### Problem 1

Calculate the Lagrangian  $\mathcal{L}(x,\alpha)$ .

$$\mathcal{L}(x,\alpha) = -(x_1 + x_2) + \alpha_1(x_1^2 + x_2^2 - 1)$$

Obtain the Lagrangian dual function  $g(\alpha)$ .

$$\frac{\nabla_{\mathcal{L}(x,\alpha)}}{\partial x_1} = 0 \Leftrightarrow$$

$$2\alpha_1 x_1 - 1 = 0 \Leftrightarrow$$

$$x_1 = \frac{1}{2\alpha_1}$$

$$\frac{\nabla_{\mathcal{L}(x,\alpha)}}{\partial x_2} = 0 \Leftrightarrow$$

$$2\alpha_1 x_2 - 1 = 0 \Leftrightarrow$$

$$x_2 = \frac{1}{2\alpha_1}$$

Solve the dual problem (Plug  $x^*$  in  $g(\alpha)$ ).

$$\frac{\nabla_{g(\alpha)}}{\partial \alpha} = 0 \Leftrightarrow$$

$$\frac{1}{\alpha_1^2} - \frac{1}{2\alpha_1^2} - 1 = 0 \Leftrightarrow$$

$$\alpha_1^2 = \frac{1}{2}$$
 (by constraint  $\alpha_i \ge 0$ )
$$\alpha_1 = \frac{1}{\sqrt{2}}$$

## Problem 2

- Similarities
  - Both algorithms try to solve the problem of binary classification by finding a decision boundary  $w^{\dagger}x + b = 0$  that separates all datapoints  $x_i$  with label 1 from all datapoints  $x_j$  with label -1
- Differences
  - SVM has a closed form solution
  - SVM gives an unique solution (constrained optimization) by choosing a decision boundary s.t.
     it has a maximum margin to its nearest datapoints
  - Perceptron must be solved iteratively
  - Perceptron may have infinitely many correct solutions (if available) (unconstrained optimization)

#### Problem 3

By the formulation of the SVM problem we have

minimize 
$$f_0(w, b) = \frac{1}{2} w^{\mathsf{T}} w$$
  
subject to  $f_i(w, b) = y_i(w^{\mathsf{T}} x_i + b) - 1 \ge 0$ , for  $i = 1, ..., N$  (1)

Clearly we can rewrite (1) to

$$f_i(w, b) = -y_i(w^{\mathsf{T}}x_i + b) + 1 \le 0$$
, for  $i = 1, ..., N$ 

By Slater's constraint qualification we have that the duality gap of the SVM problem is zero if  $f_0(x)$ ,  $f_1(x)$ , ...  $f_N(x)$  are convex and the constraints  $f_1(x)$ , ...  $f_N(x)$  are affine. Clearly both assumptions are met, because  $f_0(x)$  is simply the  $L_2$ -norm, which is convex and the constraints are linear functions in w shifted by an offset b, which makes them affine. Thus the duality gap is zero.

#### Problem 4

a). Let  $\mathbf{X} \in \mathbb{R}^{n \times d}$ , where each row is a datapoint  $\mathbf{x} \in \mathbb{R}^d$ ,  $\mathbf{Y} \in \mathbb{R}^{n \times n}$ , where each column is the label  $y_i$  of the i-th datapoint replicated n times and  $\boldsymbol{\alpha} \in \mathbb{R}^n$  with  $\alpha_i$  at position i. By the Hadamard product we have

$$\mathbf{Q} = -XX^{\mathsf{T}} \odot (Y \odot Y^{\mathsf{T}}) \tag{1}$$

$$g(\alpha) = \alpha^{\mathsf{T}} \mathbf{Q} \alpha \tag{2}$$

- b). We can reformulate (2) to  $Q = -(X \odot Y)^{\mathsf{T}}(X \odot Y)$  and define  $A = (X \odot Y)$ . By construction we have  $A^{\mathsf{T}}A$  is positive semi-definite, i.e.  $\forall z : z^{\mathsf{T}}A^{\mathsf{T}}Az \geq 0$  because  $z^{\mathsf{T}}A^{\mathsf{T}}Az = (Az)^{\mathsf{T}}Az \geq 0$  (i.e.  $L_2$  norm is non-negative). Thus  $Q = -A^{\mathsf{T}}A$  is negative semi-definite.
- c). From negative semi-definiteness of Q and the Hessian of  $\alpha^{\mathsf{T}}Q\alpha$  is negative, it follows that  $\alpha^{\mathsf{T}}Q\alpha$  is a concave function. Since in the dual formulation we maximize  $g(\alpha)$ ,  $\frac{\nabla_{g(\alpha)}}{\partial \alpha} = 0$  is a sufficient condition to get the global maximum  $\alpha^*$ .

# 07\_homework\_svm-2

December 10, 2017

## 1 Programming assignment 7: SVM

### 1.1 Your task

In this sheet we will implement a simple binary SVM classifier.

We will use CVXOPT http://cvxopt.org/ - a Python library for convex optimization. If you use Anaconda, you can install it using

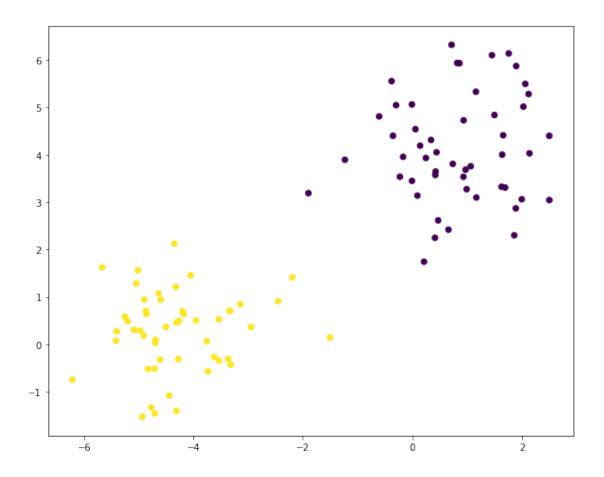
```
conda install cvxopt
```

As usual, your task is to fill out the missing code, run the notebook, convert it to PDF and attach it you your HW solution.

## 1.2 Generate and visualize the data

```
In [2]: N = 100  # number of samples
    D = 2  # number of dimensions
    C = 2  # number of classes
    seed = 3  # for reproducible experiments

X, y = make_blobs(n_samples=N, n_features=D, centers=2, random_state=seed)
    y[y == 0] = -1  # it is more convenient to have {-1, 1} as class labels (instead of {0}
    y = y.astype(np.float)
    plt.figure(figsize=[10, 8])
    plt.scatter(X[:, 0], X[:, 1], c=y)
    plt.show()
```



## 1.3 Task 1: Solving the SVM dual problem

Remember, that the SVM dual problem can be formulated as a Quadratic programming (QP) problem. We will solve it using a QP solver from the CVXOPT library.

The general form of a QP is

$$\min_{\mathbf{x}} \frac{1}{2} \mathbf{x}^T \mathbf{P} \mathbf{x} + \mathbf{q}^T \mathbf{x}$$

subject to  $Gx \leq h$ 

and 
$$Ax = b$$

where  $\leq$  denotes "elementwise less than or equal to".

**Your task** is to formulate the SVM dual problems as a QP and solve it using CVXOPT, i.e. specify the matrices **P**, **G**, **A** and vectors **q**, **h**, **b**.

**Parameters** 

```
Input features.
            y : array, shape [N]
                Binary class labels (in {-1, 1} format).
            Returns
            _____
            alphas : array, shape [N]
                Solution of the dual problem.
            11 11 11
            # TODO
            # These variables have to be of type cuxopt.matrix
            P = matrix(np.dot(X, X.T) * y[None, :] * y[:, None])
            q = matrix(-np.ones(shape=(N, 1)))
            G = matrix(-np.eye(N))
            h = matrix(-np.zeros(shape=(N,1)))
            A = matrix(y[None, :])
            b = matrix(0.0)
            solvers.options['show_progress'] = False
            solution = solvers.qp(P, q, G, h, A, b)
            alphas = np.array(solution['x'])
            return alphas
   Task 2: Recovering the weights and the bias
In [4]: def compute_weights_and_bias(alpha, X, y):
            """Recover the weights w and the bias b using the dual solution alpha.
            Parameters
            alpha : array, shape [N]
                Solution of the dual problem.
            X : array, shape [N, D]
                Input features.
            y : array, shape [N]
                Binary class labels (in {-1, 1} format).
            Returns
            w : array, shape [D]
                Weight vector.
            b : float
                Bias term.
            w = np.dot(X.T, alpha * y[:, None])
            idx_sv = np.where(alpha > 1e-4)[0][0]
```

\_\_\_\_\_

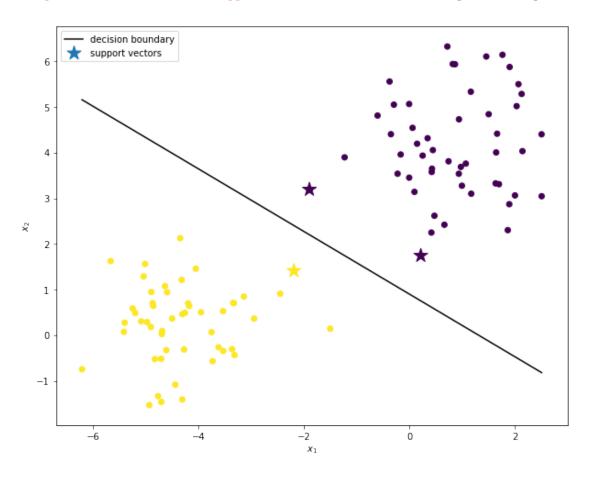
X : array, shape [N, D]

```
b = y[idx_sv] - np.dot(X[idx_sv, :], w)
return w, b
```

## 1.5 Visualize the result (nothing to do here)

```
In [5]: def plot_data_with_hyperplane_and_support_vectors(X, y, alpha, w, b):
            """Plot the data as a scatter plot together with the separating hyperplane.
            Parameters
            X : array, shape [N, D]
                Input features.
            y : array, shape [N]
                Binary class labels (in {-1, 1} format).
            alpha : array, shape [N]
                Solution of the dual problem.
            w : array, shape [D]
                Weight vector.
            b : float
                Bias term.
            plt.figure(figsize=[10, 8])
            # Plot the hyperplane
            slope = -w[0] / w[1]
            intercept = -b / w[1]
            x = np.linspace(X[:, 0].min(), X[:, 0].max())
            plt.plot(x, x * slope + intercept, 'k-', label='decision boundary')
            # Plot all the datapoints
            plt.scatter(X[:, 0], X[:, 1], c=y)
            # Mark the support vectors
            support_vecs = (alpha > 1e-4).reshape(-1)
            plt.scatter(X[support_vecs, 0], X[support_vecs, 1], c=y[support_vecs], s=250, mark
            plt.xlabel('$x_1$')
            plt.ylabel('$x_2$')
            plt.legend(loc='upper left')
  The reference solution is
w = array([[-0.69192638],
           [-1.00973312]])
b = 0.907667782
  Indices of the support vectors are
[38, 47, 92]
In [9]: alpha = solve_dual_svm(X, y)
        w, b = compute_weights_and_bias(alpha, X, y)
```

```
plot_data_with_hyperplane_and_support_vectors(X, y, alpha, w, b)
plt.show()
print('weights w = \n {} \n bias b = \n {}'.format(w, b))
print('Indices of the support vectors are {}'.format(np.where(alpha > 1e-4)[0]))
```



```
weights w =
  [[-0.69192638]
  [-1.00973312]]
bias b =
  [ 0.90766782]
Indices of the support vectors are [38 47 92]
```