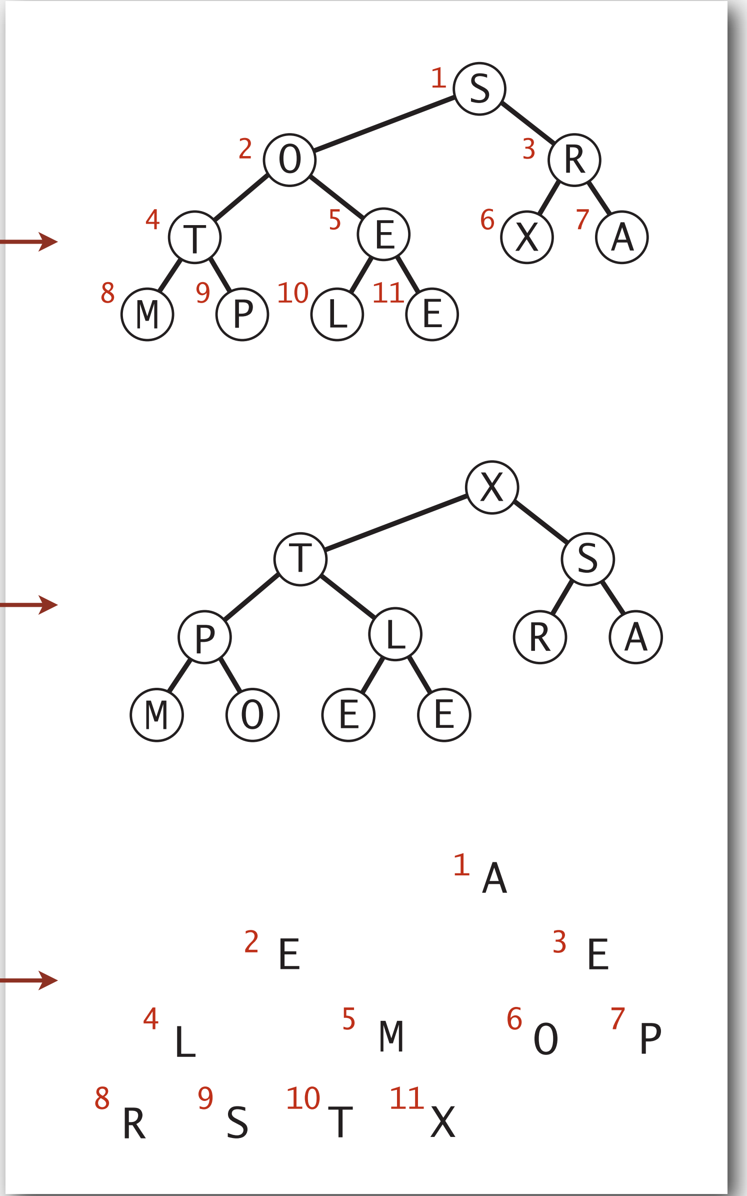
Basic plan for in-place sort.

- Create max-heap with all N keys.
- Repeatedly remove the maximum key.

start with array of keys
in arbitrary order

build a max-heap
(in place)

sorted result
(in place)

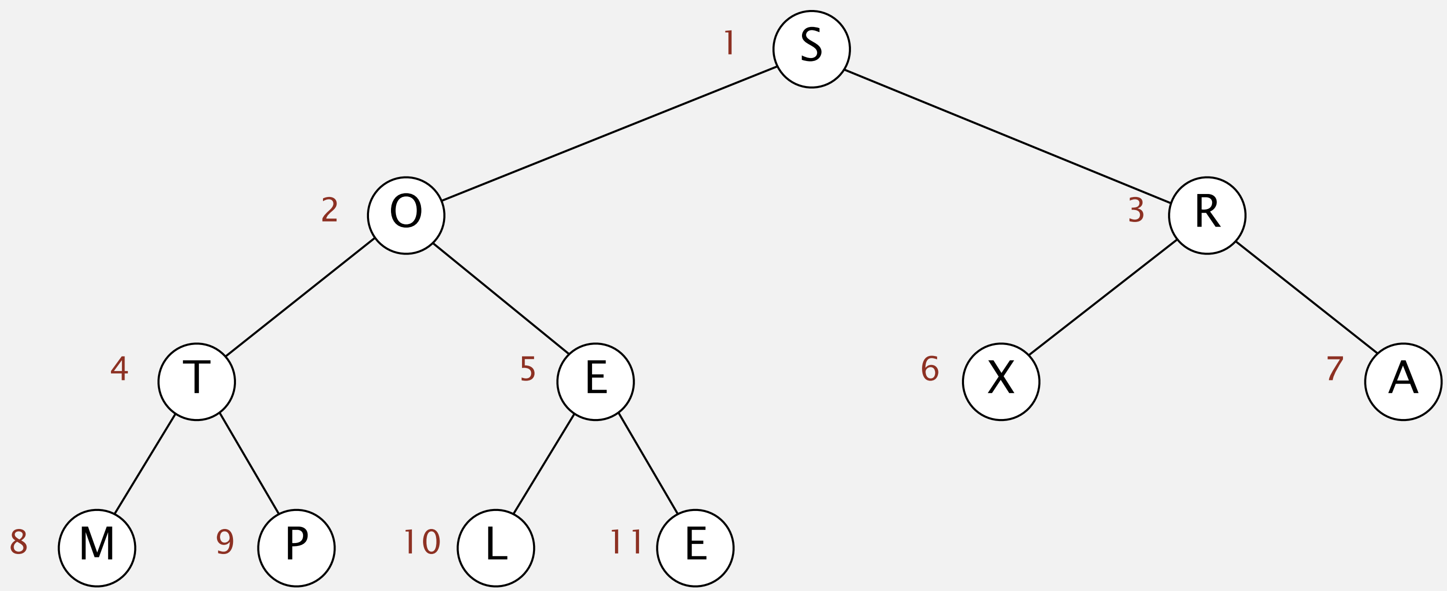


Heapsort demo

Heap construction. Build max heap using bottom-up method.

we assume array entries are indexed 1 to N

array in arbitrary order



S	O	R	T	E	X	A	M	P	L	E
1	2	3	4	5	6	7	8	9	10	11

Heapsort demo

Sortdown. Repeatedly delete the largest remaining item.

array in sorted order

A

E E

L M O P

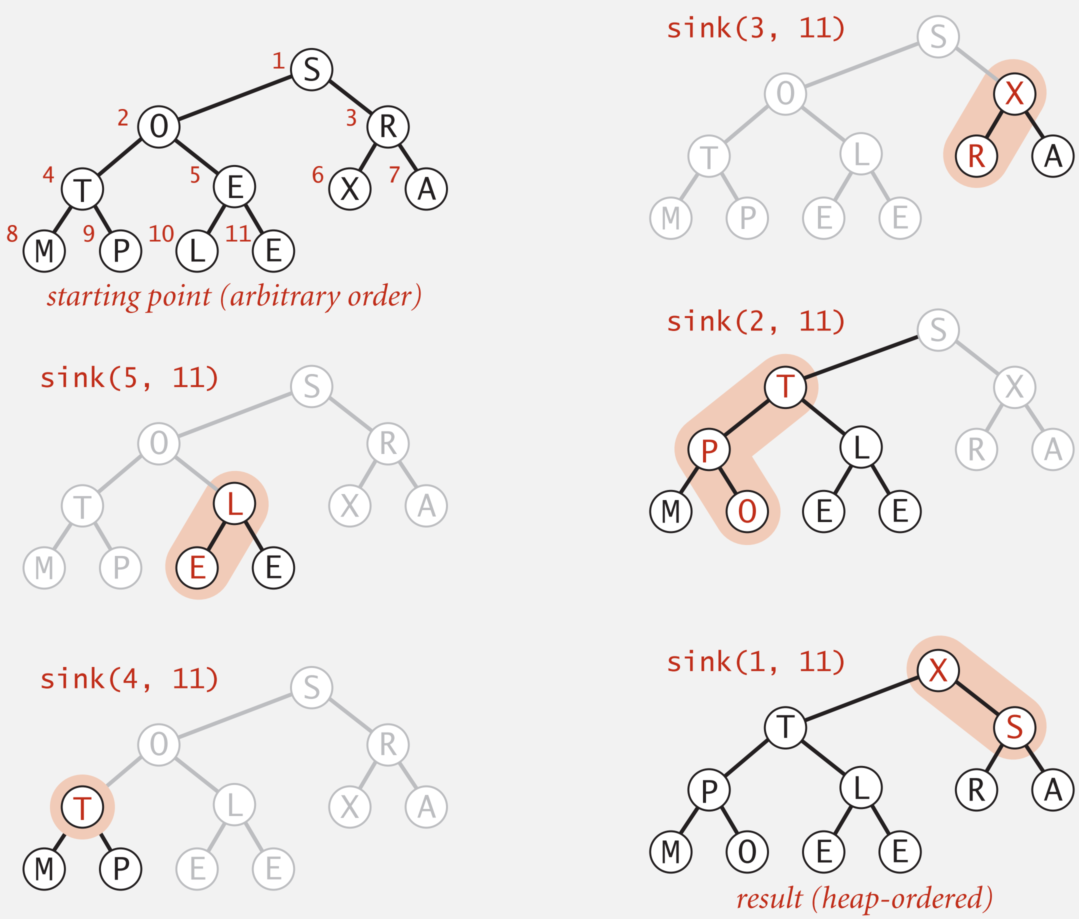
R S T X

A	E	E	L	M	O	P	R	S	T	X
1	2	3	4	5	6	7	8	9	10	11

Heapsort: heap construction

First pass. Build heap using bottom-up method.

```
for (int k = N/2; k >= 1; k--)
   sink(a, k, N);
```

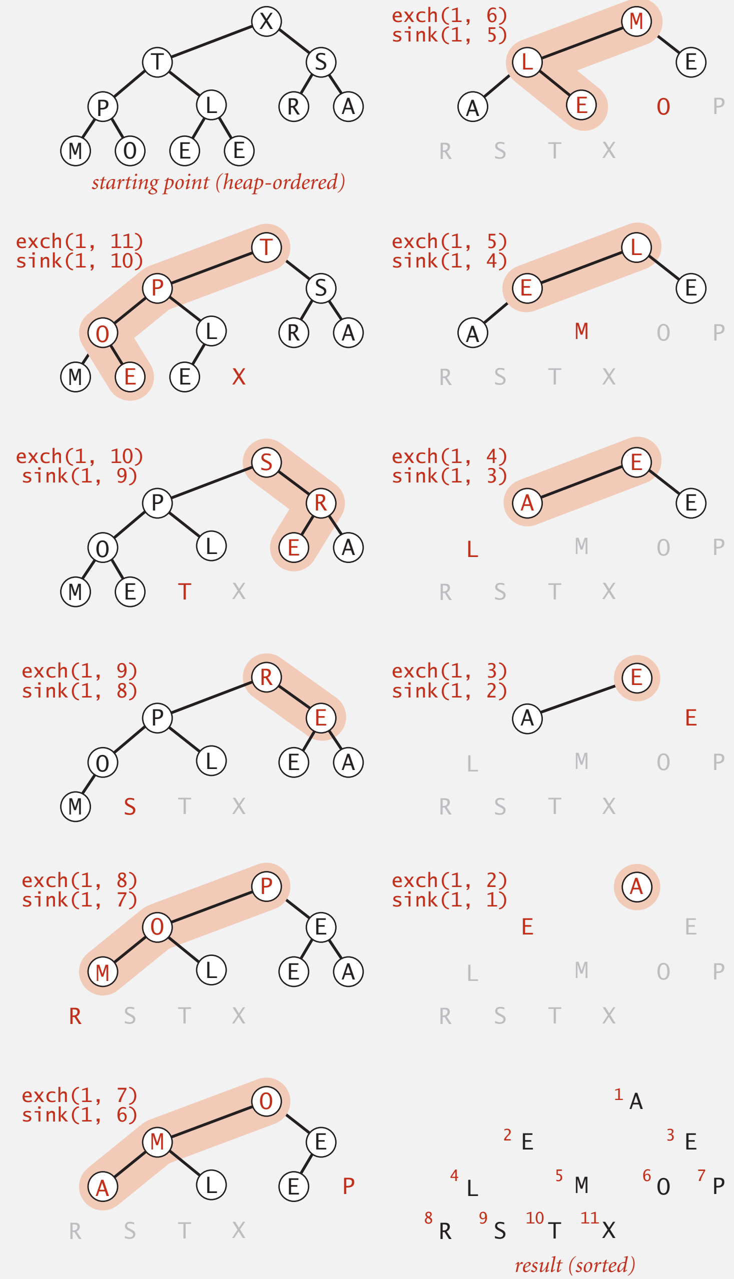


Heapsort: sortdown

Second pass.

- Remove the maximum, one at a time.
- Leave in array, instead of nulling out.

```
while (N > 1)
{
   exch(a, 1, N--);
   sink(a, 1, N);
}
```



Heapsort: Java implementation

```
public class Heap
{
   public static void sort(Comparable[] a)
   {
      int N = a.length;
      for (int k = N/2; k >= 1; k--)
         sink(a, k, N);
      while (N > 1)
      {
         exch(a, 1, N);
         sink(a, 1, --N);
      }
   }

   private static void sink(Comparable[] a, int k, int N)
   {  /* as before */  }

   private static boolean less(Comparable[] a, int i, int j)
   {  /* as before */  }

   private static void exch(Comparable[] a, int i, int j)
   {  /* as before */  }

}
```

but convert from
1-based indexing to
0-base indexing

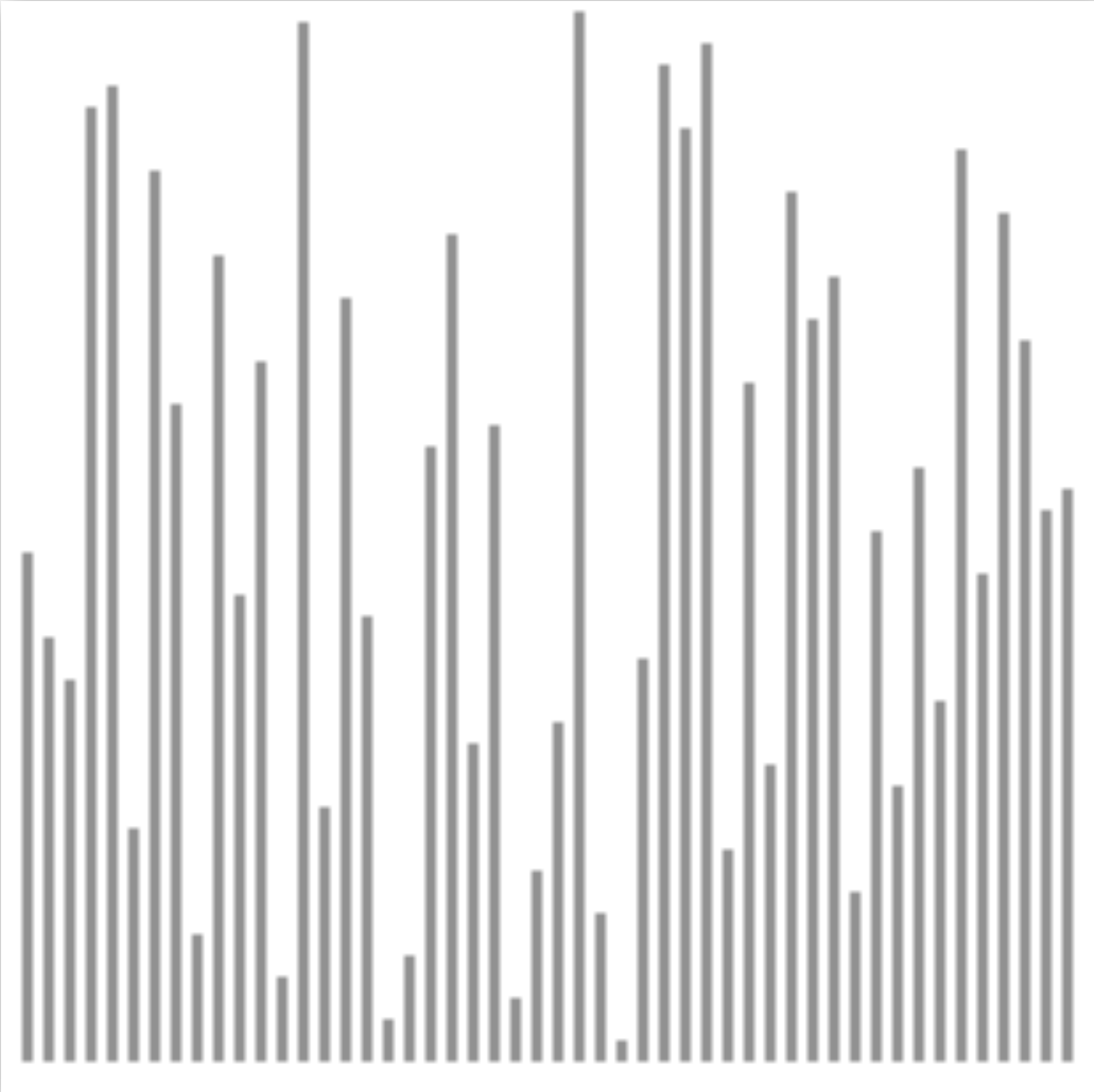
Heapsort: trace

N	k	0	1	2	3	4	5	6	7	8	9	10	11
initial values			S	O	R	T	E	X	A	M	P	L	E
11	5		S	O	R	T	L	X	A	M	P	E	E
11	4		S	O	R	T	L	X	A	M	P	E	E
11	3		S	O	X	T	L	R	A	M	P	E	E
11	2		S	T	X	P	L	R	A	M	O	E	E
11	1		X	T	S	P	L	R	A	M	O	E	E
heap-ordered			X	T	S	P	L	R	A	M	O	E	E
10	1		T	P	S	O	L	R	A	M	E	E	X
9	1		S	P	R	O	L	E	A	M	E	T	X
8	1		R	P	E	O	L	E	A	M	S	T	X
7	1		P	O	E	M	L	E	A	R	S	T	X
6	1		O	M	E	A	L	E	P	R	S	T	X
5	1		M	L	E	A	E	O	P	R	S	T	X
4	1		L	E	E	A	M	O	P	R	S	T	X
3	1		E	A	E	L	M	O	P	R	S	T	X
2	1		E	A	E	L	M	O	P	R	S	T	X
1	1		A	E	E	L	M	O	P	R	S	T	X
sorted result			A	E	E	L	M	O	P	R	S	T	X

Heapsort trace (array contents just after each sink)

Heapsort animation

50 random items



http://www.sorting-algorithms.com/heap-sort

▲ algorithm position
in order
not in order

Heapsort: mathematical analysis

Proposition. Heap construction uses $\leq 2N$ compares and exchanges.

Proposition. Heapsort uses $\leq 2N \lg N$ compares and exchanges.

Significance. In-place sorting algorithm with $N \log N$ worst-case.

- Mergesort: no, linear extra space. ← in-place merge possible, not practical
- Quicksort: no, quadratic time in worst case. ← N log N worst-case quicksort possible, not practical
- Heapsort: yes!

Bottom line. Heapsort is optimal for both time and space, but:

- Inner loop longer than quicksort's.
- Makes poor use of cache memory.
- Not stable.

Sorting algorithms: summary

	inplace?	stable?	worst	average	best	remarks
selection	x		$N^2 / 2$	$N^2 / 2$	$N^2 / 2$	N exchanges
insertion	x	x	$N^2 / 2$	$N^2 / 4$	N	use for small N or partially ordered
shell	x		?	?	N	tight code, subquadratic
quick	x		$N^2 / 2$	2 N ln N	N lg N	N log N probabilistic guarantee fastest in practice
3-way quick	x		$N^2 / 2$	2 N ln N	N	improves quicksort in presence of duplicate keys
merge		x	N lg N	N lg N	N lg N	N log N guarantee, stable
heap	x		2 N lg N	2 N lg N	N lg N	N log N guarantee, in-place
???	x	x	N lg N	N lg N	N lg N	holy sorting grail

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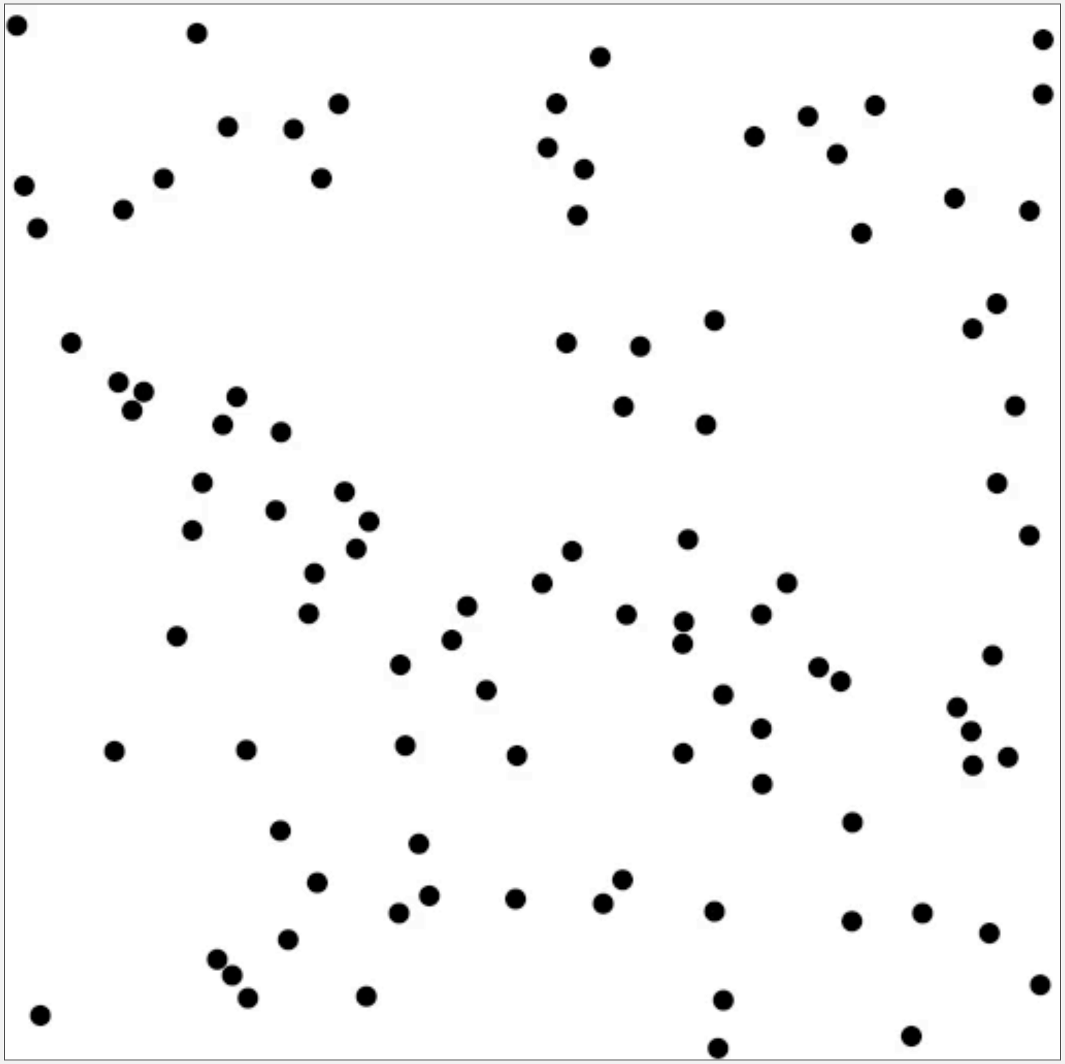
Molecular dynamics simulation of hard discs

Goal. Simulate the motion of N moving particles that behave according to the laws of elastic collision.



Molecular dynamics simulation of hard discs

Goal. Simulate the motion of N moving particles that behave according to the laws of elastic collision.

Hard disc model.

- Moving particles interact via elastic collisions with each other and walls.
- Each particle is a disc with known position, velocity, mass, and radius.
- No other forces.

temperature, pressure, diffusion constant

motion of individual atoms and molecules

Significance. Relates macroscopic observables to microscopic dynamics.

- Maxwell-Boltzmann: distribution of speeds as a function of temperature.
- Einstein: explain Brownian motion of pollen grains.

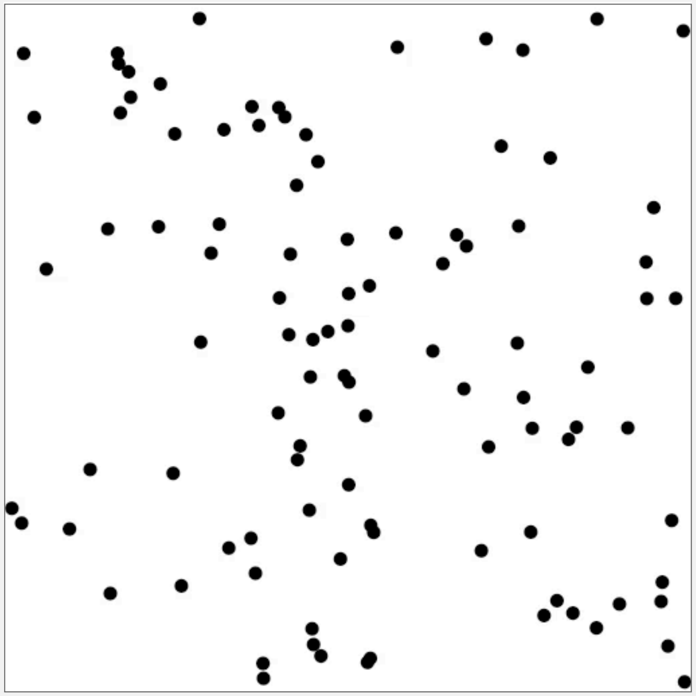
Warmup: bouncing balls

Time-driven simulation. N bouncing balls in the unit square.

```
public class BouncingBalls
{
   public static void main(String[] args)
   {
      int N = Integer.parseInt(args[0]);
      Ball[] balls = new Ball[N];
      for (int i = 0; i < N; i++)
         balls[i] = new Ball();
      while(true)
      {
         StdDraw.clear();
         for (int i = 0; i < N; i++)
         {
            balls[i].move(0.5);
            balls[i].draw();
         }
         StdDraw.show(50);
      }
   }
}
```

main simulation loop

```
% java BouncingBalls 100
```



Warmup: bouncing balls

```
public class Ball
{
    private double rx, ry;         // position
    private double vx, vy;         // velocity
    private final double radius;   // radius
    public Ball(...)
    {  /* initialize position and velocity */  }

    public void move(double dt)
    {
        if ((rx + vx*dt < radius) || (rx + vx*dt > 1.0 - radius)) { vx = -vx; }
        if ((ry + vy*dt < radius) || (ry + vy*dt > 1.0 - radius)) { vy = -vy; }
        rx = rx + vx*dt;
        ry = ry + vy*dt;
    }
    public void draw()
    {  StdDraw.filledCircle(rx, ry, radius);  }
}
```

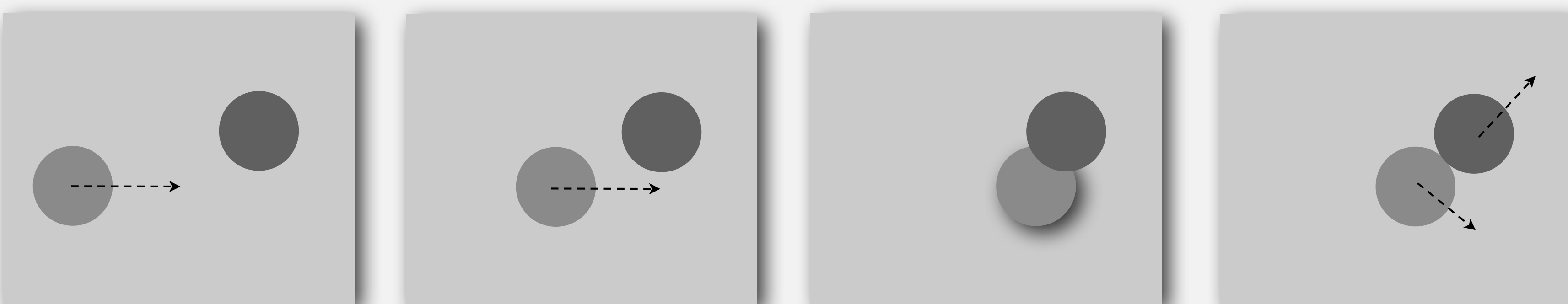
check for collision with walls

Missing. Check for balls colliding with each other.

- Physics problems: when? what effect?
- CS problems: which object does the check? too many checks?

Time-driven simulation

- Discretize time in quanta of size *dt*.
- Update the position of each particle after every *dt* units of time, and check for overlaps.
- If overlap, roll back the clock to the time of the collision, update the velocities of the colliding particles, and continue the simulation.



t

t + dt

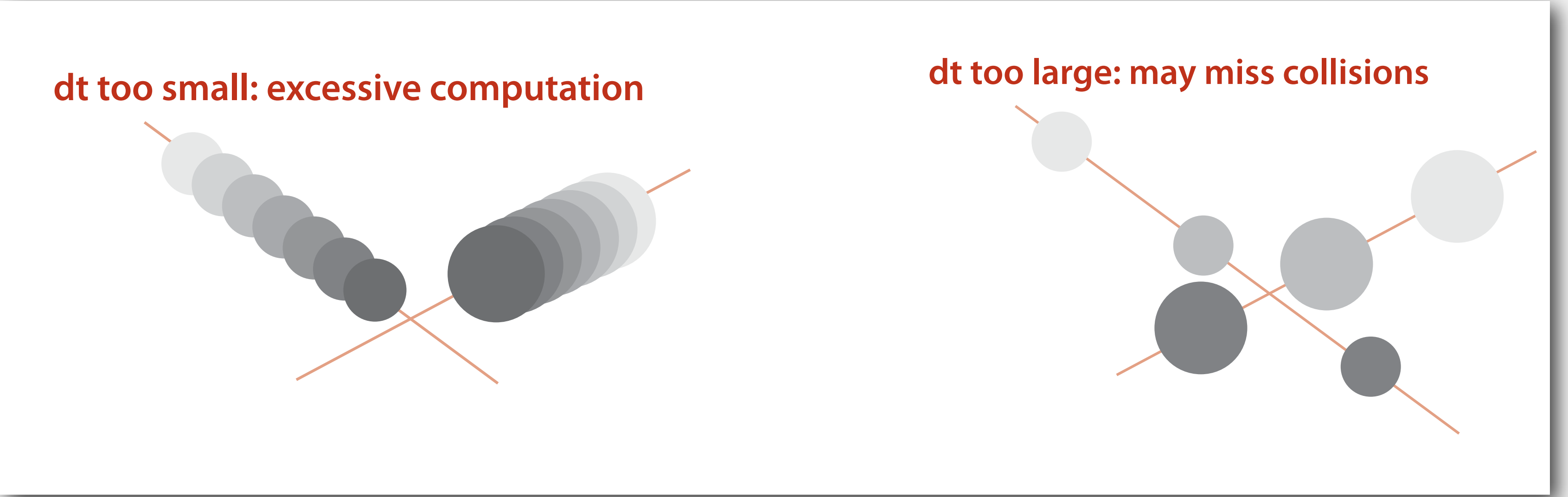
t + 2 dt
(collision detected)

t + Δt
(roll back clock)

Time-driven simulation

Main drawbacks.

- ~ $N^2 / 2$ overlap checks per time quantum.
- Simulation is too slow if dt is very small.
- May miss collisions if dt is too large.
  (if colliding particles fail to overlap when we are looking)



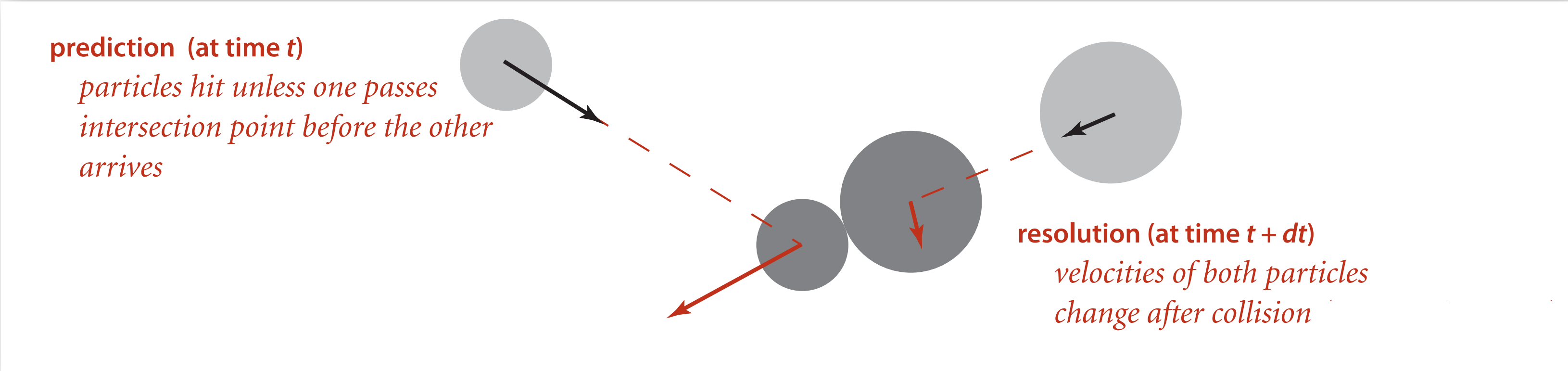
Event-driven simulation

Change state only when something happens.

- Between collisions, particles move in straight-line trajectories.
- Focus only on times when collisions occur.
- Maintain PQ of collision events, prioritized by time.
- Remove the min = get next collision.

Collision prediction. Given position, velocity, and radius of a particle, when will it collide next with a wall or another particle?

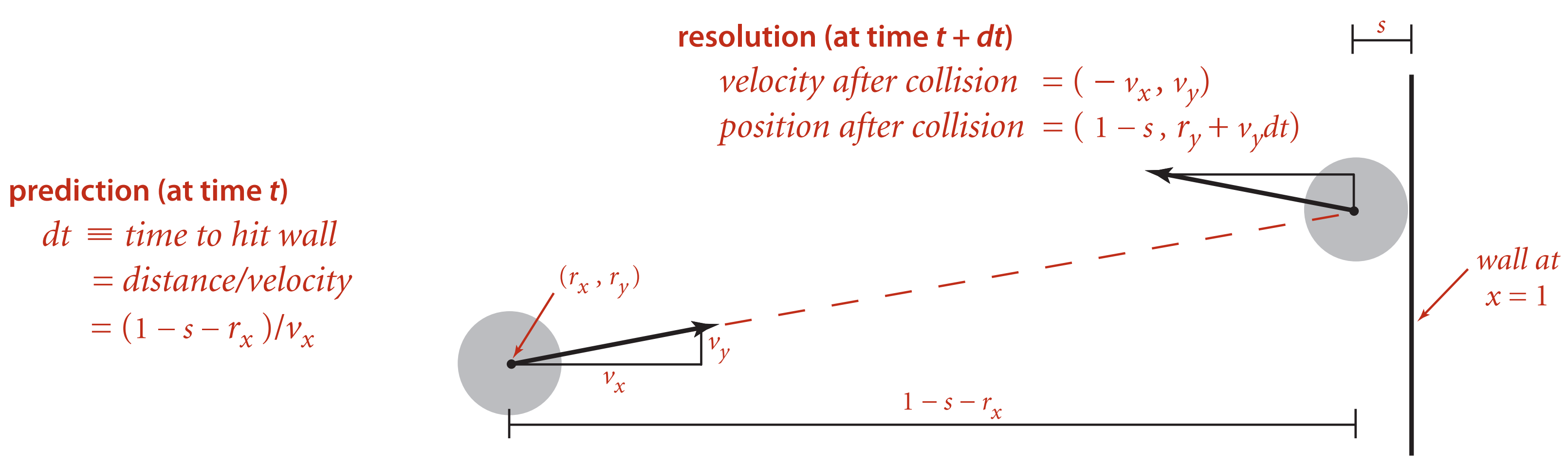
Collision resolution. If collision occurs, update colliding particle(s) according to laws of elastic collisions.



Particle-wall collision

Collision prediction and resolution.

- Particle of radius s at position (rx, ry).
- Particle moving in unit box with velocity (vx, vy).
- Will it collide with a vertical wall? If so, when?

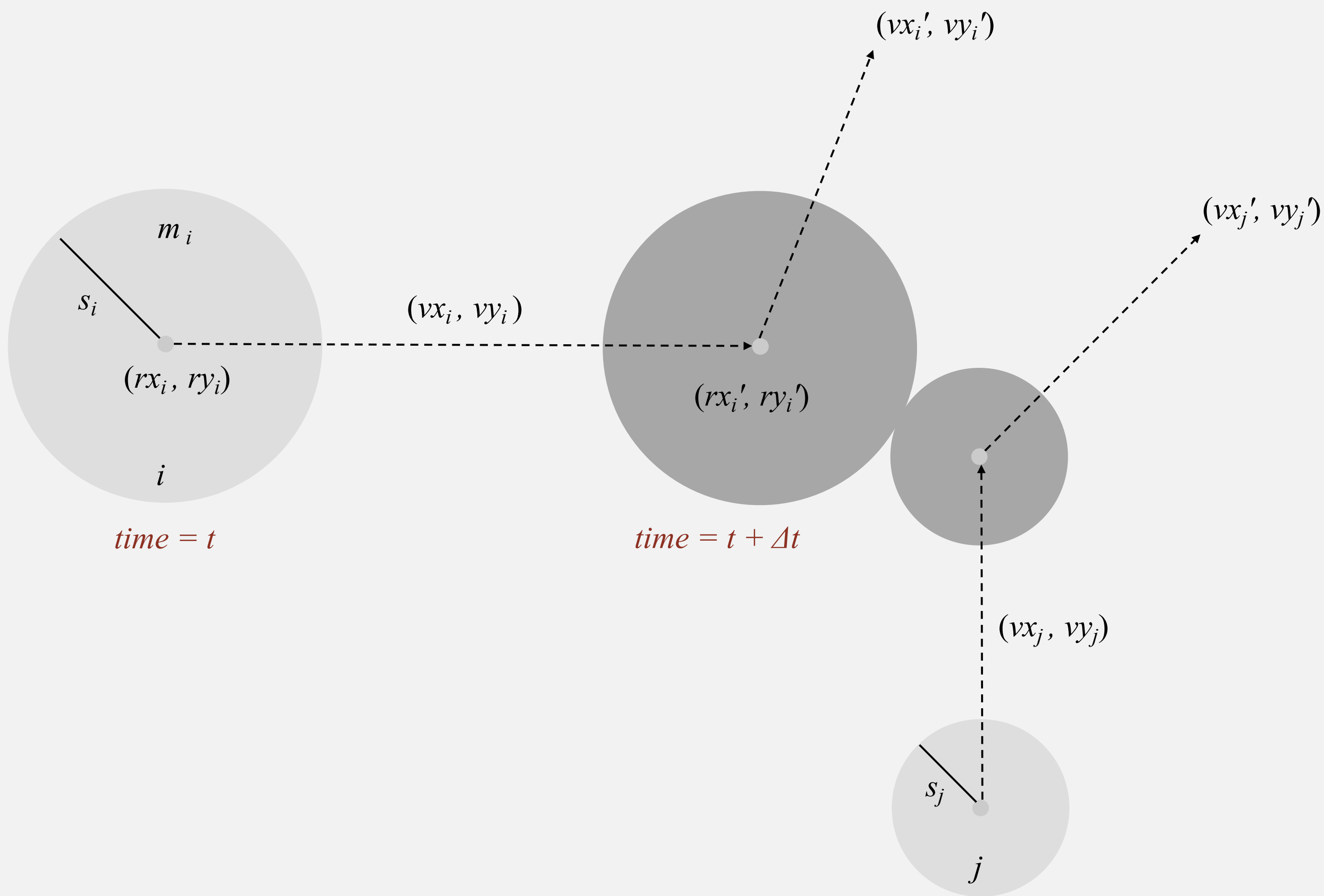


Predicting and resolving a particle-wall collision

Particle-particle collision prediction

Collision prediction.

- Particle i: radius s_i, position (rx_i, ry_i), velocity (vx_i, vy_i).
- Particle j: radius s_j, position (rx_j, ry_j), velocity (vx_j, vy_j).
- Will particles i and j collide? If so, when?



Particle-particle collision prediction

Collision prediction.

- Particle i: radius s_i, position (rx_i, ry_i), velocity (vx_i, vy_i).
- Particle j: radius s_j, position (rx_j, ry_j), velocity (vx_j, vy_j).
- Will particles i and j collide? If so, when?

$$\Delta t = \begin{cases} \infty & \text{if } \Delta v \cdot \Delta r \geq 0 \\ \infty & \text{if } d < 0 \\ -\dfrac{\Delta v \cdot \Delta r + \sqrt{d}}{\Delta v \cdot \Delta v} & \text{otherwise} \end{cases}$$

$$d = (\Delta v \cdot \Delta r)^2 - (\Delta v \cdot \Delta v)\,(\Delta r \cdot \Delta r - \sigma^2) \qquad \sigma = \sigma_i + \sigma_j$$

$$\Delta v = (\Delta vx,\ \Delta vy) = (vx_i - vx_j,\ vy_i - vy_j)$$
$$\Delta r = (\Delta rx,\ \Delta ry) = (rx_i - rx_j,\ ry_i - ry_j)$$

$$\Delta v \cdot \Delta v = (\Delta vx)^2 + (\Delta vy)^2$$
$$\Delta r \cdot \Delta r = (\Delta rx)^2 + (\Delta ry)^2$$
$$\Delta v \cdot \Delta r = (\Delta vx)(\Delta rx) + (\Delta vy)(\Delta ry)$$

Important note: This is high-school physics, so we won't be testing you on it!

Particle-particle collision resolution

Collision resolution. When two particles collide, how does velocity change?

$$
\begin{aligned}
vx_i' &= vx_i + Jx \,/\, m_i \\
vy_i' &= vy_i + Jy \,/\, m_i \\
vx_j' &= vx_j - Jx \,/\, m_j \\
vy_j' &= vy_j - Jy \,/\, m_j
\end{aligned}
$$

Newton's second law
(momentum form)

$$
Jx = \frac{J\,\Delta rx}{\sigma}, \quad Jy = \frac{J\,\Delta ry}{\sigma}, \quad J = \frac{2\,m_i\,m_j\,(\Delta v \cdot \Delta r)}{\sigma(m_i + m_j)}
$$

impulse due to normal force
(conservation of energy, conservation of momentum)

Important note: This is high-school physics, so we won't be testing you on it!

Particle data type skeleton

```
public class Particle
{
    private double rx, ry;        // position
    private double vx, vy;        // velocity
    private final double radius;  // radius
    private final double mass;    // mass
    private int count;            // number of collisions

    public Particle(...) { }

    public void move(double dt) { }
    public void draw()          { }

    public double timeToHit(Particle that)  { }
    public double timeToHitVerticalWall()   { }
    public double timeToHitHorizontalWall() { }

    public void bounceOff(Particle that)    { }
    public void bounceOffVerticalWall()     { }
    public void bounceOffHorizontalWall()   { }

}
```

predict collision with particle or wall

resolve collision with particle or wall

Particle-particle collision and resolution implementation

```
public double timeToHit(Particle that)
{
   if (this == that) return INFINITY;
   double dx  = that.rx - this.rx, dy  = that.ry - this.ry;
   double dvx = that.vx - this.vx; dvy = that.vy - this.vy;
   double dvdr = dx*dvx + dy*dvy;
   if( dvdr > 0) return INFINITY;
   double dvdv = dvx*dvx + dvy*dvy;
   double drdr = dx*dx + dy*dy;
   double sigma = this.radius + that.radius;
   double d = (dvdr*dvdr) - dvdv * (drdr - sigma*sigma);
   if (d < 0) return INFINITY;
   return -(dvdr + Math.sqrt(d)) / dvdv;
}
```

no collision

```
public void bounceOff(Particle that)
{
   double dx  = that.rx - this.rx, dy  = that.ry - this.ry;
   double dvx = that.vx - this.vx, dvy = that.vy - this.vy;
   double dvdr = dx*dvx + dy*dvy;
   double dist = this.radius + that.radius;
   double J = 2 * this.mass * that.mass * dvdr / ((this.mass + that.mass) * dist);
   double Jx = J * dx / dist;
   double Jy = J * dy / dist;
   this.vx += Jx / this.mass;
   this.vy += Jy / this.mass;
   that.vx -= Jx / that.mass;
   that.vy -= Jy / that.mass;
   this.count++;
   that.count++;
}
```

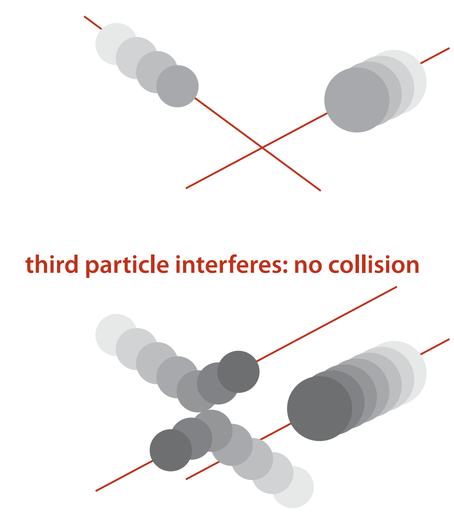
Important note: This is high-school physics, so we won't be testing you on it!

Collision system: event-driven simulation main loop

Initialization.

- Fill PQ with all potential particle-wall collisions.
- Fill PQ with all potential particle-particle collisions.

"potential" since collision may not happen if
some other collision intervenes



An invalidated event

Main loop.

- Delete the impending event from PQ (min priority = t).
- If the event has been invalidated, ignore it.
- Advance all particles to time t, on a straight-line trajectory.
- Update the velocities of the colliding particle(s).
- Predict future particle-wall and particle-particle collisions involving the colliding particle(s) and insert events onto PQ.

Event data type

Conventions.

- Neither particle `null` ⇒ particle-particle collision.
- One particle `null` ⇒ particle-wall collision.
- Both particles `null` ⇒ redraw event.

```
private class Event implements Comparable<Event>
{
    private double time;         // time of event
    private Particle a, b;       // particles involved in event
    private int countA, countB;  // collision counts for a and b

    public Event(double t, Particle a, Particle b) { }

    public int compareTo(Event that)
    {   return this.time - that.time;   }

    public boolean isValid()
    {   }
}
```

create event

ordered by time

invalid if intervening collision

Collision system implementation: skeleton

```
public class CollisionSystem
{
    private MinPQ<Event> pq;          // the priority queue
    private double t  = 0.0;          // simulation clock time
    private Particle[] particles;     // the array of particles

    public CollisionSystem(Particle[] particles) { }

    private void predict(Particle a)
    {
       if (a == null) return;
       for (int i = 0; i < N; i++)
       {
          double dt = a.timeToHit(particles[i]);
          pq.insert(new Event(t + dt, a, particles[i]));
       }
       pq.insert(new Event(t + a.timeToHitVerticalWall()  , a, null));
       pq.insert(new Event(t + a.timeToHitHorizontalWall(), null, a));
 }

    private void redraw()  { }

    public void simulate() {  /* see next slide */  }
}
```

add to PQ all particle-wall and particle-particle collisions involving this particle

Collision system implementation: main event-driven simulation loop

```
public void simulate()
{
   pq = new MinPQ<Event>();
   for(int i = 0; i < N; i++) predict(particles[i]);
   pq.insert(new Event(0, null, null));

   while(!pq.isEmpty())
   {
      Event event = pq.delMin();
      if(!event.isValid()) continue;
      Particle a = event.a;
      Particle b = event.b;

      for(int i = 0; i < N; i++)
         particles[i].move(event.time - t);
      t = event.time;

      if      (a != null && b != null) a.bounceOff(b);
      else if (a != null && b == null) a.bounceOffVerticalWall()
      else if (a == null && b != null) b.bounceOffHorizontalWall();
      else if (a == null && b == null) redraw();

      predict(a);
      predict(b);
   }
}
```

initialize PQ with collision events and redraw event

get next event

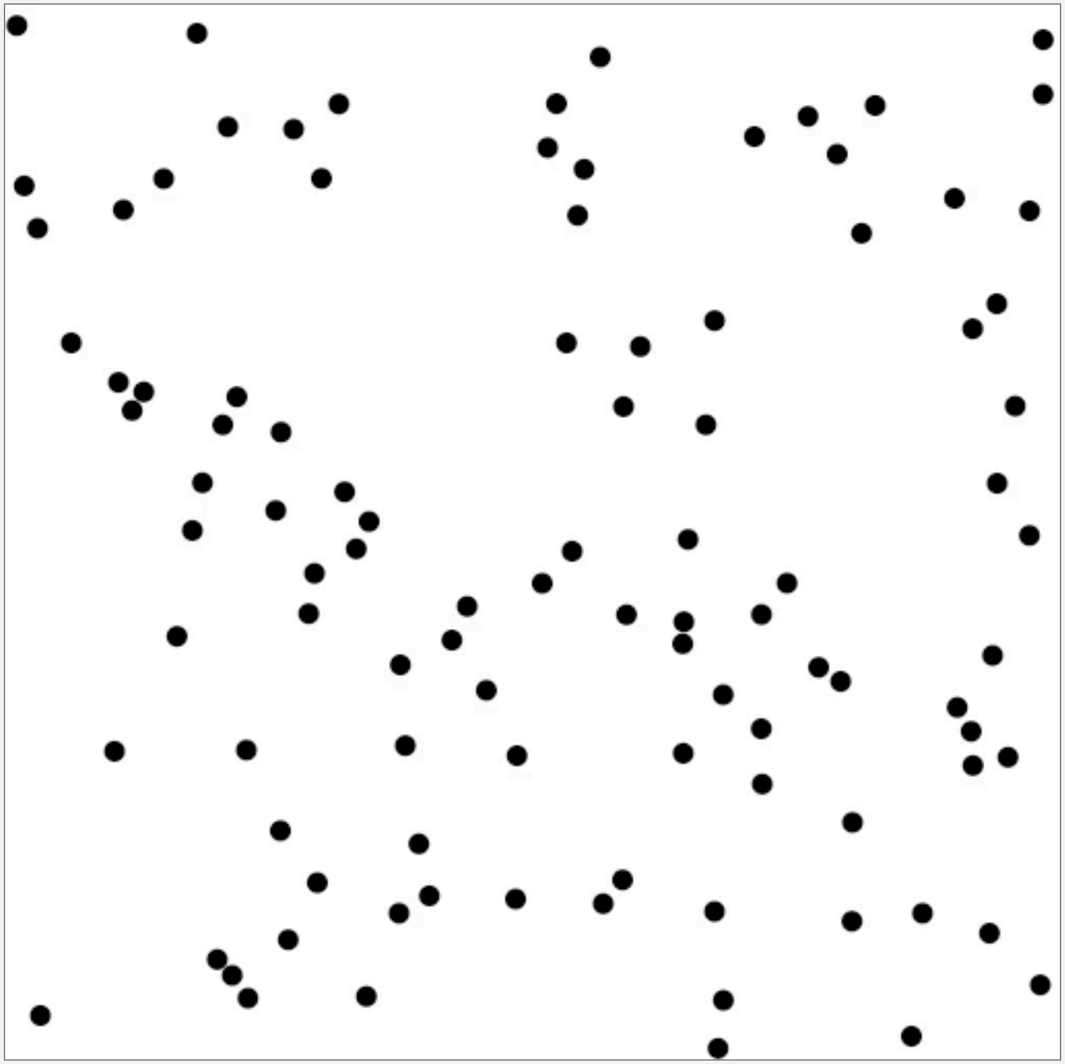
update positions and time

process event

predict new events based on changes

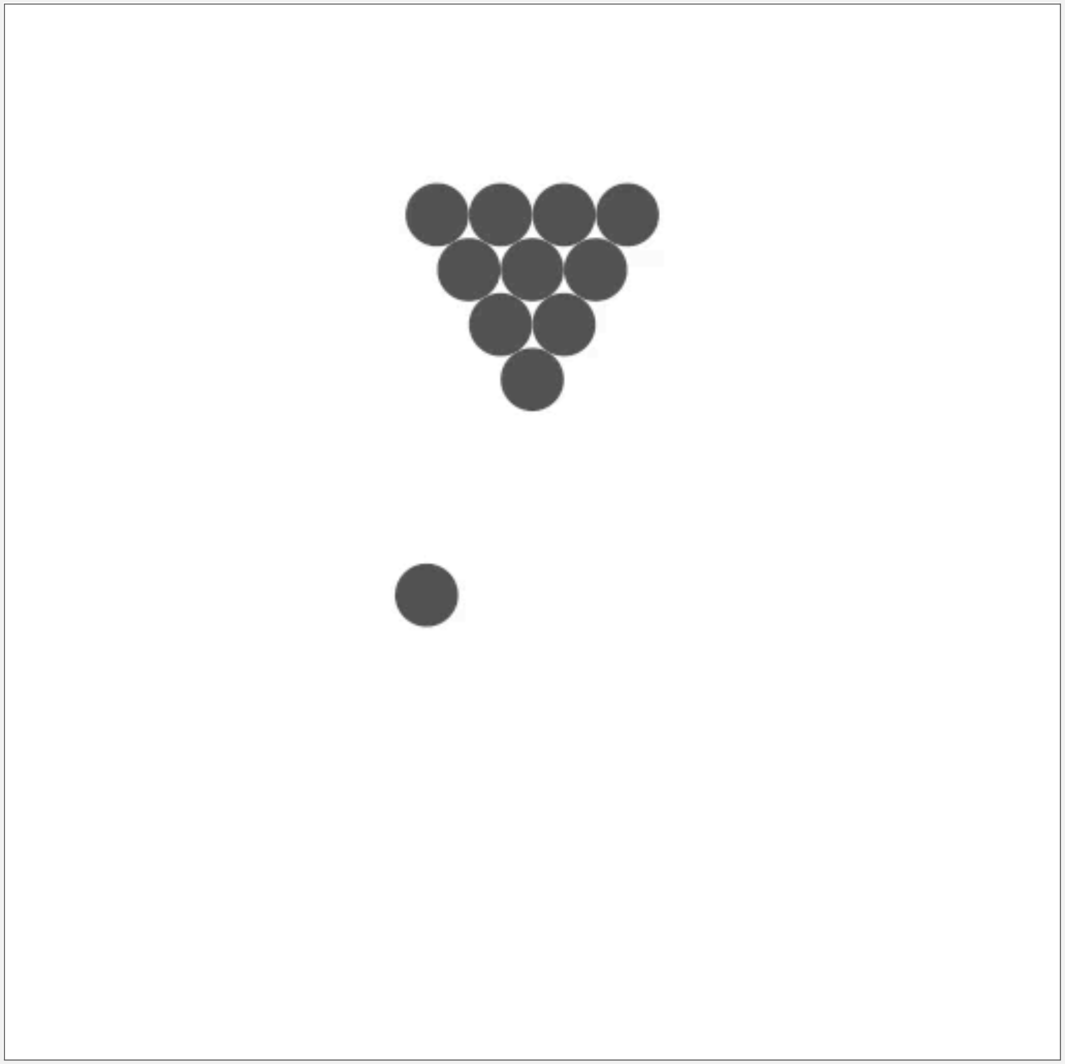
Particle collision simulation example 1

```
% java CollisionSystem 100
```



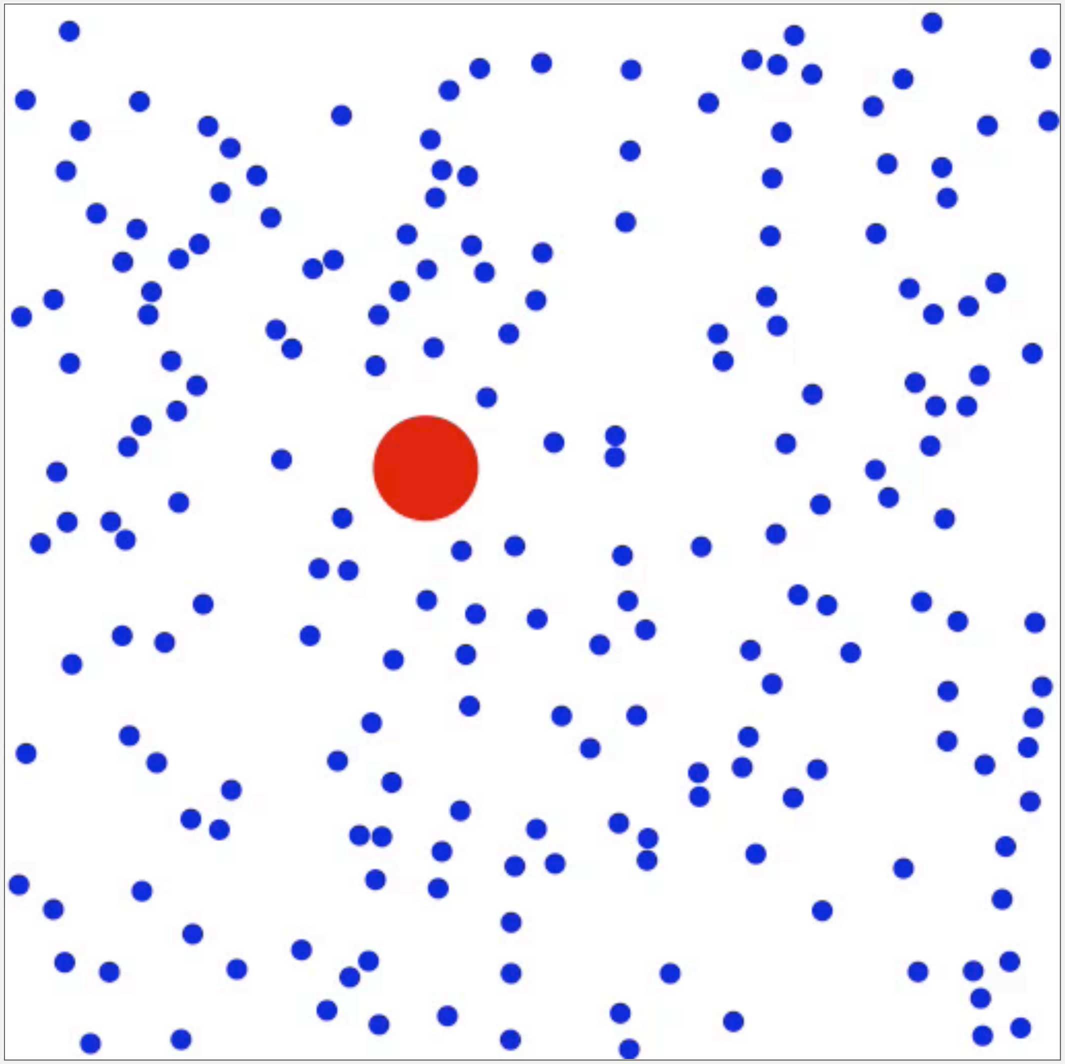
Particle collision simulation example 2

```
% java CollisionSystem < billiards.txt
```



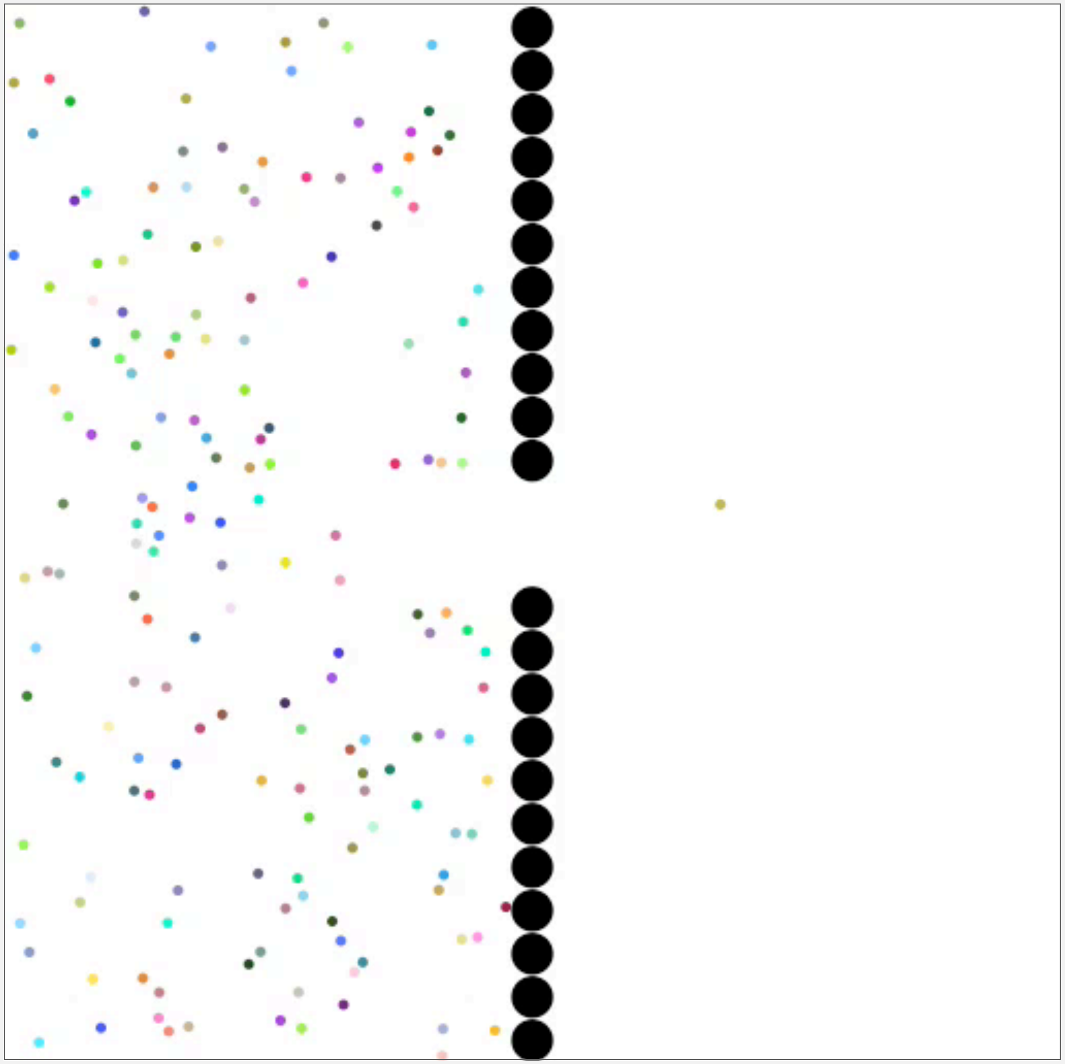
Particle collision simulation example 3

```
% java CollisionSystem < brownian.txt
```



Particle collision simulation example 4

```
% java CollisionSystem < diffusion.txt
```



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2.4 PRIORITY QUEUES

- API and elementary implementations
- binary heaps
- heapsort
- *event-driven simulation*

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2.4 Priority Queues

- *API and elementary implementations*
- *binary heaps*
- *heapsort*
- *event-driven simulation*

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3.1 SYMBOL TABLES

- *API*
- *elementary implementations*
- *ordered operations*

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3.1 Symbol Tables

- *API*
- *elementary implementations*
- *ordered operations*

Symbol tables

Key-value pair abstraction.

- Insert a value with specified key.
- Given a key, search for the corresponding value.

Ex. DNS lookup.

- Insert domain name with specified IP address.
- Given domain name, find corresponding IP address.

domain name	IP address
www.cs.princeton.edu	128.112.136.11
www.princeton.edu	128.112.128.15
www.yale.edu	130.132.143.21
www.harvard.edu	128.103.060.55
www.simpsons.com	209.052.165.60

key

value

Symbol table applications

application	purpose of search	key	value
dictionary	find definition	word	definition
book index	find relevant pages	term	list of page numbers
file share	find song to download	name of song	computer ID
financial account	process transactions	account number	transaction details
web search	find relevant web pages	keyword	list of page names
compiler	find properties of variables	variable name	type and value
routing table	route Internet packets	destination	best route
DNS	find IP address	domain name	IP address
reverse DNS	find domain name	IP address	domain name
genomics	find markers	DNA string	known positions
file system	find file on disk	filename	location on disk

Basic symbol table API

Associative array abstraction. Associate one value with each key.

`public class ST<Key, Value>`

	`ST()`	*create a symbol table*	
`void`	`put(Key key, Value val)`	*put key-value pair into the table (remove* `key` *from table if value is* `null`*)*	← `a[key] = val;`
`Value`	`get(Key key)`	*value paired with* `key` *(*`null` *if* `key` *is absent)*	← `a[key]`
`void`	`delete(Key key)`	*remove* `key` *(and its value) from table*	
`boolean`	`contains(Key key)`	*is there a value paired with* `key`*?*	
`boolean`	`isEmpty()`	*is the table empty?*	
`int`	`size()`	*number of key-value pairs in the table*	
`Iterable<Key>`	`keys()`	*all the keys in the table*	

Conventions

- Values are not `null`.
- Method `get()` returns `null` if key not present.
- Method `put()` overwrites old value with new value.

Intended consequences.

- Easy to implement `contains()`.

```
public boolean contains(Key key)
{  return get(key) != null;  }
```

- Can implement lazy version of `delete()`.

```
public void delete(Key key)
{  put(key, null);  }
```

Keys and values

Value type. Any generic type.

specify Comparable in API.

Key type: several natural assumptions.

- Assume keys are `Comparable`, use `compareTo()`.
- Assume keys are any generic type, use `equals()` to test equality.
- Assume keys are any generic type, use `equals()` to test equality; use `hashCode()` to scramble key.

built-in to Java
(stay tuned)

Best practices. Use immutable types for symbol table keys.

- Immutable in Java: `Integer`, `Double`, `String`, `java.io.File`, …
- Mutable in Java: `StringBuilder`, `java.net.URL`, arrays, ...

Equality test

All Java classes inherit a method `equals()`.

Java requirements. For any references `x`, `y` and `z`:

- Reflexive: `x.equals(x)` is `true`.
- Symmetric: `x.equals(y)` iff `y.equals(x)`.
- Transitive: if `x.equals(y)` and `y.equals(z)`, then `x.equals(z)`.
- Non-null: `x.equals(null)` is `false`.

equivalence relation

do x and y refer to the same object?

Default implementation. `(x == y)`

Customized implementations. `Integer`, `Double`, `String`, `java.io.File`, …

User-defined implementations. Some care needed.

Implementing equals for user-defined types

Seems easy.

```
public       class Date implements Comparable<Date>
{
   private final int month;
   private final int day;
   private final int year;
   ...

   public boolean equals(Date that)
   {






      if (this.day   != that.day  ) return false;
      if (this.month != that.month) return false;
      if (this.year  != that.year ) return false;
      return true;
   }
}
```

check that all significant fields are the same

Implementing equals for user-defined types

Seems easy, but requires some care.

typically unsafe to use equals() with inheritance (would violate symmetry)

```
public final class Date implements Comparable<Date>
{
   private final int month;
   private final int day;
   private final int year;
   ...

   public boolean equals(Object y)
   {
      if (y == this) return true;

      if (y == null) return false;

      if (y.getClass() != this.getClass())
         return false;

      Date that = (Date) y;
      if (this.day   != that.day  ) return false;
      if (this.month != that.month) return false;
      if (this.year  != that.year ) return false;
      return true;
   }
}
```

must be Object.
Why? Experts still debate.

optimize for true object equality

check for null

objects must be in the same class (religion: getClass() vs. instanceof)

cast is guaranteed to succeed

check that all significant fields are the same

Equals design

"Standard" recipe for user-defined types.

- Optimization for reference equality.
- Check against `null`.
- Check that two objects are of the same type and cast.
- Compare each significant field:
  - if field is a primitive type, use ==
  - if field is an object, use `equals()` ← apply rule recursively
  - if field is an array, apply to each entry ← alternatively, use `Arrays.equals(a, b)` or `Arrays.deepEquals(a, b)`, but not `a.equals(b)`

Best practices.

- No need to use calculated fields that depend on other fields.
- Compare fields mostly likely to differ first.
- Make `compareTo()` consistent with `equals()`.

`x.equals(y)` if and only if `(x.compareTo(y) == 0)`

ST test client for traces

Build ST by associating value i with i^{th} string from standard input.

```
public static void main(String[] args)
{
   ST<String, Integer> st = new ST<String, Integer>();
   for (int i = 0; !StdIn.isEmpty(); i++)
   {
     String key = StdIn.readString();
     st.put(key, i);
   }
   for (String s : st.keys())
      StdOut.println(s + " " + st.get(s));
}
```

keys	S	E	A	R	C	H	E	X	A	M	P	L	E
values	0	1	2	3	4	5	6	7	8	9	10	11	12

output

```
A  8
C  4
E  12
H  5
L  11
M  9
P  10
R  3
S  0
X  7
```

ST test client for analysis

Frequency counter. Read a sequence of strings from standard input and print out one that occurs with highest frequency.

```
% more tinyTale.txt
it was the best of times
it was the worst of times
it was the age of wisdom
it was the age of foolishness
it was the epoch of belief
it was the epoch of incredulity
it was the season of light
it was the season of darkness
it was the spring of hope
it was the winter of despair

% java FrequencyCounter 1 < tinyTale.txt
it 10

% java FrequencyCounter 8 < tale.txt
business 122

% java FrequencyCounter 10 < leipzig1M.txt
government 24763
```

tiny example (60 words, 20 distinct)

real example (135,635 words, 10,769 distinct)

real example (21,191,455 words, 534,580 distinct)

Frequency counter implementation

```
public class FrequencyCounter
{
   public static void main(String[] args)
   {
      int minlen = Integer.parseInt(args[0]);
      ST<String, Integer> st = new ST<String, Integer>();
      while (!StdIn.isEmpty())
      {
         String word = StdIn.readString();
         if (word.length() < minlen) continue;
         if (!st.contains(word)) st.put(word, 1);
         else                    st.put(word, st.get(word) + 1);
      }
      String max = "";
      st.put(max, 0);
      for (String word : st.keys())
         if (st.get(word) > st.get(max))
            max = word;
      StdOut.println(max + " " + st.get(max));
   }
}
```

create ST

ignore short strings

read string and update frequency

print a string with max freq

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3.1 Symbol Tables

- *API*
- *elementary implementations*
- *ordered operations*

3.1 Symbol Tables

- API
- *elementary implementations*
- ordered operations

Algorithms

Robert Sedgewick | Kevin Wayne

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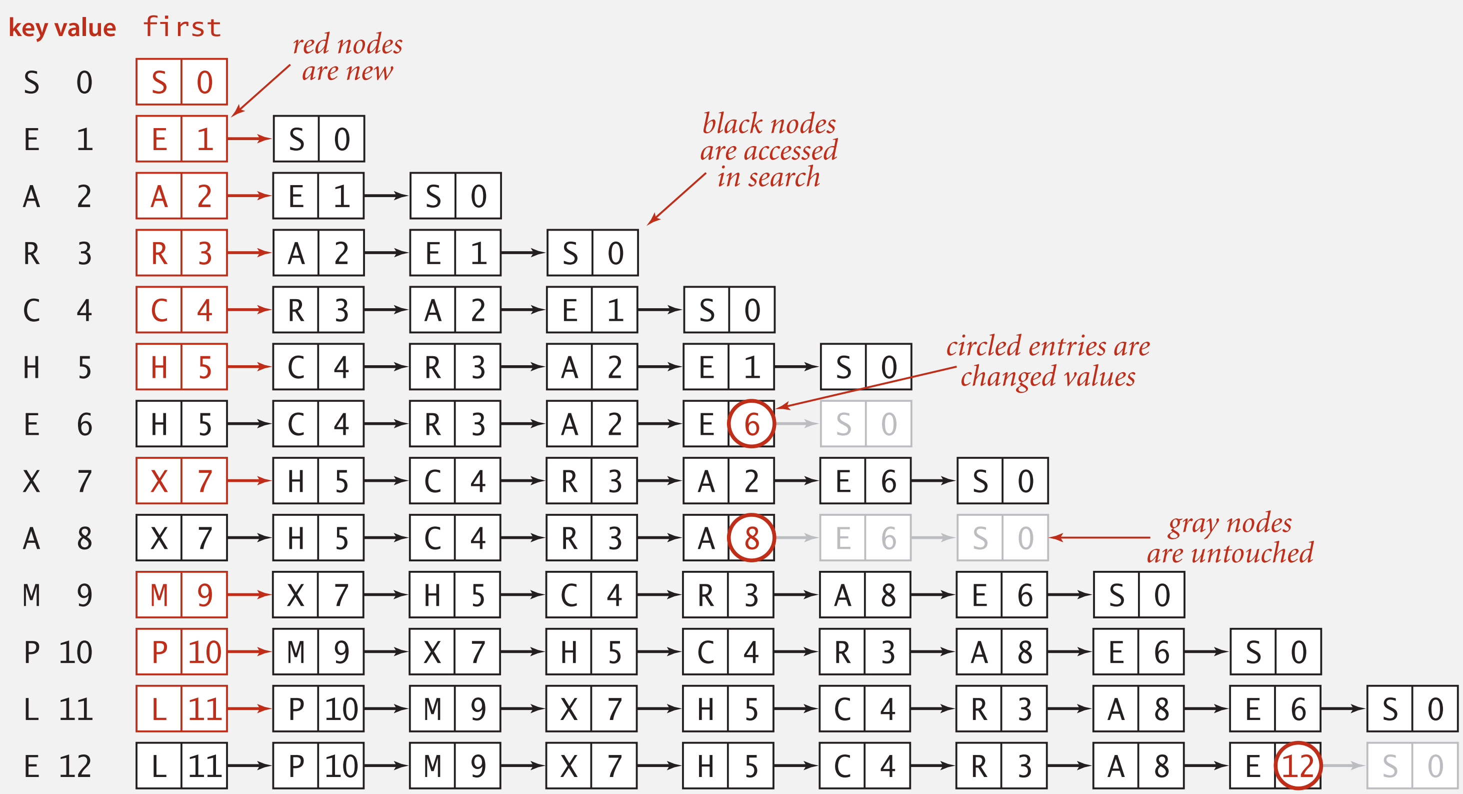
Sequential search in a linked list

Data structure. Maintain an (unordered) linked list of key-value pairs.

Search. Scan through all keys until find a match.

Insert. Scan through all keys until find a match; if no match add to front.



Trace of linked-list ST implementation for standard indexing client

Elementary ST implementations: summary

ST implementation	worst-case cost (after N inserts)		average case (after N random inserts)		ordered iteration?	key interface
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	N / 2	N	no	`equals()`

Challenge. Efficient implementations of both search and insert.

Binary search in an ordered array

Data structure. Maintain an ordered array of key-value pairs.

Rank helper function. How many keys < k ?

keys[]

successful search for P

lo	hi	m	0	1	2	3	4	5	6	7	8	9
0	9	4	A	C	E	H	L	M	P	R	S	X
5	9	7	A	C	E	H	L	M	P	R	S	X
5	6	5	A	C	E	H	L	M	P	R	S	X
6	6	6	A	C	E	H	L	M	P	R	S	X

entries in black are `a[lo..hi]`

entry in red is `a[m]`

loop exits with `keys[m] = P`: *return* 6

unsuccessful search for Q

lo	hi	m	0	1	2	3	4	5	6	7	8	9
0	9	4	A	C	E	H	L	M	P	R	S	X
5	9	7	A	C	E	H	L	M	P	R	S	X
5	6	5	A	C	E	H	L	M	P	R	S	X
7	6	6	A	C	E	H	L	M	P	R	S	X

loop exits with `lo > hi`: *return* 7

Trace of binary search for rank in an ordered array

Binary search: Java implementation

```
public Value get(Key key)
{
   if (isEmpty()) return null;
   int i = rank(key);
   if (i < N && keys[i].compareTo(key) == 0) return vals[i];
   else return null;
}
```

```
private int rank(Key key)                          number of keys < key
{
   int lo = 0, hi = N-1;
   while (lo <= hi)
   {
       int mid = lo + (hi - lo) / 2;
       int cmp = key.compareTo(keys[mid]);
       if      (cmp  < 0) hi = mid - 1;
       else if (cmp  > 0) lo = mid + 1;
       else if (cmp == 0) return mid;
  }
  return lo;
}
```

Binary search: trace of standard indexing client

Problem. To insert, need to shift all greater keys over.

		keys[]											vals[]									
key	value	0	1	2	3	4	5	6	7	8	9	N	0	1	2	3	4	5	6	7	8	9
S	0	S										1	0									
E	1	E	S									2	1	0								
A	2	A	E	S								3	2	1	0							
R	3	A	E	R	S							4	2	1	3	0						
C	4	A	C	E	R	S						5	2	4	1	3	0					
H	5	A	C	E	H	R	S					6	2	4	1	5	3	0				
E	6	A	C	E	H	R	S					6	2	4	6	5	3	0				
X	7	A	C	E	H	R	S	X				7	2	4	6	5	3	0	7			
A	8	A	C	E	H	R	S	X				7	8	4	6	5	3	0	7			
M	9	A	C	E	H	M	R	S	X			8	8	4	6	5	9	3	0	7		
P	10	A	C	E	H	M	P	R	S	X		9	8	4	6	5	9	10	3	0	7	
L	11	A	C	E	H	L	M	P	R	S	X	10	8	4	6	5	11	9	10	3	0	7
E	12	A	C	E	H	L	M	P	R	S	X	10	8	4	12	5	11	9	10	3	0	7
		A	C	E	H	L	M	P	R	S	X		8	4	12	5	11	9	10	3	0	7

entries in red were inserted

entries in gray did not move

entries in black moved to the right

circled entries are changed values

Elementary ST implementations: summary

ST implementation	worst-case cost (after N inserts)		average case (after N random inserts)		ordered iteration?	key interface
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	N / 2	N	no	`equals()`
binary search (ordered array)	log N	N	log N	N / 2	yes	`compareTo()`

Challenge. Efficient implementations of both search and insert.

Algorithms

Robert Sedgewick | Kevin Wayne

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3.1 Symbol Tables

- API
- *elementary implementations*
- ordered operations

Algorithms

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3.1 Symbol Tables

- API
- elementary implementations
- ordered operations

Examples of ordered symbol table API

	keys	*values*
`min()`	09:00:00	Chicago
	09:00:03	Phoenix
`get(09:00:13)`	09:00:13	Houston
	09:00:59	Chicago
	09:01:10	Houston
`floor(09:05:00)`	09:03:13	Chicago
	09:10:11	Seattle
`select(7)`	09:10:25	Seattle
	09:14:25	Phoenix
	09:19:32	Chicago
	09:19:46	Chicago
`keys(09:15:00, 09:25:00)`	09:21:05	Chicago
	09:22:43	Seattle
	09:22:54	Seattle
	09:25:52	Chicago
`ceiling(09:30:00)`	09:35:21	Chicago
	09:36:14	Seattle
`max()`	09:37:44	Phoenix

`size(09:15:00, 09:25:00)` *is* 5

`rank(09:10:25)` *is* 7

Ordered symbol table API

`public class ST<Key extends Comparable<Key>, Value>`

	`ST()`	*create an ordered symbol table*
`void`	`put(Key key, Value val)`	*put key-value pair into the table (remove* `key` *from table if value is* `null`*)*
`Value`	`get(Key key)`	*value paired with* `key` *(*`null` *if* `key` *is absent)*
`void`	`delete(Key key)`	*remove* `key` *(and its value) from table*
`boolean`	`contains(Key key)`	*is there a value paired with* `key`*?*
`boolean`	`isEmpty()`	*is the table empty?*
`int`	`size()`	*number of key-value pairs*
`Key`	`min()`	*smallest key*
`Key`	`max()`	*largest key*
`Key`	`floor(Key key)`	*largest key less than or equal to* `key`
`Key`	`ceiling(Key key)`	*smallest key greater than or equal to* `key`
`int`	`rank(Key key)`	*number of keys less than* `key`
`Key`	`select(int k)`	*key of rank* `k`
`void`	`deleteMin()`	*delete smallest key*
`void`	`deleteMax()`	*delete largest key*
`int`	`size(Key lo, Key hi)`	*number of keys in* `[lo..hi]`
`Iterable<Key>`	`keys(Key lo, Key hi)`	*keys in* `[lo..hi]`*, in sorted order*
`Iterable<Key>`	`keys()`	*all keys in the table, in sorted order*

Binary search: ordered symbol table operations summary

	sequential search	binary search
search	N	lg N
insert / delete	N	N
min / max	N	1
floor / ceiling	N	lg N
rank	N	lg N
select	N	1
ordered iteration	N lg N	N

order of growth of the running time for ordered symbol table operations

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3.1 Symbol Tables

- *API*
- *elementary implementations*
- *ordered operations*

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3.1 SYMBOL TABLES

- *API*
- *elementary implementations*
- *ordered operations*

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3.2 BINARY SEARCH TREES

- *BSTs*
- *ordered operations*
- *deletion*

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3.2 BINARY SEARCH TREES

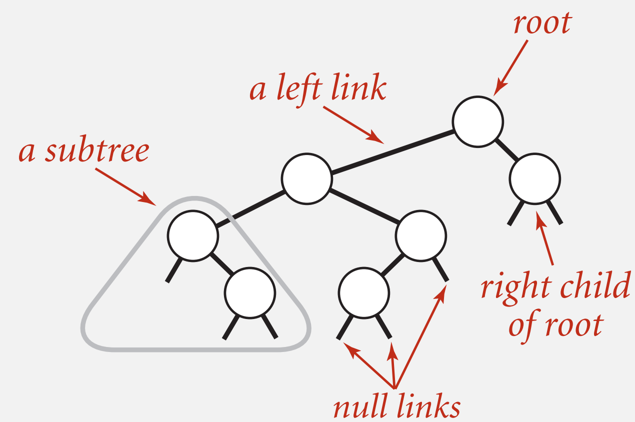
- *BSTs*
- *ordered operations*
- *deletion*

Binary search trees

Definition. A BST is a binary tree in symmetric order.

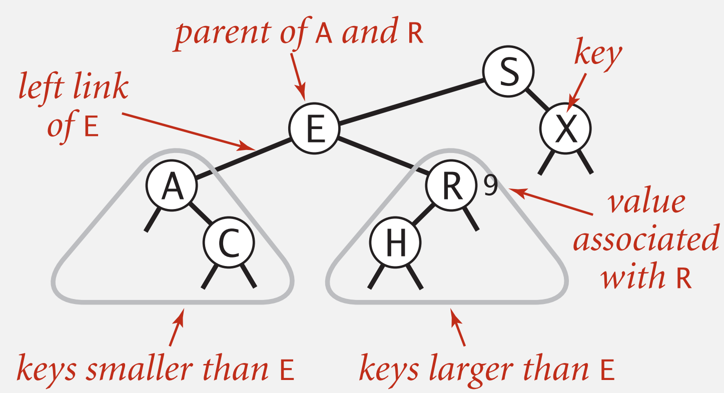
A binary tree is either:

- Empty.
- Two disjoint binary trees (left and right).



Symmetric order. Each node has a key, and every node's key is:

- Larger than all keys in its left subtree.
- Smaller than all keys in its right subtree.



BST representation in Java

Java definition. A BST is a reference to a root `Node`.

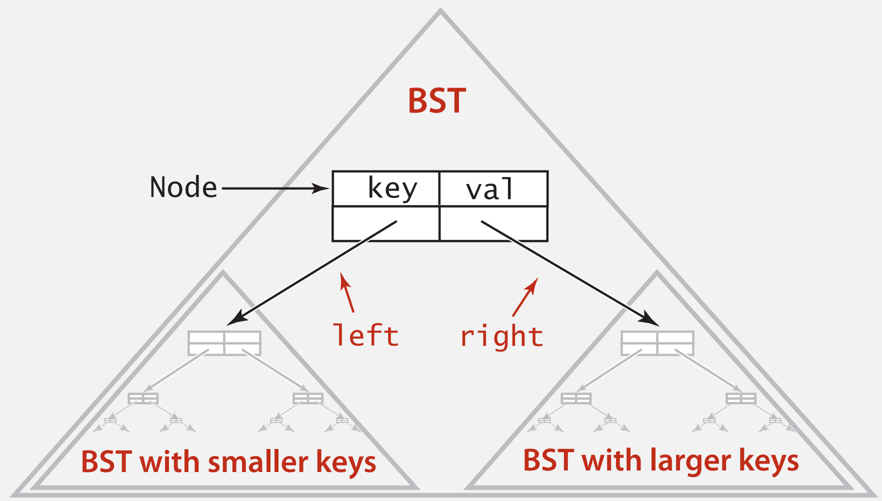
A `Node` is comprised of four fields:

- A `Key` and a `Value`.
- A reference to the left and right subtree.

smaller keys larger keys

```
private class Node
{
   private Key key;
   private Value val;
   private Node left, right;
   public Node(Key key, Value val)
   {
      this.key = key;
      this.val = val;
   }
}
```

Key and Value are generic types; Key is Comparable



Binary search tree

BST implementation (skeleton)

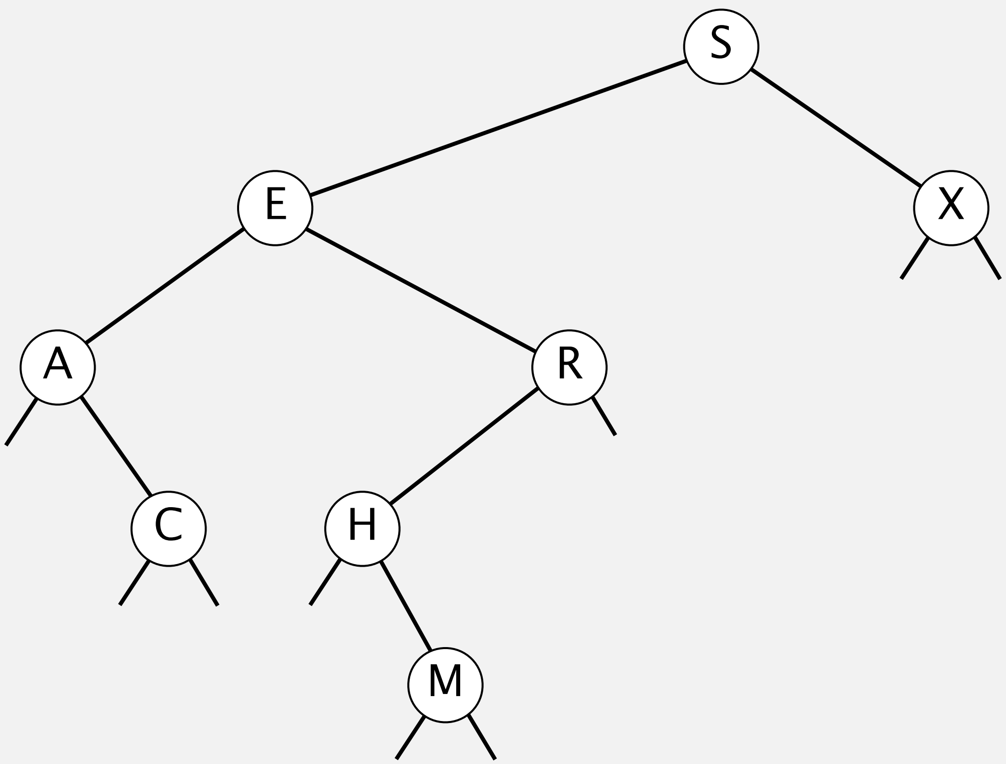
```
public class BST<Key extends Comparable<Key>, Value>
{
    private Node root;

    private class Node
    {  /* see previous slide */  }

    public void put(Key key, Value val)
    {  /* see next slides */  }

    public Value get(Key key)
    {  /* see next slides */  }

    public void delete(Key key)
    {  /* see next slides */  }

    public Iterable<Key> iterator()
    {  /* see next slides */  }

}
```

root of BST

Binary search tree demo

Search. If less, go left; if greater, go right; if equal, search hit.

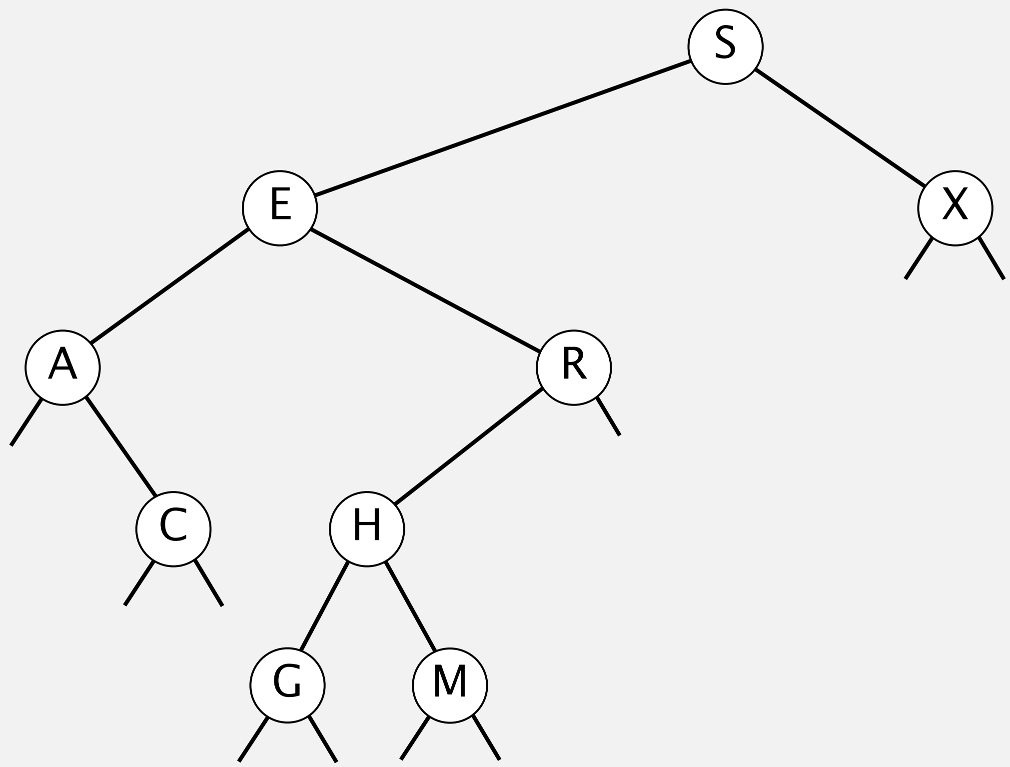
successful search for H



Binary search tree demo

Insert. If less, go left; if greater, go right; if null, insert.

insert G



BST search: Java implementation

Get. Return value corresponding to given key, or `null` if no such key.

```
public Value get(Key key)
{
   Node x = root;
   while (x != null)
   {
      int cmp = key.compareTo(x.key);
      if      (cmp  < 0) x = x.left;
      else if (cmp  > 0) x = x.right;
      else if (cmp == 0) return x.val;
   }
   return null;
}
```

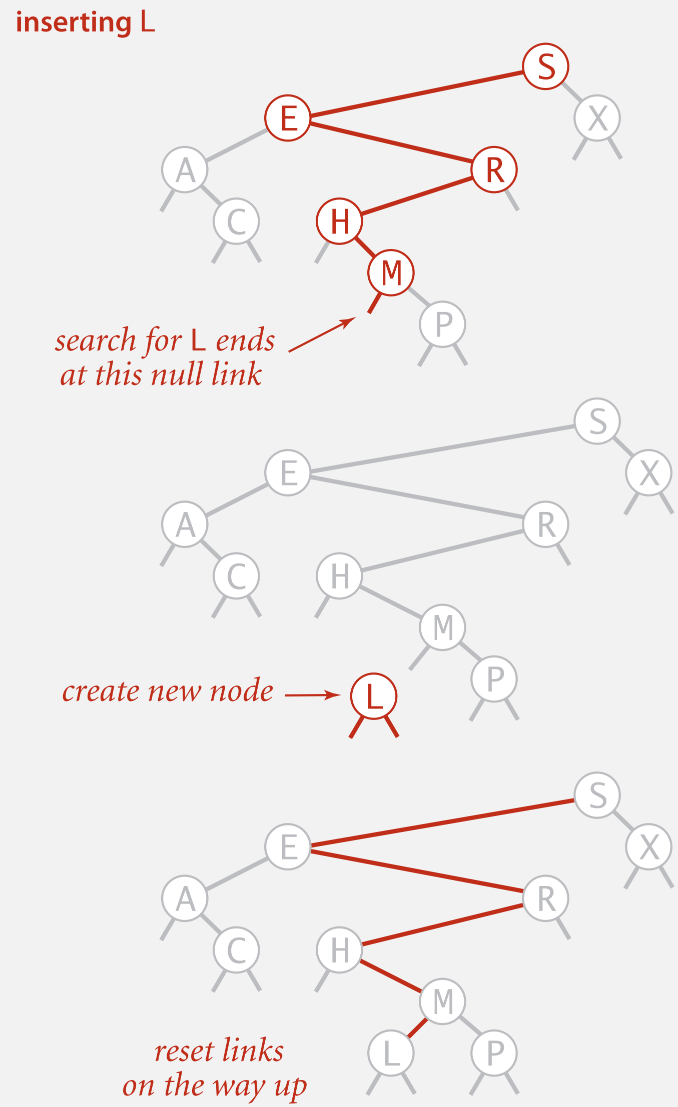
Cost. Number of compares is equal to 1 + depth of node.

BST insert

Put. Associate value with key.

Search for key, then two cases:

- Key in tree $\Rightarrow$ reset value.
- Key not in tree $\Rightarrow$ add new node.



Insertion into a BST

BST insert: Java implementation

Put. Associate value with key.

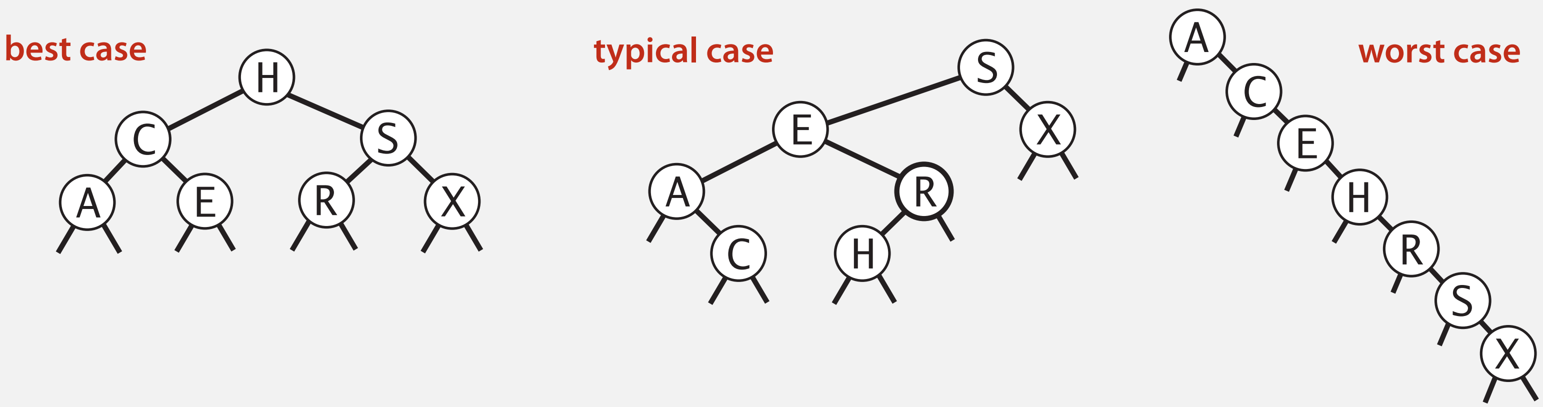
concise, but tricky, recursive code; read carefully!

```
public void put(Key key, Value val)
{  root = put(root, key, val);  }

private Node put(Node x, Key key, Value val)
{
   if (x == null) return new Node(key, val);
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0)
      x.left  = put(x.left,  key, val);
   else if (cmp  > 0)
      x.right = put(x.right, key, val);
   else if (cmp == 0)
      x.val = val;
   return x;
}
```

Cost. Number of compares is equal to 1 + depth of node.

Tree shape

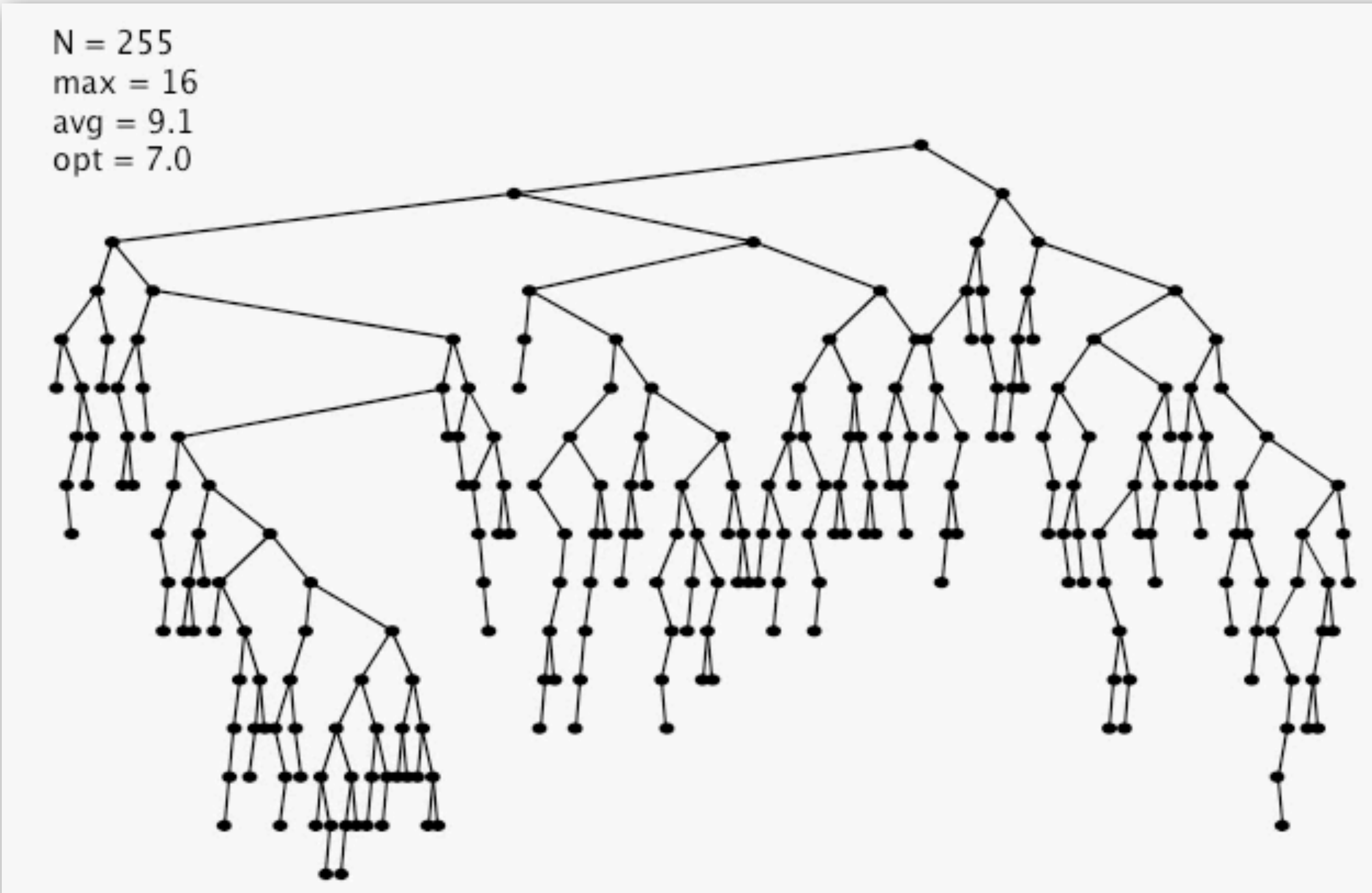
- Many BSTs correspond to same set of keys.
- Number of compares for search/insert is equal to 1 + depth of node.



Remark. Tree shape depends on order of insertion.

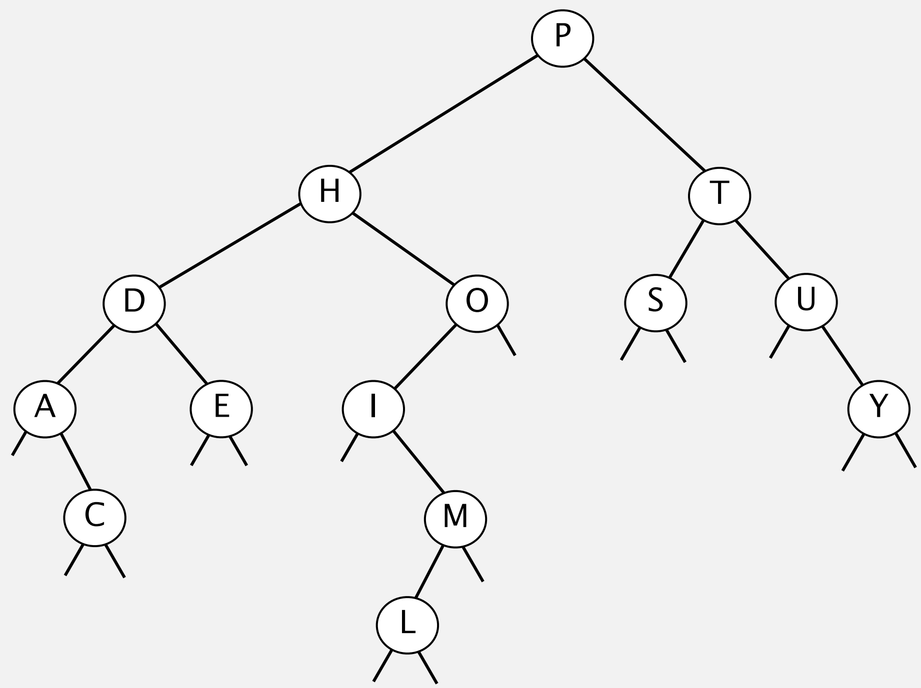
BST insertion: random order visualization

Ex. Insert keys in random order.



Correspondence between BSTs and quicksort partitioning

0	1	2	3	4	5	6	7	8	9	10	11	12	13
P	S	E	U	D	O	M	Y	T	H	I	C	A	L
P	S	E	U	D	O	M	Y	T	H	I	C	A	L
H	L	E	A	D	O	M	C	I	P	T	Y	U	S
D	C	E	A	H	O	M	L	I	P	T	Y	U	S
A	C	D	E	H	O	M	L	I	P	T	Y	U	S
A	C	D	E	H	O	M	L	I	P	T	Y	U	S
A	C	D	E	H	O	M	L	I	P	T	Y	U	S
A	C	D	E	H	O	M	L	I	P	T	Y	U	S
A	C	D	E	H	I	M	L	O	P	T	Y	U	S
A	C	D	E	H	I	M	L	O	P	T	Y	U	S
A	C	D	E	H	I	L	M	O	P	T	Y	U	S
A	C	D	E	H	I	L	M	O	P	T	Y	U	S
A	C	D	E	H	I	L	M	O	P	S	T	U	Y
A	C	D	E	H	I	L	M	O	P	S	T	U	Y
A	C	D	E	H	I	L	M	O	P	S	T	U	Y
A	C	D	E	H	I	L	M	O	P	S	T	U	Y
A	C	D	E	H	I	L	M	O	P	S	T	U	Y



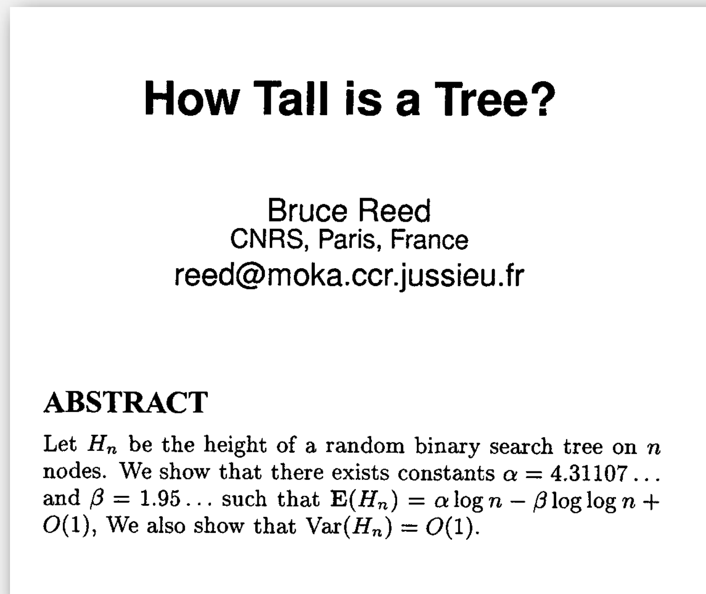
Remark. Correspondence is 1-1 if array has no duplicate keys.

BSTs: mathematical analysis

Proposition. If N distinct keys are inserted into a BST in random order, the expected number of compares for a search/insert is $\sim 2 \ln N$.

Pf. 1-1 correspondence with quicksort partitioning.

Proposition. [Reed, 2003] If N distinct keys are inserted in random order, expected height of tree is $\sim 4.311 \ln N$.



How Tall is a Tree?

Bruce Reed
CNRS, Paris, France
reed@moka.ccr.jussieu.fr

ABSTRACT

Let H_n be the height of a random binary search tree on n nodes. We show that there exists constants $\alpha = 4.31107\ldots$ and $\beta = 1.95\ldots$ such that $\mathbf{E}(H_n) = \alpha \log n - \beta \log \log n + O(1)$, We also show that $\mathrm{Var}(H_n) = O(1)$.

But... Worst-case height is N.

(exponentially small chance when keys are inserted in random order)

ST implementations: summary

implementation	guarantee		average case		ordered ops?	operations on keys
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	N/2	N	no	`equals()`
binary search (ordered array)	lg N	N	lg N	N/2	yes	`compareTo()`
BST	N	N	1.39 lg N	1.39 lg N	next	`compareTo()`

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3.2 BINARY SEARCH TREES

- *BSTs*
- *ordered operations*
- *deletion*

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3.2 Binary Search Trees

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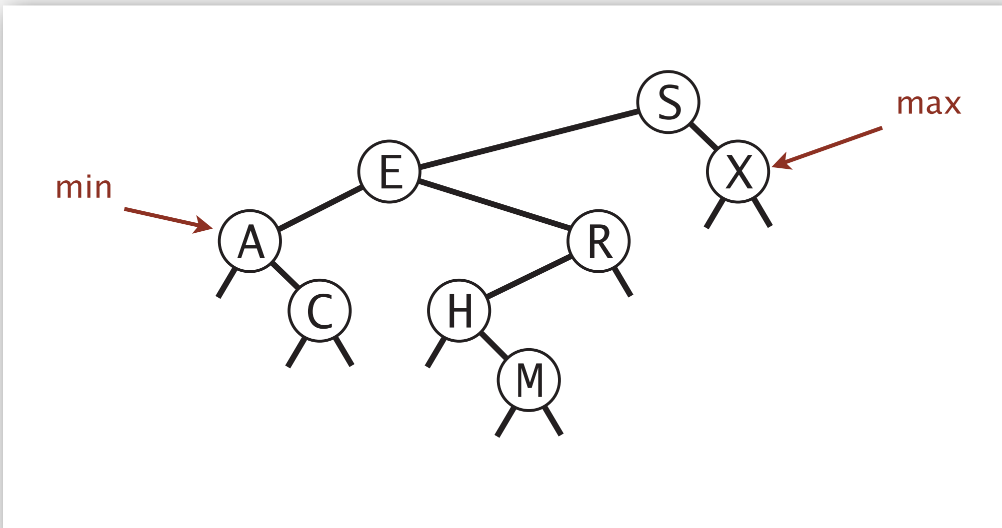
Minimum and maximum

Minimum. Smallest key in table.

Maximum. Largest key in table.

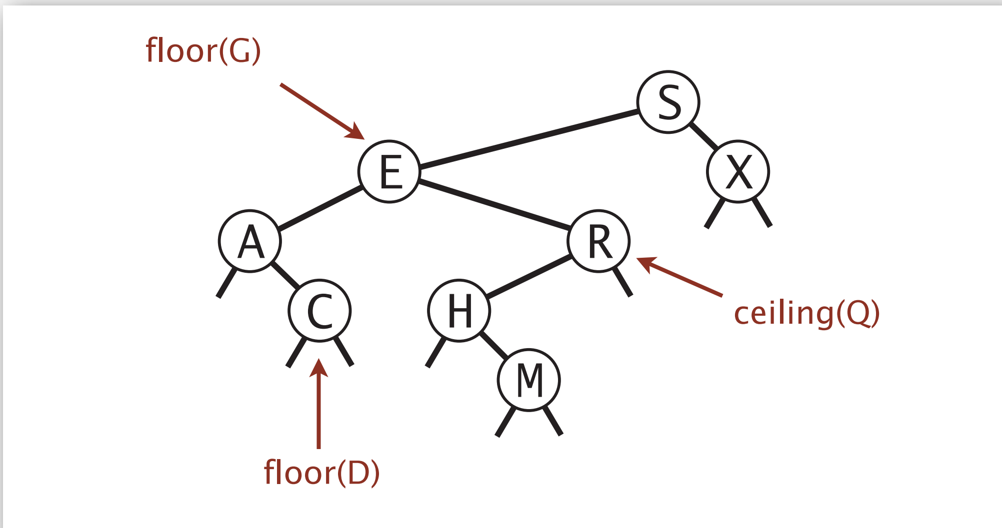


Q. How to find the min / max?

Floor and ceiling

Floor. Largest key ≤ a given key.

Ceiling. Smallest key ≥ a given key.



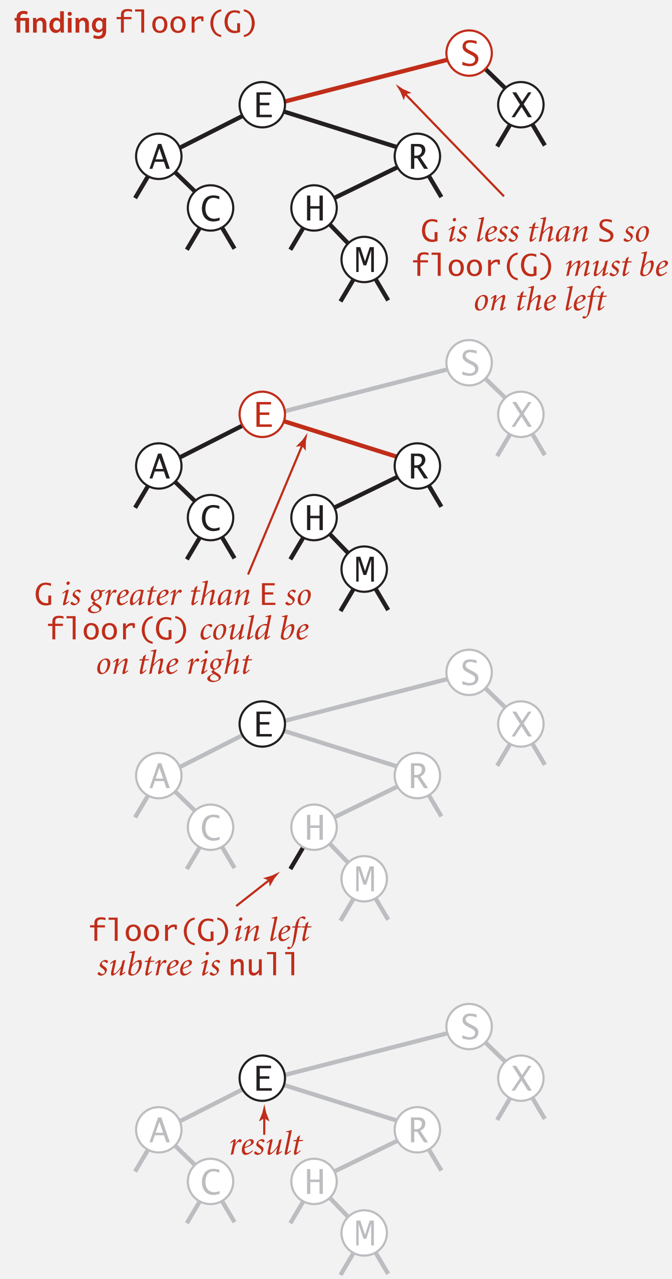
Q. How to find the floor / ceiling?

Computing the floor

Case 1. [k equals the key at root]
The floor of k is k.

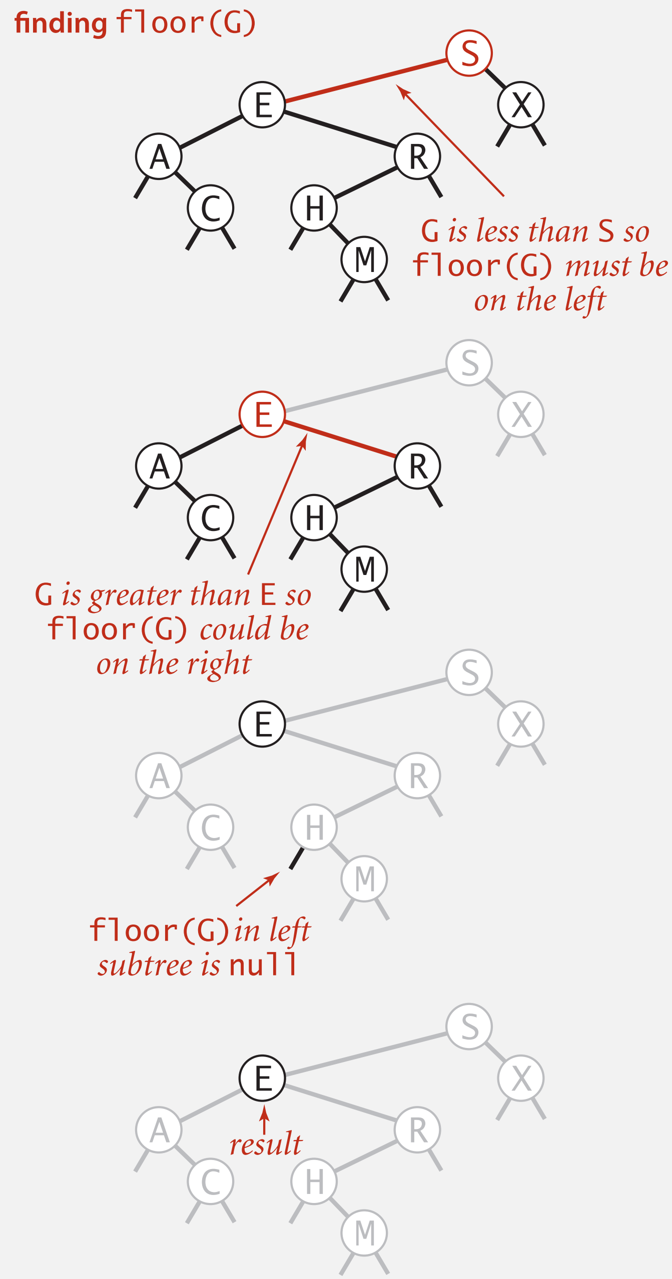
Case 2. [k is less than the key at root]
The floor of k is in the left subtree.

Case 3. [k is greater than the key at root]
The floor of k is in the right subtree
(if there is any key ≤ k in right subtree);
otherwise it is the key in the root.



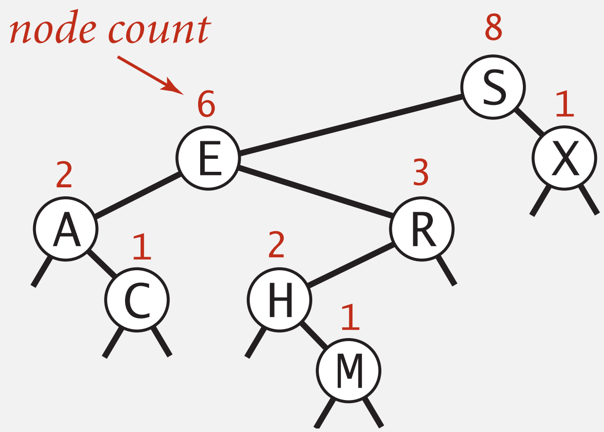
Computing the floor

```
public Key floor(Key key)
{
   Node x = floor(root, key);
   if (x == null) return null;
   return x.key;
}
private Node floor(Node x, Key key)
{
   if (x == null) return null;
   int cmp = key.compareTo(x.key);

   if (cmp == 0) return x;

   if (cmp < 0)  return floor(x.left, key);

   Node t = floor(x.right, key);
   if (t != null) return t;
   else           return x;

}
```



Subtree counts

In each node, we store the number of nodes in the subtree rooted at that node; to implement `size()`, return the count at the root.



Remark. This facilitates efficient implementation of `rank()` and `select()`.

BST implementation: subtree counts

```
private class Node
{
   private Key key;
   private Value val;
   private Node left;
   private Node right;
   private int count;
}
```

number of nodes in subtree

```
public int size()
{  return size(root);  }
```

```
private int size(Node x)
{
   if (x == null) return 0;
   return x.count;
}
```

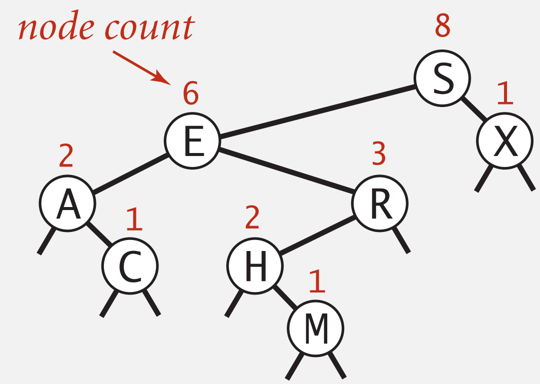
ok to call when x is null

```
private Node put(Node x, Key key, Value val)
{
   if (x == null) return new Node(key, val, 1);
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0) x.left  = put(x.left,  key, val);
   else if (cmp  > 0) x.right = put(x.right, key, val);
   else if (cmp == 0) x.val = val;
   x.count = 1 + size(x.left) + size(x.right);
   return x;
}
```

Rank

Rank. How many keys < k ?

Easy recursive algorithm (3 cases!)

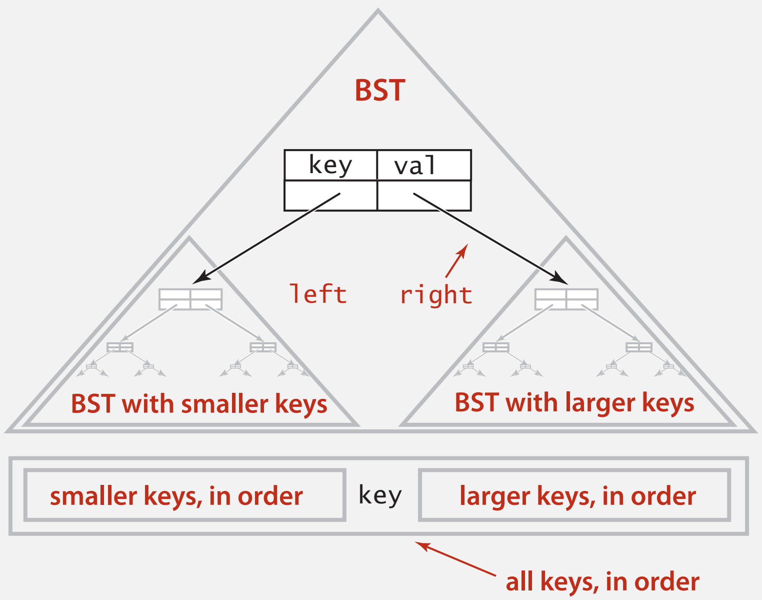



```
public int rank(Key key)
{  return rank(key, root);  }

private int rank(Key key, Node x)
{
   if (x == null) return 0;
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0) return rank(key, x.left);
   else if (cmp  > 0) return 1 + size(x.left) + rank(key, x.right);
   else if (cmp == 0) return size(x.left);
}
```

Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

```
public Iterable<Key> keys()
{
    Queue<Key> q = new Queue<Key>();
    inorder(root, q);
    return q;
}

private void inorder(Node x, Queue<Key> q)
{
   if (x == null) return;
   inorder(x.left, q);
   q.enqueue(x.key);
   inorder(x.right, q);
}
```



Property. Inorder traversal of a BST yields keys in ascending order.

BST: ordered symbol table operations summary

	sequential search	binary search	BST
search	N	lg N	h
insert	N	N	h
min / max	N	1	h
floor / ceiling	N	lg N	h
rank	N	lg N	h
select	N	1	h
ordered iteration	N log N	N	N

h = height of BST
(proportional to log N
if keys inserted in random order)

order of growth of running time of ordered symbol table operations

Algorithms

ROBERT SEDGEWICK | KEVIN WAYNE

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3.2 BINARY SEARCH TREES

- BSTs
- *ordered operations*
- deletion

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3.2 Binary Search Trees

- BSTs
- ordered operations
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ST implementations: summary

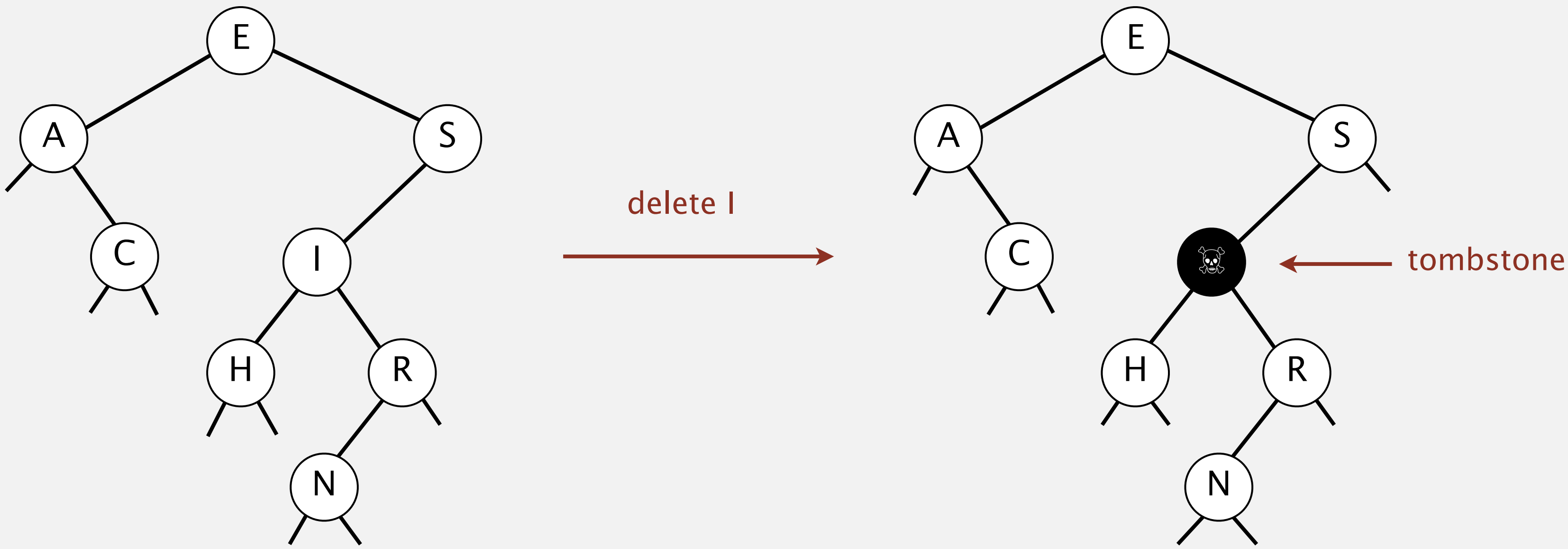
implementation	guarantee			average case			ordered iteration?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	N/2	N	N/2	no	`equals()`
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	`compareTo()`
BST	N	N	N	1.39 lg N	1.39 lg N	???	yes	`compareTo()`

Next. Deletion in BSTs.

BST deletion: lazy approach

To remove a node with a given key:

- Set its value to `null`.
- Leave key in tree to guide search (but don't consider it equal in search).



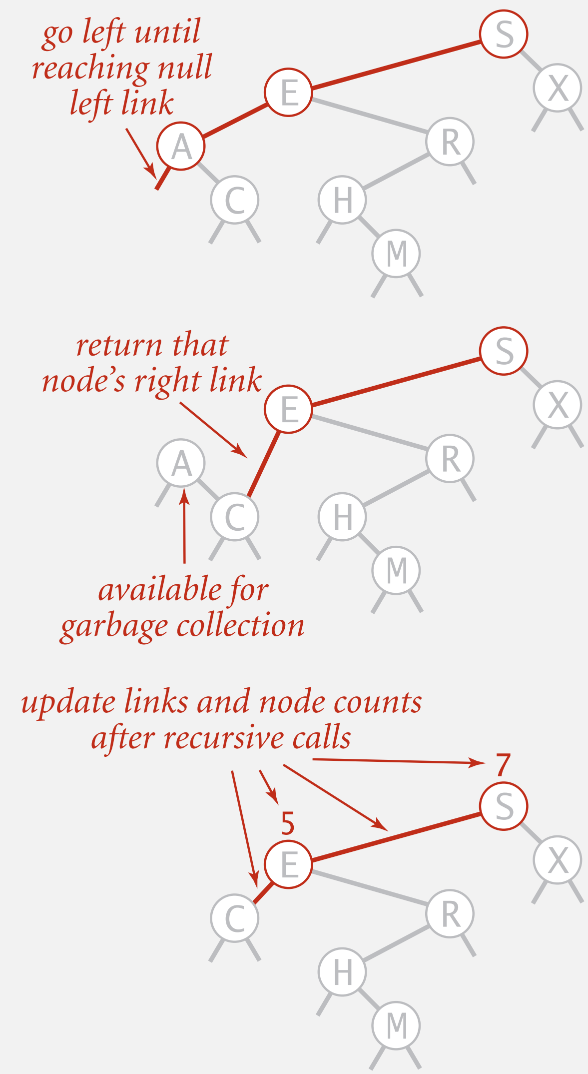
Cost. $\sim 2 \ln N'$ per insert, search, and delete (if keys in random order), where N' is the number of key-value pairs ever inserted in the BST.

Unsatisfactory solution. Tombstone (memory) overload.

Deleting the minimum

To delete the minimum key:

- Go left until finding a node with a null left link.
- Replace that node by its right link.
- Update subtree counts.



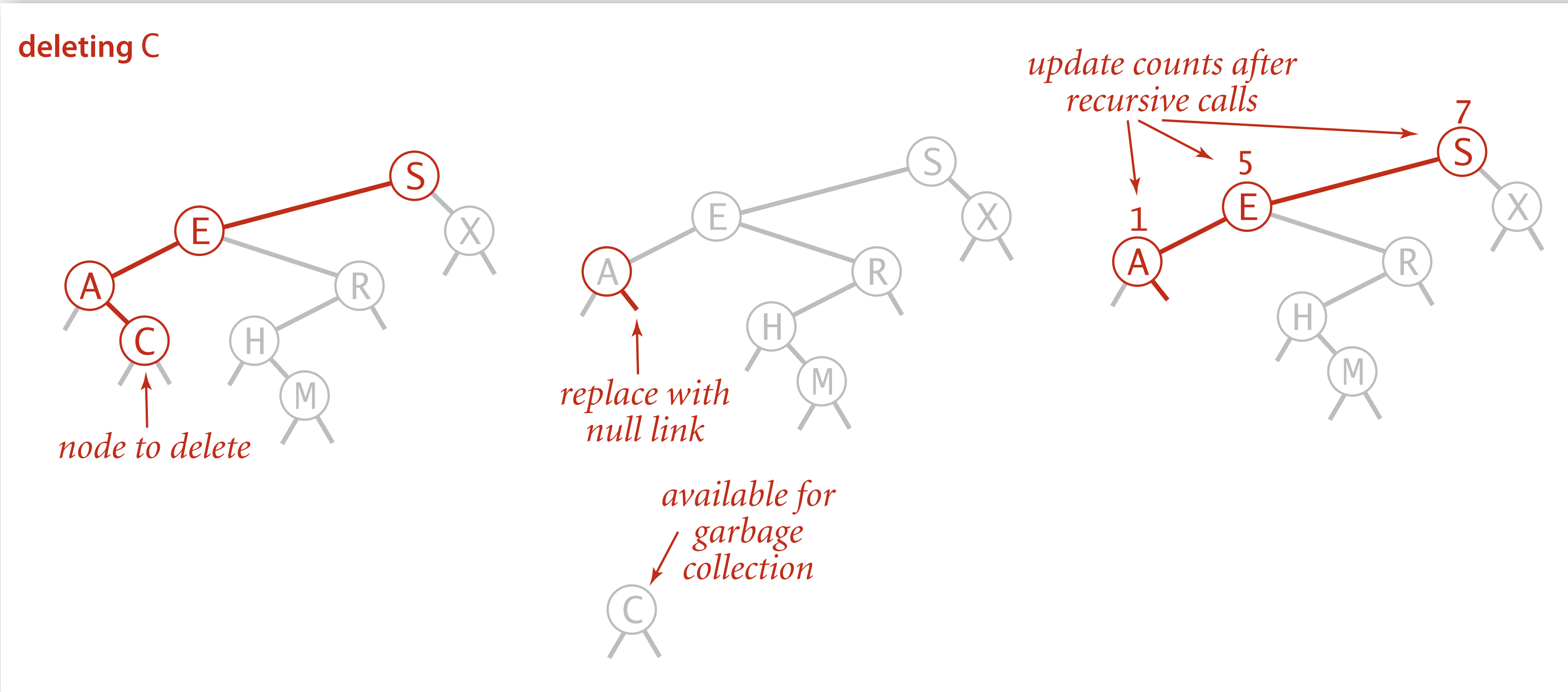

```
public void deleteMin()
{  root = deleteMin(root);  }

private Node deleteMin(Node x)
{
   if (x.left == null) return x.right;
   x.left = deleteMin(x.left);
   x.count = 1 + size(x.left) + size(x.right);
   return x;
}
```

Hibbard deletion

To delete a node with key `k`: search for node `t` containing key `k`.

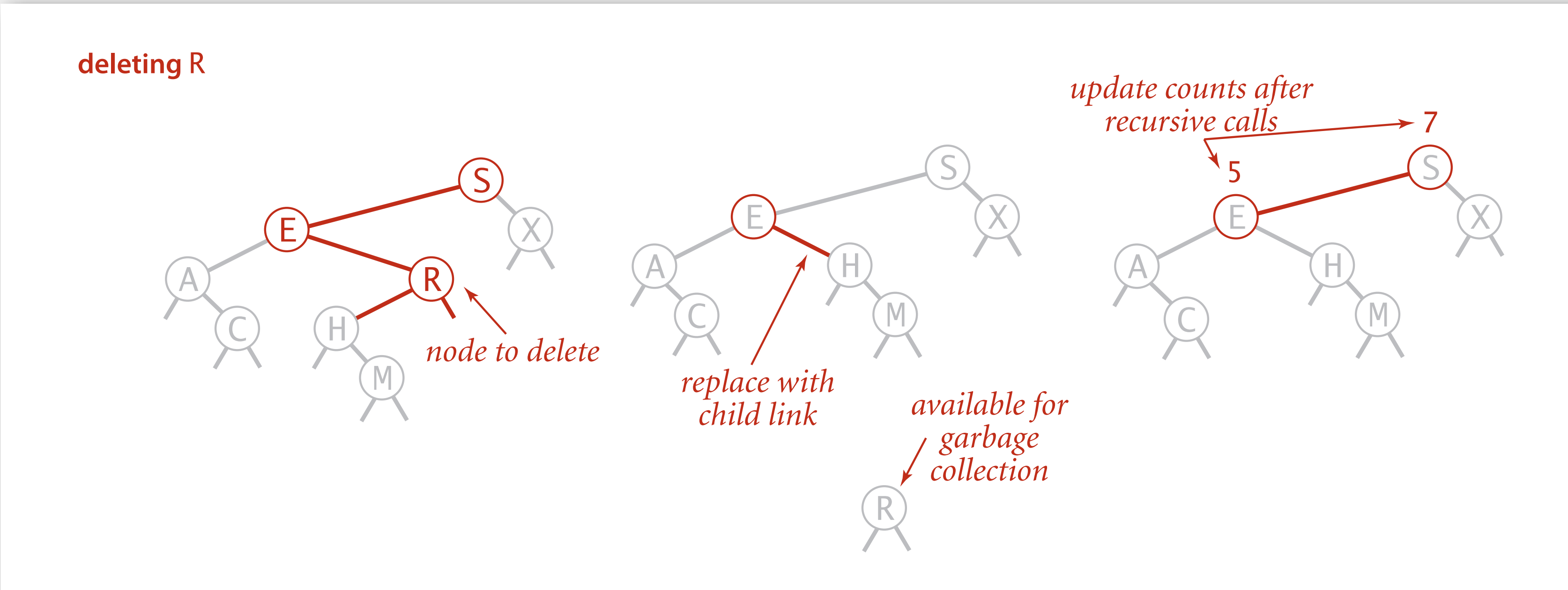
Case 0. [0 children] Delete `t` by setting parent link to null.



Hibbard deletion

To delete a node with key `k`: search for node `t` containing key `k`.

Case 1. [1 child] Delete `t` by replacing parent link.

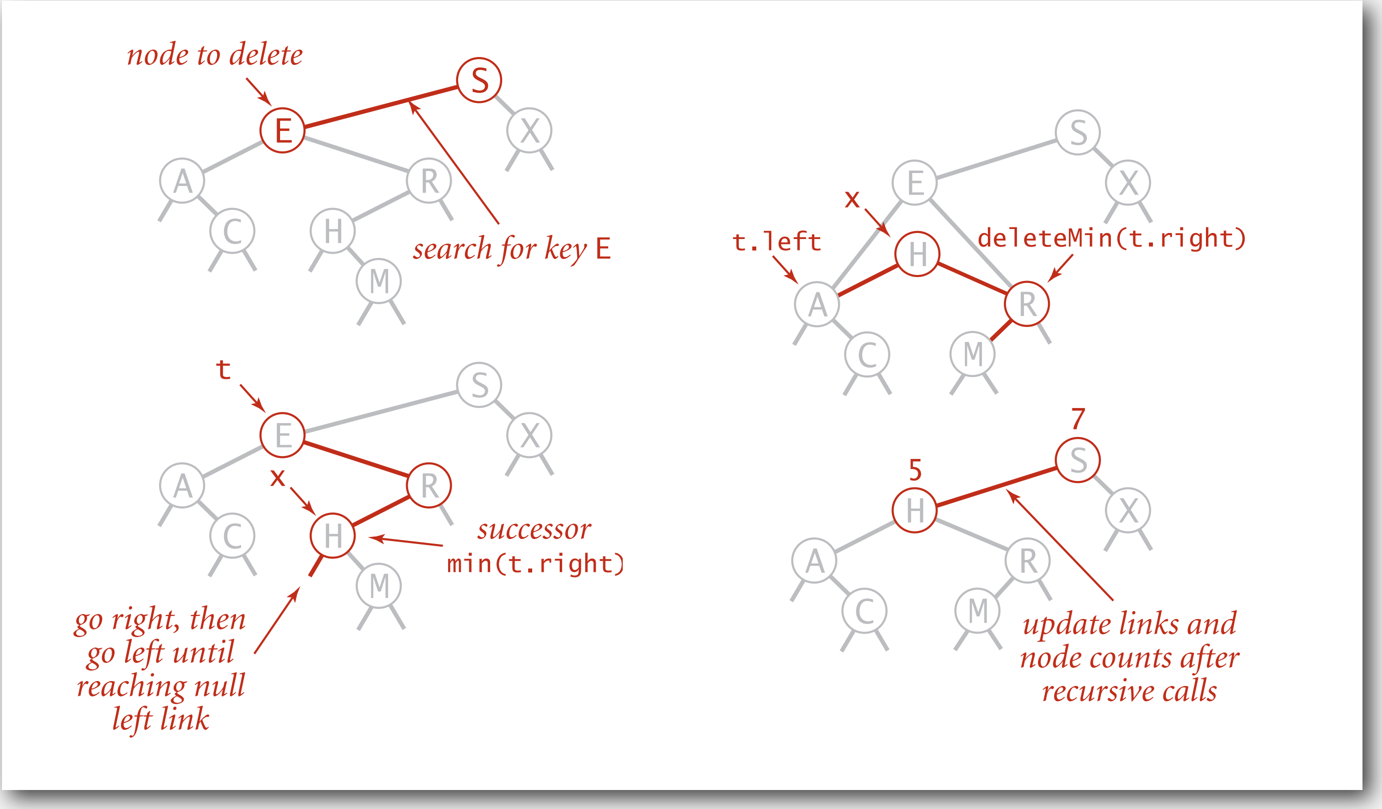


Hibbard deletion

To delete a node with key `k`: search for node `t` containing key `k`.

Case 2. [2 children]

- Find successor `x` of `t`. ← x has no left child
- Delete the minimum in `t`'s right subtree. ← but don't garbage collect x
- Put `x` in `t`'s spot. ← still a BST



Hibbard deletion: Java implementation

```
public void delete(Key key)
{  root = delete(root, key);  }

private Node delete(Node x, Key key) {
   if (x == null) return null;
   int cmp = key.compareTo(x.key);
   if      (cmp < 0) x.left  = delete(x.left,  key);
   else if (cmp > 0) x.right = delete(x.right, key);
   else {
      if (x.right == null) return x.left;
      if (x.left  == null) return x.right;

      Node t = x;
      x = min(t.right);
      x.right = deleteMin(t.right);
      x.left = t.left;
   }
   x.count = size(x.left) + size(x.right) + 1;
   return x;
}
```

search for key

no right child

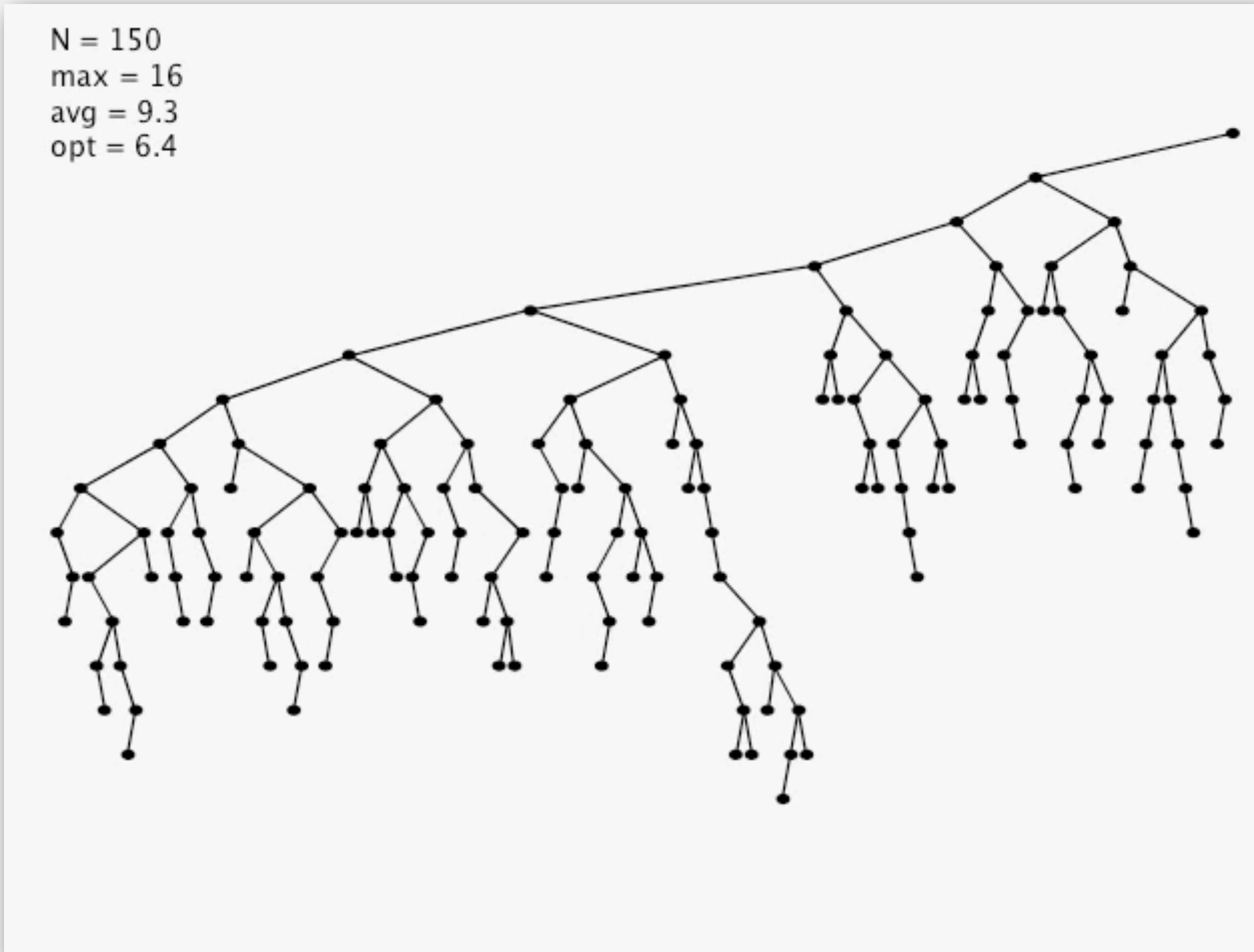
no left child

replace with successor

update subtree counts

Hibbard deletion: analysis

Unsatisfactory solution. Not symmetric.



Surprising consequence. Trees not random (!) $\Rightarrow$ sqrt (N) per op.

Longstanding open problem. Simple and efficient delete for BSTs.

ST implementations: summary

implementation	guarantee			average case			ordered iteration?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	N/2	N	N/2	no	`equals()`
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	`compareTo()`
BST	N	N	N	1.39 lg N	1.39 lg N	$\sqrt{N}$	yes	`compareTo()`

other operations also become $\sqrt{N}$
if deletions allowed

Next lecture. Guarantee logarithmic performance for all operations.

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3.2 Binary Search Trees

- BSTs
- ordered operations
- *deletion*

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3.2 BINARY SEARCH TREES

- *BSTs*
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